Correction to: Novel servo-feed-drive model considering cutting force and structural effects in milling to predict servo dynamic behaviors

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In the accepted paper, the authors' affiliation has been wrongly typeset as People's Republic of China, but this should read Taiwan. The correct affiliations are shown below. The publisher apologize for this mistake.

The online version of the original article can be found at <https://doi.org/10.1007/s00170-019-04778-9>

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