Evaluation of formability and fracture of pure titanium in incremental sheet forming

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Abstract A forming limit diagram (FLD) is commonly used as a useful means for characterising the formability of sheet metal forming processes. In this study, the Nakajima test was used to construct the forming limit curve at necking (FLCN) and fracture (FLCF). The results of the FLCF are compared with incremental sheet forming (ISF) to evaluate the ability of the Nakajima test to describe the fracture in ISF. Tests were carried out to construct the forming limit diagram at necking and fracture to cover the strain states from uniaxial tension to equi-biaxial tension with different stress triaxialities—from 0.33 for uniaxial tension to 0.67 for equi-biaxial tension. Due to the fact that the Gurson–Tvergaard–Needleman (GTN) model can be used to capture fracture occurrence at high stress triaxiality, and the shear modified GTN model (Nahshon–Hutchinson’s shear mechanism) was developed to predict the fracture at zero stress or even negative stress triaxiality, the original GTN model and shear modified GTN model may be not suitable to predict the fracture in all samples of the Nakajima test as some samples are deformed under moderate stress triaxiality. In this study, the fractures are compared using the original GTN model, shear modified GTN model and the Nielsen–Tvergaard model with regard to stress triaxiality. To

validate the ability of these models, and to assess which model is more accurate in predicting the fracture with different stress triaxialities, finite element (FE) simulations of the Nakajima test were compared with an experimental results to evaluate the applicability of the Nakajima test to characterise the fracture from ISF. The experimental and FE results showed that the shear modified GTN model could predict the fracture accurately with samples under uniaxial tension condition due to low stress triaxiality and that the original GTN model is suitable for an equi-biaxial strain state (high stress triaxiality), whereas the stress triaxiality modified GTN model should be considered for samples which have moderate stress triaxiality (from plain strain to biaxial strain). The numerical and experimental FLCF of pure titanium from the Nakajima test showed a good agreement between the experimental and numerical results of ISF.

Keywords Nakajima test · ISF · FLD · Stress triaxiality · GTN model

1 Introduction

It is important to predict the fracture and forming limits during the process in sheet metal forming processes. The forming limit diagram (FLD) of SPIF is usually employed to determine the limits of proportional straining before failure and is quite different from the corresponding diagram for traditional sheet forming such as deep drawing or hydroforming. The experimental results showed that the distribution of the thickness is uniform in the cross-section of the parts produced by ISF up to the fracture without necking before the fracture. Based on these results, the forming limit curve at necking (FLCN) of traditional sheet metal forming is not suitable for ISF. Consequently, the forming limit curve at fracture (FLCF) is

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utilised to predict the fracture of the ISF process [1]. The shape of the FLCF is a straight line with a negative slope for most of the materials and it is located in the first quadrant of the forming limit diagram. Figure 1 illustrates the typical modes of deformation when a sheet element is subjected to proportional loading. In Fig. 1, the forming limit curves FLCN and FLCF are stated as a strain ratio of the true minor strain ε_2 to the true major strain ε_1 , $\rho = \varepsilon_2/\varepsilon_1$ and this ratio takes different values for different paths of strain, e.g. $\rho = 1$ for biaxial tension and $\rho = 0$ for plain strain [2–4].

Allwood et al. [1] proved that the formability of ISF is higher than that for conventional sheet metal forming by comparing between them using a paddle forming process with the same geometry. They noted that the forming limit of ISF is increased under uniform proportional load when through-thickness shear is presented. Forming parameters, e.g. type of material, shape produced, tool diameter and step size, play an important role in increasing or decreasing the forming limits in SPIF [5]. A new forming tool containing a rotating ball was developed by Shim and Park [6] to evaluate the formability of Al 1050; in their study, different tool paths were applied to generate different strain paths. It was noted that formability was strongly influenced by the strain path. Jeswiet and Young [7] developed FLD for ISF of 5754–0 and 3003–0 Al using five distinct shapes to measure the major and minor strains at different statuses. It was found that, with SPIF, the strain increased over 300% for all shapes. An experimental methodology was then proposed to determine the FLCF using a SPIF, torsion and shear test. It is noted that the FLCF constructed by a conventional sheet test, e.g. the Nakajima test, is identical to that constructed from ISF tests on pyramidal and conical truncate parts [8]. The major strain at fracture in ISF was located above the Nakajima's forming limit curve at fracture (FLCF) when lower tool diameter is used [9]. Tensile and hydraulic bulge tests were utilised to establish the FLCF for multi-stage SPIF. The results

showed that the FLCF can be successfully employed to determine the forming limit of multi-stage SPIF. In addition, the overall strains obtained in multi-stage SPIF are higher than the FLCN established by the hydraulic bulge test [10]. The deformation mechanism and fracture behaviour of double point incremental forming has been investigated based on the membrane analysis and experimental work. It was found that by using different supporting force and tool shift the FLCF can be increased as compared with SPIF [11]. An analytical model was developed with the consideration of bending effect and strain hardening to describe the localised deformation in ISF. The results of this model showed that the deformation in ISF occurs in contact area as well in the neighbouring wall [12]. Stress-based forming limit diagram combined with maximum shear stress diagram criterion was introduced to predict the fracture in ISF process. This approach showed a good correlation between the prediction and experimental data [13]. The FLCF was constructed under proportional loading (tensile test) and non-proportional loading (SPIF test). It was found the shape and value of FLCF in SPIF differ from the one of tensile test [14].

To investigate the effect of friction on the formability and material deformation of SPIF, a new oblique roller ball (ORB) tool has been developed by Lu et al. [15]. Four grades of aluminium sheets were employed in the experiments including AA110, AA2024, AA5052, and AA6111. A small hole in the sheet was drilled to study material deformation under both traditional rigid tool and the ORB tool. Experimental results showed that higher formability and smaller through-thickness shear are obtained with the ORB tool. Modified Mohr-Coulomb (MMC) damage model was implemented in Abaqus/Explicit via user subroutine (VUMAT) to predict the ductile fracture in SPIF. According to the Lode angle parameter and stress triaxiality, it was found the loading path of SPIF is non-linear as well, the MMC model with non-linear damage accumulation can predict the SPIF fracture location accurately while there was 10% error in fracture depth prediction [14]. An analytical model has been developed with the consideration of strain hardening and bending to study the deformation stability and fracture in ISF process of aluminium grades, AA1100 and AA5052. It was found the bending mechanism has a significant effect on the deformation stability as well as the fracture occurs based on the material's ductility and deformation stability [16]. FE simulation was employed to analyse the deformation of SPIF. The results showed that the SPIF part deforms under three deformation modes, i.e. stretching, shearing and bending [17].

Ozturk and Lee [18] constructed the FLD using the ductile fracture criteria of Hill, Mises, Cockcroft and Latham as well as Oh et al. models. They proved the ability of these models to accurately predict the fracture in the tension-compression

Fig. 1 Schematic diagram showing the FLCN and FLCF [4]

region (left hand side) of FLD, although the prediction was not accurate in the tension-tension region (right hand side) of FLD. The original GTN model was utilised by Uthaisangsuk et al. [19] to simulate the FLD and forming limit stress diagram (FLSD). The investigation showed that the FLD was not suitable for the complex sheet metal forming process and that, with a multi-step forming process, the FLSD is more accurate than the FLD. Furthermore, the original GTN model showed acceptable prediction of the fracture. The original GTN model was employed by Parsa et al. [20] to predict the FLD for aluminium monolayer and sandwich sheets. The results showed a good correlation between the experiments and the original GTN model, especially in a biaxial strain state, due to the high stress triaxiality ratio created by this state. The Nakajima test was carried out by Min et al. [21] to plot the FLD and FLSD for an aluminium alloy (AA) 5052-O1 sheet. The fracture in the Nakajima test was predicted using the original GTN model, which showed good agreement with the experimental Nakajima test for all strain states. The original anisotropic GTN model was implemented in ABAQUS/Explicit by Kami et al. [22] to construct the FLD of an anisotropic aluminium sheet using the Nakajima test. The result of the original anisotropic GTN model showed a better correlation with the experimental Nakajima test, especially in the biaxial tension strain state. The ductile damage in ISF of pure Ti sheet was investigated numerically using shear modified GTN damage model. There was a good correlation of the fracture depth when the shear modified GTN model results were compared with the experimental ISF test [23].

It is clear from the literature that the original GTN model has been used to simulate the Nakajima test in order to construct the forming limit curve at necking. The results showed that there was a good correlation between the FE prediction and experiments, especially in the biaxial strain state (high stress triaxiality) [20, 22] due to the high stress triaxiality ratio created by this state. It also clear that the ability of the Nakajima test to describe the fracture in ISF is still debatable; some researchers claim that the test is identical to that constructed from ISF tests on pyramidal and conical truncate parts [8], while others proved that the major strain at fracture in ISF is located above the Nakajima's FLCF when a small tool diameter is used [9]. In this study, for the first time, the GTN damage model with consideration of stress triaxiality has been employed to construct the forming limit curves at fracture in the Nakajima test and in incremental sheet forming at moderate stress triaxiality. To evaluate the ability of stress triaxiality modified GTN damage model and to predict the fracture under different stress strain states, the results were validated by Nakajima and ISF experimental results. In addition, the results of the

FLCF of Nakajima test are in a good agreement with that from ISF, which indicates the suitability of applying the Nakajima test to describe the fracture in ISF.

2 GTN model

The Gurson model [24] was developed based on the assumption that the material has a spherical shape of voids in the matrix. This model was modified by Tvergaard-Needleman [25] and the modified yield surface is defined as

$$\Phi = \left(\frac{\sigma_q}{\sigma_y}\right)^2 + 2q_1 f^* \cosh\left(-\frac{3q_2 p}{2\sigma_y}\right) - \left(1 + q_3 f^{*2}\right) = 0 \quad (1)$$

where $\sigma_q = \sqrt{\frac{3}{2} S_{ij} S_{ij}}$ is the equivalent stress of the Von Mises; σ_y is the flow stress; q_1 , q_2 and q_3 are the constitutive parameters proposed by Tvergaard [26] with suggested values of $q_1 = 1.5$, $q_2 = 1.0$ and $q_3 = q_1^2$, $p = -\frac{1}{3} \sigma_{ii}$ is the hydrostatic stress. f^* was proposed by Tvergaard-Needleman [25] to evaluate the coalescence between the voids and is given by

$$f^* = \begin{cases} f & \text{if } f \leq f_c \\ f_c + \frac{\bar{f}_F - f_c}{f - f_c} (f - f_c) & \text{if } f_c < f < f_F \\ \bar{f}_F & \text{if } f \geq f_F \end{cases} \quad (2)$$

where f_c is the critical value of the void volume fraction; f_F is the void volume fraction at fracture, and $\bar{f}_F$ is given by:

$$\bar{f}_F = \frac{q_1 + \sqrt{q_1^2 - q_3}}{q_3} \quad (3)$$

In the original GTN model, the void volume fraction is increased under tensile loading, due to the growth of the existing void and based on the nucleation of the new void.

$$f_{total} = df_{nucleation} + df_{growth} \quad (4)$$

The increment of the void nucleation is described by:

$$df_{nucleation} = A d\bar{\varepsilon}_m^p \quad (5)$$

where

$$A = \begin{cases} \frac{f_N}{S_N \sqrt{2\pi}} e^{-0.5 \left(\frac{d\bar{\varepsilon}_m^p - \varepsilon_N}{S_N} \right)^2} & \text{if } p \geq 0 \\ 0 & \text{if } p < 0. \end{cases} \quad (6)$$

The parameter A is a function of the matrix of total equivalent plastic strain $\bar{\varepsilon}_m^p$, f_N is the void volume fraction of the nucleated void; ε_N is the mean value of the normal distribution of the nucleation strain; and S_N is the standard deviation. $d\bar{\varepsilon}_m^p$ is equivalent plastic strain.

The increment of void growth is defined by:

$$df_{growth} = (1-f)d\varepsilon_{ii}^p \quad (7)$$

where $d\varepsilon_{ii}^p$ is the trace of the plastic strain tensor.

When the shear loading is considered, the shear load can accelerate the growth of the void or nucleate the new void. Therefore, the original GTN model was modified by Nahshon and Hutchinson [27] by adding an extension to predict the rate of the growth of voids with low stress triaxiality.

$$df_{shear} = k_w \frac{f\omega(\sigma)}{\sigma_q} S : \dot{\varepsilon}^p \quad (8)$$

where $\omega(\sigma)$ is a function of the stress state and its value is calculated as:

$$\omega(\sigma) = 1 - \left(\frac{27J_3}{2\sigma_q^3} \right)^2 \quad (9)$$

The range of ω is between $0 \leq \omega \leq 1$ with all axisymmetric stress states $\omega = 0$ and for all the states of pure shear plus a hydrostatic contribution $\omega = 1$. k_w is a parameter producing the damage rate in shear loading, and J_3 is the third invariant of the deviatoric stress tensor $J_3 = \det(S)$. In shear modified GTN model the increment of the VVF is determined based on the micro-voids' nucleation, growth and shear mechanisms.

The shear modified GTN model is able to predict fracture under very low stress triaxiality (η), while the original Gurson model predicts the fracture under high stress triaxiality. Therefore, Nielsen and Tvergaard [28] modified the Nahshon and Hutchinson shear extension to cover the effect of stress triaxiality in the regions of moderate to high stress triaxiality. Therefore, the function of the stress state becomes

$$\omega_o = \omega(\sigma)\Omega(\eta), \text{ with } \Omega(\eta) = \begin{cases} 1, & \text{for } \eta < \eta_1 \\ \frac{\eta - \eta_2}{\eta_1 - \eta_2}, & \text{for } \eta_1 \leq \eta \leq \eta_2 \\ 0, & \text{for } \eta > \eta_2 \end{cases} \quad (10)$$

where $\omega(\sigma)$ is given by Eq. (9), $\eta_1 < \eta_2$; based on this addition, the original GTN model is used for $\eta > \eta_2$ and the shear modified GTN model is utilised for $\eta < \eta_1$.

3 Experimental works

3.1 Nakajima test

This test is a stretching process up to fracture and is used to predict the forming limit diagram. The tools used in this test

include a hemispherical punch, die, and blankholder. Figure 2 shows the Nakajima test configuration according to BS EN ISO 12004-2. The spark-erosion method is utilised to produce the final shape of the specimen because it does not cause cracks in the sample's edges.

More than one specimen is required for the description of a complete forming limit diagram from uniaxial to equi-biaxial tension. In this work, five geometries of pure Ti grade1 with a sheet thickness of 0.7 mm were examined with three repetitions. The sample dimensions are illustrated in Table 1 and Fig. 3. Prior to the formability test, acetone was used to clean the sample, after which grease and PVC of 1 mm thickness were applied to the contact surface as a lubricant to reduce friction between the punch and specimen. The test was with a punch velocity equal to 1.2 mm/s.

The technique utilised for obtaining the forming limit curve at necking (FLCN) included using electrical chemical etching to print a grid of circles with a 2.5-mm initial diameter on the surface before the stretching process, and to measure the major and minor axis dimensions of the ellipses that resulted from the plastic deformation. The values of strain are computed from Eq. (11) (see Fig. 4) [29]:

$$\varepsilon_{major} = \ln\left(\frac{a}{d_o}\right), \varepsilon_{minor} = \ln\left(\frac{b}{d_o}\right) \quad (11)$$

where d_o represents the original diameter of the circle and a and b are the major and minor axes of the ellipse.

In addition, the optical deformation measurement with the digital camera was used to evaluate the major and minor strain distributions on the outer surface of the blank. The procedure for establishing the FLCF began by measuring the thickness at fracture in several places along the crack in order to obtain the average thickness strain. Average thickness strain was evaluated on both sides of the fracture. By using the grid pattern, the average minor strain was evaluated along the fracture, and by using volume constancy, the major strain was determined as follows:

$$\varepsilon_{major} = -(\varepsilon_{minor} + \varepsilon_{thickness}) \quad (12)$$

3.2 Determination of mechanical properties and GTN model parameters of pure titanium

A tensile test with a digital image correlation (DIC) system was utilised to determine the mechanical properties of pure Ti grade 1, as well as the material parameters of the GTN model, as shown in Fig. 5. More than one sample was required to determine the values of the void volume fraction (VVF) in the initial state, as well as nucleation, critical and fracture values. Scanning electron microscope (SEM) and ImageJ software were employed to measure the VVF values. First of all, pure Ti sheet was scanned under the SEM; then, the SEM

Fig. 2 Illustration of the cross section of the tool used for Nakajima testing [ISO 12004-2]

image was analysed using ImageJ to determine the primary VVF (f_o). The same technique was applied to determine the values of the VVF at nucleation, critical and fracture. The value for nucleation in the VVF (f_N) is determined when plastic deformation occurs in the tensile sample and before reaching the maximum load. It is difficult to predict the load where nucleation begins; therefore, the tensile test was stopped at different stages in order to scan the sample to determine whether nucleation had started. In this study, nucleation started when the load reached 2.8 kN. When the tensile sample reached the maximum value of the force and necking was noticed, the tensile test was stopped to determine the critical value of VVF (f_c). Finally, the fracture surface of the tensile sample was scanned using SEM to determine the final value of VVF (f_F). Table 2 summarises the mechanical properties and the GTN model parameters of pure Ti grade 1.

3.3 Single-point incremental forming

The proposed experimental method to establish the forming limit curve at fracture makes use of SPIF. The SPIF test was carried out to form truncated conical and pyramidal geometries with varying forming angles from 22° to 80° , as shown in Fig. 6. The truncated cone and truncated pyramid allow construction of the FLCF directly from the experimental measurement of major and minor strains at fracture under plain strain

and biaxial stretching conditions. To measure the strain state, the circle grid analysis was utilised using a similar methodology to the Nakajima test.

These tests were done with an incremental depth equal to 0.2 mm per revolution and tool diameter of 10 mm. The tool is rotation free with a feed rate of 1000 mm/min. To ensure the repeatability of the results, the SPIF process was repeated three times and the average value was taken.

4 Finite element simulation

Abaqus/Explicit was used to implement the shear modified GTN and stress triaxiality modified GTN models as a materials user subroutine (VUMAT). A return mapping algorithm was then utilised to determine the increments in plastic strain ($d\epsilon^p$) [30, 31]. Figure 7 shows the FE model of the Nakajima test performed on a specimen with a width of $a = 90$ mm and SPIF. In the simulation of the Nakajima test, the punch, die and the blankholder were modelled as an analytical rigid surface. This was the same for the tool, the backing plate and the blankholder in the SPIF process. The blank was modelled as a deformable body with an eight node brick element (C3D8R) in both the Nakajima test and the SPIF process. Element deletion technique was used to remove the failed elements from

Table 1 The dimensions of Nakajima test specimens

Parameters	Sample 1	Sample 2	Sample 3	Sample 4	Sample 5
a	20	60	90	130	170
b	40	80	120	170	170
c	20	20	20	0	0
d	170	170	170	170	170
R	30	30	30	50	–

Fig. 3 Dimensions of different FLD samples prepared for experiments

Fig. 4 Circular grid patterns, **a** before deformation and **b** after deformation

the FE model and to model the fracture in the sheet. In FE simulation, velocity vs time was used to define the tool path in SPIF and the movement of the punch in the Nakajima test.

The Nakajima test was carried out in two steps. In the first step, a 50-kN holding force was applied to the reference point of the blankholder. In the second step, the holding force remained constant and the punch moved down in the vertical direction. In this investigation, the Nakajima test was run five times with different dimensions, as shown in Table 1, to cover a uniform distribution of the FLC from uniaxial to equi-biaxial tension. Minor and major strains were recorded at the end of each job corresponding to a point on the FLD.

To study the effect of simulation parameters on the FE results, 45° truncated cone is executed with a 116-mm major base and a final depth of 30 mm. The SPIF test is carried out with a 10-mm hemispherical forming tool and 0.2-mm step size with a 1000 mm/min feed rate. Meshing density has an effect to the simulation results. However, using a very small element size means that the computational time be increased due to the fact that a stable increment time is strictly dependent on the element's length for explicit integration. In order to study the optimum mesh size to accurately predict the fracture with GTN model simulation of Nakajima test and SPIF, six element lengths (2, 1, 0.8, 0.6, 0.5 and 0.25 mm) were chosen

Fig. 5 Load-displacement curve shows the stages of determination of the GTN model parameters

Table 2 Material properties and GTN model parameters of pure Ti

Yield stress	Ultimate tensile stress	Young's modulus	Poisson's ratio	Density	f_0	q_1	q_2	f_N	ε_N	S_N	f_c	f_f
232.49 MPa	363 MPa	108 GPa	0.34	4505 kg/m ³	0.00138	1.5	1	0.017	0.3	0.1	0.2593	0.3025

with three layers of elements through the thickness. In this work, equivalent plastic strain distribution is used to predict a suitable element size. Figure 8 shows the equivalent plastic strain distribution of SPIF with different mesh sizes. It is clear from the figure that with a smaller element size, the increment in equivalent plastic strain can be captured earlier than that with larger element sizes. It can be concluded that using a solid element with reduced integration means each element has one integration point in the middle; hence, if a large element is used, the possibility of capturing the peak of the equivalent plastic strain is less than when using a small element. In this investigation, therefore, an optimum element size of 0.5 mm was chosen for this investigation.

To check the validity of the SPIF simulation, the FE thickness was compared with experimental SPIF thickness, as shown in Fig. 9. The SPIF simulated results by Abaqus are consistent with one of the actual experiments.

In most sheet metal forming processes, low friction is favoured. In the SPIF process, a certain level of friction is required between the forming tool and the sheet to transfer the stresses onto the forming tool and allow some stretching of the sheet. In order to investigate the effect of friction on the FE model of the SPIF process, the contact between the tool and blank, was simulated with different values of friction coefficient ($\mu = 0.05, 0.1, 0.15, 0.2$, and 0.25). The predicted thickness was compared with that of the experiment to illustrate the effect of friction coefficient on thickness distribution, as shown in Fig. 10. It can be seen that there is a good correlation in the thickness distribution of the truncated cone between the simulation results of a 0.1 friction coefficient and the experimental thickness. Hence, friction coefficient, $\mu = 0.1$ is chosen in this work to simulate the friction in SPIF between the forming tool and the sheet. It is clear therefore that more

thinning can be achieved with a high friction coefficient ($\mu = 0.25$).

In Nakajima test, the friction should be controlled to get accurate results of forming limit diagram. According to the BS EN ISO 12004-2:2008, the Nakajima test is considered valid if the fracture takes place with a distance less than 15% of the punch diameter away from the centre of the dome. The occurrence of the fracture away from the apex of the dome gives Indicator a high value of friction between the punch and blank [3]. The specimen with width $a = 90$ mm was chosen to study the effect of friction coefficient on the predicted fracture location. In the FE simulation, the friction coefficient between the pure Ti sheet and the punch was set to four values $\mu = 0.25, 0.15, 0.1$ and 0.05 . Figure 11 shows the effect of friction coefficient on the fracture locations. It is clear from the figure with the high values of friction coefficient (0.25 and 0.15) the fracture occurs away from the apex of the dome with distance more than 15% of the punch diameter and this distance gets smaller to be less than 15% of the punch diameter with 0.1 friction coefficient and very near to apex of the dome with 0.05 friction coefficient. A 0.05 friction coefficient is chosen in this work to simulate the friction between the punch and blank in Nakajima test and with this value a good correlation was achieved between the FE simulation and experimental test.

5 Results and discussion

5.1 Nakajima test

The level of major strain at fracture in different strain states is illustrated in Fig. 12. It is evident that relatively high major

Fig. 6 Geometries which require establishing FLD by using SPIF. **a** Cone. **b** Pyramid

Fig. 7 Finite element model. **a** Nakajima test. **b** SPIF

strain concentrations were present in the fracture zone of the stretched piece as a result of excessive bending.

Figure 13 illustrates the distribution of major and minor strains in all samples of the Nakajima test. From the figure, it can be seen that the ratio between the minor and major strain is -0.5 , -0.11 , 0.03 , 0.901 and 1 for specimens with a width of $a = 20, 60, 90, 130$ and 170 mm, respectively. Based on these ratios, the samples are enough to cover all strain states from uniaxial tension (strain ratio $= -0.5$) to equi-biaxial tension (strain ratio $= 1$) and the specimens with a width of $a = 20, 90$ and 170 mm corresponded well to strain states of uniaxial tension, plain strain and equi-biaxial tension, respectively.

To describe the complete FLCN and FLCF, five geometries were used to cover all the strain states from uniaxial tension to

equi-biaxial tension and these samples experienced different stress triaxiality, as shown in Fig. 14. From the figure, it is clear that stress triaxiality was not constant during the deformation of each sample. Therefore, the average value of stress triaxiality was taken as a reference of each sample and was $0.39, 0.5, 0.57, 0.63$ and 0.66 for samples with a width of $a = 20, 60, 90, 130$ and 170 mm, respectively. Based on these results, stress triaxiality appears to change from one sample to another; in the Nakajima test, it also changed in the same sample. Therefore, the effect of stress triaxiality on the fracture occurrence should be taken into account when the GTN model is used to evaluate the fracture in the Nakajima test.

Major strain at fracture was measured using FE models (the original GTN, shear modified GTN and stress triaxiality

Fig. 8 Comparison of equivalent plastic strain between meshing densities of SPIF

Fig. 9 Comparison between numerical and experimental thickness distribution

modified GTN) and from experimental tests for all Nakajima samples to validate and examine these models. Figure 15a shows the distribution of major strain on all FE models, as well as the experimental tests for samples with a width equal to 20 mm (uniaxial tension). It is clear from the figure that there is a good correlation between the shear modified model and experimental curve; this correlation is due to the fact that the value of stress triaxiality is normally considered low (0.39) and the Nahshon-Hutchinson's shear mechanism was added to capture the fracture at low stress triaxiality, but the original GTN model cannot predict the void's growth within this range

of stress triaxiality and coalescence is postponed. Specimens with a width of 60 and 90 mm have moderate stress triaxiality; therefore, both the original GTN model and shear modified GTN model cannot accurately predict the value of the major strain at fracture, as shown in Fig. 11b, c; this is due to the fact that the original model and shear modified model do not work with a moderate ratio of stress triaxiality. However, the stress triaxiality modified GTN model is considered the best choice to use when moderate stress triaxiality is generated during the deformation as this model can accommodate the effect of stress triaxiality. The ratios of stress triaxiality in specimens

Fig. 10 Thickness distribution with different friction coefficients

Fig. 11 Effect of friction coefficient on the fracture location in Nakajima test

with widths of 130 and 170 mm are normally considered high at 0.63 and 0.66, respectively. With this range of stress triaxiality, the original GTN model can predict the fracture

occurrence accurately, as shown in Fig. 11d, e). Therefore, based on the above results for processes under different stress triaxialities, e.g. the Nakajima test, it is better to use the GTN

Fig. 12 Major strain distributions during the Nakajima test in different strain states

Fig. 13 Distribution of major and minor strain on Nakajima test specimens

model which considers the range of stress triaxiality as the Nielsen-Tvergaard stress triaxiality extension of the GTN model can be used as either the original GTN model, the shear modified GTN model, or as a stress triaxiality modified GTN model.

The predicted fracture depth (FD) of Nakajima test with different widths was validated by the experimental depth, as shown in Figs. 16 and 17. It is clear that the fracture depth shows a good correlation between simulations using Abaqus/

Explicit with the stress triaxiality modified GTN model and the experimental measurements.

5.2 Single-point incremental forming

The stress triaxiality modified GTN model was used to simulate the SPIF process for two shapes (hyperbolic truncated cone and hyperbolic truncated pyramid) due to the ability of this model to predict fracture occurrence with different stress

Fig. 14 Evaluation of stress triaxiality of Nakajima test specimens

Fig. 15 Evaluation of major strain in the fracture region of Nakajima specimens

triaxialities. The distribution of the major strain in SPIF parts is illustrated in Fig. 18. In the hyperbolic truncated cone

shape, the major strains are concentrated on the wall of the SPIF part in the transition area between the contact and non-

Fig. 16 Fracture depth of simulated Nakajima test specimens from the stress triaxiality modified GTN model with different widths

Fig. 17 Fracture depth of Nakajima test specimens with different widths

Fig. 18 Comparison of major strain concentration in **a** hyperbolic truncated cone and **b** hyperbolic truncated pyramid shape

contact zones, whereas in the hyperbolic truncated pyramid, it is concentrated at the corner of the part.

The values of major and minor strains for both shapes were recorded, as shown in Fig. 19, and the ratios of strain ($\rho = \varepsilon_2 / \varepsilon_1$) were 0.05 and 0.87 for the hyperbolic truncated cone and hyperbolic truncated pyramid shape, respectively. These ratios were validated experimentally by measuring the major and minor strain at fracture in SPIF for both shapes. Figure 20 shows the deformed grid at fracture; it is observed from the

diagram of the hyperbolic truncated cone shape that there is a big change on one axis of the circular grid, whereas the change in the other one is small, meaning there is an increase in major strain, while the minor strain remains unchanged (plain strain). It is also observed with the hyperbolic truncated pyramid shape that there is uniform distortion in the grid at fracture and that the ratio is close to 1 (equi-biaxial strain). Based on these ratios of strain, the hyperbolic truncated cone is deformed under plain strain conditions and the corner of the hyperbolic truncated pyramid part is deformed under equi-biaxial strain. Therefore, two points can be recorded in the first quadrant of FLD; these points are used to validate the capability of the Nakajima test to describe the formability of SPIF process.

The values of major strain in both shapes were compared with the experimental SPIF test to validate the ability of the stress triaxiality modified GTN model to accurately predict the values of major strain at fracture, as shown in Fig. 21. The results show that major strain in the hyperbolic truncated pyramid shape increases earlier than in the hyperbolic truncated cone due to the fact that the fracture develops in the corner of the hyperbolic pyramid shape under equi-biaxial stretching, whereas plain strain stretching appears in the hyperbolic cone shape. The SPIF-simulated results by Abaqus, using the stress triaxiality modified GTN model, are consistent with those of the actual experiments for both shapes. From the FE and experimental results, it is noted a higher fracture angle can be achieved with the hyperbolic truncated cone (68°) than the hyperbolic truncated pyramid (61°), this is due to the fact that the truncated cone deforms under

Fig. 19 Distribution of major and minor strain in both the hyperbolic truncated cone and hyperbolic truncated pyramid shape

Fig. 20 The distortion grid on the deformed SPIF parts. **a** Hyperbolic truncated cone shape. **b** Hyperbolic truncated pyramid shape

plane strain stretching (minor strain close to zero), while the truncated pyramid deforms under the plane strain and equi-biaxial strain stretching (minor strain equal the major strain) with the equi-biaxial stretching greater than the plane-strain stretching. Therefore, a high degree of deformation can be achieved under the plane strain condition.

5.3 Forming limit diagram

The experimental Nakajima test was conducted at ambient temperature with specimens of widths 20, 60, 90, 130 and 170 mm; the test was stopped when a crack occurred in the

sample. The FLCN was established by measuring the major and minor strain in the necking region, while the FLCF was determined by measuring the major and minor strains in the fracture region and then plotting them in the major and minor strain space, as shown in Fig. 22. It can be seen from the figure that the FLCF takes the shape of a straight line with a negative slope in the first quadrant of the FLD. The numerical FLCN and FLCF results for pure titanium showed a good agreement with the experimental results. The SPIF process was used to validate the FLCF obtained by the Nakajima test. It can be noticed that the major strain at fracture in SPIF for both tests, i.e. the truncated cone and truncated pyramid, is located above the

Fig. 21 Evaluation of major stain in the fracture region of SPIF in both the hyperbolic truncated cone and hyperbolic truncated pyramid shapes

Fig. 22 Forming limit diagram for grade 1 titanium sheet with 0.7 mm thickness

FLCF. This is due to the stress state being induced as the tool moves in SPIF, indicating that the part produced by SPIF has higher formability than traditional sheet metal forming.

6 Conclusions

The aim of this paper was twofold: first, to evaluate the capability of the original and shear modified GTN models to predict fracture occurrence with moderate stress triaxiality ratios. Second, to evaluate the formability of the ISF process and to examine the applicability of the Nakajima test to describe the fracture in the ISF process. The results of this work can be summarised as follows:

- The shear modified GTN model can predict a fracture accurately in a uniaxial strain state and the original GTN model can work in the range of the equi-biaxial strain state, while the stress triaxiality modified GTN model should be used for cases under moderate stress triaxiality (from the plain strain region to the equi-biaxial region).
- The ratios of strain at fracture in both specimens of SPIF were determined quantitatively to evaluate under which strain states the conical and pyramidal truncated specimens were deformed and to record the locations of both shapes in the FLD. With the hyperbolic truncated cone and hyperbolic truncated pyramid shapes, two points can be recorded in the FLD: the first in the plain strain region with a strain ratio equal to 0.05, and another in the equi-biaxial region with a strain ratio equal to 0.87.
- The stress triaxiality modified GTN model showed good agreement with the experimental test of SPIF in predicting the fracture for both shapes (hyperbolic truncated cone and hyperbolic truncated pyramid shape).

- The Nakajima test can be applied to establish the FLCF, which can be utilised to describe the formability of the SPIF test for conical and pyramidal truncated specimens.

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