A reverse Hölder inequality for the gradient of solutions to Trudinger's equation

Olli Saari and Sebastian Schwarzacher

Abstract. We provide a higher integrability result for the gradient of positive solutions to Trudinger's equation (also known as the doubly non-linear equation) for the range $p \in [2, \infty)$. The estimate is achieved by refining a construction of intrinsic cylinders from the vectorial setting by incorporating estimates that are only available in the scalar case.

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1. Introduction

We study doubly non-linear parabolic partial differential equations modeled by Trudinger's equation

$$\frac{\partial(u^{p-1})}{\partial t} - \operatorname{div}(|\nabla u|^{p-2} \nabla u) = 0, \quad 1 < p < \infty. \quad (1.1)$$

It was introduced by Trudinger in [25], where a scale and location invariant parabolic Harnack inequality for positive weak solutions was proved, generalizing the work of Moser [22]. The Eq. (1.1) is motivated for instance by its connection to the non-linear eigenvalue problem and sharp constants in Sobolev inequalities. Given any bounded domain $\Omega \subset \mathbb{R}^n$, one defines the first non-linear eigenvalue of the p -Laplacian

$$\lambda_p = \inf_{u \in W_0^{1,p}(\Omega) \setminus \{0\}} \frac{\int_{\Omega} |\nabla u|^p dx}{\int_{\Omega} |u|^p dx}. \quad (1.2)$$

The minimizer v of the Rayleigh quotient is unique up to a multiplicative constant [17, 18]. On the other hand, given any weak solution $u \in L_{loc}^p(0, \infty; W_0^{1,p}(\Omega))$ to (1.1), then either

$$\lim_{t \rightarrow \infty} e^{\frac{\lambda_p}{p-1}t} u = v,$$

or the limit, understood in L^p sense, is identically zero [11]. This is the connection of the evolution equation (1.1) and the geometric quantity (1.2).

Our focus is on local regularity theory of positive weak solutions to (1.1). Despite the simple form of the parabolic Harnack estimate, the regularity theory of (1.1) is not as simple as one might expect. Weak solutions are known to be locally Hölder continuous [26], but to the best of our knowledge already Hölder continuity of the gradient is unknown. In addition, some fundamental questions such as the ones about uniqueness of solutions and validity of comparison principles are still partially open, see [16] for results and a discussion on open problems. We also refer to [12, 14, 15, 24] for more on regularity theory.

In the present paper, we prove a new regularity result for the non-negative solutions of (1.1). Our proof also applies to solutions of more general equations with principal part satisfying the natural growth conditions, see Sect. 2.2. The following theorem includes all exponents $p \in [2, \infty)$, which extends over what can be deduced from the vectorial case in [1] by allowing arbitrarily large values of p .

Theorem 1.1. *Let $n \geq 1$, $p \geq 2$ and $\Lambda \geq 1$. Then there exist $c, \epsilon > 0$ only depending on n , p and Λ so that for all space time cylinders $Q_{r,r^p} = I_{r^p} \times B_r$ and for all non-negative solutions $u \in L^p_{loc}(I_{(4r)^p}; W^{1,p}_{loc}(B_{4r}))$ to (2.1) and (2.2) it holds*

$$\begin{aligned} & \iint_{Q_{r,r^p}} |\nabla u|^{p(1+\epsilon)} dx dt \\ & \leq c \left(\iint_{Q_{2r,(2r)^p}} \left(\frac{u^p}{(2r)^p} + |\nabla u|^p \right) dx dt \right)^\epsilon \iint_{Q_{2r,(2r)^p}} |\nabla u|^p dx dt. \end{aligned}$$

We briefly recall the history of the topic. The study of higher integrability of gradients of solutions to partial differential equations goes back to Bojarski [3] and quasiregular mappings in the plane. See also [6] for quasiconformal mappings in space. Meyers [19] studied general linear elliptic equations, and elliptic systems were later treated in [20]. The first results for linear uniformly parabolic equations and systems are due to Giaquinta and Struwe [9]. Extending the results on higher gradient integrability to nonlinear parabolic equations remained an open problem for some time until in their seminal paper [13] Kinunen and Lewis managed to deal with systems of p -parabolic type. Their proof relies on the method of intrinsic scaling, which was originally introduced by DiBenedetto and Friedman [5] for other purposes. The p -parabolic equation

$$\frac{\partial u}{\partial t} - \operatorname{div}(|\nabla u|^{p-2} \nabla u) = 0, \quad 1 < p < \infty \quad (1.3)$$

becomes degenerate or singular when the gradient of the solution vanishes, which accounts for the behaviour qualitatively very different from what is seen in the linear setting. The class of weak solutions is not closed under multiplication by constants and consequently no proper homogeneous reverse Hölder condition can be expected to hold for the gradients of all solutions.

Equations of porous medium type

$$\frac{\partial u}{\partial t} - m \operatorname{div}(u^{m-1} \nabla u) = 0, \quad m > 0$$

exhibit a distinct difficulty as the equations become degenerate or singular depending on the values of the solution itself rather than its gradient. The higher gradient integrability was established only very recently by Gianazza and the second author in [7, 8]. These results require a very careful analysis of the covering properties of the intrinsic cylinders relative to the solution. The ideas there, in part originating from [23], have later also been used to study systems of porous medium type [2] and global variants of the above mentioned problems [21].

Equations of the type (1.1) studied in this paper can be formally understood as equations for $v = u^{p-1}$ given by

$$\frac{\partial v}{\partial t} - \frac{1}{(p-1)^{p-1}} \operatorname{div}(v^{2-p} |\nabla v|^{p-2} \nabla v) = 0.$$

From this formulation it is clear that the equation becomes degenerate or singular depending on both the values of the solution and the values of its gradient. Prior to this work, the higher gradient integrability was only known in the restricted range $p \in (2n/(n+2), 2n/(n-2)_+)$ when the dimension $n > 2$ and for all $p > 1$ when the dimension $n \in \{1, 2\}$. These results can be found in [1], whose methods actually apply in the full generality of systems and sign-changing solutions. The two restrictions on exponents are connected to the construction of intrinsic cylinders and the Sobolev embeddings. While the lower bound $2n/(n+2)$ also appears in the analogous results for the p -Laplacian (1.3) (see [13]), the upper bound does not. Our contribution is to remove it when dealing with non-negative solutions to equations. Whether or not the upper bound can be removed even in the vectorial setting remains an open problem.

2. Preliminaries

2.1. Notation

We work on $\mathbb{R} \times \mathbb{R}^n$ where the first coordinate is called time and the remaining ones space. The dimension $n \geq 1$ is fixed throughout the paper. The symbols c and C refer to constants that only depend on quantities we do not keep track of. Their actual value may change from expression to expression even within a single line. Given two numbers $a, b > 0$, such that $a \leq cb$ holds for a constant c as above, we sometimes write $a \lesssim b$. The binary relations $\gtrsim$ and $\sim$ are defined analogously. We write χ_E for the indicator function of a set $E \subset \mathbb{R}^{1+n}$.

Given a (positive locally finite Borel) measure μ , usually given by a locally integrable weight function η , we denote the mean value over a Borel set E of positive measure by

$$\frac{1}{\mu(E)} \int_E f \, d\mu = \int_E f \, d\mu = (f)_E^\mu.$$

In case μ is the Lebesgue measure, it is suppressed from the notation. We write $|E|$ for the Lebesgue outer measure of a set E . We use the same notation for both n -dimensional and $(n+1)$ -dimensional Lebesgue measures. It will always be clear from the context which one is being used.

Given $x \in \mathbb{R}^n$ and $r > 0$, we write $B_r(x) = \{y \in \mathbb{R}^n : |x - y| < r\}$ for a Euclidean ball. If the center x and the radius r are clear from the context or not important for the argument, we suppress them from the notation. Even the letter B alone is reserved for n -dimensional Euclidean balls as above. Similarly, given $t \in \mathbb{R}$ and $h > 0$, we write $I_h(t) = (t - h/2, t + h/2)$ and omit h and t whenever we can without disturbing the reading of the argument.

Given two positive numbers r and s , we write $Q_{r,s}$ for the space time cylinder $I_s \times B_r$. We use the shorthand notation $bQ_{r,s} = Q_{br,bs}$ for concentric dilations. Similar notation is used for intervals and balls.

2.2. Solutions

Let $\Lambda \geq 1$ and $p > 1$. Let $A : \mathbb{R}^{n+1} \times \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a function measurable in each variable and satisfying the structural conditions

$$A(t, x, u, \xi) \cdot \xi \geq \Lambda^{-1} |\xi|^p, \quad |A(t, x, u, \xi)| \leq \Lambda |\xi|^{p-1}. \quad (2.1)$$

We study non-negative weak solutions to the equations

$$\frac{\partial u^{p-1}}{\partial t} - \operatorname{div} A(t, x, u, \nabla u) = 0.$$

Consider a space time cylinder $I_{r^p} \times B_r$. A function $u \in L_{loc}^p(I_{r^p}; W_{loc}^{1,p}(B_r))$ is a weak solution if

$$\iint A(t, x, u, \nabla u) \cdot \nabla \varphi \, dx dt - \iint u^{p-1} \cdot \partial_t \varphi \, dx dt = 0 \quad (2.2)$$

holds for all test functions $\varphi \in C_c^\infty(I_{r^p} \times B_r)$. If the left hand side is non-positive for all non-negative test functions, u is said to be a subsolution. If the left hand side is non-negative for all non-negative test functions, u is said to be a supersolution. By a standard approximation argument, we can use compactly supported Sobolev functions as test functions as opposed to smooth functions. In what follows, u will always denote a positive weak solution to the equation. As our main result is inherently local, we do not refer to the the cylinder $I_{r^p} \times B_r$ anymore but work as if it were the full space time.

2.3. Time derivative

As the solutions are not required to exhibit any a priori differentiability in the time variable, there is a technical difficulty when trying to use the solution itself as a test function. To overcome this problem, we can use a mollified version of the equation as an intermediate step in the proof. For a smooth and even function $\chi_{[-4^{-1}, 4^{-1}]} \leq \zeta \leq \chi_{[-2^{-1}, 2^{-1}]}$ and $\epsilon > 0$, we set for any locally integrable φ

$$\varphi_\epsilon(t, x) := \int_{\mathbb{R}} \varphi(s, x) \zeta\left(\frac{t-s}{\epsilon}\right) \frac{ds}{\epsilon}.$$

Using φ_ϵ with $\varphi \in C_c^\infty(\mathbb{R}^{1+n})$ as a test function, we can convert the Eq. (2.2) to

$$\iint A(t, x, u, \nabla u)_\epsilon \cdot \nabla \varphi \, dx dt - \iint (u^{p-1})_\epsilon \cdot \partial_t \varphi \, dx dt = 0$$

This together with the correct use of the mollified solution as a test function can then be used to justify certain computations to follow that we decided to keep at formal level for the sake of better readability.

2.4. Auxiliary inequalities

Given a Borel probability measure μ and $q \in [1, \infty)$, the mean value $(f)_E^\mu$ always satisfies

$$\left(\int_E |f - (f)_E^\mu|^q \, d\mu \right)^{\frac{1}{q}} \leq 2 \inf_c \left(\int_E |f - c|^q \, d\mu \right)^{\frac{1}{q}}.$$

We refer to this fact in its various forms as the *best constant property* of the mean value and it can be used to justify all occasions where we change a constant inside a mean oscillation integral as the one above.

In order to effectively carry out certain iterative arguments, we use the following lemma, which can be found as Lemma 6.1 on page 191 of [10].

Lemma 2.1. *Let $A, B, \alpha > 0$ and $\delta \in (0, 1)$. Let $0 < r < R < \infty$ and let Z be a bounded and positive function such that for all $r \leq \rho_1 < \rho_2 \leq R$ it holds*

$$Z(\rho_1) \leq A(\rho_2 - \rho_1)^{-\alpha} + B + \delta Z(\rho_2).$$

Then

$$Z(r) \leq c(\alpha, \delta) (A(R - r)^{-\alpha} + B).$$

2.5. Positivity

When it comes to Harnack estimates, there is some discrepancy in the positivity assumptions imposed on solutions in the literature, and we clarify that point here. For our estimates, we need not use the full strength of the Harnack inequality, but a much weaker supremum estimate for subsolutions will do. In particular, the use of Hölder continuity and strict positivity can be avoided.

We recall the following observation. Given $\epsilon > 0$ and a positive subsolution u , we let $u_\epsilon = \max(u, \epsilon)$. Consider a test function $\eta \in C_c^\infty(\mathbb{R}^{1+n})$. Following the proof of Lemma 1.1 of Section II in [4], we see that the choice of test function $\varphi = \eta(u_\epsilon - \epsilon)(u_\epsilon - \delta)^{-1}$ with $\delta \in (0, \epsilon)$ gives (using an approximation argument as in Sect. 2.3)

$$\begin{aligned} 0 &\geq \iint A(t, x, u, \nabla u) \cdot \nabla \varphi \, dx dt - \iint u^{p-1} \cdot \varphi_t \, dx dt \\ &= \iint_{\{u > \epsilon\}} \frac{u_\epsilon - \epsilon}{u_\epsilon - \delta} A(t, x, u_\epsilon, \nabla u_\epsilon) \cdot \nabla \eta \, dx dt \\ &\quad + \iint \frac{\eta(\epsilon - \delta)}{(u_\epsilon - \delta)^2} A(t, x, u, \nabla u) \cdot \nabla u_\epsilon \, dx dt \\ &\quad - \iint u^{p-1} \left(\eta_t \frac{u_\epsilon - \epsilon}{u_\epsilon - \delta} + \frac{\eta(\epsilon - \delta)}{(u_\epsilon - \delta)^2} (u_\epsilon)_t \right) \, dx dt \end{aligned}$$

$$\begin{aligned}
&\geq \iint_{\{u>\epsilon\}} \frac{u_\epsilon - \epsilon}{u_\epsilon - \delta} A(t, x, u_\epsilon, \nabla u_\epsilon) \cdot \nabla \eta \, dx dt \\
&\quad - \iint u_\epsilon^{p-1} \left(\eta_t \frac{u_\epsilon - \epsilon}{u_\epsilon - \delta} + \frac{\eta(\epsilon - \delta)}{(u_\epsilon - \delta)^2} (u_\epsilon)_t \right) dx dt \\
&\longrightarrow \iint A(t, x, u_\epsilon, \nabla u_\epsilon) \cdot \nabla \eta \, dx dt - \iint u_\epsilon^{p-1} \cdot \eta_t \, dx dt
\end{aligned}$$

as $\delta \rightarrow \epsilon$. We could extend the domain of integration on the last line from $\{u > \epsilon\}$ to $\mathbb{R}^{1+n}$ because $|A(t, x, u_\epsilon, \nabla u_\epsilon)| \leq \Lambda |\nabla u_\epsilon|^{p-1}$ by (2.1) and $\nabla u_\epsilon = 0$ almost everywhere in $\{u \leq \epsilon\}$. Hence the truncated function u_ϵ is a subsolution that is bounded from below by $\epsilon > 0$.

The following lemma is stated in [12] for subsolutions u with $u \geq \epsilon > 0$ but approximating by truncations as above, we can use it for all non-negative subsolutions $u \geq 0$.

Lemma 2.2. (Lemma 5.1 [12]). *Consider weak subsolutions to (2.1) and (2.2). There exist positive constants $C = C(n, p, \Lambda)$ and $\theta(n, p)$ such that for all $\sigma \in (1, 2)$, all $s > 0$ and all weak subsolutions $u \geq 0$ in*

$$Q_{2R, (2R)^p} = I_{(2R)^p} \times B_{2R}$$

it holds

$$\sup_{z \in Q_{R, R^p}} u(z) \leq \left(\frac{C}{(\sigma - 1)^\theta} \iint_{I_{(\sigma R)^p} \times B_{\sigma R}} u^s \, dx dt \right)^{1/s}.$$

2.6. Energy estimate

Next we derive an energy estimate for the solution. The proof is standard, but we repeat the short argument for completeness.

Lemma 2.3. (Caccioppoli estimate). *There is a constant $C = C(n, p, \Lambda)$ such that for all non-negative weak solutions u , for all $1 \leq a < b \leq 2$, and for all space time cylinders $Q_{r, r^p} = I_{r^p} \times B_r$*

$$\sup_{s \in I_{ar^p}} \int_{\{s\} \times B_{ar}} \left(\frac{u}{r} \right)^p dx + \iint_{Q_{ar, ar^p}} |\nabla u|^p \, dx dt \leq \frac{C}{(b-a)^p} \iint_{Q_{br, br^p}} \left(\frac{u}{r} \right)^p \, dx dt. \quad (2.3)$$

Proof. As the structure of the Eq. (2.2) is scaling and translation invariant, it suffices to prove the estimate in the case $Q = (-2^{-1}, 2^{-1}) \times B(0, 1)$. Consider a smooth function η with

$$\chi_{aQ} \leq \eta \leq \chi_{bQ}, \quad |\partial_t \eta| + |\nabla \eta| \leq 2(b-a)^{-1}.$$

Let $s \in (-a, a)$ and $h \in (0, a-s)$. Let τ be the piecewise linear function of one variable with

$$\chi_{(-\infty, s]} \leq \tau \leq \chi_{(-\infty, s+h]}, \quad |\tau'| \leq h^{-1}.$$

We use $\varphi = \eta^p \tau u$ as a test function in (2.2).

We start by estimating the first term on the left hand side of the claimed estimate. Note first that

$$u^{p-1}\varphi_t = u^{p-1}u_t\eta^p\tau + u^p(\eta^p\tau)_t = p^{-1}(u^p)_t\eta^p\tau + u^p(\eta^p\tau)_t.$$

Integrating by parts in the time variable and using the definition of τ

$$\begin{aligned} - \int_{-b}^{s+h} \int u^{p-1}\varphi_t dxdt &= - \left(1 - \frac{1}{p}\right) \int_{-b}^{s+h} \int u^p(\eta^p\tau)_t dxdt \\ &\geq \left(1 - \frac{1}{p}\right) \frac{1}{h} \int_s^{s+h} \int u^p\eta^p dxdt \\ &\quad - \frac{2(p-1)}{b-a} \iint_{bQ} u^p\eta^{p-1} dxdt. \end{aligned}$$

By the Eq. (2.2) and the structural condition (2.1)

$$\begin{aligned} - \int_{-b}^{s+h} \int u^{p-1}\partial_t\varphi dxdt &= - \iint A(t, x, u, \nabla u) \cdot (\eta^p\tau\nabla u + u\nabla(\eta^p\tau)) dxdt \\ &\leq -\frac{1}{\Lambda} \iint |\nabla u|^p\eta^p\tau dxdt + \frac{2p\Lambda}{b-a} \iint u|\nabla u|^{p-1}\eta^{p-1}\tau dxdt. \end{aligned} \quad (2.4)$$

Applying Young's inequality to the second term, we bound it by

$$\frac{2^p p^{p-1} \Lambda^{2p-1}}{(b-a)^p} \iint_{bQ} u^p\tau dxdt + \frac{(p-1)}{p\Lambda} \iint |\nabla u|^p\eta^p\tau dxdt.$$

Putting the estimates together we obtain

$$\begin{aligned} &\left(1 - \frac{1}{p}\right) \frac{1}{h} \int_s^{s+h} \int u^p\eta^p dxdt + \frac{1}{p\Lambda} \iint |\nabla u|^p\eta^p\tau dxdt \\ &\leq \frac{2(p-1)}{b-a} \iint u^p\eta^{p-1} dxdt + \frac{2^p p^{p-1} \Lambda^{2p-1}}{(b-a)^p} \iint_{bQ} u^p\tau dxdt. \end{aligned}$$

Sending $h \rightarrow 0$ and taking the supremum over $s \in I_{ar^p}$, we conclude the bound for the first term on the left hand side of (2.3). The second term is clear by sending $s \rightarrow a$. $\square$

Remark 2.4. By essentially the same proof, we see that there is $C = C(n, p, \Lambda)$ such that given a general cylinder $Q_{r,s} = I_s \times B_r$ and $1 \leq a < b \leq 2$, then for all non-negative solutions u

$$\begin{aligned} &\sup_{\tau \in I_{as}} \int_{\{\tau\} \times B_{ar}} \frac{u^p}{s} dx + \iint_{Q_{ar,as}} |\nabla u|^p dxdt \\ &\leq \frac{C}{b-a} \iint_{Q_{br,bs}} \frac{u|\nabla u|^{p-1}}{r} dxdt + \frac{C}{b-a} \iint_{Q_{br,bs}} \frac{u^p}{s} dxdt. \end{aligned} \quad (2.5)$$

We argue as before, but instead of applying Young's inequality to the right hand side of (2.4), we accept the second term to the right hand side of (2.5). This form of the energy estimate will also be needed later.

Lemma 2.5. *Let u be a non-negative weak solution to (2.2). Let $\eta \in C_c^\infty(\mathbb{R}^n)$. Then it holds*

$$\left| \int_{\mathbb{R}^n} u(s, x)^{p-1} \eta(x) dx - \int_{\mathbb{R}^n} u(x, t)^{p-1} \eta(x) dx \right| \leq \Lambda \int_s^t \int_{\mathbb{R}^n} |\nabla u|^{p-1} |\nabla \eta| dx dt.$$

Proof. Take the piecewise linear τ_h such that $\chi_{(s,t)} \leq \tau_h \leq \chi_{(s-h, t+h)}$ with $|(\tau_h)'| \leq h^{-1}$. Then the left hand side of the claimed inequality equals

$$\begin{aligned} & \lim_{h \rightarrow 0} \left| \iint u^{p-1} \partial_t (\tau_h \eta) dx dt \right| \\ &= \lim_{h \rightarrow 0} \left| \int_s^t \int_{\mathbb{R}^n} A(t, x, u, \nabla u) \cdot \nabla (\tau_h \eta) dx dt \right| \leq \Lambda \int_s^t \int_{\mathbb{R}^n} |\nabla u|^{p-1} |\nabla \eta| dx dt. \end{aligned}$$

□

3. Intrinsic cylinders

Consider a cylinder $Q_{\delta r, r^p}$ with $\delta \in (0, 1]$. Fix a number $K \geq 1$. Given a fixed value of $\alpha \geq 1$, we call a cylinder K -sub-intrinsic if

$$\frac{\left(\iint_{Q_{2\delta r, (2r)^p}} \left(\frac{u}{\delta r} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}}}{\left(\iint_{Q_{\delta r, r^p}} |\nabla u|^p dx dt \right)^{\frac{1}{p}}} \leq K \delta^{-\frac{p}{p-2}} \quad (3.1)$$

and K -super-intrinsic if

$$K \frac{\left(\iint_{Q_{\delta r, r^p}} \left(\frac{u}{\delta r} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}}}{\left(\iint_{Q_{2\delta r, (2r)^p}} |\nabla u|^p dx dt \right)^{\frac{1}{p}}} \geq \delta^{-\frac{p}{p-2}} \quad \text{or} \quad \delta^{-\frac{p}{p-2}} \leq K. \quad (3.2)$$

A cylinder that is both super-intrinsic and sub-intrinsic is said to be intrinsic. A general cylinder $Q_{\delta r, r^p}$ may or may not satisfy these conditions for a pair of values α and K . The argument in [1] is based on constructing a cover of the level set of the gradient of the solution so that every cylinder in the cover satisfies the conditions above with $\alpha = 1$. We carry out the corresponding construction for larger values of α .

Proposition 3.1. *Fix δ, r and a cylinder $Q_{\delta r, r}$. Let $\alpha \geq 1$ and assume that one of the alternatives in (3.2) holds. Then for a constant $C = C(n, p, \Lambda, \alpha, K)$*

$$\sup_{Q_{\delta r, r^p}} u \leq C \left(\iint_{Q_{2\delta r, (2r)^p}} u^p dx dt \right)^{1/p}.$$

Proof. We cover $Q_{\delta r, r^p}$ by cylinders Q_i of dimensions $(\delta r)^p \times \delta r$. We let $1 < \gamma < \beta < 2$, as we aim for applying the iteration Lemma 2.1, we can let all the constants appearing on the right hand side of the following estimates grow polynomially on $(\gamma - 1)^{-1}(\beta - \gamma)^{-1}$.

As $\gamma \in (1, 2)$, by Lemma 2.2

$$\sup_{Q_{\delta r, r^p}} u = \sup_i \sup_{Q_i} u \lesssim \sup_{t \in I_{(\gamma r)^p}} \left(\int_{B_{\delta \gamma r}} u(t, x)^p dx \right)^{1/p}.$$

By the Caccioppoli inequality for general cylinders (2.5)

$$\begin{aligned} & \sup_{t \in I_{(\gamma r)^p}} \int_{B_{\delta \gamma r}} \frac{u(t, x)^p}{r^p} dx + \iint_{Q_{\delta \gamma r, (\gamma r)^p}} |\nabla u|^p dx dt \\ & \lesssim \iint_{Q_{\beta \delta r, (\beta r)^p}} \frac{u |\nabla u|^{p-1}}{\delta r} dx dt + \iint_{Q_{\beta \delta r, (\beta r)^p}} \frac{u^p}{r^p} dx dt \end{aligned}$$

We assume that one of the alternatives in (3.2) holds. We start with the case when the first alternative in (3.2) holds.

First, note that as $1 < \beta < 2$, we know that $Q_{\beta \delta r, (\beta r)^p} \subset Q_{2\delta r, (2r)^p}$ and consequently (3.2) implies

$$\frac{\left(\iint_{Q_{\beta \delta r, (\beta r)^p}} \left(\frac{u}{\delta r} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}}}{\left(\iint_{Q_{\beta \delta r, (\beta r)^p}} |\nabla u|^p dx dt \right)^{\frac{1}{p}}} \gtrsim \delta^{-\frac{p}{p-2}}.$$

Using this as an upper bound for δ^{-p} , we estimate

$$\begin{aligned} & \frac{1}{\delta^p} \iint_{Q_{\beta \delta r, (\beta r)^p}} \frac{u |\nabla u|^{p-1}}{\delta r} dx dt \\ & \lesssim \left(\iint_{Q_{\beta \delta r, (\beta r)^p}} \left(\frac{u}{\delta r} \right)^{\alpha p} dx dt \right)^{\frac{p-2}{\alpha p}} \left(\iint_{Q_{\beta \delta r, (\beta r)^p}} |\nabla u|^p dx dt \right)^{-\frac{p-2}{p}} \\ & \quad \iint_{Q_{\beta \delta r, (\beta r)^p}} \frac{u |\nabla u|^{p-1}}{\delta r} dx dt. \end{aligned}$$

Applying Hölder's inequality to the third factor, we get an upper bound by

$$\left(\iint_{Q_{\beta \delta r, (\beta r)^p}} \left(\frac{u}{\delta r} \right)^{\alpha p} dx dt \right)^{\frac{p-2}{\alpha p}} \left(\iint_{Q_{\beta \delta r, (\beta r)^p}} |\nabla u|^p dx dt \right)^{\frac{1}{p}} \left(\iint_{Q_{\beta \delta r, (\beta r)^p}} \frac{u^p}{(\delta r)^p} dx dt \right)^{\frac{1}{p}}.$$

Applying Young's inequality with ϵ , we bound this by

$$\begin{aligned} & \epsilon \left[\left(\iint_{Q_{\beta \delta r, (\beta r)^p}} \left(\frac{u}{\delta r} \right)^{\alpha p} dx dt \right)^{\frac{p-2}{\alpha p}} \left(\iint_{Q_{\beta \delta r, (\beta r)^p}} |\nabla u|^p dx dt \right)^{\frac{1}{p}} \right]^{\frac{p}{p-1}} \\ & + C_\epsilon \iint_{Q_{\beta \delta r, (\beta r)^p}} \frac{u^p}{(\delta r)^p} dx dt. \end{aligned}$$

Bounding L^α norm by L^∞ norm, simplifying the exponents and applying Young's inequality again, we bound the quantity inside the square bracket by

$$\frac{p-2}{p-1} \sup_{Q_{\beta\delta r, (\beta r)^p}} \frac{u^p}{(\delta r)^p} + \frac{1}{p-1} \iint_{Q_{\beta\delta r, (\beta r)^p}} |\nabla u|^p dxdt.$$

Multiplying through by δ^p , we have concluded

$$\begin{aligned} \iint_{Q_{\beta\delta r, (\beta r)^p}} \frac{u|\nabla u|^{p-1}}{\delta r} dxdt &\leq \epsilon \left(\sup_{Q_{\beta\delta r, (\beta r)^p}} \frac{u^p}{r^p} \right. \\ &\quad \left. + \iint_{Q_{\beta\delta r, (\beta r)^p}} \delta^p |\nabla u|^p dxdt \right) + C \iint_{Q_{\beta\delta r, (\beta r)^p}} \frac{u^p}{r^p} dxdt \end{aligned}$$

so that in particular

$$\begin{aligned} \sup_{Q_{\delta r, r^p}} u(t, x)^p &+ \iint_{Q_{\delta\gamma r, (\gamma r)^p}} \delta^p r^p |\nabla u|^p dxdt \\ &\leq \epsilon \left(\sup_{Q_{\beta\delta r, (\beta r)^p}} u^p + \iint_{Q_{\beta\delta r, (\beta r)^p}} r^p \delta^p |\nabla u|^p dxdt \right) + C \iint_{Q_{\beta\delta r, (\beta r)^p}} u^p dxdt \end{aligned}$$

where the constant C grows polynomially in $\gamma - \beta$. This estimate is amenable for an application of the iteration lemma 2.1 so the proof is complete if $Q_{\delta r, r^p}$ satisfies the first condition in (3.2).

It remains to study the case when the second alternative in (3.2) holds instead of the first one. In that case we simply conclude

$$\iint_{Q_{\beta\delta r, (\beta r)^p}} \frac{u|\nabla u|^{p-1}}{\delta r} dxdt \lesssim \iint_{Q_{\beta\delta r, (\beta r)^p}} \frac{u|\nabla u|^{p-1}}{r} dxdt$$

so that by Young's inequality

$$\begin{aligned} \sup_{Q_{\delta r, r^p}} \frac{u^p}{r^p} &+ \iint_{Q_{\delta r, r^p}} |\nabla u|^p dxdt \\ &\leq \epsilon \left(\sup_{Q_{\beta\delta r, (\beta r)^p}} \frac{u^p}{r^p} + \iint_{Q_{\delta r, r^p}} |\nabla u|^p dxdt \right) + C \iint_{Q_{\beta r, (\beta r)^p}} \frac{u^p}{r^p} dxdt. \end{aligned}$$

Hence the proof is complete by Lemma 2.1. $\square$

4. Construction of a differentiation basis

We use the intrinsic scaling given by

$$\frac{s}{r^p} = \mu^{p-2}, \quad \mu = \frac{1}{\lambda} \left(\iint_{Q_{r,s}} \left(\frac{u}{r} \right)^{\alpha p} dxdt \right)^{\frac{1}{\alpha p}}$$

as a model for the construction of a basis of almost intrinsic cylinders.

As before, we keep $p > 2$ fixed throughout the section. We also fix $\alpha > (n/2)(1-p/2)$. Let $R > 0$ and consider a cylinder $Q_{R, R^p} = I_{R^p} \times B_R$. Let C_0

be a large constant whose exact value we will fix later. Consider a non-negative function $u \in L_{loc}^{\alpha p}(\mathbb{R}^{1+n})$, and consider numbers $\lambda \geq C_0 \lambda_0$ where

$$\lambda_0 = 1 + \left(\iint_{Q_{4R}, (4R)^p} \left(\frac{u}{R} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}}.$$

Given $z = (t, x) \in Q_{2R, (2R)^p}$ and $\rho \in (0, R]$, define

$$d_z(\rho) = \min_{r \in [\rho, R]} \sup \left\{ \delta \in (0, 1] : \left(\iint_{Q_{\delta r}, r^p} \left(\frac{u}{\delta r} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} \leq \delta^{-\frac{p}{p-2}} \lambda \right\}. \quad (4.1)$$

When z is fixed and no confusion can arise, we drop it from the notation. The minimum is taken in order to make $\rho \mapsto d_z(\rho)$ an increasing function. As it is not strictly increasing, we cannot directly invert it. We define instead for $\eta \in (0, 1]$.

$$\rho_{max}(z, \eta) = \max\{r : d_z(r) = \eta\}. \quad (4.2)$$

If no confusion can arise, we drop z from the notation. It either holds

$$\left(\iint_{Q_{\eta \rho_{max}(\eta), \rho_{max}(\eta)^p}} \left(\frac{u}{\eta r} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} = \eta^{-\frac{p}{p-2}} \lambda \quad (4.3)$$

or $\eta = 1$.

For brevity, we denote $S(z, \rho) := Q_{d_z(\rho)\rho, \rho^p}(z)$. Again, we drop z from the notation whenever convenient. We will use the sets $S(z, \rho)$ as a basis for the covering argument to follow. If the number λ is taken to be the appropriate mean value of the gradient of u , then the cylinders $S(z, \rho)$ will be sub-intrinsic in the sense of (3.1).

Proposition 4.1. *Let $p, \alpha, C_0, R, Q_{R, R^p}$ and u as above be given. Then*

- (i) *For all $z \in Q_{2R, (2R)^p}$, it holds $d_z(\rho) > 0$.*
- (ii) *For all $z \in Q_{2R, (2R)^p}$, $d_z(\rho)$ is a continuous and increasing function in ρ .*
- (iii) *If $0 < \rho \leq s \leq R$, then for all $z \in Q_{2R, (2R)^p}$ it holds $d_z(\rho) \leq d_z(s)$ and*

$$d_z(s) \leq \left(\frac{s}{\rho} \right)^{\frac{(n+p\alpha+p)(p-2)}{2\alpha p - n(p-2)}} d_z(\rho).$$

In particular $S(z, \rho) \subset S(z, s)$.

- (iv) *Let $1 < N \leq 4^{-1}(4C_0)^{(\alpha p)/(n+p+\alpha p)}$. If $\rho \in [R/N, 2R]$, then for all $z \in Q_{2R, (2R)^p}$*

$$d_z(\rho) = 1.$$

- (v) *There are constants $c_i = c_i(n, p, \alpha)$, $i \in \{1, 2\}$, so that if $z, w \in Q_{2R, (2R)^p}$, $0 < r \leq R$ and $S(z, r) \cap S(w, r) \neq \emptyset$, then*

$$S(z, r) \subset S(w, c_1 r)$$

and

$$\frac{1}{c_2}d_z(r) \leq d_w(r) \leq c_2d_z(r).$$

Proof. We start with the first item. Simplifying the expression defining $d_z(\rho)$ in (4.1), we write the relevant left and right hand sides as

$$L(z, r, \delta) = \left(\frac{1}{|Q_{r,r^p}|} \iint_{Q_{\delta r, r^p}} \left(\frac{u}{r} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} \leq \delta^{\frac{n}{\alpha p} - \frac{2}{p-2}} \lambda = R(\delta). \quad (4.4)$$

Now $L(z, r, \cdot)$ is increasing and $L(z, r, \delta) \rightarrow 0$ as $\delta \rightarrow 0$. The right hand side $R(\cdot)$ is decreasing and $R(\delta) \rightarrow \infty$ as $\delta \rightarrow 0$ because

$$\beta := \frac{n(p-2) - 2\alpha p}{\alpha p(p-2)} < 0.$$

This is the key point which imposes the lower bound on α . Hence there is a positive $\delta > 0$ so that $L(z, r, \delta) < R(\delta)$ and consequently $d_z(r) > 0$.

To verify the second item, we first consider

$$\tilde{d}_z(\rho) = \sup\{\delta \in (0, 1] : L(z, \rho, \delta) \leq R(\delta)\}. \quad (4.5)$$

We first show that $\tilde{d}(\rho)$ (we suppress z from now on) is continuous. Take any $r \in (0, R]$. We first show that $\limsup_{\rho \rightarrow r} \tilde{d}(\rho) \leq \tilde{d}(r)$. This is satisfied by definition in case $\tilde{d}(r) = 1$. In the other case, when $\tilde{d}(r) < 1$, then (again by definition), for all $1 > \delta > \tilde{d}(r)$ the condition (4.4) is violated so that $L(z, r, \delta) > R(\delta)$. As $L(z, \rho, \delta)$ is continuous in ρ , it holds $L(z, \rho, \delta) > R(\delta)$ for $|\rho - r|$ small enough. For such ρ we then have $\delta > \tilde{d}(\rho)$ and consequently $\limsup_{\rho \rightarrow r} \tilde{d}(\rho) \leq \tilde{d}(r)$. To prove $\liminf_{\rho \rightarrow r} \tilde{d}(\rho) \geq \tilde{d}(r)$, suppose for contradiction that $\liminf_{\rho \rightarrow r} \tilde{d}(\rho) = \theta \tilde{d}(r)$ for some $\theta < 1$. Then there is a sequence $\rho_i \rightarrow r$ so that $\tilde{d}(\rho_i) = \theta_i \tilde{d}(r)$ for all i and $\theta_i \rightarrow \theta < 1$. Moreover, as L is continuous and increasing and R continuous and decreasing, we see that the supremum in (4.5) is a maximum. Then

$$\begin{aligned} \tilde{d}(r)^{-\frac{p}{p-2}} &= \left(\iint_{Q_{\tilde{d}(r)r, r^p}} \left(\frac{u}{\tilde{d}(r)r} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} \\ &= \lim_{i \rightarrow \infty} \left(\iint_{Q_{\tilde{d}(r)\rho_i, r^p}} \left(\frac{u}{\tilde{d}(r)\rho_i} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} \\ &\geq \liminf_{i \rightarrow \infty} \theta_i^{\frac{n}{\alpha p} + 1} \left(\iint_{Q_{\theta_i \tilde{d}(r)\rho_i, r^p}} \left(\frac{u}{\theta_i \tilde{d}(r)\rho_i} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} \\ &= \theta^{\frac{n}{\alpha p} - \frac{2}{p-2}} \tilde{d}(r)^{-\frac{p}{p-2}} \end{aligned}$$

which is a contradiction as the exponent of θ is negative. Finally, taking the minimum preserves continuity so the continuity claim on $d_z(r)$ in the second item follows. The fact that $d_z(r)$ is monotone increasing is immediate as the definition (4.1) is in terms of a minimum.

The first inequality in the third item is an immediate consequence of the second item. To prove the other bound, take $0 < \rho \leq s \leq R$. Denote $\rho_{max}(d(\rho)) := \tilde{\rho}$ and $\delta := d(\rho) = d(\tilde{\rho})$. If $s \leq \tilde{\rho}$, it holds $d(\rho) = d(s)$ and the claimed bound is trivially satisfied. Hence we can assume $s > \tilde{\rho}$. We recall that by (4.3) Eq. (4.4) holds now with equality $L(z, \tilde{\rho}, \delta) = R(\delta)$. Then by the definitions

$$\begin{aligned} \delta^\beta &= \frac{1}{\lambda} \left(\frac{1}{|Q_{\tilde{\rho}, \tilde{\rho}^p}|} \iint_{Q_{\tilde{\rho}, \tilde{\rho}^p}} \left(\frac{u}{\tilde{\rho}} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} \\ &\leq \frac{1}{\lambda} \frac{s}{\tilde{\rho}} \left(\frac{|Q_{s, s^p}|}{|Q_{\tilde{\rho}, \tilde{\rho}^p}|} \right)^{\frac{1}{\alpha p}} \left(\frac{1}{|Q_{s, s^p}|} \iint_{Q_{d(s), s, s^p}} \left(\frac{u}{s} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} \\ &\leq \left(\frac{s}{\tilde{\rho}} \right)^{\frac{n+p(\alpha+1)}{\alpha p}} d(s)^\beta \end{aligned}$$

so that using $\beta < 0$, $\rho \leq \tilde{\rho}$ and the fact that $d_z(\cdot)$ is increasing we see

$$d(s) \leq \left(\frac{s}{\rho} \right)^{\frac{(n+p\alpha+p)(p-2)}{2\alpha p - n(p-2)}} d(\rho).$$

This concludes the proof of the third item.

It remains to prove the last two items in the list. Consider two points z and w and a length r so that $S(z, r) \cap S(w, r) \neq \emptyset$. We want to show $S(z, r) \subset S(w, c_1 r)$. This is trivially true for $c_1 = 3$ if $d_z(r) \leq d_w(r)$. Let $N \geq 1$. If $r \in [R/N, 2R]$, it holds

$$\begin{aligned} &\left(\iint_{Q_{\delta r, r^p}(w)} \left(\frac{u}{\delta r} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} \\ &\leq \left(\frac{|Q_{4R, (4R)^p}|}{|Q_{\delta r, r^p}|} \right)^{\frac{1}{\alpha p}} \frac{N \lambda_0}{\delta} \\ &\leq 4^{-1} (4N)^{\frac{n+p}{\alpha p} + 1} \delta^{-\frac{n}{\alpha p} - 1} \lambda_0 \leq \frac{(4N)^{\frac{n+p}{\alpha p} + 1}}{4C_0} \lambda \delta^{-\frac{n}{\alpha p} - 1} \end{aligned}$$

Hence, if we choose $C_0 \geq 4^{-1} (4N)^{\frac{n+p}{\alpha p} + 1}$, then any δ with

$$\delta^{-\frac{n}{\alpha p} - 1} \leq \delta^{-\frac{p}{p-2}}$$

satisfies $\delta \leq d_w(r)$. In particular because $\alpha > (n/2)(1-2/p)$, this is the case for all $\delta \in (0, 1]$. This proves the fourth item of the claim as a side product. When $r \geq R/10$, we can also use this with $N = 10$ to conclude $d_w(r) = 1 \geq d_z(r)$ so that the claim in the fifth item follows with $c_1 = 3$.

It remains to deal with the case when $r < R/10$ and $d_z(r) > d_w(r)$. For a moment, we denote

$$\delta_z = d_z(r), \quad \delta_w = d_w(r), \quad \rho_w = \rho_{max}(w, \delta_w)$$

Because $\delta_z > \delta_w$ and $\rho_w \geq r$, it follows

$$Q_{3\delta_z \rho_w, (3\rho_w)^p}(z) \supset Q_{\delta_w \rho_w, \rho_w^p}(w).$$

Then by monotonicity of $d_z(\cdot)$ and the definitions

$$\begin{aligned}
 \delta_z^{\frac{n}{\alpha p} - \frac{2}{p-2}} &\geq d_z(3\rho_w)^{\frac{n}{\alpha p} - \frac{2}{p-2}} \\
 &\geq \frac{1}{\lambda} \left(\frac{1}{|Q_{3\rho_w, (3\rho_w)^p}|} \iint_{Q_{3\delta_z \rho_w, (3\rho_w)^p}(z)} \left(\frac{u}{3\rho_w} \right)^{\alpha p} dxdt \right)^{\frac{1}{\alpha p}} \\
 &\geq \frac{1}{\lambda} \left(\frac{1}{|Q_{3\rho_w, (3\rho_w)^p}|} \iint_{Q_{\delta_w \rho_w, \rho_w^p}(w)} \left(\frac{u}{3\rho_w} \right)^{\alpha p} dxdt \right)^{\frac{1}{\alpha p}} \\
 &= 3^{-\frac{n+p}{\alpha p} - 1} \delta_w^{\frac{n}{\alpha p} - \frac{2}{p-2}}
 \end{aligned}$$

so that

$$\delta_z \leq 3^{-\frac{1}{\beta} \left(\frac{n+p}{\alpha p} + 1 \right)} \delta_w.$$

Consequently, there exist constants c_1 and c_2 as claimed. $\square$

The following lemma is a formulation of a Vitali type covering theorem, and we quote it from [8]. The properties established in the previous proposition show that the basis $\{S(z, r) : z \in \mathbb{R}^n, r > 0\}$ satisfies the assumptions.

Lemma 4.2. (Lemma 3.2 in [8]). *Let*

$$\{U(x, r) : x \in \Omega, r \in (0, R]\}$$

be a family of open sets which satisfy the following properties

(i) *Nestedness:*

$$\text{If } x \in \Omega \text{ and } 0 < s < r \leq R, \text{ then } U(x, s) \subset U(x, r);$$

(ii) *Almost uniform shape: There exists a constant $c_1 > 1$, such that*

$$\text{if } U(x, r) \cap U(y, r) \neq \emptyset, \text{ then } U(x, r) \subset U(y, c_1 r).$$

(iii) *Doubling property: There exists a constant $a > 1$ such that, for all $r \in (0, R]$,*

$$0 < |U(x, 2r)| \leq a|U(x, r)| < \infty.$$

Then we can find a countable and disjoint subfamily $\{U_i\}$, such that

$$\bigcup_{x \in \Omega} U(x, r_x) \subset \bigcup_i \tilde{U}_i,$$

where $\tilde{U}_i = U(x_i, 2c_1 r_{x_i})$, $|U_i| \sim |\tilde{U}_i|$ and

$$|\Omega| \leq c \sum_i |U_i|,$$

where the constant $c > 1$ depends only on c_1 , a , and the dimension M .

5. A Gehring type argument

To conclude the Gehring lemma for the gradient of the solution, we study coverings of its level sets. Although the construction of $S(z, r)$ only gave us sub-intrinsic cylinders, we can extract some additional information from the actual stopping time construction. The stopping cylinders from the sub-intrinsic basis will turn out to be intrinsic in the sense of (3.1) and (3.2).

Fix a center point in the space time, let $R > 0$ and fix

$$\alpha > \max \left\{ \frac{n}{2} \left(1 - \frac{2}{p} \right), 1 + \frac{p}{n} \right\}. \quad (5.1)$$

The lower bound $1 + p/n$ is related to use of (iv) of Proposition 4.1, and it is likely that it can be lowered by replacing the equation $d_z(\rho) = 1$ there by a smaller lower bound on $d_z(\rho)$ following the reasoning of [1]. However, as the particular choice of α only plays a qualitative role in our argument, due to Proposition 3.1, we do not attempt to optimize its exact value.

Fix a cylinder $Q_{4R, (4R)^p}$ and let

$$\lambda_0 = 1 + \left(\iint_{Q_{4R, (4R)^p}} \left(\frac{u}{4R} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} + \left(\iint_{Q_{4R, (4R)^p}} |\nabla u|^p dx dt \right)^{\frac{1}{p}}.$$

In what follows, we consider sets $S(z, \rho)$ constructed using a value of α as in (5.1). Fix $R \leq R_1 < R_2 \leq 2R$ and denote

$$E(r, \lambda) = Q_{r, r^p} \cap \{|\nabla u| > \lambda\} \cap \{\text{Lebesgue points of } |\nabla u|\} \quad (5.2)$$

for $r \in (0, 2R)$.

Lemma 5.1. *There exist constants $D = D(n, p, \Lambda)$ and $K = K(n, p, \Lambda, D)$ such that the following holds. Let u be a non-negative weak solution to (2.2) and (2.1). Let $C_0 = [4DR/(R_2 - R_1)]^{1+n/p}$ and $\lambda \geq C_0 \lambda_0$. Then for almost every $z \in E(R_1, \lambda)$ there is $\rho_z \in (0, (R_2 - R_1)/(2D))$ such that*

- *it holds for all $\rho \in [\rho_z, 2R)$*

$$\iint_{S(z, \rho_z)} |\nabla u|^p dx dt = \lambda^p \geq \iint_{S(z, \rho)} |\nabla u|^p dx dt;$$

- *every modified cylinder $\tilde{S}(z, \rho_z) := Q_{Dd(\rho_z)\rho_z, (D\rho_z)^p}$ is K -intrinsic with $\alpha = 1$ in the sense of (3.1) and (3.2).*

Proof. We consider a positive number D , whose exact value will be determined in the course of the proof. We set $C_0 = (4DR/(R_2 - R_1))^{(n+p)/p}$. Let $z \in E(R_1, \lambda)$ and $\rho \leq R_2 - R_1$. By the assumption $\lambda \geq C_0 \lambda_0$ and hence

$$\iint_{S(z, \rho)} |\nabla u|^p dx dt \leq \frac{(4R)^{n+p}}{d_z(\rho)^n \rho^{n+p}} \frac{\lambda^p}{C_0^p}. \quad (5.3)$$

Because $\alpha > 1 + p/n$, it holds

$$\frac{\alpha p}{n + p + \alpha p} \geq \frac{p}{n + p}$$

and because $C_0 \geq 1$ it further holds

$$C_0^{\frac{\alpha p}{n+p+\alpha p}} \geq \frac{4DR}{R_2 - R_1}$$

so that if $\rho \geq (R_2 - R_1)/(2D)$, then by the fourth item in Proposition 4.1 it holds $d_z(\rho) = 1$. For these values of ρ , the right hand side of (5.3) is bounded by

$$4^{n+p}(R/\rho)^{n+p}C_0^{-p}\lambda^p \leq \lambda^p.$$

As

$$\rho \mapsto \iint_{S(z,\rho)} |\nabla u|^p dxdt$$

is continuous, we define ρ_z to be the maximal number in $(0, (R_2 - R_1)/(2D)]$ such that

$$\iint_{S(z,\rho)} |\nabla u|^p dxdt \geq \lambda^p.$$

By the Lebesgue differentiation theorem such a number exists for almost every $z \in E(R_1, \lambda)$. By continuity, the inequality above holds as an equality for the maximal ρ_z , and the reverse inequality holds for all $\rho > \rho_z$ by maximality of ρ_z . This concludes the argument for the first item in the lemma.

To prove the second item, fix $z \in Q_{R_1, R_1^p}$ and take the cylinder $S(z, \rho_z) = Q_{d_z(\rho_z)\rho_z, \rho_z^p}$ as constructed above. We show first that $Q_{D\rho_z d(\rho_z), (D\rho_z)^p}$ satisfies (3.1) and (3.2) with α as specified in (5.1). We start with (3.1). Note that for all $s \in [\rho_z, R]$

$$\iint_{Q_{sd_z(\rho_z), s^p}} |\nabla u|^p dxdt < \left(\frac{d_z(s)}{d_z(\rho_z)} \right)^n \lambda^p \leq \left(\frac{s}{\rho_z} \right)^{\frac{n(n+p\alpha+p)(p-2)}{2\alpha p - n(p-2)}} \lambda^p, \quad (5.4)$$

as follows from item (iii) of Proposition 4.1. By (5.4) with $s = 2D\rho_z$

$$\iint_{Q_{2D\rho_z d_z(\rho_z), (2D\rho_z)^p}} |\nabla u|^p dxdt \lesssim \lambda^p \lesssim \iint_{Q_{2\rho_z d_z(\rho_z), (2\rho_z)^p}} |\nabla u|^p dxdt. \quad (5.5)$$

Further, by (ii) and (iii) of Proposition 4.1 $d_z(\rho_z) \sim d_z(2D\rho_z)$. This together with the definition of $d_z(\rho_z)$ and Eq. (5.5) implies

$$\begin{aligned} & \left(\iint_{Q_{2D\rho_z d_z(\rho_z), (2D\rho_z)^p}} \left(\frac{u}{d_z(\rho_z)\rho_z} \right)^{\alpha p} dxdt \right)^{\frac{1}{\alpha p}} \\ & \lesssim \left(\iint_{Q_{2D\rho_z d(2D\rho_z), (2D\rho_z)^p}} \left(\frac{u}{d_z(2D\rho_z)\rho_z} \right)^{\alpha p} dxdt \right)^{\frac{1}{\alpha p}} \\ & \lesssim d(2D\rho_z)^{-\frac{p}{p-2}} \lambda \lesssim d_z(\rho_z)^{-\frac{p}{p-2}} \iint_{Q_{D\rho_z d_z(\rho_z), (D\rho_z)^p}} |\nabla u|^p dxdt \end{aligned}$$

which is (3.1) for some value of K only depending on n, p, α and D .

Next we verify the other condition (3.2). We abbreviate $d_z(\rho_z) = \delta$. If $\delta = 1$, the second alternative in (3.2) is satisfied and there is nothing to prove. Assume $\delta < 1$ and consider first the case

$$\rho_z \leq \rho_{\max}(z, d_z(\rho_z)) \leq D\rho_z.$$

The function $\rho_{\max}$ is the one defined in (4.2). Then by (4.3) and (5.5)

$$\begin{aligned} \delta^{-\frac{p}{p-2}} &= \frac{1}{\lambda} \left(\iint_{Q_{\delta\rho_{\max}(z,\delta),\rho_{\max}(z,\delta)}^p} \left(\frac{u}{\delta\rho_{\max}(z,\delta)} \right)^{\alpha p} dxdt \right)^{\frac{1}{\alpha p}} \\ &\lesssim \left(\iint_{Q_{D\delta\rho_z,(D\rho_z)}^p} \left(\frac{u}{2D\delta\rho_z} \right)^{\alpha p} dxdt \right)^{\frac{1}{\alpha p}} \left(\iint_{Q_{2D\delta\rho_z,(2D\rho_z)}^p} |\nabla u|^p dxdt \right)^{-\frac{1}{p}} \end{aligned}$$

which is the first alternative in (3.2).

We are left with the case $\rho_{\max}(z, \delta) > D\rho_z$, and we shall show that the second alternative in (3.2) holds.

Set

$$\rho_* = \frac{\rho_{\max}(z, \delta)}{D}$$

so that $\rho_* \in (\rho_z, \rho_{\max}(z, \delta))$. Now by (4.3) and Proposition 3.1 we find

$$\begin{aligned} \delta^{-\frac{p}{p-2}} \lambda &= \left(\iint_{Q_{D\rho_*\delta,(D\rho_*)}^p} \left(\frac{u}{D\rho_*\delta} \right)^{\alpha p} dxdt \right)^{\frac{1}{\alpha p}} \\ &\leq C \left(\iint_{Q_{2D\rho_*\delta,(2D\rho_*)}^p} \left(\frac{u}{D\rho_*\delta} \right)^p dxdt \right)^{\frac{1}{p}}. \end{aligned}$$

None of our definitions applies to values of u in the large cylinder above, but we do know about the values of ∇u . On the right hand side of the display above, we estimate by the Poincaré inequality

$$\begin{aligned} &\left(\iint_{Q_{2D\rho_*\delta,(2D\rho_*)}^p} \left(\frac{u}{D\rho_*\delta} \right)^p dxdt \right)^{\frac{1}{p}} \\ &\leq (2D\rho_*)^{-1} \left(\iint_{Q_{2D\rho_*\delta,(2D\rho_*)}^p} |u(t, x) - u_{\{t\} \times B_{\delta\rho_*}}|^p dxdt \right)^{\frac{1}{p}} \\ &\quad + \frac{C}{D\rho_*\delta} \left(\int_{I_{(2D\rho_*)}^p} |u_{B_{\delta\rho_*}}|^p dxdt \right)^{\frac{1}{p}} \\ &\leq C \left(\iint_{Q_{2D\rho_*\delta,(2D\rho_*)}^p} |\nabla u|^p dxdt \right)^{1/p} \\ &\quad + \frac{C}{D\rho_*\delta} \left(\int_{I_{(2D\rho_*)}^p} |u_{B_{\delta\rho_*}}|^p dxdt \right)^{\frac{1}{p}}. \end{aligned}$$

By (5.5), the first term is bounded by $C\lambda$, which is good. The second term has a spatial support smaller than previously but still rather long support in time. This can be dealt with using the equation.

As $p \geq 2$, we can use Jensen's inequality to bound the second term by

$$\begin{aligned} & \frac{C}{D\rho_*\delta} \left(\int_{I_{(2D\rho_*)^p}} |(u^{p-1})_{B_{\delta\rho_*}}|^{p'} dx dt \right)^{\frac{1}{p}} \\ & \leq \frac{C}{D\rho_*\delta} \left(\int_{I_{(2D\rho_*)^p}} |(u^{p-1})_{B_{\delta\rho_*}} - (u^{p-1})_{Q_{\delta\rho_*, \rho_*^p}}|^{p'} dx dt \right)^{\frac{1}{p}} \\ & \quad + \frac{C}{D\rho_*\delta} (u^{p-1})_{Q_{\delta\rho_*, \rho_*^p}}^{\frac{1}{p-1}}. \end{aligned}$$

According to Lemma 2.5, Hölder's inequality and the definition of ρ_* and δ , the first term is bounded by

$$\frac{C}{D\rho_*\delta} \left(\frac{1}{(\delta\rho_*)^{n+1}} \iint_{Q_{2\delta\rho_*, (2D\rho_*)^p}} |\nabla u|^{p-1} dx dt \right)^{\frac{1}{p-1}} \leq C\delta^{-\frac{p}{p-1}} \lambda.$$

Writing $q = p - 1$ and $q' = (p - 1)/(p - 2)$, we use Young's inequality with ϵ to bound

$$C\delta^{-\frac{p}{p-1}} \lambda = (\lambda^{\frac{1}{q'}} \delta^{-\frac{p}{p-1}}) \cdot (C\lambda^{\frac{1}{q}}) \leq \epsilon\lambda\delta^{-\frac{p}{p-2}} + C_\epsilon\lambda.$$

As the first term can be sent back to the left hand side, we are done with this expression. Finally, by Hölder's inequality

$$\frac{C}{D\rho_*\delta} (u^{p-1})_{Q_{\delta\rho_*, \rho_*^p}}^{\frac{1}{p-1}} \leq \frac{C}{D} \left(\iint_{Q_{\rho_*\delta, \rho_*^p}} \left(\frac{u}{\rho_*\delta} \right)^{\alpha p} dx dt \right)^{\frac{1}{\alpha p}} \leq \frac{C_2}{D} \delta^{-\frac{p}{p-2}} \lambda.$$

Altogether we have shown

$$\lambda\delta^{-\frac{p}{p-2}} \leq C_1\lambda + \epsilon\lambda\delta^{-\frac{p}{p-2}} + \frac{C_2}{D}\delta^{-\frac{p}{p-2}}\lambda.$$

As C_2 is independent of D , we can choose D large enough so that $\delta^{-\frac{p}{p-2}} \leq C$ for a constant only depending on n, p, α and Λ . This is the second case of (3.2).

As we have shown that (3.1) and (3.2) hold for $Q_{D\delta\rho_z, (D\delta\rho_z)^p}$ with α as specified in (5.1), it follows from Proposition 3.1 and the fact

$$\iint_{Q_{2D\delta\rho_z, (2D\delta\rho_z)^p}} |\nabla u|^p dx dt \sim \iint_{Q_{2\delta\rho_z, (2\delta\rho_z)^p}} |\nabla u|^p dx dt$$

due to the maximality of ρ_z that they also hold for $Q_{2D\delta\rho_z, (2D\delta\rho_z)^p}$ and $\alpha = 1$. $\square$

We can now use the following reverse Hölder inequality from [1] and the rest of the argument is standard.

Proposition 5.2. (Proposition 6.1 in [1]). *Let $Q_{\delta r, r^p}$ be such that (3.1) and (3.2) hold with $\alpha = 1$. Then*

$$\iint_{Q_{\delta r, r^p}} |\nabla u|^p dx dt \leq C \left(\iint_{Q_{2\delta r, (2r)^p}} |\nabla u|^q dx dt \right)^{\frac{p}{q}}$$

where $q = \max(np/(n+2), p-1)$ and $C = C(n, p, \Lambda, K)$.

Proposition 5.3. *It holds*

$$\iint_{E(R_1, \lambda)} |\nabla u(t, x)|^p dx dt \lesssim \iint_{E(R_2, \lambda)} \lambda^{p-q} |\nabla u(t, x)|^{q-p} dx dt$$

where $E(R_2, \lambda)$ is the set from (5.2) and λ as in Lemma 5.1.

Proof. The sets $\tilde{S}(z, r) = Q_{Drd_z(r), (Dr)^p}(z)$ are defined as the anisotropic (D^p, D) -dilations of $S(z, r)$ (as in Lemma 5.1). The basis $\tilde{S}(z, r)$ satisfies the hypotheses of Lemma 4.2 as can be seen from Proposition 4.1. Consider the cover $\{\tilde{S}(z, \rho_z) : z \in E(R_1, \lambda)\}$ of the set $E(R_1, \lambda)$ where the cylinders $\tilde{S}(z, \rho_z)$ are the ones from Lemma 5.1 and the constant c_1 is as in Lemma 4.2. By Lemma 4.2, we can extract a countable collection of points $\{z_i\}$ so that

$$E(R_1, \lambda) \subset \bigcup_i \tilde{S}(z_i, 2c_1\rho_i) \subset E(R_2, \lambda), \quad \tilde{S}(z_i, \rho_i) \text{ are disjoint.}$$

Because for any $\epsilon > 0$

$$\begin{aligned} \lambda^p &\leq c \iint_{\tilde{S}(z_i, \rho_i)} |\nabla u(t, x)|^p dx dt \\ &\leq c \left(\iint_{\tilde{S}(z_i, \rho_i)} |\nabla u(t, x)|^q dx dt \right)^{\frac{p}{q}} \\ &\leq c\epsilon\lambda^p + c\lambda^{p-q} \cdot \frac{1}{|\tilde{S}(z_i, \rho_i)|} \iint_{\tilde{S}(z_i, \rho_i) \cap E(R_2, \epsilon\lambda)} |\nabla u(t, x)|^q dx dt, \end{aligned}$$

it holds for $\epsilon = (2c)^{-1}$ that

$$\begin{aligned} \iint_{\tilde{S}(z_i, \rho_i)} |\nabla u(t, x)|^p dx dt &\leq c\lambda^p \\ &\lesssim \frac{1}{|\tilde{S}(z_i, \rho_i)|} \iint_{\tilde{S}(z_i, \rho_i) \cap E(R_2, \epsilon\lambda)} \lambda^{p-q} |\nabla u(t, x)|^q dx dt. \end{aligned}$$

By the inequality in Lemma 5.1, it holds

$$\iint_{\tilde{S}(z_i, 2c_1\rho_i)} |\nabla u(t, x)|^p dx dt \lesssim \lambda^p \lesssim \iint_{\tilde{S}(z_i, \rho_i)} |\nabla u(t, x)|^p dx dt$$

so that

$$\begin{aligned} \int_{E(R_1, \lambda)} |\nabla u(t, x)|^p dx dt &\leq \sum_i \iint_{\tilde{S}(z_i, 2c_1\rho_i)} |\nabla u(t, x)|^p dx dt \\ &\lesssim \sum_i \iint_{\tilde{S}(z_i, \rho_i)} |\nabla u(t, x)|^p dx dt \end{aligned}$$

$$\begin{aligned}
&\lesssim \sum_i \iint_{\tilde{S}(z_i, \rho_i) \cap E(R_2, \epsilon\lambda)} \lambda^{p-q} |\nabla u(t, x)|^q dx dt \\
&\lesssim \iint_{E(R_2, \epsilon\lambda)} \lambda^{p-q} |\nabla u(t, x)|^q dx dt.
\end{aligned}$$

Because of the (trivial) estimate

$$\int_{E(R_1, \epsilon\lambda) \setminus E(R_1, \lambda)} |\nabla u(t, x)|^p dx dt \leq \iint_{E(R_2, \epsilon\lambda)} \lambda^{p-q} |\nabla u(t, x)|^q dx dt$$

and the fact that ϵ only depends on the data, we conclude

$$\int_{E(R_1, \lambda)} |\nabla u(t, x)|^p dx dt \lesssim \iint_{E(R_2, \lambda)} \lambda^{p-q} |\nabla u(t, x)|^q dx dt$$

as was claimed. $\square$

Proof of Theorem 1.1. Given the Proposition 5.3, the theorem follows by a standard argument for Gehring's lemma. This has been done, for instance, in section 7.6 of [1] starting from the inequality as given in Proposition 5.3. The result in [1] comes with an additional constant term 1 on the right hand side, but that can be removed as the structure of the PDE is invariant under scaling. Indeed, by applying the result to $u(\delta^{-p}t, \delta^{-1}x)$ on $Q_{\delta\rho, (\delta\rho)^p}$ and sending $\delta \rightarrow 0$ one recovers the scaling invariant version of the estimate. $\square$

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Olli Saari
Mathematical Institute
University of Bonn
Endenicher Allee 60
53115 Bonn
Germany
e-mail: saari@math.uni-bonn.de

Sebastian Schwarzacher
Katedra matematické analýzy
Matematicko-fyzikální fakulta Univerzity Karlovy
Sokolovská 83
186 75 Prague 8
Czech Republic
e-mail: schwarz@karlin.mff.cuni.cz

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