# A Characterization of Homothetic Simplices 

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#### Abstract

It is proved that two convex bodies $K_{1}, K_{2} \subset E^{d}$ are homothetic simplices if and only if the $d$-dimensional intersections $K_{1} \cap\left(z+K_{2}\right), z \in E^{d}$, belong to at most countably many homothety equivalence classes of convex bodies in $E^{d}$.


## 1. Introduction

In 1956 Choquet [4] defined a simplex (afterwards called a Choquet simplex) as a convex set $S$ in linear space $E$ such that for any two homothetic copies of $S$ their intersection, if nonempty, is again a homothetic copy of $S$ :

$$
\begin{equation*}
(z+\mu S) \cap(y+v S)=x+\lambda S, \quad z, y, x \in E, \quad \mu, v, \lambda \geq 0 . \tag{1}
\end{equation*}
$$

By using the technique of representing measures (see, e.g., [19]), it was shown later that a finite-dimensional compact Choquet simplex is a simplex in the usual sense, i.e., it is the convex hull of finitely many affinely independent points.

Independently of Choquet, Rogers and Shephard [20] gave a geometric proof of the assertion that a convex body $K$ in the $d$-dimensional linear space $E^{d}$ is a simplex if and only if every nonempty intersection of $K$ and a translate of $K$ is homothetic to $K$ :

$$
\begin{equation*}
K \cap(z+K)=x+\lambda K, \quad z, x \in E^{d}, \quad \lambda \geq 0 . \tag{2}
\end{equation*}
$$

In fact, analysis of their proof shows that a convex body $K \subset E^{d}$ is a simplex provided all $d$-dimensional intersections $K \cap(z+K), z \in E^{d}$, are homothetic copies of $K$. The original proof of Rogers and Shephard is rather long. A shorter proof for convex

[^0]polytopes was given by Eggleston et al. [8], and for arbitrary convex bodies by Martini [17] (see also pp. 411-412 of [23]).

These two approaches were developed in various directions. Gruber [12] has shown that vectors $z$ from (2) can be chosen within an arbitrarily small neighborhood of the origin of $E^{d}$. He also proved that $K$ can be considered a priori as a compact set with nonempty interior, not necessarily convex (see [15] for additional results).

For further development of Rogers and Shephard's assertion, leading to characterizations of direct linear sums of simplices and simplicial cones, see [21], [22], [13], [14], [16], and [18]. We mention here the following result by Gruber [13], [16]: a convex body $K \subset E^{d}$ is the direct sum of simplices if and only if all $d$-dimensional intersections $K \cap(z+K), z \in E^{d}$, are affine images of $K$.

In 1970 Simons [24] proved that a bounded Choquet simplex in $E^{d}$ is the intersection of $d+1$ half-spaces, each of them being open or closed. Independently, this assertion was strengthened by Eggleston [7] who showed, confirming a conjecture of Gruber [12], that a bounded measurable set of positive measure in $E^{d}$ satisfying condition (2) is the interior of a $d$-simplex together with the relative interiors of some of its faces. Bair and Fourneau [2] proved that a closed, unbounded, and line-free Choquet simplex in $E^{d}$ is a convex cone whose base is a $k$-simplex $(k \leq d)$. Fourneau [9]-[11] studied nonclosed unbounded Choquet simplices in $E^{d}$ (see also [1] and [3]).

In what follows, by a convex body in $E^{d}$ we mean a compact convex set with nonempty interior. The usual abbreviations int $K$ and $\exp K$ are taken for the interior and the set of exposed points of a convex body $K$, respectively; rint $F$ serves for the relative interior of a convex set $F \subset E^{d}$, and $\left.[v, w],\right] v, w[$ stand for closed and open line segments, both with the endpoints $v, w$. By a convex $d$-polytope we mean a convex polytope of dimension $d$. A facet of a convex $d$-polytope is any of its $(d-1)$-dimensional faces. We denote by $N(Q)$ the family of outward unit normals to the facets of a convex $d$-polytope $Q \subset E^{d}$.

Two convex bodies $K, L \subset E^{d}$ are called homothetic provided $K=x+\lambda L$ for a vector $x \in E^{d}$ and a real number $\lambda>0$. Clearly, the relation of homothety is reflexive, symmetric, and transitive, i.e., it is a relation of equivalence. Hence the family of convex bodies in $E^{d}$ can be considered as the union of pairwise disjoint subfamilies such that any two convex bodies in $E^{d}$ belong to the same subfamily if and only if they are homothetic. We call these subfamilies homothety classes.

## 2. Main Result

The assertion by Rogers and Shephard can be formulated in terms of the homothety relation as follows: a convex body $K \subset E^{d}$ is a simplex if and only if the $d$-dimensional intersections $K \cap(z+K), z \in E^{d}$, belong to a unique homothety class (namely, the class containing $K$ ). Based on this, we formulate the main result of the paper.

Theorem. For convex bodies $K_{1}, K_{2} \subset E^{d}, d \geq 1$, the following conditions are equivalent:
(1) $K_{1}$ and $K_{2}$ are homothetic d-simplices.
(2) The d-dimensional intersections $K_{1} \cap\left(z+K_{2}\right), z \in E^{d}$, belong to a unique homothety class of convex bodies.
(3) The d-dimensional intersections $K_{1} \cap\left(z+K_{2}\right), z \in E^{d}$, belong to at most countably many homothety classes of convex bodies.

Based on the result by Gruber mentioned above we formulate the following problem, where affine equivalence classes are defined analogously to homothety classes.

Problem. Is it true that for convex bodies $K_{1}, K_{2} \subset E^{d}, d \geq 1$, the following three conditions are equivalent?
(1) $K_{1}$ and $K_{2}$ can be represented as direct sums

$$
K_{1}=L_{1} \oplus \cdots \oplus L_{t}, \quad K_{2}=M_{1} \oplus \cdots \oplus M_{t}, \quad t \geq 1,
$$

such that $L_{i}$ and $M_{i}$ are homothetic simplices for all $i=1, \ldots, t$.
(2) The $d$-dimensional intersections $K_{1} \cap\left(z+K_{2}\right), z \in E^{d}$, belong to a unique affine equivalence class of convex bodies.
(3) The $d$-dimensional intersections $K_{1} \cap\left(z+K_{2}\right), z \in E^{d}$, belong to at most countably many affine equivalence classes of convex bodies.

## 3. Proof of the Theorem

(1) $\Rightarrow$ (2) We can represent $K_{1}$ in a suitable coordinate system of $E^{d}$ as

$$
K_{1}=\left\{\left(\xi_{1}, \ldots, \xi_{d}\right) \in E^{d}: \xi_{1} \geq 0, \ldots, \xi_{d} \geq 0, \xi_{1}+\cdots+\xi_{d} \leq 1\right\}
$$

If $K_{2}=z+\mu K_{1}$, with $z=\left(\eta_{1}, \ldots, \eta_{d}\right) \in E^{d}$ and $\mu>0$, then
$K_{2}=\left\{\left(\xi_{1}, \ldots, \xi_{d}\right) \in E^{d}: \xi_{1} \geq \eta_{1}, \ldots, \xi_{d} \geq \eta_{d}, \xi_{1}+\cdots+\xi_{d} \leq \mu+\eta_{1}+\cdots+\eta_{d}\right\}$.
In this case

$$
\begin{aligned}
K_{1} \cap K_{2}= & \left\{\left(\xi_{1}, \ldots, \xi_{d}\right) \in E^{d}: \xi_{1} \geq \max \left\{0, \eta_{1}\right\}, \ldots, \xi_{d} \geq \max \left\{0, \eta_{d}\right\},\right. \\
& \left.\xi_{1}+\cdots+\xi_{d} \leq \min \left\{1, \mu+\eta_{1}+\cdots+\eta_{d}\right\}\right\} .
\end{aligned}
$$

Clearly, the intersection $K_{1} \cap K_{2}$ is $d$-dimensional if and only if

$$
\min \left\{1, \mu+\eta_{1}+\cdots+\eta_{d}\right\}>\left(\max \left\{0, \eta_{1}\right\}+\cdots+\max \left\{0, \eta_{d}\right\}\right)
$$

One has $K_{1} \cap K_{2}=x+\lambda K_{1}$, where $x=\left(\max \left\{0, \eta_{1}\right\}, \ldots, \max \left\{0, \eta_{d}\right\}\right)$ and

$$
\lambda=\min \left\{1, \mu+\eta_{1}+\cdots+\eta_{d}\right\}-\left(\max \left\{0, \eta_{1}\right\}+\cdots+\max \left\{0, \eta_{d}\right\}\right) .
$$

(2) $\Rightarrow$ (3) Trivial.
(3) $\Rightarrow$ (1) We prove this implication by induction on $d=\operatorname{dim} E^{d}$. The case $d=1$ trivially holds. Assume that (3) $\Rightarrow$ (1) for all $d \leq n-1, n \geq 2$, and let $K_{1}, K_{2}$ be convex bodies in $E^{n}$, satisfying condition (3) with $n$ instead of $d$. We divide our consideration into a sequence of lemmas.

## Lemma 1. Both $K_{1}$ and $K_{2}$ are convex $n$-polytopes.

Proof. Assume that $K_{1}$ is not a polytope (the case when $K_{2}$ is not a polytope is considered similarly). Then the set $\exp K_{1}$ is infinite and has at least one point, say $a$, of accumulation. Denote by $H_{1}$ and $H_{1}^{\prime}$ parallel hyperplanes both supporting $K_{1}$ such that $a \in H_{1} \cap K_{1}$. Choose any point $a^{\prime} \in H_{1}^{\prime} \cap K_{1}$.

Clearly, there is a translate $z+K_{2}$ such that $a \in \operatorname{int}\left(z+K_{2}\right)$ and one of the two hyperplanes supporting $z+K_{2}$ and parallel to $H_{1}$ intersects the open line segment ] $a, a^{\prime}$ [. Denote this hyperplane by $H_{2}$. Choose two distinct points $b, c \in \exp K_{1}$ so close to $a$ that $b, c \in \operatorname{int}\left(z+K_{2}\right)$. By a continuity argument, there is a real number $\varphi>0$ such that the set $\{a, b, c\}$ lies in the interior of the body $\varepsilon\left(a-a^{\prime}\right)+z+K_{2}$ for all $\left.\varepsilon \in\right] 0, \varphi[$.

Now choose two closed half-spaces, say $P_{b}$ and $P_{c}$, satisfying $K_{1} \cap P_{b}=\{b\}$ and $K_{1} \cap P_{c}=\{c\}$. By the construction above, both points $b$ and $c$ are exposed for every convex body

$$
\left.M(\varepsilon):=K_{1} \cap\left(\varepsilon\left(a-a^{\prime}\right)+z+K_{2}\right), \quad \varepsilon \in\right] 0, \varphi[
$$

and $M(\varepsilon) \cap P_{b}=\{b\}, M(\varepsilon) \cap P_{c}=\{c\}$.
Due to condition (3), the bodies $M(\varepsilon), \varepsilon \in] 0, \varphi[$, belong to at most countably many homothety classes. Hence there are at least two distinct (in fact, uncountably many) homothetic bodies $\left.M\left(\varepsilon_{1}\right), M\left(\varepsilon_{2}\right), \varepsilon_{1}, \varepsilon_{2} \in\right] 0, \varphi\left[\right.$. Let $\varepsilon_{1}<\varepsilon_{2}$. Then the width of $M\left(\varepsilon_{1}\right)$ in the direction $l$ orthogonal to $H_{1}$ is smaller than the width of $M\left(\varepsilon_{2}\right)$ in the same direction. Therefore $M\left(\varepsilon_{1}\right)$ is a smaller copy of $M\left(\varepsilon_{2}\right)$ :

$$
M\left(\varepsilon_{1}\right)=x+\lambda M\left(\varepsilon_{2}\right), \quad x \in E^{n}, \quad 0<\lambda<1
$$

and from $M\left(\varepsilon_{2}\right) \cap P_{b}=\{b\}$ we deduce

$$
M\left(\varepsilon_{1}\right) \cap\left(x+\lambda P_{b}\right)=\left(x+\lambda M\left(\varepsilon_{2}\right)\right) \cap\left(x+\lambda P_{b}\right)=x+\lambda\left(M\left(\varepsilon_{2}\right) \cap P_{b}\right)=\{x+\lambda b\} .
$$

On the other hand, $M\left(\varepsilon_{1}\right) \cap P_{b}=\{b\}$. Since the half-space $x+\lambda P_{b}$ is a translate of $P_{b}$, both $P_{b}$ and $x+\lambda P_{b}$ support $M\left(\varepsilon_{1}\right)$ at the same exposed point, i.e., $b=x+\lambda b$.

In a similar way, $c=x+\lambda c$. Thus $b-c=\lambda(b-c)$, contradicting $b \neq c$ and $0<\lambda<1$. Hence $K_{1}$ is a convex $n$-polytope.

Lemma 2. The polytopes $K_{1}$ and $K_{2}$ have the same family of outward unit normals to their facets: $N\left(K_{1}\right)=N\left(K_{2}\right)$.

Proof. By a symmetry argument, it is sufficient to prove the inclusion $N\left(K_{2}\right) \subset N\left(K_{1}\right)$. Let $e \in N\left(K_{2}\right)$ and $F$ be the facet of $K_{2}$ with the outward unit normal $e$. Choose a point $v \in \operatorname{rint} F$. Denote by $H_{2}$ the hyperplane containing $F$ and by $P_{2}$ the closed half-space bounded by $H_{2}$ and containing $K_{2}$.

Assume that $e \notin N\left(K_{1}\right)$, and let $P_{1}$ be the translate of $P_{2}$ containing $K_{1}$ such that the boundary hyperplane $H_{1}$ of $P_{1}$ supports $K_{1}$. By the assumption, the set $G=H_{1} \cap K_{1}$ is a face of $K_{1}$ of dimension at most $n-2$. Choose any vertex $w$ of $G$. Clearly, there are at least two distinct edges of $K_{1}$, say $[w, z]$ and $\left[w, z^{\prime}\right]$, both intersecting int $P_{1}$.

Now consider the polytope $w-v+K_{2}$. Since $v \in \operatorname{rint} F$, the vertex $w$ belongs to the relative interior of the facet $w-v+F$. Hence both line segments $[w, z],\left[w, z^{\prime}\right]$ intersect the interior of the polytope $w-v+K_{2}$. By a continuity argument, there is a real number $\varphi>0$ such that both line segments $[w, z]$ and $\left[w, z^{\prime}\right]$ intersect the relative interior of the facet $\varepsilon(z-w)+(w-v+F)$, as well as the interior of the $n$-polytope $\varepsilon(z-w)+\left(w-v+K_{2}\right)$ for all $\left.\varepsilon \in\right] 0, \varphi[$. It is easily seen that both points
$a(\varepsilon):=[w, z] \cap(\varepsilon(z-w)+(w-v+F)), \quad a^{\prime}(\varepsilon):=\left[w, z^{\prime}\right] \cap(\varepsilon(z-w)+(w-v+F))$
are vertices of the convex $n$-polytope

$$
M(\varepsilon):=K_{1} \cap\left(\varepsilon(z-w)+\left(w-v+K_{2}\right)\right)
$$

and the line segment

$$
s(\varepsilon):=[w, z] \cap\left(\varepsilon(z-w)+\left(w-v+K_{2}\right)\right)
$$

is an edge of $M(\varepsilon)$.
Summing up, we have that the family $\{M(\varepsilon), \varepsilon \in] 0, \varphi[ \}$ contains uncountably many pairwise nonhomothetic convex $n$-polytopes. Indeed, the distance between the vertices $a(\varepsilon)$ and $a^{\prime}(\varepsilon)$ continuously tends to zero when $\varepsilon \rightarrow 0$, while the length of the edge $s(\varepsilon)$ does not decrease. The last contradicts condition (3). Hence $e \in N\left(K_{1}\right)$ and $N\left(K_{2}\right) \subset$ $N\left(K_{1}\right)$.

Lemma 3. Any two facets of $K_{1}$ and $K_{2}$, respectively, with the same outward unit normal are homothetic $(n-1)$-simplices.

Proof. Let $F_{1}$ and $F_{2}$ be two facets of $K_{1}$ and $K_{2}$, respectively, having the same outward unit normal. Denote by $H$ the hyperplane containing $F_{1}$, and consider the family of translates $z+K_{2}, z \in E^{n}$, having the facets $z+F_{2}$ in $H$. Clearly, rint $F_{1} \cap \operatorname{rint}\left(z+F_{2}\right) \neq \emptyset$ implies int $K_{1} \cap \operatorname{int}\left(z+K_{2}\right) \neq \emptyset$. From condition (3) it follows that the family of convex ( $n-1$ )-polytopes $F_{1} \cap\left(z+F_{2}\right)$, being facets of the $n$-polytopes $K_{1} \cap\left(z+K_{2}\right)$, belongs to at most countably many homothety classes in the ( $n-1$ )-space $H$. By the inductive hypothesis, $F_{1}$ and $F_{2}$ are homothetic ( $n-1$ )-simplices.

From Lemmas 2 and 3 we deduce the following corollary.
Corollary 1. The polytopes $K_{1}$ and $K_{2}$ are homothetic.
Without loss of generality, we may assume in what follows that $K_{1}$ is not larger than $K_{2}: K_{1}=x+\lambda K_{2}$ with $0<\lambda \leq 1$.

To formulate the next lemma, we need a definition. Let $F$ be a facet of an $n$-polytope $Q \subset E^{n}$, and let $H, H^{\prime}$ be two parallel hyperplanes both supporting $Q$ such that $F \subset H$ (since $F$ is a facet, $H$ and $H^{\prime}$ are uniquely determined). The face $Q \cap H^{\prime}$ of $Q$ is called antipodal to $F$.

Lemma 4. For any facet of $K_{1}$ its antipodal face consists of a single point.

Proof. Assume that for a facet $F$ of $K_{1}$, its antipodal face $F^{\prime}$ contains more than one point. Let $H$ be the hyperplane containing $F$, and let $H^{\prime}$ be the hyperplane parallel to $H$ such that $H^{\prime} \cap K_{1}=F^{\prime}$. Choose an edge $\left[v_{1}, w_{1}\right]$ of $F^{\prime}$, and let $\left[v_{2}, w_{2}\right]$ be the corresponding edge of $K_{2}$ (under the homothety $K_{1}=x+\lambda K_{2}$ ). The polytope $v_{1}-v_{2}+K_{2}$ contains $K_{1}$ entirely, and the edge [ $v_{1}, w_{1}$ ] lies in the corresponding edge [ $v_{1}, v_{1}-v_{2}+w_{2}$ ] of $v_{1}-v_{2}+K_{2}$. Let $\varphi>0$ be such a small real number that rint $F$ has common points with every open set int $\left.\left(\varepsilon\left(w_{1}-v_{1}\right)+v_{1}-v_{2}+K_{2}\right), \varepsilon \in\right] 0, \varphi[$, and the line segments

$$
\left[v_{1}, w_{1}\right] \quad \text { and } \quad\left[\varphi\left(w_{1}-v_{1}\right)+v_{1}, \varphi\left(w_{1}-v_{1}\right)+v_{1}-v_{2}+w_{2}\right]
$$

have more than one point in common. We claim that the family

$$
\left\{M(\varepsilon):=K_{1} \cap\left(\varepsilon\left(w_{1}-v_{1}\right)+v_{1}-v_{2}+K_{2}\right), \varepsilon \in\right] 0, \varphi[ \}
$$

contains uncountably many pairwise nonhomothetic convex $n$-polytopes, contradicting condition (3). Indeed, it is easily seen that the line segment

$$
\left[v_{1}, w_{1}\right] \cap\left[\varepsilon\left(w_{1}-v_{1}\right)+v_{1}, \varepsilon\left(w_{1}-v_{1}\right)+v_{1}-v_{2}+w_{2}\right]
$$

is an edge of $M(\varepsilon)$, whose length continuously increases when $\varepsilon \rightarrow 0$. At the same time, the width of $M(\varepsilon)$ in the direction $l$ orthogonal to $H$ equals the distance between $H$ and $H^{\prime}$, i.e., it is independent of $\varepsilon$.

The next lemma and Corollary 1 give the final point in the proof of the theorem.
Lemma 5. $\quad K_{1}$ is a simplex.
Proof. Assume that $K_{1}$ is not a simplex and choose a facet $F_{1}$ of $K_{1}$. By Lemma 3, $F$ is an $(n-1)$-simplex. Let $v_{1}$ be the vertex of $K_{1}$ antipodal to $F_{1}$ (see Lemma 4). Denote by $H$ the hyperplane containing $F_{1}$ and by $H^{\prime}$ the hyperplane through $v_{1}$ parallel to $H$. Let $l$ be the direction orthogonal to $H$. By the assumption, $K_{1}$ is distinct from the $n$-simplex $\operatorname{conv}\left(v_{1} \cup F_{1}\right)$. Hence there is at least one facet $G_{1}$ of $K_{1}$, having $(n-2)$ dimensional intersection with $F_{1}$ and not containing $v_{1}$. Put $L=F_{1} \cap G_{1}$. Choose any point $w_{1} \in \operatorname{rint} L$. Since $v_{1} \notin F_{1} \cup G_{1}$, we easily deduce that the open line segment ] $v_{1}, w_{1}$ [ lies in int $K_{1}$. Denote by $z_{1}$ the vertex of $F_{1}$ which is not in $L$.

Now let $v_{2}, w_{2}$, and $z_{2}$ be the respective vertices of $K_{2}$ (under the homothety $K_{1}=$ $x+\lambda K_{2}$ ). Clearly, $K_{1} \subset K_{2}^{\prime}:=w_{1}-w_{2}+K_{2}$ and $\left.v_{1} \in\right] w_{1}, w_{1}-w_{2}+v_{2}\left[\subset\right.$ int $K_{2}^{\prime}$. By a continuity argument, there is a real number $\varphi>0$ such that $v_{1}$ belongs to every $\left.\operatorname{translate} \varepsilon\left(z_{1}-w_{1}\right)+K_{2}^{\prime}, \varepsilon \in\right] 0, \varphi[$. The number $\varphi$ can be also chosen so small that the intersection

$$
F(\varepsilon):=F_{1} \cap\left(\varepsilon\left(z_{1}-w_{1}\right)+w_{1}-w_{2}+F_{2}\right)
$$

is not empty for all $\varepsilon \in] 0, \varphi[$. By Lemma 3, every $F(\varepsilon), \varepsilon \in] 0, \varphi[$, is an ( $n-1$ )-simplex homothetic to $F_{1}$.

Finally, consider the family of convex $n$-polytopes

$$
\left\{M(\varepsilon):=K_{1} \cap\left(\varepsilon\left(z_{1}-w_{1}\right)+K_{2}^{\prime}\right), \varepsilon \in\right] 0, \varphi[ \}
$$

Clearly, $F(\varepsilon)$ is the facet of $M(\varepsilon)$ lying in $H$, and the size of $F(\varepsilon)$ continuously increases to the size of $F_{1}$ when $\varepsilon \rightarrow 0$. On the other hand, the width of $M(\varepsilon)$ in the direction $l$ equals the distance between $H$ and $H^{\prime}$, i.e., it is independent of $\varepsilon$.

Summing up, we deduce that the family $\{M(\varepsilon), \varepsilon \in] 0, \varphi[ \}$ contains uncountably many pairwise nonhomothetic convex $n$-polytopes, contradicting (3). Hence $K_{1}$ is a simplex.

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