# Perturbation theory for the logarithm of a positive operator 

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ABSTRACT: In various contexts in mathematical physics, such as out-of-equilibrium physics and the asymptotic information theory of many-body quantum systems, one needs to compute the logarithm of a positive unbounded operator. Examples include the von Neumann entropy of a density matrix and the flow of operators with the modular Hamiltonian in the Tomita-Takesaki theory. Often, one encounters the situation where the operator under consideration, which we denote by $\Delta$, can be related by a perturbative series to another operator $\Delta_{0}$, whose logarithm is known. We set up a perturbation theory for the logarithm $\log \Delta$. It turns out that the terms in the series possess a remarkable algebraic structure, which enables us to write them in the form of nested commutators plus some "contact terms".

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## 1 Introduction

In many different problems in mathematical physics, one needs to compute the logarithm of a positive operator. This is commonplace in asymptotic quantum information theory when one is interested in various quantities constructed from the logarithm of a density matrix. For example, given a reduced density matrix $\rho$, one needs to compute $\log \rho$ to find the von Neumann entropy and relative entropies. The modular Hamiltonian $K_{\rho}=-\log \rho$ generalizes the role Hamiltonian plays in a thermal state to an arbitrary state outside the equilibrium $\rho$. In the same way that equilibrium entropy and energy satisfy laws of thermodynamics, in out-of-equilibrium states $\rho$, the von Neumann entropy and the expectation value of a modular Hamiltonian satisfy laws of entanglement thermodynamics. Quantum relative entropy generalizes the concept of free energy difference to out-of-equilibrium states. Its calculation also requires calculating the logarithm of a positive operator.

In the past two decades, with growing applications of entanglement entropy in condensed matter and high-energy physics, there have been numerous calculations of such von Neumann and relative entropies in the thermodynamic or continuum limit. The problem is that most of such calculations rely on the analytic continuation method called "replica
trick" whose domain of validity remains physically obscure. The perturbation theory we set up here is a rigorous and unambiguous framework to resolve this problem.

In a general quantum system, in the Tomita-Takesaki theory, given the modular operator $\Delta_{\Omega}$ of a state $|\Omega\rangle$ or the relative modular operator of two states $\Delta_{\Psi \Omega}$ one needs to compute their logarithms to obtain the modular flow operator $\Delta_{\Omega}^{i t}$, or to calculate relative entropies. In this case, the positive operator in question, $\Delta_{\Omega}$, is unbounded.

Consider an unbounded positive operator $\Delta$. In general, obtaining $\log \Delta$ directly is difficult since it has a simple form only in the spectral decomposition of the operator $\Delta$. We consider the following situation: (i) $\Delta$ is related to some other positive operator $\Delta_{0}$ by a smooth deformation, i.e. there exists a continuous parameter $\lambda$ and a family of operators $\Delta(\lambda)$ that interpolate between $\Delta(0)=\Delta_{0}$ and $\Delta(1)=\Delta$; (ii) the logarithm $\log \Delta_{0}$ is known explicitly. Imagine setting up a perturbative series for $\log \Delta(\lambda)$ in terms of $\log \Delta_{0}$ for $\lambda$ small. If the perturbation series converges for $\lambda \leq 1$ one can extend the series to $\lambda=1$. It is the goal of this paper to set up such a perturbation theory. For a discussion of the fractional powers and the logarithm of bounded operators in the Hilbert space see [1, 2]. For bounded operators that belong to the Lie algebra of a Lie group one often uses the Baker-Campbell-Hausdorff (BCH) expansion to compute the logarithm; see [3]. See also recent discussions [4-9] in the context of quantum field theory.

Our main result is the following series expansion

$$
\begin{equation*}
\log \Delta_{0}-\log \Delta=\sum_{m=1}^{\infty} Q_{m} \tag{1.1}
\end{equation*}
$$

where $Q_{m}$ can be written in the form of nested commutators plus "contact" contributions

$$
\begin{equation*}
\left.Q_{m}=\frac{2 \pi}{m} \lim _{\epsilon_{i} \rightarrow 0} \int d t_{1} \int d t_{2} \ldots \int d t_{m} F_{\epsilon_{i}}\left(t_{1}, t_{2}, \ldots, t_{m}\right)\left[\cdots\left[\boldsymbol{\delta}\left(t_{1}\right), \boldsymbol{\delta}\left(t_{2}\right)\right], \cdots\right], \boldsymbol{\delta}\left(t_{m}\right)\right]+P_{m} \tag{1.2}
\end{equation*}
$$

and

$$
\begin{align*}
\boldsymbol{\delta}(t) & =\Delta_{0}^{-i t} \boldsymbol{\delta} \Delta_{0}^{i t}, \quad \boldsymbol{\delta}=\frac{\boldsymbol{\alpha}}{1-\boldsymbol{\alpha} / 2}, \quad \boldsymbol{\alpha}=1-\Delta_{0}^{-\frac{1}{2}} \Delta \Delta_{0}^{-\frac{1}{2}},  \tag{1.3}\\
F_{\epsilon_{i}}\left(t_{1}, t_{2}, \ldots, t_{m}\right) & =f\left(t_{1}\right) g_{\epsilon_{1}}\left(t_{2}-t_{1}\right) g_{\epsilon_{2}}\left(t_{3}-t_{2}\right) \ldots g_{\epsilon_{m-1}}\left(t_{m}-t_{m-1}\right) f\left(t_{m}\right),  \tag{1.4}\\
f(t) & =\frac{1}{2 \cosh (\pi t)}, \quad g_{\epsilon}(t)=\frac{i}{4}\left[\frac{1}{\sinh (\pi(t-i \epsilon))}+\frac{1}{\sinh (\pi(t+i \epsilon))}\right] . \tag{1.5}
\end{align*}
$$

In (1.2) $P_{m}$ are given by terms with two fewer integrals ("contact terms") whose structure
are a bit complicated and will be given later. The first few terms of this series are given by

$$
\begin{align*}
Q_{1}= & \frac{\pi}{2} \int_{-\infty}^{\infty} \frac{d t}{\cosh ^{2}(\pi t)} \boldsymbol{\delta}(t),  \tag{1.6}\\
Q_{2}= & \frac{\pi}{4} \lim _{\epsilon \rightarrow 0} \int_{-\infty}^{\infty} \frac{d t_{1} d t_{2}}{\cosh \left(\pi t_{1}\right) \cosh \left(\pi t_{2}\right)} g_{\epsilon}\left(t_{2}-t_{1}\right)\left[\boldsymbol{\delta}\left(t_{1}\right), \boldsymbol{\delta}\left(t_{2}\right)\right]  \tag{1.7}\\
Q_{3}= & \frac{\pi}{6} \lim _{\epsilon_{1}, \epsilon_{2} \rightarrow 0} \int \frac{d t_{1} d t_{2} d t_{3}}{\cosh \left(\pi t_{1}\right) \cosh \left(\pi t_{3}\right)} g_{\epsilon_{1}}\left(t_{2}-t_{1}\right) g_{\epsilon_{2}}\left(t_{3}-t_{2}\right)\left[\left[\boldsymbol{\delta}\left(t_{1}\right), \boldsymbol{\delta}\left(t_{2}\right)\right], \boldsymbol{\delta}\left(t_{3}\right)\right] \\
& +\frac{\pi}{24} \int \frac{\boldsymbol{\delta}(t)^{3}}{\cosh ^{2}(\pi t)}  \tag{1.8}\\
Q_{4}= & \lim _{\epsilon_{1}, \epsilon_{2}, \epsilon_{3} \rightarrow 0} \frac{\pi}{8} \int \frac{d t_{1} d t_{2} d t_{3} d t_{4} g_{\epsilon_{1}}\left(t_{2}-t_{1}\right) g_{\epsilon_{2}}\left(t_{3}-t_{2}\right) g_{\epsilon_{3}}\left(t_{4}-t_{3}\right)}{\cosh \left(\pi t_{1}\right) \cosh \left(\pi t_{4}\right)}\left[\left[\left[\boldsymbol{\delta}\left(t_{1}\right), \boldsymbol{\delta}\left(t_{2}\right)\right], \boldsymbol{\delta}\left(t_{3}\right)\right], \boldsymbol{\delta}\left(t_{4}\right)\right] \\
& +\frac{\pi}{32} \lim _{\epsilon \rightarrow 0} \int \frac{d t_{1} d t_{2} g_{\epsilon}\left(t_{2}-t_{1}\right)}{\cosh \left(\pi t_{1}\right) \cosh \left(\pi t_{2}\right)}\left\{\boldsymbol{\delta}\left(t_{2}\right),\left[\boldsymbol{\delta}\left(t_{1}\right), \boldsymbol{\delta}^{2}\left(t_{2}\right)\right]\right\} \tag{1.9}
\end{align*}
$$

It is important in (1.2) that performs the integrals keeping $\epsilon$ 's nonzero and then take the $\epsilon_{i} \rightarrow 0$ limit. We have included quintic contact term $P_{5}$ in appendix B.

In the special case the operators $\Delta$ and $\Delta_{0}$ are both bounded one can use the spectral representation of these operators to match our expansion and the BCH expansion order by order in $\lambda$.

The plan of the paper is as follows. In section 2, we outline the main steps leading to the proof of (1.2) and give explicit expressions for $F_{m}$. In section 3 and section 4 we fill in the details of the proof. In appendix A we give a simple example of harmonic oscillator to illustrate the use of (1.6)-(1.9). In appendix B we present the explicit expression for $P_{m=5}$. Appendices C-E include various fine details for the proof.

## 2 Outline of the proof

### 2.1 Setup

We start with the integral representation of the logarithm of an (positive invertible) operator $\Delta$ :

$$
\begin{equation*}
\log \Delta=\int_{0}^{\infty} d \beta\left(\frac{1}{1+\beta}-\frac{1}{\Delta+\beta}\right) . \tag{2.1}
\end{equation*}
$$

For unbounded operators $\Delta$, the integral on the right-hand-side should be thought of as a limit of Riemann sums in the strong operator topology induced by the domain of the $\operatorname{logarithm}$ of $\Delta$. Thus, we have the operator equality

$$
\begin{equation*}
\log \Delta_{0}-\log \Delta=\int_{0}^{\infty} d \beta\left(\frac{1}{\Delta+\beta}-\frac{1}{\Delta_{0}+\beta}\right)=\int_{0}^{\infty} d \beta \frac{1}{\Delta_{0}+\beta}\left(\Delta_{0}-\Delta\right) \frac{1}{\Delta+\beta} \tag{2.2}
\end{equation*}
$$

on the common domain of $\log \Delta_{0}$ and $\log \Delta$.
Introduce the operator

$$
\begin{equation*}
\alpha=1-\Delta_{0}^{-\frac{1}{2}} \Delta \Delta_{0}^{-\frac{1}{2}} \tag{2.3}
\end{equation*}
$$

which we take to depend on a continuous parameter $\lambda$ and vanish as $\lambda \rightarrow 0$. To lighten the notation, we keep the $\lambda$ dependence implicit. We stress that $\boldsymbol{\alpha}$ is an unbounded operator despite the fact that it is proportional to a small parameter $\lambda$.

Since the function $f(x)=\sqrt{x}(x+\beta)^{-1}$ is bounded for positive $\beta$ and $x$ the operator $\Delta^{1 / 2}(\Delta+\beta)^{-1}$ is a bounded operator in the Hilbert space. To make sense of the perturbation theory we assume that there exists a constant $c$ such that $\Delta(\lambda)<c \Delta_{0}$. As a result, the operator $\Delta_{0}^{1 / 2}(\Delta+\beta)^{-1}$ is also bounded. This is part of what we mean by $\lambda$ being a small perturbation.

For $\beta>0$, we define the bounded operator

$$
\begin{equation*}
A=\frac{\Delta_{0}^{\frac{1}{2}}}{\Delta_{0}+\beta} \tag{2.4}
\end{equation*}
$$

to rewrite the integrand of eq. (2.2) as

$$
\begin{align*}
\frac{1}{\Delta+\beta}-\frac{1}{\Delta_{0}+\beta} & =\frac{1}{\Delta_{0}+\beta}\left(\Delta_{0}-\Delta\right) \frac{1}{\Delta+\beta}  \tag{2.5}\\
& =A \boldsymbol{\alpha} \Delta_{0}^{1 / 2}(\Delta+\beta)^{-1}=A \boldsymbol{\alpha}\left(1-\Delta_{0}^{1 / 2} A \boldsymbol{\alpha}\right)^{-1} A  \tag{2.6}\\
& =A \boldsymbol{\delta}(1-B \boldsymbol{\delta})^{-1} A, \tag{2.7}
\end{align*}
$$

where we have introduced

$$
\begin{equation*}
\boldsymbol{\delta}=\frac{\boldsymbol{\alpha}}{1-\boldsymbol{\alpha} / 2}, \quad B=\frac{\Delta_{0}-\beta}{2\left(\Delta_{0}+\beta\right)} . \tag{2.8}
\end{equation*}
$$

One might want to naively expand $\left(1-\Delta_{0}^{\frac{1}{2}} A \boldsymbol{\alpha}\right)^{-1}$ in the second line of (2.5) in a power series of $\Delta_{0}^{\frac{1}{2}} A \boldsymbol{\alpha}$. But this is not a good expansion as $\Delta_{0}^{\frac{1}{2}} A \boldsymbol{\alpha}$ is an unbounded operator. This is similar the approach taken by [9]. It leads to singular integrals which can be sensible only if one provides a prescription to deform the integration Contour. To circumvent this problem, in the third line of (2.5) we introduced the operator $\boldsymbol{\delta}$, which is bounded with a norm $\|\boldsymbol{\delta}\| \leq 2$. To see this note that the spectrum of the closure of $\boldsymbol{\alpha}$ is contained in $(-\infty, 1)$ and $\frac{x}{1-x / 2}$ is a bounded function in the range $(-2,2)$. On a dense domain, $\boldsymbol{\delta}$ and its closure agree. Finally, expanding $B$ in the spectral decomposition of $\Delta_{0}$ we find that the spectrum of $B$ is contained in $\left(0, \frac{1}{2}\right)$. Therefore, $\|B\|=1 / 2$ and by the Cauchy-Schwarz inequality $\|B \boldsymbol{\delta}\| \leq 1$.

For $\|B \boldsymbol{\delta}\|<1$ expanding the third line of (2.5) in terms of $B \boldsymbol{\delta}$ gives a convergent series. In general, it is not possible to exclude the $\|B \boldsymbol{\delta}\|=1$ case. To justify our expansion, we will restrict to those vectors $|x\rangle$ in Hilbert space which satisfy

$$
\begin{equation*}
\| B \boldsymbol{\delta} A|x\rangle\|<\| A|x\rangle \| . \tag{2.9}
\end{equation*}
$$

On this set, we have the operator equality

$$
\begin{equation*}
A \boldsymbol{\delta}(1-B \boldsymbol{\delta})^{-1} A|x\rangle=A \boldsymbol{\delta} \sum_{n=0}^{\infty}(B \boldsymbol{\delta})^{n} A|x\rangle \tag{2.10}
\end{equation*}
$$

and the sum on the right-hand-side is pointwise convergent. We will not specify $|x\rangle$ below but its presence should always be kept in mind.

Using (2.5)-(2.10) in (2.2) we then find that

$$
\begin{equation*}
\log \Delta_{0}-\log \Delta=\int_{0}^{\infty} d \beta A \delta \sum_{n=0}^{\infty}(B \boldsymbol{\delta})^{n} A \tag{2.11}
\end{equation*}
$$

We now further rewrite the above expression using the one-parameter unitary group $\Delta_{0}^{i t}$ generated by $\log \Delta_{0}$. In particular, we use the following integral expressions for $A$ and $B$

$$
\begin{equation*}
A=\frac{1}{\sqrt{\beta}} \int_{-\infty}^{\infty} d t f(t) \beta^{i t} \Delta_{0}^{-i t}, \quad B=\lim _{\epsilon \rightarrow 0} \int_{-\infty}^{\infty} d t g_{\epsilon}(t) \beta^{i t} \Delta_{0}^{-i t} \tag{2.12}
\end{equation*}
$$

with

$$
\begin{equation*}
f(t)=\frac{1}{2 \cosh (\pi t)}, \quad g_{\epsilon}(t)=\frac{i}{4}\left[\frac{1}{\sinh (\pi(t-i \epsilon))}+\frac{1}{\sinh (\pi(t+i \epsilon))}\right] . \tag{2.13}
\end{equation*}
$$

In appendix D , we show that the above $\epsilon \rightarrow 0$ limit exists.
Plugging (2.12) into (2.11) we find that

$$
\begin{align*}
\log \Delta_{0}-\log \Delta= & \sum_{m=0}^{\infty} \int_{0}^{\infty} \frac{d \beta}{\beta} \int_{-\infty}^{\infty} d t_{0} \cdots d t_{m+1} \beta^{i\left(t_{0}+\cdots+t_{m+1}\right)} \\
& \times f\left(t_{0}\right) \Delta_{0}^{-i t_{0}} \boldsymbol{\delta}\left(\prod_{i=1}^{m} g_{\epsilon_{i}}\left(t_{i}\right) \Delta_{0}^{-i t_{i}} \boldsymbol{\delta}\right) \Delta_{0}^{-i t_{m+1}} f\left(t_{m+1}\right) . \tag{2.14}
\end{align*}
$$

Notice that if we exchange the orders of $\beta$ and $t$-integrals (with associated $\epsilon_{i} \rightarrow 0$ limit) the $\beta$-integral can be performed explicitly

$$
\begin{equation*}
\int_{0}^{\infty} \beta^{-1} d \beta \beta^{i\left(t_{0}+\cdots+t_{m+1}\right)}=2 \pi \delta\left(t_{0}+\cdots+t_{m+1}\right) . \tag{2.15}
\end{equation*}
$$

Equation (2.14) can then be further written as (shifting the sum of $m$ to start from 1)

$$
\begin{equation*}
\log \Delta_{0}-\log \Delta=\sum_{m=1}^{\infty} Q_{m} \tag{2.16}
\end{equation*}
$$

with

$$
\begin{equation*}
Q_{m}=2 \pi \lim _{\epsilon_{i} \rightarrow 0} \int d t_{1} \int d t_{2} \ldots \int d t_{m} F_{\epsilon_{i}}\left(t_{1}, t_{2}, \cdots, t_{m}\right) \boldsymbol{\delta}\left(t_{1}\right) \cdots \boldsymbol{\delta}\left(t_{m}\right) \tag{2.17}
\end{equation*}
$$

where the kernel $F$ is defined by

$$
\begin{equation*}
F_{\epsilon_{i}}\left(t_{1}, t_{2}, \ldots, t_{m}\right)=f\left(t_{1}\right) g_{\epsilon_{1}}\left(t_{2}-t_{1}\right) g_{\epsilon_{2}}\left(t_{3}-t_{2}\right) \ldots g_{\epsilon_{m-1}}\left(t_{m}-t_{m-1}\right) f\left(t_{m}\right) \tag{2.18}
\end{equation*}
$$

and

$$
\begin{equation*}
\boldsymbol{\delta}(t)=\Delta_{0}^{-i t} \boldsymbol{\delta} \Delta_{0}^{i t} . \tag{2.19}
\end{equation*}
$$

A variant of (2.16)-(2.18) has appeared previously in [9]. ${ }^{1}$ The main goal of the paper is to show that the kernel (2.18) has remarkable symmetric properties which enable one to write $Q_{m}$ in terms of nested commutators of $\boldsymbol{\delta}$ 's
$\left.Q_{m}=\frac{2 \pi}{m} \lim _{\epsilon_{i} \rightarrow 0} \int d t_{1} \int d t_{2} \ldots \int d t_{m} F_{\epsilon_{i}}\left(t_{1}, t_{2}, \ldots, t_{m}\right)\left[\cdots\left[\boldsymbol{\delta}\left(t_{1}\right), \boldsymbol{\delta}\left(t_{2}\right)\right], \cdots\right], \boldsymbol{\delta}\left(t_{m}\right)\right]+P_{m}$.
The $P_{m}$ contact term involves terms which contain two fewer integrals. It has the following structure:

$$
\begin{equation*}
P_{m}=\sum_{s} \int d t_{1} \cdots d t_{m-3} d t J_{s}\left(t_{1}, \cdots t_{m-3} ; t\right) M_{s}\left(t_{1}, \cdots t_{m-3} ; t\right) \tag{2.21}
\end{equation*}
$$

where $s$ sums over all possible ways in which three $t_{i}$ 's are selected from the set $\left\{t_{1}, \cdots t_{m}\right\}$ such that at least two of the indices on the chosen $t_{i}$ are adjacent. The three chosen $t_{i}$ 's are set to be equal to $t$, with the rest relabeled as $t_{1}, \cdots t_{m-3}$. $J_{s}$ is a kernel which can be obtained from $F_{\epsilon_{i}}$ after applying a number of operations which are described in the next subsection. For now, we give some simple examples. Suppose $t_{1}=t_{2}=t_{3}=t$, then

$$
\begin{equation*}
M=\delta(t)^{3} \delta\left(t_{1}\right) \ldots \delta\left(t_{m-3}\right), \quad J=\frac{\pi}{2 m} F_{\epsilon}\left(t, t_{1}, \ldots, t_{m-3}\right) \tag{2.22}
\end{equation*}
$$

For $t_{1}=t_{2}=t_{5}=t$, one has $M=\delta(t)^{2} \delta\left(t_{1}\right) \delta\left(t_{2}\right) \delta(t) \delta\left(t_{3}\right) \ldots \delta\left(t_{m-3}\right)$ and

$$
\begin{equation*}
J=\frac{\pi}{2 m}\left(F_{\epsilon}\left(t_{2}, t_{1}, t, t_{3}, t_{4} \ldots, t_{m-3}\right)-F_{\epsilon}\left(t_{1}, t_{2}, t, t_{3}, t_{4}, \ldots, t_{m-3}\right)\right) \tag{2.23}
\end{equation*}
$$

As the selected indices become larger, the number of terms in $J$ increases and the terms also become more complicated. For $t_{6}=t_{2}=t_{3}=t$ one has $M=\delta\left(t_{1}\right) \delta(t)^{2} \delta\left(t_{2}\right) \delta\left(t_{3}\right) \delta(t) \delta\left(t_{4}\right) \ldots \delta\left(t_{m-3}\right)$, and $J$ has a term of the form $\frac{1}{f(t)^{2}} F\left(t_{3}, t_{2}, t, t_{1}\right) F\left(t, t_{4}, t_{5}, \ldots, t_{m-3}\right)$.

### 2.2 Basic ideas for the proof

The kernel (2.18) looks complicated, but it satisfies a number of amazing identities under the permutation of its arguments. To explain the basic idea leading to the proof of (2.20), we need to first establish some notation.

Let $S_{m}$ be the symmetric group of permutations of $m$-distinct objects. We use the cycle notation $(12 \cdots m)$ to represent the permutation that sends $1 \rightarrow 2 \rightarrow 3 \cdots \rightarrow(m-1) \rightarrow$ $m \rightarrow 1$. Any index not listed in the cycle is left untouched. We define the action of an element $\sigma \in S_{m}$ on a product of operators $\boldsymbol{\delta}\left(t_{i_{1}}\right) \boldsymbol{\delta}\left(t_{i_{2}}\right) \ldots \boldsymbol{\delta}\left(t_{i_{m}}\right)$ and a general function $H\left(t_{i_{1}}, t_{i_{2}}, \ldots, t_{i_{m}}\right)$ in the following manner:

$$
\begin{align*}
\sigma\left(\boldsymbol{\delta}\left(t_{i_{1}}\right) \boldsymbol{\delta}\left(t_{i_{2}}\right) \ldots \boldsymbol{\delta}\left(t_{i_{m}}\right)\right) & :=\boldsymbol{\delta}\left(t_{i_{\sigma(1)}}\right) \boldsymbol{\delta}\left(t_{i_{\sigma(2)}}\right) \ldots \boldsymbol{\delta}\left(t_{i_{\sigma(m)}}\right)  \tag{2.24}\\
\sigma\left(H\left(t_{i_{1}}, t_{i_{2}}, \ldots, t_{i_{m}}\right)\right) & :=H\left(t_{\sigma\left(i_{1}\right)}, t_{\sigma\left(i_{2}\right)}, \ldots, t_{\sigma\left(i_{m}\right)}\right) \tag{2.25}
\end{align*}
$$

[^0]Note that in (2.24) $\sigma$ acts on the left while in (2.25) it acts on the right. See appendix C for further explanations and examples. Let us also introduce the special permutations

$$
\begin{equation*}
\mu_{j}=(j(j-1)(j-2) \ldots 4321), \quad \Lambda_{j}=(1234 \ldots(j-1) j), \quad \mu_{j}=\Lambda_{j}^{-1} . \tag{2.26}
\end{equation*}
$$

One can show that the following statements are true:

1. Introduce the operator

$$
\begin{equation*}
T_{m}=\left(\mathrm{id}-\mu_{m}\right)\left(\mathrm{id}-\mu_{m-1}\right) \ldots\left(\mathrm{id}-\mu_{2}\right) \tag{2.27}
\end{equation*}
$$

where id denotes the identity operation. Then,

$$
\begin{equation*}
\left.T_{m}\left(\boldsymbol{\delta}\left(t_{1}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)\right)=\left[\left[\cdots\left[\boldsymbol{\delta}\left(t_{1}\right), \boldsymbol{\delta}\left(t_{2}\right)\right], \cdots\right], \boldsymbol{\delta}\left(t_{m-1}\right)\right], \boldsymbol{\delta}\left(t_{m}\right)\right] . \tag{2.28}
\end{equation*}
$$

See [10] for a proof. For completeness, we have included a proof in appendix C.
2. For any function $H\left(t_{1}, t_{2}, \ldots, t_{m}\right)$ we have

$$
\begin{align*}
\int H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)= & \int H\left(t_{1}, t_{2}, \ldots, t_{m}\right) T_{m}\left(\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)\right) \\
& +\int \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right) \Sigma_{m} H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \tag{2.29}
\end{align*}
$$

where the operation $\Sigma_{m}$ is defined as

$$
\begin{equation*}
\Sigma_{m} H\left(t_{1}, t_{2}, \ldots, t_{m}\right)=\sum_{k=1}^{m-1}(-1)^{k-1} \Xi_{k}^{m} H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \tag{2.30}
\end{equation*}
$$

with

$$
\begin{equation*}
\Xi_{k}^{m} H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \equiv \sum_{i_{1}=k+1}^{m} \sum_{i_{2}=k}^{i_{1}-1} \sum_{i_{3}=k-1}^{i_{2}-1} \ldots \sum_{i_{k}=2}^{i_{k-1}-1} \Lambda_{i_{1}} \Lambda_{i_{2}} \ldots \Lambda_{i_{k}} H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \tag{2.31}
\end{equation*}
$$

3. For a general operator $O\left(t_{1}, \ldots, t_{m}\right)$ and function $F_{\epsilon}$ of (2.18) we have

$$
\begin{equation*}
\lim _{\epsilon_{i} \rightarrow 0} \int O\left(t_{1}, \ldots, t_{m}\right) \Xi_{k}^{m} F_{\epsilon}\left(t_{1}, \ldots, t_{m}\right)=(-1)^{k} \lim _{\epsilon_{i} \rightarrow 0} \int O\left(t_{1}, \ldots, t_{m}\right) F_{\epsilon}\left(t_{1}, \ldots, t_{m}\right)+\sum_{j=k+2}^{m} N_{j}[O] \tag{2.32}
\end{equation*}
$$

where $N_{j}[O]$ are "contact terms" containing only $m-2$ integrals. They will be given explicitly at the end.
4. If we set $H=F_{\epsilon}$ in (2.29) and use (2.32) in (2.30) we find that

$$
\begin{equation*}
Q_{m}=\frac{2 \pi}{m} \lim _{\epsilon_{i} \rightarrow 0} \int F_{\epsilon}\left(t_{1}, t_{2}, \ldots, t_{m}\right) T_{m}\left(\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)\right)+\frac{2 \pi}{m} \sum_{k=1}^{m-1}(-1)^{k-1} \sum_{j=k+2}^{m} N_{j} \tag{2.33}
\end{equation*}
$$

which leads to (2.20) upon using (2.28) together with the identification

$$
\begin{equation*}
P_{m}=\frac{2 \pi}{m} \sum_{k=1}^{m-1}(-1)^{k-1} \sum_{j=k+2}^{m} N_{j} . \tag{2.34}
\end{equation*}
$$

We now give the explicit expressions for $N_{j}$. First, let us introduce some definitions. For integers $q_{2}<q_{1}$ we define

$$
\begin{align*}
L_{q_{1}, q_{2}}^{\epsilon}(t) & \left.\equiv \frac{\Lambda_{q_{2}} F_{\epsilon}\left(t_{1}, \ldots, t_{q_{1}}\right)}{g_{\epsilon}\left(t_{1}-t_{q_{2}}\right) g_{\epsilon}\left(t_{q_{2}+1}-t_{1}\right)}\right|_{t_{1}=t_{q_{2}}=t_{q_{2}+1}=t}  \tag{2.35}\\
R_{q_{2}}^{\left(q_{1}\right)}[M] & \left.\equiv \lim _{\epsilon_{i} \rightarrow 0} \int L_{q_{1}, q_{2}}^{\epsilon}(t) M\left(t_{1}, t_{2}, \ldots, t_{q_{1}}\right)\right|_{t_{1}=t_{q_{2}}=t_{q_{2}+1}=t} \tag{2.36}
\end{align*}
$$

where $M$ is some operator and on the right hand side of (2.36) the integrations are over all distinct $t_{i}$ 's (i.e. $q_{1}-2$ integrations). Given an operator $O\left(t_{1}, t_{2}, \ldots, t_{m}\right)$, for each $p \leq k$ and $k+3 \leq j \leq m$ where $k$ is the lower index in the object $\Xi_{k}^{m}$, we define the operator $W$ as

$$
\begin{align*}
& W\left(t_{1}, t_{2}, \ldots, t_{p}, t_{j-1}, t_{j}\right)=\frac{1}{f\left(t_{j}\right) f\left(t_{j-1}\right)} \sum_{i_{p+1}=k-p+1}^{j-p-2} \sum_{i_{p+2}=k-p}^{i_{p+1}-1} \cdots \sum_{i_{k}=2}^{i_{k-1}-1}  \tag{2.37}\\
& \quad \times \int\left(\Pi_{n=p+1}^{j-2} d t_{n} \Pi_{l=j+1}^{m} d t_{l}\right) \chi_{p j} O\left(t_{1}, \ldots t_{m}\right) g_{j, j+1, \epsilon_{j}} g_{j+1, j+2, \epsilon_{j+1}}^{\ldots} g_{m-1, m, \epsilon_{m-1}} f_{m}
\end{align*}
$$

where $\chi_{p j}$ is given by

$$
\begin{equation*}
\chi_{p j}\left(t_{p+1}, t_{p+2}, \ldots, t_{j-2}, t_{j-1}\right)=\Pi_{n=j-1}^{j-p} \Lambda_{n} \Pi_{l=p+1}^{k} \Lambda_{i_{l}}\left(f_{1} g_{1,2, \epsilon_{1}} g_{2,3, \epsilon_{2}} \ldots g_{j-p-2, j-p-1, \epsilon_{j-p-2}}\right), \tag{2.38}
\end{equation*}
$$

and we have used the following shorthand notations

$$
\begin{equation*}
f_{m} \equiv f\left(t_{m}\right), \quad g_{m-1, m, \epsilon_{m-1}} \equiv g_{\epsilon_{m-1}}\left(t_{m}-t_{m-1}\right) \tag{2.39}
\end{equation*}
$$

We also introduce

$$
\begin{equation*}
\tilde{O}_{j}\left(y_{1}, y_{2}, \ldots, y_{p+2}\right)=W\left(y_{p+2}, y_{p+1}, \ldots, y_{3}, y_{2}, y_{1}\right) \tag{2.40}
\end{equation*}
$$

which amounts to the relabelling

$$
\begin{equation*}
y_{1}=t_{j}, \quad y_{2}=t_{j-1}, \quad y_{3+q}=t_{p-q}, \quad 0 \leq q \leq p-1 \tag{2.41}
\end{equation*}
$$

Finally, the expression for $N_{j}[O]$ is given by

$$
N_{j}[O]= \begin{cases}\frac{1}{4} \sum_{p=1}^{k} \sum_{l=2}^{p+1} R_{l}^{(p+2)}\left[\tilde{O}_{j}\right] & j \geq k+3  \tag{2.42}\\ \frac{1}{4} \sum_{l=2}^{k+1} R_{l}^{k+2)}\left[\tilde{O}_{k+2}\right] & j=k+2\end{cases}
$$

for $m \geq 2$ and $1 \leq k \leq m-1$.
In summary, to obtain the kernel $J$ of (2.21) corresponding to $t_{j}, t_{r+1}, t_{r}$ for some $1 \leq r<j-1$, we use the following algorithm:

1. Choose an integer $k$ such that $1 \leq k \leq j-2$. If $k=j-2$ then set $p=k$, otherwise choose $p$ in the range $r+1 \leq p \leq k$.
2. For each such $k$ and $p$, apply the string of permutations on the right-hand-side of eq. (2.38) to the first $j-p-2$ arguments of $F_{\epsilon}$ to obtain $\chi_{p j}$. Sum over these permutations.
3. Keep all arguments above $j$ unpermuted, and delete the arguments between $j-p-2$ and $j$. Divide the result by $\frac{1}{f\left(t_{j}\right) f\left(t_{j-1}\right)}$.
4. Define the variables $y_{i}$ as in (2.41). Apply the permutation $\Lambda_{p+2-r}$ to $F\left(y_{1}, \ldots, y_{p+2}\right)$ and divide by $4 g_{\epsilon}\left(y_{1}-y_{p+2-r}\right) g_{\epsilon}\left(y_{p+3-r}-y_{1}\right)$. Now set $t_{j}=t_{r+1}=t_{r}$
5. Multiply this by the result obtained in Step 3 after reexpressing $y_{i}$ in terms of $t_{i}$. Perform the sum over $p$. Sum over $k$ after multipying by $(-1)^{k-1}$. Multiply the whole result by $\frac{2 \pi}{m}$.

To obtain $J$ corresponding to the choice $t_{j}=t_{j-1}=t_{r}$ when $1<r<j-2$, the previous steps are followed with the choice $p=r$ and no sum over $p$ in the last step. To obtain $J$ corresponding to the choice $t_{j}=t_{j-1}=t_{1}$ follow the previous steps after setting $p=1$ and to the result, add the term $\frac{\pi \Lambda_{j-1} F\left(t_{1}, \ldots, t_{m}\right)}{2 m\left(g_{\epsilon}\left(t_{1}-t_{j-1}\right) g_{\epsilon}\left(t_{j}-t_{1}\right)\right)}$. This exhausts all the cases.

The rest of the paper is devoted to establishing (2.28)-(2.32) and justifying the existence of $\epsilon_{i} \rightarrow 0$ limit. In section 3 we prove (2.28) and (2.29). In section 4 we prove (2.32). Appendix D discusses in detail the $\epsilon_{i} \rightarrow 0$ limit. In appendix E we examine more carefully the interchange of $\beta$-integral and $\epsilon_{i} \rightarrow 0$ limit used in (2.14).

## 3 Permutation identities (I)

In this section, we present a proof of eq. (2.29). Consider the integral

$$
\begin{equation*}
I_{m}=\int H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right) \tag{3.1}
\end{equation*}
$$

for some function $H\left(t_{1}, t_{2}, \ldots, t_{m}\right)$. Then, we have

$$
\begin{align*}
I_{m}= & \int H\left(t_{1}, t_{2}, \ldots, t_{m}\right)(1-(12)+(12)) \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right) \\
= & \int H\left(t_{1}, t_{2}, \ldots, t_{m}\right)[(1-(321))(1-(12))+(321)(1-(12))+(12)] \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right) \\
= & \int H\left(t_{1}, t_{2}, \ldots, t_{m}\right)[(1-(4321))(1-(321))(1-(12))  \tag{3.2}\\
& \quad+(4321)(1-(321))(1-(12))+(321)(1-(12))+(12)] \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right) .
\end{align*}
$$

Note that the third line is simply $T_{4}\left[\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{4}\right)\right] \boldsymbol{\delta}\left(t_{5}\right) \cdots \boldsymbol{\delta}\left(t_{m}\right)$, while the fourth line when expanded gives

$$
\begin{equation*}
\sum_{k=1}^{3}(-1)^{k-1} \sum_{i_{1}=k+1}^{4} \sum_{i_{2}=k}^{i_{1}-1} \sum_{i_{3}=k-1}^{i_{2}-1} \ldots \sum_{i_{k}=2}^{i_{k-1}-1} \mu_{i_{1}} \mu_{i_{2}} \ldots \mu_{i_{k}}\left(\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{4}\right)\right) \boldsymbol{\delta}\left(t_{5}\right) \cdots \boldsymbol{\delta}\left(t_{m}\right) \tag{3.3}
\end{equation*}
$$

Continuing this process repeatedly, we get

$$
\begin{align*}
I_{m}= & \int H\left(t_{1}, t_{2}, \ldots, t_{m}\right) T_{m}\left[\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)\right]+\int H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \\
& \times \sum_{k=1}^{m-1}(-1)^{k-1} \sum_{i_{1}=k+1}^{m} \sum_{i_{2}=k}^{i_{1}-1} \sum_{i_{3}=k-1}^{i_{2}-1} \ldots \sum_{i_{k}=2}^{i_{k-1}-1} \mu_{i_{1}} \mu_{i_{2}} \ldots \mu_{i_{k}}\left(\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)\right) . \tag{3.4}
\end{align*}
$$

In eq. (3.4), the permutations act on the operators. But for subsequent applications, we need the permutations to act on functions. This is achieved by the obervations

$$
\begin{align*}
& \int H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \mu_{i_{1}} \ldots \mu_{i_{k}}\left(\boldsymbol{\delta}\left(t_{1}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)\right)  \tag{3.5}\\
&=\int H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \boldsymbol{\delta}\left(t_{\tau(1)}\right) \boldsymbol{\delta}\left(t_{\tau(2)}\right) \ldots \boldsymbol{\delta}\left(t_{\tau(m)}\right) \quad \tau=\mu_{i_{1}} \star \mu_{i_{2}} \star \ldots \star \mu_{i_{k}}  \tag{3.6}\\
&=\int H\left(t_{\sigma(1)}, t_{\sigma(2)} \ldots t_{\sigma(m)}\right) \boldsymbol{\delta}\left(t_{\tau \sigma(1)}\right) \boldsymbol{\delta}\left(t_{\tau \sigma(2)}\right) \ldots \boldsymbol{\delta}\left(t_{\tau \sigma(m)}\right)  \tag{3.7}\\
&=\int \tau^{-1} H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \boldsymbol{\delta}\left(t_{1}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)  \tag{3.8}\\
&=\int\left(\mu_{i_{k}}^{-1} \star \mu_{i_{k-1}}^{-1} \ldots \mu_{i_{2}}^{-1} \star \mu_{i_{1}}^{-1}\right) H\left(t_{1}, t_{2}, \ldots, t_{m}\right) \boldsymbol{\delta}\left(t_{1}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)  \tag{3.9}\\
&=\int\left[\Lambda_{i_{1}} \Lambda_{i_{2}} \ldots \Lambda_{i_{k}} H\left(t_{1}, t_{2}, \ldots, t_{m}\right)\right] \boldsymbol{\delta}\left(t_{1}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right) \tag{3.10}
\end{align*}
$$

where in (3.6), we used (C.5), in (3.7), used the permutation invariance of $n$-dimensional integrals, in (3.8), chose $\sigma=\tau^{-1}$, and finally in (3.10), used (C.6) and that $\mu_{j}$ and $\Lambda_{j}$ are inverse of each other. Using (3.10) in (3.4) we then find (2.29).

## 4 Permutation identities (II)

In this section, we prove (2.32) which is the most nontrivial step in the proof of (2.20). Let us first note the identity

$$
\begin{equation*}
\lim _{\epsilon \rightarrow 0} \int_{-\infty}^{\infty} d t \frac{\sinh (\pi t)}{\sinh (\pi(t \pm i \epsilon))} h(t)=\int_{-\infty}^{\infty} d t h(t) \tag{4.1}
\end{equation*}
$$

where $h(t)$ is a regular function at $t=0$. In subsequent manipulations, we will abbreviate identities of this type by dropping the integral and the limit as

$$
\begin{equation*}
\frac{\sinh (\pi t)}{\sinh (\pi(t \pm i \epsilon))}=1 \tag{4.2}
\end{equation*}
$$

which should (hopefully) cause no confusion. We also remind the reader of the short-hand notation introduced in (2.39). For instance, from (2.18) we have

$$
\begin{equation*}
F_{m}^{\epsilon} \equiv F_{\epsilon_{i}}\left(t_{1}, t_{2}, \cdots t_{m}\right)=f_{1} g_{1,2, \epsilon_{1}} g_{2,3, \epsilon_{2}} \cdots g_{m-1, m, \epsilon_{m-1}} f_{m} \tag{4.3}
\end{equation*}
$$

and

$$
\begin{equation*}
F_{m}^{\epsilon}=\left(\frac{g_{m-1, m, \epsilon_{m-1}} f_{m}}{f_{m-1}}\right) F_{m-1}^{\epsilon} \tag{4.4}
\end{equation*}
$$

### 4.1 Preparation

Before proving (2.32) we first prove a lemma.

Lemma. Consider the operator

$$
\begin{equation*}
I_{m}[O] \equiv \lim _{\epsilon_{i} \rightarrow 0} \int F_{m}^{\epsilon} O\left(t_{1}, t_{2}, \ldots, t_{m}\right) \tag{4.5}
\end{equation*}
$$

where $O\left(t_{1}, \cdots t_{m}\right)$ is a general operator and $F_{m}^{\epsilon}$ is defined in (4.3). For all $m \geq 2$, we have

$$
\begin{equation*}
\sum_{l=2}^{m} \Lambda_{l} I_{m}=-I_{m}+\frac{1}{4} \sum_{l=2}^{m-1} R_{l}^{(m)}[O] \tag{4.6}
\end{equation*}
$$

where $R_{q}^{(m)}[O]$ is defined in eq. (2.36). We remind the reader that $\Lambda_{l}$ only acts on the kernel function $F$.

Proof. We prove this by induction on $m$. Taking $m=2, \Lambda_{2}=(12)$, we get

$$
\begin{equation*}
\Lambda_{2} I_{2}=-I_{2} \tag{4.7}
\end{equation*}
$$

which is trivially true by the antisymmetry of the function $g$. So the correct base case is $m=3$. Performing a few relabelings of the $t_{i}$, we get

$$
\begin{equation*}
\Lambda_{2} I_{3}+\Lambda_{3} I_{3}=\lim _{\epsilon_{1} \rightarrow 0} \int d t_{2} \int d t_{1} \lim _{\epsilon_{2} \rightarrow 0} \int d t_{3}\left(F_{\epsilon_{1}, \epsilon_{2}}\left(t_{2}, t_{3}, t_{1}\right)+F_{\epsilon_{1}, \epsilon_{2}}\left(t_{2}, t_{1}, t_{3}\right)\right) O\left(t_{1}, t_{2}, t_{3}\right) \tag{4.8}
\end{equation*}
$$

Using the identity

$$
\begin{align*}
& 4 \cosh \left(\pi t_{2}\right) \sinh \left(\pi\left(t_{1}-t_{2}\right)\right) \sinh \left(\pi\left(t_{2}-t_{3}\right)\right)  \tag{4.9}\\
& =-\cosh \left(\pi\left(t_{1}-t_{2}+t_{3}\right)\right)-\cosh \left(\pi\left(3 t_{2}-t_{1}-t_{3}\right)\right)+\cosh \left(\pi\left(t_{3}+t_{2}-t_{1}\right)\right)+\cosh \left(\pi\left(t_{1}-t_{3}+t_{2}\right)\right)
\end{align*}
$$

and some algebraic manipulations we can write the term in the parentheses of (4.8) as

$$
\begin{align*}
& F_{\epsilon_{1}, \epsilon_{2}}\left(t_{2}, t_{3}, t_{1}\right)+F_{\epsilon_{1}, \epsilon_{2}}\left(t_{2}, t_{1}, t_{3}\right)= \\
& -4\left(\frac{i}{4}\right) \frac{f\left(t_{1}\right) f\left(t_{2}\right) f\left(t_{3}\right) \cosh \left(\pi t_{2}\right) \sinh \left(\pi\left(t_{1}-t_{2}\right)\right) \sinh \left(\pi\left(t_{2}-t_{3}\right)\right)}{\left|\sinh \left(\pi\left(t_{3}-t_{2}+i \epsilon_{1}\right)\right)\right|^{2}\left|\sinh \left(\pi\left(t_{1}-t_{2}+i \epsilon_{1}\right)\right)\right|^{2}} g_{\epsilon_{2}}\left(t_{1}-t_{3}\right) \sinh \left(\pi\left(t_{1}-t_{3}\right)\right) \\
& +\frac{i}{4} \frac{f\left(t_{1}\right) f\left(t_{2}\right) f\left(t_{3}\right) g_{\epsilon_{2}}\left(t_{1}-t_{3}\right)}{\left|\sinh \left(\pi\left(t_{3}-t_{2}+i \epsilon_{1}\right)\right)\right|^{2}\left|\sinh \left(\pi\left(t_{1}-t_{2}+i \epsilon_{1}\right)\right)\right|^{2}} \sinh \left(\pi\left(t_{1}-t_{3}\right)\right) \\
& \times\left[\cosh \left(\pi\left(t_{1}-t_{2}+t_{3}\right)\right)\left(\cosh \left(3 \pi i \epsilon_{1}\right)-1\right)-\cosh \left(\pi\left(t_{3}+t_{2}-t_{1}\right)\right)\left(\cosh \left(i \pi \epsilon_{1}\right)-1\right)\right. \\
& \left.\quad-\cosh \left(\pi\left(t_{1}-t_{3}+t_{2}\right)\right)\left(\cosh \left(i \pi \epsilon_{1}\right)-1\right)+\cosh \left(\pi\left(3 t_{2}-t_{1}-t_{3}\right)\right)\left(\cosh \left(i \pi \epsilon_{1}\right)-1\right)\right] . \tag{4.10}
\end{align*}
$$

Integrating against $O\left(t_{1}, t_{2}, t_{3}\right)$ and taking $\epsilon_{i} \rightarrow 0$, we get

$$
\begin{align*}
\Lambda_{2} I_{3} & +\Lambda_{3} I_{3}=-\lim _{\epsilon_{1} \rightarrow 0} \int F_{\epsilon_{1}, \epsilon_{1}}\left(t_{1}, t_{2}, t_{3}\right) O\left(t_{1}, t_{2}, t_{3}\right)  \tag{4.11}\\
& -\frac{1}{8} \lim _{\epsilon_{1} \rightarrow 0} \int O\left(t_{1}, t_{2}, t_{3}\right) \frac{f\left(t_{1}\right) f\left(t_{2}\right) f\left(t_{3}\right)}{\left|\sinh \left(\pi\left(t_{3}-t_{2}+i \epsilon_{1}\right)\right)\right|^{2}\left|\sinh \left(\pi\left(t_{1}-t_{2}+i \epsilon_{1}\right)\right)\right|^{2}} \\
& \times\left[\cosh \left(\pi\left(t_{1}-t_{2}+t_{3}\right)\right)\left(\cosh \left(3 \pi i \epsilon_{1}\right)-1\right)-\cosh \left(\pi\left(t_{3}+t_{2}-t_{1}\right)\right)\left(\cosh \left(i \pi \epsilon_{1}\right)-1\right)\right. \\
& \left.\quad-\cosh \left(\pi\left(t_{1}-t_{3}+t_{2}\right)\right)\left(\cosh \left(i \pi \epsilon_{1}\right)-1\right)+\cosh \left(\pi\left(3 t_{2}-t_{1}-t_{3}\right)\right)\left(\cosh \left(i \pi \epsilon_{1}\right)-1\right)\right]
\end{align*}
$$

The second term of (4.11) can be simplified by noting the identity

$$
\begin{equation*}
\lim _{\epsilon \rightarrow 0} \int_{-\infty}^{\infty} d x \frac{\epsilon}{\epsilon^{2}+(x-a)^{2}} f(x)=\pi f(a) \tag{4.12}
\end{equation*}
$$

for $f$ continuous in $a$, bounded and integrable. Thus, we obtain

$$
\begin{equation*}
\Lambda_{2} I_{3}+\Lambda_{3} I_{3}=-\lim _{\epsilon_{1} \rightarrow 0} \int F_{\epsilon_{1}, \epsilon_{1}}\left(t_{1}, t_{2}, t_{3}\right) O\left(t_{1}, t_{2}, t_{3}\right)+\frac{1}{4} \int_{-\infty}^{\infty} f(t)^{2} O(t, t, t) d t \tag{4.13}
\end{equation*}
$$

From the definitions (2.35)-(2.36) we note that

$$
\begin{equation*}
R_{2}^{(3)}\left[O\left(t_{1}, t_{2}, t_{3}\right)\right]=\int d t f(t)^{2} O(t, t, t) \tag{4.14}
\end{equation*}
$$

and thus

$$
\begin{equation*}
\sum_{j=2}^{3} \Lambda_{j} I_{3}[O]=-I_{3}[O]+\frac{1}{4} R_{2}^{(3)}[O] \tag{4.15}
\end{equation*}
$$

which establishes the lemma for the case $m=3$.
Suppose the lemma holds for some $m \geq 4$, i.e,

$$
\begin{equation*}
\sum_{l=2}^{m-1} \Lambda_{l} I_{m-1}[O]=-I_{m-1}[O]+\frac{1}{4} \sum_{l=2}^{m-2} R_{l}^{(m-1)}[O] \tag{4.16}
\end{equation*}
$$

Then, we have

$$
\begin{align*}
& \sum_{l=2}^{m} \Lambda_{l} I_{m}[O]=\lim _{\epsilon \rightarrow 0} \sum_{j=2}^{m-2} \int \Lambda_{l} F_{m-1}^{\epsilon}\left(\frac{g_{m-1, m, \epsilon_{m-1}} f_{m}}{f_{m-1}}\right) O\left(t_{1}, \ldots, t_{m}\right) \\
& +\lim _{\epsilon \rightarrow 0} \int \Lambda_{m} F_{m}^{\epsilon} O\left(t_{1}, \ldots, t_{m}\right)+\lim _{\epsilon \rightarrow 0} \int \frac{g_{1, m, \epsilon_{m-1}} f_{m}}{f_{1}} \Lambda_{m-1} F_{m-1}^{\epsilon} O\left(t_{1}, t_{2}, \ldots, t_{m}\right) \tag{4.17}
\end{align*}
$$

Rearranging the terms above gives

$$
\begin{align*}
& \sum_{l=2}^{m} \Lambda_{l} I_{m}[O]=\lim _{\epsilon \rightarrow 0} \sum_{l=2}^{m-1} \int \Lambda_{l} F_{m-1}^{\epsilon}\left(\frac{g_{m-1, m, \epsilon_{m-1}} f_{m}}{f_{m-1}}\right) O\left(t_{1}, \ldots, t_{m}\right)+\lim _{\epsilon \rightarrow 0} \int \Lambda_{m} F_{m}^{\epsilon} O\left(t_{1}, \ldots, t_{m}\right) \\
& +\lim _{\epsilon_{m-1} \rightarrow 0} \int d t_{m} \lim _{\epsilon \rightarrow 0} \int f_{m}\left(\frac{g_{1, m, \epsilon_{m-1}}}{f_{1}}-\frac{g_{m-1, m, \epsilon_{m-1}}}{f_{m-1}}\right) \Lambda_{m-1} F_{m-1}^{\epsilon} O\left(t_{1}, t_{2}, \ldots, t_{m}\right) \tag{4.18}
\end{align*}
$$

With a computation very similar to the case $m=3$ we find the relation

$$
\begin{align*}
& \lim _{\epsilon \rightarrow 0} \int \Lambda_{m} F_{m}^{\epsilon} O\left(t_{1}, \ldots, t_{m}\right)  \tag{4.19}\\
& +\lim _{\epsilon_{m-1} \rightarrow 0} \int d t_{m} \lim _{\epsilon \rightarrow 0} \int f_{m}\left(\frac{g_{1, m, \epsilon_{m-1}}}{f_{1}}-\frac{g_{m-1, m, \epsilon_{m-1}}}{f_{m-1}}\right) \Lambda_{m-1} F_{m-1}^{\epsilon} O\left(t_{1}, t_{2}, \ldots, t_{m}\right)  \tag{4.20}\\
& =\frac{1}{4} R_{m-1}^{(m)}[O] \tag{4.21}
\end{align*}
$$

Finally, we perform the integration over $t_{m}$ in the first term on right hand side of (4.18) and use the induction hypothesis to obtain

$$
\begin{equation*}
\sum_{l=2}^{m} \Lambda_{l} I_{m}[O]=-I_{m}[O]+\frac{1}{4} \sum_{l=2}^{m-1} R_{l}^{(m)}[O] \tag{4.22}
\end{equation*}
$$

which proves the lemma.

### 4.2 Final proof

We now prove (2.32) which using the definition (4.5) can be written as

$$
\begin{equation*}
\Xi_{k}^{m} I_{m}[O]=(-1)^{k} I_{m}[O]+\sum_{j=k+2}^{m} N_{j}[O] \tag{4.23}
\end{equation*}
$$

with $N_{j}[O]$ given in eq. (2.42).
Our strategy is to use induction on $m$ with a fixed $k$. First, consider $m=k+1$ for which we have

$$
\begin{equation*}
\Xi_{k}^{k+1}=\Lambda_{m} \Lambda_{m-1} \Lambda_{m-2} \ldots \Lambda_{2} \tag{4.24}
\end{equation*}
$$

It can be checked by an explicit computation

$$
\begin{equation*}
\Xi_{k}^{k+1} F_{m}=F\left(t_{m}, t_{m-1}, t_{m-2}, \ldots, t_{3}, t_{2}, t_{1}\right)=(-1)^{m-1} F_{m} \tag{4.25}
\end{equation*}
$$

following from $g_{\epsilon}(-t)=-g_{\epsilon}(t)$. This completes the proof for the case $m=k+1$. Next, consider $m=k+2$, which is the base case for our induction argument. By explicit computation one can show that

$$
\begin{equation*}
\Xi_{k}^{k+2} I_{m}[O]=\sum_{i_{1}=m-1}^{m} \sum_{i_{2}=m-2}^{i_{1}-1} \ldots \sum_{i_{m-2}=2}^{i_{m-3}-1} \Lambda_{i_{1}} \ldots \Lambda_{i_{m-2}} I_{m}[O]=\sum_{l=2}^{m}\left(\Lambda_{l} I_{m}\right)\left[O^{\prime}\right] \tag{4.26}
\end{equation*}
$$

where $O^{\prime}$ is defined as

$$
\begin{equation*}
O^{\prime}\left(y_{1}, \ldots y_{m}\right) \equiv O\left(y_{m}, y_{m-1}, \ldots, y_{1}\right) \tag{4.27}
\end{equation*}
$$

Now applying Lemma 1 (4.6) to the right hand side of (4.26) we find

$$
\begin{equation*}
\Xi_{k}^{k+2} I_{m}[O]=-I_{m}\left[O^{\prime}\right]+\frac{1}{4} \sum_{j=1}^{k+1} R_{j}\left[O^{\prime}\right]=(-1)^{k} I_{m}[O]+\frac{1}{4} \sum_{l=2}^{k+1} R_{l}^{(k+2)}\left[O^{\prime}\right] \tag{4.28}
\end{equation*}
$$

where in the last step we have used the fact that $g_{\epsilon}(t)$ is an odd function. This completes the proof for $m=k+2$.

Now, suppose (2.32) holds for $m \geq k+3$. Remember the definition of $\Xi_{k}^{m}$ from (2.31). It can be checked explicitly that $\Xi_{k}^{m}=\Xi_{k}^{m-1}+\Lambda_{m} \Xi_{k-1}^{m-1}$. Then, we have

$$
\begin{align*}
\Xi_{k}^{m} F_{m}^{\epsilon} & =\sum_{i_{1}=k+1}^{m} \sum_{i_{2}=k}^{i_{1}-1} \sum_{i_{3}=k-1}^{i_{2}-1} \ldots \sum_{i_{k}=2}^{i_{k-1}-1} \Lambda_{i_{1}} \Lambda_{i_{2}} \ldots \Lambda_{i_{k}} F_{m}^{\epsilon}  \tag{4.29}\\
& =\Xi_{k}^{m-2}\left(F_{m-1}^{\epsilon} \frac{g_{m-1, m} f_{m}}{f_{m-1}}\right)+\Lambda_{m-1} \Xi_{k-1}^{m-2}\left(F_{m-1}^{\epsilon} \frac{g_{m-1, m} f_{m}}{f_{m-1}}\right)+\Lambda_{m} \Xi_{k-1}^{m-1} F_{m}^{\epsilon}  \tag{4.30}\\
& =\frac{g_{m-1, m} f_{m}}{f_{m-1}} \Xi_{k}^{m-1} F_{m-1}^{\epsilon}+\Lambda_{m} \Xi_{k-1}^{m-1} F_{m}^{\epsilon}+C \Lambda_{m-1} \Xi_{k-1}^{m-2} F_{m-1}^{\epsilon} \tag{4.31}
\end{align*}
$$

Here,

$$
\begin{equation*}
C=\frac{g_{1, m} f_{m}}{f_{1}}-\frac{g_{m-1, m} f_{m}}{f_{m-1}} \tag{4.32}
\end{equation*}
$$

If we integrate against $O\left(t_{1}, t_{2}, \ldots, t_{m}\right)$ and take $\epsilon_{i} \rightarrow 0$, the first term in (4.31) goes to

$$
\begin{equation*}
(-1)^{k} I_{m}[O]+\sum_{j=k+2}^{m-1} N_{j}[O] \tag{4.33}
\end{equation*}
$$

by the induction hypothesis. To finish the proof we need to show that the second and the third term add up to $N_{m}[O]$.

Let us denote the sum of the second and the third terms in (4.31) as $V$. First, split $V$ into

$$
\begin{align*}
V & =S_{1}+V_{1}  \tag{4.34}\\
S_{1} & =\Lambda_{m} \Xi_{k-1}^{m-3} F_{m}^{\epsilon}+C \Lambda_{m-1} \Xi_{k-1}^{m-3} F_{m-1}^{\epsilon}  \tag{4.35}\\
V_{1} & =\Lambda_{m} \Lambda_{m-1} \Xi_{k-2}^{m-2} F_{m}^{\epsilon}+\Lambda_{m} \Lambda_{m-2} \Xi_{k-2}^{m-3} F_{m}^{\epsilon}+C \Lambda_{m-1} \Lambda_{m-2} \Xi_{k-2}^{m-3} F_{m-1}^{\epsilon} \tag{4.36}
\end{align*}
$$

where we have repeatedly used $\Xi_{k}^{m}=\Lambda_{m} \Xi_{k-1}^{m-1}+\Xi_{k}^{m-1}$. Let us rename $y_{1}=t_{m}, y_{2}=t_{m-1}$ and $y_{3}=t_{1}$ for the moment. We find

$$
\begin{align*}
S_{1} & =\frac{\chi_{1 m}(t)^{\prime}}{f_{m-1}} \sum_{l=1}^{3} \Lambda_{l} F_{3}^{\epsilon}\left(y_{1}, y_{2}, y_{3}\right)  \tag{4.37}\\
\chi_{1 m}(t)^{\prime} & =\Lambda_{m-1} \sum_{i_{2}=k}^{m-3} \sum_{i_{3}=k-1}^{i_{2}-1} \ldots \sum_{i_{k}=2}^{i_{k-1}-1} \Lambda_{i_{2}} \ldots \Lambda_{i_{k}}\left(f_{1} g_{1,2, \epsilon_{1}} g_{2,3, \epsilon_{2}} \ldots g_{m-3, m-2, \epsilon_{m-3}}\right) \tag{4.38}
\end{align*}
$$

Integrating $S_{1}$ against $O\left(t_{1}, \ldots, t_{m}\right)$ and taking $\epsilon \rightarrow 0$, we find this is precisely the $p=1, j=m$ term in $N_{j}[O]$ that we are looking for, after applying the Lemma, in eq. (2.42).

Now, $V_{1}$ can be further split into

$$
\begin{align*}
& V_{1}=S_{2}+V_{2}  \tag{4.39}\\
& S_{2}=\Lambda_{m} \Theta_{2}^{m} \Xi_{k-2}^{m-4} F_{m}^{\epsilon}+C \Lambda_{m-1} \Lambda_{m-2} \Xi_{k-2}^{m-4} F_{m-1}^{\epsilon}  \tag{4.40}\\
& V_{2}=\Lambda_{m} \Theta_{3}^{m} \Xi_{k-3}^{m-4} F_{m}^{\epsilon}+\Lambda_{m} \Lambda_{m-1} \Lambda_{m-2} \Lambda_{m-3} \Xi_{k-4}^{m-4} F_{m}^{\epsilon}+C \Lambda_{m-1} \Lambda_{m-2} \Lambda_{m-3} \Xi_{k-3}^{m-4} F_{m-1}^{\epsilon} \tag{4.41}
\end{align*}
$$

where

$$
\begin{align*}
& \Theta_{2}^{m} \equiv \Lambda_{m-1}+\Lambda_{m-2}  \tag{4.42}\\
& \Theta_{3}^{m} \equiv \Lambda_{m-1} \Lambda_{m-2}+\Lambda_{m-1} \Lambda_{m-3}+\Lambda_{m-2} \Lambda_{m-3}=\sum_{i_{1}=m-2}^{m-1} \sum_{i_{2}=m-3}^{i_{1}-1} \Lambda_{i_{1}} \Lambda_{i_{2}} \tag{4.43}
\end{align*}
$$

It is convenient to rename $y_{1}=t_{m}, y_{2}=t_{m-1}, y_{3}=t_{2}$ and $y_{4}=t_{1}$. Now, using the equalities

$$
\begin{align*}
\Lambda_{m} \Lambda_{m-1} \Xi_{k-1}^{m-4} F_{m}^{\epsilon} & =\chi_{2 m}^{\prime} g_{m, m-1} g_{2, m} g_{1,2} f_{1}  \tag{4.44}\\
\Lambda_{m} \Lambda_{m-2} \Xi_{k-1}^{m-4} F_{m}^{\epsilon} & =\chi_{2 m}^{\prime} g_{2, m-1} g_{m, 2} g_{1, m} f_{1}  \tag{4.45}\\
\Lambda_{m-1} \Lambda_{m-2} \Xi_{k-1}^{m-4} F_{m-1}^{\epsilon} & =\chi_{2 m}^{\prime} g_{2, m-1} g_{1,2} f_{1} \tag{4.46}
\end{align*}
$$

we can write $S_{2}$ as

$$
\begin{equation*}
S_{2}=\frac{\chi_{2 m}^{\prime}}{f_{m-1}}\left(\sum_{j=1}^{4} \Lambda_{j} F_{4}\left(y_{1}, y_{2}, y_{3}, y_{4}\right)\right) \tag{4.47}
\end{equation*}
$$

Note that since

$$
\begin{equation*}
\chi_{2 m}^{\prime}(t)=\Lambda_{m-1} \Lambda_{m-2} \sum_{i_{3}=k-1}^{m-4} \sum_{i_{4}=k-2}^{i_{2}-1} \ldots \sum_{i_{k}=2}^{i_{k-1}-1} \Lambda_{i_{2}} \ldots \Lambda_{i_{k}}\left(f_{1} g_{1,2, \epsilon_{1}} g_{2,3, \epsilon_{2}} \ldots g_{m-4, m-3, \epsilon_{m-4}}\right) \tag{4.48}
\end{equation*}
$$

if we integrate $S_{2}$ in (4.47) against $O\left(t_{1}, \ldots, t_{m}\right)$ and take all the $\epsilon \rightarrow 0$ we find the $p=2, j=m$ term in $N_{j}[O]$ in eq. (2.42).

Now, the pattern is clear: we split the remainder $V_{j}$ into $S_{j+1}$ and $V_{j+1}$ until $j=k$. Since $V_{k}=0$ we have

$$
\begin{equation*}
V=\sum_{p=1}^{k} S_{p}, \quad S_{p}=\Lambda_{m} \Theta_{p}^{m} \Xi_{k-p}^{m-p-2} F_{m}^{\epsilon}+C \Lambda_{m-1} \Lambda_{m-2} \cdots \Lambda_{m-p} \Xi_{k-p}^{m-p-2} F_{m-1}^{\epsilon}, \tag{4.49}
\end{equation*}
$$

where

$$
\begin{equation*}
\Theta_{p}^{m}=\sum_{i_{1}=m-2}^{m-1} \sum_{i_{2}=m-3}^{i_{1}-1} \cdots \sum_{i_{p-1}=m-p}^{i_{p-2}-1} \Lambda_{i_{1}} \cdots \Lambda_{i_{p-1}} . \tag{4.50}
\end{equation*}
$$

Note that $\Theta_{p}^{m}$ is a direct generalization of (4.43)) and $\Xi_{0}^{j}=1$.
The basic idea to compute $S_{p}$ is the same as that of $S_{2}$. One has to show that $S_{p}$ can be written as

$$
\begin{equation*}
S_{p}=\frac{\chi_{p m}^{\prime}}{f_{m-1}}\left(\sum_{j=1}^{p+2} \Lambda_{j} F_{p+2}\left(y_{1}, y_{2}, \cdots y_{p+2}\right)\right) \tag{4.51}
\end{equation*}
$$

with

$$
\begin{equation*}
y_{1}=t_{m}, \quad y_{2}=t_{m-1}, \quad y_{3+q}=t_{p-q} \text { for } 0 \leq q \leq p-1 . \tag{4.52}
\end{equation*}
$$

It is important to remember that $\chi_{p m}^{\prime}$ does not depend on any of the $y$ variables. It then follows from the Lemma that after integrating against $O\left(t_{1}, \ldots, t_{m}\right)$ and sending $\epsilon \rightarrow 0, S_{p}$ has the form required in eq. (2.42).

To finish the proof, we need to demonstrate (4.51). ${ }^{2}$ For this purpose, let us look at the first term of $S_{p}$ in (4.49):

$$
\begin{equation*}
\Lambda_{m} \Theta_{p}^{m} \Xi_{k-p}^{m-p-2} F_{m}^{\epsilon} . \tag{4.53}
\end{equation*}
$$

Expanding $\Xi$ explicitly we have

$$
\begin{equation*}
\Xi_{k-p}^{m-p-2} F_{m}^{\epsilon}=\sum_{i_{p+1}=k-p+1}^{m-p-2} \sum_{i_{p+2}=k-p}^{i_{p+1}-1} \cdots \sum_{i_{k}=2}^{i_{k-1}-1} \Lambda_{i_{p+1}} \ldots \Lambda_{i_{k}} F_{m}^{\epsilon} \tag{4.54}
\end{equation*}
$$

and

$$
\begin{align*}
\Lambda_{i_{p+1}} \Lambda_{i_{p+2}} \ldots \Lambda_{i_{k}} F_{m}^{\epsilon} & =\chi_{1} g_{m-p-1, m-p} \ldots g_{m-1, m} f_{m}  \tag{4.55}\\
\chi_{1} & =f_{\tau(1)} g_{\tau(1) \tau(2)} g_{\tau(2) \tau(3)} \ldots g_{\tau(m-p-3), \tau(m-p-2)} g_{\tau(m-p-2), m-p-1} \tag{4.56}
\end{align*}
$$

where the permutation $\tau$ and the function $\chi_{1}$ depend on the multi-index $i_{p+1}, \cdots, i_{k}$. It is crucial that the permutation $\tau$ does not touch any of the indices above $m-p-2$. To

[^1]lighten the notation, we suppress the $i$ dependence of $\chi_{1}$. Equation (4.54)-(4.55) further imply
\[

$$
\begin{equation*}
\Xi_{k-p}^{m-p-2} F_{m}^{\epsilon}=\chi_{2} g_{m-p-1, m-p} \ldots g_{m-1, m} f_{m} \tag{4.57}
\end{equation*}
$$

\]

where we have introduced

$$
\begin{equation*}
\chi_{2}=\sum_{i_{p+1}=k-p+1}^{m-p-2} \sum_{i_{p+2}=k-p}^{i_{p+1}-1} \ldots \sum_{i_{k}=2}^{i_{k-1}-1} \chi_{1} . \tag{4.58}
\end{equation*}
$$

Next, note that

$$
\begin{equation*}
\Lambda_{m} \Theta_{p}^{m}=\Lambda_{m} \sum_{j=0}^{p-1} K_{j}, \quad K_{j}=\left(\Pi_{l=1}^{j} \Lambda_{m-l}\right)\left(\Pi_{n=j+1}^{p-1} \Lambda_{m-n-1}\right) \tag{4.59}
\end{equation*}
$$

Every cyclic permutation appearing in (4.59), has the exact same action on $\chi_{2}$, therefore

$$
\begin{equation*}
\Lambda_{m} K_{j} \chi_{2}=\chi_{p m}^{\prime}=\Lambda_{m-1} \ldots \Lambda_{m-p} \chi_{2} \tag{4.60}
\end{equation*}
$$

The first equality of (4.60) says that the action of $\Lambda_{m} K_{j}$ on $\chi_{2}$ is independent of $j$ and we have named the resulting function $\chi_{p m}^{\prime}$ in (4.51). The second equality says $\chi_{p m}^{\prime}$ can also be obtained from the permutation $\Lambda_{m-1} \cdots \Lambda_{m-p}$ acting on $\chi_{2}$. The reasons behind (4.60) are: (i) the number of cycles in each permutation string acting on $\chi_{2}$ is the same; (ii) the length of each cycle is larger than the highest index occurring in $\chi_{2}$. As a simple example, consider the following permutation on some function $G\left(t_{1}, t_{2}, t_{3}\right)$

$$
\begin{equation*}
\Lambda_{10} \Lambda_{9} \Lambda_{8} G\left(t_{1}, t_{2}, t_{3}\right)=\Lambda_{6} \Lambda_{5} \Lambda_{4} G\left(t_{1}, t_{2}, t_{3}\right) \tag{4.61}
\end{equation*}
$$

The $\chi_{p m}^{\prime}$ in eq. (4.60) has the precise expression we saw for the $j=m$ contact contribution in eq. (2.42) which is

$$
\begin{align*}
\chi_{p m}^{\prime}= & \Lambda_{m-1} \cdots \Lambda_{m-p} \sum_{i_{p+1}=k-p+1}^{m-p-2} \sum_{i_{p+2}=k-p}^{i_{p+1}-1} \ldots \\
& \times \sum_{i_{k}=2}^{i_{k-1}-1} \Lambda_{i_{p+1}} \Lambda_{i_{p+2}} \ldots \Lambda_{i_{k}}\left(f_{1} g_{1,2, \epsilon_{1}} g_{2,3, \epsilon_{2}} \ldots g_{m-p-2, m-p-1, \epsilon_{m-p-2}}\right) \tag{4.62}
\end{align*}
$$

Now, let us look at how $K_{j}$ act on the product of the functions in (4.57) other than $\chi_{2}$. To this end, we define

$$
\begin{equation*}
G\left(u_{1}, u_{2}, \ldots, u_{l}\right) \equiv g_{\epsilon_{1}}\left(u_{2}-u_{1}\right) g_{\epsilon_{2}}\left(u_{3}-u_{2}\right) \ldots g_{\epsilon_{l-1}}\left(u_{l}-u_{l-1}\right) \tag{4.63}
\end{equation*}
$$

We then find

$$
\begin{equation*}
\Lambda_{m} \sum_{j=0}^{p-1} K_{j} G\left(t_{m-p-1}, t_{m-p}, \ldots t_{m-1}, t_{m}\right)=\sum_{j=0}^{p-1} G\left(t_{m-1}, t_{p}, t_{p-1} \ldots, t_{j+2}, t_{m}, t_{j+1}, t_{j}, \ldots, t_{2}, t_{1}\right) \tag{4.64}
\end{equation*}
$$

Collecting everything together we thus find (4.53) can be written as

$$
\begin{equation*}
\Lambda_{m} \Theta_{p}^{m} \Xi_{k-p}^{m-p-2} F_{m}^{\epsilon}=\chi_{p m}^{\prime} f_{1} \sum_{j=0}^{p-1} G\left(t_{m-1}, t_{p}, t_{p-1}, \ldots, t_{j+2}, t_{m}, t_{j+1}, t_{j} \ldots, t_{2}, t_{1}\right) . \tag{4.65}
\end{equation*}
$$

The second term of $S_{p}$ in (4.49) can be treated exactly in parallel, and we find

$$
\begin{equation*}
C \Lambda_{m-1} \Lambda_{m-2} \ldots \Lambda_{m-p} \Xi_{k-p}^{m-p-2} F_{m-1}^{\epsilon}=\chi_{p m}^{\prime} f_{1} C G\left(t_{m-1}, t_{p}, t_{p-1}, \ldots, t_{2}, t_{1}\right) \tag{4.66}
\end{equation*}
$$

Plugging the explicit expression for $C$, combining (4.65) and (4.66), cancelling some terms, and relabeling the arguments as in (4.52), we then obtain (4.51). This completes the proof.

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## A Harmonic oscillator example

As an illustration of the perturbation series (1.1) here we consider a very simple example. Consider $\Delta_{0}$ given by the (unnormalized) thermal density matrix for a harmonic oscillator

$$
\begin{equation*}
\Delta_{0}=\exp (-\beta H), \quad H=\hat{a}^{\dagger} \hat{a} \tag{A.1}
\end{equation*}
$$

and $\Delta$ by a "squeezed transform" of $\Delta_{0}$

$$
\begin{equation*}
\Delta=S(r)^{\dagger} \exp (-\beta H) S(r), \quad S(r)=\exp \left(\frac{1}{2} r \hat{a}^{2}-\frac{1}{2} r \hat{a}^{\dagger 2}\right), \quad r>0 . \tag{A.2}
\end{equation*}
$$

We will compute $\log \Delta_{0}-\log \Delta$ as a perturbative expansion in the parameter $r$ two ways, firstly using the BCH (which in this example is extremely simple) and then using the formula (1.2).

From BCH, it is straightforward to see that

$$
\begin{equation*}
\Delta=\exp \left(-\beta H^{\prime}\right), \quad H^{\prime}=S^{\dagger} H S=\sigma^{\dagger} \sigma, \quad \sigma=S^{\dagger} \hat{a} S=\hat{a} \cosh r-\hat{a}^{\dagger} \sinh r, \tag{A.3}
\end{equation*}
$$

and thus

$$
\begin{equation*}
\log \Delta_{0}-\log \Delta=\beta\left(H^{\prime}-H\right)=\left(2 \hat{a}^{\dagger} \hat{a}+1\right)\left(\beta r^{2}+\frac{\beta r^{4}}{3}\right)-\left(\hat{a}^{2}+\hat{a}^{\dagger 2}\right)\left(r \beta+\frac{2 \beta r^{3}}{3}\right)+\mathcal{O}\left(r^{5}\right) . \tag{A.4}
\end{equation*}
$$

Now let us consider the perturbation series (1.2). Note that

$$
\begin{equation*}
\Delta_{0}^{-i t} \hat{a} \Delta_{0}^{i t}=\hat{a} e^{-i \beta t}, \quad \Delta_{0}^{-1 / 2} \hat{a} \Delta_{0}^{1 / 2}=\hat{a} e^{-\beta / 2}, \quad \Delta_{0}^{1 / 2} \hat{a} \Delta_{0}^{-1 / 2}=\hat{a} e^{\beta / 2} \tag{A.5}
\end{equation*}
$$

Here, the domain one should consider is the set of finitely excited Harmonic oscillator states. Throughout, we will be working on this set. Then, we get

$$
\begin{align*}
\boldsymbol{\alpha}= & -\Delta_{0}^{-1 / 2} \Delta_{1} \Delta_{0}^{-1 / 2}  \tag{A.6}\\
= & \frac{1}{2} r \Delta_{0}^{-1 / 2}\left[\hat{a}^{2}-\hat{a}^{\dagger 2}, \Delta_{0}\right] \Delta_{0}^{-1 / 2}-\frac{1}{8} r^{2} \Delta_{0}^{-1 / 2}\left[\hat{a}^{2}-\hat{a}^{\dagger 2},\left(\hat{a}^{2}-\hat{a}^{\dagger 2}, \Delta_{0}\right]\right] \Delta_{0}^{-1 / 2}  \tag{A.7}\\
& +\frac{r^{3}}{3!2^{3}} \Delta_{0}^{-1 / 2}\left[\hat{a}^{2}-\hat{a}^{\dagger 2},\left[\hat{a}^{2}-\hat{a}^{\dagger 2},\left(\hat{a}^{2}-\hat{a}^{\dagger 2}, \Delta_{0}\right]\right] \Delta_{0}^{-1 / 2}\right.  \tag{A.8}\\
& -\frac{r^{4}}{2^{4} 4!} \Delta_{0}^{-1 / 2}\left[\hat{a}^{2}-\hat{a}^{\dagger 2},\left[\hat{a}^{2}-\hat{a}^{\dagger 2},, \hat{a}^{2}-\hat{a}^{\dagger 2},\left[\hat{a}^{2}-\hat{a}^{\dagger 2}, \Delta_{0}\right] \Delta_{0}^{-1 / 2},\right.\right.  \tag{A.9}\\
\delta= & \frac{\boldsymbol{\alpha}}{1-\alpha / 2}  \tag{A.10}\\
= & -r \sinh \beta\left(\hat{a}^{2}+\hat{a}^{\dagger 2}\right)+\frac{r^{2}}{4}\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right] \sinh (2 \beta)+\frac{r^{3}}{12} \sinh ^{3} \beta\left(\hat{a}^{2}+\hat{a}^{\dagger 2}\right)^{3}  \tag{A.11}\\
& -\frac{r^{3}}{24} \cosh \beta \sinh (2 \beta)\left[\hat{a}^{2}-\hat{a}^{\dagger 2},\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right]\right]  \tag{A.12}\\
& -\frac{r^{4}}{3 \cdot 2^{4}} \sinh { }^{2} \beta \sinh 2 \beta\left(\left(\hat{a}^{2}+\hat{a}^{\dagger 2}\right)^{2}\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right]+\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right]\left(\hat{a}^{2}+\hat{a}^{\dagger 2}\right)^{2}+\left(\hat{a}^{2}+\hat{a}^{\dagger 2}\right)\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right]\left(\hat{a}^{2}+\hat{a}^{\dagger 2}\right)\right)  \tag{A.13}\\
& +\sinh 2 \beta \frac{r^{4}}{4!2^{3}}\left(\cosh ^{2} \beta\left[\left[\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right], \hat{a}^{2}-\hat{a}^{\dagger 2}\right], \hat{a}^{2}-\hat{a}^{\dagger 2}\right]-\sinh ^{2} \beta\left[\left[\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right], \hat{a}^{2}+\hat{a}^{\dagger 2}\right], \hat{a}^{2}+\hat{a}^{\dagger 2}\right]\right) . \tag{A.14}
\end{align*}
$$

We define

$$
\begin{equation*}
s(t)=\hat{a}^{2} e^{-2 i \beta t}+\hat{a}^{\dagger 2} e^{2 i \beta t}, \quad d(t)=\hat{a}^{2} e^{-2 i \beta t}-\hat{a}^{\dagger 2} e^{2 i \beta t} \tag{A.15}
\end{equation*}
$$

in terms of which we obtain

$$
\begin{align*}
\boldsymbol{\delta}(t)= & -r \sinh \beta s(t)+\frac{r^{2}}{4}\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right] \sinh 2 \beta  \tag{A.16}\\
& +\frac{r^{3}}{12} \sinh ^{3} \beta s(t)^{3}-\frac{r^{3}}{24} \cosh \beta \sinh (2 \beta)\left[d(t),\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right]\right]  \tag{A.17}\\
& -\frac{r^{4}}{3.2^{4}} \sinh ^{2} \beta \sinh 2 \beta\left(s(t)^{2}\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right]+\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right] s(t)^{2}+s(t)\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right] s(t)\right)  \tag{A.18}\\
& +\sinh 2 \beta \frac{r^{4}}{4!2^{3}}\left(\cosh ^{2} \beta\left[\left[\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right], d(t)\right], d(t)\right]-\sinh ^{2} \beta\left[\left[\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right], s(t)\right], s(t)\right]\right) . \tag{A.19}
\end{align*}
$$

We would need the expressions

$$
\begin{align*}
\int d t \frac{e^{i x t}}{\cosh ^{2}(\pi t)} & =\frac{x}{\pi} \frac{1}{\sinh (x / 2)},  \tag{A.20}\\
\lim _{\epsilon \rightarrow 0} \int \frac{d t}{\cosh (\pi t)} \frac{e^{i x(t-a)}}{\sinh (\pi(t-a+i \epsilon))} & =2 i \frac{e^{-x / 2}-e^{-i a x}}{1-e^{-x}} \frac{e^{-x / 2}}{\cosh (\pi a)}  \tag{A.21}\\
\lim _{\epsilon \rightarrow 0} \int \frac{d t}{\cosh (\pi t)} \frac{e^{i x(t-a)}}{\sinh (\pi(t-a-i \epsilon))} & =2 i \frac{e^{x / 2}-e^{-i a x}}{1-e^{-x}} \frac{e^{-x / 2}}{\cosh (\pi a)} . \tag{A.22}
\end{align*}
$$

Plugging all this in the expressions in (1.6)-(1.9), and adding all the contributions, we
get, upto $\mathcal{O}\left(r^{4}\right)$,

$$
\begin{align*}
\sum_{i} Q_{i}= & -r \beta\left(\hat{a}^{2}+\hat{a}^{\dagger 2}\right)+\frac{1}{2} \beta r^{2}\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right]-\frac{\beta r^{3}}{12}\left[\hat{a}^{2}-\hat{a}^{\dagger 2},\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right]\right]  \tag{A.23}\\
& -\frac{\beta r^{4}}{96}\left(\left[\left[\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right], \hat{a}^{2}\right], \hat{a}^{\dagger 2}\right]+\left[\left[\left[\hat{a}^{2}, \hat{a}^{\dagger 2}\right], \hat{a}^{\dagger 2}\right], \hat{a}^{2}\right]\right)  \tag{A.24}\\
= & \left(2 \hat{a}^{\dagger} \hat{a}+1\right)\left(\beta r^{2}+\frac{\beta r^{4}}{3}\right)-\left(\hat{a}^{2}+\hat{a}^{\dagger 2}\right)\left(r \beta+\frac{2 \beta r^{3}}{3}\right) \tag{A.25}
\end{align*}
$$

where we have combined terms using the identity

$$
\begin{equation*}
\left[s_{1}, s_{2}^{3}\right]-3 s_{2}\left[s_{1}, s_{2}\right] s_{2}=\left[\left[\left[s_{1}, s_{2}\right], s_{2}\right], s_{2}\right] \tag{A.26}
\end{equation*}
$$

Eq. (A.25) and eq. (A.4) agree precisely.

## B Contact term at quintic order

For completeness, we evaluate the formula given for the contact terms $P_{m}$ for the case $m=5$. We get

$$
\begin{align*}
P_{5}= & \frac{\pi}{40} \lim _{\epsilon_{1}, \epsilon_{2} \rightarrow 0} \int \frac{g_{\epsilon_{1}}\left(t_{2}-t_{1}\right) g_{\epsilon_{2}}\left(t_{3}-t_{2}\right)}{\cosh \left(\pi t_{1}\right) \cosh \left(\pi t_{3}\right)}\left(\boldsymbol{\delta}\left(t_{1}\right)^{3} \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{3}\right)+\boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right)^{2} \boldsymbol{\delta}\left(t_{3}\right)\right. \\
& +\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{1}\right)^{2}+\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{3}\right)^{3}+\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right)^{2} \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{2}\right) \\
& +\boldsymbol{\delta}\left(t_{1}\right)^{2} \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{1}\right)-\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{1}\right)^{2}-\boldsymbol{\delta}\left(t_{2}\right)^{2} \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{1}\right) \\
& \left.-\boldsymbol{\delta}\left(t_{1}\right)^{2} \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{1}\right)-\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{2}\right)^{2}+\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right)^{3} \boldsymbol{\delta}\left(t_{3}\right)\right) \tag{B.1}
\end{align*}
$$

The first three terms above come from the object $\Xi_{1}^{5}$ applied to the kernel. The next three terms come from $\Xi_{3}^{5}$. The last five terms come from $\Xi_{2}^{5}$.

This can be further simplified as

$$
\begin{align*}
P_{5}= & \frac{\pi}{40} \lim _{\epsilon_{1}, \epsilon_{2} \rightarrow 0} \int \frac{g_{\epsilon_{1}}\left(t_{2}-t_{1}\right) g_{\epsilon_{2}}\left(t_{3}-t_{2}\right)}{\cosh \left(\pi t_{1}\right) \cosh \left(\pi t_{3}\right)}\left(\left[\boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{1}\right), \boldsymbol{\delta}\left(t_{2}\right)^{2} \boldsymbol{\delta}\left(t_{3}\right)\right]\right. \\
& +\boldsymbol{\delta}\left(t_{1}\right)\left[\boldsymbol{\delta}\left(t_{3}\right), \boldsymbol{\delta}\left(t_{2}\right)\right] \boldsymbol{\delta}\left(t_{1}\right)^{2}+\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right)\left[\boldsymbol{\delta}\left(t_{2}\right), \boldsymbol{\delta}\left(t_{3}\right)\right] \boldsymbol{\delta}\left(t_{2}\right)+\boldsymbol{\delta}\left(t_{1}\right)^{2}\left[\boldsymbol{\delta}\left(t_{2}\right), \boldsymbol{\delta}\left(t_{3}\right)\right] \boldsymbol{\delta}\left(t_{1}\right) \\
& \left.+\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right)^{3} \boldsymbol{\delta}\left(t_{3}\right)+\boldsymbol{\delta}\left(t_{1}\right)^{3} \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{3}\right)+\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{3}\right)^{3}\right) . \tag{B.2}
\end{align*}
$$

## C Action of the permutation group on operators and functions

In this appendix, we elaborate more on the action of the permutation group on operators and functions introduced in (2.24)-(2.25).
$S_{m}$ denotes the symmetric group of permutations on $m$-distinct objects and we use $(1,2, \ldots, m)$ to denote the permutation that sends $1 \rightarrow 2 \rightarrow 3 \cdots \rightarrow(m-1) \rightarrow m \rightarrow 1$. We will follow the convention where group composition, denoted by $\star$ in $S_{m}$ is from left to right, e.g.,

$$
\begin{align*}
(1234) \star(124) & =(1423)  \tag{C.1}\\
(12345) \star(342) & =(13245) \tag{C.2}
\end{align*}
$$

We define

$$
\begin{align*}
\sigma\left(\boldsymbol{\delta}\left(t_{i_{1}}\right) \boldsymbol{\delta}\left(t_{i_{2}}\right) \cdots \boldsymbol{\delta}\left(t_{i_{m}}\right)\right) & =\boldsymbol{\delta}\left(t_{i_{\sigma(1)}}\right) \boldsymbol{\delta}\left(t_{i_{\sigma(2)}}\right) \cdots \boldsymbol{\delta}\left(t_{i_{\sigma(m)}}\right)  \tag{C.3}\\
\sigma\left(F\left(t_{i_{1}}, t_{i_{2}}, \cdots, t_{i_{m}}\right)\right) & =F\left(t_{\sigma\left(i_{1}\right)}, t_{\sigma\left(i_{2}\right)}, \cdots, t_{\sigma\left(i_{m}\right)}\right) . \tag{C.4}
\end{align*}
$$

Note that in (C.3) the permutations act to the left, while in (C.4), the permutations act to the right. More explicitly,

$$
\begin{align*}
\sigma\left(\tau\left(\boldsymbol{\delta}\left(t_{i_{1}}\right) \boldsymbol{\delta}\left(t_{i_{2}}\right) \cdots \boldsymbol{\delta}\left(t_{i_{m}}\right)\right)\right) & =\sigma \star \tau\left(\boldsymbol{\delta}\left(t_{i_{1}}\right) \boldsymbol{\delta}\left(t_{i_{2}}\right) \cdots \boldsymbol{\delta}\left(t_{i_{m}}\right)\right),  \tag{C.5}\\
\sigma\left(\tau\left(F\left(t_{i_{1}}, t_{i_{2}}, \cdots, t_{i_{m}}\right)\right)\right) & \left.=\tau \star \sigma\left(F\left(t_{i_{1}}, t_{i_{2}}, \cdots, t_{i_{m}}\right)\right)\right) . \tag{C.6}
\end{align*}
$$

Now consider some examples

$$
\begin{align*}
(123) F\left(t_{2}, t_{1}, t_{3}\right) & =F\left(t_{3}, t_{2}, t_{1}\right), \quad(123) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{3}\right)=\boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{2}\right),  \tag{C.7}\\
(12)\left((123) F\left(t_{2}, t_{1}, t_{3}\right)\right) & =F\left(t_{3}, t_{1}, t_{2}\right)=(23) F\left(t_{2}, t_{1}, t_{3}\right),  \tag{C.8}\\
(12)\left((123) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{3}\right)\right) & =\boldsymbol{\delta}\left(t_{3}\right) \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{2}\right)=(13) \boldsymbol{\delta}\left(t_{2}\right) \boldsymbol{\delta}\left(t_{1}\right) \boldsymbol{\delta}\left(t_{3}\right), \tag{C.9}
\end{align*}
$$

with $(12) \star(123)=(13)$ and $(123) \star(12)=(23)$.
We now give a proof eq. (2.28) [10]. Notice that

$$
\begin{equation*}
(m, m-1 \ldots 4321) X \boldsymbol{\delta}\left(t_{m}\right)=\boldsymbol{\delta}\left(t_{m}\right) X \tag{C.10}
\end{equation*}
$$

for any product of operators $X$ not involving $\boldsymbol{\delta}\left(t_{m}\right)$, and thus

$$
\begin{equation*}
(\mathrm{id}-(m, m-1, \ldots 4321)) X \boldsymbol{\delta}\left(t_{m}\right)=\left[X, \boldsymbol{\delta}\left(t_{m}\right)\right] . \tag{C.11}
\end{equation*}
$$

Now (2.28) follows by induction. For $m=2$ it is obviously true. Assume its true for $m-1$. Then we have

$$
\begin{align*}
T_{m}\left(\boldsymbol{\delta}\left(t_{1}\right) \ldots \boldsymbol{\delta}\left(t_{m}\right)\right) & =(\mathrm{id}-(m, m-1, \ldots 4321))\left[T_{m-1}\left(\boldsymbol{\delta}\left(t_{1}\right) \ldots \boldsymbol{\delta}\left(t_{m-1}\right)\right)\right] \boldsymbol{\delta}\left(t_{m}\right) \\
& =\left[T_{m-1}\left(\boldsymbol{\delta}\left(t_{1}\right) \ldots \boldsymbol{\delta}\left(t_{m-1}\right)\right), \boldsymbol{\delta}\left(t_{m}\right)\right] \tag{C.12}
\end{align*}
$$

which completes the proof.

## D The $\epsilon \rightarrow 0$ limit

In this appendix, we include a proof of the existence of the $\epsilon \rightarrow 0$ limit in (1.2). In other words, we establish the identity in (2.12) treating the $\epsilon \rightarrow 0$ limit carefully.

Using the spectral decomposition of $\Delta$ in (E.9) for any $\epsilon, \beta>0$ and vectors $|x\rangle$ and $|y\rangle$ we have

$$
\begin{equation*}
\lim _{\epsilon \rightarrow 0}\langle x| \frac{\Delta^{1-\epsilon}}{\Delta+\beta}|y\rangle=\frac{-i}{2} \lim _{\epsilon \rightarrow 0} \int_{-\infty}^{\infty} \frac{d t}{\sinh (\pi(t-i \epsilon))} \beta^{-i t}\langle y| \Delta^{-i t}|x\rangle \tag{D.1}
\end{equation*}
$$

Note that we can freely interchange the $\lambda$ and $t$ integrals because the integrand above is an absolutely convergent function. Our goal is to show the limit above gives $\langle y| \frac{\Delta}{\Delta+\beta}|x\rangle$.

The following inequalities

$$
\begin{array}{ll}
\frac{e^{(1-\epsilon) \lambda}}{e^{\lambda}+\beta}<\frac{e^{\lambda}}{e^{\lambda}+\beta}<1 & \forall \lambda>0 \\
\frac{e^{(1-\epsilon) \lambda}}{e^{\lambda}+\beta}<\frac{1}{e^{\lambda}+\beta}<\frac{1}{\beta} & \forall \lambda<0 \tag{D.3}
\end{array}
$$

imply that $\frac{e^{\lambda(1-\epsilon)}}{e^{\lambda}+\beta}$ is dominated by an integrable function. Then, the Lebesgue dominated convergence theorem [11] implies that

$$
\begin{equation*}
\lim _{\epsilon \rightarrow 0} \int \frac{e^{\lambda(1-\epsilon)}}{e^{\lambda}+\beta}\langle x| P(d \lambda)|y\rangle=\int \frac{e^{\lambda}}{e^{\lambda}+\beta}\langle x| P(d \lambda)|y\rangle \tag{D.4}
\end{equation*}
$$

This is sufficient to guarantee

$$
\begin{equation*}
\frac{-i}{2} \lim _{\epsilon \rightarrow 0} \int_{-\infty}^{\infty} \frac{d t}{\sinh (\pi(t-i \epsilon))} \beta^{-i t}\langle y| e^{i t K}|x\rangle=\langle y| \frac{\Delta}{\Delta+\beta}|x\rangle . \tag{D.5}
\end{equation*}
$$

## E Interchange of $\beta$ integral with $\epsilon \rightarrow 0$ limit

Finally, we consider the question of interchange of the order of the $\beta$ integral and the $\epsilon \rightarrow 0$ limit in (2.14). For concreteness, consider the $m=2$ in (2.14):

$$
\begin{align*}
& Q_{2}^{(\epsilon)}=\int_{0}^{\infty} \frac{d \beta}{\beta} \lim _{\epsilon \rightarrow 0} \int d t_{0} d t_{1} d t_{2} \beta^{i\left(t_{0}+t_{1}+t_{2}\right)} f\left(t_{0}\right) g_{\epsilon}\left(t_{1}\right) f\left(t_{2}\right)\langle x| \Delta^{-i t_{0}} \boldsymbol{\delta} \Delta^{-i t_{1}} \delta \Delta^{-i t_{2}}|y\rangle,  \tag{E.1}\\
& f(t)=\frac{1}{2 \cosh (\pi t)},  \tag{E.2}\\
& g_{\epsilon}(t)=\frac{i}{4}\left[\frac{1}{\sinh (\pi(t-i \epsilon))}+\frac{1}{\sinh (\pi(t+i \epsilon))}\right] . \tag{E.3}
\end{align*}
$$

Our aim is to justify bringing the limit $\epsilon \rightarrow 0$ out of the integral. The integrals over the $t_{i}$ can be done explicitly to get

$$
\begin{align*}
Q_{2}^{(\epsilon)} & =\int_{0}^{\infty} d \beta\left(\beta^{\epsilon} X_{\epsilon}(\beta)-\beta^{1-\epsilon} Y_{\epsilon}(\beta)\right),  \tag{E.4}\\
X_{\epsilon}(\beta) & =\langle x| A \boldsymbol{\delta}\left(\frac{\Delta^{1-\epsilon}}{\Delta+\beta}\right) \boldsymbol{\delta} A|y\rangle,  \tag{E.5}\\
Y_{\epsilon}(\beta) & =\langle x| A \boldsymbol{\delta}\left(\frac{\Delta^{\epsilon}}{\Delta+\beta}\right) \boldsymbol{\delta} A|y\rangle . \tag{E.6}
\end{align*}
$$

In appendix D we show that

$$
\begin{align*}
\lim _{\epsilon \rightarrow 0} X_{\epsilon}(\beta) & =\langle x| A \boldsymbol{\delta}\left(\frac{\Delta}{\Delta+\beta}\right) \boldsymbol{\delta} A|y\rangle=X(\beta)  \tag{E.7}\\
\lim _{\epsilon \rightarrow 0} Y_{\epsilon}(\beta) & =\langle x| A \boldsymbol{\delta}\left(\frac{1}{\Delta+\beta}\right) \boldsymbol{\delta} A|y\rangle=Y(\beta) \tag{E.8}
\end{align*}
$$

It is instructive to think of the spectral decomposition of the positive operator $\Delta$ :

$$
\begin{equation*}
\Delta=\int_{\lambda \in \mathcal{R}} e^{-\lambda} P(d \lambda), \tag{E.9}
\end{equation*}
$$

where $P(d \lambda)$ is a positive-operator valued measure. Then, for any $0<\epsilon<1, \beta>0$ and all vectors $|x\rangle$ we have

$$
\begin{equation*}
\langle x| \frac{\Delta^{1-\epsilon}}{\Delta+\beta}|x\rangle \leq\langle x| H|x\rangle \tag{E.10}
\end{equation*}
$$

where

$$
\begin{equation*}
H=\int_{0<\lambda<1} \frac{1}{\lambda+\beta} P(d \lambda)+\int_{\lambda>1} \frac{\lambda}{\lambda+\beta} P(d \lambda) \tag{E.11}
\end{equation*}
$$

By the Cauchy-Schwarz inequality we have the estimates

$$
\begin{align*}
&\left|\beta^{\epsilon} X_{\epsilon}(\beta)-\beta^{1-\epsilon} Y_{\epsilon}(\beta)\right|<2 F(\beta), \forall 0<\beta<1  \tag{E.12}\\
&\left|\beta^{\epsilon} X_{\epsilon}(\beta)-\beta^{1-\epsilon} Y_{\epsilon}(\beta)\right|<2 \beta F(\beta), \quad \forall 1<\beta  \tag{E.13}\\
& F(\beta)=\langle x| A \boldsymbol{\delta} H \boldsymbol{\delta} A|x\rangle+\langle y| A \boldsymbol{\delta} H \boldsymbol{\delta} A|y\rangle . \tag{E.14}
\end{align*}
$$

Since $\int_{0}^{1} F(\beta)<\infty$ and $\int_{1}^{\infty} \beta F(\beta)<\infty$ the dominated convergence theorem guarantees

$$
\begin{equation*}
\lim _{\epsilon \rightarrow 0} Q_{2}^{(\epsilon)}=\int_{0}^{\infty} d \beta\left(X_{\beta}-\beta Y(\beta)\right) \tag{E.15}
\end{equation*}
$$

which implies

$$
\begin{align*}
& \int_{0}^{\infty} \frac{d \beta}{\beta} \lim _{\epsilon \rightarrow 0} \int d t_{0} d t_{1} d t_{2} \beta^{i\left(t_{0}+t_{1}+t_{2}\right)} f\left(t_{0}\right) g_{\epsilon}\left(t_{1}\right) f\left(t_{2}\right)\langle x| \Delta^{-i t_{0}} \boldsymbol{\delta} \Delta^{-i t_{1}} \boldsymbol{\delta} \Delta^{-i t_{2}}|y\rangle  \tag{E.16}\\
& =\lim _{\epsilon \rightarrow 0} \int_{0}^{\infty} \frac{d \beta}{\beta} \int d t_{0} d t_{1} d t_{2} \beta^{i\left(t_{0}+t_{1}+t_{2}\right)} f\left(t_{0}\right) g_{\epsilon}\left(t_{1}\right) f\left(t_{2}\right)\langle x| \Delta^{-i t_{0}} \boldsymbol{\delta} \Delta^{-i t_{1}} \boldsymbol{\delta} \Delta^{-i t_{2}}|y\rangle \tag{E.17}
\end{align*}
$$

The argument above generalizes to the $m^{t h}$ term in (2.14) and justifies the interchange of the $\beta$ and $\epsilon \rightarrow 0$ limits. This generalization makes it clear that the order of limits of the $\epsilon_{i} \rightarrow 0$ does not matter in (2.14).

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[^0]:    ${ }^{1}$ Note that the expansion in [9] is similar to expanding (2.5) in $\alpha$ which is an unbounded operator in our case. To have a convergent series we use the bounded operator $\boldsymbol{\delta}$ as the expansion parameter. Our expressions (2.16)-(2.18) appear to differ from that in [9] in the $i \epsilon$ prescription, the integration contours, and operator orderings.

[^1]:    ${ }^{2}$ It is enough to take $k \geq 3$ as the previous computations of $S_{1,2}$ are sufficent to cover $k=2$.

