# Integrability and non-integrability for marginal deformations of $4 \mathrm{~d} \mathcal{N}=2$ SCFTs 

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Abstract: We study integrability and non-integrability for marginal deformations of 4 d $\mathcal{N}=2$ SCFTs. We estimate various chaos indicators for the bulk theory which clearly shows the onset of a chaotic string dynamics in the limit of large deformations. On the other hand, for small values of the deformation parameter, the resulting dynamics exhibits a non-chaotic motion and therefore presumably an underlying integrable structure. Our analysis reveals that the $\gamma$-deformation in the type-IIA theory could be interpreted as an interpolation between a class of integrable $\mathcal{N}=2$ SCFTs and a class of non-integrable $\mathcal{N}=1$ SCFTs at strong coupling. We also generalise our results in the presence of the flavor branes.

Keywords: AdS-CFT Correspondence, Gauge-Gravity Correspondence

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## 1 Introduction and general idea of this paper

Exploring the chaotic behaviour and the associated non-integrable structure in the context of gauge/gravity duality has been one of the thrust areas in modern theoretical physics for the last couple of decades. In most of these examples, one finds chaotic motion of string trajectories [1-17], while on the other hand, there are only handful of examples [18-21] that exhibit non-chaotic dynamics which therefore lead to an integrable structure.

Non-integrable systems are important in the context of the AdS/CFT correspondence $[22,23]$. The key idea here is to analyse the classical phase space trajectory governed by the (semi)-classical string solutions that give rise to various chaos indicators. These indicators guarantee whether the associated phase space would be lacking the usual Kolmogorov-Arnold-Moser (KAM) tori characterising (quasi)-periodic orbits [1-3]. Identification of these orbits is the key step towards unveiling an underlying integrable structure of the dynamical phase space at the classical level.

Following the holographic principle, it is conjectured that the semi-classical strings are dual to a class of single trace operators in the large $N$ limit. Hence, the above framework leads to a conjecture about the integrability (or nonintegrability) of the strongly coupled dual superconformal field theory. There have been standard approaches to prove or disprove integrability of a classical dynamical system. The most robust way to prove integrability is through the construction of Lax pairs [24-28]. Classical integrability of supergravity backgrounds containing an $\mathrm{AdS}_{5}$ and $\mathrm{AdS}_{4}$ factor have been studied extensively using Lax pairs in [24-29]. On the other hand, a popular approach towards disproving classical
integrability is based on the Kovacic's algorithm [12-14, 30-32] that has recently found extensive applications in the context of gauge/string duality.

Together with the above, it is also equally important to examine the integrable structure of the "deformed" superconformal field theories using a holographic setup. Among these theories, $\beta$-deformed $\mathcal{N}=4$ super Yang-Mills (SYM) [33] and $\gamma$-deformed KlebanovWitten model [9] are worthwhile to be mentioned. It is shown that the real $\beta$-deformed $\mathcal{N}=4$ SYM gives rise to an integrable structure [29, 34], while it looses integrability for imaginary $\beta$ deformation [10]. On the other hand, the deformed Klebanov-Witten exhibits a chaotic behaviour whose phase space dynamics is controlled by some deformation parameter supplemented by the energy of the system [9].

Following the above spirit, in the present paper, we are interested in studying the integrability and/or non-integrability of marginally deformed $4 \mathrm{~d} \mathcal{N}=2$ SCFTs that are introduced recently in [35]. The marginal deformed quiver corresponding to the dual $\gamma$-deformed background is conjectured to be a superconformal fixed point that preserves $\mathcal{N}=1$ supersymmetries. It is shown that the dual $\gamma$-deformed supergravity background can be obtained by applying an $\operatorname{SL}(3, R)$ transformation in the eleven dimensional M-theory solution followed by a type-IIA reduction [33, 35-37]. In what follows, we explore semiclassical string solutions associated to these class of $\gamma$-deformed supergravity backgrounds and estimate various chaos indicators. Based on our findings and the holographic principle, this would eventually allow us to conjecture about the integrability and/or non-integrability of the dual $\mathcal{N}=1$ quiver at strong coupling.

The equations of motion of semi-classical strings are in principle difficult to solve analytically. Therefore, we solve them numerically, upon fixing the winding numbers associated with the remaining $\mathrm{U}(1)$ isometries. We analyse the Poincaré sections and estimate the corresponding Lyapunov exponents for different values of $\gamma$ and show that the chaotic dynamics of the string is explicitly controlled by the deformation parameter $\gamma$.

Upon fixing the winding numbers $\lambda=k=1$, we study various Poincaré sections and the associated Lyapunov exponents. ${ }^{1}$ We notice that for large values of the deformation parameter ( $\gamma \gg 1$ ), the system eventually becomes more and more chaotic. On the other hand, the string does not exhibit any chaotic behaviour when the deformation is small enough $(\gamma \sim 0)$. This clearly connects to the fact that the integrable structure persists for the usual Sfetsos-Thompson (ST) background $[14,38,39]$ which is a special case of $\gamma=0$. From the perspective of the bulk theory, the above observation allows us to conjecture that the $\gamma$-deformation acts as an interpolation between an integrable $\mathcal{N}=2$ SCFTs $(\gamma=0)$ and non-integrable $\mathcal{N}=1$ SCFTs $(\gamma \gg 1)$ in the dual QFT description. ${ }^{2}$

The rest of the paper is organised as follows. We briefly review the $\gamma$-deformed type-IIA background in section 2. In section 3, we study the Poincaré sections and the Lyapunov exponents taking specific examples of $\gamma$-deformed type-IIA solutions. Finally, we draw our conclusion in section 4, where we provide physical explanation of our observations.

[^0]
## 2 Marginal deformations of 4d $\mathcal{N}=2$ SCFTs

Here, we first review the marginal deformations of four dimensional $\mathcal{N}=2$ SCFTs [35]. The marginal deformation of these theories results in a new class of $\mathcal{N}=1$ SCFTs in four spacetime dimensions. The holographic dual of which corresponds to a $\gamma$-deformed type-IIA supergravity which was constructed following the prescriptions of $[33,36,37,40]$.

These new class of $\gamma$-deformed backgrounds are obtained following an $\operatorname{SL}(3, R)$ transformation in eleven dimensional M-theory background while keeping $\gamma$ as a deformation parameter. Upon dimensional reduction along one of the $\mathrm{U}(1)$ isometric directions, ${ }^{3}$ one finds a ten dimensional type-IIA background of the form [35]

$$
\begin{gather*}
d s_{\mathrm{IIA}}^{2}=\alpha^{\prime} \mu^{2}\left[4 f_{1} d s_{A d S_{5}}^{2}+f_{2}\left(d \sigma^{2}+d \eta^{2}\right)+f_{3} d \chi^{2}+\frac{f_{3} \sin ^{2} \chi}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi} d \xi^{2}\right. \\
\left.+\frac{f_{4}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi}\left(d \beta-\gamma f_{5} \sin \chi d \chi\right)^{2}\right] . \tag{2.1}
\end{gather*}
$$

In the limit $\gamma \rightarrow 0$, the above ten dimensional solution (2.1) maps into the standard $\mathcal{N}=2$ supersymmetric Gaiotto-Maldacena background [14, 35, 41-44].

In global coordinates, the $A d S_{5}$ line element can be expressed as

$$
\begin{equation*}
d s_{A d S_{5}}^{2}=-\cosh ^{2} r d t^{2}+d r^{2}+\sinh ^{2} r d \Omega_{3}^{2}, \tag{2.2}
\end{equation*}
$$

where $d \Omega_{3}^{2}$ is the metric of the three-sphere with unit radius.
The warp factors $f_{i}(\sigma, \eta) \mathrm{s}$ in (2.1) can be expressed in terms of a potential function $V(\sigma, \eta)[35]$

$$
\begin{array}{lll}
f_{1}=\left(\frac{2 \dot{V}-\ddot{V}}{V^{\prime \prime}}\right)^{\frac{1}{2}} ; & f_{2}=f_{1} \frac{2 V^{\prime \prime}}{\dot{V}} ; & f_{3}=f_{1} \frac{2 V^{\prime \prime} \dot{V}}{\Delta} ;
\end{array} f_{4}=f_{1} \frac{4 V^{\prime \prime}}{2 \dot{V}-\ddot{V}} \sigma^{2}, ~\left(\frac{\dot{V}}{\Delta}-\eta\right) ; \quad f_{6}=\frac{2 \dot{V} \dot{V}^{\prime}}{2 \dot{V}-\ddot{V}} ; \quad f_{7}=-\frac{4 \dot{V}^{2} V^{\prime \prime}}{\Delta} ; \quad f_{8}=\left[\frac{4(2 \dot{V}-\ddot{V})^{3}}{\mu^{12} V^{\prime \prime} \dot{V}^{2} \Delta^{2}}\right]^{\frac{1}{2}},
$$

which satisfies Laplace's equation of the form

$$
\begin{equation*}
\ddot{V}+\sigma^{2} V^{\prime \prime}=0 . \tag{2.4}
\end{equation*}
$$

In the expressions of $f_{i}$ and $\Delta$, the dot and the prime of the potential function $V(\sigma, \eta)$ can be explicitly written as

$$
\begin{align*}
& \dot{V}=\sigma \partial_{\sigma} V, V^{\prime}=\partial_{\eta} V, \ddot{V}=\sigma \partial_{\sigma} \dot{V}, V^{\prime \prime}=\partial_{\eta}^{2} V, \dot{V}^{\prime}=\sigma \partial_{\sigma} V^{\prime}, \\
& \Delta=(2 \dot{V}-\ddot{V}) V^{\prime \prime}+\left(\dot{V}^{\prime}\right)^{2} . \tag{2.5}
\end{align*}
$$

[^1]The $\gamma$-deformed type-IIA background in (2.1) is supported by NS-NS two form and RR one form and three form fluxes along with the background dilaton ${ }^{4}$ [35]

$$
\begin{align*}
B_{2} & =\frac{\mu^{2} \alpha^{\prime}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi}\left(f_{5} d \Omega_{2}(\chi, \xi)-\gamma f_{3} f_{4} \sin ^{2} \chi d \xi \wedge d \beta\right) \\
C_{1} & =\mu^{4} \sqrt{\alpha^{\prime}}\left(f_{6} d \beta+\gamma\left(f_{7}-f_{5} f_{6}\right) \sin \chi d \chi\right) \\
C_{3} & =\frac{\mu^{6} \alpha^{\prime \frac{3}{2}}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi} f_{7} d \beta \wedge d \Omega_{2}(\chi, \xi) \\
e^{2 \Phi} & =\frac{f_{8}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi} \tag{2.6}
\end{align*}
$$

## 3 String motion in marginal deformed background

### 3.1 Sigma model

We begin our analysis with bosonic strings propagating on a curved manifold endowed with a metric $G_{\mu \nu}$ together with NS-NS two-form field $B_{\mu \nu}$. The dynamics of the string is characterised by the Polyakov action

$$
\begin{equation*}
S=-\frac{1}{2} \int d \tau d \tilde{\sigma}\left[\eta^{\alpha \beta} G_{\mu \nu}+\epsilon^{\alpha \beta} B_{\mu \nu}\right] \partial_{\alpha} X^{\mu} \partial_{\beta} X^{\nu} \tag{3.1}
\end{equation*}
$$

where $\eta_{\alpha \beta}$ is the two dimensional world sheet metric of the form $-\eta_{\tau \tau}=\eta_{\tilde{\sigma} \tilde{\sigma}}=1$ and $X^{\mu}$ are the string embedding coordinates on the world sheet. Moreover, we set our convention as $-\epsilon_{\tau \tilde{\sigma}}=\epsilon_{\tilde{\sigma} \tau}=-1$, throughout the rest of the analysis.

The canonical momentum corresponding to the coordinate $X^{\mu}$ takes the form

$$
\begin{equation*}
p_{\mu}=G_{\mu \nu} \partial_{\tau} X^{\nu}+B_{\mu \nu} \partial_{\sigma} X^{\nu} \tag{3.2}
\end{equation*}
$$

The Hamiltonian of the system is given by

$$
\begin{equation*}
\mathcal{H}=p_{\mu} \dot{X}^{\mu}-\mathcal{L}=\frac{1}{2} G_{\mu \nu}\left(\partial_{\tau} X^{\mu} \partial_{\tau} X^{\nu}+\partial_{\sigma} X^{\mu} \partial_{\sigma} X^{\nu}\right) . \tag{3.3}
\end{equation*}
$$

The equations of motion for $X^{\mu}$ is supplemented by the Virasoro constraints that leads to the vanishing of the 2 d stress tensor

$$
\begin{equation*}
T_{\tau \tau}=\frac{1}{2} G_{\mu \nu}\left(\partial_{\tau} X^{\mu} \partial_{\tau} X^{\nu}+\partial_{\sigma} X^{\mu} \partial_{\sigma} X^{\nu}\right)=0 ; T_{\tau \sigma}=\frac{1}{2} G_{\mu \nu} \partial_{\tau} X^{\mu} \partial_{\sigma} X^{\nu}=0 . \tag{3.4}
\end{equation*}
$$

Notice that, from (3.4), it is straightforward to show that the Hamiltonian (3.3) could be read as the time-time component of the 2 d stress tensor namely $\mathcal{H}=T_{\tau \tau}$.

To begin with, we consider that the string sits at the center $(r=0)$ of the $\mathrm{AdS}_{5}$ and wraps the $\mathrm{U}(1)$ isometries of the $\gamma$-deformed background. We choose an ansatz of the following form

$$
\begin{array}{lll}
t=t(\tau) ; & \sigma=\sigma(\tau) ; & \eta=\eta(\tau) ; \\
\xi=\xi(\tilde{\sigma})=k \tilde{\sigma} ; & \beta=\beta(\tilde{\sigma})=\lambda \tilde{\sigma} . & \tag{3.5}
\end{array}
$$

[^2]Here $\{\tau, \tilde{\sigma}\}$ are the coordinates of the two-dimensional world sheet and $\{k, \lambda\}$ are the integers which we denote as the winding numbers of the string along the $U(1)$ isometric directions ( $\xi$ and $\beta$ ) of the $\gamma$-deformed background (2.1). Following the embedding (3.5), the world sheet Lagrangian takes the following form

$$
\begin{align*}
& \mathcal{L}_{P}=-\frac{1}{2}\left[4 f_{1} \dot{t}^{2}-f_{2}\left(\dot{\sigma}^{2}+\dot{\eta}^{2}\right)-\left(f_{3}+\gamma^{2} \frac{f_{4} f_{5}^{2}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi} \sin ^{2} \chi\right) \dot{\chi}^{2}+\frac{f_{3} k^{2} \sin ^{2} \chi}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi}\right. \\
&\left.+\frac{f_{4} \lambda^{2}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi}\right]+\frac{k f_{5}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi} \sin \chi \dot{\chi}, \tag{3.6}
\end{align*}
$$

where dot denotes the derivative with respect to the world sheet time $(\tau)$.
The Lagrangian (3.6), leads to the following Hamiltonian

$$
\begin{align*}
\mathcal{H}=\frac{1}{2}[ & -\frac{p_{t}^{2}}{4 f_{1}}+\frac{1}{f_{2}}\left(p_{\sigma}^{2}+p_{\eta}^{2}\right)+\frac{f_{3} k^{2} \sin ^{2} \chi}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi}+\frac{f_{4} \lambda^{2}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi} \\
& \left.+\left(f_{3}+\gamma^{2} \frac{f_{4} f_{5}^{2}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi} \sin ^{2} \chi\right)^{-1}\left(p_{\chi}-\frac{k f_{5}}{1+\gamma^{2} f_{3} f_{4} \sin ^{2} \chi} \sin \chi\right)^{2}\right] . \tag{3.7}
\end{align*}
$$

### 3.2 Example I: $\gamma$-deformed Abelian T-dual

The potential function for the Abelian T-dual (ATD) case takes the form [44]

$$
\begin{equation*}
V_{\mathrm{ATD}}(\sigma, \eta)=\ln \sigma-\frac{1}{2} \sigma^{2}+\eta^{2} . \tag{3.8}
\end{equation*}
$$

Using (3.8), the associated functions $f_{i}(\sigma, \eta)$ in (2.3) take the following form

$$
\begin{array}{lll}
f_{1}=1 ; & f_{2}=\frac{4}{1-\sigma^{2}} ; & f_{3}=1-\sigma^{2} ;
\end{array} \quad f_{4}=4 \sigma^{2}, ~ 子 f_{7}=-2\left(1-\sigma^{2}\right)^{2} ; \quad f_{8}=\frac{64}{1-\sigma^{2}} .
$$

Using (3.9), the Hamiltonian (3.7) can be expressed as

$$
\begin{align*}
\mathcal{H}= & \frac{1}{2}\left[-\frac{p_{t}^{2}}{4}+\frac{\left(1-\sigma^{2}\right)}{4}\left(p_{\sigma}^{2}+p_{\eta}^{2}\right)+\frac{\left(1-\sigma^{2}\right) k^{2} \sin ^{2} \chi+4 \sigma^{2} \lambda^{2}}{1+4 \gamma^{2} \sigma^{2}\left(1-\sigma^{2}\right) \sin ^{2} \chi}\right. \\
& \left.+\left(p_{\chi}+\frac{2 k \eta \sin \chi}{1+4 \gamma^{2} \sigma^{2}\left(1-\sigma^{2}\right) \sin ^{2} \chi}\right)^{2}\left(\left(1-\sigma^{2}\right)+\frac{16 \eta^{2} \sigma^{2} \gamma^{2} \sin ^{2} \chi}{1+4 \gamma^{2} \sigma^{2}\left(1-\sigma^{2}\right) \sin ^{2} \chi}\right)^{-1}\right], \tag{3.10}
\end{align*}
$$

which serves as the basis for studying the Hamiltonian dynamics and hence the various chaos indicators that we compute next.

Using (3.10), the Hamilton's equations of motion could be read as

$$
\begin{align*}
\dot{\chi} & =\frac{p_{\chi}}{1-\sigma^{2}},  \tag{3.11a}\\
\dot{p}_{\chi} & =\frac{\left(\sigma^{2}-1\right)\left(k^{2}-16 \gamma^{2} \lambda^{2} \sigma^{4}\right)}{2\left(1+4 \gamma^{2} \sigma^{2}\left(1-\sigma^{2}\right) \sin ^{2} \chi\right)^{2}} \sin 2 \chi,  \tag{3.11b}\\
\dot{\sigma} & =\frac{1}{4}\left(1-\sigma^{2}\right) p_{\sigma}, \tag{3.11c}
\end{align*}
$$

| $\gamma$ | $\chi$ | $\sigma$ | $p_{\sigma}$ | $p_{\chi}$ |
| :---: | :---: | :---: | :---: | :---: |
| 0.25 | 0.5 | 0.1 | 0 | 1.40099 |
| 2.0 | 0.5 | 0.1 | 0 | 1.40425 |
| 3.0 | 0.5 | 0.1 | 0 | 1.40808 |
| 5.0 | 0.5 | 0.1 | 0 | 1.41835 |

Table 1. Initial conditions for different values of the deformation parameter $\gamma$ for the Abelian T-dual case.

$$
\begin{align*}
\dot{p}_{\sigma}=\frac{1}{4} \sigma\left[p_{\sigma}^{2}\right. & -\frac{4 p_{\chi}^{2}}{\left(1-\sigma^{2}\right)^{2}}+\frac{4\left(k^{2} \sin ^{2} \chi-4 \lambda^{2}\right)}{1+4 \gamma^{2} \sigma^{2}\left(1-\sigma^{2}\right) \sin ^{2} \chi}  \tag{3.11d}\\
& \left.+\frac{16 \gamma^{2}\left(2 \sigma^{2}-1\right) \sin ^{2} \chi\left(k^{2}\left(\sigma^{2}-1\right) \sin ^{2} \chi-4 \lambda^{2} \sigma^{2}\right)}{\left(1+4 \gamma^{2} \sigma^{2}\left(1-\sigma^{2}\right) \sin ^{2} \chi\right)^{2}}\right],
\end{align*}
$$

while in writing the above set equations of motion (3.11a)-(3.11d), we choose $\eta=0$ and $p_{\eta}=0$ for our convenience.

We now numerically estimate the Poincaré sections by solving the Hamilton's equations of motion (3.11a)-(3.11d) that is subjected to the Virasoro constraints (3.4). In our numerical plots, we set the energy of the string to be $E=3$. On the other hand, we choose the following set of values for the deformation parameter: $\{\gamma\}=\{0.25,2.0,3.0,5.0\}$. The corresponding plots are found in figures $1(\mathrm{a})-1(\mathrm{~d})$. Also notice that, in our analysis we set the winding numbers as $k=1$ and $\lambda=1$ (for general values of the winding numbers see appendix A).

We now proceed to choose sets of initial conditions that generate solutions to the dynamical equations (3.11a)-(3.11d) for different values of the deformation parameter $\gamma$. These initial conditions are indeed consistent with the Virasoro constraints (3.4). In the following analysis, we choose the initial conditions as $\sigma(0)=0.1$ and $p_{\sigma}(0)=0$. With this initial set of data and the choice $\chi(0)=0.5$, the corresponding $p_{\chi}(0)$ is fixed while satisfying the constraint (3.4). For different values of the deformation parameter $(\gamma)$ this is shown in table 1 below.

In the present example, the phase space under consideration is four dimensional and characterised by the following set of generalised coordinates and momenta: $\left\{\sigma, \chi, p_{\sigma}, p_{\chi}\right\}$. At fixed energy $E=3$ of the string, for small deformation $(\gamma=0.25)$ the phase space trajectory is observed to be quasi-periodic (cf. figure 1(a)). However, as the deformation is increased the perturbations of the Hamiltonian result the destruction of the quasi-periodicity and randomly distributed data sets are generated. These are shown in figures 1(b)-1(d). Since these distributions lack any nice foliation in the form of KAM tori [ $1-3]$, which are observed in an integrable systems, we conclude that the system is chaotic at large deformations.

Next we numerically compute another chaos indicator namely, the Lyapunov exponent [1-3]. During the time evolution of a chaotic system, the system becomes sensitive to the choice of initial conditions that are imposed on the dynamics. The Lyapunov expo-


Figure 1. Plots of Poincaré sections for $\gamma$-deformed Abelian T-dual background. Here we fix the energy of the string $E=3$ and choose different values of the deformation parameter $\gamma$. As the deformation increases, the configuration becomes more and chaotic.
nent ( $\lambda$ ) measures the deviation between two nearby trajectories in the phase space due to a small variation in the initial conditions. ${ }^{5}$

As before, we choose the energy of the string as $E=3$, whereas the rest of the initial conditions are chosen as in table 1. With this initial set of data, we study the dynamical evolution of two nearby orbits in the phase space which have an initial separation $\Delta X(0)=10^{-7}$ (cf. (3.12)). The resulting plots are shown in figure 2. We observe that, for $\gamma>1$, the Lyapunov exponent saturates to positive non-zero values at sufficient late times indicating the onset of chaos. On the other hand, for small $\gamma<1$, it asymptotes to zero at sufficiently late times indicating an underlying non-chaotic dynamics of the associated phase space.

[^3]where $\Delta X\left(X_{0}, \tau\right)$ is the separation between the infinitesimally close trajectories in the phase space at sufficiently late times.


Figure 2. Numerical plots of Lyapunov exponent(s) for $\gamma$-deformed Abelian T-dual background. Here we fix the energy of the string as $E=3$. Different curves correspond to different values of the deformation parameter $\gamma$, as indicated in the figure.

### 3.3 Example II: $\gamma$-deformed Sfetsos-Thompson solution

For Sfetsos-Thompson (ST) solution (also known as non-Abelian T-dual (NATD) solution) the corresponding potential function reads as [44]

$$
\begin{equation*}
V_{\mathrm{ST}}(\sigma, \eta)=\eta\left(\ln \sigma-\frac{1}{2} \sigma^{2}\right)+\frac{1}{3} \eta^{3} . \tag{3.13}
\end{equation*}
$$

Using (3.13), the associated metric functions $f_{i}(\sigma, \eta)$ in (2.3) take the following form

$$
\begin{array}{lll}
f_{1}=1 ; \quad f_{2}=\frac{4}{1-\sigma^{2}}, & f_{3}=\frac{4 \eta^{2}\left(1-\sigma^{2}\right)}{4 \eta^{2}+\left(1-\sigma^{2}\right)^{2}}, & f_{4}=4 \sigma^{2}, \\
f_{5}=-\frac{8 \eta^{3}}{4 \eta^{2}+\left(1-\sigma^{2}\right)^{2}}, & f_{6}=\left(1-\sigma^{2}\right)^{2}, & f_{7}=-\frac{8 \eta^{3}\left(1-\sigma^{2}\right)^{2}}{4 \eta^{2}+\left(1-\sigma^{2}\right)^{2}}, \\
f_{8}=\frac{256}{\left(1-\sigma^{2}\right)^{2}\left(4 \eta^{2}+\left(1-\sigma^{2}\right)^{2}\right)} . & \tag{3.14}
\end{array}
$$

Using (3.14) the Hamiltonian of the system (3.7) can be expressed as ${ }^{6}$

$$
\mathcal{H}=\frac{1}{8}\left[-p_{t}^{2}-\left(\sigma^{2}-1\right) p_{\sigma}^{2}-\left(\sigma^{2}-1\right) p_{\eta}^{2}\right.
$$

$$
-\frac{16 \eta^{2}\left(\sigma^{2}-1\right)\left(\frac{k^{2} \sin ^{2} \chi}{1-\frac{16 \gamma^{2} \eta^{2} \sigma^{2}\left(\sigma^{2}-1\right) \sin ^{2} \chi}{4 \eta^{2}+\left(\sigma^{2}-1\right)^{2}}}+\frac{\left(8 \eta^{3} k \sin \chi+4 \eta^{2} p_{\chi}\left(-4 \gamma^{2} \sigma^{4} \sin ^{2} \chi+4 \gamma^{2} \sigma^{2} \sin ^{2} \chi+1\right)+\left(\sigma^{2}-1\right)^{2} p_{\chi}\right)^{2}}{16 \eta^{2}\left(\sigma^{2}\left(16 \gamma^{2} \eta^{2} \sin ^{2} \chi-1\right)+1\right)^{2}}\right)}{4 \eta^{2}+\left(\sigma^{2}-1\right)^{2}}
$$

$$
\begin{equation*}
\left.+\frac{16 \sigma^{2}\left(\lambda^{2}+\frac{4 \gamma^{2} \eta^{2} \sin ^{2} \chi\left(8 \eta^{3} k \sin \chi+4 \eta^{2} p_{\chi}\left(-4 \gamma^{2} \sigma^{4} \sin ^{2} \chi+4 \gamma^{2} \sigma^{2} \sin ^{2} \chi+1\right)+\left(\sigma^{2}-1\right)^{2} p_{\chi}\right)^{2}}{\left(4 \eta^{2}+\left(\sigma^{2}-1\right)^{2}\right)^{2}\left(\sigma^{2}\left(16 \gamma^{2} \eta^{2} \sin ^{2} \chi-1\right)+1\right)^{2}}\right)}{1-\frac{16 \gamma^{2} \eta^{2} \sigma^{2}\left(\sigma^{2}-1\right) \sin ^{2} \chi}{4 \eta^{2}+\left(\sigma^{2}-1\right)^{2}}}\right] . \tag{3.15}
\end{equation*}
$$

[^4]| $\gamma$ | $\chi$ | $\sigma$ | $p_{\sigma}$ | $p_{\chi}$ |
| :---: | :---: | :---: | :---: | :---: |
| 0.25 | 0.5 | 0.1 | 0 | 0.0171369 |
| 2.0 | 0.5 | 0.1 | 0 | 0.0855865 |
| 3.0 | 0.5 | 0.1 | 0 | 0.1647719 |
| 5.0 | 0.5 | 0.1 | 0 | 0.374748 |

Table 2. Initial conditions for different values of the deformation parameter $\gamma$ for the non-Abelian T-dual case. Here we set the string energy $E=2$.

The resulting Hamilton's equations of motion easily follow from (3.15) and can be summarised as

$$
\begin{align*}
\dot{\sigma}= & -\frac{1}{4}\left(-1+\sigma^{2}\right) p_{\sigma},  \tag{3.16a}\\
\dot{p}_{\sigma}= & \frac{1}{4 \sigma^{3}}\left(\sigma^{4}\left(p_{\sigma}^{2}+p_{\chi}^{2}\right)-\frac{16 \lambda^{2}\left(\sigma^{2}-3\right)\left(\sigma^{2}+1\right) \sigma^{6}}{\left(\sigma^{2}-1\right)\left(\sigma^{2}\left(8 \gamma^{2}\left(\sigma^{2}-1\right) \cos 2 \chi-8 \gamma^{2} \sigma^{2}+8 \gamma^{2}+\sigma^{2}-2\right)+5\right)}\right. \\
& +\frac{16 \lambda^{2}\left(\sigma^{4}-10 \sigma^{2}+5\right)\left(\sigma^{4}-2 \sigma^{2}+5\right) \sigma^{4}}{\left(\sigma^{2}-1\right)\left(\sigma^{2}\left(8 \gamma^{2}\left(\sigma^{2}-1\right) \cos 2 \chi-8 \gamma^{2} \sigma^{2}+8 \gamma^{2}+\sigma^{2}-2\right)+5\right)^{2}}+\frac{k^{2}}{\gamma^{2}} \\
& \left.+\frac{k^{2}-\sigma^{2}\left(k^{2}+4 \gamma^{2} p_{\chi}\left(4 k \sin \chi+p_{\chi}\right)\right)}{\gamma^{2}\left(\sigma^{2}\left(8 \gamma^{2} \cos (2 \chi)-8 \gamma^{2}+1\right)-1\right)^{2}}+\frac{2 k^{2}-\sigma^{2}\left(k^{2}+4 \gamma^{2} p_{\chi}\left(4 k \sin \chi+p_{\chi}\right)\right)}{\gamma^{2}\left(\sigma^{2}\left(8 \gamma^{2} \cos (2 \chi)-8 \gamma^{2}+1\right)-1\right)}\right),  \tag{3.16b}\\
\dot{\chi}= & -\frac{2 k \sin \chi+p_{\chi}}{\sigma^{2}\left(8 \gamma^{2} \cos 2 \chi-8 \gamma^{2}+1\right)-1}-\frac{1}{4}\left(\sigma^{2}-1\right) p_{\chi},  \tag{3.16c}\\
\dot{p}_{\chi}= & -\frac{2 p_{\chi} k \cos \chi}{\sigma^{2}\left(8 \gamma^{2} \cos (2 \chi)-8 \gamma^{2}+1\right)-1}-\frac{32 \gamma^{2} \lambda^{2}\left(\sigma^{6}-3 \sigma^{4}+7 \sigma^{2}-5\right) \sigma^{4} \sin 2 \chi}{\left(\sigma^{2}\left(8 \gamma^{2}\left(\sigma^{2}-1\right) \cos 2 \chi-8 \gamma^{2} \sigma^{2}+8 \gamma^{2}+\sigma^{2}-2\right)+5\right)^{2}} \\
& +\frac{4 \cos \chi\left(\sigma^{2}\left(\sin \chi\left(k^{2}+4 \gamma^{2} p_{\chi}^{2}\right)+k p_{\chi}\right)-k\left(k \sin \chi+p_{\chi}\right)\right)}{\left(\sigma^{2}\left(8 \gamma^{2} \cos 2 \chi-8 \gamma^{2}+1\right)-1\right)^{2}} . \tag{3.16d}
\end{align*}
$$

In the next step, we numerically study the Poincaré sections and the Lyapunov exponents for the string configuration for different values of the deformation parameter $\gamma$. We choose the initial data as given in table 2. These data sets are indeed consistent with the Virasoro constraints (3.4). The resulting plots are shown in figures 3(a)-3(d) and figure 4.

Like before, we observe that for small values deformation parameter ( $\gamma \ll 1$ ), the Poincaré section is quasi-periodic (figure 3(a)) indicating an underline integrable structure. On the other hand, if the deformation is increased enough, the perturbation of the Hamiltonian destroys the quasi-periodicity and the resulting dynamics becomes chaotic. These are shown in figures $3(\mathrm{~b})-3(\mathrm{~d})$.

In figure 4, we plot the Lyapunov exponents $(\lambda)$ for different values of the deformation parameter. The Lyapunov exponent for $\gamma \gg 1$ and at sufficiently later times, saturates to a positive value. On the other hand, in the limit of small deformation ( $\gamma \ll 1$ ), the


Figure 3. Plots of Poincaré sections for $\gamma$-deformed non-Abelian T-dual background. Here we fix the energy of the string $E=2$ and choose different values of the deformation parameter $\gamma$. As the deformation increases, the configuration becomes more chaotic.


Figure 4. Numerical plots of Lyapunov exponent(s) for $\gamma$-deformed ST background. Here, we fix the energy of the string as $E=2$. Different curves correspond to different values of the deformation parameter $\gamma$, as indicated in the plot. The initial separation between two nearby phase space trajectories is set to be $\Delta X(0)=10^{-7}$.


Figure 5. We show $\gamma$-deformation as an interpolation between Sfetsos-Thompson background and chaotic dynamics of strings.
conclusion remains same as in the $\gamma$-deformed ATD example studied previously. The Lyapunov asymptotes to zero indicating a non chaotic motion and this is clearly visible in the figure 4. This observation (for small range of $\gamma$ ) is similar to what has been observed previously in the context of ST background in [14].

Therefore, we conjecture that, for a small range of $\gamma \sim 0$, we have a class of integrable $\mathcal{N}=1$ backgrounds in type-IIA theory whose dual SCFTs are also conjectured to be integrable. However, as we increase the values of $\gamma$-deformation, we deviate away from these class of integrable theories to a class of non-integrable SCFTs. Therefore, to summarise, $\gamma$-deformation acts like a bulk interpolating parameter (see figure 5) that connects a class of integrable $\mathcal{N}=1$ SCFTs (that are obtained from $\mathcal{N}=2$ SCFTs via marginal deformation) to a class of non-integrable $\mathcal{N}=1$ SCFTs at strong coupling.

### 3.4 Example III: Adding flavor branes

We now generalise our results in the presence of flavor brane [45]. The first one of these backgrounds is known as the single kink space-time where $N_{6}$ flavor $D 6$-branes sit at $\eta=P$ of the internal manifold, where $P(\gg 1)$ is an integer. The dual SCFT endows with a gauge group $\mathrm{SU}(N) \times \mathrm{SU}(2 N) \times \cdots \times \operatorname{SU}(P N)$ which is closed due to an addition of $\operatorname{SU}((P+1) N)$ flavor group. The second background that we choose is called the periodic Uluru space-time that corresponds to placing $N_{6}$ flavor $D 6$-branes at $\eta=P$ and $\eta=K+P$ of the internal manifold. These dual SCFT are characterised by a linear quiver consisting of $K \operatorname{SU}(N)$ gauge group nodes terminated on each end by placing suitable flavor nodes.

The potential function corresponding to the single kink solution may be written as [45]

$$
\begin{equation*}
V(\sigma \sim 0, \eta)=\eta N_{6} \ln \sigma+\frac{\eta N_{6} \sigma^{2}}{4} \Lambda_{k}(\eta, P)-\frac{\eta N_{6} \sigma^{2}}{4} \frac{P+1}{P^{2}-\eta^{2}}, \tag{3.17}
\end{equation*}
$$

where we define the above function as

$$
\begin{align*}
\Lambda_{k}(\eta, P)= & (P+1) \sum_{m=1}^{k}\left(\frac{1}{(2 m+(2 m-1) P)^{2}-\eta^{2}}-\frac{1}{(2 m+(2 m+1) P)^{2}-\eta^{2}}\right)  \tag{3.18}\\
& +\frac{P}{(2 k+1)^{2}(1+P)^{2}-\eta^{2}} .
\end{align*}
$$



Figure 6. Plot of a Poincaré section for $\gamma$-deformed single kink profile. Here we fix the energy of the string $E=3$ and choose of the deformation parameter $\gamma=0.25$. Also, we set $\eta=7, p_{\eta}=0$, $P=6$ and $k=10$.

In what follows, we consider $\gamma$-deformation of the above theory and calculate various chaos indicators. In order to establish the (non-)integrability of the string sigma model, we numerically study the Poincaré sections corresponding to different values of the deformation parameter $\gamma$. The below figure 6 shows a Poincaré section when the value of the deformation parameter is set as $\gamma=0.25$. We set the energy of the string as $E=3$. Clearly, the Poincaré section consists of random data points in the $\sigma-p_{\sigma}$ plane of the phase space. This indicates the chaotic dynamics of strings in the phase space.

Next, in the case of Uluru space-time, the potential function may be expressed as [45]

$$
\begin{equation*}
V(\sigma \sim 0, \eta)=-\eta N_{6} \ln \sigma+\frac{\eta N_{6} \sigma^{2}}{4} \Lambda_{u}(\eta, K, P)+\frac{\eta N_{6} \sigma^{2}}{4\left(P^{2}-\eta^{2}\right)} \tag{3.19}
\end{equation*}
$$

where we define

$$
\begin{equation*}
\Lambda_{u}(\eta, K, P)=\sum_{n=1}^{u}(-1)^{n+1}\left(\frac{1}{(n K+(2 n-1) P)^{2}-\eta^{2}}-\frac{1}{(n K+(2 n+1) P)^{2}-\eta^{2}}\right) \tag{3.20}
\end{equation*}
$$

In this case as well we observe from figure 7 that the Poincare section at energy $E=3$ and deformation $\gamma=0.25$ is a random sets of data points which are indicator of chaotic dynamics of the string. The above result is not surprising and in fact is expected since the presence of flavor branes spoil the integrability in dual SCFTs [14, 46].

## 4 Summary and outlook

In this present paper, we explore chaotic dynamics for a class of $\mathcal{N}=1$ supergravity backgrounds namely the $\gamma$-deformed abelian and non-Abelian T-dual of Gaiotto-Maldacena solutions. The dual $\mathcal{N}=1$ SCFT is characterised by a linear quiver theory proposed in [35]. The deformed background can be obtained by applying an $\operatorname{SL}(3, R)$ transformation in the eleven dimensional background followed by a type-IIA reduction.

The primary goal was to examine the integrability of the semi-classical string trajectories in the presence of the $\gamma$-deformation as introduced in [35]. In our analysis, we use the


Figure 7. Plots of Poincaré sections for $\gamma$-deformed Uluru profile. Here we fix the energy of the string $E=3$ and choose of the deformation parameter $\gamma=0.25$. Also, we set $\eta=7, p_{\eta}=0, P=6$, $n=10$ and $K=10$.


Figure 8. Motion in $(\sigma-\tau)$ plane for Abelian T-dual case with $E=3, k=\lambda=1, \eta=0, p_{\eta}=0$.
standard Hamiltonian formulation and study the Poincaré sections and the Lyapunov exponents for different values of the deformation parameter $(\gamma)$.

We obtain distorted KAM tori and positive Lyapunov exponents for sufficiently large values of $\gamma$. On the other hand, we observe an integrable dynamics for sufficiently small values of $\gamma \ll 1$. This allows us to interpret the $\gamma$-deformation as an interpolation between an integrable and non-integrable dynamics sitting at two different extrema of the parameter space (see figure 5). A careful analysis reveals that the string hits $\sigma \sim 1$ singularity (3.9), (3.14) when the deformation parameter is large enough, $\gamma \gg 1$. One the other hand, the string never reaches the above singularity for small values of the deformation $(\gamma \ll 1)$ parameter (see figures $8(\mathrm{a})-8(\mathrm{~b})$ and $9(\mathrm{a})-9(\mathrm{~b})$ ). From the bulk perspective, we therefore argue that the chaotic motion of these semi-classical strings could be an artefact of $\sigma \sim 1$ singularity as seen by the "extended" string for large values of the deformation parameter $(\gamma \gg 1)$.


Figure 9. Motion in $(\sigma-\tau)$ plane for $\gamma$-deformed ST case with $E=2, k=\lambda=1, \eta=1, p_{\eta}=0$.

From figures $8(\mathrm{a})-8(\mathrm{~b})$ and $9(\mathrm{a})-9(\mathrm{~b})$, one could see that the string rapidly touches $\sigma \sim 1$ singularity as the deformation is increased. This results in a sudden change in the string embedding which eventually causes a chaotic motion. To summarise, one must therefore treat the $\gamma$-deformed solution (2.1) carefully at large values of the deformation parameter $(\gamma)$ and see whether it is a trustable classical string background beyond certain limit [33].

From the perspective of the dual $\mathcal{N}=1 \mathrm{SCFTs}$, this could be an artefact of the fragmentation of the dual operator [45]. One could imagine, in the simplest possible scenario heavy single trace operators $\mathcal{O} \sim \operatorname{Tr} \Phi^{i j}$; where $\Phi^{i j}$ s are adjoint matter of some vector multiplet $V_{i}$. For large $\gamma$-deformations these operators are broken and the associated spin-chain structure is lost. A detailed understanding of the underlying mechanism is still lacking at this moment and certainly deserves further investigations in the future.

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## A String motion for zero and general windings

In this appendix, we provide plots for the Poincaré sections corresponding to the string configurations with zero $(k=\lambda=0)$ as well as general values of the winding numbers $(\{k, \lambda\}>1)$. As illustrative examples, we choose $k=\lambda=3$ and $k=\lambda=5$ for the latter cases.

As can be seen from figure 10, the point particle limits $(k=\lambda=0)$ of the strings for the Abelian T-dual background preserve the integrability of the string $\sigma$-models irrespective of the values of the deformation parameters $(\gamma)$. This is seen to follow from (3.11). On the other hand, in the $\gamma$-deformed Sfetsos-Thompson case the point particle limits $(k=\lambda=0)$ preserve integrability at small deformations only, as shown in figure 12 . In the large


Figure 10. Poincaré section for point-particle limit $(k=\lambda=0)$ corresponding to $\gamma$-deformed Abelian T-dual background. Here we fix the energy of the string as $E=6$ and the deformation parameters as $\gamma=0.25,5$.


Figure 11. Poincaré sections for $\gamma$-deformed Abelian T-dual background with non-zero winding numbers. Here we fix the winding numbers as $k=\lambda=3$ in figures 11(a), 11(c) and $k=\lambda=5$ in figures $11(\mathrm{~b}), 11(\mathrm{~d})$. In all cases we set the energy $E=6$. The plots in the upper row correspond to small deformation parameters $(\gamma=0.25)$ whereas, those in the lower row correspond to large values of the deformation $(\gamma=5)$.


Figure 12. Poincaré section for point-particle limit $(k=\lambda=0)$ corresponding to $\gamma$-deformed Sfetsos-Thompson background. Here we fix the energy of the string as $E=5$, and the deformation parameter as $\gamma=0.25$.


Figure 13. Poincaré sections for $\gamma$-deformed Sfetsos-Thompson background with non-zero winding numbers. Here we fix the winding numbers as $k=\lambda=3$ in figures $13(\mathrm{a}), 13(\mathrm{c})$ and $k=\lambda=5$ in figures $13(\mathrm{~b}), 13(\mathrm{~d})$. In all cases we set the energy $E=5$. The plots in the upper row correspond to small deformation parameters $(\gamma=0.25)$ whereas, those in the lower row correspond to large values of the deformation $(\gamma=5)$.
deformation $(\gamma \gg 1)$ the Hamilton's equation for $p_{\chi}$ (3.16d) can be expanded as

$$
\begin{equation*}
\dot{p}_{\chi}=\frac{p_{\chi}^{2} \sin 2 \chi}{8(\cos 2 \chi-1)^{2} \sigma^{2} \gamma^{2}}+\mathcal{O}\left(\gamma^{-3}\right) . \tag{A.1}
\end{equation*}
$$

Clearly, in the limit $\chi \rightarrow 0, \dot{p}_{\chi} \rightarrow \infty$. This is the reason we do not get a phase space plot at large deformation. This also indicates the fact that we can not take arbitrarily large values of the deformation parameter $(\gamma)$ - we need to truncate $\gamma$ at some finite value to obtain reasonable solution. In this regard, the point particle limit corresponding to the $\gamma$-deformed Sfetsos-Thompson background may be considered as a special case.

Nevertheless, the (non-)integrability of the $\sigma$-models for (large) small values of the deformation parameter $(\gamma)$ remain preserved even when we set the winding numbers of the strings greater than $1(k=\lambda=3,5)$. These have been shown in figures 11,13 .

## B Background dilaton and semi-classical analysis

In $\gamma$-deformed Sfetsos-Thompson solution, for sufficiently small values of $\gamma(\gamma \ll 1)$ the string moves close to $\sigma \sim 0$ as described in figure 9(a). For $\gamma \ll 1$ and around $\sigma \sim 0$ the background dilaton in (2.6) takes the form

$$
\left.e^{2 \Phi}\right|_{\gamma \ll 1} \sim \text { const. }+ \text { small fluctuations }\left(\mathcal{O}\left(\gamma^{2} \sigma^{2}\right)\right)
$$

Hence for $\gamma \ll 1$, the $\alpha^{\prime}$ correction term $\left(\alpha^{\prime} \sqrt{g} \mathcal{R}^{(2)} \Phi\right)$ in the Polyakov action (3.1) gives a constant contribution (ignoring the small fluctuations) and the equations of motion still remain same. Therefore, for $\gamma \ll 1$ the semi-classical analysis holds.

On the other hand, for sufficiently large values of $\gamma(\gamma \gg 1)$ the background dilaton in (2.6) takes the form

$$
\left.e^{2 \Phi}\right|_{\gamma \gg 1} \sim \frac{1}{\gamma^{2} \sigma^{2}\left(1-\sigma^{2}\right)^{3}}+\mathcal{O}\left(\frac{1}{\gamma^{3}}\right)
$$

As described in figure 9 (b) we observe that the string rapidly touches $\sigma \sim 1$ for $\gamma \gg 1$. Therefore, for $\gamma \gg 1$ the background dilaton blows up and the semi-classical approximation breaks down. In other words, the $\alpha^{\prime}$ corrections are important in the limit of large $\gamma$ deformations. Similar remarks hold for the $\gamma$-deformed Abelian T-dual example which we therefore prefer not to repeat here.

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[^0]:    ${ }^{1}$ One can show that for winding numbers greater than unity, the plots do not change qualitatively.
    ${ }^{2}$ Notice that, unlike the ST example [14], here we have a much richer structure in the sense that for small and non-zero $\gamma$, we have a class of type-IIA backgrounds that preserves integrability.

[^1]:    ${ }^{3}$ See [35] for details.

[^2]:    ${ }^{4}$ For the purpose of present analysis, we restrict ourselves only to the NS sector of the full superstring background. We also set $\alpha^{\prime}=\mu=1$ in our calculation.

[^3]:    ${ }^{5}$ The Lyapunov exponent is defined as $[1-3]$

    $$
    \begin{equation*}
    \lambda=\lim _{\tau \rightarrow \infty} \lim _{\Delta X_{0} \rightarrow \infty} \frac{1}{\tau} \log \frac{\Delta X\left(X_{0}, \tau\right)}{\Delta X\left(X_{0}, 0\right)} \tag{3.12}
    \end{equation*}
    $$

[^4]:    ${ }^{6}$ Notice that, in writing the above equations of motion (3.16a)-(3.16d) we set $\eta=1$ and $p_{\eta}=0$.

