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Holographic entanglement and Poincaré blocks in three-dimensional flat space

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ABSTRACT: We propose a covariant prescription to compute holographic entanglement entropy and Poincaré blocks (Global BMS blocks) in the context of three-dimensional Einstein gravity in flat space. We first present a prescription based on worldline methods in the probe limit, inspired by recent analog calculations in AdS/CFT. Building on this construction, we propose a full extrapolate dictionary and use it to compute holographic correlators and blocks away from the probe limit.

KEYWORDS: AdS-CFT Correspondence, Classical Theories of Gravity, Gauge-gravity correspondence, Space-Time Symmetries

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1 Introduction / motivation

The holographic principle [1, 2] relates a theory of quantum gravity in a volume of space-time to a field theory in a lower dimensional boundary. The most fruitful concrete version of this principle is the AdS/CFT correspondence [3], which relates a theory of quantum gravity in asymptotically anti-de Sitter space-time (AdS) with a conformal field theory (CFT) at the boundary of AdS. Other versions of the same principle include the dS/CFT [4], Kerr/CFT [5], Warped AdS/CFT [6], the Lifshitz/Non-relativistic CFT correspondence [7], and the higher spin gauge theory / CFT correspondence [8, 9].

In this note we study the case of flat holography, where a quantum field theory is expected to arise as a dual to quantum gravity in asymptotically flat geometries. Research in this direction started in the four dimensional case [10], and has recently gained attention due to possible implications concerning the infamous information paradox [11]. The three-dimensional case [12, 13] provides with a testing ground for ideas concerning classical and quantum gravity in flat space-times.

However, unlike the case of asymptotically anti-de Sitter space-times, a full fledged holographic dictionary is missing in flat holography. Currently the only entry in the dictionary relates the asymptotic symmetry group of Minkowski space with the symmetry of the boundary field theory. Whether such a theory can be dynamically realized is currently unknown. This is however enough to try to understand the duality at the level of kinematics. In this note, we will study the holographic interpretation of entanglement entropy, two-point and three-point correlation functions, and global blocks. We will describe a prescription which correctly computes these objects in the probe limit. Building on the intuition provided by this limit, we will propose a full extrapolate dictionary and successfully compute correlators and blocks involving light operators. We will then argue how the probe computations arise as a WKB approximation.

Preliminarily, we will discuss the entanglement entropy of a boundary interval. The holographic picture will serve as motivation to discuss the other kinematic invariants of the theory. Entanglement entropy measures the correlation structure of a quantum system. Computations in the field theory are generally a daunting task. An example where the calculation can be performed analytically is the case of two dimensional conformal field theories, where the existence of a infinite dimensional symmetry simplifies the problem greatly. Studying entanglement becomes more complicated as the dimension of the field theory increases, due to the lack of an infinite dimensional symmetry to capitalize on. Two dimensional Galilean conformal field theories (GCFT's) have been proposed as holographic duals to three-dimensional theories of gravity in asymptotically flat space-times [14]. The symmetry algebra is a central extension of the asymptotic symmetry of three dimensional Minkowski space-time at null infinity. It is known as the three dimensional Bondi-Metzner-Sachs algebra (BMS₃), and it is infinite dimensional. One can thus hope that the same simplifications arising in the conformal field theory case also arise in BMS field theories. The entanglement entropy calculations in the field theory literature are based in the replica trick [15] or "flat" extensions of the Cardy formula [16–18].

In the context of AdS/CFT holography, Ryu and Takayanagi (RT) proposed that entanglement entropy was holographically computed by the area of a co-dimension two bulk minimal surface [19]. A proposal for a covariant generalization was put forward by Hubeny, Rangamani and Takayanagi [20] (HRT), and was proven in [21]. In order to establish a connection between Einstein gravity in three dimensional asymptotically Minkowski space and a BMS₃ field theory, it is necessary to understand whether a generalization of the RT/HRT proposals exist in flat space. The authors of [18] have recently computed holo-

¹This is the limit where the dimensions of the operators in the correlation functions are in the regime $1 \ll m \ll 1/G$, so that the geodesic approximation can be used but back reaction can be neglected.

graphic entanglement entropy of a single interval region A in a BMS₃ field theory living at null infinity. The prescription, which they dubded the Rindler method, emulates the Casini-Huerta-Myers [22] calculation of entanglement entropy of ball shaped regions in a conformal field theory. In the CFT case, the causal development of the boundary region is conformally mapped to hyperbolic space, where the theory enjoys a thermal periodicity in time. As a consequence, entanglement entropy is associated to the thermal entropy of the transformed theory. In the flat case, the boundary region A is mapped to a different manifold with a thermal cycle using a finite BMS transformation. The thermal entropy of the transformed theory can then be computed by assuming a flat version of the Cardy formula. The calculation can also be extended into the bulk. The geometry dual to the transformed theory is a flat space cosmology (FSC), which possesses a co-dimension one horizon whose area computes entanglement entropy. The geometric picture in the untransformed theory is the length of a space-like geodesic connected to two null geodesics γ_i falling from the boundary endpoints $\partial_i \mathcal{A}$. The main properties of the geodesics in this picture is that they are tangent to the bulk modular flow vector whose boundary value corresponds to the modular generator. In [18], it was also noted that the space-like geodesic connecting the null lines γ_i is extremal. A figure of this set-up can be found in figure 1 (a). It is worth noting that the first calculation of holographic entanglement in three dimensional flat space was put forward in [15], where it was shown that holographic entanglement can be computed using Wilson lines, much like the AdS construction introduced in [23]. Nevertheless, the construction in [18] is explicitly geometric, and similar to the RT/HRT proposals in AdS.

In this note, we will extend on the covariant formulation of the same geometric picture. The prescription consists of finding an extremal path connecting the end-points of the boundary interval, in the spirit of [20]. In flat space, the only geodesics that reach the points $\partial_i \mathcal{A}$ on future null infinity are null lines.

Unlike the case in AdS/CFT, the geodesics falling from the different boundary endpoints do not intersect in the bulk, which forces us to connect them with an additional geodesic line. Extremizing the total length of the resulting path yields a covariant answer, equivalent to the one found in [18]. In section 2.4 we will test this proposal in non-trivial asymptotically flat geometries.

Our proposal mimics the HRT formula for holographic entanglement entropy in AdS₃. In this case, the entanglement of a boundary interval is computed by the length of a bulk extremal geodesic connecting the interval endpoints, displaced slightly with a spacelike regulator away from the boundary. In the context of AdS₃, a prescription for computing holographic scalar global conformal blocks in the probe limit has recently been proposed [24, 25]. It consists on extremizing the length of a network of geodesic segments attached to the boundary of Anti de-Sitter space. The obvious prescription in flat space is to extremize a network of geodesics connected to the operators at the boundary through null geodesics, much like one does to compute entanglement entropy. Each of the geodesics is weighted by the mass of the corresponding primary operator in the BMS field theory, as drawn in figure 3. The physical intuition this picture provides is that the extremal weighted length of the network is the on-shell action of massive particles propagating in flat space. Our

proposal in terms of on-shell actions simply reads

global BMS block = extr
$$\left(e^{-\sum_{i} \xi_{i} S_{\text{on-shell}}^{(i)}}\right)$$
, (1.1)

where ξ_i are the masses of the particles and $S^{(i)}$ are the corresponding on-shell actions. This prescription can also be used to compute the two-point and three-point functions of scalar operators in a BMS₃ field theory. In section 5, this proposal will be generalized to include propagation of particles with spin, following the work in [26]. The calculations in this work correctly reproduce the probe limit of low-point correlators and general Poincaré blocks (or global BMS₃ blocks) computed in the field theory in [27].

Inspired by the construction of global blocks in the probe limit, in section 6 we will propose a flat version of the extrapolate dictionary, and argue how the geodesic network construction arises as a WKB approximation. We will argue that the holographic construction of boundary correlators consists of attaching a position space Feynman diagram to null lines falling from the boundary at the operator locations, and integrating the position of the legs over an affine parameter;

$$\langle \mathcal{O}_1(x_1)\mathcal{O}_2(x_2)\ldots\rangle \sim \int_{\gamma_{x_1}} d\lambda_1 \int_{\gamma_{x_2}} d\lambda_2 \ldots \langle \Psi_1(\lambda_1)\Psi_2(\lambda_2)\ldots\rangle.$$
 (1.2)

Here, λ_i is the affine parameter along the null geodesic γ_{x_i} and Ψ_i is the bulk field dual to the operator \mathcal{O}_i . The symbol \sim is used because both sides can be rescaled by arbitrary constant factors as both the normalisation of the operators and the measure of an affine parametrisation can be rescaled.

We turn now to a detailed description of the theories on both sides of the holographic duality.

1.1 Flat gravity in 2+1 dimensions

We consider Einstein gravity on 2+1 dimensional Minkowski spacetime. We work on Eddington-Fikelstein coordinates, for which the line element reads

$$ds^{2} = -du^{2} - 2dudr + r^{2}d\phi^{2}, \qquad (1.3)$$

with retarded time u = t - r and the cylindrical identification $\phi \sim \phi + 2\pi$. The future boundary is at $r \to \infty$ with u and ϕ fixed. The holographic coordinate is r, which renders the holographic direction null. The asymptotic symmetry group is spanned by the following killing vectors

$$\xi^{u} = u\partial_{\phi}Y(\phi) + T(\phi) ,$$

$$\xi^{\phi} = Y(\phi) - \frac{u}{r}\partial_{\phi}^{2}Y(\phi) - \frac{1}{r}\partial_{\phi}T(\phi) ,$$

$$\xi^{r} = -\frac{J}{2r}\partial_{\phi}\xi^{u} - r\partial_{\phi}\xi^{\phi} ,$$

$$(1.4)$$

with the restriction $(\partial_{\phi}^3 + \partial_{\phi})T(\phi) = (\partial_{\phi}^3 + \partial_{\phi})Y(\phi) = 0$. Expanding $Y(\phi)$ and $T(\phi)$ in the modes $e^{in\phi}$ with n = -1, 0, 1, the killing vectors realize a sub-algebra of the Galilean

Conformal Algebra (GCA).

$$[L_{i}, L_{j}] = (i - j)L_{i+j},$$

$$[L_{i}, M_{j}] = (i - j)M_{i+j},$$

$$[M_{i}, M_{j}] = 0,$$
(1.5)

where i, j = -1, 0, 1. At null infinity this algebra is enhanced to an infinitely dimensional asymptotic symmetry group known as the BMS₃ group, or also the 2d Galilean Conformal Algebra. The conserved charges of this group satisfy a centrally extended version of the algebra that reads

$$[\mathcal{L}_{i}, \mathcal{L}_{j}] = (i - j)\mathcal{L}_{i+j} + \frac{c_{L}}{12}(i + 1)i(i - 1)\delta_{i+j,0},$$

$$[\mathcal{L}_{i}, \mathcal{M}_{j}] = (i - j)\mathcal{M}_{i+j} + \frac{c_{M}}{12}(i + 1)i(i - 1)\delta_{i+j,0},$$

$$[\mathcal{M}_{i}, \mathcal{M}_{i}] = 0.$$
(1.6)

The central charges depend on the specific theory of gravity. For the case of Einstein gravity, in order for the phase space of three-dimensional asymptotically flat gravity to match the space of coadjoint representations of the BMS₃ group, it is required that [28, 29]

$$c_L = 0, \quad c_M = \frac{3}{G}.$$
 (1.7)

Invoking the holographic principle in the semi-classical limit implies that a theory of gravity in asymptotically flat space-times is described by a field theory that enjoys BMS symmetry. The field content of such theory must organize into representations of this symmetry; $\{L_0, M_0\}$ form a maximally commuting subalgebra, so we will label out representations by their eigenvalues $\{\Delta, \xi\}$. The generators $\{L_{-1}, L_0, L_1, M_{-1}, M_0, M_1\}$ form the global sub-algebra which corresponds to the Poincaré group. This sub-algebra has two quadratic casimirs [30]

$$C_1 = M_0^2 - M_{-1}M_1 (1.8)$$

$$C_2 = 2L_0 M_0 - \frac{1}{2} \left(L_{-1} M_1 + L_1 M_{-1} + M_1 L_{-1} + M_{-1} L_1 \right). \tag{1.9}$$

The eigenvalues of the casimirs are

$$\lambda_1 = \xi^2 \qquad \lambda_2 = 2\xi(\Delta - 1).$$
 (1.10)

In order to make the connection to bulk physics, it helps to write these in terms of the familiar generators of the Poincaré algebra

$$[P_{\mu}, P_{\nu}] = 0$$
 $[\mathcal{M}_{\mu,\nu}, P_{\rho}] = i (\eta_{\mu\rho} P_{\nu} - \eta_{\nu\rho} P_{\mu})$ (1.11)

$$[\mathcal{M}_{\mu,\nu}, \mathcal{M}_{\rho,\sigma}] = i \left(\eta_{\mu\rho} M_{\nu\sigma} - \eta_{\mu\sigma} M_{\nu\rho} - \eta_{\nu\rho} M_{\mu\sigma} + \eta_{\nu\sigma} M_{\mu\rho} \right) , \qquad (1.12)$$

which are related by

$$P_t = M_0$$
 $P_x = \frac{M_1 + M_{-1}}{2}$ $P_y = i\frac{M_1 - M_{-1}}{2}$, (1.13)

$$P_{t} = M_{0} P_{x} = \frac{M_{1} + M_{-1}}{2} P_{y} = i \frac{M_{1} - M_{-1}}{2}, (1.13)$$

$$\mathcal{M}_{xy} = L_{0} \mathcal{M}_{ty} = \frac{L_{1} + L_{-1}}{2} \mathcal{M}_{tx} = -i \frac{L_{1} - L_{-1}}{2}. (1.14)$$

In terms of these, the casimirs read

$$C_1 = -P^2 \qquad C_2 = \epsilon^{\mu\nu\rho} M_{\mu\nu} P_{\rho} \,. \tag{1.15}$$

Matching these casimirs allows us to identify the mass as $m^2 = \xi^2$ and determine the spin in terms of Δ . For a scalar field, C_1 imposes the Klein-Gordon equation whereas $M_{\mu\nu}$ acts trivially so that $C_2 = 0$ and $\Delta = 1$.

Note that in 3 dimensions, spin is a continuously tunable parameter. We conclude that BMS primary operators must correspond to massive spinning particles propagating in flat space. A conjecture for the extrapolate dictionary relating flat space quantum field solutions and local BMS primary operator insertions will be discussed in section 6.

We now turn to a more detailed description of some properties of BMS₃ field theories.

1.2 BMS_3 field theory

The holographic principle applied to flat space relies on the existence of a field theory living at null infinity. The symmetry of the theory must consist of the BMS₃ algebra. A theory which realises this symmetry is a BMS₃ Field Theory or BMSFT. It is currently not clear whether this algebra can be dynamically realized, as very few examples of such theories exist. For example, in [31] the authors construct a prototypical theory with BMS₃ symmetry, as a limit of Liouville theory. In [32] other exampes are constructed using holomorphic free fields. We will simply study kinematics which are fixed by the symmetry properties of the theory. We consider an asymptotically flat bulk space-time \mathcal{M} . At null infinity the manifold is endowed with a degenerate metric

$$ds^2 = 0du^2 + d\phi^2, (1.16)$$

where ϕ is the solid angle in S^1 . The diffeomorphism group is the BMS₃ group, and it acts on the coordinates of the theory as

$$u \to u' = u\partial f(\phi) + g(\phi),$$

$$\phi \to \phi' = f(\phi).$$
(1.17)

As an aside, we should note that this transformation law means that any two points (u_1, ϕ_1) and (u_2, ϕ_2) with $\phi_1 \neq \phi_2$ can be mapped to lie at the same u = 0 by

$$f(\phi) = \phi$$
, $g(\phi) = \frac{u_2 \sin(\phi - \phi_1) - u_1 \sin(\phi - \phi_2)}{\sin(\phi_1 - \phi_2)}$. (1.18)

By micro-causality, we must conclude that any local operators inserted at points such that $\phi_1 \neq \phi_2$ must commute. In other words, a BMS₃ invariant theory must be ultra-local with no propagating degrees of freedom. However, [18] found non-trivial entanglement in these theories. The simplest scenario consistent with these facts is a local theory of local degrees of freedom which do not propagate, but are subject to non-local constraints which impose non-trivial correlations.

The correlators we are hoping to compute are kinematic invariants, and have been written on the plane in [27]. The expressions for the two- and three-point functions in the cylinder can be obtained by performing the BMS transformation

$$x = e^{i\phi}, \quad t = iue^{i\phi}, \tag{1.19}$$

which acts on primaries as [33] $\Phi(u,\phi) = e^{i\phi\Delta}e^{iu\xi}\Phi(x,t)$. The result we would like to reproduce then reads

$$\langle \Phi_{\Delta,\xi} \Phi_{\Delta,\xi} \rangle = e^{-\xi \frac{u_2^{\partial} - u_1^{\partial}}{\tan \frac{\phi_2^{\partial} - \phi_1^{\partial}}{2}}} \left(\sin \frac{\phi_2^{\partial} - \phi_1^{\partial}}{2} \right)^{-2\Delta},$$

$$\langle \Phi_{\Delta_1,\xi_1} \Phi_{\Delta_2,\xi_2} \Phi_{\Delta_3,\xi_3} \rangle = C_{123} \prod_k e^{\xi_k \frac{\sum_{i < j} (-1)^{1+i+j} (u_i^{\partial} - u_j^{\partial}) \cos(\phi_k^{\partial} - \phi_i^{\partial})}{\sum_{i < j} (-1)^{1+i+j} \sin(\phi_i^{\partial} - \phi_j^{\partial})}} \left(\sin \frac{\phi_i^{\partial} - \phi_j^{\partial}}{2} \right)^{-\Delta_{ijk}},$$

$$(1.20)$$

where the primary operators are located in the null plane at points $(u, \phi) = (u_i^{\partial}, \phi_i^{\partial})$, and have quantum numbers ξ_i and Δ_i .

The four-point function is not fixed by BMS symmetry. It can however be expanded in a basis of BMS invariant functions, or global BMS₃ blocks. In this paper we study the block of four identical operators $\Phi_{\Delta,\xi}$ that interchange a BMS₃ representation with primary Φ_{Δ_p,ξ_p} . We will place the four primaries at boundary locations $x_k = (u_k^{\partial}, \phi_k^{\partial})$ for k = 1, 2, 3, 4, and the channel of the block will be $12 \to 34$. The four-point function of BMS₃ primaries on the plane decomposes into blocks as

$$\langle \phi_{1}\phi_{2}\phi_{3}\phi_{4}\rangle = \prod_{1 \leq i \leq j \leq 4} x_{ij}^{-\sum_{k} \Delta_{ijk}/3} e^{\frac{t_{ij}}{x_{ij}} \sum_{k} \xi_{ijk}/3} F_{\text{BMS}}(x,t) ,$$

$$F_{\text{BMS}}(x,t) = (1-x)^{(\Delta_{231}+\Delta_{234})/3} x^{(\Delta_{341}+\Delta_{342})} e^{\frac{t}{1-x} \frac{\xi_{231}+\xi_{234}}{3} - 3\frac{t}{x}(\xi_{341}+\xi_{342})} \times \sum_{p} C_{12p} C_{34p} g_{p}(x,t) ,$$

$$(1.21)$$

where the crossratios are defined as

$$x = \frac{x_{12}x_{34}}{x_{13}x_{24}}, \quad \frac{t}{x} = \frac{t_{12}}{x_{12}} + \frac{t_{34}}{x_{34}} - \frac{t_{13}}{x_{13}} - \frac{t_{24}}{x_{24}}.$$
 (1.22)

The constants C_{12p} and C_{34p} depend on the details of the field theory. In the large central charge limit, the full BMS block reduces to the global block. For equal external primary operators, the global block reads

$$g_p(x,t) = 2^{2\Delta_p - 2} (1-x)^{-1/2} x^{\Delta_p - 2\Delta} \left(1 + \sqrt{1-x}\right)^{2-2\Delta_p} e^{2\xi \frac{t}{x} - \xi_p \frac{t}{x\sqrt{1-x}}}.$$
 (1.23)

We turn now to the computation of holographic entanglement entropy, which will serve as motivation for the introduction of geodesic networks to compute low-point correlation functions and holographic global conformal blocks in the probe limit.

2 Flat space holographic entanglement entropy

In this section we provide with an alternative covariant re-formulation of the geometrical picture presented in [18]. The background metric is given by equation (1.3), and the boundary is taken to be null future infinity, at $r \to \infty$, with u and ϕ fixed. We define an interval \mathcal{A} as a straight line connecting two points at future infinity. We denote them by $\partial_i \mathcal{A}$ and they are located at $(u_i^{\partial}, \phi_i^{\partial})$. The authors of [18] compute holographic entanglement entropy as the length of a space-like geodesic which is connected to the interval at null infinity by two null geodesics. The space-like geodesic is the fixed points of replica symmetry, and the null geodesics are tangential to the modular flow.

This construction arises from an inverse bulk Rindler map, which is the BMS analog to the conformal map used in [22] to compute holographic entanglement entropy in the AdS/CFT context. The map transforms a flat space cosmological solution (FSC) back to the original Minkowski space-time. The Cauchy Horizon of the FSC maps to the union of two null planes in Minkowski space. The equations for these planes read

$$N_i$$
: $u = u_i^{\partial} - r + r \cos\left(\phi - \phi_i^{\partial}\right)$. (2.1)

Each plane contains a null line γ_i with $u = u_i^{\partial}$ and $\phi = \phi_i^{\partial}$. These lines are tangential to the bulk modular flow. Entanglement entropy is computed in [18] as the length of the space-like geodesic connecting γ_1 and γ_2 along $N_1 \cap N_2$. The construction is summarized in figure 1.

We would like to re-phrase this prescription in the language of extremal geodesics connecting the boundary endpoints ∂A_i , in the spirit of HRT [20]. For this we will first review the AdS case, which we will then generalize to the flat space case at hand.

2.1 Review of covariant holographic entanglement entropy in AdS/CFT

Before we attempt to understand the flat space case, it is instructive to review the construction in AdS/CFT. The vacuum entanglement entropy for a conformal field theory region in the plane consisting of an interval $[0, \omega]$ with $\omega \in \mathbb{C}$ is given by [34]

$$S_{\rm EE}^{\rm CFT_2} = \frac{c}{6} \log \frac{\omega}{\epsilon} + \frac{\bar{c}}{6} \log \frac{\bar{\omega}}{\epsilon}, \qquad (2.2)$$

where c, \bar{c} are the central charges of the conformal field theory and ϵ is the lattice distance, acting as a regulator of UV divergences.

For the holographic picture, we follow [20] very closely, where this prescription was first presented. The RT prescription for calculating entanglement is usually associated to Euclidean geometries. In relies on finding minimal surfaces, which is not a well defined Lorentzian concept. Wiggling space-like surfaces in the time direction one can make the area of a surface arbitrarily small. The solution to this puzzle is to consider the extrema of the area of a surface instead of the minima. We thus need to solve δ Area = 0 for small variations of the location of the co-dimension two surface, which we will call \mathcal{S} . We specify \mathcal{S} with two constraints

$$\varphi_1(x^{\nu}) = 0, \quad \varphi_2(x^{\nu}) = 0.$$
 (2.3)

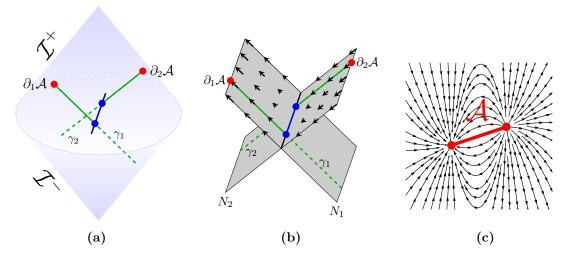


Figure 1. a) Holographic entanglement entropy as understood in [18]. The green lines γ_i are null geodesics falling from the null boundary \mathcal{I}_+ at the endpoints of the region \mathcal{A} . The blue space-like geodesic represents the fixed points of the bulk replica symmetry. b) Picture of bulk modular flow. The gray planes (N_i) correspond to the codimension one Cauchy Horizon of the flat space cosmological solution. The green lines are null, and we have dubbed them γ_1 and γ_2 throughout this note. The black arrows stand for the modular flow vector in the bulk, which vanishes at the intersection between the two planes; $N_1 \cap N_2$. The extremal path connecting the boundary endpoints is then formed by null lines tangent to modular flow (green) and the fixed points of replica symmetry (blue). c) Modular flow at the null boundary \mathcal{I}_+ . The axis are ϕ , u. The red line is the boundary region \mathcal{A} whose entanglement entropy is being studied.

We construct two null vectors N_{\pm}^{μ} obeying $N_{+}^{2}=N_{-}^{2}=0$ and $N_{+}\cdot N_{-}=-1$, such that they are orthogonal to the surface. We thus write

$$N_{\pm}^{\mu} = \mathcal{N}g^{\mu\nu} \left(\nabla_{\nu}\varphi_1 + \mu_{\pm}\nabla_{\nu}\varphi_2 \right) , \qquad (2.4)$$

and solve for μ_{\pm} and \mathcal{N} . The induced metric on \mathcal{S} reads

$$h_{\mu\nu} = g_{\mu\nu} + N_{+\mu}N_{-\nu} + N_{+\nu}N_{-\mu}, \qquad (2.5)$$

and the null curvatures can be written as

$$(\chi_{\pm})_{\mu\nu} = h^{\rho}_{\mu} h_{\sigma\nu} \nabla_{\rho} N_{+}^{\sigma}. \tag{2.6}$$

The null expansions are then defined as follows

$$\theta_{\pm} = g^{\mu\nu} \left(\chi_{\pm} \right)_{\mu\nu} \,. \tag{2.7}$$

Finally, the variation of the area of the surface S under a variation of its location can be written in terms of the null expansions as

$$\delta \text{Area} \sim \int_{\mathcal{S}} \left(\theta_+ N_+^{\mu} \delta X_{\mu} + \theta_- N_-^{\mu} \delta X_{\mu} \right) .$$
 (2.8)

The variation of the area will vanish if $\theta_{\pm} = 0$, rendering the surface S extremal.

For the sake of clarity and simplicity, we will perform the computation of holographic entanglement entropy in pure AdS_3 , where the answer must match the CFT₂ vacuum entanglement entropy of equation (2.2). We consider the Poincaré metric

$$ds^2 = \frac{-dt^2 + dx^2 + dz^2}{z^2} \,, (2.9)$$

where the holographic boundary lives at $z \to 0$. Consider a general co-dimension two curve S specified by

$$\varphi_1 = t - T(z) \quad \varphi_2 = x - X(z).$$
 (2.10)

The computation of the null expansions yileds

$$\theta_{+} - \theta_{-} \sim \left(X'^{3} + X'(1 - T'^{2}) - zX'' \right) ,$$

$$\theta_{+} + \theta_{-} \sim \left(T'^{3} + z \left(1 + X'^{2} \right) T'' - T' \left(1 + X'^{2} + zX'X'' \right) \right) ,$$
(2.11)

where the symbol \sim omits non-vanishing dependence on X(z) and T(z). We now need to solve for $\theta_{\pm} = 0$. The first equation implies

$$T'(z) = \pm \sqrt{\frac{X' + X'^3 - zX''}{X'}},$$
(2.12)

which can be used in the second differential equation to obtain

$$X' (3X'' + zX''') - 3zX''^{2} = 0. (2.13)$$

The solution reads

$$(X(z) - c_3)^2 = c_1 + c_2 z^2, (2.14)$$

where c_i are arbitrary constants. This implies, in virtue of equation (2.12),

$$(T(z) - d_1)^2 = (c_1 + c_2 z^2) \left(1 + \frac{1}{c_2}\right),$$
 (2.15)

where again d_i are constants. We now need to fix the constants of integration by depanding that the curve S starts and ends at the asymptotic boundary at the points (x_1, t_1) and (x_2, t_2) . After this, the solution for the curve reads

$$(X(z) - x_1)(X(z) - x_2) = \frac{z^2(x_1 - x_2)^2}{(t_1 - t_2 - x_1 + x_2)^2},$$

$$(T(z) - t_1)(T(z) - t_2) = \frac{z^2(t_1 - t_2)^2}{(t_1 - t_2 - x_1 + x_2)^2}.$$
(2.16)

The length of such curve from point (x_1, t_1) and (x_2, t_2) is formally infinite, but can be regulated by moving the holographic screen to $z = \epsilon \ll 1$. The regulated length is

$$S_{EE} = \frac{1}{4G} L_{\mathcal{S}}^{\text{extremal}} = \frac{1}{4G} \left(\log \frac{\omega_{12}}{\epsilon} + \log \frac{\bar{\omega}_{12}}{\epsilon} \right), \qquad (2.17)$$

where $\omega, \bar{\omega} = t \pm x$ are coordinates on the boundary plane. The result matches the CFT₂ result upon the replacement $c = \bar{c} = 3l/2G$.

Note here that the screen was introduced only to regulate the length, not to define the geodesic in the first place.

2.2 Covariant entanglement entropy in flat space

The field theory calculations in the literature are based in the replica trick [15] or "flat" extensions of the Cardy formula [18]. The vacuum result for a region consisting of an interval [(0,0),(u,x)] in the plane is given by

$$S_{\text{EE}}^{\text{BMS}_3} = \frac{c_L}{6} \log \frac{x}{\epsilon} + \frac{c_M}{6} \frac{u}{x}, \qquad (2.18)$$

where u is the time-like coordinate while x is space-like, and c_L , c_M are the central charges of the theory. As before, ϵ is a regulator of the UV divergences. For the case of theories dual to Einstein gravity in asymptotically flat geometries, the central charges are $c_L = 0$ and $c_M = 3/G$. The result for entanglement entropy in this case does not diverge as we take the UV regulator to zero. This seems to imply that in a continuum QFT with BMS symmetry there are no UV correlations at arbitrarily small scales, which makes it possible to split the Hilbert space along some dividing surface. Clearly this signals a fundamental difference between two-dimensional conformal field theories and field theories with BMS₃ symmetry.

In this section we follow the logic of HRT [20] to propose a covariant approach for the computation of holographic entanglement entropy in the context of flat 2+1 dimensional Minkowski space.

As in previous sections, we work with Eddingston-Fikelstein coordinates and the line element of equation (1.3). The boundary region \mathcal{A} is located at the null plane $r \to \infty$ with u and ϕ fixed. The boundary endpoints of the region \mathcal{A} are dubbed $\partial_i \mathcal{A}$, and they are placed at $(u_i^{\partial}, \phi_i^{\partial})$. In these coordinates, we hope to reproduce the BMSFT result for entanglement entropy as written in (2.18).

We define a curve S with the following constraints

$$\varphi_1 = u - U(r), \quad \varphi_2 = \phi - \Phi(r). \tag{2.19}$$

The null vectors in equation (2.4) are then specified by

$$\mu_{\pm} = \frac{-r^2 \Phi'(1 + U')}{1 + r^2 \Phi'^2} \pm \frac{r \sqrt{r^2 \Phi'^2 - U'(2 + U')}}{1 + r^2 \Phi'^2}, \quad \mathcal{N} = \sqrt{\frac{1 + r^2 \Phi'^2}{2r^2 \Phi'^2 - 2U'(2 + U')}}. \quad (2.20)$$

The null expansions read

$$\theta_{+} - \theta_{-} \sim \left(2\Phi' + r^{2}\Phi'^{3} + r\Phi''\right) ,$$

$$\theta_{+} + \theta_{-} \sim \left(r\Phi'(1 + U')(\Phi' + r\Phi'') - (1 + r^{2}\Phi'^{2})U''\right) .$$
(2.21)

The solutions with $\theta_{\pm}=0$ specify extremal curves. The second differential equation in (2.21) can be solved by replacing

$$U(r) = c_1 - r + r\cos(\Phi(r) - c_2), \qquad (2.22)$$

which makes the second differential equation in (2.21) proportional to the first. The constants c_1 and c_2 can be fixed by imposing that the curve \mathcal{S} starts at $\partial_1 \mathcal{A}$. This implies $U(r \to \infty) = u_1^{\partial}$ and $\Phi(r \to \infty) = \phi_1^{\partial}$, which leads to $c_1 = u_1^{\partial}$ and $c_2 = \phi_1^{\partial}$. We thus have

$$U(r) = u_1^{\partial} - r + r \cos\left(\Phi(r) - \phi_1^{\partial}\right). \tag{2.23}$$

It is important to note that the solution (2.23) matches the equation for the null plane N_1 in formula (2.1). In the work [18], this plane corresponds to the Cauchy horizon of a flat space cosmological solution that arises through the bulk Rindler map used to compute entanglement entropy. Here, the same plane arises naturally when studying extremal curves in flat space.

The solution for $\Phi(r)$ can be obtained by solving the first differential equation in equation (2.21). The solution reads

$$\Phi(r) = \pm \arctan \frac{d_1}{\sqrt{r^2 - d_1^2}} + d_2, \qquad (2.24)$$

where d_i are constants of integration. Imposing $\Phi(r \to \infty) = \phi_1^{\partial}$ implies $d_2 = \phi_1^{\partial}$. The resulting curve specified by $\Phi(r)$ still depends on a constant of integration d_1 , and corresponds to a null straight line along the null direction of the plane N_1 specified in (2.23). Solutions with different d_1 correspond to inequivalent null parallel lines and d_1 is the impact parameter or point of closest approach to our chosen origin.

These parallel lines all go to the same point on the conformal boundary. However, the Minkowski metric at the $r \to \infty$ boundary reads

$$ds^2 \to -du^2 + r^2 d\phi^2 \,, \tag{2.25}$$

and so parallel null lines points with different ϕ will be distinguishable unless $r\Delta\phi=0$. The choice of d_1 is an ambiguity in associating null rays to points on future null infinity which must be fixed in a consistent way. A choice for d_1 can be mapped into another by changing the origin of our coordinate system. We will fix d_1 by setting it to zero, so that all the null rays we consider pass through the origin of our coordinate system. This choice has the nice feature that in our coordinate system, the null rays meet the natural cut-off surface at fixed r at a right angle. They obey $r\Phi'(r)=0$ at large r. In other words, this is the requirement that the boundary point reached by our null ray should be stable under changes to our cut-off surface.

The solution for the extremal curve falling from $\partial_1 A$ is then

$$U(r) = u_1^{\partial}, \quad \Phi(r) = \phi_1^{\partial}, \tag{2.26}$$

which corresponds to a null straight line in the radial direction. Unlike the curve studied in AdS/CFT, an extremal curve in flat space cannot connect two different boundary points $\partial_1 \mathcal{A}$ and $\partial_2 \mathcal{A}$.

That the points on the asymptotic boundary can not be connected could be circumvented by introducing a cut-off surface at a large fixed $r = \epsilon^{-1}$ and connecting the points on the regulated surface. However, this geodesic will not be well defined in the limit where we remove the cut-off. In AdS, the extension of a geodesic connecting points on the regulated surface will reach the asymptotic boundary near the correct location. In flat space, the geodesic connecting these regulated boundary points will generically be spacelike and run off to the spacelike asymptotic boundary rather than future null infinity. In any case, the length of this regulated geodesic diverges in the $\epsilon \to 0$ limit and there are no BMS₃

invariant counter-terms which can be added to the length so as to reproduce the correct entanglement entropy. In the following we will introduce a prescription motivated by the construction of [18] which does correctly reproduce the entanglement entropy.

So far, we have concluded that the extremal curves falling from the boundary correspond to radial null geodesic lines which we will refer to as γ_i . In general these curves do not intersect, so in order to connect the boundary points we need to introduce a third curve connecting γ_1 and γ_2 . We choose points $y_i \in \gamma_i$ and connect them with a curve \mathcal{S}' . Imposing extremality of \mathcal{S}' as above implies that \mathcal{S}' is a straight line connecting y_1 with y_2 . The total length functional is then

$$L_{\text{total}} = L^{\text{extr}}(\partial_1 \mathcal{A}, y_1) + L^{\text{extr}}(y_1, y_2) + L^{\text{extr}}(y_2, \partial \mathcal{A}_2) = L^{\text{extr}}(y_1, y_2), \qquad (2.27)$$

where $L^{\text{extr}}(P,Q)$ is the length of a straight line from point P to point Q, and we have used the fact that null geodesics have no length. The final step is to extremize the total length functional with respect to the locations of y_i along the null lines γ_i . We start with the following expression for the length between the points at the null geodesics

$$L^{\text{extr}}(y_1, y_2) = \sqrt{r_1^2 + r_2^2 - 2r_1r_2\cos\left(\phi_1^{\partial} - \phi_2^{\partial}\right) - \left(u_2^{\partial} + r_2 - u_1^{\partial} - r_1\right)^2},$$
 (2.28)

where r_i is the radial location of the points y_i along γ_i . Solving for $\partial L_{\text{total}}/\partial r_i = 0$ implies

$$r_1 = \frac{u_2^{\partial} - u_1^{\partial}}{1 - \cos(\phi_1^{\partial} - \phi_2^{\partial})}, \quad r_2 = -\frac{u_2^{\partial} - u_1^{\partial}}{1 - \cos(\phi_1^{\partial} - \phi_2^{\partial})}.$$
 (2.29)

Note that this is the condition that the straight line connecting y_1 and y_2 must be orthogonal to the null rays γ_i :

$$\frac{\partial L^{\text{extr}}(y_1, y_2)}{\partial r_1} = \frac{\partial y_1^{\mu}}{\partial r_1} \frac{\partial L^{\text{extr}}(y_1, y_2)}{\partial y_1^{\mu}} = n_1^{\mu} t_{\mu} = 0, \qquad (2.30)$$

where t^{μ} is tangent to the line connecting y_1 and y_2 and n_i^{μ} is the null vector tangent to γ_i . The plane orthogonal to γ_i is the N_i introduced in (2.1), which includes n_i^{μ} since it is null. Thus extremising over the two endpoints imposes the condition that the line connecting y_1 and y_2 lies along $N_1 \cap N_2$, which is sufficient to fix it.

Replacing these back in (2.28) gives

$$L^{\text{extr}}(y_1, y_2) = \left| \frac{u_2^{\partial} - u_1^{\partial}}{\tan \frac{\phi_2^{\partial} - \phi_1^{\partial}}{2}} \right|. \tag{2.31}$$

We conclude that

$$S_{EE} = \frac{1}{4G} L_{\text{total}}^{\text{extremal}} = \frac{1}{4G} \left| \frac{u_2^{\partial} - u_1^{\partial}}{\tan \frac{\phi_2^{\partial} - \phi_1^{\partial}}{2}} \right|, \qquad (2.32)$$

which is the same answer obtained in the BMSFT.

Summarizing, we have successfully computed holographic entanglement as the length of an extremal geodesic path homologous to A. However, we had to consider an extremal

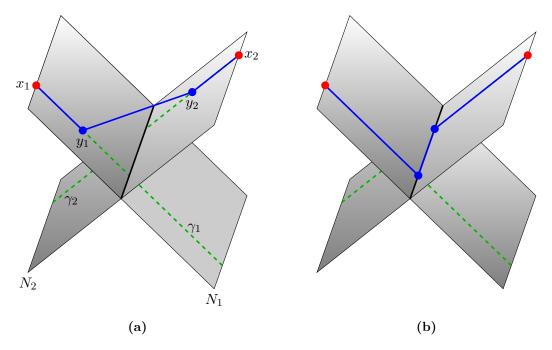


Figure 2. a) Calculation of Entanglement Entropy before extremizing. The red boundary points x_i are connected to the blue points y_i , which live at the null lines γ_i . b) Geometrical picture after extremizing the total length. The bulk points live at the intersections $N_1 \cap N_2 \cap \gamma_i$.

geodesic path with corners.² The following question then arises; if we were happy to introduce two corners, why not more? In particular, by adding one more corner we would find an extremal curve with no length connecting the two boundary points. One approach would be to use the curve with the least corners such that it has finite length. Instead, we will think of the null rays γ_i associated to points on the future null boundary as regulators which do not contribute to the length and find the minimal length curve which connects the two null rays. This latter view point will lead us to propose an extrapolate dictionary for flat space.

2.3 Relation to the replica trick

We can now ask why this prescription works from the point of view of the replica trick. In [15], The entanglement entropy in a generic BMS₃ field theory is computed by evaluating the two point function of twist fields Φ_n located at the boundary endpoints, and with quantum numbers

$$\Delta_n = \frac{c_L}{24} \left(1 - \frac{1}{n^2} \right), \quad \xi_n = \frac{c_M}{24} \left(1 - \frac{1}{n^2} \right).$$
(2.33)

In the case of semi-classical Einstein gravity in the bulk, we should set $c_L = 0$ and take the limit of large c_M , which turns the twist field into a bulk propagating particle of mass ξ_n . The limit $n \to 1$ is equivalent to the probe limit

$$\frac{\xi_n}{c_M} = 1 - \frac{1}{n^2} \ll 1. \tag{2.34}$$

²Note that corners do not result on a finite contribution to the length as can be seen by smoothing them out and taking the corner limit.

Entanglement entropy is then computed as

$$S_{EE} = -\lim_{n \to 1} \partial_n \text{Tr} \rho_{\mathcal{A}}^n = -\lim_{n \to 1} \partial_n \langle \Phi_n(\partial_1 \mathcal{A}) \Phi_n(\partial_2 \mathcal{A}) \rangle.$$
 (2.35)

We must now propose a holographic prescription for computing this correlator.

In the standard AdS/CFT dictionary, the correlator in this expression is computed as the exponential of an on-shell action corresponding to a massive particle propagating along an extremal trajectory $X^{\mu}(s)$. The computation in the previous subsection leads us to propose that in flat space, the particles should be sourced at the null geodesics γ_i associated to the boundary points in the correlator. In the probe limit, this means that the extremal trajectory $X^{\mu}(s)$ must be anchored along the γ_i such that the endpoints are free to move along the γ_i and should included in the extremisation.

The expression is

$$\langle \Phi_n(\partial_1 \mathcal{A}) \Phi_n(\partial_2 \mathcal{A}) \rangle = e^{-m_n S_{\text{on-shell}}},$$
 (2.36)

where $m_n = \xi_n$ and

$$S_{\text{on-shell}} = \sqrt{\eta_{\mu\nu}\dot{X}^{\mu}\dot{X}^{\nu}} = L_{\text{total}}^{\text{extr}}.$$
 (2.37)

Plugging (2.36) in (2.35), we obtain the same formula used in the previous subsection

$$S_{EE} = \frac{1}{4G} L_{\text{total}}^{\text{extr}}.$$
 (2.38)

In sections 3.1 and 3.2, we will use the same logic to calculate holographic BMS₃ two/three-point functions, and in section 4 we will consider Poincaré blocks.

2.4 Holographic entanglement in flat space cosmologies (quotients)

General classical solutions of Einstein gravity in three dimensions are locally equivalent. In the absence of a cosmological constant all solutions are locally flat, and are related to Minkowski space through quotients. An example of these solutions are Flat Space Cosmologies (FSC), whose metric reads

$$ds^{2} = Mdu^{2} - 2dudr + Jdud\phi + r^{2}d\phi^{2}.$$
 (2.39)

The dual BMSFT is expected to be a finite temperature theory with thermal cycle $(u, \phi) \sim (u + i\beta_u, \phi - i\beta_\phi)$ with $\beta_u = \pi J M^{-3/2}$ and $\beta_\phi = 2\pi M^{-1/2}$. The entanglement entropy in these field theories was computed in [35], where they arrived to the following formula

$$S_{EE} = \frac{1}{4G} \left[\sqrt{M} \left(T + \frac{J}{2M} L \right) \coth \frac{\sqrt{M}L}{2} - \frac{J}{M} \right]. \tag{2.40}$$

The same result can be achieved by extremizing the length of an extremal path homologous to \mathcal{A} in the FSC geometry. Geodesics in this geometry are not straight lines, so the problem becomes a bit more complicated. The strategy we will follow here will be to compute the invariant length between two points in Minkowski space, and then map those points to

points in the FSC using the coordinate transformation that implements the appropriate quotient. The coordinate transformation from Minkowski space to the FSC reads

$$r = \sqrt{M(t^2 - x^2) + \frac{J^2}{4M}},$$

$$\phi = -\frac{1}{\sqrt{M}} \log \left[\frac{\sqrt{M}(t - x)}{r + \frac{J}{2\sqrt{M}}} \right],$$

$$u = \frac{1}{M} \left(r - \sqrt{M}y - \frac{J}{2}\phi \right).$$

$$(2.41)$$

The invariant length in Minkowski space reads

$$\int ds = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 - (t_1 - t_2)^2},$$
(2.42)

and under the coordinate transformation (2.41), the points r_i, u_i, ϕ_i are mapped to the points

$$x_{i} = \frac{r_{i}}{\sqrt{M}} \sinh\left(\sqrt{M}\phi_{i}\right) - \frac{J}{2M} \cosh\left(\sqrt{M}\phi_{i}\right) ,$$

$$y_{i} = -\frac{r_{i}}{\sqrt{M}} + \frac{J}{2\sqrt{M}}\phi_{i} + u_{i}\sqrt{M} ,$$

$$t_{i} = \frac{r_{i}}{\sqrt{M}} \cosh\left(\sqrt{M}\phi_{i}\right) - \frac{J}{2M} \sinh\left(\sqrt{M}\phi_{i}\right) .$$

$$(2.43)$$

Replacing (2.43) in (2.42) we obtain the length between two points in the FSC. The boundary points $\partial_i \mathcal{A}$ are located at $(u, \phi) = (u_i^{\partial}, \phi_i^{\partial})$ in the future null plane. We need to find the extremal curve that starts at these boundary points. In the original minkowski coordinates the curve is a null line, and so the invariant length between any point in the extremal curve and the boundary point is zero. We thus need to find the points in the flat space cosmological solution that have zero invariant distance with the boundary points $\partial_i \mathcal{A}$.

The distance between a bulk point y_i and $\partial_i \mathcal{A}$ will be infinite unless the bulk point lies on a special hypersurface that we call N_i^{FSC} .

$$N_i^{\text{FSC}} : 0 = M\left(u_i - u_i^{\partial}\right) + \frac{J}{2}\left(\phi_i - \phi_i^{\partial}\right) + 2r_i \sinh^2 \frac{\sqrt{M}\left(\phi_i - \phi_i^{\partial}\right)}{2} - \frac{J}{2\sqrt{M}}\sinh\left(\sqrt{M}\left(\phi_i - \phi_i^{\partial}\right)\right). \tag{2.44}$$

The invariant length between a point $y_i \in N_i^{\text{FSC}}$ and $\partial_i \mathcal{A}$ reads

$$L(y_i, \partial_i \mathcal{A}) = \frac{1}{M} \left| J \sinh \left(\sqrt{M} \frac{\phi_i - \phi_i^{\partial}}{2} \right) + \sqrt{M} r_i \sinh \left(\sqrt{M} \left(\phi_i - \phi_i^{\partial} \right) \right) \right|, \qquad (2.45)$$

and so null lines are geodesics of constant $\phi_i = \phi_i^{\partial}$. All in all, the null geodesic in the flat space cosmological solution reads

$$\phi_i = \phi_i^{\partial}, \quad u_i = u_i^{\partial}. \tag{2.46}$$

Just like in the previous section, the extremal geodesic falling from $\partial_1 \mathcal{A}$ does not intersect the one falling from $\partial_2 \mathcal{A}$. This forces us to connect the null lines with an extra extremal

curve connecting the two different lightlike ones. We choose a bulk point $y_1 \in \gamma_1$ and another point $y_2 \in \gamma_2$, such that the total length is

$$L_{\text{total}} = L^{\text{extr}}(y_1, \partial_1 \mathcal{A}) + L^{\text{extr}}(y_1, y_2) + L^{\text{extr}}(y_2, \partial_2 \mathcal{A}) = L^{\text{extr}}(y_1, y_2). \tag{2.47}$$

Extremizing the total length with respect to the location of the points y_i along the null lines involves a morally similar computation as the one in the previous section. The process is a bit more cumbersome as the length of the geodesics is more complicated as a function of r_i , but the final answer matches the result written in equation (2.40).

3 Two-point and three-point BMS_3 correlation functions

In this section we generalize the worldline methods used in section 2.2 to commute entanglement entropy and we apply them to the computation of two- and three-point correlation functions of BMS₃ operators in the cylinder. The correlators we are hoping to compute have been written above in equations (1.20).

As a starting point we will consider primaries with $\Delta=1$ in the $1\ll \xi\ll c_M$ probe limit. In section 5 we will consider the spinning case $\Delta\neq 1$. The resulting primaries should correspond to massive scalars, and so we expect the correlator to be computed with the exponential of a scalar on-shell action. The on-shell action of massive particles corresponds to the length of the particle's worldline, and so we expect the correlator to be computed as the extremal length of a geodesic network. This is a consequence of the probe limit $1\ll \xi\ll c_M$. A general correlator involving BMS₃ primaries computed in this worldline picture involves a path integral whose saddle point corresponds to the geodesic networks studied in this section. We study correlators away from the probe limit in section 6.

The prescription in the probe limit is to compute a Poincaré invariant by connecting the null lines γ_i falling from the boundary points with a geodesic network, and then extremizing the answer with respect to the free parameters of the problem. We first consider the simplest correlator; the two-point function.

3.1 Scalar two-point function

In order to compute the two-point function we place two primaries of mass ξ at the null boundary, with cylinder coordinates $x_i = (u_i^{\partial}, \phi_i^{\partial})$, for i = 1, 2. We want to connect these two points by geodesics in such a way that the total on-shell action is extremal. The first step is to connect each boundary point with a bulk point $y_i = (r_i, u_i, \phi_i)$ located at the corresponding null geodesic γ_i . The bulk points are then connected with a space-like geodesic, giving rise to a total on-shell action

$$S_{\text{total}} = \xi \left[L(y_1, y_2) + \sum_{i=1,2} L(x_i, y_i) \right] = L(y_1, y_2).$$
 (3.1)

The extremization of this function with respect to the locations of y_i follows exactly the same logic as the one between formulas (2.28) and (2.31). The solution for the extremum

is $y_i = N_1 \cap N_2 \cap \gamma_i$. We thus conclude

$$S_{\text{total}}^{\text{extr}} = \xi \left| \frac{u_2^{\partial} - u_1^{\partial}}{\tan \frac{\phi_2^{\partial} - \phi_1^{\partial}}{2}} \right| . \tag{3.2}$$

We recover the result for the scalar two point function by exponentiating the extremal length

$$\langle \Phi_{1,\xi} \Phi_{1,\xi} \rangle = e^{-S_{\text{total}}^{\text{extr}}} = e^{-\xi \frac{u_2^{\partial} - u_1^{\partial}}{\tan \frac{\phi_2^{\partial} - \phi_1^{\partial}}{2}}}.$$
 (3.3)

The result presented in (3.3) matches expressions (1.20) up to factors that are subleading in the probe limit $1 \ll \xi \ll c_M$. Curiously, this is in fact the exact answer for the two point function of primaries with $\Delta = 0$. However, since we are working in the probe approximation, this computation does not track these subleading factors and we will trust the analysis of section 1.1 which lead us to conclude that a bulk scalar corresponds to a primary with $\Delta = 1$. This will be vindicated in section 6 where we move away from the probe limit and obtain the full answer including these subleading factors.

The calculation in this section is exactly the same as the calculation of holographic entanglement entropy. We next study a slightly more complicated case; the scalar three-point function.

3.2 Scalar three-point function

The prescription is the following. There are three primaries located at the points $x_k = (u_k^{\partial}, \phi_k^{\partial})$, with k = 1, 2, 3, and mass ξ_k . We want to connect the boundary points with geodesics in such a way that we obtain an extremum of the total length. The extremal curves falling from the boundary are null lines γ_k . We thus connect each null line with a common bulk vertex. For this we choose three points $y_k \in \gamma_k$ and connect them to the vertex point $y_v = (r_v, u_v, \phi_v)$. A picture of the set-up can be found in figure 3.a). The total length weighted by the corresponding masses is then

$$S_{\text{total}} = \sum_{k=1,2,3} \xi_k \left[L(x_k, y_k) + L(y_k, y_v) \right] = \sum_{k=1,2,3} \xi_k L(y_k, y_v).$$
 (3.4)

The free parameters are the radial locations of y_k along γ_k , which we denote by r_k , and the vertex point y_v . The action as a function of these variables reads

$$S_{\text{total}} = \sum_{k=1,2,3} \xi_k \left[\sqrt{r_k \left(u_v - u_k^{\partial} + 2r_v \sin^2 \frac{\phi_v - \phi_k^{\partial}}{2} \right) - \left(u_v - u_k^{\partial} \right) \left(2r_v + u_v - u_k^{\partial} \right)} \right]. \tag{3.5}$$

Extremizing with respect to r_k gives rise to three equations imposing the orthogonality between each of the lines y_k - y_v and γ_k . Namely

$$u_v - u_i^{\partial} + 2r_v \sin^2 \frac{\phi_v - \phi_i^{\partial}}{2} = 0, \quad \forall i = 1, 2, 3.$$
 (3.6)

³To be precise: given a quantity F computed in a background geometry without backreaction, consider the formal power series $\log F = a_0 \xi + a_1 + O(\xi^{-1})$ in a parameter ξ . The probe limit consist of keeping only the leading term in this expansion.

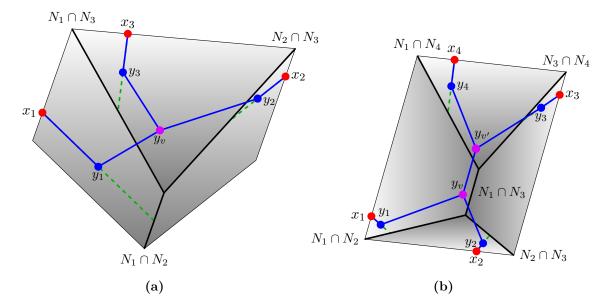


Figure 3. a) Set-up for the calculation of the holographic three point function before extremizing. The red boundary points x_i are connected to the blue points y_i , which live at the null lines γ_i . The bulk points are then connected to a completely arbitrary vertex point y_v , drawn in purple. b) Set-up for the calculation of the holographic scalar global block before extremizing. The red boundary points x_i are connected to the blue points y_i , which live at the null lines γ_i . The bulk points are then connected to two completely arbitrary vertex points y_v and $y_{v'}$, drawn in purple. These two vertex are connected with a line where a particle with mass ξ_p is propagating.

Solving these conditions fixes the position of y_v completely. Note that each of these equations corresponds to the planes N_i of equation (2.1). The point y_v must live at $N_1 \cap N_2 \cap N_3$. The result can be written simply in Minkowski coordinates

$$u_{v} + r_{v} = \frac{u_{3}^{\partial} \sin\left(\phi_{1}^{\partial} - \phi_{2}^{\partial}\right) - u_{2}^{\partial} \sin\left(\phi_{1}^{\partial} - \phi_{3}^{\partial}\right) + u_{1}^{\partial} \sin\left(\phi_{2}^{\partial} - \phi_{3}^{\partial}\right)}{\sin\left(\phi_{1}^{\partial} - \phi_{2}^{\partial}\right) - \sin\left(\phi_{1}^{\partial} - \phi_{3}^{\partial}\right) + \sin\left(\phi_{2}^{\partial} - \phi_{3}^{\partial}\right)},$$

$$r_{v} \cos \phi_{v} = \frac{\left(u_{3}^{\partial} - u_{2}^{\partial}\right) \sin \phi_{1}^{\partial} - \left(u_{3}^{\partial} - u_{1}^{\partial}\right) \sin \phi_{2}^{\partial} + \left(u_{2}^{\partial} - u_{1}^{\partial}\right) \sin \phi_{3}^{\partial}}{\sin\left(\phi_{1}^{\partial} - \phi_{2}^{\partial}\right) - \sin\left(\phi_{1}^{\partial} - \phi_{3}^{\partial}\right) + \sin\left(\phi_{2}^{\partial} - \phi_{3}^{\partial}\right)},$$

$$r_{v} \sin \phi_{v} = -\frac{\left(u_{3}^{\partial} - u_{2}^{\partial}\right) \cos \phi_{1}^{\partial} - \left(u_{3}^{\partial} - u_{1}^{\partial}\right) \cos \phi_{2}^{\partial} + \left(u_{2}^{\partial} - u_{1}^{\partial}\right) \cos \phi_{3}^{\partial}}{\sin\left(\phi_{1}^{\partial} - \phi_{2}^{\partial}\right) - \sin\left(\phi_{1}^{\partial} - \phi_{3}^{\partial}\right) + \sin\left(\phi_{2}^{\partial} - \phi_{3}^{\partial}\right)}.$$

$$(3.7)$$

Replacing these back in S_{total} results in

$$S_{\text{total}}^{\text{extr}} = \sum_{k=1,2,3} \xi_k \frac{\sum_{i < j} (-1)^{1+i+j} \left(u_i^{\partial} - u_j^{\partial} \right) \cos \left(\phi_k^{\partial} - \phi_i^{\partial} \right)}{\sum_{i < j} (-1)^{1+i+j} \sin \left(\phi_i^{\partial} - \phi_j^{\partial} \right)}.$$
 (3.8)

We recover the desired result for the scalar three-point function after exponentiating the extremal value of the length.

$$\langle \Phi_{1,\xi_1} \Phi_{1,\xi_2} \Phi_{1,\xi_3} \rangle = e^{-S_{\text{total}}^{\text{extr}}} = \prod_k e^{\xi_k \frac{\sum_{i < j} (-1)^{1+i+j} \left(u_i^{\partial} - u_j^{\partial}\right) \cos\left(\phi_k^{\partial} - \phi_i^{\partial}\right)}{\sum_{i < j} (-1)^{1+i+j} \sin\left(\phi_i^{\partial} - \phi_j^{\partial}\right)}}.$$
 (3.9)

Note that even though we did not need to solve for r_k in order to compute the value of S_{total} at the extremum, the extremality condition for the components of y_v fixes them. Performing this calculation yields

$$y_k = \frac{\gamma_k \cap N_i + \gamma_k \cap N_j}{2}, \text{ with } k \neq i \neq j.$$
 (3.10)

4 Holographic scalar global BMS₃ blocks (Poincaré blocks)

We are now ready to propose a calculation of a Poincaré invariant object that computes a global BMS₃ block holographically in the probe limit. The strategy is very similar to the one used for computing low-point correlation functions and it emulates the holographic construction of global blocks in the context of AdS/CFT.

The result we are hoping to reproduce in this section corresponds to the scalar part of equation (1.23). As we will see, the exponential involving ξ and ξ_p can be obtained holographically with the technology described in this note so far. The terms involving the spin Δ and Δ_p require additional tools, and we will discuss how to obtain the holographic result in section 5.

The prescription is to extremize the length of a geodesic network weighted by the mass of the corresponding primaries. We first introduce four bulk points y_k . Each of these must live on the corresponding null geodesic γ_k such that the curve connecting y_k and the boundary points x_k is extremal. The next step is to introduce two vertex points y_v and $y_{v'}$. Two geodesics join the points $y_{k=1,2}$ with y_v , while two different geodesics join the points $y_{k=3,4}$ with $y_{v'}$. All the geodesics we have introduced until now are weighted by the mass ξ of the external primaries of the block. The last step is to join the vertex points y_v and $y_{v'}$ with a geodesic whose length is weighted by the mass of the exchanged family, ξ_p . A figure of this set-up can be found in 3.b).

The total length we have to extremize reads

$$S_{\text{total}} = \xi \left[\sum_{k=1}^{4} L(x_k, y_k) + \sum_{k=1}^{2} L(y_k, y_v) + \sum_{k=3}^{4} L(y_k, y_{v'}) \right] + \xi_p L(y_{v'}, y_v). \tag{4.1}$$

The free parameters with respect to which S_{total} must be extremal are the bulk vertex points y_v and $y_{v'}$, and the radial locations of y_k along γ_k , which we dub r_k . The action in terms of these variables reads

$$S_{\text{total}} = \xi \sum_{k=1,2} \left[\sqrt{2r_k \left(u_v - u_k^{\partial} + 2r_v \sin^2 \frac{\phi_v - \phi_k^{\partial}}{2} \right) - \left(u_v - u_k^{\partial} \right) \left(2r_v + u_v - u_k^{\partial} \right)} \right]$$

$$+ \xi \sum_{k=3,4} \left[\sqrt{2r_k \left(u_{v'} - u_k^{\partial} + 2r_{v'} \sin^2 \frac{\phi_{v'} - \phi_k^{\partial}}{2} \right) - \left(u_{v'} - u_k^{\partial} \right) \left(2r_{v'} + u_{v'} - u_k^{\partial} \right)} \right]$$

$$+ \xi_p \sqrt{r_v^2 + r_{v'}^2 - 2r_v r_{v'} \cos \left(\phi_v - \phi_{v'} \right) - \left(u_v + r_v - u_{v'} - r_{v'} \right)^2} .$$

$$(4.2)$$

We now solve for $\partial S_{\text{total}}/\partial r_k = 0$. These equations read

$$u_{v} - u_{1}^{\partial} + 2r_{v} \sin^{2} \frac{\phi_{v} - \phi_{1}^{\partial}}{2} = 0,$$

$$u_{v} - u_{2}^{\partial} + 2r_{v} \sin^{2} \frac{\phi_{v} - \phi_{2}^{\partial}}{2} = 0,$$

$$u_{v'} - u_{3}^{\partial} + 2r_{v'} \sin^{2} \frac{\phi_{v'} - \phi_{3}^{\partial}}{2} = 0,$$

$$u_{v'} - u_{4}^{\partial} + 2r_{v'} \sin^{2} \frac{\phi_{v'} - \phi_{4}^{\partial}}{2} = 0.$$

$$(4.3)$$

As before, we can think of these as orthogonality constraints which constrain the location of the bulk vertices. They imply that y_v lives somewhere on $N_1 \cap N_2$, which is the minimal spacelike line connecting the null rays which appeared in the computation of the two-point function. Similarly, $y_{v'}$ lives somewhere on $N_3 \cap N_4$. Using (4.3) to simplify S_{total} yields

$$S_{\text{total}} = \xi \left[\sum_{k=1,2} \sqrt{\left(r_v \sin \left(\phi_v - \phi_k^{\partial} \right) \right)^2} + \sum_{k=3,4} \sqrt{\left(r_{v'} \sin \left(\phi_{v'} - \phi_k^{\partial} \right) \right)^2} \right] + \xi_p \sqrt{r_v^2 + r_{v'}^2 - 2r_v r_{v'} \cos \left(\phi_v - \phi_{v'} \right) - \left(u_v + r_v - u_{v'} - r_{v'} \right)^2} .$$

$$(4.4)$$

Expression (4.4) justifies introducing the parameters

$$s_{k} = r_{v} \sin \left(\phi_{v} - \phi_{k}^{\partial}\right) \quad \text{for} \quad k = 1, 2,$$

$$s'_{k} = r_{v'} \sin \left(\phi_{v'} - \phi_{k}^{\partial}\right) \quad \text{for} \quad k = 3, 4,$$

$$(4.5)$$

which correspond to the lengths on either side of y_v along $N_1 \cap N_2$ and similarly for $y_{v'}$:

$$s_1 + s_2 = \left(u_2^{\partial} - u_1^{\partial}\right) \cot \frac{\phi_1^{\partial} - \phi_2^{\partial}}{2}, \quad s_3' + s_4' = \left(u_4^{\partial} - u_3^{\partial}\right) \cot \frac{\phi_3^{\partial} - \phi_4^{\partial}}{2}. \tag{4.6}$$

Using this parametrisation, the location of the vertices can be written in terms of s_2 and s'_4 . The position of y_v reads

$$t_{v} = u_{v} + r_{v} = \frac{u_{1}^{\partial} - u_{2}^{\partial} \cos\left(\phi_{1}^{\partial} - \phi_{2}^{\partial}\right) + s_{2} \sin\left(\phi_{1}^{\partial} - \phi_{2}^{\partial}\right)}{1 - \cos\left(\phi_{1}^{\partial} - \phi_{2}^{\partial}\right)},$$

$$x_{v} = r_{v} \cos\phi_{v} = \frac{\left(u_{1}^{\partial} - u_{2}^{\partial}\right) \cos\left(\phi_{2}^{\partial}\right) + s_{2} \left(\sin\left(\phi_{1}^{\partial}\right) - \sin\left(\phi_{2}^{\partial}\right)\right)}{1 - \cos\left(\phi_{1}^{\partial} - \phi_{2}^{\partial}\right)},$$

$$y_{v} = r_{v} \sin\phi_{v} = \frac{\left(u_{1}^{\partial} - u_{2}^{\partial}\right) \sin\left(\phi_{2}^{\partial}\right) + s_{2} \left(\cos\left(\phi_{2}^{\partial}\right) - \cos\left(\phi_{2}^{\partial}\right)\right)}{1 - \cos\left(\phi_{1}^{\partial} - \phi_{2}^{\partial}\right)}.$$

$$(4.7)$$

Similarly, for $y_{v'}$ we have

$$t_{v'} = u_{v'} + r_{v'} = \frac{u_3^{\partial} - u_4^{\partial} \cos(\phi_3^{\partial} - \phi_4^{\partial}) + s_4' \sin(\phi_3^{\partial} - \phi_4^{\partial})}{1 - \cos(\phi_3^{\partial} - \phi_4^{\partial})},$$

$$x_{v'} = r_{v'} \cos \phi_{v'} = \frac{(u_3^{\partial} - u_4^{\partial}) \cos(\phi_4^{\partial}) + s_4' (\sin(\phi_3^{\partial}) - \sin(\phi_4^{\partial}))}{1 - \cos(\phi_3^{\partial} - \phi_4^{\partial})},$$

$$y_{v'} = r_{v'} \sin \phi_{v'} = \frac{(u_3^{\partial} - u_4^{\partial}) \sin(\phi_3^{\partial}) + s_4' (\cos(\phi_4^{\partial}) - \cos(\phi_4^{\partial}))}{1 - \cos(\phi_3^{\partial} - \phi_4^{\partial})}.$$
(4.8)

We can now replace formulas (4.7), (4.8), and (4.6) in S_{total} . The resulting on-shell action now depends on the parameters s_2 , and s'_4 .

$$S_{\text{total}} = \xi \left[\sqrt{\left(\left(u_2^{\partial} - u_1^{\partial} \right) \cot \frac{\phi_1^{\partial} - \phi_2^{\partial}}{2} \right)^2} + \sqrt{\left(\left(u_4^{\partial} - u_3^{\partial} \right) \cot \frac{\phi_3^{\partial} - \phi_4^{\partial}}{2} \right)^2} \right] + \xi_p \sqrt{F(s_2, s_4')}.$$

$$(4.9)$$

We are now ready to extremize with respect to s_2 and s'_4 . This means we have to solve for $\partial S_{\text{total}}/\partial s_2 = \partial S_{\text{total}}/\partial s'_4 = 0$, which fully determine s_2 and s'_4 .⁴ After replacing the solution back in S_{total} , we obtain

$$S_{\text{total}} = \xi \left[\left(u_2^{\partial} - u_1^{\partial} \right) \cot \frac{\phi_2^{\partial} - \phi_1^{\partial}}{2} + \left(u_4^{\partial} - u_3^{\partial} \right) \cot \frac{\phi_4^{\partial} - \phi_3^{\partial}}{2} \right]$$

$$+ \xi_p \frac{u_{43}^{\partial} \sin \phi_{21}^{\partial} + u_{42}^{\partial} \sin \phi_{13}^{\partial} + u_{14}^{\partial} \sin \phi_{23}^{\partial} + u_{23}^{\partial} \sin \phi_{14}^{\partial} + u_{31}^{\partial} \sin \phi_{24}^{\partial} + u_{12}^{\partial} \sin \phi_{34}^{\partial}}{8 \sin \frac{\phi_{34}^{\partial}}{2} \sin \frac{\phi_{12}^{\partial}}{2} \sqrt{\sin \frac{\phi_{13}^{\partial}}{2} \sin \frac{\phi_{14}^{\partial}}{2} \sin \frac{\phi_{24}^{\partial}}{2} \sin \frac{\phi_{24}^{\partial}}{2}}} .$$

$$(4.10)$$

This is the answer we expect from the BMSFT result in [27]. This can be seen by writing everything in terms of cross-ratios and coordinates in the plane

$$S_{\text{total}} = \left(\frac{t_{ij}}{x_{ij}} \sum_{k} \frac{\xi_{ijk}}{3}\right) + \left(\frac{t}{1-x} \frac{\xi_{231} + \xi_{234}}{3} - 3\frac{t}{x} (\xi_{341} + \xi_{342})\right) + \left(2\xi \frac{t}{x} - \xi_p \frac{t}{x\sqrt{1-x}}\right). \tag{4.11}$$

Here the first two parenthesis match the prefactors in (1.21), while the third term corresponds to the contribution from $g_p(x,t)$.

5 Spinning correlators and Poincaré blocks

In the previous sections we have studied global blocks concerning primaries with vanishing L_0 eigenvalue. The representations of the BMS₃ algebra are usually labeled by two quantum numbers Δ and ξ , which are the eigenvalues of L_0 and M_0 respectively acting on the highest weight state. In this section, we compute low-point functions and global blocks involving general representations with non-vanishing Δ and ξ . Note that these representations of the BMS₃ algebra are not unitary [36, 37]. It would also be interesting to understand the holography of blocks involving unitary irreducible representations of the BMS₃ algebra. However, to our knowledge there are no results concerning these blocks in the literature.

In the $\Delta = 0$ case, the parameter ξ was associated to the mass of a particle propagating in flat space. We thus expect that the parameter Δ is associated with the spin of such particle. In [26], an action of a massive spinning particle (anyon) was used to compute

⁴The 6 coordinates of y_v and $y_{v'}$ have been parametrised by 2 variables s_2 and s'_4 , hiding 4 extremality constraints. These can be used to fix the 4 r_k along the external legs. However, these are not needed to compute the value of the action at the extremum so we have omitted them from the discussion.

entanglement entropy in the context of AdS/CFT in a theory of topologically massive gravity. We will use the same action in this work.

$$S = \int d\sigma \left[\xi \sqrt{\eta_{\mu\nu} \dot{X}^{\mu} \dot{X}^{\nu}} + \Delta \left(\tilde{n} \cdot \nabla n \right) \right] + S_{\text{constraints}}, \qquad (5.1)$$

where \tilde{n} is a space-like vector, n is a time-like vector, both normal vectors to the trajectory of the particle X^{μ} , and $S_{\text{constraints}}$ is an action imposing constraints through Langrange multipliers.

$$S_{\text{constraints}} = \int d\sigma \left[\lambda_1 n \cdot \tilde{n} + \lambda_2 n \cdot \dot{X} + \lambda_3 \tilde{n} \cdot \dot{X} + \lambda_4 \left(n^2 + 1 \right) + \lambda_5 \left(\tilde{n}^2 - 1 \right) \right]. \tag{5.2}$$

The action (5.1) introduces two vectors in three-dimensional Minkowski space, amounting to six new degrees of freedom. It also introduces five constraints, resulting in a single new degree of freedom. Studying the equations of motion however reveals that it is not a true degree of freedom. The action (5.1) is insensitive to the variation of n, \tilde{n} along the path X^{μ} , and only depends on the boundary values of the vectors. It is also important to mention that the new equation of motion for X^{μ} reads

$$\nabla \left[\xi \dot{X}^{\mu} + \Delta \dot{X}_{\rho} \nabla \left(n^{\mu} \tilde{n}^{\nu} - n^{\nu} \tilde{n}^{\mu} \right) \right] = -\frac{\Delta}{2} \dot{X}^{\nu} \left(n^{\rho} \tilde{n}^{\sigma} - n^{\sigma} \tilde{n}^{\rho} \right) R^{\mu}_{\nu\rho\sigma} \,. \tag{5.3}$$

Using the constraint equations one can show that \tilde{n} is completely fixed as a function of n. Namely, $\tilde{n}^{\mu} = \epsilon^{\mu\nu\rho}\dot{X}_{\nu}n_{\rho}$. This, together with the fact that in Minkowski space the Riemann tensor vanishes, is enough to conclude that the solution to (5.3) is still a straight line obeying $\ddot{X}^{\mu} = 0$. This is equivalent to the statement that particles with spin also move in straight lines in a Minkowski background. The on-shell version of the action (5.1) of a particle moving from point x_i and vector n_i to a point x_f with vector n_f reads

$$S_{\text{on-shell}} = \xi L(x_i, x_f) + \Delta \cosh^{-1} \left(-n_i \cdot n_f \right) , \qquad (5.4)$$

where $L(x_i, x_f)$ is the length of a straight line connecting the points x_i and x_f , while $n_i \cdot n_f$ is obtained by parallel transporting n_f from x_f to x_i along X^{μ} and taking the scalar product between the resulting vector and n_i . Otherwise, one can compute $n_i \cdot n_f$ by writing the vectors in global Minkowski coordinates and taking the scalar product directly. The second term in the action corresponds to the total boost parameter required to take the frame defined by (\dot{X}, n, \tilde{n}) at the initial point to that at the final point.

In order to compute low-point correlators and Poincaré blocks involving spinning particles, we need to repeat the method of previous sections using the new on-shell action (5.4). As in previous sections, we regulate the problem by translating the boundary points to new bulk points y_i that lie on null lines γ_i falling from the boundary. The new ingredient is that we must introduce bulk vectors n at each of the bulk points. A natural assignment would be to use the direction of the null ray assigned to each boundary point. We thus define

$$\dot{\gamma}_i = \partial_r|_{\gamma_i} \,. \tag{5.5}$$

The extrimization of r_i along γ_i ensures that $\dot{\gamma}_i$ is orthogonal to the outgoing line, so that this definition will not result in a degenerate frame. However, the action above only makes

sense for n_i timelike. One way to think of this is that the boost required to take us between different null vectors is infinite and must be regulated. We will do so by introducing a regulator ϵ and taking n_i to approach $\dot{\gamma}_i$ in the limit where $\epsilon \to 0$, but keeping n_i a finite timelike unit vector for finite ϵ . The vector associated to the regulated bulk point at γ_i is then

$$n_i = \frac{1}{\epsilon} \dot{\gamma}_i + \epsilon m_i$$
, where m_i is null and $\gamma_i \cdot m_i = -1$. (5.6)

There is another perspective from which this prescription is natural. When this action was used in the standard AdS/CFT setup [26], the timelike vector defining the frame at the boundary was chosen to coincide with the boundary coordinate time direction, ∂_t . Similarly here, we could start with the vector ∂_u at large r and parallel transport it down the null ray to the bulk point y_i . This will give us a null vector orthogonal to $\dot{\gamma}$, which corresponds to the $\epsilon \to 0$ limit of \tilde{n} in the prescription (5.6).

Bulk vertices also come equipped with a unit time-like vector n_{vertex} for which the on-shell action must be extremized.

Note that the dependence of the on-shell action (5.1) on the vectors n and the points x factorizes, and so the extremizations with respect to the bulk points and the bulk vectors are completely independent. We can then borrow the results from previous sections for the ξ -dependent part of the correlators/blocks, and focus on extremizing the total on-shell action involving the vectors n to obtain the Δ -dependent parts.

We now have all necessary ingredients to compute and extremize the spinning part of the total on-shell action. The total action will be composed of terms that connect the regulated bulk vectors with vertex vectors, and terms that connect vertex vectors with vectors at other vertices. These can be written respectively as

$$\cosh^{-1}(-n_i \cdot n_v)$$
, and $\cosh^{-1}(-n_v \cdot n_{v'})$. (5.7)

The first object will diverge as n_i becomes null in the $\epsilon \to 0$ limit of equation (5.6). The terms in the action which connect these regulated bulk vectors to other bulk vectors have the form

$$\cosh^{-1}(-n_i \cdot n_v) = \log \frac{-2\dot{\gamma}_i \cdot n_v}{\epsilon} + O(\epsilon), \qquad (5.8)$$

independent of the precise choice of m_i used to regulate. This contribution to the action is divergent, but can be regulated by adding a counter-term of the form $S_{ct} = \Delta \log \epsilon$ for each boundary point. In what follows we will directly use this regulated action for such segments.

As we will show in the subsections below, extremizing a total on-shell action composed of these terms gives rise to the Δ -dependent part of BMS₃ correlators and Poincaré blocks in the $1 \ll \Delta \ll \frac{1}{G}$ probe limit.

Before moving on to explicit calculations, it is worth mentioning a particularly useful connection between the total on-shell action at hand and the holographic calculation of correlators and global blocks of CFT₁ primaries.

5.1 Recasting the spinning calculation as holographic blocks in AdS_2/CFT_1

Note that the Δ -dependent part of BMS₃ correlators are identical to those appearing in a CFT₁. In this section we present a connection between the computations involving the extremization of a spinning on-shell action in flat space, and extremal geodesic networks in AdS₂. This implies that the spinning part of BMS₃ correlators can be obtained by borrowing results from conformal field theories in one dimension. As a cautionary remark, it is worth mentioning that the method presented in this section applies only to correlators of primary operators of the BMS₃ algebra. It is not clear whether the same logic can be applied to other correlators obtained in the BMSFT literature, such as correlators involving conserved currents [38].

We start by choosing an illuminating parametrization of a general time-like vector attached to each of the bulk points

$$n = \sec \rho \partial_t + \tan \rho \cos \phi \partial_x + \tan \rho \sin \phi \partial_y. \tag{5.9}$$

Null vectors can also be written in this form. In the limit $\rho \to \pi/2$, the vector in (5.9) becomes null

$$m = \lim_{\cos \rho \to 0} n = \frac{1}{\cos \rho} \left(\partial_t + \cos \phi \partial_x + \sin \phi \partial_y \right). \tag{5.10}$$

This null vector matches the $\epsilon \to 0$ limit of (5.6) if we identify $\cos \rho$ with ϵ , as well as ϕ with ϕ_i^{∂} .

The key point is that vectors of the form (5.9) can be thought as points in the 2+1 dimensional embedding space of global euclidean AdS_2 [39]. Because they are time-like, they correspond to bulk points inside AdS_2 . The null vectors m correspond to points at the boundary. Note that $\cosh^{-1}(-n \cdot n')$ corresponds to the geodesic distance between the AdS_2 points associated with n and n'. We conclude that the total spinning on-shell action we need to extremize corresponds to the length of a network of geodesic segments in euclidean global AdS_2 .

In [24] it was shown that such objects compute holographic correlators and global blocks of primaries in the dual conformal field theory, in the limit of large central charge $c \to \infty$ with scaling dimension $\Delta/c = \epsilon \ll 1$. This limit is also equivalent to first taking the large central charge limit while keeping the scaling dimensions $\Delta \sim \mathcal{O}(1)$, and then sending the scaling dimensions to ∞ [40]. We can then borrow euclidean AdS₂ results to obtain the Δ -dependent part of BMS₃ correlators and global blocks.

The results for low-point correlators and conformal blocks in CFT_1 can be found in [41, 42] in coordinates associated to the boundary of Lorentzian AdS_2 in Poincaré coordinates

$$ds^2 = \frac{dz^2 - dt^2}{z^2} \,, (5.11)$$

where z is the holographic coordinate and the CFT₁ is located at the z=0 boundary. The geodesic networks obtained from our spinning on-shell action correspond to euclidean global AdS₂ with line element

$$ds^{2} = \frac{d\rho^{2} + \sin^{2}\rho d\phi^{2}}{\cos^{2}\rho},$$
 (5.12)

where the boundary is now located at $\rho \to \pi/2$. The topology is that of a disk, whose standard map to the euclidean infinite strip reads

$$\sigma + i\tau = 2\tan^{-1}\tanh\frac{\log\tan\frac{\rho}{2} + i\phi}{2}.$$
 (5.13)

The line element in the new coordinates reads

$$ds^2 = \frac{d\sigma^2 + d\tau^2}{\sin^2 \sigma} \,. \tag{5.14}$$

Under this map, the boundary of the disk with $-\pi/2 < \phi < \pi/2$ is mapped to the line of constant $\sigma = 0$, while the boundary of the disk with $\pi/2 < \phi < 3\pi/2$ is mapped to the line of constant $\sigma = \pi$. Euclidean global AdS₂ is thus equivalent to two copies of a CFT₁ on a line.

The usual state-operator correspondence on a d-dimensional conformal field theory relates the action of local operators in S^d to states in a conformal field theory on $S^{d-1} \times \mathbb{R}$. In the particular case of d=1, the map relates the action of local operators in S^1 (boundary of a disk), to states in $S^0 \times \mathbb{R}$. The manifold S^0 is simply two points, which in our choice of coordinates correspond to the $\sigma=0$ and the $\sigma=\pi$ points. Equation (5.13) at the boundary is nothing but the explicit map between S^1 and $S^0 \times \mathbb{R}$.

The Euclidean strip can be inverse-Wick rotated to Lorentzian signature by sending $\tau=iT$. The lorentzian strip is then covered with Poincaré patches with coordinates

$$z = \frac{\sin \sigma}{\cos T + \cos \sigma}, \quad t = \frac{\sin T}{\cos T + \cos \sigma}, \tag{5.15}$$

which give rise to the line element in equation (5.11). All in all, the map between Poincaré time and the angular disk coordinate at the boundary reads

$$t = -i \tan \frac{\phi}{2}, \quad \text{for} \quad \phi \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right).$$

$$t = -i \cot \frac{\phi}{2}, \quad \text{for} \quad \phi \in \left(\frac{\pi}{2}, \frac{3\pi}{2}\right).$$

$$(5.16)$$

For a picture that summarizes this construction, see figure 4. In the following subsections, we will make use of this map to compute the spinning part of correlators and blocks in a BMSFT.

With this guarantee that our prescription produces the desired results, we turn now to explicit computations of spinning two- and three-point correlators and Poincaré blocks.

5.2 Spinning two-point function

A figure of the set-up involved in this section can be found in figure 5.a). In the case of a two-point function we have two bulk points y_1 and y_2 at the locations $N_1 \cap N_2 \cap \gamma_1$ and $N_1 \cap N_2 \cap \gamma_2$ respectively. At each of these points we have a regulated bulk vector pointing in the radial direction (along the null lines γ_i)

$$\dot{\gamma}_1 = \partial_r|_{y_1} = \partial_t + \cos\phi_1^{\partial}\partial_x + \sin\phi_1^{\partial}\partial_y \,, \quad \dot{\gamma}_2 = \partial_r|_{y_2} = \partial_t + \cos\phi_2^{\partial}\partial_x + \sin\phi_2^{\partial}\partial_y \,. \tag{5.17}$$

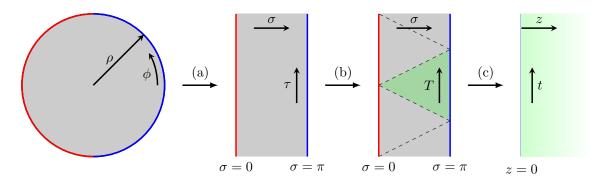


Figure 4. Map from euclidean global AdS₂ (left) to the Poincaré patch (right). a) Transformation from the disk to the strip, implemented by the change of coordinates in equation (5.13). b) Inverse Wick rotation from the euclidean strip to the lorentzian one, implemented by $\tau = iT$. c) Poincaré patching of the lorentzian strip, implemented by formula (5.15).

These two vectors are automatically perpendicular to the path connecting y_1 and y_2 , which lies on $N_1 \cap N_2$. However, these vectors are null, while the action (5.1) concerns time-like vectors. For this reason we introduce the following time-like vectors, as explained above equation (5.6)

$$n_1 = \frac{1}{\epsilon} \dot{\gamma}_1 - \frac{\epsilon}{2} \frac{1}{\dot{\gamma}_1 \cdot \dot{\gamma}_2} \dot{\gamma}_2, \quad n_2 = \frac{1}{\epsilon} \dot{\gamma}_2 - \frac{\epsilon}{2} \frac{1}{\dot{\gamma}_1 \cdot \dot{\gamma}_2} \dot{\gamma}_1, \tag{5.18}$$

which become null and proportional to (5.17) in the $\epsilon \to 0$ limit. The spinning part of the on-shell action is then

$$S_{\text{total}}^{\text{spin, regulated}} = \Delta \lim_{\epsilon \to 0} \left[\cosh^{-1}(-n_1 \cdot n_2) + 2\Delta \log \epsilon \right] = 2\Delta \log (\dot{\gamma}_1 \cdot \dot{\gamma}_2) = 2\Delta \log 2 \sin \frac{\phi_2^{\partial} - \phi_1^{\partial}}{2}.$$
(5.19)

The contribution to the correlator is then

$$e^{-S_{\text{total}}^{\text{spin, reg.}}} = \left(2\sin\frac{\phi_2^{\partial} - \phi_1^{\partial}}{2}\right)^{-2\Delta},\tag{5.20}$$

which combined with the ξ -dependent part computed in section 3.1 gives rise to the correct result as written in equation (1.20).

As we have explained in previous subsections, we could have obtained this same answer by borrowing results from computations in a CFT_1 . The two point function of primary operators reads

$$\langle \Phi_{\Delta}(t_1)\Phi_{\Delta}(t_2)\rangle \sim \frac{1}{(t_2 - t_1)^{2\Delta}}.$$
 (5.21)

Performing the change of coordinates of equation (5.16) yields

$$\langle \Phi_{\Delta}(\phi_1^{\partial}) \Phi_{\Delta}(\phi_2^{\partial}) \rangle \sim \left(\frac{\partial \tan \frac{\phi_1}{2}}{\partial \phi_1} \right)^{\Delta} \left(\frac{\partial \tan \frac{\phi_2}{2}}{\partial \phi_2} \right)^{\Delta} \frac{1}{\left(\tan \frac{\phi_2}{2} - \tan \frac{\phi_1}{2} \right)^{2\Delta}} = \left(\frac{1}{2 \sin \frac{\phi_{21}^{\partial}}{2}} \right)^{2\Delta}, \tag{5.22}$$

which matches the result we have obtained by extremizing the spinning on-shell action.

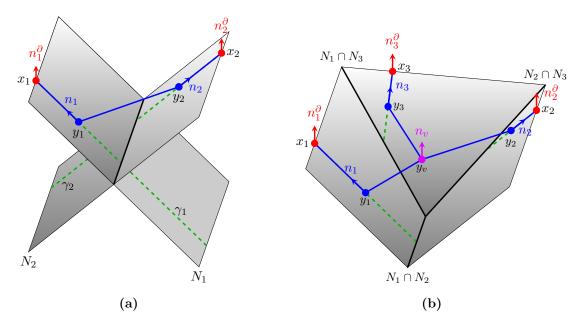


Figure 5. a) Set-up for the calculation of the holographic spinning two-point function. The red points are located at the null boundary at $x_{i=1,2}$, equipped with boundary vectors $n_i^{\partial} = \partial_u$. The regulated blue points are located at γ_i , and they are equipped with blue vectors $n_i = \partial_r|_{y_i}$. The spinning particle propagates between the blue points, along the green straight line connecting γ_1 and γ_2 . b) Set-up for the calculation of the holographic spinning three-point function. There are three boundary points drawn in red, and their regulated bulk versions are drawn in blue. At each blue point we have a blue vector $n_{i=1,2,3} = \partial_r|_{y_i}$ pointing along the null geodesics γ_i . The spining particles meet at a common purple point y_v , where we have a purple time-like vector n_v for which the spinning total on-shell action must be extremized.

5.3 Spinning three-point function

The geometrical set-up studied in this section is presented in figure 5.b). We start with three regulated bulk points y_i along the γ_i associated to each boundary point connected to a bulk vertex at y_v . The action to be extremised is:

$$S_{\text{total}}^{\text{spin, regulated}} = \sum_{i=1}^{3} \Delta_i \log \left(-2\dot{\gamma}_i \cdot n_v \right). \tag{5.23}$$

The problem can be solved in two ways. First, we will solve the extremization problem explicitly. Then, we will obtain the same result by borrowing the result for the analytically continued euclidean CFT_1 three-point function of primaries.

A useful way of parametrizing the vector n_v is the following. In global threedimensional Minkowski coordinates we have

$$n_v = \frac{x^2 + u^2 + 1}{2u} \partial_t + \frac{x^2 + u^2 - 1}{2u} \partial_x + \frac{x}{u} \partial_y, \qquad (5.24)$$

where x and u are free parameters and the form (5.24) ensures $n_v \cdot n_v = -1$. The interpretation of x, u is simply the Poincaré coordinates of euclidean AdS₂. The action now reads

$$S_{\text{total}}^{\text{spin}} = \sum_{i=1}^{3} \left[\Delta_i \log \frac{1}{\epsilon} + \Delta_i \log \left(\frac{u^2 + x^2 + 1}{u} - \frac{u^2 + x^2 - 1}{u} \cos \phi_i^{\partial} - \frac{2x}{u} \sin \phi_i^{\partial} \right) \right]. \tag{5.25}$$

We proceed by changing variables as

$$\frac{u^2 + x^2 + 1}{u} - \frac{u^2 + x^2 - 1}{u} \cos \phi_i^{\partial} - \frac{2x}{u} \sin \phi_i^{\partial} = l_i, \quad \text{for} \quad i = 1, 2, 3,$$
 (5.26)

which can be thought as a system of equations for the variables u, x, and l_3 . The on-shell action as a function of l_1 and l_2 reads

$$S_{\text{total}}^{\text{spin}} = \sum_{i=1}^{3} \Delta_{i} \log \frac{1}{\epsilon} + \Delta_{1} \log l_{1} + \Delta_{2} \log l_{2} + \Delta_{3} \log \left(l_{1} \frac{\sin^{2} \frac{\phi_{32}^{\partial}}{2}}{\sin^{2} \frac{\phi_{21}^{\partial}}{2}} + l_{2} \frac{\sin^{2} \frac{\phi_{31}^{\partial}}{2}}{\sin^{2} \frac{\phi_{21}^{\partial}}{2}} - 4 \sin \frac{\phi_{31}^{\partial}}{2} \sin \frac{\phi_{32}^{\partial}}{2} \sqrt{l_{1} l_{2} - 4 \sin^{2} \frac{\phi_{21}^{\partial}}{2}} \right).$$
(5.27)

This can now be organized further by replacing

$$l_1 = c_1 \frac{\sin\frac{\phi_{21}^{\partial}}{2}\sin\frac{\phi_{31}^{\partial}}{2}}{\sin\frac{\phi_{32}^{\partial}}{2}}, \quad l_2 = c_2 \frac{\sin\frac{\phi_{21}^{\partial}}{2}\sin\frac{\phi_{32}^{\partial}}{2}}{\sin\frac{\phi_{31}^{\partial}}{2}}, \quad (5.28)$$

which implies

$$S_{\text{total}}^{\text{spin}} = \sum_{i=1}^{3} \Delta_{i} \log \frac{1}{\epsilon} + \Delta_{1} \log \frac{\sin \frac{\phi_{21}^{\partial}}{2} \sin \frac{\phi_{31}^{\partial}}{2}}{\sin \frac{\phi_{32}^{\partial}}{2}} + \Delta_{2} \log \frac{\sin \frac{\phi_{21}^{\partial}}{2} \sin \frac{\phi_{32}^{\partial}}{2}}{\sin \frac{\phi_{31}^{\partial}}{2}} + \Delta_{3} \log \frac{\sin \frac{\phi_{31}^{\partial}}{2} \sin \frac{\phi_{32}^{\partial}}{2}}{\sin \frac{\phi_{21}^{\partial}}{2}} + \Delta_{3} \log \frac{\sin \frac{\phi_{31}^{\partial}}{2} \sin \frac{\phi_{32}^{\partial}}{2}}{\sin \frac{\phi_{21}^{\partial}}{2}} + \Delta_{4} \log c_{1} + \Delta_{2} \log c_{2} + \Delta_{3} \log \left(c_{1} + c_{2} - 2\sqrt{c_{1}c_{2} - 4}\right).$$

$$(5.29)$$

Extremizing now implies solving for $\partial S_{\text{total}}^{\text{spin}}/\partial c_1 = \partial S_{\text{total}}^{\text{spin}}/\partial c_2 = 0$. The solution only contributes to an overall constant in the on-shell action, and it reads

$$\frac{c_1}{\sqrt{c_1c_2 - 4}} = 2\frac{\Delta_1}{\Delta_{132}}, \quad \frac{c_2}{\sqrt{c_1c_2 - 4}} = 2\frac{\Delta_2}{\Delta_{231}}.$$
 (5.30)

The spinning part of the three-point function thus reads

$$e^{-S_{\text{total}}^{\text{spin}}} = C \prod_{k} \left(\sin \frac{\phi_i^{\partial} - \phi_j^{\partial}}{2} \right)^{-\Delta_{ijk}}, \tag{5.31}$$

where C is a constant that depends on ϵ and Δ_i . As can be seen easily, this matches the Δ -dependent part of the BMS₃ three-point function written in (1.20).

A much quicker way to solve the problem is to study the CFT₁ three-point function of primary operators. On the line, these read

$$\langle \Phi_{\Delta_1}(t_1)\Phi_{\Delta_2}(t_2)\Phi_{\Delta_3}(t_3)\rangle_{\text{CFT}_1} \sim \prod_k (t_{ij})^{-\Delta_{ijk}} .$$
 (5.32)

Performing the change of coordinates from Poincaré time to S^1 of equation (5.16) results in

$$\langle \Phi_{\Delta_1} \left(\phi_1^{\partial} \right) \Phi_{\Delta_2} \left(\phi_2^{\partial} \right) \Phi_{\Delta_3} \left(\phi_3^{\partial} \right) \rangle_{\text{CFT}_1} \sim \prod_k \left(\sin \frac{\phi_i^{\partial} - \phi_j^{\partial}}{2} \right)^{-\Delta_{ijk}}$$
 (5.33)

which of course agrees with the previously obtained result (5.31).

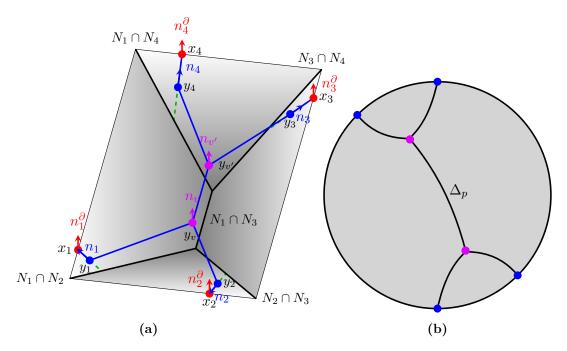


Figure 6. a) Set-up for the calculation of the holographic spinning block. The red points are located at the null boundary at $x_{i=1,2,3,4}$, equipped with boundary vectors $n_i^{\partial} = \partial_u$. The regulated blue points are located at γ_i , and they are equipped with blue vectors $n_i = \partial_r|_{y_i}$. The spinning particles propagate from the blue bulk points to the purple vertex points and also between the two vertex points. At each vertex we have a general time-like vector n_v and $n_{v'}$. The total spinning on-shell action is extremized with respect to the components of these vectors. b) Alternative way to compute the spinning part of a Poincaré block. It is equivalent to the worldline method for computing global conformal blocks in euclidean global AdS₂.

5.4 Spinning Poincaré blocks

The set-up for the computation of the spinning Poincaré block can be found in figure 6.a). We consider external spins Δ and internal exchanged spin Δ_p . We start with four regulated bulk points y_i . These must be connected to two vertices restricted to lie along $N_1 \cap N_2$ and $N_3 \cap N_4$ respectively, equipped with time-like vectors n_v and $n_{v'}$. The total on-shell action we need to extremize reads

$$S_{\text{total}}^{\text{spin}} = -4\Delta \log \epsilon + \Delta \left[\sum_{i=1}^{2} \log \left(-2\dot{\gamma}_{i} \cdot n_{v} \right) + \sum_{i=3}^{4} \log \left(-2\dot{\gamma}_{i} \cdot n_{v'} \right) \right] + \Delta_{p} \cosh^{-1} \left(-n_{v} \cdot n_{v'} \right). \tag{5.34}$$

Extremizing this object for general boundary angular locations ϕ_i^{∂} is very cumbersome, so we will use BMS transformations to move the operators to the points

$$\phi_{1,2}^{\partial} = \mp \Phi/2$$
, and $\phi_{3,4}^{\partial} = \pi \mp \Phi/2$. (5.35)

The cross-ratio η is then parametrised by Φ as

$$\eta = \frac{\sin\frac{\phi_{12}^{0}}{2}\sin\frac{\phi_{34}^{0}}{2}}{\sin\frac{\phi_{13}^{0}}{2}\sin\frac{\phi_{24}^{0}}{2}} = \sin^{2}\frac{\Phi}{2}.$$
 (5.36)

We can now write the bulk vertex vectors in the form (5.24). Namely,

$$n_{v} = \frac{x^{2} + u^{2} + 1}{2u} \partial_{t} + \frac{x^{2} + u^{2} - 1}{2u} \partial_{x} + \frac{x}{u} \partial_{y},$$

$$n_{v'} = \frac{x'^{2} + u'^{2} + 1}{2u'} \partial_{t} + \frac{x'^{2} + u'^{2} - 1}{2u'} \partial_{x} + \frac{x'}{u'} \partial_{y},$$
(5.37)

where u, x and u', x' are the variables with respect to which the action (5.34) must be extremal, and as before, they correspond to euclidean AdS_2 bulk points in Poincaré coordinates. Before continuing it is useful to exploit the symmetry of the problem. Due to the choice of angular locations of the primary operators, we expect the lengths of the external geodesics to be equal. We can then solve the following system of equations which changes variables from (u, x, u', x') to a single variable L

$$-n_{i} \cdot n_{v} = L \sin \frac{\Phi}{2}$$
 for $i = 1, 2,$
 $-n_{i} \cdot n_{v'} = L \sin \frac{\Phi}{2}$ for $i = 3, 4.$ (5.38)

The solution to (5.38) can be used to write the length between the points parametrised by n_v^{bulk} and $n_{v'}^{\text{bulk}}$ as a function of L exclusively. We thus have a total on-shell action that reads

$$\begin{split} S_{\text{total}}^{\text{spin}} &= \Delta \sum_{i=1}^{4} \log \frac{L \sin \frac{\Phi}{2}}{\epsilon} + 2\Delta_{p} \log \left(\cot \frac{\Phi}{2} \frac{L \pm \sqrt{L^{2} - 4}}{2} \right), \\ &= 2\Delta \log \frac{\eta}{\epsilon} + 2\Delta_{p} \log \left(\frac{1 + \sqrt{1 - \eta}}{\sqrt{\eta}} \right) + 4\Delta \log L + 2\Delta_{p} \log \left(L + \sqrt{L^{2} - 4} \right). \end{split}$$
(5.39)

Extremizing with respect to L gives rise to

$$L = \frac{4\Delta}{\sqrt{4\Delta^2 - \Delta_p^2}},\tag{5.40}$$

which only contributes to the result by an overall constant that we will ignore. The final result for the Δ -dependent part of the block reads

$$e^{-S_{\text{total}}^{\text{spin}}} = C\eta^{\Delta_p - 2\Delta} \left(1 + \sqrt{1 - \eta} \right)^{-2\Delta_p}. \tag{5.41}$$

This matches the large Δ , Δ_p limit of equations (1.23) and (1.21). Note that this result is missing the terms in (1.23) that are subleading in a large Δ , Δ_p limit. This is an expected feature of the geodesic network method for computing blocks.

We could have also obtained the same exact result by borrowing results for conformal blocks in CFT₁ [42]. For equal external operator dimensions Δ and exchanged dimension Δ_p , the CFT₁ conformal block decomposition of a four-point function in Poincaré time reads

$$\langle \Phi_{\Delta} \Phi_{\Delta} \Phi_{\Delta} \Phi_{\Delta} \rangle_{\text{CFT}_1} = \frac{1}{(t_{12}t_{34})^{2\Delta}} \sum_{p} C_{12p} C_{34p} t^{\Delta_p} {}_2 F_1 \left(\Delta_p, \Delta_p; 2\Delta_p; t \right) , \qquad (5.42)$$

with time-like cross ratio

$$t = \frac{t_{12}t_{34}}{t_{13}t_{24}}. (5.43)$$

The map to the boundary of euclidean global AdS_2 is written in equation (5.16), and it yields

$$\langle \Phi_{\Delta} \Phi_{\Delta} \Phi_{\Delta} \Phi_{\Delta} \rangle_{\text{CFT}_{1}} = \frac{1}{\left(\sin \frac{\phi_{12}^{\partial}}{2}\right)^{2\Delta} \left(\sin \frac{\phi_{34}^{\partial}}{2}\right)^{2\Delta}} \sum_{p} C_{12p} C_{34p} \eta^{\Delta_{p}} {}_{2} F_{1} \left(\Delta_{p}, \Delta_{p}; 2\Delta_{p}; \eta\right) ,$$

$$(5.44)$$

with

$$\eta = \frac{\sin\frac{\phi_{12}^{\theta}}{2}\sin\frac{\phi_{34}^{\theta}}{2}}{\sin\frac{\phi_{13}^{\theta}}{2}\sin\frac{\phi_{24}^{\theta}}{2}}.$$
 (5.45)

We must now send $\Delta, \Delta_p \to \infty$. The prefactors multiplying the hypergeometric functions remain unchanged. For the limit of the hypergeometric function we will use the following identity

$$_{2}F_{1}(a,b;c;\eta) = \frac{1}{B(b,c-b)} \int_{0}^{1} dt \, t^{b-1} (1-t)^{c-b-1} (1-\eta t)^{-a},$$
 (5.46)

where the beta function also has an integral expression

$$B(b,c-b) = \int_0^1 dt \, t^{b-1} (1-t)^{c-b-1} \,. \tag{5.47}$$

We start with the integral in equation (5.46).

$$\mathcal{I} = \int_0^1 dt \, t^{b-1} (1-t)^{c-b-1} (1-\eta t)^{-a} = \int_0^1 dt \, e^{\Delta_p \mathcal{S}(t)} \frac{1}{t(1-t)},$$

$$\mathcal{S}(t) = \log t + \log(1-t) - \log(1-\eta t).$$
(5.48)

We can evaluate this object in a large Δ_p limit using the method of saddle-point approximation. We need to find the critical points of $\mathcal{S}(t)$ by solving $\partial_t \mathcal{S}(t) = 0$. There is a unique critical point in the interval $t \in [0, 1]$. It reads

$$t_{\star} = \frac{1 - \sqrt{1 - \eta}}{\eta} \,. \tag{5.49}$$

We thus have

$$\mathcal{I} \to \sqrt{\frac{2\pi}{-\Delta_p \partial_t^2 \mathcal{S}(t_\star)}} e^{\Delta_p \mathcal{S}(t_\star)} \frac{1}{t_\star (1 - t_\star)}.$$
 (5.50)

The integral appearing in the beta function follows a similar logic.

$$\mathcal{I}' = \int_0^1 dt \, t^{b-1} (1-t)^{c-b-1} = \int_0^1 dt \, e^{\Delta_p \mathcal{S}'(t)} \frac{1}{t(1-t)},$$

$$\mathcal{S}'(t) = \log t + \log(1-t).$$
(5.51)

Solving for $\partial_t \mathcal{S}'(t) = 0$ results in a unique critical point at

$$t'_{\star} = \frac{1}{2} \,. \tag{5.52}$$

We conclude

$$\mathcal{I}' \to \sqrt{\frac{2\pi}{-\Delta_p \partial_t^2 \mathcal{S}'(t_\star')}} e^{\Delta_p \mathcal{S}'(t_\star')} \frac{1}{t_\star'(1 - t_\star')}, \qquad (5.53)$$

which implies, after some simple algebra

$$_{2}F_{1}\left(\Delta_{p},\Delta_{p};2\Delta_{p};\eta\right) \to 2^{2\Delta_{p}-1}(1-\eta)^{-\frac{1}{4}}\left(1+\sqrt{1-\eta}\right)^{1-2\Delta_{p}}.$$
 (5.54)

Replacing this result in (5.44) we obtain

$$\langle \Phi_{\Delta} \Phi_{\Delta} \Phi_{\Delta} \Phi_{\Delta} \rangle_{\text{CFT}_1} = \frac{1}{\left(\sin \frac{\phi_{12}^{\partial}}{2}\right)^{2\Delta} \left(\sin \frac{\phi_{34}^{\partial}}{2}\right)^{2\Delta}} \sum_{p} C_{12p} C_{34p} 2^{2\Delta_p} \eta^{\Delta_p} \left(1 + \sqrt{1 - \eta}\right)^{-2\Delta_p},$$

$$(5.55)$$

where we have ignored the subleading factors. The answer matches the result (5.41) obtained from extremizing the spinning on-shell action. It also agrees with the large Δ , Δ_p limit of equations (1.21) and (1.23), which were obtained in the BMSFT in [27].

Note that the factors obtained in this section that are subleading in the large ξ , Δ limit do not match the correct result as presented in equation (1.23). This is an expected feature of the worldline method, which applies exclussively in the probe limit. In order to obtain the full answer we need to build a full extrapolate dictionary and use it to make a proposal for the holographic computation of the block in the light regime.

6 A proposal for the extrapolate dictionary

Given the results presented in this note, it is natural to ask whether the construction we have proposed above can be understood as the probe limit of a full extrapolate dictionary. In this section, we propose such a dictionary and use it to match the above results in a WKB approximation. By computing corrections to this approximation, we will be able to match the finite dimension form of BMS₃ correlation functions and blocks.

The prescription presented throughout this work consists of attaching a geodesic network to a set of null lines falling from the boundary from the locations of the boundary insertions. Given a point x at the boundary, we thus associate a unique null line γ_x . The geodesics that constitute the network correspond to the saddle points of flat space propagators. The proposed extrapolate dictionary is then to attach a position space Feynman diagram to the null lines and integrate the position of the legs over an affine parameter along γ_x .

$$\langle \mathcal{O}_1(x_1)\mathcal{O}_2(x_2)\ldots\rangle \sim \int_{\gamma_{x_1}} d\lambda_1 \int_{\gamma_{x_2}} d\lambda_2 \ldots \langle \Psi_1(\lambda_1)\Psi_2(\lambda_2)\ldots\rangle.$$
 (6.1)

Here, λ_i is the affine parameter along the null geodesic γ_{x_i} and Ψ_i is the bulk field dual to the operator \mathcal{O}_i . The symbol \sim is used because both sides can be rescaled by arbitrary constant factors as both the normalisation of the operators and the measure of an affine parametrisation can be rescaled. We might have used a different measure when integrating the bulk operators along the null geodesics, but we will find that this choice reproduces the correct BMS₃ correlation functions.

Equation (6.1) is the main conjecture presented in this work. The dictionary presented here is qualitatively different from the one in AdS/CFT. The first version of the AdS/CFT duality was presented as an equivalence of partition functions between a theory of gravity in the bulk and a conformal field theory on its boundary. The boundary conditions of the bulk fields $\Phi(x)$ correspond to operator deformations of the CFT lagrangian. An equivalent formulation of this dictionary consists on pulling bulk correlators to the boundary. These correlators typically vanish, but the leading behavior can be extracted by stripping off a decaying factor

$$\langle O_{\text{CFT}}(x_1) \dots O_{\text{CFT}}(x_n) \rangle = \lim_{z \to 0} z^{-n\Delta} \langle \Phi(x_1, z) \dots \Phi(x_n, z) \rangle_{\text{bulk}}.$$
 (6.2)

The dictionary spelled out in (6.2) cannot apply to flat holography. The reason is that massive scalar bulk solutions in flat space are not well behaved at null infinity. Massive propagators either exponentially decay or fluctuate with divergent frequencies depending on whether the bulk point and the point at null infinity are space-like or time-like separated. This leads to the conclusion that null infinity cannot act as an initial-value surface for massive scalar fields. It is clear then than a modification of the dictionary (6.2) is required in flat holography. The proposal (6.1) projects Minkowski fields to null infinity along null lines in such a way that the resulting correlator is well behaved and matches the results for BMS₃ correlators in the BMSFT literature.

The objective of this section is to test formula (6.1) for the case of propagating massive scalar fields in Minkowski space-time. We expect to compute the exact form of correlators involving boundary operators with mass $m = \xi$ and spin $\Delta = 1$, as explained in section 1.1.

6.1 Two-point function

The easiest correlation on which formula (6.1) can be tested is the two point function. The object to compute reads

$$\langle \mathcal{O}(x_1)\mathcal{O}(x_2)\rangle \sim \int_{\gamma_{x_1}} d\lambda_1 \int_{\gamma_{x_2}} d\lambda_2 \langle \Psi(\lambda_1)\Psi(\lambda_2)\rangle,$$
 (6.3)

where the integrand is simply the bulk to bulk Feynman propagator for the field dual to \mathcal{O} . For the case of a scalar field, it is useful to write this object in momentum space form

$$\langle \Psi(\lambda_1)\Psi(\lambda_2)\rangle = G_F(\lambda_1, \lambda_2) = \int d^3p \frac{e^{ip_\mu(x^\mu_{\gamma_1} - x^\mu_{\gamma_2})}}{p_\mu p^\mu + \xi^2 - i\epsilon}, \tag{6.4}$$

where $x_{\gamma_i}^{\mu}$ are the locations of the null lines

$$x_{\gamma_i}^0 = u_i + \lambda_i, \quad x_{\gamma_i}^1 = \lambda_i \cos \phi_i^{\partial}, \quad \text{and} \quad x_{\gamma_i}^2 = \lambda_i \sin \phi_i^{\partial},$$
 (6.5)

and the components of the three-momentum are dubbed as $p^{\mu} = \{w, p^x, p^y\}$.

The calculation of the correlator can be started by performing the integrals over the affine parameters λ_i . The relevant integrals read

$$\int d\lambda_i e^{i\lambda_i \left(-w + p^x \cos\phi_i^{\partial} + p^y \sin\phi_i^{\partial}\right)} = 2\pi\delta \left(-w + p^x \cos\phi_i^{\partial} + p^y \sin\phi_i^{\partial}\right). \tag{6.6}$$

We can thus inmediately integrate the momenta p^x and p^y , which in virtue of the delta functions are forced to correspond to the following expressions

$$p^{x} = w \frac{\sin \phi_{1}^{\partial} - \sin \phi_{2}^{\partial}}{\sin \phi_{12}^{\partial}}, \quad p^{y} = -w \frac{\cos \phi_{1}^{\partial} - \cos \phi_{2}^{\partial}}{\sin \phi_{12}^{\partial}}. \tag{6.7}$$

The remaining integral over w is

$$\langle \mathcal{O}_1(x_1)\mathcal{O}_2(x_2)\rangle \sim \frac{1}{\sin\phi_{12}^{\partial}} \int dw \frac{e^{-iwu_{12}}}{w^2 \tan^2\frac{\phi_{12}^{\partial}}{2} + \xi^2 - i\epsilon}.$$
 (6.8)

A simple Fourier transform yields the right result

$$\langle \mathcal{O}_1(x_1)\mathcal{O}_2(x_2)\rangle \sim \frac{1}{\sin^2\frac{\phi_{12}^0}{2}} e^{\frac{\xi \frac{u_{12}}{\phi_{12}^0}}{\tan\frac{\phi_{12}^0}{2}}}.$$
 (6.9)

The calculation done in this section arives to the same result obtained in previous sections using the probe limit. However, the method used here does not rely on a large mass limit. This will be more obvious when studying Poincaré blocks, as the probe limit does not capture the exact result for the block. Before we study these issues, we turn our attention to the next more complicated correlator; the three-point function.

6.2 Three-point function

The calculation of the three-point correlator is morally simmilar to the computation of the two-point function, albeit the addition of a bulk vertex where the propagators interact through a coupling of the form Ψ^3 . The computation we propose is to attach a tree level Feynman diagram to the null geodesics following from the boundary. We thus have

$$\langle \mathcal{O}_1(x_1)\mathcal{O}_2(x_2)\mathcal{O}_3(x_3)\rangle \sim \int_{\gamma_{x_1}} d\lambda_1 \int_{\gamma_{x_2}} d\lambda_2 \int_{\gamma_{x_3}} d\lambda_3 \langle \Psi_1(\lambda_1)\Psi_2(\lambda_2)\Psi_3(\lambda_3)\rangle,$$
 (6.10)

where the bulk correlator reads

$$\langle \Psi_1(\lambda_1)\Psi_2(\lambda_2)\Psi_3(\lambda_3)\rangle \sim \int d^3y_v \prod_{i=1}^3 \int d^3p_i \frac{e^{ip_{i,\mu}(x_{\gamma_i}^{\mu} - y_v^{\mu})}}{p_{i,\mu}p_i^{\mu} + \xi_i^2 - i\epsilon}$$
 (6.11)

The Feynman propagators connect points in the null geodesics γ_i with a common bulk vertex at y_v , which must be integrated over all of Minkowski space-time in order to obtain a gauge invariant answer. As we did in the previous subsection, we start by integrating over the null geodesics. Again the relevant integrals are the ones in equation (6.10). The delta functions can be used to integrate the variables $p_i^0 = w_i$, which are constrained to the values

$$w_i = p_i^x \cos \phi_i^{\partial} + p_i^y \sin \phi_i^{\partial}. \tag{6.12}$$

After performing the integrals over w_i , it is useful to change variables as follows

$$\tilde{p}_i = p_i^x \sin \phi_i^{\partial} - p_i^y \cos \phi_i^{\partial}. \tag{6.13}$$

The correlator then reads

$$\langle \Psi_1(\lambda_1)\Psi_2(\lambda_2)\Psi_3(\lambda_3)\rangle \sim \int d^3y_v \prod_i \int d\tilde{p}_i \frac{e^{-i\tilde{p}_i \frac{x_v + (u_i - t_v)\cos\phi_i^{\partial}}{\sin\phi_i^{\partial}}}}{\tilde{p}_i^2 + \xi_i^2 - i\epsilon} \int dp_i^y \frac{e^{-ip_i^y \frac{u_i - t_v + r_v\cos(\phi_v - \phi_i^{\partial})}{\sin\phi_i^{\partial}}}}{\sin\phi_i^{\partial}}$$

$$(6.14)$$

The integrals over p_i^y are delta functions that completely fix the vertex point y_v . The expression for the resulting coordinate location of the vertex is precisely the expression (3.7), which was found in previous sections studying geodesic networks as the probe limit of (6.1). The remaining integrals over \tilde{p}_i are simple Fourier transforms. The final result reads

$$\langle \Psi_1(\lambda_1)\Psi_2(\lambda_2)\Psi_3(\lambda_3)\rangle \sim \prod_k e^{\xi_k \frac{\sum_{i < j}(-1)^{1+i+j}(u_i^{\partial} - u_j^{\partial})\cos(\phi_k^{\partial} - \phi_i^{\partial})}{\sum_{i < j}(-1)^{1+i+j}\sin(\phi_i^{\partial} - \phi_j^{\partial})}} \left(\sin \frac{\phi_i^{\partial} - \phi_j^{\partial}}{2}\right)^{-2}, \quad (6.15)$$

which matches (1.20) upon replacing $\Delta_i = 1$. Much like the case of the two point function, the result here matches the result obtained from studying geodesic networks.

6.3 Poincaré Blocks — geodesic Feynman diagrams

We now explore holographic Poincaré blocks following the extrapolate dictionary proposed in this section. The new feature of this calculation is the fact that the four-point correlator $\langle \Psi_1(\lambda_1)\Psi_2(\lambda_2)\Psi_3(\lambda_3)\Psi_4(\lambda_4)\rangle$ is not fixed by Lorentz invariance. We could think of attaching any tree level Feynman diagram to the null lines γ_i to compute gauge invariant objects. The work in [24, 40] showed that, in the context of the AdS/CFT correspondence, holographic conformal blocks are computed with geodesic Witten diagrams (GWD). These objects are defined as exchange Witten diagrams where the internal vertices are not integrated over the whole bulk manifold, but only over the geodesics connecting pairs of boundary operators. Inspired by the AdS picture, we now construct a geodesic Feynman diagram (GFD) by integrating the vertices of an exchange Feynman diagram over the geodesics $\gamma_{12} = N_1 \cap N_2$ and $\gamma_{34} = N_3 \cap N_4$. As we have seen above, these geodesics are the paths of extremal length connecting the points at the null boundary. We parametrise these geodesics in terms of their arc-length as follows

$$t_{\gamma_{12}} = s \cot \frac{\phi_{21}^{\partial}}{2},$$

$$x_{\gamma_{12}} = -s \frac{\cos \phi_{2}^{\partial} + \cos \phi_{1}^{\partial}}{\sin \phi_{21}^{\partial}} + \frac{u_{2}^{\partial} \sin \phi_{1}^{\partial} - u_{1}^{\partial} \sin \phi_{2}^{\partial}}{\sin \phi_{21}^{\partial}},$$

$$y_{\gamma_{12}} = -s \frac{\sin \phi_{2}^{\partial} + \sin \phi_{1}^{\partial}}{\sin \phi_{21}^{\partial}} + \frac{u_{1}^{\partial} \cos \phi_{2}^{\partial} - u_{2}^{\partial} \cos \phi_{1}^{\partial}}{\sin \phi_{21}^{\partial}},$$
(6.16)

and simmilarly for γ_{34} . The holographic block as a GFD attached to the null geodesics thus reads

$$\langle \mathcal{O}_{1}(x_{1})\mathcal{O}_{2}(x_{2})\mathcal{O}_{3}(x_{3})\mathcal{O}_{4}(x_{4})\rangle \sim \int_{\gamma_{12}} ds \int_{\gamma_{34}} ds' \left(\prod_{i} \int_{\gamma_{x_{i}}} d\lambda_{i}\right)$$

$$G_{F}^{\xi}(\lambda_{1}, \sigma)G_{F}^{\xi}(\lambda_{2}, \sigma)G_{F}^{\xi_{p}}\left(\sigma, \sigma'\right)G_{F}^{\xi}\left(\lambda_{3}, \sigma'\right)G_{F}^{\xi}\left(\lambda_{4}, \sigma'\right),$$
(6.17)

where G_F^m stand for Feynman propagators of spinless fields of mass m. For simplicity, we will choose the operators at the null boundary to be placed at

$$\phi_1^{\partial} = -\frac{\Phi}{2}, \qquad \phi_2^{\partial} = \frac{\Phi}{2}, \qquad \phi_3^{\partial} = \pi - \frac{\Phi}{2}, \qquad \phi_4^{\partial} = \pi + \frac{\Phi}{2},
u_1^{\partial} = -\frac{T}{2}, \qquad u_2^{\partial} = \frac{T}{2}, \qquad u_3^{\partial} = -\frac{T}{2}, \qquad u_4^{\partial} = \frac{T}{2}.$$
(6.18)

This leads to the cross ratios

$$x = \sin^2 \frac{\Phi}{2}, \quad t = T \sin \frac{\Phi}{2} \cos \frac{\Phi}{2}. \tag{6.19}$$

The calculation of (6.17) can be done by writing the Feynman propagators in momentum space form. For the external propagators, we use the notation $p_i^{\mu} = (w_i, p_i^x, p_i^y)$, while for the internal propagator we use $p_p^{\mu} = (w_p, p_p^x, p_p^y)$. The integrals over λ_i can then be done inmediately, resulting on delta functions of the form (6.6). The resulting expression can then be simplified by changing variables as in equation (6.13). The integral over the arc-length s then reads

$$\int_{\gamma_{12}} ds e^{-is\left(\tilde{p}_1 - \tilde{p}_2 - w_p \cot\frac{\Phi}{2} + p_p^x \csc\frac{\Phi}{2}\right)} = 2\pi\delta\left(\tilde{p}_1 - \tilde{p}_2 - w_p \cot\frac{\Phi}{2} + p_p^x \csc\frac{\Phi}{2}\right), \quad (6.20)$$

and similarly for the integral over s'. These delta functions fix w_p and p_p^x as a function of \tilde{p}_i . We are left with integrals over p_p^y , p_i^y , and \tilde{p}_i . The resulting integrand however does not depend on p_i^y , so the corresponding integrals contribute to an overall infinity. The remaining calculation reads

$$\langle \mathcal{O}_1(x_1)\mathcal{O}_2(x_2)\mathcal{O}_3(x_3)\mathcal{O}_4(x_4)\rangle \sim \frac{\cos\frac{\Phi}{2}}{\sin^2\Phi} \left(\prod_i \int d\tilde{p}_i \frac{e^{-i\tilde{p}_i \frac{T}{2}\cot\frac{\Phi}{2}}}{\tilde{p}_i^2 + \xi^2 - i\epsilon} \right) \int dp_p^y \frac{e^{-ip_p^y \frac{T}{\sin\frac{\Phi}{2}}}}{A(p_p^y, \tilde{p}_i)},$$

$$\tag{6.21}$$

with

$$A\left(p_{p}^{y}, \tilde{p}_{i}\right) = \left(p_{p}^{y}\right)^{2} + \xi_{p}^{2} + \frac{\sin^{2}\frac{\Phi}{2}}{4}\left(\tilde{p}_{1} - \tilde{p}_{2} + \tilde{p}_{3} - \tilde{p}_{4}\right)^{2} - \frac{\tan^{2}\frac{\Phi}{2}}{4}\left(\tilde{p}_{1} - \tilde{p}_{2} - \tilde{p}_{3} + \tilde{p}_{4}\right)^{2}.$$
(6.22)

We now proceed by using a Schwinger identity for the denominator in the p_p^y integral of (6.21).

$$\frac{1}{A\left(p_{p}^{y}, \tilde{p}_{i}\right)} = \int_{0}^{\infty} d\nu e^{-\nu A\left(p_{p}^{y}, \tilde{p}_{i}\right)}.$$
(6.23)

The resulting expression is easy to integrate with respect to the variables \tilde{p}_i using the residue theorem. Namely, due to the choice of Feynman contour, only the residues $\tilde{p}_i = +i\xi$ contribute to the final result. Computing the residues yields

$$\langle \mathcal{O}_{1}(x_{1})\mathcal{O}_{2}(x_{2})\mathcal{O}_{3}(x_{3})\mathcal{O}_{4}(x_{4})\rangle \sim \frac{\cos\frac{\Phi}{2}}{\sin^{2}\Phi}e^{2\xi T\cot\frac{\Phi}{2}}\int_{0}^{\infty}d\nu\int dp_{p}^{y}e^{-\nu\left(\left(p_{p}^{y}\right)^{2}+\xi_{p}^{2}\right)}e^{-ip_{p}^{y}\frac{T}{\sin\frac{\Phi}{2}}}.$$
(6.24)

The integral over the Schwinger parameter now yields

$$\langle \mathcal{O}_1(x_1)\mathcal{O}_2(x_2)\mathcal{O}_3(x_3)\mathcal{O}_4(x_4)\rangle \sim \frac{\cos\frac{\Phi}{2}}{\sin^2\Phi}e^{2\xi T\cot\frac{\Phi}{2}}\int dp_p^y \frac{e^{-ip_p^y}\frac{T}{\sin\frac{\Phi}{2}}}{(p_p^y)^2 + \xi_p^2}.$$
 (6.25)

The last integral over p_p^y is a simple Fourier transform, which leads to the final result

$$\langle \mathcal{O}_1(x_1)\mathcal{O}_2(x_2)\mathcal{O}_3(x_3)\mathcal{O}_4(x_4)\rangle \sim \frac{1}{\cos\frac{\Phi}{2}\sin^2\frac{\Phi}{2}}e^{2\xi T\cot\frac{\Phi}{2}-\xi_p\frac{T}{\sin\frac{\Phi}{2}}}.$$
 (6.26)

In terms of the cross ratios of equation (6.19) we obtain

$$\langle \mathcal{O}_1(x_1)\mathcal{O}_2(x_2)\mathcal{O}_3(x_3)\mathcal{O}_4(x_4)\rangle \sim x^{-1}(1-x)^{-\frac{1}{2}}e^{2\xi\frac{t}{x}-\xi_p\frac{t}{x\sqrt{1-x}}}$$
 (6.27)

This results matches exactly the result (1.23) upon the replacement $\Delta_p = \Delta_i = 1$. Note that the prefactors which are subleading in the large ξ , ξ_p , Δ , Δ_p limit were not obtained in the probe limit of section 5. The computation in this section does generate the correct result, as it should be valid for any value of the mass and the spin of the bulk fields, as long as these do not backreact the background geometry. We conclude that the extrapolate dictionary proposed in (6.1), together with the introduction of geodesic Feynman diagrams, provide a holographic picture for Poincaré blocks in three dimensional Minkowski space.

6.4 Comments on the nature of this dictionary

A few comments on the dictionary we have proposed in this section are in order. First, there is the fact that this dictionary is quite different in nature from the extrapolate dictionary used in AdS/CFT. Instead of reading off the boundary correlators from bulk correlators evaluated on a cut-off surface near the conformal boundary, we have regulated them by integration along a bulk null ray. It would be interesting to understand the relation between this procedure and other approaches that have been taken to relating bulk physics to field theories at null infinity (e.g.: [43, 44]).

Second, there is the question of how we have related the physics of massive fields in the bulk to correlators of a BMSFT defined at null infinity. The usual objection is that massive particles cannot propagate to null infinity, but in AdS massive particles cannot propagate to the conformal boundary either. Nonetheless, there is the issue that wavefunctions in AdS for massive particles have a power law fall off near the conformal boundary whereas in Minkowski they have an exponential fall off near the conformal boundary. However, the nature of our proposed dictionary bypasses this issue: it does not relate BMSFT correlators to the asymptotic behaviour of fields, instead it uses null rays to probe the inside of the geometry. In any case, by matching the global part of the symmetries between the bulk and boundary, we have seen that the quantum number ξ of the BMS₃ representation must be related to the mass of the bulk Poincaré representation, so correlators of operators with non-zero ξ must be related to the physics of massive fields in the bulk.

In this work, we have studied our proposed dictionary at the level of matching bulk and boundary physics that is fixed by the global part of the BMS₃ symmetry. While finding a dictionary which works at this level is non-trivial, the real test of its usefulness will come from moving away from the universal sector. From the point of view of trying to understand how to apply the holographic principle in flat space, the interesting question is what happens when local bulk interactions are included. Understanding what these entail for the dual BSMFT, perhaps in the spirit of [45], is an important direction for future work.

7 Discussion

In this note we have proposed an extrapolate dictionary in the context of Einstein gravity in three dimensional Minkowski space-time, dual to a BMS₃ field theory at the null boundary. We have tested this dictionary through the holographic computation of BMS₃ entanglement entropy, low-point correlators, and global blocks. We have further introduced the concept of geodesic Feynman diagrams, in imitation of geodesic Witten diagrams in the AdS/CFT context. In the probe limit, this construction leads to the extremization of the length of a network of straight lines attached to the asymptotic boundary through null geodesics. There are a number of inmediate directions of future research. Let us discuss some of them.

The extrapolate dictionary (6.1) has been tested for scalar fields propagating through flat space. It would also be interesting to test its validity in the case of propagating spinning particles, which should lead to correlation functions involving boundary operators with quantum numbers $\Delta \neq 1$. For the case of spinning propagators, the prescription for the bulk-to-boundary propagator should correspond to integrating the pullback of the Feynman propagator to the null line γ_i falling from the boundary point where the corresponding operator is inserted.

The holographic construction of conformal blocks in AdS was first studied in [40], where the relation between Witten diagrams and conformal blocks was also explored. In the case of CFT scalar operators, it was shown that Witten diagrams and global blocks are distinct basis of conformally invariant functions. The authors of [40] were also able to expand a single Witten diagram into the global block basis. Denoting by W_p an exchange Witten diagram exchanging the conformal dimension h_p with pairs of operators of conformal dimensions h, the result reads

$$W_p = \mathcal{W}_p + \sum_n a_n \mathcal{W}_n + \sum_m a_m \mathcal{W}_m, \qquad (7.1)$$

where W_p is the global block exchanging the representation labeled by h_p , while $W_{n,m}$ correspond to blocks exchanging conformal families associated to double trace operators built out of the external operator pairs. In the context of flat space, one can also wonder what the relation is between attaching a standard position space Feynman diagram to the null lines γ_i (F_p), an attaching a geodesic Feynman diagram as done in section 6.3 (\mathcal{F}_p). A simple calculation shows that for the case of bulk scalar fields, the geodesic Feynman diagram leads to the same result as the standard Feynman diagram

$$F_p = \mathcal{F}_p. (7.2)$$

This implies that the Feynman diagram basis is equivalent to the global BMS block basis. It is not clear to us what this means in terms of the nature of BMS field theories, but it

clearly points to a fundamental difference between holography in flat space and holography in anti-de Sitter space.

It would also be interesting to explore flat space holography in higher dimensions. In [46], the two- and three-point functions invariant under BMS₄ were computed. It was found that the answer matched the expression for correlators in a two dimensional conformal field theory, which hints at the statement that gravity in Minkowski₄ space-time might be dual to a relativistic CFT₂.

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