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Infinite distances and the axion weak gravity conjecture

Thomas W. Grimm and Damian van de Heisteeg

Institute for Theoretical Physics, Utrecht University, Princetonplein 5, 3584 CE Utrecht, The Netherlands

E-mail: t.w.grimm@uu.nl, d.t.e.vandeheisteeg@uu.nl

ABSTRACT: The axion Weak Gravity Conjecture implies that when parametrically increasing the axion decay constants, instanton corrections become increasingly important. We provide strong evidence for the validity of this conjecture by studying the couplings of R-R axions arising in Calabi-Yau compactifications of Type IIA string theory. Specifically, we consider all possible infinite distance limits in complex structure moduli space and identify the axion decay constants that grow parametrically in a certain path-independent way. We then argue that for each of these limits a tower of D2-brane instantons with decreasing actions can be identified. These instantons ensure that the convex hull condition relevant for the multi-axion Weak Gravity Conjecture cannot be violated parametrically. To argue for the existence of such instantons we employ and generalize recent insights about the Swampland Distance Conjecture. Our results are general and not restricted to specific examples, since we use general results about the growth of the Hodge metric and the sl(2)-splittings of the three-form cohomology associated to each limit.

KEYWORDS: D-branes, Differential and Algebraic Geometry, Effective Field Theories, Superstring Vacua

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1 Introduction

A generic feature of four-dimensional string compactifications is the existence of scalar fields with approximate shift symmetries appearing in the effective action. Such axions appear in many phenomenologically motivated models, including models of cosmic inflation, in which the axions are considered as inflaton fields [1, 2]. The axion decay constants f, determined by the kinetic term of the axions, are of crucial importance and, depending on the precise application, required to have a certain range of values. For example, in large field inflationary models large values for f, comparable to the Planck mass, are often required. It has been suggested long ago, starting with [3], that large axion decay constants cannot be obtained in string theory, while at the same time controlling the instanton corrections that need to be included in a consistent formulation of the effective theory. This observation is formalized in the axion Weak Gravity Conjecture [4], which states that the axion decay constant times the action of an appropriate instanton coupling to the axion is smaller than the Planck mass times the instanton charge. Clearly, it is notoriously hard to establish such a conjecture, since it requires to control the behaviour of the axion decay constants and then reliably determine the non-perturbative corrections to the effective action as recently reviewed in [5].

Recently, the Swampland Distance Conjecture [6] has received much attention [7–33].¹ It states that an infinite tower of modes becomes exponentially light when approaching a point that is at infinite geodesic distance in field space. In particular, the recent constructions [15, 23, 27] suggest that effective theories near such infinite distance points exhibit universal properties that can be investigated model-independently and quantitatively. As a consequence, one might thus argue that any quantum gravity conjecture should first pass its validity tests in the limits in field space that lie at infinite geodesic distance. We will see in this work that this is also a fruitful path to test the axion Weak Gravity Conjecture and uncover new mechanisms that can be relevant in understanding the underlying reasons for its validity. In particular, note that it was argued for the Swampland Distance Conjecture in [15] that the number of relevant states that have to be included into the effective theory has to grow with a certain rate depending on properties of the infinite distance point. In the present context we will find the analog statement concerning the growth rate of the number of instantons that need to be included in the effective theory when approaching the infinite distance point.

Our focus in this work will be on the dynamics of the R-R three-form axions in Type IIA string theory compactified on a Calabi-Yau threefold. These axions are part of the $\mathcal{N} = 2$ hypermultiplet field space of the effective theory. The hypermultiplet moduli space of Type II string theory compactification has been studied in detail, see e.g. [34, 35] for reviews, or [36–48] for some papers on this subject. The classical dimensional reduction shows that their kinetic terms, and hence their square axion decay constants, are proportional to the Hodge star metric in the Calabi-Yau manifold. This implies that they generally depend very non-trivially on the complex structure moduli of the Calabi-Yau threefold. It will be the first task of this work to descibe their behaviour near infinite distance points in

¹A recent review on the various swampland conjectures can be found in [5].

correlation with the general classification of infinite distance points in the complex structure moduli space [23, 49]. We will find that the *classical* axion decay constants for some of the axions can, in general, grow to become increasingly large in the infinite distance limits. The axion Weak Gravity Conjecture is stating that instanton corrections must therefore become relevant in such limits. These corrections can modify the classical axion decay constants and 'tame' its behavior at such points by directly correcting their quantum expression. Alternatively, the classical behaviour could dominate still in the full axion decay constants, which then would imply that the axion Weak Gravity Conjecture states a minimal rate of the decrease in the instanton action. In either case it is important to identify instantons at such points, since the classical behavior of the axion decay constants without the presence of instantons would clearly violate the axion Weak Gravity Conjecture. In other words, instanton corrections should become relevant at such points in order that the axion Weak Gravity Conjecture is not violated parametrically. We suggest that these corrections stem from D-brane states and identify candidate D2-brane instanton states wrapped on threecycles of the Calabi-Yau manifold that non-trivially modify the effective theory at such points. Our construction follows the ideas of [15, 23] to characterize a tower of D3-brane states wrapped on three-cycles that gives the relevant particles for the Swampland Distance Conjecture in Type IIB compactifications. Note that we are not able to fully include these corrections e.g. by computing the quantum corrected axion decay constants. Rather the aim of this paper is to identify these instantons and study the behavior of their action in comparison to the *classical* behavior of the axion decay constants. It is a very complicated open problem to combine this to do the full quantum analysis.

The axion Weak Gravity Conjecture has already been investigated in various ways, see for instance [25, 31, 50–65]. One of the main challenges in addressing the axion Weak Gravity Conjecture arises when dealing with higher-dimensional field spaces. In this case one does not expect a simple direct link between the instanton actions and the axion decay constants. In fact, the kinetic term of the axions will generally be given in terms of a non-diagonal field-dependent metric and instanton actions will generally not align with any diagonalization attempt. A related issue in each higher-dimensional setting is the fact that we have to deal with path dependence when approaching an infinite distance point. In particular, the kinetic term for a certain axion might grow along one specific path, but might stay finite along another. It is one of our main tasks to address these general issues for the Type IIA setting under consideration. We will argue that there is a natural basis for the axions that is adapted to the infinite distance locus under consideration. More precisely, this special basis will arise from the fact that we can non-trivially associate an $\mathfrak{sl}(2,\mathbb{C})^n$ algebra to each infinite distance locus reached by sending n coordinates into a limit [66, 67]. This algebra acts on the three-forms defining the axion basis and thus splits the axion space into subspaces. We can then generally determine the growth of these subspaces when reaching the infinite distance point. This allows us to focus on the set of axions that have decay constants that grow parametrically in a certain path-independent way.

This paper is structured as follows. In section 2 we first review the classification of infinite distance points in complex structure moduli space. We then introduce a special real three-form basis adapted to the $\mathfrak{sl}(2,\mathbb{C})^n$ -algebra associated to the infinite distance limit

and discuss the growth of the associated Hodge metric. In section 3 we then recall some of the recent insights about the Swampland Distance conjecture for Calabi-Yau moduli spaces [15, 23] and adapt the presentation to the special three-form basis of section 2, whereafter we will generalize the stability argument presented in [15] to multi-variable settings. The axion Weak Gravity Conjecture will then be addressed in section 4. We identify a candidate tower of D2-brane instantons which prevents the parametric violation of this conjecture.

Note added. While we were in the process of writing up this paper the reference [31] appeared, which has some overlap with our work, but is in many respects complementary. On the one hand, our Type IIA treatment is general and does not focus on particular infinite distance limits, while [31] focuses on specific limits in the large volume regime. On the other hand [31] gives an interesting discussion on the modifications of the effective theories, while we will not address the modifications of the effective theory in the present work.

2 Infinite distances in Calabi-Yau moduli spaces

The aim of this work is to study the couplings of R-R axions in the four-dimensional effective theory. To motivate the use of the mathematical tools introduced in this section, let us first briefly recall the relevant structures in Type IIA Calabi-Yau compactifications. In this case we consider the axions $\xi^{\mathcal{I}}$ arising from expanding the R-R field C_3 into a basis $\gamma_{\mathcal{I}}$ of the third cohomology group $H^3(Y_3, \mathbb{R})$ via

$$C_3 = \xi^{\mathcal{I}} \gamma_{\mathcal{I}} \,. \tag{2.1}$$

The four-dimensional kinetic terms are readily derived to be²

$$\mathcal{L}_{\rm kin} = G_{\mathcal{I}\mathcal{J}} \; \partial_{\mu} \xi^{\mathcal{I}} \partial^{\mu} \xi^{\mathcal{J}} \,, \qquad G_{\mathcal{I}\mathcal{J}} = \frac{1}{2} e^{2D} \int_{Y_3} \gamma_{\mathcal{I}} \wedge * \gamma_{\mathcal{J}} \,, \tag{2.2}$$

where e^D is the four-dimensional dilaton and * is the Hodge star of the Calabi-Yau threefold. Note that the metric $G_{\mathcal{I}\mathcal{J}}$, crucial in defining the axion decay constants as we discuss below, non-trivially depends on the complex structure moduli through *.

In this section we will discuss the techniques needed to analyze limits in the moduli space of Calabi-Yau manifolds in which the axion metric $G_{\mathcal{I}\mathcal{J}}$ grows. We will not be able to introduce the complete mathematical theory relevant to answer these questions, but rather constrain ourselves to stating some of its main results from [49, 66, 67, 70, 71]. For a proper mathematical review on the foundations of this subject see e.g. [72]. More details are also provided in [23].

²Let us stress that in a Calabi-Yau threefold reduction of Type IIA the axions reside in a quaternionic field space and have additional kinetic terms. These terms play no important role for the considered limits discussed in section 4, and are absent in Type IIA orientifold truncations [68, 69].

2.1 On the geometry of the complex structure moduli space

In order to set the stage for the later discussions, let us first recall some basic properties of the complex structure moduli space \mathcal{M}^{cs} . This moduli space is spanned by the complex structure deformations that preserve the Calabi-Yau property and has complex dimension $h^{2,1}$, where $h^{p,q} = \dim(H^{p,q}(Y_3,\mathbb{C}))$ are the Hodge numbers of Y_3 . Since $\mathcal{M}^{cs}(Y_3)$ admits a special Kähler structure its metric can be derived from a Kähler potential K. Let us introduce local coordinates z^I with $I = 1, \ldots, h^{2,1}$. Furthermore, recall that the Calabi-Yau threefold Y_3 admits a unique (3,0)-form $\Omega(z)$ that varies holomorphically in these coordinates z^I . Ω can be used to define the metric on \mathcal{M}^{cs} via the Kähler potential

$$K(z,\bar{z}) = -\log\left[i\int_{Y_3}\Omega\wedge\bar{\Omega}\right].$$
(2.3)

Next we introduce a real, integral basis $\gamma_{\mathcal{I}}$ for $H^3(Y_3, \mathbb{Z})$, with $\mathcal{I} = 1, \ldots, 2h^{2,1} + 2$. This allows us to decompose Ω in its periods $\Pi^{\mathcal{I}}$ as

$$\Omega(z) = \Pi^{\mathcal{I}}(z)\gamma_{\mathcal{I}}.$$
(2.4)

Furthermore, we can construct a skew-symmetric product $\langle \cdot, \cdot \rangle$ on $H^3(Y_3, \mathbb{C})$, or componentwise an anti-symmetric pairing matrix η , given by³

$$\langle v, w \rangle = \int_{Y_3} v \wedge w, \qquad \eta_{\mathcal{I}\mathcal{J}} = -\langle \gamma_{\mathcal{I}}, \gamma_{\mathcal{J}} \rangle,$$
 (2.5)

with $v, w \in H^3(Y_3, \mathbb{C})$. Then we can express the Kähler potential as

$$K = -\log\left[i\langle \mathbf{\Pi}, \bar{\mathbf{\Pi}}\rangle\right] = -\log\left[i\bar{\Pi}^{\mathcal{I}}\eta_{\mathcal{I}\mathcal{J}}\Pi^{\mathcal{J}}\right].$$
(2.6)

Note that due to the skew-symmetry of $\langle \cdot, \cdot \rangle$ one can choose a symplectic basis $\gamma_{\mathcal{I}} = (\alpha_{\hat{K}}, \beta^{\hat{L}})$ with $\hat{K}, \hat{L} = 0, \ldots, h^{2,1}$. This basis satisfies the following properties

$$\langle \alpha_{\hat{K}}, \beta^{\hat{L}} \rangle = \delta^{\hat{L}}_{\hat{K}}, \qquad \langle \alpha_{\hat{K}}, \alpha_{\hat{L}} \rangle = \langle \beta^{\hat{K}}, \beta^{\hat{L}} \rangle = 0.$$
 (2.7)

As we will discuss in detail in section 2.4 there is a very special choice of such a symplectic basis associated to the considered point in moduli space when analyzing asymptotic limits.

2.2 Limits in the complex structure moduli space

We next discuss the relevant limits in this complex structure moduli space \mathcal{M}^{cs} . It will turn out that the metric $G_{\mathcal{I}\mathcal{J}}$ of the axions (2.2) can only grow unboundedly if we approach a point on in \mathcal{M}^{cs} at which the Calabi-Yau manifold Y_3 degenerates. Well-known examples of such degeneration points are the conifold point or the large complex structure point, but our analysis will be completely general and include also higher-dimensional degeneration loci. It can be shown that one can blow-up \mathcal{M}^{cs} in such a way that the subspaces at which Y_3 degenerates can locally be described as the vanishing locus of n coordinates

³Note that the skew-symmetric product in [67], and also [15, 23], was denoted by S(v, u) and differs by a minus sign from the definition used here.



Figure 1. Two paths γ_1, γ_2 towards the limiting point $t^1 \to i\infty$ $(z_1 = 0)$ and $t^2 \to i\infty$ $(z_2 = 0)$, respectively. The paths can lie in different growth sectors, since either the growth of y^1 or y^2 dominate in these cases. We also indicated the associate log-monodromy matrices N_1, N_2 .

 $z^1 = \ldots = z^n = 0.^4$ Instead of working with the z^I we will introduce new coordinates $t^i = \frac{1}{2\pi i} \log z^i$ such that the limits of interest are given by

$$t^1, \dots, t^n \to i\infty, \qquad \zeta^{\kappa} \text{ fixed}, \qquad (2.8)$$

where ζ^{κ} are the coordinates that are not taken to a limit.

The growth of the axion metric $G_{\mathcal{I}\mathcal{J}}$ in the limits (2.8) will in general depend on the precise path we are taking to these limiting points. The mathematical machinery we intend to use does provide us with general growth estimates in case we first divide the space into sectors, so-called growth sectors, and then demand that the considered path lies within one of such growth sectors at least for sufficiently large $y^i = \text{Im } t^i$. One of such growth sectors is given by

$$\mathcal{R}_{12\cdots n} = \left\{ t^i = x^i + iy^i \left| \frac{y^1}{y^2} > \lambda, \ \dots, \frac{y^{n-1}}{y^n} > \lambda, \ y^n > \lambda, \ x^i < \delta \right\},$$
(2.9)

where we can chose arbitrary positive λ, δ . Other growth sectors can be obtained by the same expression but with permuted y^i . Clearly, if a path lies within one of these sectors we can relabel the y^i such that the respective sector is given by (2.9). In figure 1 we illustrate two paths for the case that two t^i are send to the limit. Let us stress that the requirement that the considered path resides in one growth sector introduces a mild path dependence into our analysis, since we exclude paths which are so complicated that they always pass through multiple sectors.

It is a famous mathematical result [66] that the limiting behaviour of the periods Π , and also the metric $G_{\mathcal{I}\mathcal{J}}$, crucially depends on the monodromy matrix T_i associated to the $t^i = i\infty$ point. This monodromy matrix appears if one asks how Π transforms under $t^i \to t^i - 1$ for some index *i*, i.e. one has

$$\mathbf{\Pi}(\dots, t^i - 1, \dots) = T_i \mathbf{\Pi}(\dots, t^i, \dots).$$
(2.10)

⁴This equation describes the intersection of n divisors in the blown-up \mathcal{M}^{cs} .

The monodromy matrices T_i turn out to possess several very useful properties. Firstly, all T_i associated to the limit (2.8) commute with each other. Secondly, if a T_i possesses a non-trivial unipotent part, it defines a nilpotent matrix⁵

$$N_i = \log T_i \,. \tag{2.11}$$

The N_i also form a commuting set of matrices and one has $\eta N_i = -N_i^T \eta$. The nilpotent orbit theorem of [66] allows us to express Π in terms of the nilpotent matrices⁶

$$\mathbf{\Pi} = e^{-t^i N_i} \mathbf{A}(e^{2\pi i t^i}, \zeta) = e^{-t^i N_i} \big(\mathbf{a}_0(\zeta) + \mathcal{O}(e^{2\pi i t^i}, \zeta) \big),$$
(2.12)

where we sum in the exponential over i = 1, ..., n. Here \mathbf{a}_0 is a holomorphic function in the coordinates that are not send to a limit (2.8). Note here that the exponential yields a polynomial in t^i , since the N_i are nilpotent matrices. The important statement is that the vector \mathbf{A} is holomorphic in $z^A = e^{2\pi i t^A}$ and ζ , which allows for the above expansion with leading term \mathbf{a}_0 . This vector \mathbf{a}_0 determines the asymptotic behavior of $\mathbf{\Pi}$ in the limit (2.8), since the other terms will be suppressed if we take Im t^i to be large. \mathbf{a}_0 naturally defines a so-called nilpotent orbit given by

$$\mathbf{\Pi}_{\mathrm{nil}}(t,\zeta) = e^{-t^{i}N_{i}}\mathbf{a}_{0}(\zeta) \tag{2.13}$$

This nilpotent orbit is the starting point for our analysis of the asymptotic regions in \mathcal{M}^{cs} .

2.3 Classifying infinite distance limits

The information captures by Π_{nil} or (N_i, \mathbf{a}_0) can be used to classify infinite distance limits. Recall that the distance between two points P, Q along a path γ is determined by the integral

$$d_{\gamma}(P,Q) = \int_{\gamma} \sqrt{g_{k\bar{l}}} \dot{t}^k \dot{\bar{t}}^l ds \qquad (2.14)$$

where in the complex structure moduli space one has to use the metric $g_{k\bar{l}} = \partial_{t^k} \partial_{\bar{t}^l} K$ determined from (2.6). In order that the geodesic distance between points P, Q is infinite, every path γ between P, Q has to be of infinite lengths. This can only potentially happen if one of the points, say P, is located at one of the loci $t^1 = \ldots = t^n = i\infty$. However, not every such locus is at infinite distance. In fact, using the nilpotent orbit (2.13) and the properties of \mathbf{a}_0 one shows that [71]

$$P$$
 at infinite distance : $N_{(n)}\mathbf{a}_0 \neq 0$, (2.15)

as discussed in detail in [23]. Here we have defined $N_{(n)} = N_1 + \ldots + N_n$, but stress that every linear combination of the N_i with positive coefficients could equally be used.

⁵In the following we will assume that we have transformed the variables z^i and t^i , such that only the uni-potent part of T_i is relevant in the transformation (2.10). This procedure causes us to lose some of the information about the monodromies of orbifold singularities, but the aspects crucial to the infinite distances are retained.

⁶Note that this statement is true up to an overall holomorphic rescaling of Π . Such rescalings yield to a Kähler transformation of K given in (2.6). Unless otherwise indicated the following discussion is invariant under such rescalings.

Tuno	d_i	Index range	rank of			or a standard of a M
rybe			$N_{(i)}$	$N_{(i)}^2$	$N^3_{(i)}$	eigenvalues of $\eta_{IV}(i)$
I_a	0	$a=0,\ldots,h^{2,1}$	a	0	0	a negative
Π_b	1	$b = 0, \dots, h^{2,1} - 1$	2+b	0	0	2 positive, b negative
III_c	2	$c=0,\ldots,h^{2,1}-2$	4+c	2	0	not needed
IV_d	3	$d=1,\ldots,h^{2,1}$	2+d	2	1	not needed

 Table 1. Classification of limits in the complex moduli space.

It was shown in [15, 23] that it is crucial to actually distinguish several cases of infinite distance limits. In order to do that one needs to analyze the properties of $N_{(n)}$ and η . In fact, one can analyze the occurring singularity for any step sending $t^1, \ldots, t^i \to i\infty$, for $i = 1, \ldots, n$, associating an $N_{(i)} = N_1 + \ldots + N_i$. For each such pair $(N_{(i)}, \eta)$ one finds one of $4h^{2,1}$ types of limiting behaviours denoted by [49]

$$\mathbf{I}_a, \quad \mathbf{II}_b, \quad \mathbf{III}_c, \quad \mathbf{IV}_d, \tag{2.16}$$

where a, b, c, d are indices with index ranges listed in table 1. The table also gives the rules that allow to associate the types to $(N_{(i)}, \eta)$. Let us stress that each of this limits corresponds to making Y_3 singular and (2.16) provides a classification of all allowed singularities.

One can show that the type at each step i also determines the highest integer d_i such that

$$N_{(i)}^{d_i} \mathbf{a}_0 \neq 0, \qquad (2.17)$$

with $d_i = 0, 1, 2, 3$ for the four types I, II, III, and IV, respectively. We have included these labels in table 1. Since we are interested in limits that lie at infinite distance, we can use (2.15) to infer

infinite distance limits:
$$(N_{(n)}, \eta)$$
 is of type II_b, III_c or IV_d. (2.18)

It will be these limits in which we will study the behaviour of the axion metric $G_{\mathcal{IJ}}$ given in (2.2).

2.4 A special three-form basis and the $\mathfrak{sl}(2)$ -splitting

Having classified the infinite distance limits in \mathcal{M}^{cs} we next want to connect this information with the axion metric (2.2) for the axions $\xi^{\mathcal{I}}$ arising in the expansion (2.1). In order to do that it turns out to be very useful to introduce a special basis $\gamma_{\mathcal{I}}$ for $H^3(Y_3, \mathbb{R})$, which is adapted to the limiting locus that we approach. More precisely, the basis will depend on the following set of data:

- (1) the monodromy matrices N_i relevant for the considered limit;
- (2) the limiting vector \mathbf{a}_0 relevant for the considered limit;
- (3) the growth sector (2.9) in which the considered path resides.

The rough idea is to split up $H^3(Y_3, \mathbb{R})$ into a direct sum of smaller subspaces whose elements have a particular growth in the fields $y^i = \text{Im } t^i$ approaching infinity. Furthermore, one finds a 'limiting Hodge metric', in which these spaces are orthogonal. At first, this seems like an impossible task, since even the approximate periods (2.13) contain numerous mixed terms due to the general form of the N_i and \mathbf{a}_0 . However, there is the famous formalism of [66, 67] that allows to systematically approach this problem.

The in-genius idea of [67] is to reformulate this structure such that it non-trivially 'decomposes' into $\mathfrak{sl}(2,\mathbb{C})$ -blocks that decouple in a well-defined sense. More precisely, [67] constructs a set of *n* mutually commuting $\mathfrak{sl}(2,\mathbb{C})$ -triples acting on $H^3(Y_3,\mathbb{R})$ form the above local data (1)-(3). We will not describe the steps to actually perform this construction, but refer the reader to [23] for a detailed review and the study of an explicit example. Let us simply assert that we went through the relevant steps and introduce the

commuting
$$\mathfrak{sl}(2,\mathbb{C})$$
-triples: $(N_i^-, N_i^+, Y_i), \quad i = 1, \dots, n.$ (2.19)

These triples satisfy the standard commutation relations $[Y_i, N_i^{\pm}] = \pm 2N_i^{\pm}$ and $[N_i^+, N_i^-] = Y_i$. We can now use these triples to split $H^3(Y_3, \mathbb{R})$ into eigenspaces. Let us introduce

$$H^{3}(Y_{3},\mathbb{R}) = \bigoplus_{\underline{\ell}\in\mathcal{E}} V_{\underline{\ell}}, \qquad \underline{\ell} = (\ell_{1},\ldots,\ell_{n}), \qquad (2.20)$$

where $\ell_i \in \{0, \ldots, 6\}$ are integers representing the eigenvalues of $Y_{(i)} = Y_1 + \ldots + Y_i$, i.e.

$$v_{\ell} \in V_{\ell}: \qquad Y_{(i)}v_{\ell} = (\ell_i - 3)v_{\ell}.$$
 (2.21)

We have denoted by \mathcal{E} the set of all possible vectors ℓ labelling non-trivial $V_{\underline{\ell}}$ and collecting all eigenvalue combinations of $(Y_{(1)}, \ldots, Y_{(n)})$. Let us stress that the range of ℓ_i labelling non-empty $V_{\underline{\ell}}$ is correlated with the type of limit associated to $(N_{(i)}, \eta)$ when sending $t^1, \ldots, t^i \to i\infty$ as listed in table 1. In fact, one finds

I, II :
$$\ell_i = 2, \dots, 4$$
, III : $\ell_i = 1, \dots, 5$, IV : $\ell_i = 0, \dots, 6$. (2.22)

Note that using the fact that the singularity can only increase sending more t^i to the limit we find that the range of ℓ_i successively increases with *i*.

One can derive several interesting properties of the vector spaces $V_{\underline{\ell}}$. Most important for us is the fact that

$$\dim V_{\ell} = \dim V_{6-\ell} \,, \tag{2.23}$$

where we abbreviated $\underline{6} = (6, \ldots, 6)$. This implies that we can one-to-one identify a basis vector of $V_{\underline{\ell}}$ and $V_{\underline{6}-\underline{\ell}}$. Furthermore, these spaces $V_{\underline{\ell}}$ satisfy certain orthogonality relations, as follows from

$$(r_i - 3)\langle V_{\underline{\ell}}, V_{\underline{r}} \rangle = \langle V_{\underline{\ell}}, Y_{(i)} V_{\underline{r}} \rangle = -\langle Y_{(i)} V_{\underline{\ell}}, V_{\underline{r}} \rangle = (3 - \ell_i) \langle V_{\underline{\ell}}, V_{\underline{r}} \rangle, \qquad (2.24)$$

by using (2.21) and that $\langle \cdot, Y_{(i)} \cdot \rangle = -\langle Y_{(i)} \cdot, \cdot \rangle$. Namely, it implies that the product between these spaces can only be non-zero if $\ell_i + r_i = 6$. And since this should hold for all *i*, the vector spaces V_{ℓ} satisfy the orthogonality property

$$\langle V_{\underline{\ell}}, V_{\ell'} \rangle = 0$$
 unless $\underline{\ell} + \underline{\ell'} = \underline{6}$. (2.25)

It should now be clear from (2.23), (2.25), and the skew-symmetry of the inner product $\langle \cdot, \cdot \rangle$ that the $V_{\underline{\ell}}$ define naturally a special symplectic basis with the properties (2.7).

Importantly the limiting vector \mathbf{a}_0 turns out to not generally fall into one of the spaces $V_{\underline{\ell}} \otimes \mathbb{C}$ of the splitting (2.20). However, as shown in [67] and discussed in detail in [23], there are always two real matrices ζ', δ which rotate $\tilde{\mathbf{a}}_0 = e^{\zeta'} e^{-i\delta} \mathbf{a}_0$, such that

$$\tilde{\mathbf{a}}_{\mathbf{0}} \in V_{\underline{3}+\underline{d}} \otimes \mathbb{C}, \quad \underline{d} = (d_1, \dots, d_n), \qquad (2.26)$$

with d_i defined in (2.17). Crucially, this construction is such that one also finds that the complex conjugate of $\tilde{\mathbf{a}}_0$ lies in V_d , such that

Re
$$\tilde{\mathbf{a}}_{\mathbf{0}}$$
, Im $\tilde{\mathbf{a}}_{\mathbf{0}} \in V_{3+d}$, $\underline{d} = (d_1, \dots, d_n)$. (2.27)

The vector $\tilde{\mathbf{a}}_{\mathbf{0}}$ generally depends on the remaining coordinates ζ^{κ} not taken to a limit in (2.8). It can be used to define the so-called Sl(2)-orbit

$$\mathbf{\Pi}_{\mathrm{Sl}(2)}(y,\zeta) = e^{-iy^{i}N_{i}^{-}} \widetilde{\mathbf{a}}_{0}(\zeta) \,. \tag{2.28}$$

This orbit asymptotically approximates the nilpotent orbit (2.13) in the limit $\frac{y^1}{y^2}, \ldots, \frac{y^{n-1}}{y^n}, y^n \to \infty$ and $x^i = 0$.

It should be stressed that many key properties of our later constructions are contained in this very non-trivial $\mathfrak{sl}(2)$ -split (2.20) of $H^3(Y_3, \mathbb{R})$. One of these properties, namely the growth of the Hodge metric of this basis, we will discuss next.

2.5 Asymptomatic behavior of the Hodge norm

One of the remarkable applications of the $\mathfrak{sl}(2)$ -splitting, which we introduced in section 2.4, is to obtain an asymptotic expression for the Hodge metric that appears, for example, in the definition (2.2) of the axion metric $G_{\mathcal{I},\mathcal{I}}$.

Let us first introduce some notation and define the Hodge norm of a three-forms $\mathbf{v} \in H^3(Y_3, \mathbb{C})$ by

$$\|\mathbf{v}\|^2 = \langle \bar{\mathbf{v}}, *\mathbf{v} \rangle = \int_{Y_3} \bar{\mathbf{v}} \wedge *\mathbf{v} \,. \tag{2.29}$$

As stressed above, the Hodge star * in general depends very non-trivially on the complex structure moduli. In order to make this dependence explicit, one can decompose **v** into its components in $H^{p,q}(Y_3, \mathbb{C})$, with p + q = 3. The individual components can then be expressed in terms of the period vector **II** and its Kähler-covariant derivatives. It turns out that one can control the asymptotic of the periods **II** in the limits (2.8) which then leads to an asymptotic expression for the Hodge metric.⁷

To make the asymptotic form of the metric explicit, we first introduce a limit Hodge norm [67, 72]

$$\|\mathbf{v}\|_{\infty}^{2} = \langle \bar{\mathbf{v}}, *_{\infty} \mathbf{v} \rangle.$$
(2.30)

While we will not define $*_{\infty}$ in any detail, let us record some of its properties. Firstly, $\|\cdot\|_{\infty}$ is finite in the limit (2.8), since $*_{\infty}$ does no longer depend on the fields $t^1, \ldots, t^{n.8}$

⁷This again non-trivially applies the $\mathfrak{sl}(2)$ -splitting introduced in the previous subsection.

⁸Note that $*_{\infty}$ can still depend on the coordinates ζ and hence become singular if these are sent into special limits.

It is adapted to the splitting of the vector space $H^3(Y_3, \mathbb{R})$ introduced in (2.20) via the orthogonality relations

$$\langle V_{\ell}, *_{\infty} V_{\ell'} \rangle = 0$$
 unless $\underline{\ell} = \underline{\ell'}$. (2.31)

The norm (2.30) can be used to give an asymptotic expression for the original Hodge norm (2.29) in the limit (2.8). Decomposing a general real three-form **u** into its components $\mathbf{u}_{\ell} \in V_{\ell}$ one has [67, 70]

$$\|\mathbf{u}\|^2 \sim \sum_{\underline{\ell}\in\mathcal{E}} \left(\frac{y^1}{y^2}\right)^{\ell_1-3} \dots \left(\frac{y^{n-1}}{y^n}\right)^{\ell_{n-1}-3} (y^n)^{\ell_n-3} \|\mathbf{u}_{\underline{\ell}}\|_{\infty}^2, \qquad \mathbf{u} = \sum_{\underline{\ell}\in\mathcal{E}} \mathbf{u}_{\underline{\ell}}.$$
(2.32)

This expression will be our main tool in the rest of this paper to evaluate the growth of the axion metric $G_{\mathcal{I}\mathcal{J}}$ and the associated D2-brane instanton actions.

3 The swampland distance conjecture for Calabi-Yau moduli

In this section we revisit the recent constructions of [15, 23] that provided strong evidence for the validity of the Swampland Distance Conjecture (SDC) for all infinite distance limits in $\mathcal{M}^{cs}(Y_3)$. The crucial observation of these works is, that one can relate the classification of infinite distance points, recalled in section 2.3, with the existence of a tower of D3-branes wrapped on three-cycles of Y_3 with masses becoming exponentially light when approaching the infinite distance points. One of the main tasks in establishing such a picture is the search for suitable three-cycles that can host such states. While it will not add much to the strategy presented in [15, 23], we will reformulate and generalize the statements using the special basis introduced in section 2.4. This reformulation turns out to be an elegant way of stating the findings and will serve as a prelude to section 4, where we will consider axion decay constants and Euclidean D2-branes wrapping three-cycles of Y_3 . Furthermore, we will generalize the stability properties of the D3-brane states of [15], where they studied the oneparameter setting, to the multi-parameter infinite distance limits considered in [23], which will play an important role in the test of the axion Weak Gravity Conjecture in section 4.

3.1 Construction of the D3-brane states

Let us begin by introducing the necessary basic properties of the three-cycles that can host the D3-brane states required to satisfy the SDC. In order to specify the state that we obtain from wrapping a D3-brane on a three-cycle of Y_3 , we will give its Poincaré dual three-form $\mathbf{Q} \in H^3(Y_3, \mathbb{R})$. Since we are mainly interested in the mass of this state we will not discuss the quantization of \mathbf{Q} in the following.⁹ Since we are performing a Calabi-Yau compactification the four-dimensional theory is an $\mathcal{N} = 2$ supergravity theory. Our aim is to considere candidate charges \mathbf{Q} that correspond to BPS states. This non-trivial assertion will have severe consequences, as we discuss below. In the following we will first establish the conditions on \mathbf{Q} in order that the corresponding D3-branes state becomes light in an infinite distance limit $t^1, \ldots t^n \to i\infty$ introduced in (2.8).

 $^{^9 \}mathrm{We}$ note that many aspects of the structure introduced here can be generalized over $\mathbb{Q}.$

Given a BPS D3-brane state with charge \mathbf{Q} we can compute its mass by evaluating its central charge using $M(\mathbf{Q}) = |Z(\mathbf{Q})|$, with the central charge given by

$$Z(\mathbf{Q}) = \frac{\langle \mathbf{Q}, \mathbf{\Pi} \rangle}{\|\mathbf{\Pi}\|}, \qquad (3.1)$$

where $\mathbf{\Pi}$ are the periods appearing in (2.6) and $\langle \cdot, \cdot \rangle$, $\|\cdot\|$ were defined in (2.5), (2.29). We are interested in finding the charge vectors \mathbf{Q} such that the states become massless in the infinite distance limit. Since $*\mathbf{\Pi} = -i\mathbf{\Pi}$ we can apply Cauchy-Schwarz inequality to find the following upper bound on the mass of the state

$$M(\mathbf{Q}) = \frac{|\langle \mathbf{Q}, *\mathbf{\Pi} \rangle|}{\|\mathbf{\Pi}\|} \le \|\mathbf{Q}\|.$$
(3.2)

This implies that a sufficient condition for becoming light in the limit (2.8) is that $\|\mathbf{Q}\| \to 0$. Classifying in a higher-dimensional moduli space the states that admit such a behaviour for a general path approaching the infinite distance point is clearly challenging. However, as we will see in the following the machinery introduced in section 2 allows us to do this for all paths that reside in a single growth sector.

Let us now consider a path with (2.8) that approaches an infinite distance point and eventually resides in the growth sector (2.9). In this case we can apply the growth result (2.32). The requirement that \mathbf{Q} behaves as $\|\mathbf{Q}\| \to 0$ along each such path, leads us to define the vector space

$$V_{\text{light}} = \bigoplus_{\underline{\ell} \in \mathcal{E}_{\text{light}}} V_{\underline{\ell}}, \qquad \mathcal{E}_{\text{light}} = \{\underline{\ell} \in \mathcal{E} \mid \ell_1, \dots, \ell_{n-1} \le 3, \, \ell_n < 3\}, \tag{3.3}$$

where we recall that $V_{\underline{\ell}}$ are the vector spaces introduced in (2.20). If we require $\mathbf{Q} \in V_{\text{light}}$ we thus have a corresponding state that becomes massless at the infinite distance point. Let us remarks in order here. Firstly, the requirement \mathbf{Q} is a sufficient condition for masslessness, since $\|\mathbf{Q}\|$ gives an upper bound for $M(\mathbf{Q})$. In other words, there could be states that become massless in the infinite distance limit whose charges are not in V_{light} .¹⁰ Secondly, the set V_{light} labels states that are massless along *any* path in the considered growth sector. Along special paths there could be more states becoming light than captured by V_{light} . Let us already mention that this path-independence requirement will be equally relevant when studying the axion decay constants and thus will be discussed further in section 4.

Next we want to make a distinction between two types of components for \mathbf{Q} , such that we can write it as

$$\mathbf{Q} = \mathbf{Q}^{\mathrm{G}} + \mathbf{Q}^{\mathrm{F}}, \qquad (3.4)$$

where the subscripts indicate that we are dealing with Type G states and Type F states, respectively.¹¹ We define this split, such that the former are intimately linked to the presence of gravity, while the latter are also present in purely field theoretic settings. Concretely,

¹⁰In particular, all Type F states introduced in (3.5) become massless at the infinite distance point. Note, however, that this condition together with the BPS condition is likely very strong.

¹¹In [15] Type G and F states were dubbed Type I and II states respectively. It is convenient to change the name to avoid confusion with the types of limits in (2.16).

we require that Type G states become massless as a power law in the y^i , whereas Type F states do so at an exponential rate. These growth rates can be inferred from the product of the charge vectors \mathbf{Q} with the nilpotent orbit $\mathbf{\Pi}_{nil}$. Namely, by using the nilpotent orbit approximation for $\mathbf{\Pi}$ we neglect exactly the exponential terms that determine the mass of Type F states. Then the conditions for Type F and Type G states can be phrased as

$$\langle \mathbf{\Pi}_{\text{nil}}, \mathbf{Q}^{\text{F}} \rangle = 0, \qquad \langle \mathbf{\Pi}_{\text{nil}}, \mathbf{Q}^{\text{G}} \rangle \neq 0.$$
 (3.5)

Note that this does not define a unique split. The set of Type F states defines a vector space. However, \mathbf{Q}^{G} should be viewed as representing an equivalence class, since we are free to add any Type F charges to a Type G state. This last feature will be crucial in the context of the axion Weak Gravity Conjecture later on.

Although Type G states do not form a vector space, we can still write down a basis of representatives $\{\hat{\mathbf{q}}_{\hat{l}}\}_{\hat{l}=0,1,\ldots}$ for the Type G charges. However, relating such a basis to the subspaces $V_{\underline{\ell}}$ turns out more difficult. Let us therefore derive a sufficient condition that determines a set of Type G vectors. The main issue is that the nilpotent orbit approximation relies on the vector \mathbf{a}_0 , whereas it is Re $\tilde{\mathbf{a}}_0$ and Im $\tilde{\mathbf{a}}_0$ that have a definite location (2.27) in the spaces $V_{\underline{\ell}}$. To relate the nilpotent orbit and the Sl(2)-orbit (2.28) directly, we must take a special limit. Namely, if we take the limit $\frac{y^1}{y^2}, \ldots, \frac{y^{n-1}}{y^n}, y^n \to \infty$ we can replace $\mathbf{\Pi}_{nil}$ by $\mathbf{\Pi}_{Sl(2)}$. Now let us apply this to the defining property of a Type F state. Since it should hold for all values of y^i , we find the following implication

$$\langle \mathbf{\Pi}_{\mathrm{nil}}, \mathbf{Q}^F \rangle = 0 \qquad \Longrightarrow \qquad \langle \mathbf{\Pi}_{\mathrm{Sl}(2)}, \mathbf{Q}^F \rangle = 0.$$
 (3.6)

We can use the negation of this statement to find Type G states. Namely, it tells us that

$$\langle \mathbf{\Pi}_{\mathrm{Sl}(2)}, \mathbf{q} \rangle \neq 0 \qquad \Longrightarrow \qquad \langle \mathbf{\Pi}_{\mathrm{nil}}, \mathbf{q} \rangle \neq 0,$$
(3.7)

with $\mathbf{q} \in H^3(Y_3, \mathbb{R})$. Thus the search for a basis of Type G states can be partly fulfilled by finding vectors \mathbf{q} that satisfy $\langle \mathbf{\Pi}_{\mathrm{Sl}(2)}, \mathbf{q} \rangle \neq 0$. And because $\mathbf{\Pi}_{\mathrm{Sl}(2)}$ can be expressed in terms of $\tilde{\mathbf{a}}_0$, we can directly relate such vectors to the vector spaces $V_{\underline{\ell}}$. We can thus use (3.7) to derive a relevant set of Type G states. With these preliminaries, we are now able to further discuss the construction of the charge vectors \mathbf{Q} for the infinite tower of states. We already noted that we will restrict our considerations to charges $\mathbf{Q} \in V_{\text{light}}$ defined in (3.3). Furthermore we pointed out that only the Type G charge of these states is relevant in the context of the SDC. These can be determined using the condition (3.7), and the polarization constraint

$$-i^{3-d_n} \langle \tilde{\mathbf{a}}_0, (N_1^-)^{d_1} (N_2^-)^{d_2-d_1} \dots (N_n^-)^{d_n-d_{n-1}} \bar{\tilde{\mathbf{a}}}_0 \rangle > 0, \qquad (3.8)$$

where $\underline{d} = (d_1, \ldots, d_n)$ was given in (2.27). Hence, we see that by using the $\mathfrak{sl}(2, \mathbb{C})^n$ -algebra a set of candidate vectors generating the Type G states is given by acting sufficiently many times with N_1^-, \ldots, N_n^- on the vectors Re $\tilde{\mathbf{a}}_0$ and Im $\tilde{\mathbf{a}}_0$, such that the resulting vectors are in V_{light} . In order to do that it is convenient to recall that

$$N_i^- V_{\underline{\ell}} \subseteq V_{\underline{\ell}'} \quad \text{with} \quad \underline{\ell}' = (\ell_1, \dots, \ell_{i-1}, \ell_i - 2, \dots, \ell_n - 2), \tag{3.9}$$

and the location of Re $\tilde{\mathbf{a}}_0$ and Im $\tilde{\mathbf{a}}_0$ is $V_{\underline{d}+\underline{3}}$ as given in (2.27). Let us denote by $\{\mathbf{q}_{\hat{l}}\}_{\hat{l}=0,1,\ldots}$ the set of charge vectors obtained by acting with N_1^-,\ldots,N_n^- on Re $\tilde{\mathbf{a}}_0$, Im $\tilde{\mathbf{a}}_0$ that are located in V_{light} .

Having constructed representatives $\mathbf{q}_{\hat{I}}$ of all Type G states, we can check their respective growths by using (2.32). By definition of V_{light} all such states will have decreasing norm $\|\cdot\|$ when approaching the singularity. Let us denote by \mathbf{q}_0 the state with the slowest decrease. In order to do that we consider the growth of a vector \mathbf{q}_I to be smaller or equal to the growth of \mathbf{q}_I , if there exists a finite constant γ such that

$$\frac{||\mathbf{q}_I||}{||\mathbf{q}_J||} < \gamma \,, \tag{3.10}$$

along every path approaching $t^1, \ldots, t^n \to i\infty$ in the considered growth sector (2.9). It is not hard to check in examples that this gives a well-defined transitive order among the $\mathbf{q}_{\hat{f}}$, since they are in V_{light} and constructed from Re $\tilde{\mathbf{a}}_0$, Im $\tilde{\mathbf{a}}_0$. It is, however, important to stress that there are cases in which there is no unique element with the slowest decrease. We then can consider the set of elements with the slowest decrease and pick any element calling it \mathbf{q}_0 .

We have now the sufficient preparation to introduce the infinite set of charge vectors that we will consider. We thus define

$$\mathbf{Q}^{\mathrm{G}}(\mathbf{q}_{0}|m_{I}) = \mathbf{q}_{0} + \sum_{I} m_{I} \mathbf{q}_{I} , \qquad (3.11)$$

with m_I some integer coefficients. For simplicity, we will take the m_I to be non-negative in the rest of this paper. It was argued in [15] that the tower of states relevant to the SDC should arise from increasing the numbers m_I . The intuitive argument for this statement was by considering stability of BPS states, i.e. by asking if the states (3.11) labelled by m_I can possibly decay. For the general expression (3.11) of $\mathbf{Q}^{\mathrm{G}}(\mathbf{q}_0|m_I)$ stability is very hard to analyze. However, as noted in [15] the situation improves if the charges $\mathbf{Q}^{\mathrm{G}}(m_I)$ can be represented as an orbit

$$\mathbf{Q}^{\mathrm{G}}(\mathbf{q}_{0}|m_{I}) = \exp\left(\sum_{I} m_{I} N_{I}^{-}\right) \mathbf{q}_{0} \,. \tag{3.12}$$

In this case one can argue for a stability argument by using the phase shifts and we will discuss this in more detail in section 3.2. However, as we will see below and was already pointed out in [15], such an orbit does not exist for every type of limit. In these cases one can still write down a tower of states (3.11) labelled by integers m_I by using several Type G states with the same growth. However, in such cases one loses the stability arguments valid for the orbit (3.12) and different arguments would have to be employed.¹² We stress here, that a slightly more involved the construction of (3.11) and (3.12) was suggested in [23]. Namely, it was shown that there exists a natural construction of the orbit and hence the \mathbf{q}_I if the type of the singularity enhances further when sending more than n coordinates to a limit. We will not need this construction in the following when working with (3.11).

¹²This was also stressed in [30].

Having discussed the Type G component \mathbf{Q}^{G} of the charge vectors, let us next turn to the Type F component \mathbf{Q}^{F} . As mentioned above, we are in principle free to add any Type F charges to our charge vector, since these will only result in additional terms for the central charge $Z(\mathbf{Q})$ that are exponentially suppressed. Thus from the perspective of the SDC, we do not have to keep track of such components of the state. However, it will be crucial from the perspective of the axion WGC to include these Type F charges for the state. We can therefore consider the following generalized charge vector

$$\mathbf{Q}(\mathbf{q}_0|m_I, m_{\underline{\ell}}) = \mathbf{Q}^{\mathrm{G}}(\mathbf{q}_0|m_I) + \mathbf{Q}^{\mathrm{F}}(m_{\underline{\ell}}) = \mathbf{q}_0 + \sum_I m_I \mathbf{q}_I + \sum_{\underline{\ell} \in \mathcal{E}_{\mathrm{light}}, \alpha_{\underline{\ell}}} m_{\underline{\ell}}^{\alpha_{\underline{\ell}}} \mathbf{v}_{\underline{\alpha}_{\underline{\ell}}}^{\underline{\ell}} \qquad (3.13)$$

where the prime indicate that we should exclude the basis vectors $\mathbf{q}_0, \mathbf{q}_I$ in the sum over the Type F charge vectors. This means that the Type F charges $m_{\underline{\ell}}^{\alpha_{\underline{\ell}}}$ exclude these components as well.

3.2 On the stability of the D3-brane states

Now that we have discussed which D3-brane states become light in the infinite distance limit, we want to examine the stability properties of this tower of states. In [15] it was already found for one-parameter Type IV infinite distance limits that, at a given instance along the limit, only a finite number of these states are stable against decays. Let us denote this finite number by m_{crit}^I for the charge generated by \mathbf{q}_I , which indicates the critical length of our tower of states. They found that this critical length scaled as $m_{\text{crit}}^1 \sim y^1$, such that the length of the tower increases as we move further along the infinite distance limit, and that the tower becomes of infinite size as we send $y^1 \to \infty$. Here we will generalize this feature to multi-parameter infinite distance limits, which will play an important role in the test of the axion Weak Gravity Conjecture in section 4.

The arguments made in [15] relied crucially on aspects of $\mathcal{N} = 2$ BPS states, and thus so will ours. Let us therefore begin by shortly recalling their stability properties, and refer to the original articles [73–83]. Consider three BPS states A, B and C, with their charge vectors denoted by $\mathbf{q}_A, \mathbf{q}_B$ and \mathbf{q}_C respectively. We want to study the situation where state C is unstable against decay into anti-state \overline{A} and state B. The charge vectors of these states must satisfy

$$\mathbf{q}_C = \mathbf{q}_{\bar{A}} + \mathbf{q}_B \,, \tag{3.14}$$

with $\mathbf{q}_{\bar{A}} = -\mathbf{q}_A$. The masses of these states satisfy

$$M(\mathbf{q}_C) \le M(\mathbf{q}_{\bar{A}}) + M(\mathbf{q}_B), \qquad (3.15)$$

which follows from the linearity of the central charge in the charges. The state C then becomes unstable against decay if this inequality is saturated. This statement can be made more explicit by considering the (normalized) phase of the central charge

$$\varphi = \frac{1}{\pi} \operatorname{Im} \log Z(\mathbf{q}) \,. \tag{3.16}$$

The alignment of the phases $\varphi(B) = \varphi(\bar{A})$ then indicates that C becomes unstable against the decay into \bar{A} and B, which corresponds to

$$\varphi(B) - \varphi(A) = 1. \tag{3.17}$$

The loci of this equation in \mathcal{M}^{cs} are called curves of marginal stability, such that if we cross this curve in the moduli space, the state C is only marginally stable against decay. In essence, this boils down to a restriction of this phase to a range (-1, 1) in order for the state C to remain stable, as discussed in more detail in [75, 78] in the context of so-called stable pairs. This aspect played an important role in the argument presented in [15], where they generated the states of the tower by circling the infinite distance point until the phase of the central charge began to rotate and they thus crossed such a curve of marginal stability. Then the number of windings before they encountered this curve set the critical length m_{crit}^1 of the tower.

It is important to mention that the product states \overline{A} , B cannot be chosen arbitrarily such that (3.14) holds, but they must be mutually non-local as well, that is, $\langle \mathbf{q}_{\overline{A}}, \mathbf{q}_{B} \rangle \neq$ 0 [73, 74]. Phrased oppositely, it tells us that two states can only form a bound state if their charges are mutually non-local. Then for states that lie in V_{light} it is useful to recall that, by use of orthogonality relations (2.25), this vector space satisfies the following property

$$\langle V_{\text{light}}, V_{\text{light}} \rangle = 0.$$
 (3.18)

Therefore no two states that lie in V_{light} can form a bound state together. In particular, this tells us that any two states $\mathbf{Q}(\mathbf{q}_0|m_I, m_{\underline{\ell}}), \mathbf{Q}(\mathbf{q}_0|m'_I, m'_{\underline{\ell}})$ in our infinite tower are mutually local, such that they cannot bound together. It also indicates that the product states that result from the decay of a state $\mathbf{Q}(\mathbf{q}_0|m_I, m_{\underline{\ell}})$ of our tower must necessarily have charges that do not lie in V_{light} to have a non-zero intersection product between these states.

Before we argue for stability properties of our tower of states, it will prove to be useful to examine the asymptotic properties of the central charge of Type G charge vectors in more detail. To be more precise, we want to consider Type G charges that are constructed out of $\tilde{\mathbf{a}}_0$ by applying lowering operators N_i^- , which will always be realized in our constructions. Therefore, we want to rewrite the nilpotent orbit (2.13) using the $\mathfrak{sl}(2, \mathbb{C})$ -data. This can be done by rewriting the orbit as [67, 72]

$$\mathbf{\Pi}_{\text{nil}} = \alpha(x, y) \, e^{-x^i N_i} e^{-1}(y) \, p(y) \, e^{-i N_{(n)}^-} \tilde{\mathbf{a}}_0 \,, \tag{3.19}$$

where $\alpha(x, y)$ is some overall coefficient function that accounts for the freedom to rescale the periods. Crucially, the nilpotent orbit contains the matrix-valued function

$$e(y) = \exp\left[\frac{1}{2}\sum_{j=1}^{n-1}\log\left(\frac{y^j}{y^{j+1}}\right)Y_{(j)} + \frac{1}{2}\log(y^n)Y_{(n)}\right]$$

$$= \left(\frac{y^1}{y^2}\right)^{\frac{1}{2}Y_{(1)}} \dots \left(\frac{y^{n-1}}{y^n}\right)^{\frac{1}{2}Y_{(n-1)}} (y^n)^{\frac{1}{2}Y_{(n)}},$$
(3.20)

which encodes the asymptotic behaviour in the limit $y^1, \ldots, y^n \to \infty$ and is the origin of the scaling in (2.32). The complex matrix-valued function p(y) is a polynomial in $(y^1/y^2)^{-1/2}$,

..., $(y^{n-1}/y^n)^{-1/2}$, $(y^n)^{-1/2}$ with constant term 1. Note that the other terms in this polynomial can be bounded by factors of $\lambda^{-1/2}$ within the growth sector (2.9).

Then consider the central charge $Z(\mathbf{q})$ of a Type G charge \mathbf{q} that is located in a single eigenspace $V_{\underline{\ell}}$. For simplicity let us set x = 0, since we want to determine the growth in the coordinates y^i . Then we obtain

$$Z(\mathbf{q}) = \alpha(x, y) \, e^{K/2} \langle e^{-1}(y) \, p(y) \, e^{-iN_{(n)}^{-}} \tilde{\mathbf{a}}_{0}, \mathbf{q} \rangle \,. \tag{3.21}$$

By properties of the symplectic product $\langle \cdot, \cdot \rangle$ we can move e^{-1} to the other side of the product as e, and application on \mathbf{q} then results in the same growth behavior as one finds for $\|\mathbf{q}\|$ using (2.32). Inserting (3.19) into the expression for $e^{K/2}$ we then obtain

$$Z(\mathbf{q}) \sim e^{i\theta} \left(\frac{y^1}{y^2}\right)^{\frac{\ell_1 - 3}{2}} \dots \left(\frac{y^{n-1}}{y^n}\right)^{\frac{\ell_n - 1 - 3}{2}} \langle y^n \rangle^{\frac{\ell_n - 3}{2}} \langle p(y) e^{-iN_{(n)}^-} \tilde{\mathbf{a}}_0, \mathbf{q} \rangle, \qquad (3.22)$$

where θ is the overall phase inherited from α and we stress that this equation is true only up to overall numerical factors. Note that for relative phases between two central charges the factor $e^{i\theta}$ cancels, such that the only remaining part of the phase is determined by $\langle p(y)e^{-iN_{(n)}^{-}}\tilde{\mathbf{a}}_{0}, \mathbf{q} \rangle$.

To simplify this expression even further, consider a Type G charge vector \mathbf{q} that is constructed out of $\tilde{\mathbf{a}}_0$ by acting with lowering operators N_i^- . We can infer from the polarization condition (3.8) that the intersection product of $e^{-iN_{(n)}^-}\tilde{\mathbf{a}}_0$ via the constant 1 in the expansion of p(y) with \mathbf{q} is non-zero by construction.¹³ Then (3.22) reduces to

$$Z(\mathbf{q}) \sim e^{i\theta} \left(\frac{y^1}{y^2}\right)^{\frac{\ell_1 - 3}{2}} \dots \left(\frac{y^{n-1}}{y^n}\right)^{\frac{\ell_n - 1 - 3}{2}} \langle y^n \rangle^{\frac{\ell_n - 3}{2}} \langle e^{-iN_{(n)}^-} \tilde{\mathbf{a}}_0, \mathbf{q} \rangle.$$
(3.23)

In this case $\langle e^{-iN_{(n)}^{-}} \tilde{\mathbf{a}}_{0}, \mathbf{q} \rangle$ indicates the relevant part of the phase of the central charge.

Now we want to investigate how far we can move up into our tower before states start to become unstable, where we will set the Type F charges to zero for simplicity. Thus we consider a state \mathbf{q}_0 , and look at how the phase of its central charge $\varphi(\mathbf{q}_0)$ shifts as we move up in the tower to a non-zero value m_J for a Type G charge. Then we find that

$$\begin{aligned} |\varphi \left(\mathbf{Q}^{\mathrm{G}}(m_{J}) \right) - \varphi (\mathbf{q}_{0})| &= \frac{1}{\pi} \left| \mathrm{Im} \log \left[1 + \frac{Z(m_{J}\mathbf{q}_{J})}{Z(\mathbf{q}_{0})} \right] \right| \\ &\sim \frac{m_{J} ||\mathbf{q}_{J}||}{\pi ||\mathbf{q}_{0}||} \left| \mathrm{Im} \frac{\langle e^{-iN_{(n)}^{-}} \tilde{\mathbf{a}}_{0}, \mathbf{q}_{J} \rangle}{\langle e^{-iN_{(n)}^{-}} \tilde{\mathbf{a}}_{0}, \mathbf{q}_{0} \rangle} \right| \\ &\lesssim \frac{m_{J} ||\mathbf{q}_{J}||}{\pi ||\mathbf{q}_{0}||} \end{aligned} \tag{3.24}$$

where we expanded this logarithm and used (3.22). Note the analogy with [15], where they circled the infinite distance loci to generate the tower of states, which resulted in these

¹³Other terms in this expansion of p(y) can potentially lead to non-zero intersections as well, but these contributions can never exceed the growth of $Z(\mathbf{q})$ that follows from the constant term 1, since these other terms are bounded by factors of $\lambda^{-1/2}$.

phase shifts. This expression is simply the generalized version of those phase shifts to multiparameter infinite distance limits, which reduces to the one-parameter result $\|\mathbf{q}_0\|/\|\mathbf{q}_1\| \sim y^1$ by picking $\mathbf{q}_0 = (N_1^-)^2 \mathbf{\tilde{a}}_0$ and $\mathbf{q}_1 = (N_1^-)^3 \mathbf{\tilde{a}}_0$ using (2.32). It hints at some critical scale

$$n_{\rm crit}^J \sim \|\mathbf{q}_0\| / \|\mathbf{q}_J\|, \qquad (3.25)$$

such that the phase of the central charge $Z(\mathbf{Q}^{G}(\mathbf{q}_{0}|m_{J}))$ potentially shifts by $\frac{1}{2}$. If this phase shift actually occurs, depends on whether the central charges of \mathbf{q}_{0} and \mathbf{q}_{I} differ in phase, as can be seen in the second line of (3.24). For charge vectors given in orbit form (3.12) this phase difference is always realized, since $\mathbf{q}_{J} = N_{J}^{-}\mathbf{q}_{0}$, and thus the numerator picks up a factor of *i* less than the denominator by use of the polarization condition (3.8). For charge vectors that cannot be written in orbit form, one needs to go more carefully through the polarization conditions (3.8).

We can then see this shift in phase of the central charge $Z(\mathbf{Q}^{\mathrm{G}}(m_J))$ as we increase m_J as an indication that the states will become unstable after a certain critical scale m_{crit}^J . Namely, we know from the stability properties of BPS states that a state can become unstable when phases of central charges rotate, and we have

$$\varphi(\mathbf{Q}^{\mathrm{G}}(m_{J})) = \begin{cases} \varphi(\mathbf{q}_{0}) + \frac{1}{2}, & \text{for } \|\mathbf{q}_{0}\| / \|\mathbf{q}_{J}\| \ll m_{J}, \\ \varphi(\mathbf{q}_{0}), & \text{for } \|\mathbf{q}_{0}\| / \|\mathbf{q}_{J}\| \gg m_{J}. \end{cases}$$
(3.26)

Thus the phase of $Z(\mathbf{Q}^{G}(m_{J}))$ must rotate in the region given by $\|\mathbf{q}_{0}\|/\|\mathbf{q}_{J}\| \sim m_{J}$, such that relative phase between product states can potentially rotate out of the stable range (-1, 1), and $\mathbf{Q}^{G}(m_{I})$ then becomes unstable. Therefore it is a sufficient condition to require $m_{J} \leq m_{\text{crit}}^{J} \sim \|\mathbf{q}_{0}\|/\|\mathbf{q}_{J}\|$ to ensure the stability of the states that we consider at a given instance along the limit. Note that different arguments would have to be employed for the growth of the tower in the case that the norms of \mathbf{q}_{0} and \mathbf{q}_{J} have the same growth behavior. However, for the purposes of this work such properties will not be needed.

We expect a similar story to hold for the Type F charges of our states, that is, the charges m_{ℓ} must have some upper bound $m_{\rm crit}$ as well. This bound can be motivated from the fact that their contribution to the central charge vanishes asymptotically by construction (3.5), since Type F charges enter the central charge via the exponentially suppressed corrections to the nilpotent orbit approximation (2.13). Then the upper bound $m_{\rm crit}$ for Type F charges should grow such that contributions to the central charge still vanish asymptotically, which suggests scales comparable to exponential growth.

3.3 One-parameter infinite distance limits

It is instructive to briefly review the properties of the towers of states that arise in oneparameter infinite distance limit. This means that we consider Type II_b, III_c, and IV_d infinite distance limits with one parameter y^1 . A first task is to determine the dimensions of the vector spaces V_{ℓ} . Using appendix A.1 and the classification in [23, 49], we readily find the result listed in table 2.

The next step is to find the vectors that generate the Type G charges. As discussed in the section 3.1 they satisfy

$$\langle \mathbf{\Pi}_{\mathrm{Sl}(2)}, \mathbf{q} \rangle \neq 0.$$
 (3.27)

name	$\dim V_0$	$\dim V_1$	$\dim V_2$	$\mathbf{q}_0,\mathbf{q}_1$
Ia	0	0	a	-
II _b	0	0	b+2	$\mathbf{q}_0 = N_1^{-} \operatorname{Re}(\tilde{\mathbf{a}}_0)$ $\mathbf{q}_1 = N_1^{-} \operatorname{Im}(\tilde{\mathbf{a}}_0)$
III _c	0	2	С	$\begin{aligned} \mathbf{q}_0 &= (N_1^-)^2 \mathrm{Re}(\mathbf{\tilde{a}}_0) \\ \mathbf{q}_1 &= (N_1^-)^2 \mathrm{Im}(\mathbf{\tilde{a}}_0) \end{aligned}$
IV_d	1	0	d	$ \mathbf{q}_0 = (N_1^-)^2 \tilde{\mathbf{a}}_0 \\ \mathbf{q}_1 = (N_1^-)^3 \tilde{\mathbf{a}}_0 $

Table 2. This table lists the dimensions of the spaces V_{ℓ} for $\ell \in \mathcal{E}_m = \{0, 1, 2\}$ for the possible one-parameter infinite distance limits. In addition, it includes the vectors that span the Type G charges for the charge vector \mathbf{Q}^G .

Here $\Pi_{Sl(2)}$ can be expressed in terms of nilpotent matrices N_1^- and the vector $\tilde{\mathbf{a}}_0$. Therefore it will prove to be useful to recall some polarization conditions for this vector $\tilde{\mathbf{a}}_0$. To be begin with, we know that

$$-i^{3-d}\langle \tilde{\mathbf{a}}_0, (N_1^-)^d \bar{\tilde{\mathbf{a}}}_0 \rangle > 0, \qquad (3.28)$$

with d = 1, 2, 3 for a Type II, III or IV infinite distance limit respectively. Furthermore, we have that $\overline{\tilde{a}}_0 = \tilde{a}_0$ for a Type IV infinite distance limit, such that \tilde{a}_0 is real. And for a Type II or III singularity we have an additional polarization condition that tells us that

$$\langle \tilde{\mathbf{a}}_0, (N_1^-)^d \tilde{\mathbf{a}}_0 \rangle = 0.$$
(3.29)

Together these relations suffice to identify basis vectors $\mathbf{q}_0, \mathbf{q}_1$ for the Type G charges of our charge vector \mathbf{Q} , which have been included in table 2. We should note that $\mathbf{q}_0, \mathbf{q}_1 \in V_{3-d}$ for Type II and III infinite distance limits, whereas $\mathbf{q}_0 \in V_2$ and $\mathbf{q}_1 \in V_0$ for a Type IV singularity.

Now let us discuss the stability of the tower of states for each of these infinite distance limits, that is, we will comment on the critical size $m_{\rm crit}^1$ of the tower of states at a given instance along the infinite distance limit. For Type IV infinite distance limits it has already been argued that $m_{\rm crit}^1 \sim y^1$ in [15], which is in agreement with our discussion in section 3.2. In contrast, for Type II and III infinite distance limits we cannot apply directly the stability arguments after (3.24), since $\mathbf{q}_0, \mathbf{q}_1$ have the same growth. In specific examples, one might be able to argue for an $m_{\rm crit}$ using global properties of the moduli space [27, 30]. Fortunately, we will not need an expression for $m_{\rm crit}$ in these cases.

4 The weak gravity conjecture for R-R axions

In this section we study the couplings of R-R axions in the context of the Weak Gravity Conjecture (WGC) for axions. Let us therefore shortly recall this conjecture [4]. In the case that one has only one axion, the conjecture states that there exists an instanton coupled to the axion such that 14

$$fS \le qM_p \,, \tag{4.1}$$

where f denotes the axion decay constant, S is the instanton action, and q is the instanton charge. For a given axion ξ , with a periodic field range $\xi \cong \xi + 2\pi$, we define its decay constant f via its kinetic term

$$\mathcal{L}_{\rm kin} = -f^2 \,\partial_\mu \xi \partial^\mu \xi \,. \tag{4.2}$$

The instanton charge is defined by noting that axion couples to the instanton via the exponential $e^{-S+iq\xi}$. This implies that the periodicity of this contribution is $2\pi/q$ and the field range of the canonically normalized axion $2\pi f/q$.

The formulation of the axion WGC becomes significantly more subtle in a higherdimensional axion space. In order to treat such cases requires us to introduce the vectors

$$z_a^{\mathcal{I}} = \sum_{\mathcal{J}} \frac{f^{\mathcal{I}\mathcal{J}} q_{a\mathcal{J}}}{S_a} \,, \tag{4.3}$$

where $f^{\mathcal{I}\mathcal{J}}$ are the inverse axion decay constants, S_a instanton action of an instanton labelled by a, and $q_{a\mathcal{J}}$ encodes the axion coupling such that the instantons are weighted by a factor $\exp(-S_a + iq_{a\mathcal{J}}\xi^{\mathcal{J}})$. The axion decay constants are defined to diagonalize the metric of the axions as $G_{\mathcal{I}\mathcal{J}} = (f^T \cdot f)_{\mathcal{I}\mathcal{J}}$. It was suggested in [50, 52] that the generalization of (4.1) is the statement that the convex hull that is spanned by $\pm \mathbf{z}_a = \pm z_a^{\mathcal{I}} \gamma_{\mathcal{I}}$ contains the unit ball (i.e. with radius M_p^{-1}), where $\gamma_{\mathcal{I}}$ are the basis vectors in axion space normalized such that the axion $\xi^{\mathcal{I}}$ has a 2π periodicity. It is important to notice that there are various refinements of this conjecture which propose stronger conditions [4, 15, 62, 64, 65]. Most relevant for us will be the statement of the strong axion WGC, which states that the convex hull condition should be satisfied for the \mathbf{z}_a constructed from the instantons with the smallest actions. In other words, one orders the instantons coupling to some axion direction by the value of their action and only retains the one with the smallest value S_a to construct the vectors (4.3).

Before we proceed with the analysis of the general multi-axion setup, let us already give a qualitative outline of what we can expect. In the four-dimensional Type IIA Calabi-Yau compactifications that we will be considering, the quantities f and S vary non-trivially over the complex structure moduli space $\mathcal{M}^{cs}(Y_3)$. If we take an infinite distance limit in \mathcal{M}^{cs} , we will find that f and S have certain growth rates in the coordinates y^i by use of growth properties (2.32). The axion WGC (4.1) then suggests that the parametrical growth of the axion decay constant f should be cancelled by the decrease of the instanton action S. Therefore, our task is to find, for an axion direction with a parametrically growing decay constant, an instanton that couples to this axion with an instanton action that decreases at a sufficient rate. It is at this stage that the three-cycles of Y_3 discussed in the previous section become relevant. Namely, instead of wrapping D3-branes on these three-cycles to find states that become massless in infinite distance limits, these three-cycles can now host Euclidean D2-branes with a parametrically decreasing action. We will find that we can

¹⁴We should note that we have set $M_p = 1$ throughout the rest of this section.

couple every R-R axion to one of these instantons, provided that its axion decay constant f grows in a path-independent manner. The fact that our tower of instantons also grows at a certain rate specified by $m_{\rm crit}$, discussed in section 3.2, implies that the instanton charge q grows parametrically as well, which will play a crucial role in this test of the axion WGC. Namely, we will find that the decrease of the instanton action S will not always suffice to cancel the growth of the axion decay constant f completely, and that then the leftover growth is matched by the growth of the instanton charge q.

4.1 Asymptomatic axion decay constants for R-R axions

For completeness, we will first recall some basic aspects of R-R axions. As mentioned before, these axions $\xi^{\mathcal{I}}$ follow from expanding the R-R field C_3 into a basis of harmonic 3-forms $\gamma_{\mathcal{I}}$ of Y_3 via

$$C_3 = \xi^{\mathcal{I}} \gamma_{\mathcal{I}} \,, \tag{4.4}$$

with the kinetic terms for these fields given by

$$\mathcal{L}_{\rm kin} = G_{\mathcal{I}\mathcal{J}} \; \partial_{\mu}\xi^{\mathcal{I}}\partial^{\mu}\xi^{\mathcal{J}}, \qquad G_{\mathcal{I}\mathcal{J}} = \frac{1}{2}e^{2D}\langle\gamma_{\mathcal{I}}, *\gamma_{\mathcal{J}}\rangle, \tag{4.5}$$

where D denotes the four-dimensional dilaton, and $\langle \cdot, \cdot \rangle$ is defined in (2.5). Then the field range of these axions is $\xi^{\mathcal{I}} \cong \xi^{\mathcal{I}} + 2\pi$, such that the metric $G_{\mathcal{I}\mathcal{J}}$ defines the axion decay constants. A suitable basis for this metric adapted to the infinite distance limit is the special threeform basis discussed in section 2.4, since it decomposes the Hodge norm in blocks that have the same growth rate (2.32). Let us therefore split up these fields into axions $\xi_{\alpha_{\ell}}^{\underline{\ell}}$ corresponding to the basis vectors $\mathbf{v}_{\underline{\ell}}^{\alpha_{\ell}}$, $\alpha_{\underline{\ell}} = 1, \ldots, \dim V_{\underline{\ell}}$, that span the vector spaces $V_{\underline{\ell}}$. Collecting all $\mathbf{v}_{\underline{\ell}}^{\alpha_{\underline{\ell}}}$ we have, by using (2.20), a basis of $H^3(Y_3, \mathbb{R})$ and the $\xi_{\alpha_{\underline{\ell}}}^{\underline{\ell}}$ parameterize all axion directions. The kinetic terms for these fields are then given by

$$\mathcal{L}_{\rm kin} = \frac{1}{2} e^{2D} \sum_{\underline{\ell}, \underline{r} \in \mathcal{E}} \sum_{\alpha_{\underline{\ell}}, \beta_{\underline{r}}} \langle \mathbf{v}_{\underline{\ell}}^{\alpha_{\underline{\ell}}}, * \mathbf{v}_{\underline{r}}^{\beta_{\underline{r}}} \rangle \ \partial_{\mu} \xi_{\underline{\alpha}_{\underline{\ell}}}^{\underline{\ell}} \partial^{\mu} \xi_{\underline{\beta}_{\underline{r}}}^{\underline{r}}, \tag{4.6}$$

which, by using (2.31) and (2.32), we can rewrite in the infinite distance limit into

$$\mathcal{L}_{\rm kin} \sim \frac{1}{2} e^{2D} \sum_{\underline{\ell} \in \mathcal{E}} \sum_{\alpha_{\underline{\ell}}, \beta_{\underline{\ell}}} \left(\frac{y^1}{y^2} \right)^{\ell_1 - 3} \dots \left(\frac{y^{n-1}}{y^n} \right)^{\ell_{n-1} - 3} (y^n)^{\ell_n - 3} \langle \mathbf{v}_{\underline{\ell}}^{\alpha}, \ast_{\infty} \mathbf{v}_{\underline{\ell}}^{\beta_{\underline{\ell}}} \rangle \ \partial_{\mu} \xi_{\underline{\alpha}_{\underline{\ell}}}^{\underline{\ell}} \partial^{\mu} \xi_{\underline{\beta}_{\underline{\ell}}}^{\underline{\ell}} .$$
(4.7)

Some comments about (4.7) are in order here. Firstly, note that this expression is an asymptotic expression for the kinetic terms, as indicated by the symbol \sim , which can be used to bound the actual field space metric. As it is equally true for (2.32), it does not capture the numerical factors and in fact it does not follow from our considerations how large the numerical constants in (4.7) need to be chosen such that it provides a good approximation to (4.6). In fact, the more precise statement it is the actual Hodge norm is bounded by the norm asymptotic norm (2.32) when multiplied by some finite constant depending only on how close one is to the limiting point. Accordingly our results will always only gives bounds with undetermined numerical coefficients. Secondly, we note that we have used the orthogonality (2.31) among the V_{ℓ} . This simplifies the result significantly, but needs to be read, with our first remark in mind, as the statement that the off-diagonal terms among different $V_{\underline{\ell}}$ are sub-dominant when considering sufficiently large y^1, \ldots, y^n . Nevertheless, it divides the axions into various sets that 'decouple' at least when considering the dominant growth. It is clear from (4.7) that we can make no such decoupling statements when considering axions coming from the same $V_{\underline{\ell}}$. All axions from a fixed $V_{\underline{\ell}}$ grow with the same rate in y^1, \ldots, y^n .

Let us now look at the growth of the various terms in (4.7) in more detail. Clearly, depending on the values of $\underline{\ell}$ and the considered path in the y^1, \ldots, y^n the kinetic terms either go to zero, stay constant, or grow to become infinitely large in the limit. Clearly, in order to test the axion WGC (4.1) we are interested in increasing kinetic terms and axion decay constants. In this work, however, we will restrict our considerations to axions whose decay constants grows in a certain path-independent way. More precisely, we will demand that f^2 grows for any path that resides in a growth sector such as (2.9). This immediately implies constraints on the integers ℓ_k . Namely, we find by inspecting (4.7) together with (2.9) that the basis vectors \mathbf{v}_{ℓ} of the considered axions must be elements of

$$V_{\text{heavy}} = \bigoplus_{\underline{\ell} \in \mathcal{E}_{\text{heavy}}} V_{\underline{\ell}}, \qquad \mathcal{E}_{\text{heavy}} = \{ \underline{\ell} \in \mathcal{E} \mid \ell_1, \dots, \ell_{n-1} \ge 3, \, \ell_n > 3 \}.$$
(4.8)

Note, in particular, that V_{heavy} is defined in an opposite fashion compared to the vector space V_{light} in (3.3), which contained all vector spaces whose Hodge norm decreased along every path with (2.8) in the growth sector. In fact, we can use these two definitions to decompose the vector space $H^3(Y_3, \mathbb{R})$ as

$$H^{3}(Y_{3},\mathbb{R}) = V_{\text{light}} \oplus V_{\text{heavy}} \oplus V_{\text{rest}} \,. \tag{4.9}$$

The last part V_{rest} are the remaining directions in the vector space decomposition. They parametrize axions whose decay constants grow, decrease, or stay constant depending on the considered path approaching the limit $y^1, \ldots, y^n \to \infty$. Recall that the products between vectors out of two spaces $V_{\ell}, V_{\ell'}$ can only be non-zero if $\ell + \ell' = 6$. This implies

$$\langle V_{\text{heavy}}, V_{\text{heavy}} \rangle = 0, \qquad \langle V_{\text{light}}, V_{\text{light}} \rangle = 0.$$
 (4.10)

Furthermore, we find that the vector spaces V_{heavy} and V_{light} are dual to each other under the product $\langle \cdot, \cdot \rangle$ and indices in the index sets $\mathcal{E}_{\text{light}}$ and $\mathcal{E}_{\text{heavy}}$ can be canonically identified. In other words, we find that for every vector $\mathbf{v}_{\text{heavy}} \in V_{\text{heavy}}$ there exists a vector $\mathbf{v}_{\text{light}} \in$ V_{light} such that

$$\langle \mathbf{v}_{\text{heavy}}, \mathbf{v}_{\text{light}} \rangle \neq 0$$
 (4.11)

This canonical duality between V_{heavy} and V_{light} will be crucial in arguing that we can couple every axion direction $\mathbf{v}_{\ell} \in V_{\text{heavy}}$ to a D2-brane instanton $\mathbf{Q} \in V_{\text{light}}$.

Now that the asymptotic behavior of the kinetic terms has been discussed in detail, we are ready to analyze the asymptomatic axion decay constants. From (4.7) we can deduce that only the couplings between axions in the same subspace V_{ℓ} are relevant in the infinite

distance limit, and that axions that reside in different subspaces decouple. Therefore the asymptomatic axion decay constants are given by

$$(f_{\mathcal{I}\mathcal{J}}) \sim \text{diag}\left[e^{D}\left(\frac{y^{1}}{y_{2}}\right)^{\frac{\ell_{1}-3}{2}} \cdots \left(\frac{y^{n-1}}{y^{n}}\right)^{\frac{\ell_{n-1}-3}{2}} (y^{n})^{\frac{\ell_{n-3}}{2}} \hat{f}_{\alpha_{\underline{\ell}},\beta_{\underline{\ell}}}\right],$$
 (4.12)

where we stress that we find a matrix with blocks along the diagonal labelled by $\underline{\ell}$ and each index \mathcal{I} is associated with one pair $\underline{\ell}, \alpha_{\underline{\ell}}$. The axion decay constants for the individual blocks are proportional to $\hat{f}_{\alpha_{\ell},\beta_{\ell}}$ defined as

$$(\hat{f}^T \cdot \hat{f})_{\alpha_{\underline{\ell}},\beta_{\underline{\ell}}} = \frac{1}{2} \langle \mathbf{v}_{\underline{\ell}}^{\alpha_{\underline{\ell}}}, *_{\infty} \mathbf{v}_{\underline{\ell}}^{\beta_{\underline{\ell}}} \rangle .$$

$$(4.13)$$

As discussed already in the context of the kinetic terms and in section 2.5, this matrix remains finite in the infinite distance limit, and, in fact, does not depend on the coordinates y^i . Thus the asymptomatic behavior in y^i of the axion decay constants is captured by the power law in (4.12).

4.2 D2-brane instantons and the axion WGC

Having discussed the kinetic terms (4.6), (4.7) and the resulting axion decay constants (4.12), we now study D2-brane instantons. Recall that the world-volume action of an Euclidean D2-brane wrapping a three-cycle specified by **Q** is given by

$$S_{D2} = e^{-D} |Z(\mathbf{Q})| + i \langle C_3, \mathbf{Q} \rangle, \qquad (4.14)$$

with $Z(\mathbf{Q})$ being the central charge defined in (3.1). The coupling functions, such as the moduli space metric, of the effective theory thus receive corrections of the form $e^{-S_{\text{D2}}}$. Expanding C_3 in $\xi_{\overline{\alpha}_{\ell}}^{\underline{\ell}} \mathbf{v}_{\underline{\ell}}^{\alpha_{\ell}}$ then tells us that the charges of this instanton are given by

$$q_{\overline{\alpha}_{\ell}}^{\ell}(\mathbf{Q}) = \langle \mathbf{v}_{\underline{\ell}}^{\alpha_{\underline{\ell}}}, \mathbf{Q} \rangle.$$
(4.15)

Let us next focus on identifying candidate D2-brane instantons which have an instanton action S that decreases along the infinite distance limit. The instanton action S of a Euclidean D2-brane is given by the real part of S_{D2} in (4.14), from which we obtain

$$S = e^{-D} |Z(\mathbf{Q})|. \tag{4.16}$$

The idea is to consider the charges \mathbf{Q} introduced in (3.13) that described asymptotically massless D3-brane states in the SDC consideration of section 3. Wrapping Euclidean D2branes on these three-cycles then provides us with candidate instantons that can couple to the R-R axions. More specifically, the mass of these D3-brane states was previously given by $|Z(\mathbf{Q})|$, and it now gives us the instanton action S. Thus the fact that the D3-brane states became massless in the infinite distance limit ensures us that S is decreasing as well, and we have

$$S = e^{-D} |Z(\mathbf{Q})| \sim e^{-D} ||\mathbf{q}_0||.$$
(4.17)

Note that in order to get this asymptotic expression for the central charge we have used (3.22). Moreover, since \mathbf{q}_0 is the slowest decreasing charge in \mathbf{Q} the leading growth of (3.22) agrees with the growth of $||\mathbf{q}_0||$ up to a finite prefactor.

We are now ready to determine the vectors \mathbf{z}_a defined in (4.3). Since our instantons are labeled by the charge vector \mathbf{Q} we thus need to determine $\mathbf{z}(\mathbf{Q})$. Inserting (4.12), (4.15) and (4.16) into the vectors (4.3) we find

$$z^{\mathcal{I}}(\mathbf{Q}) \sim \left(\frac{y^{1}}{y_{2}}\right)^{\frac{3-\ell_{1}}{2}} \cdots \left(\frac{y^{n-1}}{y^{n}}\right)^{\frac{3-\ell_{n-1}}{2}} (y^{n})^{\frac{3-\ell_{n}}{2}} \sum_{\beta_{\underline{\ell}}} \frac{\hat{f}^{\alpha_{\underline{\ell}},\beta_{\underline{\ell}}} q_{\beta_{\underline{\ell}}}^{\ell}(\mathbf{Q})}{|Z(\mathbf{Q})|}, \qquad (4.18)$$

where as before \mathcal{I} is split into $\underline{\ell}, \alpha_{\ell}$.

In the following we will simplify our discussion by no longer indicating the block structure and hence suppress the indices $\alpha_{\underline{\ell}}, \beta_{\underline{\ell}}$ and the finite asymptotic axion decay constants $\hat{f}_{\alpha_{\underline{\ell}},\beta_{\underline{\ell}}}$. This can be done since the asymptotic behavior is entirely captured by the y^i dependent growth factors and we will keep this relevant information for evaluating the axion WGC constraint. More precisely, we will consider the vectors

$$z^{\mathcal{I}}(\mathbf{Q}) \sim \left(\frac{y^{1}}{y_{2}}\right)^{\frac{3-\ell_{1}}{2}} \cdots \left(\frac{y^{n-1}}{y^{n}}\right)^{\frac{3-\ell_{n-1}}{2}} (y^{n})^{\frac{3-\ell_{n}}{2}} \frac{q^{\underline{\ell}}(\mathbf{Q})}{|Z(\mathbf{Q})|}, \qquad (4.19)$$

when discussing the axion WGC introduced at the beginning of this section. Since we are only concerned with parametric control, we thus ask, if the $z^{\mathcal{I}}(\mathbf{Q})$ is bounded from below in the directions with parametrically growing axion decay constants. Recall that we will be only discussing directions where this happens path-independently in a growth sector. This implies that we consider

$$\mathbf{z}(\mathbf{Q}) = z^{\mathcal{I}}(\mathbf{Q})\gamma_{\mathcal{I}} \in V_{\text{heavy}}.$$
(4.20)

To make the growth of (4.19) fully explicit we next use (4.17) and $\mathbf{q}_0 \in V_{\underline{r}}$ in (4.19) to determine

$$z^{\mathcal{I}}(\mathbf{Q}) \sim \underbrace{\left(\frac{y^{1}}{y_{2}}\right)^{\frac{6-\ell_{1}-r_{1}}{2}} \cdots \left(\frac{y^{n-1}}{y^{n}}\right)^{\frac{6-\ell_{n-1}-r_{n-1}}{2}}_{\hat{z}^{\ell}(\mathbf{q}_{0})} (y^{n})^{\frac{6-\ell_{n}-r_{n}}{2}}_{\hat{z}^{\ell}(\mathbf{Q})} q^{\ell}(\mathbf{Q}), \qquad (4.21)$$

where we have evaluated the growth of \mathbf{q}_0 using (2.32). Therefore, in order to show that the axion WGC is not parametrically violated, it will often suffice to argue that the y^i dependent pre-factor $\hat{z}^{\underline{\ell}}(\mathbf{q}_0)$ in (4.21) is bounded from below. However, in order to capture all cases it turns out to be important to also consider the growth of the tower encoded by $q^{\underline{\ell}}(\mathbf{Q})$. In fact, in the next subsections we will argue that one can use (4.11) together with the growth of the tower discussed in section 3.2 to always identify appropriate combinations of Type G and Type F charges specifying \mathbf{Q} given in (3.13) such that the convex hull condition for the multi-axion WGC is never parametrically violated.

space	decomposition	dimensions
$V_{ m light}$	$V_0\oplus V_2$	1+d
$V_{ m heavy}$	$V_6\oplus V_4$	1+d
$V_{ m rest}$	V_3	$2(h^{2,1}-d)$

Table 3. Decomposition of $H^3(Y_3, \mathbb{R})$ for IV_d . Note that we have used different colors to indicate the dimensions of the individual subspaces.

4.3 Axion WGC in one-parameter infinite distance limits

To illustrate how to construct the D2-brane instantons relevant for the axion WGC, let us first look at an example before moving to more general settings. Concretely, we first consider a one-parameter Type IV_d infinite distance limit. As detailed in appendix A.1 we can decompose V_{light} , V_{heavy} and V_{rest} into the vector spaces V_{ℓ} as listed in table 3.

We can reformulate the charge vectors found in [15] as

$$\mathbf{Q}^{\mathrm{G}}(m_1) = \mathbf{q}_0 + m_1 \mathbf{q}_1, \qquad \mathbf{Q}^{\mathrm{F}}(m_2^i) = \sum_{\mathbf{v}_2^i \neq \mathbf{q}_0} m_2^i \mathbf{v}_2^i,$$
(4.22)

with the representatives for the Type G charges given by

$$\mathbf{q}_0 = (N_1^-)^2 \mathbf{\tilde{a}}_0 \in V_2, \qquad \mathbf{q}_1 = (N_1^-)^3 \mathbf{\tilde{a}}_0 \in V_0.$$
 (4.23)

Note that the sum over Type F charges for \mathbf{Q}^{F} indeed excludes the two basis vectors $\mathbf{q}_0, \mathbf{q}_1$, and only sums over the remaining d-1 basis vectors for V_2 . In the following we will discuss how these instantons \mathbf{Q} allow us to examine the WGC for axion directions in each of the subspaces of V_{heavy} via the vectors $\mathbf{z}(\mathbf{Q})$.

First consider an axion direction $\mathbf{v}_4 \in V_4$ for $\mathbf{z}(\mathbf{Q})$. Its growth in this component $z^4(\mathbf{Q})$ can be deduced from (4.21), and using that $\mathbf{q}_0 \in V_2$ we find that all factors of y^1 cancel each other, such that $\hat{z}^4(\mathbf{q}_0)$ remains finite along the infinite distance limit. Then to provide evidence for the axion WGC for this direction, the only remaining thing to show is that we can ensure that one of our D2-brane instantons has non-zero charge with respect to this axion, that is, $q^4(\mathbf{Q}) = \langle \mathbf{Q}, \mathbf{v}_4 \rangle \neq 0$. This axion direction can couple to either the Type G charge vector \mathbf{q}_0 or some Type F charge vector \mathbf{v}_2^i of V_2 under the product $\langle \cdot, \cdot \rangle$, which can be seen from its orthogonality properties (2.25). If it couples to \mathbf{q}_0 then every instanton in our tower (4.22) suffices to argue that the axion WGC is not violated parametrically in this direction, whereas if it couples to some \mathbf{v}_2^i we must pick a non-zero Type F charge $m_2^i \neq 0$ to ensure a non-zero charge with respect to this axion.

Now consider the direction $\mathbf{v}_6 \in V_6$. The orthogonality properties (2.25) of $\langle \cdot, \cdot \rangle$ tell us that this axion direction couples to \mathbf{q}_1 , since V_6 and V_0 are dual to each other and both vector spaces are one-dimensional. This axion therefore couples to one of the D2-brane instantons (4.22) provided that $m_1 \neq 0$. However, at first sight this axion direction seems to violate the WGC for axions, because we find by use of (4.21) that the growth of $z^6(\mathbf{Q})$ is given by $\hat{z}^6(\mathbf{q}_0) = (y^1)^{-1}$, since $\mathbf{q}_0 \in V_2$. This suggests that the convex hull cannot envelop a ball of finite size in this direction, and that instead the convex hull seems to shrink along this direction as we move further along the infinite distance limit. We can resolve this issue by using that we have a tower of instantons. Namely, if we consider a D2-brane instanton with $m_1 = m_{\text{crit}}^1$, with $m_{\text{crit}}^1 \sim y^1$ the growth of our tower discussed in section 3.2, we find that its charge grows as

$$q^{6}(\mathbf{Q}) = \langle \mathbf{Q}^{G}(m_{\text{crit}}^{1}), \mathbf{v}_{6} \rangle = \langle \mathbf{q}_{0} + m_{\text{crit}}^{1} \mathbf{q}_{1}, \mathbf{v}_{6} \rangle = m_{\text{crit}}^{1} \langle \mathbf{q}_{1}, \mathbf{v}_{6} \rangle \sim y^{1}.$$
(4.24)

Then combined with the growth specified by (4.21), we find that

$$z^{6}(\mathbf{Q}) \sim \hat{z}^{6}(\mathbf{q}_{0}) q^{6}(\mathbf{Q}) \sim (y^{1})^{-1}(y^{1}) \sim 1$$
 (4.25)

which thus provides us with a vector $\mathbf{z}(\mathbf{Q})$ whose component in the direction \mathbf{v}_6 is bounded in size from below, what suffices to argue that the axion WGC is not violated parametrically in this direction either.

In summary we have thus found, for every direction in V_{heavy} , a vector $\mathbf{z}(\mathbf{Q})$ by picking an appropriate instanton \mathbf{Q} out of (4.22), such that its component in that direction is bounded in size from below along this infinite distance limit. Therefore we found a set of vectors $\mathbf{z}(\mathbf{Q})$ that span a convex hull which will always contain a certain ball of finite size. From a physics perspective, this means that we have found that the axion WGC cannot be violated parametrically by considering axion decay constants that grow path-independently in this example, since we have showed that there always exists an appropriate instanton with decreasing action that couples to such axions. The fact that our tower has a critical size m_{crit} which increases parametrically was crucial for arguing that the WGC for axions cannot be violated parametrically. We will motivate this feature more generally in the next subsection, where it falls under case (2), and a demonstrative figure is also provided in figure 2.

From the discussion in 2.3 we know that the remaining one-parameter infinite distance limits are Type II and III limits, which turn out to be slightly less interesting than the Type IV infinite distance limit. Namely, the Type G charge vectors \mathbf{q}_0 , \mathbf{q}_1 that generate the states are located in the same eigenspace V_1 for a Type III limit, or V_2 for a Type II limit, as can be inferred from table 2. Furthermore, the Hodge norm on these eigenspaces V_1 and V_2 possesses the largest decrease out of all eigenspaces for the corresponding limits by use of the growth properties (2.32), since these eigenspaces have the lowest index.¹⁵ And since the decrease of the instanton action is determined by $\|\mathbf{q}_0\|$ via (4.17), we know that the growth of any axion decay constant will be matched or even exceeded by the decrease of the instanton action, using the duality between V_{heavy} , where the axion directions reside, and V_{light} , where the instanton charges reside. This tells us that none of the axion directions can violate the axion WGC parametrically in these examples either. Note in particular that we do not need the parametrical growth of m_{crit} to fulfill the WGC for axion directions that couple to \mathbf{q}_1 , because \mathbf{q}_1 lies in the same eigenspace as \mathbf{q}_0 , whereas it played a crucial role for the Type IV infinite distance limit.

¹⁵For Type III the non-empty eigenspaces are V_1, V_2, V_3, V_4, V_5 , and for Type II we have V_2, V_3, V_4 .

4.4 Strategy for general infinite distance limits

Here we argue that the axion WGC cannot be violated parametrically by the R-R axions under consideration for general infinite distance limits. In doing so, we will only need to use the reformulated expression for the charge vector (3.13) of the D2-brane instantons, together with some requirements on the growth rate of the size of the tower m_{crit} that we argued for in section 3.2. We can strategically analyze the axion directions $\mathbf{v}_{\underline{\ell}} \in V_{\text{heavy}}$ by breaking them down to the following four cases, where we have that:

- (1) $q^{\underline{\ell}}(\mathbf{Q}^{\mathrm{G}}(m_{I})) \neq 0$ for some m_{I} , and $\hat{z}^{\underline{\ell}}(\mathbf{q}_{0})$ is bounded from below;
- (2) $q^{\underline{\ell}}(\mathbf{Q}^{\mathrm{G}}(m_{I})) \neq 0$ for some m_{I} , and $\hat{z}^{\underline{\ell}}(\mathbf{q}_{0})$ unbounded from below;
- (3) $q^{\underline{\ell}}(\mathbf{Q}^{\mathrm{F}}(m_{\underline{s}})) \neq 0$ for some $m_{\underline{s}}$, and $\hat{z}^{\underline{\ell}}(\mathbf{q}_{0})$ is bounded from below;
- (4) $q^{\underline{\ell}}(\mathbf{Q}^{\mathrm{F}}(m_{\underline{s}})) \neq 0$ for some $m_{\underline{s}}$, and $\hat{z}^{\underline{\ell}}(\mathbf{q}_{0})$ unbounded from below.

The purpose of this separation of cases is to investigate how every axion direction $\mathbf{v}_{\ell} \in$ V_{heavy} can be coupled to one of the D2-brane instantons **Q** specified by (3.13) such that, provided we pick the right charges, the growth of this component $z^{\underline{\ell}}(\mathbf{Q}(\mathbf{q}_0|m_I,m_s))$ can be bounded from below. Namely, by showing that we can pick a vector $\mathbf{z}(\mathbf{Q})$ for every direction in V_{heavy} such that its component in that direction is bounded in size from below, we know that the associated convex hull must contain a ball of finite size. The first condition then indicates whether this axion couples to our tower of D2-brane instantons via one of their Type G charges or one of their Type F charges. This coupling can be ensured via the canonical duality (4.11) between V_{heavy} and V_{light} , since the Type F and Type G charge vectors of our D2-brane instantons together span the whole of V_{light} by construction (see section 3.1), such that we only need to pick the right combination of instanton charges. Therefore we are left with analyzing the growth rate of the vectors $\mathbf{z}(\mathbf{Q}(\mathbf{q}_0, m_I, m_s))$ in that direction, which is given by $z^{\underline{\ell}}(\mathbf{Q}(\mathbf{q}_0|m_I,m_s))$ in (4.21). Then we ther the growth of $\hat{z}^{\underline{\ell}}(\mathbf{q}_0)$ is bounded from below tells us directly if this component remains finite for all paths within the growth sector (2.9). However, the growth of $\hat{z}^{\underline{\ell}}(\mathbf{q}_0)$ is not necessarily bounded from below, such that there can be directions where the convex hull seems to shrink along the infinite distance limit. The fact that we still have to account for the possible parametrical growth of charge $q^{\underline{\ell}}(\mathbf{Q})$ in (4.21) will resolve this issue for cases (2) and (4). Below we examine these cases separately in more detail, such that we can argue that each of these cases does not violate the axion WGC parametrically.

Case (1). We have that $q^{\underline{\ell}}(\mathbf{Q}^{\mathrm{G}}(m_{I})) = \langle \mathbf{Q}^{\mathrm{G}}, \mathbf{v}_{\underline{\ell}} \rangle \neq 0$ for some m_{I} , so the axion direction couples to a Type G charge of our charge vector. Additionally, we know that the growth of $\hat{z}^{\underline{\ell}}(\mathbf{q}_{0})$ in (4.21) is bounded from below, such that the convex hull can envelop a ball of finite size in this direction, which indicates that these axions can therefore never violate the axion WGC parametrically. For example, the axion direction $N_{1}^{-}\tilde{\mathbf{a}}_{0} \in V_{4}$ in the one-parameter Type IV limit belonged to this case.

Case (2). This case seems to violate the axion WGC at first sight, since $\hat{z}^{\underline{\ell}}(\mathbf{q}_0)$ cannot be bounded from below, that is, $\hat{z}^{\underline{\ell}}(\mathbf{q}_0) \to 0$ for certain paths within the growth sector (2.9), which suggests that the convex hull can shrink in this direction as we move along the infinite distance limit, similar to the axion direction $\tilde{\mathbf{a}}_0 \in V_6$ we encountered in the one-parameter Type IV in section 4.3. However, we did not account for the charge of this instanton yet, which is given by¹⁶

$$q^{\underline{\ell}}(\mathbf{Q}^{\mathrm{G}}(m_{I})) = \langle \mathbf{Q}^{\mathrm{G}}(m_{I}), \mathbf{v}_{\underline{\ell}} \rangle = \sum_{I} m_{I} \langle \mathbf{q}_{I}, \mathbf{v}_{\underline{\ell}} \rangle.$$
(4.26)

We know that this axion must couple to a Type G charge, so we must have that $\langle \mathbf{q}_J, \mathbf{v}_{\underline{\ell}} \rangle \neq 0$ for some J, and thus $\mathbf{q}_J \in V_{\underline{6}-\underline{\ell}}$ by use of (2.25). Then increasing this m_J results in increasing the charge $q^{\underline{\ell}}(\mathbf{Q})$, such that if we pick $m_J = m_{\text{crit}}^J \sim ||\mathbf{q}_0||/||\mathbf{q}_J||$ following (3.25), we find

$$z^{\underline{\ell}}(\mathbf{Q}(\mathbf{q}|m_{\text{crit}}^{J})) \sim \hat{z}^{\underline{\ell}}(\mathbf{q}_{0}) m_{\text{crit}}^{J} \\ \sim \left(\frac{y^{1}}{y_{2}}\right)^{\frac{6-\ell_{1}-r_{1}}{2}} \cdots \left(\frac{y^{n-1}}{y^{n}}\right)^{\frac{6-\ell_{n-1}-r_{n-1}}{2}} (y^{n})^{\frac{6-\ell_{n}-r_{n}}{2}} \frac{\|\mathbf{q}_{0}\|}{\|\mathbf{q}_{J}\|}$$
 (4.27)
~ 1,

where we used that the growths of the norms of \mathbf{q}_0 and \mathbf{q}_J cancel the growth rate in front precisely, using that $\mathbf{q}_0 \in V_{\underline{r}}$ and $\mathbf{q}_J \in V_{\underline{6}-\underline{\ell}}$. Thus we found that the tower of D2-brane instantons grows at exactly the right rate to avoid parametrical violations of the WGC for these axion directions, since it allowed us to pick appropriate instanton charges such that the component of $\mathbf{z}(\mathbf{Q})$ in this direction is bounded in size from below, which indicates that the convex hull can envelop a ball of finite size in this direction. Note that this crucially relies on the growth of the instanton charge $q^{\underline{\ell}}(\mathbf{Q})$, which means that one cannot use only the smallest charge with respect to these axions. A depiction of this interplay between the growth of the tower and the convex hull condition of the axion WGC has been provided in figure 2.

Case (3). By picking the right Type F charges $m_{\underline{s}}$ we can ensure that such an axion direction couples to a D2-brane instanton \mathbf{Q} out of our tower (3.13), and the fact that $\hat{z}^{\underline{\ell}}(\mathbf{q}_0)$ is bounded from below then indicates that the convex hull can envelop a ball of finite size in this direction, which tells us that these axions cannot violate the WGC. As an example, in the one-parameter Type IV limit in 4.3 an axion direction $\mathbf{v}_4 \in V_4$ that does not couple to the Type G charge vector \mathbf{q}_0 falls under this case.

Case (4). We know that v_{ℓ} must couple to one of the Type F charge vectors via

$$q^{\underline{\ell}}(\mathbf{Q}^{\mathrm{F}}(m_{\underline{s}})) = \langle \mathbf{Q}^{\mathrm{F}}(m_{\underline{s}}), \mathbf{v}_{\underline{\ell}} \rangle = \sum_{i}' m^{i}_{\underline{6}-\underline{\ell}} \langle \mathbf{v}^{i}_{\underline{6}-\underline{\ell}}, \mathbf{v}_{\underline{\ell}} \rangle, \qquad (4.28)$$

¹⁶The fact that $\hat{z}^{\underline{\ell}}(\mathbf{q}_0)$ cannot be bounded from below indicates that $\|\mathbf{q}_0\| \|\mathbf{v}_{\underline{\ell}}\|$ can grow parametrically for certain paths, such that (2.32) tells us that the eigenspaces $V_{\underline{r}}, V_{\underline{\ell}}$ in which they reside are not dual to each other under the product $\langle \cdot, \cdot \rangle$. Therefore we must have $\langle \mathbf{q}_0, \mathbf{v}_{\underline{\ell}} \rangle = 0$ by use of orthogonality properties (2.25).

with the relevant Type F charge vectors given by $\mathbf{v}_{\underline{6}-\underline{\ell}}^i \in V_{\underline{6}-\underline{\ell}} \subset V_{\text{light}}$. However, we cannot bound $\hat{z}^{\underline{\ell}}(\mathbf{q}_0)$ from below, such that we can have $\hat{z}^{\underline{\ell}}(\mathbf{q}_0) \to 0$ for certain paths to the infinite distance limit. It indicates that the convex hull shrinks along these directions, and to avoid this we must pick $m_{\underline{6}-\underline{\ell}}^i \sim ||\mathbf{q}_0|| ||\mathbf{v}_{\underline{\ell}}||$, such that we do not have parametrical violations of the axion WGC, similar to case (2). In section 3.2 we argued that the upper bound m_{crit} for Type F charges increases at a sufficient rate to allow for such choices of Type F charge. We should note that this case did not occur in the one-parameter examples, but can occur in multi-parameter limits.

4.5 Axion WGC in two-parameter infinite distance limits

In this section we provide some examples to demonstrate the strategy outlined above. We go through all two-parameter infinite distance limits $t^1, t^2 \to i\infty$ and construct the relevant charge vectors. It should be stressed that in contrast to [23] we will not require the charge vector \mathbf{Q} to be in orbit-form. This allows us to address all possible enhancements and show a general result.

In the case of considering a limit $t^1, t^2 \to i\infty$ one has two log-monodromy matrices N_1, N_2 and hence one has two singularity types (2.16) associated to N_1 and $N_{(2)} = N_1 + N_2$ according to our discussion in section 2.3. Denoting these types by Type A and Type B, the two-parameter configurations are split into all possible enhancements Type A \rightarrow Type B. Going through all relevant cases we will determine the split (4.9) with V_{light} and V_{heavy} defined in (3.3) and (4.8). The various components are given as direct sums in the vector spaces $V_{\underline{\ell}} \equiv V_{\ell_1 \ell_2}$. By use of appendix A.2 we first give the dimensions of the $V_{\ell_1 \ell_2}$ and indicate the positions of the basis of Type G representatives $\mathbf{q}_0, \mathbf{q}_I$ in V_{light} , such that we can write the charge vectors in the formulation introduced in section 3.1. Then we consider each axion direction $v_{\ell_1\ell_2}$ that lies in a subspace $V_{\ell_1\ell_2}$ of V_{heavy} and identify the candidate D2-brane instanton that ensures that the axion WGC is not violated parametrically. In doing so, we employ the orthogonality properties (2.25) of the product $\langle \cdot, \cdot \rangle$ and the growth properties (2.32) for the $\mathfrak{sl}(2,\mathbb{C})$ -eigenspaces $V_{\ell_1\ell_2}$. Furthermore, we point out for each of these axion directions $\mathbf{v}_{\ell_1\ell_2}$ to which cases it belongs in the strategy outlined in the previous section. In particular, wether $\|\mathbf{v}_{\ell_1\ell_2}\|\|\mathbf{q}_0\|$ can grow unboundedly indicates directly, by use of (4.21), if the growth of $\hat{z}^{\ell_1\ell_2}(\mathbf{Q})$ is bounded from below, or if it is unbounded and we need to consider growth of instanton charges as well.

4.5.1 Enhancement $I_a \rightarrow IV_d$

Let us first consider the enhancement from type I_a to IV_d , which can occur for d = r + awith $r \ge 1$. Then $H^3(Y_3, \mathbb{R})$ decomposes as in table 4.

The charge vectors found in [23] can be reformulated as

$$\mathbf{Q}^{\mathrm{G}}(m_{1}) = \mathbf{q}_{0} + m_{1}\mathbf{q}_{1},$$

$$\mathbf{Q}^{\mathrm{F}}(m_{22}, m_{32}) = \sum_{i} m_{22}^{i}\mathbf{v}_{22}^{i} + \sum_{\mathbf{v}_{32}^{j} \neq \mathbf{q}_{0}} m_{32}^{j}\mathbf{v}_{32}^{j}$$
(4.29)

with the basis of representatives for the Type G charges given by

$$\mathbf{q}_0 = (N_2^-)^2 \tilde{\mathbf{a}}_0 \in V_{32}, \qquad \mathbf{q}_1 = (N_2^-)^3 \tilde{\mathbf{a}}_0 \in V_{30}.$$
 (4.30)

space	decomposition	dimensions
$V_{ m light}$	$V_{30}\oplus V_{22}\oplus V_{32}$	1 + a + r
$V_{ m heavy}$	$V_{36}\oplus V_{44}\oplus V_{34}$	1 + a + r
$V_{\rm rest}$	V_{33}	$2(h^{2,1}-a-r)$

Table 4. Decomposition of $H^3(Y_3, \mathbb{R})$ for $I_a \to IV_d$. Note again that we use colors to indicate the dimensions of individual subspaces.

space	decomposition	dimensions
$V_{ m light}$	$V_{20}\oplus V_{22}\oplus V_{32}$	1 + b + r - 1
$V_{ m heavy}$	$V_{46}\oplus V_{44}\oplus V_{34}$	1 + b + r - 1
$V_{\rm rest}$	$V_{42}\oplus V_{33}\oplus V_{24}$	$1 + 2(h^{2,1} - b - r) + 1$

Table 5. Decomposition of $H^3(Y_3, \mathbb{R})$ for $II_b \to IV_d$.

Now let us go systematically through axion directions for each of the subspaces of V_{heavy} :

- The axion direction $\mathbf{v}_{44} \in V_{44}$ must couple to some Type F charge vector \mathbf{v}_{22}^{j} . For certain paths we can have that $\|\mathbf{v}_{44}\|\|\mathbf{q}_{0}\|$ can grow unboundedly, which means that we must require $m_{22}^{i} \sim \|\mathbf{q}_{0}\|\|\mathbf{v}_{44}\|$ such that we do not violate the WGC for axions parametrically. These axion directions belong to case (4).
- The axion direction $\mathbf{v}_{36} \in V_{36}$ couples to the Type G charge vector \mathbf{q}_1 , thus we must pick $m_1 \neq 0$ such that it couples to the D2-brane instanton. Furthermore we have that $\|\mathbf{v}_{36}\|\|\mathbf{q}_0\|$ grows unboundedly, which indicates that we must pick $m_1 = m_{\text{crit}}^1 \sim$ $\|\mathbf{q}_0\|/\|\mathbf{q}_1\|$ to avoid parametrical violations of the axion WGC. This axion direction belongs therefore to case (2).
- The axion direction v₃₄ ∈ V₃₄ can couple to either the Type G charge vector q₀ or some other Type F charge vector vⁱ₃₂. For both cases we have that the growth of ||q₀|| ||v₃₄|| is bounded, so we cannot have a parametrical violation of the axion WGC. If it couples to q₀ this axion belongs to case (1), whereas if it couples to some other vⁱ₃₂ we must pick mⁱ₃₂ ≠ 0, and thus it belongs to case (3).

4.5.2 Enhancement $II_b \rightarrow IV_d$

This type of enhancement from Type II_b to IV_d can occur if we have d = r + b with $r \ge 1$. The vector spaces V_{light} , V_{heavy} and V_{rest} can be decomposed as in table 5.

The charge vectors found in [23] can be reformulated as

$$\mathbf{Q}^{\rm G}(m_1) = \mathbf{q}_0 + m_1 \mathbf{q}_1, \mathbf{Q}^{\rm F}(m_{32}^i, m_{22}^j) = \sum_i m_{32}^i \mathbf{v}_{32}^i + \sum_{\mathbf{v}_{22}^j \neq \mathbf{q}_0} m_{22}^j \mathbf{v}_{22}^j$$
(4.31)

space	decomposition	dimensions
$V_{ m light}$	$V_{10} \oplus V_{12} \oplus V_{22} \oplus V_{32}$	1 + 1 + c + (r + 1)
$V_{\rm heavy}$	$V_{56} \oplus V_{54} \oplus V_{44} \oplus V_{34}$	1+1+c+(r+1)
$V_{ m rest}$	V_{33}	$2(h^{2,1}-c-r-2)$

Table 6. Decomposition of $H^3(Y_3, \mathbb{R})$ for $III_c \to IV_d$.

with the basis of representatives for the Type G charges given by

$$\mathbf{q}_0 = N_1^- N_2^- \tilde{\mathbf{a}}_0 \in V_{22}, \qquad \mathbf{q}_1 = N_1^- (N_2^-)^2 \tilde{\mathbf{a}}_0 \in V_{20}.$$
 (4.32)

Let us go through each of the subspaces of V_{heavy} systematically:

- For $\mathbf{v}_{46} \in V_{46}$ we know that it couples to the Type G charge vector \mathbf{q}_1 from orthogonality conditions, since V_{20}, V_{46} are dual one-dimensional vector spaces. We also know that $\|\mathbf{v}_{46}\|\|\mathbf{q}_0\|$ can grow unboundedly, and that we therefore must pick $m_1 = m_{\text{crit}}^1 \sim \|\mathbf{v}_{46}\|\|\mathbf{q}_0\|$. Thus this axion direction belongs to case (2).
- For $\mathbf{v}_{44} \in V_{44}$ we can have that it couples either to the Type G charge vector \mathbf{q}_0 or to some other Type F charge vector \mathbf{v}_{22}^j . Either way the growth rates of $\|\mathbf{q}_0\|$ and $\|\mathbf{v}_{44}\|$ cancel each other. In the first case we have that it couples to Type G charge and thus belongs to (1), and in the other case it couples to Type F charge and thus belongs to (3).
- For $\mathbf{v}_{34} \in V_{34}$ we know that it couples to some Type F charge vector \mathbf{v}_{32}^i , and that the growth rates of $\|\mathbf{v}_{34}\|$ and $\|\mathbf{q}_0\|$ cancel each other. Therefore these axion directions belong to case (3).

4.5.3 Enhancement $III_c \rightarrow IV_d$

The enhancement from type III_c to IV_d can occur if we have d = r + c + 2 and $r \ge 0$. The vector spaces can then be decomposed as listed in table 6.

The charge vectors can be given by

$$\mathbf{Q}^{\rm G}(m_1, m_2) = \mathbf{q}_0 + m_1 \mathbf{q}_1 + m_2 \mathbf{q}_2 , \mathbf{Q}^{\rm F}(m_{32}^i, m_{22}^j) = \sum_{\alpha_{22}} m_{22}^j \mathbf{v}_{22}^j + \sum_{\mathbf{v}_{32}^i \neq \mathbf{q}_0} m_{32}^i \mathbf{v}_{32}^i ,$$
(4.33)

with the basis of representatives for the Type G charges given by

$$\mathbf{q}_0 = N_1^- N_2^- \tilde{\mathbf{a}}_0 \in V_{32}, \qquad \mathbf{q}_1 = (N_1^-)^2 \tilde{\mathbf{a}}_0 \in V_{12}, \qquad \mathbf{q}_2 = N_2^- (N_1^-)^2 \tilde{\mathbf{a}}_0 \in V_{10}.$$
(4.34)

Note that these charge vectors \mathbf{Q}^{G} differ from the ones found in [23]. There they generated the tower by acting with $e^{N_{2}^{-}}$ on \mathbf{q}_{1} , such that only $\mathbf{q}_{1}, \mathbf{q}_{2}$ were used to span the charges of the states. A non-zero component for \mathbf{Q} in the direction \mathbf{q}_{0} will be necessary to couple certain axion directions in V_{34} to the tower of D2-brane instantons.

space	decomposition	dimensions
$V_{ m light}$	$V_{21}\oplus V_{22}\oplus V_{32}$	2 + (b - 2) + r
$V_{ m heavy}$	$V_{45}\oplus V_{44}\oplus V_{34}$	2 + (b - 2) + r
$V_{\rm rest}$	$V_{43}\oplus V_{33}\oplus V_{23}$	$2 + 2(h^{2,1} - b - r - 1) + 2$

Table 7. Decomposition of $H^3(Y_3, \mathbb{R})$ for $II_b \to III_c$.

Now let us go through each of the subspaces of V_{heavy} :

- For $\mathbf{v}_{56} \in V_{56}$ we know that the axion couples to the Type G charge \mathbf{q}_2 . We can increase $m_2 = m_{\text{crit}}^2 \sim ||\mathbf{q}_0|| ||\mathbf{v}_{56}||$, such that we cancel the growth of $||\mathbf{q}_0|| ||\mathbf{v}_{56}||$. This axion direction belongs therefore to case (2).
- For $\mathbf{v}_{54} \in V_{54}$ we know that it couples to the Type G charge \mathbf{q}_1 from orthogonality conditions. Again we have that $\|\mathbf{q}_0\| \|\mathbf{v}_{54}\|$ can grow unboundedly, thus we must increase $m_1 = m_{\text{crit}}^1 \sim \|\mathbf{q}_0\| \|\mathbf{v}_{54}\|$ to cancel this growth. Therefore this axion direction belongs to case (2) as well.
- For $\mathbf{v}_{44} \in V_{44}$ we have that it couples to some Type F charge \mathbf{v}_{22}^j . The growth rate of $\|\mathbf{v}_{44}\|$ can exceed the growth of $\|\mathbf{q}_0\|$. We must therefore increase $m_{22}^j \sim \|\mathbf{v}_{44}\| \|\mathbf{q}_0\|$. This tells us that these axion directions belong to case (4).
- For $\mathbf{v}_{34} \in V_{34}$ we can have that it either couples to the Type G charge \mathbf{q}_0 or to some other Type F charge \mathbf{v}_{32}^i . For both cases we have that $\|\mathbf{v}_{34}\|\|\mathbf{q}_0\|$ is bounded. If it couples to \mathbf{q}_0 it belongs to case (1), whereas if it couples to some \mathbf{v}_{32}^i we must pick $m_{32}^i \neq 0$ and it belongs to case (3).

4.5.4 Enhancement $II_b \rightarrow III_c$

The enhancement Type II_b to Type III_c can occur if we have c = b + r - 2 and $r \ge 0$. The vector spaces are then decomposed as in table 7.

Here we consider charge vectors different from [23], given by

$$\mathbf{Q}^{\rm G}(m_1) = \mathbf{q}_0 + m_1 \mathbf{q}_1, \mathbf{Q}^{\rm F}(m_{32}^i, m_{22}^j) = \sum_j m_{22}^j \mathbf{v}_{22}^j + \sum_i m_{32}^i \mathbf{v}_{32}^i,$$
(4.35)

and the basis for the representatives for the Type G charges can be given by

$$\mathbf{q}_0 = N_1^- N_2^- \operatorname{Re} \tilde{\mathbf{a}}_0 \in V_{21}, \qquad \mathbf{q}_1 = N_1^- N_2^- \operatorname{Im} \tilde{\mathbf{a}}_0 \in V_{21}.$$
 (4.36)

Then let us go through each of the subspaces of V_{heavy} for the axion directions:

• The axion direction $\mathbf{v}_{45} \in V_{45}$ can couple to Type G charge vectors \mathbf{q}_0 and \mathbf{q}_1 . In both cases the growth of $\|\mathbf{v}_{45}\|$ is matched by the decrease of $\|\mathbf{q}_0\|$. These axion directions therefore belong to case (1).

- The axion direction $\mathbf{v}_{44} \in V_{44}$ couples to some Type F charge \mathbf{v}_{22}^j . The growth rate of $\|\mathbf{v}_{44}\|$ can never exceed the decrease of $\|\mathbf{q}_0\|$, and thus we can just pick $m_{22}^j \neq 0$. Therefore these axion directions belong to case (3).
- The axion direction $\mathbf{v}_{34} \in V_{34}$ couples to a Type F charge vector \mathbf{v}_{32}^i . We have that the growth of $\|\mathbf{v}_{34}\|$ never exceeds the decrease of $\|\mathbf{q}_0\|$. Thus we pick $m_{32}^i \neq 0$ and therefore such axion directions belong to case (3).

5 Conclusions

In this paper we studied the axion Weak Gravity Conjecture for asymptotic regimes in field space that are at infinite geodesic distance. Specifically we focused on the axions arising from the R-R three-forms in Type IIA string theory compactified on a Calabi-Yau threefold. The kinetic terms of these axions depend non-trivially on the complex structure moduli of the threefold, but we showed the this dependence can be made explicit in asymptotic regimes that are at infinite geodesic distance. The infinite distance points in general Calabi-Yau threefold moduli spaces that are obtained by sending any number of coordinates to a limit can be classified [23, 49]. We have shown that the data characterizing a limit can also be used to group the axions into subsets, with each subset having a kinetic term with a common growth behaviour. We then focused on the axions that have growing kinetic terms for any path, in a growth sector of the form (2.9), and hence growing axion decay constants. In order that these do not violate the axion Weak Gravity Conjecture, instantons have to become relevant with actions decreasing with the inverse rate when approaching the infinite distance point. By using recent insights about the SDC [15, 23], we have argued that one can always find such instantons, since an infinite number of candidate D2-brane states has vanishing action at the infinite distance point. In order to address the axion WGC for multiple axions, we have constructed a set of vectors $\mathbf{z}(\mathbf{Q})$ that depend on the axion decay constants, the instanton action, and instanton charge. Here it was crucial to introduce appropriate charge vectors $\mathbf{Q}(\mathbf{q}_0|m)$ in (3.13) such that these instantons actually correct the effective theory. These instantons will form only a subsector of the set of D2brane instantons becoming relevant along the infinite distance limits, since in general there are more instantons whose action becomes small in these regimes. The convex hull of such vectors should contain the unit ball, in order that the axion WGC is satisfied. We stress that this statement does not have to be true for the smallest charge coupling the instanton to the axion. Indeed we have shown that there are many infinite distance limits in moduli space, namely the limits that contain type IV enhancements, for which the convex hull of the $\mathbf{z}(\mathbf{Q})$ cannot contain a unit ball if one considers the smallest instanton charge. The emerging picture is, however, compelling: the closer we approach such infinite distance points the higher the instanton charge of the instanton relevant in (4.3) has to be. We have depicted this result in figure 2. This implies that actually an ever increasing tower of instanton states becomes relevant when approaching the infinite distance point. Clearly, such a picture is reminiscent of the SDC where an increasing tower of particles needs to be included in the effective theory. It is interesting that our findings can also be viewed as providing evidence



Figure 2. Depiction of the convex hull spanned by the vectors $\pm \mathbf{z}(\mathbf{Q}(0))$ and $\pm \mathbf{z}(\mathbf{Q}(m_{\text{crit}}))$, which correspond to the lowest and highest instanton in our tower respectively. Note that we explicitly depicted the steps that we go through as we move up in this tower of instantons. As we move further along the infinite distance limit, we find that these steps become smaller and smaller, which is compensated by the fact that our tower of instantons is becoming larger, such that the total length of this side of the convex hull remains finite and thus that the convex hull will always contain a ball of finite size.

for the strong axion WGC, if the charge vectors $\mathbf{Q}(\mathbf{q}_0|\underline{m})$ are indeed describing the lightest stable states relevant for the SDC. The instanton actions for all charges $\mathbf{Q}(\mathbf{q}_0|\underline{m})$ have the same leading growth determined by \mathbf{q}_0 and are thus equally relevant in the effective theory. It would be very interesting to explore this further and, in particular, clarify the role of individual Type G and Type F states that are not of the form $\mathbf{Q}(\mathbf{q}_0|\underline{m})$.

In our analysis of the D2-brane instantons it was crucial to collect information about D-brane states with asymptotically vanishing actions. We started our considerations by asserting that these states are BPS and their action can be determined by evaluating the central charge. Furthermore, at least for a certain large class of possible limits, it was essential to argue how the number of stable states changes when approaching the infinite distance point. In order to do that we generalized the stability argument of [15] to multiple variables. More precisely, we derived a maximal growth of the tower of states that are stable when approaching the infinite distance point by ensuring the absence of decays of these states. Our stability arguments apply to situations in which one can identify a charge vector \mathbf{q}_0 that has a distinguished slowest decrease of the associated central charge. Such an identification was also important in the construction of the charge orbits of [23] to which our results naturally apply. It is important to stress, however, that even if the instanton charges do not take the form of a charge orbit our findings suffice to provide general evidence that the axion WGC is not parametrically violated. It should be clear that our findings cannot be conclusive when it comes to checking the BPS properties of D-brane states. It would be interesting to explore these issues further and, in particular, study stability at limits in moduli space that do not allow for a local construction of a charge orbits. A potential avenue was suggested in [23], and exemplified in [27], in which charge orbits were transferred along the moduli space.

Our results were obtained in full generality for any infinite distance limit in complex structure moduli space and hence do not apply to only a specific example or a class of examples. This was achieved by using the powerful mathematical machinery of [66, 67], which describes so-called limiting mixed Hodge structures. One of the central results of these papers is the introduction of n commuting $\mathfrak{sl}(2, \mathbb{C})$ -algebras associated to an infinite distance locus obtained by sending n coordinates to a limit. These algebras act on the vector space $H^3(Y_3, \mathbb{C})$ and induce a canonical splitting of $H^3(Y_3, \mathbb{R})$, which we argued to be crucial in studying the axion kinetic terms. The $\mathfrak{sl}(2, \mathbb{C})$ -data arises from log-monodromy matrices N_i , the limiting period vector \mathbf{a}_0 , and the growth sector (2.9) associated to the path along which one takes the limit. We believe that this approach will be fruitful in many further applications [84]. However, it should be stressed that it is particularly powerful when it comes to estimates, such as the ones encountered for the axion WGC. This can be traced back to the fact that the asymptotic behaviour of periods Π can be bounded by using the $\mathfrak{sl}(2, \mathbb{C})$ structure, but the corrections are only under parametric control. It would be very interesting to systematically classify the corrections arising in the link of Π to the $\mathfrak{sl}(2, \mathbb{C})$ -structure.

This leaves us to close with highlighting further interesting open problems for future projects. A first direction is to address the generalization of our considerations to any path in complex structure moduli space and hypermultiplet moduli space. On the one hand, this would require to go beyond the growth sector description presented here. On the other hand, it would also amount to consider paths in which one sends the four-dimensional dilaton e^D to a limit. Satisfying the axion WGC then requires to consider more general D-brane configurations as very recently also discussed in [31-33]. We stress that it is an interesting and challenging task to unify the mathematical structure presented here, with the general insights about the hypermultiplet moduli space [34, 35]. A second open question is to address the issue of emergence in hypermultiplet moduli space. More precisely, it was suggested in [15], that infinite distances in moduli space could be emergent from integrating out the infinite tower of states relevant to the SDC. Furthermore, it was very recently argued in [31] that in certain situations the inclusion of D-instanton corrections into the moduli space metric can render formerly infinite distance points to lie at finite distance. It would be interesting to check if this is indeed true for all infinite distance limits investigated here. Studying how these non-perturbative corrections alter the behavior of the axion decay constants would be interesting as well, especially in the context of the axion WGC. We expect that such corrections indeed change their asymptotic behavior, and believe this results in slower growth of the decay constants along the infinite distance limits. Finally, let us close with the rather obvious statement that we did not check the precise numerical constraint suggested by the axion WGC. While the introduced mathematical machinery gives bounds on the relevant quantities, the appearing numerical coefficients are not further constraint. While they can be derived in explicit examples, it would be very exciting to check if there are general constraints arising from geometry.

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A Derivation of eigenspaces for infinite distance limits

In this appendix we decompose the eigenspaces $V_{\underline{\ell}}$ in the primitive subspaces $P^{p,q}(N_{(k)})$ for one- and two-parameter infinite distance limits, including their dimensions. We make the location of the vectors that follow from $\tilde{\mathbf{a}}_0 \in P^{3,d_n}(N_{(n)}^-)$ explicit,¹⁷ because of their importance in constructing Type G charge vectors in sections 3 and 4. These results can be argued from the Hodge-Deligne diamonds in each step of the enhancement chain, which were given in [23]. We explain this procedure for the one- and two-parameter infinite distance limits separately. Note that the $V_{\underline{\ell}}$ given in this appendix are the complexifications of the vector spaces used in the main text.

A.1 Eigenspaces V_{ℓ} for one-parameter infinite distance limits

Here we give the decomposition and the dimension of the eigenspaces V_{ℓ} for all types of oneparameter infinite distance limits considered in section 3. The content of these spaces can be read off from the rows of the Hodge-Deligne diamond which were given in [15, 23], with the index of the row indicating the subscript ℓ . This follows from the fact that elements of the same row have the same eigenvalue under the generator Y_1 of the $\mathfrak{sl}(2, \mathbb{C})$ -triple.

A.1.1 Type I_a

For a Type I_a infinite distance limit the eigenspaces V_{ℓ} and their dimensions are given by

$$V_4 = P^{2,2}(N_1^-), \qquad \dim V_4 = a,$$

$$V_3 = P^3(N_1^-), \qquad \dim V_3 = 2(a'+1), \qquad (A.1)$$

$$V_2 = N_1^- P^{2,2}(N_1^-), \qquad \dim V_2 = a.$$

Note that $\tilde{\mathbf{a}}_0 \in P^{3,0}(N_1^-) \subseteq P^3(N_1^-)$.

A.1.2 Type II_b

For a Type II_b infinite distance limit the eigenspaces V_{ℓ} and their dimensions are given by

$$V_{4} = \operatorname{span}_{\mathbb{C}} \{ \tilde{\mathbf{a}}_{0}, \bar{\tilde{\mathbf{a}}}_{0} \} \oplus P^{2,2}(N_{1}^{-}), \qquad \dim V_{4} = b + 2, V_{3} = P^{3}(N_{1}^{-}), \qquad \dim V_{3} = 2b', \qquad (A.2)$$
$$V_{2} = \operatorname{span}_{\mathbb{C}} \{ N_{1}^{-} \tilde{\mathbf{a}}_{0}, N_{1}^{-} \bar{\tilde{\mathbf{a}}}_{0} \} \oplus N_{1}^{-} P^{2,2}(N_{1}^{-}), \qquad \dim V_{2} = b + 2.$$

Note that $\tilde{\mathbf{a}}_0 \in P^{3,1}(N_1^-) \subseteq P^4(N_1^-).$

¹⁷Recall that $d_n = 0, 1, 2, 3$ for an *n*-parameter Type I_a, II_b, III_c or IV_d infinite distance limit respectively.

A.1.3 Type III_c

For a Type III_c infinite distance limit the eigenspaces V_{ℓ} and their dimensions are given by

$$V_{5} = \operatorname{span}_{\mathbb{C}}\{\tilde{\mathbf{a}}_{0}, \tilde{\bar{\mathbf{a}}}_{0}\}, \qquad \dim V_{5} = 2, V_{4} = P^{2,2}(N_{1}^{-}), \qquad \dim V_{4} = c, V_{3} = \operatorname{span}_{\mathbb{C}}\{N_{1}^{-}\tilde{\mathbf{a}}_{0}, N_{1}^{-}\tilde{\bar{\mathbf{a}}}_{0}\} \oplus P^{3}(N_{1}^{-}), \qquad \dim V_{3} = 2(c'+1), \qquad (A.3) V_{2} = N_{1}^{-}P^{2,2}(N_{1}^{-}), \qquad \dim V_{2} = c, V_{1} = \operatorname{span}_{\mathbb{C}}\{(N_{1}^{-})^{2}\tilde{\mathbf{a}}_{0}, (N_{1}^{-})^{2}\tilde{\bar{\mathbf{a}}}_{0}\}, \qquad \dim V_{1} = 2.$$

Note that $\tilde{\mathbf{a}}_0 \in P^{3,2}(N_1^-) \subseteq P^5(N_1^-)$.

A.1.4 Type IV_d

For a Type IV_d infinite distance limit the eigenspaces V_{ℓ} and their dimensions are given by

$$V_{6} = \operatorname{span}_{\mathbb{C}}\{\tilde{\mathbf{a}}_{0}\}, \qquad \dim V_{6} = 1, V_{4} = \operatorname{span}_{\mathbb{C}}\{N_{1}^{-}\tilde{\mathbf{a}}_{0}\} \oplus P^{2,2}(N_{1}^{-}), \qquad \dim V_{4} = d + 1, V_{3} = P^{3}(N_{1}^{-}), \qquad \dim V_{3} = 2d', \qquad (A.4) V_{2} = \operatorname{span}_{\mathbb{C}}\{(N_{1}^{-})^{2}\tilde{\mathbf{a}}_{0}\} \oplus N_{1}^{-}P^{2,2}(N_{1}^{-}), \qquad \dim V_{2} = d + 1, V_{0} = \operatorname{span}_{\mathbb{C}}\{(N_{1}^{-})^{3}\tilde{\mathbf{a}}_{0}\}, \qquad \dim V_{0} = 1.$$

Note that $\tilde{\mathbf{a}}_0 \in P^{3,3}(N_1^-) \subseteq P^6(N_1^-)$.

A.2 Eigenspaces $V_{\ell_1\ell_2}$ for two-parameter infinite distance limits

Here we give the spaces $V_{\ell_1\ell_2}$ for the two-parameter infinite distance limits considered in section 4.5. Let us first shortly explain the procedure used to derive these spaces $V_{\ell_1\ell_2}$, which uses the Hodge-Deligne diamonds considered in [23]. We start with the Hodge-Deligne diamond induced by N_1^- . This diamond can be split up into components $(N_1^-)^a P^b(N_1^-)$, with $P^b(N_1^-)$ the primitive vector space of weight *b* associated with N_1^- . The row to which this component belongs determines the number $\ell_1 = b - 2a$, similar to the one-parameter infinite distance limits. Then N_2^- induces a mixed Hodge structure on these components $(N_1^-)^a P^b(N_1^-)$ individually. In practice, this means that $(N_1^-)^a P^b(N_1^-)$ is split up into further pieces, and each piece belongs to a specific point in the Hodge-Deligne diamond induced by $N_{(2)}^-$. Then we can determine ℓ_2 from the row at which this piece ends up in the Hodge-Deligne diamond induced by $N_{(2)}^-$.

A.2.1 Enhancement $I_a \rightarrow IV_d$

Here we consider the enhancement of a Type I_a infinite distance limit to a Type IV_d infinite distance limit by sending an additional coordinate to infinity, i.e. $y^2 \to \infty$. The decompositions and dimensions of the eigenspaces $V_{\ell_1\ell_2}$ are then given by

$$V_{44} = P^{2,2}(N_1^-), \qquad \dim(V_{44}) = a, V_{36} = \operatorname{span}_{\mathbb{C}}\{\tilde{\mathbf{a}}_0\}, \qquad \dim(V_{36}) = 1,$$

$$V_{34} = \operatorname{span}_{\mathbb{C}} \{ N_2^- \tilde{\mathbf{a}}_0 \} \oplus \left(P^3(N_1^-) \cap P^{2,2}(N_{(2)}^-) \right), \quad \dim(V_{34}) = r, \\ V_{33} = P^3(N_{(2)}^-), \quad \dim(V_{33}) = 2(a'-r), \quad (A.5) \\ V_{32} = \operatorname{span}_{\mathbb{C}} \{ (N_2^-)^2 \tilde{\mathbf{a}}_0 \} \oplus N_2^- \left(P^3(N_1^-) \cap P^{2,2}(N_{(2)}^-) \right), \quad \dim(V_{32}) = r, \\ V_{30} = \operatorname{span}_{\mathbb{C}} \{ (N_2^-)^3 \tilde{\mathbf{a}}_0 \}, \quad \dim(V_{30}) = 1, \\ V_{22} = N_1^- P^{2,2}(N_1^-), \quad \dim(V_{22}) = a. \end{cases}$$

Note that $\tilde{\mathbf{a}}_0 \in P^{3,3}(N_{(2)}^-)$.

A.2.2 Enhancement $II_b \rightarrow IV_d$

Here we consider the enhancement of a Type II_b infinite distance limit to a Type IV_d infinite distance limit. The decompositions and dimensions of the eigenspaces $V_{\ell_1\ell_2}$ are then given by

$$\begin{split} V_{46} &= \operatorname{span}_{\mathbb{C}} \{ \tilde{\mathbf{a}}_0 \}, & \operatorname{dim}(V_{46}) = 1, \\ V_{44} &= \operatorname{span}_{\mathbb{C}} \{ N_2^- \tilde{\mathbf{a}}_0 \} \oplus \left(P^{2,2}(N_1^-) \cap P^{2,2}(N_{(2)}^-) \right), & \operatorname{dim}(V_{44}) = b, \\ V_{42} &= \operatorname{span}_{\mathbb{C}} \{ (N_2^-)^2 \tilde{\mathbf{a}}_0 \}, & \operatorname{dim}(V_{42}) = 1, \\ V_{34} &= P^3(N_1^-) \cap P^{2,2}(N_{(2)}^-), & \operatorname{dim}(V_{34}) = r - 1, \\ V_{33} &= P^3(N_{(2)}^-), & \operatorname{dim}(V_{33}) = 2(b' - r + 1), & (A.6) \\ V_{32} &= N_2^- \left(P^3(N_1^-) \cap P^{2,2}(N_{(2)}^-) \right), & \operatorname{dim}(V_{32}) = r - 1, \\ V_{24} &= \operatorname{span}_{\mathbb{C}} \{ N_1^- \tilde{\mathbf{a}}_0 \}, & \operatorname{dim}(V_{24}) = 1, \\ V_{22} &= \operatorname{span}_{\mathbb{C}} \{ N_1^- N_2^- \tilde{\mathbf{a}}_0 \} & \\ &\oplus N_1^- N_2^- \left(P^{2,2}(N_1^-) \cap P^{2,2}(N_{(2)}^-) \right), & \operatorname{dim}(V_{22}) = b, \\ V_{20} &= \operatorname{span}_{\mathbb{C}} \{ (N_1^- (N_2^-)^2 \tilde{\mathbf{a}}_0 \}, & \operatorname{dim}(V_{33}) = 1. \end{split}$$

Note that $\tilde{\mathbf{a}}_0 \in P^{3,3}(N_{(2)}^-)$.

A.2.3 Enhancement $III_c \rightarrow IV_d$

Here we consider the enhancement of a Type III_c infinite distance limit to a Type IV_d infinite distance limit. The decompositions and dimensions of the eigenspaces $V_{\ell_1\ell_2}$ are then given by

$$\begin{split} V_{56} &= \operatorname{span}_{\mathbb{C}} \{ \tilde{\mathbf{a}}_0 \}, & \operatorname{dim}(V_{56}) = 1, \\ V_{54} &= \operatorname{span}_{\mathbb{C}} \{ N_2^- \tilde{\mathbf{a}}_0 \}, & \operatorname{dim}(V_{54}) = 1, \\ V_{44} &= P^{2,2}(N_1^-), & \operatorname{dim}(V_{44}) = c, \\ V_{34} &= \left(P^3(N_1^-) \cap P^{2,2}(N_{(2)}^-) \right) \oplus \operatorname{span}_{\mathbb{C}} \{ N_1^- \tilde{\mathbf{a}}_0 \}, & \operatorname{dim}(V_{34}) = r+1, \\ V_{33} &= P^3(N_{(2)}^-), & \operatorname{dim}(V_{33}) = 2(c'-r-1), & (A.7) \\ V_{32} &= N_2^- \left(P^3(N_1^-) \cap P^{2,2}(N_{(2)}^-) \right) \oplus \operatorname{span}_{\mathbb{C}} \{ N_1^- N_2^- \tilde{\mathbf{a}}_0 \}, & \operatorname{dim}(V_{32}) = r+1, \end{split}$$

$V_{22} = N_1^- P^{2,2}(N_1^-), \qquad d$	$\operatorname{im}(V_{33}) = c,$
$V_{12} = \operatorname{span}_{\mathbb{C}}\{(N_1^-)^2 \tilde{\mathbf{a}}_0\},$ d	$\operatorname{im}(V_{12}) = 1,$
$V_{10} = \operatorname{span}_{\mathbb{C}} \{ N_2^- (N_1^-)^2 \tilde{\mathbf{a}}_0 \} $ d	$\operatorname{im}(V_{10}) = 1.$

Note that $\tilde{\mathbf{a}}_0 \in P^{3,3}(N_{(2)}^-)$.

A.2.4 Enhancement $II_b \rightarrow III_c$

Here we consider the enhancement of a Type II_b infinite distance limit to a Type III_c infinite distance limit. The decompositions and dimensions of the eigenspaces $V_{\ell_1\ell_2}$ are then given by

$$\begin{aligned} V_{45} &= \operatorname{span}_{\mathbb{C}} \{ \tilde{\mathbf{a}}_{0}, \tilde{\mathbf{a}}_{0} \}, & \operatorname{dim}(V_{45}) = 2, \\ V_{44} &= P^{2,2}(N_{1}^{-}), & \operatorname{dim}(V_{44}) = b - 2, \\ V_{43} &= \operatorname{span}_{\mathbb{C}} \{ N_{2}^{-} \tilde{\mathbf{a}}_{0}, N_{2}^{-} \tilde{\bar{\mathbf{a}}}_{0} \}, & \operatorname{dim}(V_{43}) = 2, \\ V_{34} &= P^{3}(N_{1}^{-}) \cap P^{2,2}(N_{(2)}^{-}), & \operatorname{dim}(V_{34}) = r, \\ V_{33} &= P^{3}(N_{(2)}^{-}), & \operatorname{dim}(V_{33}) = 2(b' - r), & (A.8) \\ V_{32} &= N_{2}^{-} \left(P^{3}(N_{1}^{-}) \cap P^{2,2}(N_{(2)}^{-}) \right), & \operatorname{dim}(V_{32}) = r, \\ V_{23} &= \operatorname{span}_{\mathbb{C}} \{ N_{1}^{-} \tilde{\mathbf{a}}_{0}, N_{1}^{-} \tilde{\bar{\mathbf{a}}}_{0} \}, & \operatorname{dim}(V_{23}) = 2, \\ V_{22} &= N_{1}^{-} P^{2,2}(N_{1}^{-}), & \operatorname{dim}(V_{22}) = b - 2, \\ V_{21} &= \operatorname{span}_{\mathbb{C}} \{ N_{1}^{-} N_{2}^{-} \tilde{\mathbf{a}}_{0}, N_{1}^{-} N_{2}^{-} \tilde{\bar{\mathbf{a}}}_{0} \}, & \operatorname{dim}(V_{33}) = 2. \end{aligned}$$

Note that $\tilde{\mathbf{a}}_0 \in P^{3,2}(N_{(2)}^-)$.

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