# A covariantisation of M5-brane action in dual formulation 

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#### Abstract

We construct a manifestly diffeomorphic M5-brane action in dual formulation coupled to an eleven-dimensional supergravity target space. The covariantisation is carried out by using (generalised) PST technique with 5 auxiliary scalar fields, which are obtained by using a geometrical consideration as a reduction of an auxiliary 4 -form of Maznytsia-Preitschopf-Sorokin. As is typical in PST-covariantised theory, our construction possesses as usual the two local PST symmetries. By using one of the local PST symmetries, the action can be reduced to the non-manifestly covariant M5-brane action in dual formulation constructed earlier by the authors. The discussion on double dimensional reduction to D4-brane, and on the comparison of on-shell action then easily follows.


Keywords: D-branes, Gauge Symmetry, Global Symmetries, M-Theory

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## 1 Introduction

On a quest to construct an M5-brane action in the literature, one of the important obstacles is related to a certain field content of an M5-brane - a chiral 2-form field, i.e. a 2 -form gauge field with non-linear self-dual 3 -form field strength. The obstacle is evident on the theory of a chiral 2 -form field by itself, or more generally on the theory of a chiral $p$-form in $(2 p+2)$ dimensions for even $p$. On these theories, it is non-trivial to impose the Lorentz invariance and the self-duality together at the action level. As a related issue, at the linear level, self-duality conditions are first order differential equations, which are not obtainable via a standard consideration from a quadratic action. There are two ways to resolve these issues. For definiteness, let us focus the discussion on chiral 2 -form theories.

The first way is to give up the manifest $\mathrm{SO}(1,5)$ Lorentz invariance at the action level by making a split of spacetime. This way was achieved by [1], which presented the chiral 2-form action with manifest $\mathrm{SO}(5)$ subgroup of $\mathrm{SO}(1,5)$ Lorentz symmetry, and alternatively by [2], in which the action possesses a manifest $\mathrm{SO}(1,4)$ subgroup of $\mathrm{SO}(1,5)$ Lorentz symmetry.

Alternatively, as was done by [3-5], a manifestly Lorentz covariant chiral 2 -form action can be constructed by introducing an auxiliary scalar field, which appears non-linearly even in the quadratic theory. This way of introducing the auxiliary scalar field is called the PST covariantisation, and the theory itself is known as the PST theory. This theory possesses
two notable local symmetries, one of which is used to ensure the field equation reduces to self-duality condition, whereas the other is used to ensure the auxiliary nature of the auxiliary field. The latter symmetry is used to gauge fix the auxiliary field, reducing the theory to the non-manifest covariant versions [1, 2], thus realising non-covariant theories as different gauge-fixings of the PST theory.

From either way, the chiral 2-form theory can be extended to the complete M5-brane theory coupled to 11d supergravity background [6-8]. This makes use of Green-Schwarz formalism [9], in which an M5-brane is coupled to the supersymmetric background. This is shown by $[10-12]$ that the field equations agree with those obtained from the superembedding approach [13], in which a supersymmetric M5-brane is coupled to the supersymmetric background.

In the framework of string theory and M-theory, theories have been known and expected to be related to one another by some duality transformations. In the case of M5brane theory, an early attempt of the dualisation is given by [14, 15] in which a quadratic PST covariantised chiral 2-form action is dualised. It was found that while the dualisation applied to the chiral 2 -form does not change the theory, the dualisation applied to the auxiliary field gives rise to a quadratic PST covariantised chiral 2-form action with an auxiliary 4 -form. This theory is said to be in a dual formulation.

The paper [16] extended this theory to a complete M5-brane theory coupled to the 11d supergravity background. The construction did not make use of the auxiliary field, but instead made the split in the worldvolume indices in such a way that the action only presented a manifest 5 d worldvolume diffeomorphism, but it can be shown that there is an off-shell modified 6d worldvolume diffeomorphism.

In the standard formulation, the non-manifestly covariant M5-brane theory contains second-class constraints which complicate the quantisation. A way to remedy this is to make the PST covariantisation, giving PST-covariant M5-brane theory containing only first-class constraints [5]. We expect this to be analogous to the dual formulation. Although the complete M5-brane theory in dual formulation has been constructed, the theory is still not manifestly covariant. The covariantisation of this theory is then expected to put the action in the form which makes it simpler to later carry out the quantisation procedure. In fact, the covariantisation of 6 d chiral 2-form theory with quadratic action was already given in $[14,15]$ by using an auxiliary 4 -form. However, by a closer inspection it turns out that there seems to be a potential issue which might prevent the extension to the complete M5-brane theory.

The goal of this paper is to construct a covariant complete M5-brane theory in dual formulation. As to be discussed in this paper, it is still inconclusive whether using an auxiliary 4-form would really lead to an issue. Instead of keeping on investigating to see whether the issue truly exists, we simply aim to look for a special case of auxiliary field which make it possible to construct a covariant complete M5-brane theory in dual formulation. It turns out that the covariantisation and extension to the complete M5brane theory can be made possible by using 5 auxiliary scalar fields.

On the technical side, the constructions and studies in this paper are made possible using differential form language. In particular, the 5 auxiliary scalar fields appear in
the theory via projector matrices, which can be incorporated into the differential form language through the use of the induced linear transformation, to be given a quick review in this paper.

This paper is organised as follows. Section 2 starts by reviewing the standard M5brane theory, then followed by the main result of this paper, which is M5-brane theory in dual formulation. Section 3 presents the derivation, by first reviewing 6d chiral 2 -form theory with quadratic action covariantised using an auxiliary 4 -form [14, 15], and stating its potential issues. Then motivates an alternative way to covariantise, which is by the use of 5 auxiliary scalars. Finally we proceed to make a detailed analysis in quadratic action, and nonlinear action. Section 4 discusses that the covariantised M5-brane action in dual formulation using 5 auxiliary scalar fields is reduced, upon a suitable gauge-fixing of the auxiliary fields, to the action constructed in [16]. Finally, in section 5 we give conclusions and suggestions for future works.

## 2 The M5-brane actions

In this paper, the 11-dimensional target superspace is parametrised by supercoordinates $Z^{\mathcal{M}}=\left(X^{M}, \theta\right)$, in which $X^{M}$ are eleven bosonic coordinates and $\theta$ are 32 real fermionic coordinates. The geometry of the 11d supergravity are described by tangent-space vector super-vielbeins $E^{A}(Z)=d Z^{\mathcal{M}} E_{\mathcal{M}}{ }^{A}(Z)(A=0,1,2, \cdots, 10)$ and Majorana-spinor supervielbeins $E^{\alpha}(Z)=d Z^{\mathcal{M}} E_{\mathcal{M}}{ }^{\alpha}(Z)(\alpha=1,2, \cdots, 32)$. The kappa-symmetry of the $M 5$-brane action requires that the vector super-vielbein satisfies the torsion constraint

$$
\begin{equation*}
T^{A}=D E^{A}=d E^{A}+E^{B} \Omega_{B}^{A}=-i E^{\alpha} \Gamma_{\alpha \beta}^{A} E^{\beta}, \tag{2.1}
\end{equation*}
$$

where $\Omega_{B}{ }^{A}(Z)$ is the 1 -form spin connection in eleven dimension, $\Gamma_{\alpha \beta}^{A}=\Gamma_{\beta \alpha}^{A}$ are real symmetric gamma matrices and the exterior differential acts from the right. The signature of the metric is taken to be mostly plus.

The M5-brane worldvolume is parametrised by the coordinates $x^{\mu}(\mu=0,1, \cdots, 5)$. Its induced metric is constructed with the pull-backs of the vector super-vielbeins $E^{A}(Z)$

$$
\begin{equation*}
g_{\mu \nu}(x)=E_{\mu}^{A} E_{\nu}^{B} \eta_{A B}, \quad E_{\mu}^{A}=\partial_{\mu} Z^{\mathcal{N}} E_{\mathcal{N}}^{A}(Z(x)) \tag{2.2}
\end{equation*}
$$

It couples to the 11 d supergravity 3 -form gauge superfield, $C_{3}(Z)=\frac{1}{3!} d Z^{\mathcal{M}_{1}} d Z^{\mathcal{M}_{2}} d Z^{\mathcal{M}_{3}}$ - $C_{\mathcal{M}_{3} \mathcal{M}_{2} \mathcal{M}_{1}}$, and its $C_{6}(Z)$ dual. Their field strengths are constrained as follows

$$
\begin{align*}
d C_{3} & =-\frac{i}{2} E^{A} E^{B} E^{\alpha} E^{\beta}\left(\Gamma_{B A}\right)_{\alpha \beta}+\frac{1}{4!} E^{A} E^{B} E^{C} E^{D} F_{D C B A}^{(4)}(Z), \\
d C_{6}-C_{3} d C_{3} & =\frac{2 i}{5!} E^{A_{1}} \cdots E^{A_{5}} E^{\alpha} E^{\beta}\left(\Gamma_{A_{5} \cdots A_{1}}\right)_{\alpha \beta}+\frac{1}{7!} E^{A_{1}} \cdots E^{A_{7}} F_{A_{7} \cdots A_{1}}^{(7)}(Z)  \tag{2.3}\\
F^{(7) A_{1} \cdots A_{7}} & =\frac{1}{4!} \epsilon^{A_{1} \cdots A_{11}} F_{A_{8} \cdots A_{11}}^{(4)}, \quad \epsilon^{0 \ldots 10}=-\epsilon_{0 \ldots 10}=1 .
\end{align*}
$$

The M5-brane carries the chiral 2-form gauge field $B_{2}(x)=\frac{1}{2} d x^{\mu} d x^{\nu} B_{\nu \mu}(x)$ with field strength

$$
\begin{equation*}
H_{3}=d B_{2}+C_{3}, \tag{2.4}
\end{equation*}
$$

where $C_{3}(Z(x))$ is the pullback of the 3 -form gauge field on the M 5 -brane worldvolume.

### 2.1 PST-covariantised M5-brane action

The original M5-brane action in a generic $D=11$ supergravity superbackground is constructed in [6-8]. In order for the worldvolume theory to be manifestly covariant at the action level, an auxiliary scalar field $a(x)$ is introduced. Its gradient $\partial_{\mu} a$ could be either time-like or space-like. These two cases share the same action. However, for definiteness, we present the action in the form which accommodates space-like case:

$$
\begin{align*}
S_{\mathrm{PST}-\mathrm{M} 5}= & -\int_{\mathcal{M}_{6}} d^{6} x\left[\sqrt{-\operatorname{det}\left(g_{\mu \nu}+i(\tilde{H} \cdot u)_{\mu \nu}\right)}+\frac{\sqrt{-g}}{4}(\tilde{H} \cdot u)^{\mu \nu}(H \cdot u)_{\mu \nu}\right] \\
& +\frac{1}{2} \int_{\mathcal{M}_{6}}\left(C_{6}+H_{3} \wedge C_{3}\right) \tag{2.5}
\end{align*}
$$

where

$$
\begin{align*}
(H \cdot u)_{\mu \nu} & =H_{\mu \nu \rho} u^{\rho}, & (\tilde{H} \cdot u)_{\mu \nu} & =\tilde{H}_{\mu \nu \rho} u^{\rho}, \tag{2.6}
\end{align*} \quad u_{\rho}=\frac{\partial_{\rho} a}{\sqrt{\partial_{\mu} a g^{\mu \nu} \partial_{\nu} a}}, ~ \tilde{H}^{\rho \mu \nu} \equiv \frac{1}{6 \sqrt{-g}} \epsilon^{\rho \mu \nu \lambda \sigma \tau} H_{\lambda \sigma \tau}, \quad ~=\operatorname{det} g_{\mu \nu}, ~ l l
$$

with

$$
\epsilon^{0 \cdots 5}=-\epsilon_{0 \cdots 5}=1
$$

In addition to the conventional abelian gauge symmetry for the chiral 2 -form, the action (2.5) has also the following two local gauge symmetries. The first one, of type called PST1, is given by

$$
\begin{equation*}
\delta B_{\mu \nu}=2 \partial_{[\mu} a \Phi_{\nu]}(x), \quad \delta a(x)=0 \tag{2.8}
\end{equation*}
$$

with $\Phi_{\mu}(x)$ being arbitrary local functions on the woldvolume. This symmetry ensures that the equation of motion of $B_{2}$ reduces to the non-linear self-duality condition

$$
\begin{equation*}
(H \cdot u)_{\mu \nu}=\mathcal{U}_{\mu \nu} \tag{2.9}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathcal{U}^{\mu \nu} \equiv-2 \frac{\delta \sqrt{\operatorname{det}\left(\delta_{\mu}^{\nu}+i(\tilde{H} \cdot u)_{\mu}{ }^{\nu}\right)}}{\delta(\tilde{H} \cdot u)_{\mu \nu}} \tag{2.10}
\end{equation*}
$$

Another local gauge symmetry, whose type is called PST2, is given by

$$
\begin{equation*}
\delta a=\varphi(x), \quad \delta B_{\mu \nu}=\frac{\varphi(x)}{\sqrt{(\partial a)^{2}}}\left(H_{\mu \nu}-\mathcal{U}_{\mu \nu}\right) \tag{2.11}
\end{equation*}
$$

with $\varphi(x)$ being an arbitrary local function on the woldvolume. This symmetry ensures that the scalar field $a(x)$ is indeed arbitrary and that the action is $6 d$ covariant.

The action (2.5) is also invariant under the local fermionic kappa-symmetry transformations which acts on the worldvolume fields and pullbacks of the target-space fields as follows

$$
\begin{align*}
i_{\kappa} E^{\alpha} & \equiv \delta_{\kappa} Z^{\mathcal{M}} E_{\mathcal{M}}^{\alpha}=\frac{1}{2}(1+\bar{\Gamma})^{\alpha}{ }_{\beta} \kappa^{\beta}, & i_{\kappa} E^{A} & \equiv \delta_{\kappa} Z^{\mathcal{M}} E_{\mathcal{M}}^{A}=0  \tag{2.12}\\
\delta_{\kappa} g_{\mu \nu} & =-4 i E_{(\mu}^{\alpha}\left(\Gamma_{\nu)}\right)_{\alpha \beta} i_{\kappa} E^{\beta}, & \delta_{\kappa} H^{(3)} & =i_{\kappa} d C^{(3)},
\end{align*}
$$

where $\kappa(x)$ is the parameter of kappa-symmetry transformation. The matrix $\bar{\Gamma}$ is given by

$$
\begin{align*}
\sqrt{\operatorname{det}\left(\delta_{\mu}^{\nu}+i(\tilde{H} \cdot u)_{\mu}^{\nu}\right)} \bar{\Gamma}= & \gamma^{(6)}-\frac{1}{2} \Gamma^{\mu \nu \lambda} u_{\mu}(\tilde{H} \cdot u)_{\nu \lambda} \\
& -\frac{1}{16 \sqrt{-g}} \epsilon^{\mu_{1} \cdots \mu_{6}}(\tilde{H} \cdot u)_{\mu_{1} \mu_{2}}(\tilde{H} \cdot u)_{\mu_{3} \mu_{4}} \Gamma_{\mu_{5} \mu_{6}} . \tag{2.13}
\end{align*}
$$

So that $(1+\bar{\Gamma}) / 2$ is the projector of rank 16 , and that

$$
\begin{equation*}
\bar{\Gamma}^{2}=1, \quad \operatorname{tr} \bar{\Gamma}=0, \tag{2.14}
\end{equation*}
$$

where

$$
\begin{equation*}
\Gamma_{\mu}=E_{\mu}{ }^{A} \Gamma_{A}, \quad \gamma^{(6)}=\frac{1}{6!\sqrt{-g}} \epsilon^{\mu_{1} \cdots \mu_{6}} \Gamma_{\mu_{1} \cdots \mu_{6}} . \tag{2.15}
\end{equation*}
$$

### 2.2 M5-brane action in the dual formulation

In this paper, a covariantised M5-brane action in the dual formulation is constructed with the help of 5 auxiliary scalar fields $a^{s}(x)$. The index $s$, as well as other from at the end of lower-case Roman alphabets, labels the different auxiliary scalar fields, and is chosen to be $s=0,1,2,3,4$. This is just a choice of numbering and should not be confused with spacetime indices. The projector matrices associated to the auxiliary fields are given by ${ }^{1}$

$$
\begin{equation*}
P_{\mu}^{\nu}=\partial_{\mu} a^{r} Y_{r s}^{-1} \partial^{\nu} a^{s}, \quad P_{\mu}^{\perp^{\nu}}=\delta_{\mu}^{\nu}-P_{\mu}^{\nu}, \quad P_{\mu}^{\nu} \partial_{\nu} a^{s}=\partial_{\mu} a^{s}, \tag{2.16}
\end{equation*}
$$

where $Y_{r s}^{-1}$ is the matrix inverse of

$$
\begin{equation*}
Y^{r s}=\partial_{\mu} a^{r} \partial_{\nu} a^{s} g^{\mu \nu} . \tag{2.17}
\end{equation*}
$$

The projector $P$ has rank 5 whereas the projector $P^{\perp}$ has rank 1 .
It is also convenient to define a vector

$$
\begin{equation*}
\lambda^{\mu}=-\frac{1}{5!} \frac{1}{\sqrt{-g}} \epsilon_{s_{0} s_{1} s_{2} s_{3} s_{4}} \zeta_{\mu_{0}}^{s_{0}} \zeta_{\mu_{1}}^{s_{1}} \zeta_{\mu_{2}}^{s_{2}} \zeta_{\mu_{3}}^{s_{3}} \zeta_{\mu_{4}}^{s_{4}} \epsilon^{\mu \mu_{0} \mu_{1} \mu_{2} \mu_{3} \mu_{4}}, \tag{2.18}
\end{equation*}
$$

where

$$
\epsilon_{s_{0} s_{1} s_{2} s_{3} s_{4}}= \begin{cases}1 & \text { even permutation of } 01234  \tag{2.19}\\ -1 & \text { odd permutation of } 01234 \\ 0 & \text { otherwise }\end{cases}
$$

and $\zeta_{\mu}^{s} \equiv \partial_{\mu} a^{s}$. It is related to the projector by the following identity

$$
\begin{equation*}
P^{\perp^{\nu}}=\frac{g_{\mu \rho} \lambda^{\rho} \lambda^{\nu}}{g_{\sigma \eta} \lambda^{\sigma} \lambda^{\eta}} \equiv \frac{g_{\mu \rho} \lambda^{\rho} \lambda^{\nu}}{(\lambda)^{2}}, \tag{2.20}
\end{equation*}
$$

where we have denoted $(\lambda)^{2} \equiv g_{\sigma \eta} \lambda^{\sigma} \lambda^{\eta}$, which is not to be confused with the $\mu=2$ component of $\lambda^{\mu}$. The proof of this identity and other discussions related to the projectors will be discussed later after we present some tools for calculations.

[^0]The M5-brane action in the dual formulation with PST covariantisation in the 11d supergravity background constructed as a main result of this paper is given by

$$
\begin{align*}
S_{\mathrm{cov}-\text { dual-M5 }}= & \int_{\mathcal{M}_{6}} d^{6} x\left[-\sqrt{-g} \sqrt{\operatorname{det}\left(\delta_{\mu}^{\nu}+(H \cdot v)_{\mu}^{\nu}\right)}+\frac{\sqrt{-g}}{4}(\tilde{H} \cdot v)^{\mu \nu}(H \cdot v)_{\mu \nu}\right] \\
& +\frac{1}{2} \int_{\mathcal{M}_{6}}\left(C_{6}+H_{3} \wedge C_{3}\right) \tag{2.21}
\end{align*}
$$

with

$$
\begin{equation*}
(\tilde{H} \cdot v)_{\mu \nu} \equiv \tilde{H}_{\mu \nu \rho} v^{\rho}, \quad(H \cdot v)_{\mu \nu} \equiv H_{\mu \nu \rho} v^{\rho}, \quad v^{\mu}=\frac{\lambda^{\mu}}{\sqrt{(\lambda)^{2}}} \tag{2.22}
\end{equation*}
$$

For definiteness, we have put the action (2.21) in the form which accommodates $(\lambda)^{2}>0$. In fact, the action (2.21) can be brought to the form which allows both $(\lambda)^{2}>0$ and $(\lambda)^{2}<0$. This can be made possible because $v^{\mu}$ appear in pair in each expression and hence after expressing them in terms of $\lambda^{\mu}$, the square roots in the denominators always appear in pair $\sqrt{(\lambda)^{2}} \sqrt{(\lambda)^{2}}=(\lambda)^{2}$.

Similar to the case of the original M5-brane action, the M5-brane action in the dual formulation also has symmetries of type PST1 and PST2 in addition to the conventional abelian gauge symmetry for $B_{2}$. In this case, The PST1 symmetry is given by

$$
\begin{equation*}
\delta a^{s}=0, \quad \delta B_{\mu \nu}=\partial_{[\mu} a^{r} \partial_{\nu]} a^{s} \psi_{r s}\left(a^{w}\right) \tag{2.23}
\end{equation*}
$$

where $\psi_{r s}\left(a^{w}\right)$ are functions of auxiliary fields $a^{s}$. Although semi-local, this symmetry allows the equation of motion to be reduced to the nonlinear self-duality condition

$$
\begin{equation*}
(\tilde{H} \cdot v)_{\mu \nu}=\mathcal{V}_{\mu \nu} \tag{2.24}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathcal{V}^{\mu \nu} \equiv 2 \frac{\delta \sqrt{\operatorname{det}\left(\delta_{\rho}^{\sigma}+(H \cdot v)_{\rho}^{\sigma}\right)}}{\delta(H \cdot v)_{\mu \nu}} \tag{2.25}
\end{equation*}
$$

The semi-locality of the PST1 symmetry is analogous to its counterpart seen in a PST covariantised version [14, 15] of chiral boson theory in two-dimensions [19]. The PST2 symmetry is given by

$$
\begin{equation*}
\delta a^{s}=\varphi^{s}, \quad \delta B_{\mu \nu}=\frac{1}{2} v_{\rho} \varphi^{r} Y_{r s}^{-1} \partial_{\sigma} a^{s} \frac{\epsilon^{\mu^{\prime} \nu^{\prime} \rho \sigma \lambda \tau}}{\sqrt{-g}}\left(\mathcal{V}_{\lambda \tau}-(\tilde{H} \cdot v)_{\lambda \tau}\right) g_{\mu \mu^{\prime}} g_{\nu \nu^{\prime}} \tag{2.26}
\end{equation*}
$$

where $\varphi^{s}(x)$ are arbitrary functions. This symmetry ensures that the fields $a^{s}(x)$ are arbitrary. By following the analysis of [20], the dynamical system of the action (2.21) is separated into two branches: that with $(\lambda)^{2}>0$, and that with $(\lambda)^{2}<0$. These two branches are disconnected because there is no non-singular PST2 transformation which can move the system from one branch to the other without passing through the forbidden region $(\lambda)^{2}=0$, in which the action becomes singular.

In order for the second order field equation of $B$ to be gauge equivalent to non-linear self-duality equation (2.24), the semi-local PST1 symmetry has to be a gauge symmetry.

This is the case when the Noether's charge vanishes [21, 22]. Noether's current of the PST1 symmetry (2.23) is given by

$$
\begin{equation*}
j^{\rho}=\frac{1}{2} \psi_{r s} \partial_{\mu} a^{r} \partial_{\nu} a^{s}\left(\mathcal{V}^{\mu \nu}-(\tilde{H} \cdot v)^{\mu \nu}\right) v^{\rho}, \tag{2.27}
\end{equation*}
$$

which is conserved on-shell. The form of the Noether's current makes it clear that Noether's charge vanishes when $\lambda^{0}=0$. In general, the analysis in each branch has to be done separately [20]. In the $(\lambda)^{2}>0$ branch, one can always use PST2 symmetry to gauge-fix $a^{s}=x^{s}$ giving $\lambda^{0}=0$, which in turn implies that PST1 symmetry is a gauge symmetry and can be used to ensure that the second order field equation of $B$ is equivalent to the non-linear self-duality condition. On the other hand, throughout the $(\lambda)^{2}<0$ branch, the Noether's charge does not vanish. So in this branch, the PST1 symmetry is a global symmetry, and hence the non-linear self-duality condition is not obtainable from gaugefixing the second order field equation.

The M5-brane action in the dual formulation is also invariant under the kappa symmetry (2.12), which instead of $\delta_{\kappa} a=0$ we have $\delta_{\kappa} a^{s}=0$. Additionally, $\bar{\Gamma}$ for this theory is given via

$$
\begin{align*}
\left(\sqrt{\operatorname{det}\left(\delta_{\mu}^{\nu}+(H \cdot v)_{\mu^{\nu}}\right)}\right) \bar{\Gamma}= & \gamma^{(6)}+\frac{1}{2} v_{\mu}(H \cdot v)_{\nu \rho} \gamma^{(6)} \Gamma^{\mu \nu \rho}  \tag{2.28}\\
& +\frac{1}{16 \sqrt{-g}} \epsilon^{\mu_{1} \cdots \mu_{6}}(H \cdot v)_{\mu_{1} \mu_{2}}(H \cdot v)_{\mu_{3} \mu_{4}} \Gamma_{\mu_{5} \mu_{6}}
\end{align*}
$$

which also satisfies

$$
\begin{equation*}
\bar{\Gamma}^{2}=1, \quad \operatorname{tr} \bar{\Gamma}=0 . \tag{2.29}
\end{equation*}
$$

## 3 Derivations

In this section, we present the derivation of the M5-brane action in dual formulation (2.21). By using differential form language, the construction and the study of the properties of the action is naturally made possible. Therefore, let us first develop the necessary tools before working on the construction.

### 3.1 Mathematical preliminary: induced linear transformation

The M5-brane action in dual formulation presented by eq. (2.21) requires 5 auxiliary scalar fields $a^{s}, s=0,1,2,3,4$, which appear in the action only via their gradients $\zeta^{s} \equiv d a^{s}$. In principle, the study of the action (2.21) can be done by directly making use of five 1 -forms $\zeta^{s}$. However, we find it more convenient to study by using projectors $P_{\nu}^{\mu}, P_{\nu}^{\perp \mu}$ incorporated into differential form language. This can be done by using the idea of induced linear transformation. Let us now give a quick review on this idea. See for example [23, 24] for more information. The discussions and examples presented in the following can be easily generalised and made suitable for the context and purpose of this paper. Readers who are familiar with this mathematical language may wish to read this subsection quickly to find out the convention we used.

Let $V$ be a vector space with $V^{*}$ its dual space. Consider a linear map

$$
\begin{equation*}
T: V \rightarrow V \tag{3.1}
\end{equation*}
$$

The transpose of $T$ is given by a linear map

$$
\begin{equation*}
T^{\dagger}: V^{*} \rightarrow V^{*} \tag{3.2}
\end{equation*}
$$

such that

$$
\begin{equation*}
\zeta(T(v))=\left(T^{\dagger} \zeta\right)(v), \quad \forall v \in V, \forall \zeta \in V^{*} \tag{3.3}
\end{equation*}
$$

Given two or more linear maps $V \rightarrow V$, a multilinear map on products of $V$ can be introduced. For example, consider two linear maps $T: V \rightarrow V$, and $S: V \rightarrow V$. An induced transformation $\bigwedge^{2} T \bigwedge S$ is a multilinear map

$$
\begin{align*}
\bigwedge^{2} T \bigwedge S: \otimes^{3} V & \rightarrow \bigwedge^{3} V  \tag{3.4}\\
\left(v_{1}, v_{2}, v_{3}\right) & \mapsto T v_{1} \wedge T v_{2} \wedge S v_{3}
\end{align*}
$$

Other induced maps, for example $\bigwedge^{3} T, \bigwedge T \bigwedge S \bigwedge T$, etc. can also be defined in a similar manner. A "trace" is given by the sum of all possible permutations of the induced transformations. For example,

$$
\begin{equation*}
\operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right)=\bigwedge T \bigwedge T \bigwedge S+\bigwedge T \bigwedge S \bigwedge T+\bigwedge S \bigwedge T \bigwedge T \tag{3.5}
\end{equation*}
$$

These maps are totally antisymmetric. For example

$$
\begin{align*}
\operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right)\left(v_{1}, v_{2}, v_{3}\right) & =-\operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right)\left(v_{1}, v_{3}, v_{2}\right)=\operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right)\left(v_{3}, v_{1}, v_{2}\right) \\
& =-\operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right)\left(v_{3}, v_{2}, v_{1}\right)=\operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right)\left(v_{2}, v_{3}, v_{1}\right)  \tag{3.6}\\
& =-\operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right)\left(v_{2}, v_{1}, v_{3}\right)
\end{align*}
$$

The "trace" satisfies a binomial expansion property

$$
\begin{equation*}
\bigwedge^{n}(T+S)=\sum_{r=0}^{n} \operatorname{tr}\left(\bigwedge^{r} T \bigwedge^{n-r} S\right) \tag{3.7}
\end{equation*}
$$

It is clear that the constructions on a dual vector space can be defined in a similar way.
Let us now consider a useful identity. For example, let $T: V \rightarrow V$, and $S: V \rightarrow V$ be a linear map, and let $F$ be a 3 -form. Then, it can be shown that

$$
\begin{equation*}
\operatorname{tr}\left(\bigwedge^{2} T^{\dagger} \bigwedge S^{\dagger}\right)(F)=F \circ \operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right) \tag{3.8}
\end{equation*}
$$

where $\circ$ is the symbol for function composition. To avoid future clutter of notation, we will simply drop the symbols ${ }^{\dagger}$ and $\circ$ as it should be clear from the context where these symbols should appear. So we may simply write the above equation as

$$
\begin{equation*}
\operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right)(F)=F\left(\operatorname{tr}\left(\bigwedge^{2} T \bigwedge S\right)\right) \tag{3.9}
\end{equation*}
$$

In the subsequent subsections, we start by reviewing the construction of a covariantised quadratic action for chiral 2 -form in dual formulation [14, 15], in which the covariantisation is made possible with the help of an auxiliary 4 -form. We then show the potential issues which could possibly prevent the extension of the action to a complete M5-brane action in the dual formulation. Our next goal is not to thoroughly investigate whether these issues are truly problematic, let alone to try to resolve them. We simply limit the study to a special case of auxiliary fields which avoid these potential issues. This choice will make it evident that the extension to a complete M5-brane action in the dual formulation is possible.

### 3.2 Quadratic dual action of a six-dimensional chiral 2-form theory with an auxiliary 4-form

Let us give a review and analysis of the quadratic action of a chiral 2-form in six dimensions in a dual formulation with an auxiliary 4 -form constructed by [14, 15]. We translate the presentation into differential form language. We use the convention that exterior derivatives and interior products act from the right, and that a $p$-form is expressed as

$$
\begin{equation*}
A_{p}=\frac{1}{p!} d x^{\mu_{1}} \wedge \cdots \wedge d x^{\mu_{p}} A_{\mu_{p} \cdots \mu_{1}} \tag{3.10}
\end{equation*}
$$

and a Hodge star is given by

$$
\begin{equation*}
* d x^{\mu_{1}} \wedge \cdots d x^{\mu_{p}}=\frac{(-1)^{p+1}}{(6-p)!\sqrt{-g}} d x^{\mu_{p+1}} \wedge \cdots \wedge d x^{\mu_{6}} \epsilon^{\nu_{p+1} \cdots \nu_{6} \mu_{1} \cdots \mu_{p}} g_{\mu_{p+1} \nu_{p+1}} \cdots g_{\mu_{6} \nu_{6}} \tag{3.11}
\end{equation*}
$$

where $x^{\mu}, \mu=0,1, \cdots, 5$ are 6 d coordinates, and $g$ is the determinant of the 6 d metric. Let us denote the field strength of a chiral 2-form as

$$
\begin{equation*}
F=d B \tag{3.12}
\end{equation*}
$$

and define

$$
\begin{equation*}
\mathcal{F}=F-* F . \tag{3.13}
\end{equation*}
$$

The action constructed by $[14,15]$ made use of an auxiliary 4 -form $\chi_{4}$ which appears in the action via the Hodge dual of its field strength:

$$
\begin{equation*}
\tilde{\lambda}=* d \chi \tag{3.14}
\end{equation*}
$$

This naturally gives rise to the projectors

$$
\begin{equation*}
\tilde{P}=\frac{g^{-1}(\tilde{\lambda}) \otimes \tilde{\lambda}}{g^{-1}(\tilde{\lambda}, \tilde{\lambda})}, \quad \tilde{P}^{\perp}=\mathbb{1}-\tilde{P} \tag{3.15}
\end{equation*}
$$

where $\mathbb{1}$ is the identity map. Here the inverse metric $g^{-1}$ takes the role of a linear map which maps a one-form to a vector. The induced linear transformations are defined as

$$
\begin{equation*}
\tilde{\mathcal{P}} \equiv \operatorname{tr}\left(\bigwedge \tilde{P} \bigwedge^{2} \tilde{P}^{\perp}\right), \quad \tilde{\mathcal{P}}^{\perp} \equiv \operatorname{tr}\left(\bigwedge^{3} \tilde{P}^{\perp}\right), \quad \mathcal{I} \equiv \operatorname{tr}\left(\bigwedge^{3} \mathbb{1}\right) . \tag{3.16}
\end{equation*}
$$

They satisfy the following identities

$$
\begin{equation*}
\tilde{\mathcal{P}}+\tilde{\mathcal{P}}^{\perp}=\mathcal{I}, \quad \tilde{\mathcal{P}} \bigwedge \mathcal{I}=\mathcal{I} \bigwedge \tilde{\mathcal{P}}^{\perp}, \quad \mathcal{I} \bigwedge \tilde{\mathcal{P}}=\tilde{\mathcal{P}}^{\perp} \bigwedge \mathcal{I} \tag{3.17}
\end{equation*}
$$

It can be shown that for any 3 -form $A_{3}$,

$$
\begin{equation*}
\tilde{\mathcal{P}}^{\perp} A_{3}=-\frac{1}{\tilde{\lambda}^{2}} i_{g^{-1} \tilde{\lambda}}\left(\tilde{\lambda} \wedge A_{3}\right) . \tag{3.18}
\end{equation*}
$$

With the above setup, we can write the 6 d chiral 2 -form action of $[14,15]$ as

$$
\begin{equation*}
S=\int \frac{1}{2} F \wedge \tilde{\mathcal{P}}^{\perp} \mathcal{F} . \tag{3.19}
\end{equation*}
$$

The variations with respect to the 2 -form field and auxiliary 4 -form field are given by

$$
\begin{align*}
\delta_{(B)} S= & \int \delta B \wedge d \tilde{\mathcal{P}}^{\perp} \mathcal{F}-\frac{1}{2} \int d\left(\delta B \wedge\left(2 \tilde{\mathcal{P}}^{\perp} \mathcal{F}-F\right)\right),  \tag{3.20}\\
\delta_{(\chi)} S & =\int \frac{1}{2 \tilde{\lambda}^{2}} \delta \tilde{\lambda} \wedge \tilde{\mathcal{P}} \mathcal{F} \wedge i_{g^{-1} \tilde{\lambda}} \tilde{\mathcal{P} \mathcal{F}}  \tag{3.21}\\
& =\frac{1}{2} \int \delta \chi \wedge d *\left(\frac{1}{\tilde{\lambda}^{2}} \tilde{\mathcal{P}} \mathcal{F} \wedge i_{g^{-1}} \tilde{\mathcal{D}} \tilde{\mathcal{F}}\right)-\int d\left(\frac{1}{2 \tilde{\lambda}^{2}} \delta \chi \wedge *\left(\tilde{\mathcal{P}} \mathcal{F} \wedge i_{g^{-1} \tilde{\mathcal{~}}} \tilde{\mathcal{P}} \mathcal{F}\right)\right)
\end{align*}
$$

So the field equations for $B$ and $\chi$ are

$$
\begin{align*}
d \tilde{\mathcal{P}}^{\perp} \mathcal{F} & =0,  \tag{3.22}\\
d *\left(\frac{1}{\tilde{\lambda}^{2}} \tilde{\mathcal{P}} \mathcal{F} \wedge i_{g^{-1}} \tilde{\mathcal{P}} \mathcal{F}\right) & =0 . \tag{3.23}
\end{align*}
$$

Apart from the tensor gauge symmetry of $B$, the action (3.19) also has tensor gauge symmetry for $\chi$, as well as PST1 and PST2 symmetries. The tensor gauge variation for $\chi$ is given as an exterior derivative of a 3 -form gauge parameter, which is reducible. Out of the 20 components of 3 -form gauge parameter, only $(20-(15-(6-1)))=10$ are independent. The PST1 symmetry of the action (3.19) is given by

$$
\begin{equation*}
\delta B=\frac{1}{\sqrt{\tilde{\lambda}^{2}}} i_{g^{-1} \tilde{\lambda}} \Psi, \quad \delta \chi=0 \tag{3.24}
\end{equation*}
$$

where the parameter $\Psi$ satisfies

$$
\begin{equation*}
\mathcal{L}_{g^{-1} \tilde{\lambda}}\left(\frac{1}{\sqrt{\tilde{\lambda}^{2}}} i_{g^{-1} \tilde{\lambda}} \Psi\right)=0, \tag{3.25}
\end{equation*}
$$

where $\mathcal{L}_{g^{-1} \tilde{\lambda}}$ is the Lie derivative along the vector field $g^{-1} \tilde{\lambda}$. The PST2 symmetry is given by

$$
\begin{equation*}
\delta B=i_{\xi} \tilde{\mathcal{P}}^{\perp} \mathcal{F}, \quad \delta \chi=i_{\xi} * \tilde{\lambda} \tag{3.26}
\end{equation*}
$$

where the parameter $\xi$ is an arbitrary vector field. The variation $\delta \chi$ implies the variation on $\tilde{\lambda}$ as

$$
\begin{equation*}
\delta \tilde{\lambda}=g\left(\mathcal{L}_{\xi} g^{-1} \tilde{\lambda}\right)+\operatorname{div} \xi \tilde{\lambda} \tag{3.27}
\end{equation*}
$$

Here, the metric $g$ takes a role of a linear map, which maps a vector to a one-form.

In general, PST1 symmetry is used in order to reduce the second order field equation (3.22) to self-duality equation. In order to do so, PST1 has to be a gauge symmetry. However, PST1 symmetry (3.24) is semi-local (see for example [20, 22] for similar issues), which means that it can either be a gauge symmetry or a global symmetry. In order for the PST1 symmetry to be a gauge symmetry, its Noether's charge has to vanish (see for example [21]). The Noether's charge is given by the 5 d spatial integral of $j^{0}$, where

$$
\begin{equation*}
j=-*\left(\frac{1}{\sqrt{\tilde{\lambda}^{2}}} i_{g^{-1} \tilde{\lambda}} \Psi \wedge \tilde{\mathcal{P}}^{\perp} \mathcal{F}\right) . \tag{3.28}
\end{equation*}
$$

In order for $j^{0}$ to vanish, one demands that

$$
\begin{equation*}
d t \wedge i_{g^{-1} \tilde{\lambda}} \Psi \wedge \tilde{\mathcal{P}}^{\perp} \mathcal{F}=0 . \tag{3.29}
\end{equation*}
$$

By adopting the viewpoint similar to that of [20], one may expect that the dynamical system is separated into two branches: that with $g^{-1}(\tilde{\lambda}, \tilde{\lambda})>0$, and that with $g^{-1}(\tilde{\lambda}, \tilde{\lambda})<0$. The task is to determine the branch in which the condition (3.29) is satisfied. Let us now give an analysis on this.

Consider the transformation

$$
\begin{equation*}
\delta \chi=i_{\xi} d \chi+d i_{\xi} \chi . \tag{3.30}
\end{equation*}
$$

The first term on the r.h.s. is a PST2 transformation, while the second term is a tensor gauge transformation whose parameter is identified with $i_{\xi} \chi$. The transformation (3.30) is simply given by a Lie derivative acting on $\chi$. Therefore, it is well-known that an associated finite transformation is given by

$$
\begin{equation*}
\chi^{(h)}=\frac{1}{4!} d\left(x^{\mu}+h \xi^{\mu}\right) \wedge d\left(x^{\nu}+h \xi^{\nu}\right) \wedge d\left(x^{\rho}+h \xi^{\rho}\right) \wedge d\left(x^{\sigma}+h \xi^{\sigma}\right) \chi_{\sigma \rho \nu \mu}^{(0)}(x+h \xi), \tag{3.31}
\end{equation*}
$$

where $h$ is a parameter along the integral curve of $\xi$. One then obtains

$$
\begin{align*}
\tilde{\lambda}^{(h)}= & \frac{1}{4!} d x^{\rho} \frac{\epsilon^{\nu_{5} \nu_{1} \nu_{2} \nu_{3} \nu_{4} \mu_{5}}}{\sqrt{-g}} g_{\nu_{5} \rho} \partial_{\nu_{1}}\left(x^{\mu_{1}}+h \xi^{\mu_{1}}\right) \partial_{\nu_{2}}\left(x^{\mu_{2}}+h \xi^{\mu_{2}}\right)  \tag{3.32}\\
& \times \partial_{\nu_{3}}\left(x^{\mu_{3}}+h \xi^{\mu_{3}}\right) \partial_{\nu_{4}}\left(x^{\mu_{4}}+h \xi^{\mu_{4}}\right) \partial_{\mu_{5}} \chi_{\mu_{4} \mu_{3} \mu_{2} \mu_{1}}(x+h \xi) .
\end{align*}
$$

Given $\chi^{(0)}$, and $\xi$, it can be seen that $g^{-1}\left(\tilde{\lambda}^{(h)}, \tilde{\lambda}^{(h)}\right)$ varies smoothly in $h$. Using this result and the fact that the dynamical system is not defined at $g^{-1}(\tilde{\lambda}, \tilde{\lambda})=0$, one concludes that the dynamical system is separated into two branches: that with $g^{-1}(\tilde{\lambda}, \tilde{\lambda})>0$, and that with $g^{-1}(\tilde{\lambda}, \tilde{\lambda})<0$. It is not possible to connect these two branches without passing through the region with $g^{-1}(\tilde{\lambda}, \tilde{\lambda})=0$.

In the $g^{-1}(\tilde{\lambda}, \tilde{\lambda})>0$ branch, one can use the combined transformation (3.30) to gauge fix $\chi$ to, say

$$
\begin{equation*}
\chi=-x^{0} d x^{1234}, \tag{3.33}
\end{equation*}
$$

which gives $j^{0}=0$, and hence PST1 is a gauge symmetry making the field equations (3.22)(3.23) to be gauge equivalent to self-duality condition $\mathcal{F}=0$. On the other hand, in the
$g^{-1}(\tilde{\lambda}, \tilde{\lambda})<0$ branch, one always have $j^{0} \neq 0$. Therefore, one does not obtain self-duality condition in this branch.

By counting the number of components, one may expect that the action (3.19) has a potential issue with PST2 symmetry (3.26). If one makes use of reducible tensor gauge symmetry of $\chi$, i.e. by gauge-fixing, then the number of remaining independent components of $\chi$ is $15-10=5$. So 5 out of 6 independent components of PST2 parameter $\xi$ are used to completely gauge away the remaining components of $\chi$. The remaining 1 independent PST2 parameter could potentially remove 1 degree of freedom of $B$. The predicted removal of component of $B$ by gauge-fixing PST2 symmetry is not desired and could be considered as an issue.

In order to make sure, one will need to give an explicit analysis to see whether the issue actually arises. However, we do not intend to pursue this investigation through the end. Let us simply give a remark that in an example of gauge-fixing to a non-manifest covariant theory, the issue does not seem to arise. Suppose that one has used the combined PST2 and tensor gauge transformation to gauge-fix $\chi$ to

$$
\begin{equation*}
\chi=\frac{1}{5!} \epsilon_{a b c d e 5} x^{\underline{a}} d x^{\underline{b}} \wedge d x^{\underline{c}} \wedge d x^{\underline{d}} \wedge d x^{\underline{e}}, \tag{3.34}
\end{equation*}
$$

where underlined lower case Roman indices $\underline{a}, \underline{b}, \ldots$ take the values $0,1,2,3,4$. Next, by demanding that the combined diffeomorphism, PST2, and tensor gauge transformation do not change this gauge, one obtains

$$
\begin{align*}
0= & d x^{\underline{a}} \wedge d x^{\underline{b}} \wedge d x^{\underline{c}} \wedge d x^{\underline{d}}\left(\frac{1}{4!} \epsilon_{a b c d e 5}\left(\xi^{\underline{e}}+\epsilon^{\underline{e}}\right)+\frac{1}{5} \frac{1}{3!} \partial_{\underline{d}}\left(\epsilon^{\epsilon_{\epsilon}} \epsilon_{\text {eabcf } 5} x^{\underline{e}}\right)+\frac{1}{3!} \partial_{\underline{d}} \gamma_{c b a}\right)  \tag{3.35}\\
& +d x^{\underline{a}} \wedge d x^{\underline{b}} \wedge d x^{\underline{c}} \wedge d x^{5}\left(\frac{1}{5} \frac{1}{3!} \partial_{5}\left(\epsilon^{d} \epsilon_{\epsilon_{\text {eabcd } 5}} x^{\underline{e}}\right)+\frac{4}{3!} \partial_{[5} \gamma_{\underline{c b a]}}\right),
\end{align*}
$$

where $\gamma_{\mu \nu \rho}$ is the parameter for the tensor gauge transformation of $\chi$, and $\epsilon$ is the parameter for the diffeomorphism transformation. This condition is solved by

$$
\begin{equation*}
\gamma_{5 \underline{b a}}=0, \quad \gamma_{c b a}+\frac{1}{5} \epsilon^{\underline{d}} \epsilon_{\underline{e a b c d} 5} x^{\underline{e}}=0, \quad \xi^{\underline{a}}=-\epsilon^{\underline{a}}, \tag{3.36}
\end{equation*}
$$

which is a special solution. Note that there is no condition which specifies $\xi^{5}$ component of the PST2 transformation. Naively, this component could potentially kill a degree of freedom of $B_{2}$. However, an explicit analysis shows that this is not the case. Under the combined diffeomorphism and PST2 transformation, and after imposing (3.36), one obtains

$$
\begin{align*}
\delta B & =\mathcal{L}_{\epsilon} B-\epsilon^{\underline{a}} i_{\partial_{\underline{a}}} \tilde{\mathcal{P}}^{\perp} \mathcal{F} \\
& =\mathcal{L}_{\epsilon} B-\frac{2}{g_{55}} \epsilon^{\underline{p}} d x^{\underline{m n}} g_{5[5} \mathcal{F}_{\underline{\text { mm }}]}, \tag{3.37}
\end{align*}
$$

which is clear that $\xi^{5}$ does not enter and hence no degree of freedom is unintentionally removed.

The fact that the extra component of PST2 parameter does not appear in the above example is interesting. However, we leave it as a future work to investigate in a more general setup whether the extra component of PST2 parameter would remain unharmful.

### 3.3 4-form to 5 scalars

The paper $[14,15]$ derives the quadratic dual action of a 6 d chiral 2 -form with an auxiliary 4form by starting from the covariant quadratic action of a 6 d chiral 2 -form with an auxiliary scalar $a(x)$, and then applying a dualisation technique on the auxiliary scalar. The process gives rise to a quadratic dual action of a 6 d chiral 2 -form such that an auxiliary field must appear through a 1 -form $\tilde{\lambda}$ satisfying the condition $d * \tilde{\lambda}=0$. The converse of the Poincare's lemma then gives $\tilde{\lambda}=* d \chi$, for an arbitrary 4 -form $\chi$. This is how the auxiliary 4 -form appears in the paper $[14,15]$.

As discussed in the previous subsection, it is still unclear whether there is an issue when using an auxiliary 4 -form. So we only follow the above procedure up to a certain step, and then put in some restrictions. In particular, we follow the procedure up to the step in which the condition $d * \tilde{\lambda}=0$ is obtained. Imposing some restrictions then means that a suitable decomposition has to be made on the solution of $\tilde{\lambda}$. For example, one might wish to use a Helmholtz decomposition and then restricting to a special case by turning off some fields in the decomposition. However, for the problem at hand, Helmholtz decomposition is not suitable. To find a more suitable decomposition, we make use of a geometrical interpretation. Recall that in a PST covariantised theory, an auxiliary scalar field $a$ appears in the action via a 1 -form $\zeta=d a$. The geometrical interpretation is that $\zeta$ describes a normal to 5D hypersurfaces $a=$ const. For the dual theory, however, the condition $\tilde{\lambda}=d b$ for some scalar field $b$ cannot be imposed as it contradicts to $d * \tilde{\lambda}=0$. So a different interpretation has to be made. An alternative description of 5 D hypersurfaces is given by wedge product of five 1 -forms. Therefore, the decomposition we look for is to decompose $* \tilde{\lambda}$ into a wedge product of five 1 -forms plus some other terms. It turns out that this problem is related to a decomposability problem in the context of exterior algebra.

So let us first discuss this problem in exterior algebra. Consider a 6-dimensional dual vector space $V^{*}$. We would like to investigate the conditions in which a 5 -form $* \lambda$ can be written as a wedge product of 51 -forms. It turns out that this is always possible. For the proof, let us closely follow the arguments in the reference [25], adopted to the case at hand. Let us define a linear map

$$
\begin{align*}
T: V^{*} & \rightarrow \wedge^{6} V^{*} \\
w & \mapsto(* \lambda) \wedge w . \tag{3.38}
\end{align*}
$$

Note that $\operatorname{dim}(\operatorname{im} T) \leq \operatorname{dim}\left(\wedge^{6} V^{*}\right)=1$. So from rank-nullity theorem, we have $\operatorname{dim}(\operatorname{ker} T) \geq 5$, which means that the kernel should consist of at least 5 linearly independent 1 -forms. Let $w^{0}, w^{1}, w^{2}, w^{3}, w^{4}$ be linearly independent 1 -forms in the kernel. Then extend the set of these 1 -forms to a basis $w^{0}, w^{1}, w^{2}, w^{3}, w^{4}, w^{5}$ in $V^{*}$. This allows us to write the 5 -form $* \lambda$ as

$$
\begin{align*}
* \lambda= & \lambda_{01234} w^{0} \wedge w^{1} \wedge w^{2} \wedge w^{3} \wedge w^{4}+\lambda_{01235} w^{0} \wedge w^{1} \wedge w^{2} \wedge w^{3} \wedge w^{5} \\
& +\lambda_{01245} w^{0} \wedge w^{1} \wedge w^{2} \wedge w^{4} \wedge w^{5}+\lambda_{01345} w^{0} \wedge w^{1} \wedge w^{3} \wedge w^{4} \wedge w^{5}  \tag{3.39}\\
& +\lambda_{02345} w^{0} \wedge w^{2} \wedge w^{3} \wedge w^{4} \wedge w^{5}+\lambda_{12345} w^{1} \wedge w^{2} \wedge w^{3} \wedge w^{4} \wedge w^{5}
\end{align*}
$$

Since $w^{0}, w^{1}, w^{2}, w^{3}, w^{4} \in \operatorname{ker} T$, we have

$$
\begin{equation*}
(* \lambda) \wedge w^{0}=(* \lambda) \wedge w^{1}=(* \lambda) \wedge w^{2}=(* \lambda) \wedge w^{3}=(* \lambda) \wedge w^{4}=0 . \tag{3.40}
\end{equation*}
$$

So

$$
\begin{equation*}
\lambda_{12345}=\lambda_{02456}=\lambda_{01345}=\lambda_{01245}=\lambda_{01235}=0 . \tag{3.41}
\end{equation*}
$$

This leaves us with

$$
\begin{equation*}
* \lambda=\lambda_{01234} w^{0} \wedge w^{1} \wedge w^{2} \wedge w^{3} \wedge w^{4}, \tag{3.42}
\end{equation*}
$$

which indeed shows that any 5 -form in $\Lambda^{5} V^{*}$ where $\operatorname{dim} V^{*}=6$ is always decomposable in terms of a wedge product of 51 -forms.

The above proof works for tensors but not necessarily tensor fields as in the case of our concern. Nevertheless, we suppose that after some suitable restrictions, if any, the above result can also be applied. This means that the theorem suggests that a generic 5 -form $* \lambda$ can be written as, modulo some possible restrictions when generalising from tensors to tensor fields,

$$
\begin{align*}
* \lambda & =l(x) w^{0}(x) \wedge w^{1}(x) \wedge w^{2}(x) \wedge w^{3}(x) \wedge w^{4}(x) \\
& =l(x) \frac{1}{5!} \epsilon_{s_{0} s_{1} s_{2} s_{3} s_{4}} w^{s_{0}}(x) \wedge w^{s_{1}}(x) \wedge w^{s_{2}}(x) \wedge w^{s_{3}}(x) \wedge w^{s_{4}}(x) . \tag{3.43}
\end{align*}
$$

Next, applying the condition $d * \lambda=0$ gives

$$
\begin{align*}
0= & \frac{1}{5!} \epsilon_{s_{0} s_{1} s_{2} s_{3} s_{4}} d l(x) \wedge w^{s_{0}}(x) \wedge w^{s_{1}}(x) \wedge w^{s_{2}}(x) \wedge w^{s_{3}}(x) \wedge w^{s_{4}}(x)  \tag{3.44}\\
& +l(x) \frac{1}{4!} \epsilon_{s_{0} s_{1} s_{2} s_{3} s_{4}} w^{s_{0}}(x) \wedge w^{s_{1}}(x) \wedge w^{s_{2}}(x) \wedge w^{s_{3}}(x) \wedge d w^{s_{4}}(x),
\end{align*}
$$

which is implied by

$$
\begin{equation*}
d l=d w^{s}=0, \quad s \in\{0, \cdots, 4\} . \tag{3.45}
\end{equation*}
$$

Note that this is not necessarily a general solution. Our goal is simply to look for a possible reduction of a 4 -form, use it as auxiliary field in the covariantisation, and see if it solves the issues discussed in subsection 3.2. So a special solution to eq. (3.44) is sufficient for our purpose. However, it will be interesting for future investigation to see what a general solution looks like, and whether it would also eventually serve the purpose. The solution (3.45) is solved by

$$
\begin{equation*}
l=\text { const. } \equiv-1, \quad w^{s}=d a^{s}, \quad s \in\{0, \cdots, 4\} . \tag{3.46}
\end{equation*}
$$

So

$$
\begin{equation*}
* \lambda=-d a^{0} \wedge d a^{1} \wedge d a^{2} \wedge d a^{3} \wedge d a^{4} \tag{3.47}
\end{equation*}
$$

We will make use of this decomposition in the construction of covariant formulation of dual M5-brane. This means that the solution $\tilde{\lambda}=* d \chi$ to $d * \tilde{\lambda}=0$ is restricted as

$$
\begin{equation*}
\tilde{\lambda}|\equiv \tilde{\lambda}|_{\chi=-d a^{0} \wedge d a^{1} \wedge d a^{2} \wedge d a^{3} a^{4}}=-*\left(d a^{0} \wedge d a^{1} \wedge d a^{2} \wedge d a^{3} \wedge d a^{4}\right)=\lambda . \tag{3.48}
\end{equation*}
$$

### 3.4 Quadratic dual action of a 6 d chiral 2 -form with five auxiliary scalars

In this subsection, we construct and show in detail that the restriction made by eq. (3.48) allows the successful covariantisation of the quadratic action of the 6 d chiral 2 -form in the dual formulation.

Applying the restriction (3.48) to the action (3.19) gives

$$
\begin{equation*}
\left.S=\int \frac{1}{2} F \wedge \tilde{\mathcal{P}}^{\perp} \right\rvert\, \mathcal{F} \tag{3.49}
\end{equation*}
$$

where

$$
\begin{equation*}
\tilde{\mathcal{P}}\left|\equiv \operatorname{tr}\left(\bigwedge \tilde{\mathcal{P}}\left|\bigwedge^{2} \tilde{P}^{\perp}\right|\right), \quad \tilde{\mathcal{P}}^{\perp}\right| \equiv \operatorname{tr}\left(\bigwedge^{3} \tilde{P}^{\perp} \mid\right) \tag{3.50}
\end{equation*}
$$

with

$$
\begin{equation*}
\left.\tilde{P}\left|=\frac{g^{-1}(\tilde{\lambda} \mid) \otimes \tilde{\lambda} \mid}{g^{-1}(\tilde{\lambda}|, \tilde{\lambda}|)} \equiv \frac{g^{-1}(\lambda) \otimes \lambda}{g^{-1}(\lambda, \lambda)}, \quad \tilde{P}^{\perp}\right|=\mathbb{1}-\tilde{P} \right\rvert\, \tag{3.51}
\end{equation*}
$$

and the symbol $\mid$ denotes the restriction (3.48) to the choices of five auxiliary scalars. Since $\lambda$ is expressed by eq. (3.47), the action (3.49) requires 5 auxiliary scalar fields $a^{s}, s=$ $0,1,2,3,4$ via the gradients $d a^{s}$.

The projector matrices $P_{\mu}^{\nu}, P_{\mu}^{\perp}$ defined in the eq. (2.16) can also be written as

$$
\begin{equation*}
P=Y_{r s}^{-1} g^{-1}\left(\zeta^{r}\right) \otimes \zeta^{s} \equiv g^{-1}\left(\zeta_{s}\right) \otimes \zeta^{s}, \quad P^{\perp}=\mathbb{1}-P \tag{3.52}
\end{equation*}
$$

where $\zeta^{s}=d a^{s}, \zeta_{r} \equiv Y_{r s}^{-1} \zeta^{s}$. The fact that ranks of $P$ and $P^{\perp}$ are 5 and 1, respectively, are symbolically represented by

$$
\begin{equation*}
\bigwedge^{6} P=0=\bigwedge^{2} P^{\perp} \tag{3.53}
\end{equation*}
$$

Then

$$
\begin{align*}
\bigwedge^{6} \mathbb{1} & =\bigwedge^{6}\left(P+P^{\perp}\right) \\
& =\operatorname{tr}\left(\bigwedge^{5} P \bigwedge^{\perp}\right) . \tag{3.54}
\end{align*}
$$

Next, let us denote

$$
\begin{equation*}
\mathcal{P} \equiv \bigwedge^{3} P, \quad \mathcal{P}^{\perp} \equiv \operatorname{tr}\left(\bigwedge^{2} P \bigwedge P^{\perp}\right), \quad \mathcal{I} \equiv \bigwedge^{3} \mathbb{1} \tag{3.55}
\end{equation*}
$$

They satisfy the following identities

$$
\begin{equation*}
\mathcal{P}+\mathcal{P}^{\perp}=\mathcal{I}, \quad \mathcal{P} \bigwedge \mathcal{I}=\mathcal{I} \bigwedge \mathcal{P}^{\perp}, \quad \mathcal{I} \bigwedge \mathcal{P}=\mathcal{P}^{\perp} \bigwedge \mathcal{I} \tag{3.56}
\end{equation*}
$$

Let us now verify the identity (2.20). By direct calculation, this gives

$$
\begin{equation*}
g^{-1}(\lambda) \otimes \lambda=-\operatorname{det} Y(\mathbb{1}-P) \tag{3.57}
\end{equation*}
$$

So

$$
\begin{equation*}
g^{-1}(\lambda, \lambda)=-\operatorname{det} Y(6-5)=-\operatorname{det} Y \tag{3.58}
\end{equation*}
$$

and hence

$$
\begin{align*}
\tilde{P} \mid & =\frac{g^{-1}(\lambda) \otimes \lambda}{g^{-1}(\lambda, \lambda)} \\
& =\mathbb{1}-P  \tag{3.59}\\
& =P^{\perp},
\end{align*}
$$

as required. Using identity (2.20), with the definitions (3.16) and (3.55), the action (3.49) can be rewritten as

$$
\begin{equation*}
S=\frac{1}{2} \int F \wedge \mathcal{P} \mathcal{F} . \tag{3.60}
\end{equation*}
$$

Next, let us discuss the computation of the variation of the action (3.60). The variation of the action with respect to $B$ can be computed using the identities (3.56) as well as

$$
\begin{equation*}
* \mathcal{P}=\mathcal{P}^{\perp} * . \tag{3.61}
\end{equation*}
$$

The variation is done as follows

$$
\begin{align*}
\delta_{(B)} S & =\int \frac{1}{2} \delta F \wedge \mathcal{P} \mathcal{F}+\frac{1}{2} F \wedge \mathcal{P} \delta F-\frac{1}{2} F \wedge \mathcal{P} * \delta F \\
& =\int \frac{1}{2} \delta F \wedge\left(\mathcal{P} \mathcal{F}-\mathcal{P}^{\perp} F-\mathcal{P} * F\right) \\
& =\int \delta F \wedge \mathcal{P} \mathcal{F}-\frac{1}{2} \delta F \wedge F  \tag{3.62}\\
& =\int \delta B \wedge d(\mathcal{P F})-\frac{1}{2} d(\delta B \wedge(2 \mathcal{P} \mathcal{F}-F)) .
\end{align*}
$$

As for the variation of the action with respect to $a^{s}$, it is useful to first consider the variation of the projector $P=g^{-1}\left(\zeta_{s}\right) \otimes \zeta^{s}$ with respect to $a^{s}$ :

$$
\begin{equation*}
\delta_{(a)} P=P^{\perp} g^{-1}\left(\delta \zeta^{s}\right) \otimes \zeta_{s}+g^{-1}\left(\zeta_{s}\right) \otimes P^{\perp} \delta \zeta^{s} . \tag{3.63}
\end{equation*}
$$

Then from an identity

$$
\begin{equation*}
\mathcal{P F}=-2 \mathcal{F}+\zeta^{s} \wedge i_{g^{-1} \zeta_{s}} \mathcal{F}, \tag{3.64}
\end{equation*}
$$

we can use eq. (3.63) to read off

$$
\begin{equation*}
\delta_{(a)} \mathcal{P F}=\zeta_{s} \wedge i_{P \perp^{-1}\left(\delta \zeta^{s}\right)} \mathcal{F}+P^{\perp} \delta \zeta^{s} \wedge i_{g^{-1}\left(\zeta_{s}\right)} \mathcal{F} . \tag{3.65}
\end{equation*}
$$

Further calculation gives

$$
\begin{equation*}
\delta_{(a)} \mathcal{P F}=(1+*)\left(P^{\perp} \delta \zeta^{s} \wedge i_{g^{-1} \zeta_{s}} \mathcal{F}\right) . \tag{3.66}
\end{equation*}
$$

Then the variation of the action with respect to $a^{s}$ can be done as follows

$$
\begin{align*}
\delta_{(a)} S & =\frac{1}{2} \int F \wedge(1+*)\left(P^{\perp} \delta \zeta^{s} \wedge i_{g^{-1} \zeta_{s}} \mathcal{F}\right) \\
& =-\frac{1}{2} \int \delta \zeta^{s} \wedge \mathcal{P} \mathcal{F} \wedge i_{g^{-1} \zeta_{s}} \mathcal{P F}  \tag{3.67}\\
& =-\int \delta a^{s} i_{g^{-1} \zeta_{s}}(\mathcal{P F}) \wedge d(\mathcal{P F})+\frac{1}{2} \int d\left(\delta a^{s} \mathcal{P} \mathcal{F} \wedge i_{g^{-1} \zeta_{s}} \mathcal{P F}\right) .
\end{align*}
$$

In the last step, we use the identity

$$
\begin{equation*}
d\left(\mathcal{P} F_{1} \wedge i_{g^{-1} \zeta_{s}} \mathcal{P} F_{2}\right)=d \mathcal{P} F_{1} \wedge i_{g^{-1} \zeta_{s}} \mathcal{P} F_{2}+i_{g^{-1} \zeta_{s}} \mathcal{P} F_{1} \wedge d \mathcal{P} F_{2}, \tag{3.68}
\end{equation*}
$$

which is valid for any 3 -forms (as well as 3 -form superfields) $F_{1}$ and $F_{2}$. This can be shown by using Leibniz rules for $d$ and $i_{g^{-1} \zeta_{s}}$, Cartan's magic formula, and the identity

$$
\begin{equation*}
\mathcal{L}_{g^{-1} \zeta_{s}} P=\left[g^{-1} \zeta_{s}, g^{-1} \zeta_{r}\right] \otimes \zeta^{r}, \tag{3.69}
\end{equation*}
$$

where $[\cdot, \cdot]$ is a Lie bracket.
Combining eq. (3.62), and eq. (3.67) gives

$$
\begin{align*}
\delta_{(B)} S+\delta_{(a)} S= & \int\left(\delta B-\delta a^{s} i_{g^{-1} \zeta_{s}}(\mathcal{P F})\right) \wedge d(\mathcal{P F}) \\
& -\int \frac{1}{2} d(\delta B \wedge(2 \mathcal{P F}-F))+\frac{1}{2} \int d\left(\delta a^{s} \mathcal{P} \mathcal{F} \wedge i_{g^{-1} \zeta_{s}} \mathcal{P F}\right) . \tag{3.70}
\end{align*}
$$

This gives the field equations for $B$, and $a^{s}$ :

$$
\begin{array}{r}
d(\mathcal{P F})=0, \\
i_{g^{-1} \zeta_{s}}(\mathcal{P F}) \wedge d(\mathcal{P F})=0, \tag{3.72}
\end{array}
$$

So clearly, the field equations for $a^{s}$ are implied by the field equations for $B$. The variation (3.70) can also be used to read off the PST1 and PST2 symmetries. PST1 symmetry is only due to the transformation of $B$. So it should satisfy

$$
\begin{equation*}
\mathcal{P}^{\perp} d \delta B=0, \quad \delta a^{s}=0 . \tag{3.73}
\end{equation*}
$$

The form of $\delta B$ which solves this condition is given by

$$
\begin{align*}
\delta B & =\operatorname{tr}\left(\bigwedge^{2} P\right) \Phi  \tag{3.74}\\
& =\frac{1}{2} \psi_{r s} d a^{s} \wedge d a^{r},
\end{align*}
$$

where $\psi_{r s}=i_{g^{-1} \zeta_{s}} i_{g^{-1} \zeta_{r}} \Phi$. Then

$$
\begin{equation*}
\mathcal{P}^{\perp} d \delta B=\frac{1}{2} P^{\perp} d \psi_{r s} \wedge d a^{s} \wedge d a^{r} . \tag{3.75}
\end{equation*}
$$

So the condition (3.73) implies that

$$
\begin{equation*}
P^{\perp} d \psi_{r s}=0 . \tag{3.76}
\end{equation*}
$$

Note that since

$$
\begin{equation*}
P^{\perp} d a^{r}=0, \tag{3.77}
\end{equation*}
$$

$\psi_{r s}$ should be a function of $a^{w}$. So PST1 symmetry is given by

$$
\begin{equation*}
\delta B=\frac{1}{2} \psi_{r s}\left(a^{w}\right) d a^{s} \wedge d a^{r}, \quad \delta a^{s}=0, \tag{3.78}
\end{equation*}
$$

which is semi-local. The analogous form $[14,15,26]$ can be seen in the covariant version of Floreanini-Jackiw $d=2$ chiral boson theory [19]. As for PST2 symmetry, it involves the variations of $B$, and $a^{s}$. This symmetry can easily be read off from the equation (3.70) giving

$$
\begin{equation*}
\delta a^{s}=\varphi^{s}, \quad \delta B=\varphi^{s} i_{g^{-1} \zeta_{s}}(\mathcal{P F}) \tag{3.79}
\end{equation*}
$$

The PST2 symmetry is used to ensure that the auxiliary fields $a^{s}$ are arbitrary. Therefore, it is not surprising that the field equations of the auxiliary scalars, eq. (3.72) are implied by the field equations of $B$, eq. (3.71).

To complete the analysis of the action (3.60), we need to investigate the possible case in which the second order field equation (3.71) is equivalent to self-duality condition. For this let us closely follow the analysis given by [20]. We first note that the action and field equations are singular when $g^{-1}(\lambda, \lambda)=0$. This separates the dynamical system into two branches: that with $g^{-1}(\lambda, \lambda)>0$, and that with $g^{-1}(\lambda, \lambda)<0$. To see that the two branches are really separated, one considers a generic integral curve generated by PST2 transformation. Let $h$ be a parameter along the integral curve, then given $a^{s}=a_{(0)}^{s}$ at $h=0$, the scalars evolve as

$$
\begin{equation*}
a_{(h)}^{s}=a_{(0)}^{s}+h \varphi^{s} \tag{3.80}
\end{equation*}
$$

Then

$$
\begin{equation*}
g^{-1}\left(\lambda_{(h)}, \lambda_{(h)}\right)=g \operatorname{det} Y_{(h)} \tag{3.81}
\end{equation*}
$$

where $\lambda_{(h)}$ is given as in eq. (3.47) with $a^{s}$ replaced by $a_{(h)}^{s}$, and $\operatorname{det} Y_{(h)}$ is the determinant of a matrix

$$
\begin{equation*}
Y_{(h)}^{r s}=\left(\partial_{\mu} a_{(0)}^{r}+h \partial_{\mu} \varphi^{r}\right) g^{\mu \nu}\left(\partial_{\nu} a_{(0)}^{s}+h \partial_{\nu} \varphi^{s}\right) \tag{3.82}
\end{equation*}
$$

It can then be seen that along the curve, the value of $g^{-1}(\lambda, \lambda)$ varies smoothly. Therefore, if a curve connects a point with $g^{-1}(\lambda, \lambda)>0$, and another point with $g^{-1}(\lambda, \lambda)<0$, then it should inevitably pass through the singular region with $g^{-1}(\lambda, \lambda)=0$. The two branches of the dynamical system will need to be studied separately to see which branch would give self-duality condition. For this, one needs the PST1 symmetry to be a gauge symmetry. A criteria for this is that the PST1 symmetry is a gauge symmetry if its Noether's charge vanishes [21]. The Noether's current is

$$
\begin{equation*}
j=-*\left(\left(\operatorname{tr}\left(\wedge^{2} P\right) \Phi\right) \wedge \mathcal{P} \mathcal{F}\right) \tag{3.83}
\end{equation*}
$$

It can be shown that $j^{0}=0$ when $\lambda^{0}=0$. This is the case only in the $g^{-1}(\lambda, \lambda)>0$ branch, in which PST2 gauge transformation can be used to gauge-fix $a^{s}=x^{s}$, giving $\lambda^{0}=0$. So in this branch PST1 is a gauge symmetry, and can be used to gauge fix the equation (3.71) to a self-duality condition

$$
\begin{equation*}
F=* F \tag{3.84}
\end{equation*}
$$

On the other hand, PST1 is a global symmetry in the $g^{-1}(\lambda, \lambda)<0$ branch. Therefore, in this branch one does not obtain self-duality condition from a gauge-fixing of field equation.

By fixing the gauge

$$
\begin{equation*}
a^{s}=x^{s} \tag{3.85}
\end{equation*}
$$

and demanding that the combined PST2 and 6d diffeomorphism transformation does not modify this gauge condition, one obtains

$$
\begin{equation*}
\varphi^{s}=-\epsilon^{s} \tag{3.86}
\end{equation*}
$$

where $\epsilon^{\mu}$ is a 6 d diffeomorphism parameter. Under the combined PST2 and 6 d diffeomorphism transformation, $B_{2}$ transforms as

$$
\begin{equation*}
B=\mathcal{L}_{\epsilon} B-2 \frac{\epsilon^{s}}{g_{55}} d x^{p q} g_{5[5} \mathcal{F}_{s q p]} \tag{3.87}
\end{equation*}
$$

which is a modified diffeomorphism transformation rule of the non-manifest covariant chiral 2 -form with quadratic action in dual formulation. It also exactly agrees with eq. (3.37) which was intended to come from exactly the same theory.

Having reviewed quadratic action of chiral 2 -form in dual formulation covariantised using an auxiliary 4 -form $[14,15]$ in subsection 3.2 , and having presented the alternative covariantisation of the theory using 5 auxiliary scalars in this subsection, let us give a remark on whether these two actions are related. A 4 -form field has 15 components. However, the reducible tensor gauge symmetry reduces the number of components to be $15-(20-(15-(6-1)))=5$ which agrees with the number of scalar fields we introduced. In fact, an example of the relationship can be seen from eq. (3.48) which suggests that 5 auxiliary scalars give a particular choice of $\chi$, i.e. $\chi=-d a^{0} \wedge d a^{1} \wedge d a^{2} \wedge d a^{3} a^{4}$. Given $a^{s}$, other equivalent choices of $\chi$ can also be made for example

$$
\begin{equation*}
\chi=-a^{0} d a^{1} \wedge d a^{2} \wedge d a^{3} \wedge d a^{4} \tag{3.88}
\end{equation*}
$$

which is related to the choice of eq. (3.48) by the tensor gauge transformation $\delta \chi=$ $d\left(a^{0} a^{4} d a^{1} \wedge d a^{2} \wedge d a^{3}\right)$. Furthermore, in the gauge (3.85) for $a^{s}$, the choice (3.88) reduces to eq. (3.33) which is the corresponding gauge choice of $\chi$. Another notable choice of $\chi$ in terms of given $a^{s}$ is

$$
\begin{equation*}
\chi=\frac{1}{5!} \epsilon_{a b c d e 5} x^{\underline{a}} d x^{\underline{b}} \wedge d x^{\underline{c}} \wedge d x^{\underline{d}} \wedge d x^{\underline{e}}, \tag{3.89}
\end{equation*}
$$

which is related to the choice (3.48) by the tensor gauge transformation

$$
\begin{equation*}
\delta \chi=\frac{4}{5} d\left(a^{4} a^{[0} d a^{1} \wedge d a^{2} \wedge d a^{3]}\right) . \tag{3.90}
\end{equation*}
$$

In the gauge (3.85), the choice (3.89) reduces to eq. (3.34).
Having seen explicit examples of the relationship between the two types of auxiliary fields, a natural question to ask is whether the 5 auxiliary fields give a parametrisation of the independent components of the auxiliary 4 -form field. In order for the parametrisation to valid, one needs to check at the level of the field equation to see if the equations (3.22)-(3.23) would reduce, after setting $\chi$ for example as in eq. (3.48), to the equations (3.71)-(3.72). While we still do not have a direct check, there is a supporting evidence that this could be the case; the full check will be left as a future work. Previously, we have investigated that for $\chi$ in the gauge (3.34), where the theory reduces to a non-manifest covariant chiral 2 -form
with quadratic action in dual formulation, the equations (3.22)-(3.23) are equivalent to selfduality condition $F=* F$. For 5 auxiliary scalar in the gauge (3.85), which corresponds to $\chi$ in the gauge (3.34), the equations (3.71)-(3.72) also reduce to self-duality condition $F=* F$. Furthermore, the modified diffeomorphism transformations (3.37) for the theory with gauge-fixed 4 -form agrees with the one (3.87) for the theory with gauge-fixed 5 scalars.

### 3.5 Nonlinear dual action of a 6 d chiral 2-form with five auxiliary scalars

Having obtained a quadratic action for a 6 d chiral 2 -form theory with five auxiliary scalars and shown that it indeed has desirable properties, let us now extend it to a non-linear action. By looking, for example, at the non-manifestly covariant M5-brane action in the dual formulation [16], it is natural to write down the action

$$
\begin{equation*}
\left.S=\int d^{6} x \sqrt{-g}\left(-\sqrt{\operatorname{det}\left(\delta_{\mu}^{\nu}+(F \cdot v)_{\mu}{ }^{\nu}\right.}\right)+\frac{1}{4}(\tilde{F} \cdot v)^{\mu \nu}(F \cdot v)_{\mu \nu}\right), \tag{3.91}
\end{equation*}
$$

where

$$
\begin{gather*}
(F \cdot v)_{\mu \nu}=F_{\mu \nu \rho} v^{\rho}, \quad(\tilde{F} \cdot v)_{\mu \nu}=\tilde{F}_{\mu \nu \rho} v^{\rho},  \tag{3.92}\\
v_{\mu}=\frac{\lambda_{\mu}}{\sqrt{g^{-1}(\lambda, \lambda)}}, \quad \tilde{F}^{\mu \nu \rho}=\frac{1}{6 \sqrt{-g}} \epsilon^{\mu \nu \rho \lambda \sigma \tau} F_{\lambda \sigma \tau} . \tag{3.93}
\end{gather*}
$$

Let us show that this action indeed has desirable properties. We first start from the variation of the action,

$$
\begin{align*}
\delta_{(B)} S+\delta_{(a)} S= & -\int\left(\delta B+\delta a^{s} i_{g^{-1} \zeta_{s}} * \mathcal{P}^{\perp}(W-* F)\right) \wedge d * \mathcal{P}^{\perp}(W-* F) \\
& +\frac{1}{2} \int d\left(\delta B \wedge\left(2 * \mathcal{P}^{\perp}(W-* F)+F\right)\right)  \tag{3.94}\\
& +\frac{1}{2} \int d\left(\delta a^{s} * \mathcal{P}^{\perp}(W-* F) \wedge i_{g^{-1} \zeta_{s}} * \mathcal{P}^{\perp}(W-* F)\right),
\end{align*}
$$

where

$$
\begin{gather*}
W=\frac{1}{3!} d x^{\mu} \wedge d x^{\nu} \wedge d x^{\rho} W_{\rho \nu \mu},  \tag{3.95}\\
W_{\mu \nu \rho}=\frac{\left(1+\frac{1}{2}(F \cdot v)_{\lambda \sigma}(F \cdot v)^{\lambda \sigma}\right) F_{\mu \nu \rho}+\frac{3}{2}(F \cdot v)_{[\mu \mid \sigma}(F \cdot v)^{\sigma \lambda} F_{\lambda \mid \nu \rho]}}{\left.\sqrt{\operatorname{det}\left(\delta_{\mu}^{\nu}+(F \cdot v)_{\mu} \nu\right.}\right)} \tag{3.96}
\end{gather*}
$$

The variation (3.94) can be obtained by using tools and steps similar to the quadratic action, in particular the identity (3.68). We also use the identity

$$
\begin{equation*}
i_{g^{-1} \zeta_{s}} * \mathcal{P}^{\perp} W \wedge * \mathcal{P}^{\perp} W=i_{g^{-1} \zeta_{s}} * \mathcal{P}^{\perp} F \wedge * \mathcal{P}^{\perp} F . \tag{3.97}
\end{equation*}
$$

Using the variation of the action, the field equations for $B$, and $a^{s}$ are

$$
\begin{gather*}
d * \mathcal{P}^{\perp}(W-* F)=0,  \tag{3.98}\\
i_{g^{-1} \zeta_{s}} * \mathcal{P}^{\perp}(W-* F) \wedge d * \mathcal{P}^{\perp}(W-* F)=0, \tag{3.99}
\end{gather*}
$$

which is clear that the field equations for $a^{s}$ are implied by the field equations for $B$. Next, the PST1 symmetry reads

$$
\begin{equation*}
\delta B=\frac{1}{2} \psi_{r s}\left(a^{w}\right) d a^{s} \wedge d a^{r}, \quad \delta a^{s}=0 \tag{3.100}
\end{equation*}
$$

In the case where PST1 is a gauge symmetry, it will be used to gauge fix the field equation for $B$ to give

$$
\begin{equation*}
\mathcal{P}^{\perp}(W-* F)=0 \tag{3.101}
\end{equation*}
$$

or

$$
\begin{equation*}
i_{g^{-1} v} * F=i_{g^{-1} v} W \tag{3.102}
\end{equation*}
$$

Next, PST2 Symmetry is given by

$$
\begin{equation*}
\delta a^{s}=\varphi^{s}, \quad \delta B=-\varphi^{s} i_{g^{-1} \zeta_{s}} * \mathcal{P}^{\perp}(W-* F) \tag{3.103}
\end{equation*}
$$

which can be used to ensure that the $a^{s}$ are indeed auxiliary.
By a similar analysis to the previous subsection, it can also be concluded that in the $g^{-1}(\lambda, \lambda)>0$ branch the second order field equation (3.98) can be gauge-fixed to give nonlinear self-duality condition (3.102), whereas in the $g^{-1}(\lambda, \lambda)<0$ branch, the second order field equation is not gauge equivalent to nonlinear self-duality condition.

Having shown that the action (3.94) has desirable properties, it is then natural to extend this action to a complete M5-brane action in the dual formulation (2.21). As for the symmetries, it can be easily checked that the conventional abelian gauge symmetry and the PST1 symmetry are not modified, whereas the PST2 symmetry is modified by having all $F$ promoted to $H=F+C$. As well as the bosonic symmetries, the couple of the M5-brane to an 11d supergravity background also enjoys a local fermionic symmetry called kappa-symmetry. The check of kappa-symmetry can easily be done by following the standard techniques used for example in $[7,8]$.

## 4 Gauge-fixing auxiliary fields

In [16], the non-manifest covariant M5-brane action in the dual formulation coupled to 11d supergravity background was presented and shown that the theory is justified. The checks were done by using constrained analysis, comparison of on-shell actions, and double dimensional reduction to D 4 -brane.

It can be shown that the covariant M5-brane action in the dual formulation coupled to 11d supergravity background presented in section 2.2 can be reduced to the action of [16]. Let us start by using the PST2 symmetry (2.26) of the action (2.21) to fix the gauge

$$
\begin{equation*}
a^{s}=x^{s}, \quad \text { so } \quad \partial_{\mu} a^{s}=\delta_{\mu}^{s} \tag{4.1}
\end{equation*}
$$

This gives

$$
\begin{equation*}
\lambda^{\mu}=\frac{\delta_{5}^{\mu}}{\sqrt{-g}}, \quad \lambda_{\mu}=\frac{g_{\mu 5}}{\sqrt{-g}} \tag{4.2}
\end{equation*}
$$

and hence

$$
\begin{array}{rlrl}
v^{\mu} & =\frac{\delta_{5}^{\mu}}{\sqrt{g_{55}}}, & =\frac{g_{\mu 5}}{\sqrt{g_{55}}}, \\
(H \cdot v)_{\mu \nu} & =\frac{H_{\mu \nu 5}}{\sqrt{g_{55}}}, & (\tilde{H} \cdot v)^{\mu \nu} & =\frac{1}{3!} \frac{\epsilon^{\mu \nu \rho \sigma \lambda \tau}}{\sqrt{-g}} H_{\sigma \lambda \tau} \frac{g_{\rho 5}}{\sqrt{g_{55}}} . \tag{4.4}
\end{array}
$$

It can easily be seen that in the gauge (4.1) the action (2.21) reduces to the non-manifestly covariant M5-brane action in the dual formulation constructed in [16]. Under the combined local transformation of PST2 and 6 d diffeomorphism $\delta x^{\mu}=\xi^{\mu}(x)$, the auxiliary fields transform as

$$
\begin{equation*}
\delta a^{s}(x)=\xi^{\mu}(x) \partial_{\mu} a^{s}(s)+\varphi^{s}(x)=\xi^{s}(x)+\varphi^{s}(x) . \tag{4.5}
\end{equation*}
$$

This combined transformation should not modify the gauge-fixing condition (4.1). So the PST2 gauge parameter should be chosen to be

$$
\begin{equation*}
\varphi^{s}(x)=-\xi^{s}(x), \tag{4.6}
\end{equation*}
$$

in which case, the combined local transformation on $B_{\mu \nu}$ is given by

$$
\begin{equation*}
\delta B_{\mu \nu}=\xi^{\rho} \partial_{\rho} B_{\mu \nu}+2 \partial_{[\nu} \xi^{\rho} B_{\mu] \rho}-\xi^{q}\left(4 \frac{1}{g_{55}} g_{5[5} H_{\mu \nu q]}+\epsilon_{\mu \nu q m n 5}\left(-\frac{1}{2} \frac{\mathcal{V}^{m n}}{\sqrt{g_{55}}} \sqrt{-g}\right)\right), \tag{4.7}
\end{equation*}
$$

We see that this is simply a modified diffeomorphism transformation obtained from the analysis in [16]. In particular, the modification only appears in the $\xi^{m}$ directions of the components $\delta B_{m n}$.

In [16], after presenting and analysing the non-manifestly covariant M5-brane action in the dual formulation, the analyses of comparison of on-shell actions, and of double dimensional reduction to D4-brane were discussed. These analyses do not require the use of auxiliary fields. So one can safely say that these analyses are indeed also valid for the covariant M5-brane action in the dual formulation.

So far in the literature, there are three alternative descriptions of the complete M5brane actions: (i) the original M5-brane action [7, 8]. (ii) the M5-brane action in the $3+3$ formulation [17, 18], and (iii) the M5-brane action in the dual formulation constructed in [16] and this paper. Although the off-shell actions from different descriptions are different from one another, it was shown that they all agree on-shell. The consequence of this is for example that these actions give the same value for the the tension of a string soliton solution.

The double dimensional reduction of M5-brane action in the dual formulation is done by compactifying one direction on M5-brane on a circle. The theory directly reduces to a D4-brane theory coupled to a ten-dimensional type IIA supergravity background [27, 28] without the need to make any further dualisation.

## 5 Conclusion

In this paper we have presented the covariant M5-brane action in dual formulation coupled to 11d supergravity background. The covariantisation of this theory is made possible
by using 5 auxiliary fields. It can be shown that by gauge-fixing PST2 symmetry, the constructed action can be reduced to the non-manifestly covariant version constructed and analysed in [16]. It is then evident that the action constructed in this paper inherits some properties from the the one constructed in [16].

We have demonstrated that at the quadratic level of the action, the covariantised action with 5 auxiliary scalar fields, eq. (3.49), can be obtained by replacing auxiliary 4 -form field in the action of $[14,15]$, which is written using differential form as eq. (3.19), by using eq. (3.48). Although the number of independent components of the auxiliary 4-form field is the same as that of the 5 auxiliary scalar fields, the substitution using eq. (3.48) at the action level does not necessarily mean that the 5 auxiliary scalar fields are result from a parametrisation of the auxiliary 4-form field. In fact, this has to be studied at the level of field equations. By gauge-fixing to non-manifestly covariant theory, we found a supporting evidence that this might be the case. However, it is still not enough to conclude in favour or against this. We leave the full verification as a future work.

In [18], the covariant M5-brane action coupled to 11d supergravity background is constructed with the help of 3 auxiliary fields. This result and the result of our paper suggests that PST covariantisation using more than 1 auxiliary scalar field is also possible. However, the paper [29] attempted to obtain a covariant M5-brane action using 2 auxiliary fields, but did not succeed.

As for self-dual fields in other dimensions, it is also interesting to investigate whether covariantisation using more than 1 auxiliary scalar field is possible. For example, we expect that for a chiral 4-form theory in 10 dimensions, the version with 9 auxiliary scalar fields is possible and is dual to the usual PST version with 1 auxiliary field. At the moment, this is just only an anticipation. We plan to work on this as a future work to see if this is really the case.

The PST covariantisation has also been used in duality-symmetric theories [30-32], which are the theories generalising the duality transformation between electric fields and magnetic fields. More recently, as a way to investigate and study counterterms in supergravity and string theory effective action, the non-linearisation of duality-symmetric action in 4 d is constructed and analysed in [33, 34]. The theory is covariantised in [35]. The covariantisation of the dual theory of this using 3 auxiliary scalar fields will be reported separately.

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[^0]:    ${ }^{1}$ The projector matrix $P^{\perp}$ was called $\Pi$ in [17] and [18]. The choice made in this paper is purely because of typesetting. For each projector matrix there is an induced projector, to be defined later, which are written using a calligraphic style. We simply have no access to calligraphic version of $\Pi$.

