

Regular motion of the Kovalevskaya problem for a rigid body rotating about a fixed point

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(*Nuovo Cimento B*, 109 (1994) 1175)

PACS 03.20 – Classical mechanics of discrete systems: general mathematical aspects.
PACS 46.90 – Other topics in applied classical mechanics.
PACS 99.10 – Errata.

On page 1175, formula (1), first line

$$2 \frac{dx_1}{d\tau} = \dots$$

should read

$$2 \frac{dx_1}{dt} = \dots$$

On page 1179, eq. (8)

$$V_i(0, x) = E$$

should read

$$V_i(x, 0) = E.$$