# On a class of partial differential equations of even order (*). 

by Alexander Weinstein (at College Park).

To Mauro Picone on his 70 binthday.

Summary. - The general solution for a class of equations of even order is expressed as a sum of solutions of equations of second order.

## 1. Introduction.

This paper deals with the general solution for a class of elliptic and hyperbolic partial differential equations of even order which includes some classical equations among which the best known is the equation for polyharmonic functions. As is well known, this equation gave rise to many outstanding papers from Almansi to Proone [1]. For this reason the author hopes that the following modest contribution is not out of place as a tribute to Professor Mauro Picone on the occasion of his anniversary.

Before going into the general theory let us illustrate our results on the example of the biharmonic equation $\Delta \Delta w=0$ where $w$ will be, as all functions in the following, considered as a function of the $m+1$ variables $x_{1}, x_{2}, \ldots, x_{m+1}$. One of the variables, say $x_{m+1}$, will play a special role in our considerations and will be denoted by $y$. We shall also use often the abbreviation $x$ for the set $x_{1}, x_{2}, \ldots, x_{m}$. A classical result of Almansi states that every regular solution of the biharmonic equation can be written in the form $w=h+y h_{1}$, where $h$ and $h_{1}$ are harmonic functions satisfying $\Delta u=0$ in the $m+1$ variables $\left(x_{1}, \ldots, x_{m}, y\right)$. The interesting feature of this decomposition is that the first term $h$ satisfies a partial differential equation of the second order while the second term $y h_{1}$ is itself a biharmonic function of a special type and satisfies an equation of the fourth order. The same remark is true for the other decompositions considered by Atmansi; for instance $w=h+r^{2} h_{1}$ where $r^{2}=x_{1}^{2}+\ldots+x_{m}^{2}+y^{2}$. Let us compare the biharmonic equation to the equation $\Delta(\Delta+\varepsilon) w=0$ where $\varepsilon$ is a constant. The general solution of this equation is $w=h+v$ where $\Delta h=0$ and $\Delta v+\varepsilon v=0$ (see [8, p. 15]). This means that the solution $w$ of an equation

[^0]of fourth order appears here as the sum two functions, each satisfying an equation of the second order. This property seemingly disappears if we put $\varepsilon$ equal to zero, and it is easily checked that the decomposition of certain solutions of our fourth order equation tends formally to ALmansi's decomposition of the biharmonic equation.

It will be one of the purposes of this paper to show that, using some recent results, it is possible to find a decomposition of a biharmonic function into a sum of two functions each satisfying an equation of the second order (see equation (3.3)) which occurs in generalized axially symme. tric potential theory.

## 2. Two Differential Operators.

In this paragraph we will consider two differential operators; namely,

$$
\begin{equation*}
\frac{\partial^{2}}{\partial x_{1}^{2}}+\ldots+\frac{\partial^{2}}{\partial x_{m}^{2}}+\frac{\partial^{2}}{\partial y^{2}}+\frac{k}{y} \frac{\partial}{\partial y} \tag{2.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\partial^{2}}{\partial x_{1}^{2}}+\ldots+\frac{\partial^{2}}{\partial x_{m}^{2}}-\frac{\partial^{2}}{\partial y^{2}}-\frac{k}{y} \frac{\partial}{\partial y} \tag{2.2}
\end{equation*}
$$

where $k$ is a real parameter, $-\infty<k<\omega$. The first operator is elliptic and occurs in generalized axially symmetric potential theory which we denote fort short by GASPT [2]. The second operator is hyperbolic and appears in the theory of the Euler-Poisson-Darboux (abbreviated EPD) equation [3, 4]. While the study of the two operators leads to essentially different problems, we shall use for both of them the same notation $L_{k}$ because only common properties of both operators will be used in the major part of this paper.

A solution of the partial differential equation of the second order

$$
\begin{equation*}
L_{k} u=0 \tag{2.3}
\end{equation*}
$$

will be denoted as $u^{k}$ or $u^{(k)}$. According to what was said previously $u^{k}$ may be a solution of an equation of GASPT or a solution of an EPD equation. In particular $u^{(0)}$ denotes either a harmonic function or, alternatively, a solution of the wave equation in an $m+1$ dimensional space or space time.

The basic common property of the two operators is that in both cases we have the following fundamental recursion formulas

$$
\begin{align*}
& u_{y}^{k}(x, y)=y u^{k+2}(x, y)  \tag{2.4}\\
& u^{k}(x, y)=y^{1-k} u^{2-k}(x, y) \tag{2.5}
\end{align*}
$$

As the present author stressed many times, these formulas reflect only an elementary property of the expression

$$
\begin{equation*}
u_{y y}+\frac{k}{y} u_{y} \tag{2.6}
\end{equation*}
$$

where $u$ is considered to be a function of a single variable $y$, the $x_{i}$ being parameters. For this reason the recursion formulas are valid for the solutions of any differential equation which is obtained by equating (2.6) to any linear differential operator which is free of the variable $y$. The recursion formula (2.4) defines $u^{(k+2)}$ in terms of $u^{(k)}$. However, if we rewrite (2.4) as

$$
\begin{equation*}
u^{(k)}(x, y)=\int_{b}^{y} \eta u^{(k+2)}(x, \eta) d \eta+f(x, b) \tag{2.7}
\end{equation*}
$$

where $f(x, b)$ are the values which $u^{(k)}$ takes for $y=b$, we may interpret it as an integral equation which yields a function $u^{(k)}$ from a function $u^{(k+2)}$. This integral equation will play an important role in the present paper. A similar equation plays a dominant part in the solution of the Cauchy problem for the EPD equation as will be briefly indicated in paragraph 3, Remark B.
3. Equations of the Fourth Order Associated with the Operator $L_{\beta}$.

In this paragraph we shall prove the following fundamental theorem. Theorem. - The general solution of the equation

$$
\begin{equation*}
L_{\alpha} L_{\beta} w=0, \quad \beta \neq \alpha-2 \tag{3.1}
\end{equation*}
$$

is given by the formula

$$
\begin{equation*}
w=u^{(8)}+u^{(x-2)} \tag{3.2}
\end{equation*}
$$

The only arbitrariness in this decomposition is that $u^{\alpha-2}$ and $u^{\beta}$ can be replaced by $u^{x-2}+h$ and $u^{\beta}-h$, respectively, where $h$ - is an arbitrary harmonic function of the variables $x_{1}, x_{2}, \ldots, x_{m}$. Our decomposition (3.2) is valid in any cylindrical domain of $m+1$ dimensional space with its base in base in the subspace $y=b=$ constant and with generators parallel to the $y$-axis, this cylinder lying entirely in the domain ef regularity of $w$. In the special case $\alpha=\beta=0$ we have the result that every biharmoaic function $w$ admits the decomposition

$$
\begin{equation*}
w=u^{(0)}+u^{(-2)} \tag{3.3}
\end{equation*}
$$

The appearance of axially symmetric functions in this decomposition is remarkable because the biharmonic function $w$ does not in general have any simmetric properties. For $m=1, u^{(0)}$ and $u^{\left(-z^{\prime}\right.}$ are STokes stream functions in a two and a four dimensional space, respectively. By our previous remark the same decomposition holds for the solution of the iterated wave equation.

To prove our theorem let us observe that it follows immediately from (3.1) by our definition of the differential operators that every solution $w$ of (3.1) satisfies the equation

$$
\begin{equation*}
L_{\beta} w=u^{(\alpha)} \tag{3.4}
\end{equation*}
$$

Conversely, any solution of (3.4) satisfies (3.1). Therefore, the proof of our theorem is reduced to the determination of the general solution $w$ of (3.4) for a given function $\boldsymbol{u}^{(\alpha)}$ which satisfies by definition the equation $L_{\alpha} u^{(\alpha)}=0$. We shall show as a first step that for $\beta-\alpha+2 \neq 0$ (3.4) admits a particular solution $w=u^{\alpha-2}$ so that

$$
\begin{equation*}
L_{\beta} u^{\alpha-2}=u^{\alpha} \tag{3.5}
\end{equation*}
$$

To this end let us observe that as $\beta=(\alpha-2)+(\beta-\alpha+2)$ and as $L_{\alpha-2} u^{\alpha-2}=0$ we have for any $u^{(\alpha-8)}$ the obvious identity

$$
\begin{align*}
L_{\beta} u^{(\alpha-2)} & \equiv \sum_{1}^{m} \frac{\partial^{2} u^{\alpha-2}}{\partial x_{i}{ }^{2}}+\frac{\partial^{z} u^{\alpha-s}}{\partial y^{2}}+\frac{\alpha-2}{y} \frac{\partial u^{\alpha-2}}{\partial y}  \tag{3.6}\\
& +\frac{\beta-\alpha+2}{y} \frac{\partial u^{\alpha-2}}{\partial y}=\frac{\beta-\alpha+2}{y} \frac{\partial u^{\alpha-2}}{\partial y}
\end{align*}
$$

For the sake of definiteness let us assume that in (3.6) and in the following proof, $L_{\beta}$ is the operator in GASPT as the proof for the EPD equation is entirely analogous. In view of (3.6), equation (3.5) can be replaced by the equation

$$
\begin{equation*}
\frac{\partial u^{\alpha-2}}{\partial y}=\frac{1}{\beta-\alpha+2} y u^{\alpha} \tag{3.7}
\end{equation*}
$$

This equation is obviously of the type of the recursion formala (2.4) with $u^{\alpha}$ being replaced by $\frac{1}{\beta-\alpha+2} u^{\alpha}$. As in paragraph 2, (3.7) leads to the integral equation

$$
\begin{equation*}
u^{\alpha-2}(x, y)=c \int_{b}^{y} \eta u^{\alpha}(x, \eta) d \eta+f(x, b) \tag{3.8}
\end{equation*}
$$

where

$$
c=\frac{1}{\beta-\alpha+2} .
$$

The value $y=b$ is assumed to be in the domain of regularity of $w$. It can be assumed without loss of generality that $b \neq 0$. The function $f(x, b)=$ $=f\left(x_{1}, \ldots, x_{m}, b\right)$ will now be determined by using the differential equation

$$
\begin{equation*}
L_{\alpha-2} u^{\alpha-2} \equiv \Delta_{x} u^{\alpha-2}+u_{y y}^{\alpha-2}+\frac{\alpha-2}{y} u_{y}^{\alpha-2}=0 \tag{3.9}
\end{equation*}
$$

where $\Delta_{x}$ denotes the operator $\sum_{i=1}^{m} \frac{\partial^{2}}{\partial x_{t}{ }^{2}}$. By (3.8) we have

$$
\begin{aligned}
\Delta_{x} \boldsymbol{u}^{\alpha-2} & =c \int_{b}^{y} \eta \Delta_{x} u^{\alpha}(x, \eta) d \eta+\Delta_{x} f(x, b) \\
& =-c \int_{b}^{y} \eta\left[u_{\eta n}^{\alpha}+\frac{\alpha}{\eta} u_{\eta}^{\alpha}\right] d \eta+\Delta_{x} f(x, b) .
\end{aligned}
$$

The integration on the right hand side can be performed in an elementary way and leads immediately to the following formula,

$$
\begin{align*}
& \Delta_{x} u^{\alpha-2}=-c\left\{y u_{n}^{\alpha}(x, y)-b u_{n}^{\alpha}(x, b)\right.  \tag{3.10}\\
& \left.-u^{\alpha}(x, y)+u^{\alpha}(x, b)+\alpha u^{\alpha}(x, y)-\alpha u^{\alpha}(x, b)\right\} \\
& +\Delta_{x} f(x, b) .
\end{align*}
$$

Further, by (3.8)

$$
\begin{equation*}
u_{y y}^{x-2}=c\left\{u^{\alpha}(x, y)+y u_{n}^{\alpha}(x, y)\right\} \tag{3.11}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\alpha-2}{y} u_{y}^{\alpha-2}=c(\alpha-2) u^{\alpha}(x, y) \tag{3.12}
\end{equation*}
$$

The sum of the left hand of (3.10), (3.11), (3.12) is by (3.9) equal to zero. Therefore, we have for the sum of the right hand sides the equation

$$
\begin{equation*}
\Delta_{\alpha} f(x, b)+c\left\{b u_{y}^{\alpha}(x, b)+(\alpha-1) u^{\alpha}(x, b)\right\}=0 . \tag{3.13}
\end{equation*}
$$

This equation is an $m$-dimensional Poisson equation for the function $f\left(x_{1}, \ldots, x_{m}, b\right)$ on the manifold $y=b$ and determines the unknown function $f(x, b)$ up to a harmonic function $h$ in $x_{1}, x_{2}, \ldots, x_{m}$. This last remark is confirmed by the fact that difference, $u_{1}^{x-i}-u_{2}^{\alpha-2}$, of the two solutions of (3.7) is a function $u^{\alpha-2}$ which is independent of $y$ and, therefore, by the equation $L_{\alpha-2} u^{\alpha-2}=0$ is a harmonic function in the $x$-space.

Once $f$ has been determined it is obvious that the right hand side of (3.8) defines indeed a function $u^{\alpha-2}$ satisfying the equation (3.4). As we have by (3.4) and (3.5)

$$
L_{\beta} w-L_{\beta} u^{\alpha-2}=L_{\beta}\left(w-u^{x-2}\right)=0
$$

it follows by the definition of a function $u^{\beta}$ that $w-\boldsymbol{u}^{\alpha-2}=u^{\beta}$ which proves our assertion (3.2). As $u^{\alpha-2}$ is determined up to an arbitrary harmonic function $h$ in $x_{1}, \ldots, x_{m}$, the function $u^{\beta}$ for a given $w$ is determined up to the function $-h$.

Remark (A). - The computation which leads to (3.6) yields for any values of $\beta$ and $\gamma$, the equation $L_{\beta} u r=\frac{\beta-\gamma}{y} \frac{\partial u r}{\partial y}$. The right hand side is by (2.4), regardless of the value of the constant $\beta-\gamma$, obviously a function $u^{++2}$ so that we have for any given $u$ r the general relation

$$
\begin{equation*}
L_{\beta} u_{r}=u^{r+2} \tag{3.14}
\end{equation*}
$$

valid for all values or $\beta$ and $\gamma$.

Remark (B). Cauchy problem. - Let us put in (3.8), $c=1, b=0$ and write $f(x)$ in place of $f(x, 0)$ so that we have for the EPD equation

$$
\begin{equation*}
u^{\alpha-2}(x, y)=\int_{0}^{y} \eta u^{\alpha}(x, \eta) d \eta+f(x) \tag{3.15}
\end{equation*}
$$

Then the computations leading to (3.13) show that the Cauchy problem for $u^{(\alpha-2)}, \alpha \equiv \equiv 1$, with the data $u^{\alpha-2}(x, 0)=f(x), u_{y}^{\alpha-2}(x, 0)=0$ can be solved provided a function $u^{\alpha}(x, y)$ can be determined from the data $u^{\alpha}(x, 0)=\frac{\Delta f}{1-\alpha}$ and $u_{y}^{\alpha}(x, 0)=0$. This fact was of basic importance for the solution of the Cauchy problem as given by the present author in 1952 [3a].

## 4. Generalization to Equations of Higher Order.

Let us consider the differential equation

$$
\begin{equation*}
L_{\alpha_{1}} L_{\alpha_{2}} \ldots L_{\alpha_{n}} w=0 \tag{4.1}
\end{equation*}
$$

Theorem. - Under the assumption

$$
\begin{equation*}
\alpha_{r} \neq \alpha_{j}-2(r-j), \quad j<r=2,3, \ldots, n \tag{4.2}
\end{equation*}
$$

the equation (4.1) has the general solution

$$
\begin{equation*}
w=u^{\alpha_{n}}+u^{\alpha_{n-1}-2}+u^{\alpha_{n-2}-4}+\ldots+u^{\alpha_{1}-2\{n-1)} \tag{4.3}
\end{equation*}
$$

Each of the functions $u$ on the right hand side of (4.3) is determined up to a harmonic function $h\left(x_{1}, x_{2}, \ldots, x_{m}\right)$ such that their sum $\Sigma h$ is identically zero. The proof is obviously obtained from the case $n=2$ by induction. In fact we have from (4.1)

$$
\begin{equation*}
L_{\alpha_{2}} L_{\alpha_{8}} L_{\alpha_{4}} \ldots L_{\alpha_{n}} w=u^{\alpha_{1}} \tag{4.4}
\end{equation*}
$$

As by assumption $\alpha_{2} \neq \alpha_{1}-2$, there is a function $u^{x_{1}-2}$ such that $u^{\alpha_{1}}=L_{\alpha_{2}} u^{\alpha_{1}-2}$. By the same assumption we can put $u^{\alpha_{1}-2}=L_{\alpha_{3}} u^{\alpha_{1}-2.2}$ so that $u^{\alpha_{1}}=L_{\alpha_{2}} L_{\alpha_{3}} u^{\alpha_{1}-2 \cdot \mu}$. Continuing in the same way, we obtain the equation $L_{\alpha_{2}} L_{\alpha_{a}} \ldots L_{\alpha_{n}} u^{\left.\left(\alpha_{1}-2 \mid n-1\right)\right\rangle}=\boldsymbol{u}^{\alpha_{1}}$. By subtracting this equation from (4.4) we obtain

$$
\begin{equation*}
L_{\alpha_{2}} L_{\alpha_{3}} \ldots L_{\alpha_{n}}\left(w-u^{\left(\alpha_{1}-2(n-1)\right.}\right)=0 \tag{4.5}
\end{equation*}
$$

This procedure reduces the solution of (4.1) to the solution of (4.5) which contains only ( $n-1$ ) operators $L$. Repeating this process we reduce the solution of (4.1) to the problem treated in Paragraph 3. This proves the formula (4.3) and also the statement about the non-uniqueness of this decomposition.

## 5. The Polyharmonic Equation.

By our previous result the general solution of the polyharmonic equation of order $n, L_{0}^{n} w$ (where according to our notations, $L_{0}=\sum_{1}^{m} \frac{\partial^{2}}{\partial x_{i}{ }^{2}}+\frac{\partial^{2}}{\partial y^{2}}$ ) is given by (4.3) as

$$
\begin{equation*}
w=u^{(0)}+u^{(-2)}+\ldots u^{(-2 n+2)} . \tag{5.1}
\end{equation*}
$$

According to Almansi. we have the decomposition

$$
\begin{equation*}
w=u_{0}^{(0)}+y u_{1}^{(0)}+\ldots+y^{n-1} u_{n-1}^{(0)} \tag{5.2}
\end{equation*}
$$

where all functions $\boldsymbol{u}^{(0)}$ are harmonic. However, the corresponding terms of (5.2) are polyharmonic functions of orders $1,2, \ldots, n$, respectively. Let us compare (5.1) with (5.2), taking for the sake of simplicity $n=2$. In this case we have with abbreviated notations,

$$
\begin{equation*}
w=y P+Q \tag{5.3}
\end{equation*}
$$

where $P$ and $Q$ are harmonic functions in $\left(x_{i}, \ldots, x_{m}, y\right)$. We shall now compute from $P$ and $Q$ two functions $u_{1}^{(-2)}$ and $u_{1}^{(0)}$ such that

$$
\begin{equation*}
y P+Q=u_{1}^{(-2)}+u_{1}^{(0)} . \tag{5.4}
\end{equation*}
$$

To this end we introduce a harmonic function $u^{(0)}$ defined by the equation

$$
\begin{equation*}
u_{y}^{(0)}=P . \tag{5.5}
\end{equation*}
$$

Such a function exists and can be computed by a procedure similar to that used to solve the equation (3.7) (see also R. J. Duffin [5], p. 6). We prove now that we can put in (5.4)

$$
\begin{equation*}
u_{1}^{(-2)}=y u_{y}^{(0)}-u^{(0)} . \tag{5.6}
\end{equation*}
$$

In fact the right hand side of (5.6) satisfies the equation $L_{-2} u=0$ as can be checked by the following differentiation of (5.6):

$$
\begin{gathered}
y \sum_{i} u_{y x_{i} x_{i}}^{(0)}-\sum_{i} u_{x_{i} x_{i}}^{(0)}+2 u_{y y}^{(0)}+y u_{y y y}^{(0)}-u_{y y}^{(0)}- \\
-\frac{2}{y}\left\{u_{y}^{(0)}+y u_{y y}^{(0)}-u_{y}^{(0)}\right\}= \\
=y \frac{\partial}{\partial y}\left(\sum_{i} u_{x_{i}}^{(0)} x_{i}+u_{y y}^{(0)}\right)-\left(\sum_{i} u_{x_{i} x_{i}}^{(0)}+u_{y y}^{(0)}\right)+ \\
+2 u_{y y}^{(0)}-2 u_{y y}^{(0)}=0 .
\end{gathered}
$$

Therefore, by (5.5) and (5.6) we can rewrite (5.3) as follows:

$$
w=y P+Q=\left(y u_{y}^{(0)}-u^{(0)}\right)+\left(u^{(0)}+Q\right)
$$

which shows that in (5.4) $u_{1}^{(-2)}$ is given by (5.6) and $u_{1}^{(0)}$ equals $u^{(0)}+Q$.

## 6. The iterated Wave Equation.

Our decomposition of the solutions of the polyharmonic equations applies also to the solutions of the iterated wave equation. The formula (5.1) remains valid on the understanding that the functions $u$ appearing there are solutions of the EPD equations with the corresponding indices. As in paragraph 5 let us consider here only the case $n=2$.

The general solution of the iterated wave equation $L_{n} L_{0} w=0$, $w=w\left(x_{1}, \ldots, x_{m}, y\right)$, where $y$ plays the role of the time variable, is given by the formula

$$
\begin{equation*}
w=u_{1}^{(0)}+u_{1}^{(-2)} \tag{6.1}
\end{equation*}
$$

with arbitrary $u_{1}^{(0)}$ and $u_{1}^{(-2)}$.
We shall show now briefly how the formula for the general solution $w$ leads to the solution of the Cavory problem for the iterated wave equation with the initial data

$$
\begin{equation*}
w=f_{0}(x), \quad w_{y}=f_{1}(x), \quad w_{y y}=f_{2}(x), \quad w_{y y y}=f_{3}(x) \tag{6.2}
\end{equation*}
$$

for $y=0$.
Let us first remark that the formula (6.1) contains not two but four arbitrary functions. In fact (6.1) can be rewritten as follows

$$
\begin{equation*}
w=u^{(0)}+y u^{(2)}+u^{(-2)}+y^{3} u^{(4)} \tag{6.3}
\end{equation*}
$$

because by (2.5) the additional terms are again solutions of $L_{0} u=0$ and $L_{-2} u=0$, respectively.

It is possible to satisfy the conditions (6.2) by taking for $u^{(0)}, u^{(2)}, u^{(-2)}$, $\boldsymbol{u}^{(4)}$ solutions of a singular CAUCHY problem for the corresponding EPD equation, $L_{k} u^{(k)}=0$, with preseribed values for $u^{(k)}(x, 0)$ and $u_{y}^{(k)}(x, 0)=0$. This last problem was recently solved for all values of $k[3,4]$ and, therefore the solation is known for $k=0,2,-2$, and 4.

For the sake of brevity we shall solve in this way the Cauchy problem for $w$ only in the special case where $f_{0}, f_{4}$, and $f_{2}$ are identically zero while $f_{3}(x)$ does not vanish identically. Then we see at once from (6.3) that a solution of the Caduchy ppoblem for $w$ is given by the formula

$$
\begin{equation*}
w\left(x_{1}, x_{2}, \ldots, x_{m}, y\right)=y^{3} u^{(4)}\left(x_{1}, x_{2}, \ldots, x_{m}, y\right) \tag{6.4}
\end{equation*}
$$

where $u^{4}$ is a solution of a Cauchy problem, $L_{4} u=0$, with the initial conditions

$$
\begin{equation*}
u^{(4)}\left(x_{1}, x_{2}, \ldots, x_{m}, 1\right)=\frac{1}{6} f_{3}\left(x_{1}, x_{2} \ldots, x_{m}\right) \tag{6.5}
\end{equation*}
$$

and

$$
\begin{equation*}
u_{y}^{(4)}\left(x_{1}, x_{2}, \ldots, x_{m}, 0\right)=0 \tag{6.6}
\end{equation*}
$$

According to previous results [3] obtained by the present author the solution $w$ for $m=1,2,3$ and 4 is given by the formula

$$
\begin{gather*}
w=y^{3} \frac{\omega_{5}-m}{6 \omega_{5}} \int_{\substack{m \\
\sum_{1} \alpha_{j}^{2} \leq 1}} \ldots \int f_{3}\left(x_{1}+\alpha_{1} y, \ldots, x_{m}+\alpha_{m} y\right) \cdot  \tag{6.7}\\
\cdot\left(1-\sum_{1}^{m} \alpha_{j}^{2}\right)^{\frac{3-m}{2}} d \alpha_{1} \ldots d \alpha_{m}
\end{gather*}
$$

where $\omega_{s}=2(\pi)^{s / 2} / \Gamma(s / 2)$. For $m=5$, we have

$$
\begin{equation*}
w=\frac{y^{3}}{6 \omega_{5}} \int_{\substack{5 \\ \sum_{1} \alpha_{j}^{2}=1 \\ 1}} \ldots \int f\left(x_{1}+\alpha_{1} y, \ldots, x_{5}+\alpha_{5} y\right) d \omega_{5} \tag{6,8}
\end{equation*}
$$

Finally, if $4<m-1$, we select the smallest integer $v$ such that $4+2 \vee \geqq m-1$. Then

$$
w=\left(\frac{\partial}{y \partial y}\right)^{v}\left(y^{2 \nu+3} u^{(4+2 v)}(x, y)\right)
$$

where $u^{(4+2 \nu)}(x, y)$ satisfies the corresponding EPD equation and the initial conditions

$$
\begin{gather*}
u^{(4+2 v)}(x, 0)=\frac{\frac{1}{6} f_{3}(x)}{5 \cdot 7 \ldots(3+2 v)}  \tag{6.9}\\
u_{y}^{(4+2 v)}(x, 0)=0 \tag{6.10}
\end{gather*}
$$

The function $u^{(4+2 v)}$ can be determined by a formula of the type (6.7) in the case $4+2 v>m-1$ or by the formula (6.8) if $4+2 v=m-1$. From these formulas it is seen that Huygens' principle holds only for the values

$$
m=5+2 v, \quad v=0,1,2, \ldots
$$

because only in these cases the solution is given by the integral over a hypersurface in the $m$-dimensional $x$-space. This last result confirms a remark by Garding 6 , p. 788 and connects Huygens' principle for the $n$-fold iterated wave equation with the fact that Huygens' principle holds for the EPD equation of index $k$ each time $m-k$ is an odd positive integer even if $k$ itself is negative, $k \neq-1,-3,-5, \ldots$ [3c, p. 112].

## 7. The Iterated EPD and GASPT Equation.

Let us consider the equation

$$
L_{2 n} u=0, \quad n=1,2,3, \ldots
$$

which is either an EPD equation or a GASPT equation and let $L_{2 n}^{n+1}$ denote the $n+1$ times iterated operator $L_{2 n}$. The we obtain as a special case of (4.3)
that the general solution of

$$
\begin{equation*}
L_{2 n}^{n+1} w=0 \tag{7.1}
\end{equation*}
$$

is

$$
\begin{equation*}
w=u^{(2 n)}+u^{(2 n-2)}+\ldots+u^{(0)} . \tag{7.2}
\end{equation*}
$$

This result includes ar a special case a theorem of Friedrichs which was extensively discussed in Courant-Hilbert Vol. II [7, p. 416 ff.]. This teorem states that in the case of one $x$ variable, $m=1$, the equation (7.1) admits $u^{(0)}$ as a particular solution. It would be, of course, easy to find by our method all equations of the type (4.1) which admit $u^{(0)}$ as a solution. The corresponding results hold obviously for the GASPT equation. The results of this paper were summarized in an abstract, Bull. Amer. Math. Soc., vol. 60, p. 254, 1954.

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[^0]:    (*) This research was supported in part by the United States Air Force under Contract $\mathrm{N}^{\mathrm{o}} . \mathrm{AF}(600)-573$ - monitored by the Office of Scientific Research, Air Research and Development Command.

