## **ERRATA**

At the request of A. A. Makarov, the author of the article "Control System for a Winding Machine" [No. 1, p. 85 (2000)], we are printing the corrected version of the system of Eqs. (5):

$$F\omega_{\rm b}(E\omega_{\rm pr}) = \begin{cases} U_1 & \text{for } E\omega_{\rm pr} < -E\omega_{\rm pr.max} \\ 0 & \text{for } E\omega_{\rm pr} = 0 \\ -U_1 & \text{for } E\omega_{\rm pr} > E\omega_{\rm pr.max} \\ -K_1 E\omega_{\rm pr} & \text{for } \left| E\omega_{\rm pr} \right| \le E\omega_{\rm pr.max} \end{cases}$$

$$F\omega_{\rm pr}(E\omega_{\rm pr}) = \begin{cases} -U_2 & \text{for } E\omega_{\rm pr} > -E\omega_{\rm pr.max} \\ 0 & \text{for } E\omega_{\rm pr} > -E\omega_{\rm pr.max} \\ U_2 & \text{for } E\omega_{\rm pr} > E\omega_{\rm pr.max} \\ K_2 E\omega_{\rm pr} & \text{for } \left| E\omega_{\rm pr} \right| \le E\omega_{\rm pr.max} \end{cases}$$

$$(5)$$