# On the Nonlinear Parabolic Systems in Divergence Form. Hölder Continuity and Partial Hölder Continuity of the Solutions ( ${ }^{(*)}\left({ }^{(* *)}\right.$. 

Sergio Campanato (Pisa)

Sunto. - $\Omega$ è un aperto limitato di $R^{n}, n \geqslant 1$. Nel cilindro $Q=\Omega \times(-T, 0)$, di punto $X=(x, t)$, si considera il sistema non lineare, in forma di divergenza,

$$
\begin{equation*}
-\sum_{1=i}^{n} D_{i} A^{i}(X, u, D u)+\frac{\partial u}{\partial t}=-\sum_{i=1}^{n} D_{i} B^{i}(X, u)+B^{0}(X, u, D u) \tag{1}
\end{equation*}
$$

dove $u, A^{i}, B^{i}, B^{0}$ sono vettori di $R^{N}, N>1$. Si suppone ohe il sistema (1) sia fortemente parabolico e che $i$ vettori $A^{i}, B^{i}, B^{0}$ abbiano andamenti strettamente controllati. In queste ipotesi, si studia la regolarità, o la parziale regolarità, hälderiana delle soluzioni

$$
u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)
$$

Preliminare è lo studio dei sistemi non lineari del tipo

$$
\begin{equation*}
-\sum_{i} D_{i} A^{i}(D u)+\frac{\hat{c} u}{\partial t}=0 \quad \text { in } Q \tag{2}
\end{equation*}
$$

che hanno lo stesso ruolo che, nella teoria lineare, hanno isistemi a coefficienti costanti e ridotti alla parte principale. Questo studio, che ha interesse in sè, viene fatto nei paragrafi 3, 4, 5 e 6. Per le soluzioni del sistema (2), si dimostrano la locale differenziabilità, le maggiorazioni tipo Poincaré e le cosidette maggiorazioni fondamentali dalle quali si deduce, in particolare, che le soluzioni del sistema (2) sono hölderiane in $Q$ se $n \leqslant 2$. Per maggiori dettagli si veda l'introduzione.

## 1. - Introduction.

For the sake of simplicity, throughout the present work we will be concerned with second order differential systems, even if what we will prove could be extended to systems of even order $2 m$.

Let $\Omega$ be a bounded open subset of $R^{n}$, with $n \geqslant 1$, whose boundary $\partial \Omega$ is as smooth as necessary; $x$ is a point of $R^{n} ; t \in R$ and $X=(x, t)$ is a point of $R^{n} \times R$.
$N$ is an integer $>1\left({ }^{1}\right),(\mid)_{k}$ and $\|\cdot\|_{k}$ are the scalar product and the norm in $R^{k}$, respectively. We will drop the subscript $k$ when there is no fear of confusion.
(*) Entrata in Redazione il 27 luglio 1983.
(**) Lavoro eseguito nell'ambito di un progetto nazionale di ricerca finanziato dal Mị. nistero della Pubblica Istruzione ( $40 \%$-1982).
${ }^{(1)}$ For the case $N=1$ (equations) see for instance [10].

Set $Q=\Omega \times(-T, 0)$ with $T>0$.
If $X_{0}=\left(x^{0}, t_{0}\right)$ we define

$$
\begin{aligned}
& B\left(x^{0}, \sigma\right)=\left\{x \in R^{n}:\left\|x-x^{0}\right\|<\sigma\right\} \\
& Q\left(X_{0}, \sigma\right)=B\left(x^{0}, \sigma\right) \times\left(t_{0}-\sigma^{2}, t_{0}\right) .
\end{aligned}
$$

Moreover, we say that $Q\left(X_{0}, \sigma\right) \subset \subset Q$ if

$$
B\left(x^{0}, \sigma\right) \subset \subset \Omega \quad \text { and } \quad \sigma^{2}<t_{0}+T \leqslant T
$$

If $u: Q \rightarrow R^{N}$, we set $D u=\left(D_{1} u, \ldots, D_{n} u\right)$ where, as usual, $D_{i}=\partial / \partial x_{i}$. Clearly $D u \in R^{n N}$ and we denote by $p=\left(p^{1}, \ldots, p^{n}\right), p^{i} \in R^{N}$, a typical vector of $R^{n N}$.

Let $a^{i}(X, u, p), i=1, \ldots, n$, and $B^{0}(X, u, p)$ be vectors of $R^{N}$, defined in $A=$ $=Q \times R^{N} \times R^{n N}$, measurable in $X$ and continuous in $(u, p)$.

Let us consider the nonlinear differential operator of second order

$$
\begin{equation*}
E u=-\sum_{i=1}^{n} D_{i} \omega^{i}(X, u, D u)+\frac{\partial u}{\partial t}-B^{0}(X, u, D u) \tag{1.1}
\end{equation*}
$$

Having set

$$
\left\{\begin{array}{l}
A^{i}(X, u, p)=a^{i}(X, u, p)-a^{i}(X, u, 0)  \tag{1.2}\\
B^{i}(X, u)=-a^{i}(X, u, 0)
\end{array}\right.
$$

it can be written in the form

$$
\begin{equation*}
E u=E_{0} u+\sum_{i} D_{i} B^{i}(X, u)-B^{0}(X, u, D u) \tag{1.3}
\end{equation*}
$$

where

$$
\begin{equation*}
E_{0} u=-\sum_{i} D_{i} A^{i}(X, u, D u)+\frac{\partial u}{\partial t} \tag{1.4}
\end{equation*}
$$

is the principal part of the operator $E$.
Let us suppose that the vector mappings $p \rightarrow a^{i}(X, u, p)$ are differentiable with derivatives $\partial a^{i} / \partial p_{k}^{j}$ measurable in $X$, continuous in $(u, p)$ and bounded in $\Lambda$ :

$$
\begin{equation*}
\left.\left\{\sum_{i j} \sum_{h k} \left\lvert\, \frac{\left.\partial a_{h}^{i}\right|^{2}}{\partial p_{k}^{j}}\right.\right\}^{\frac{1}{2}}\right\}^{\frac{1}{2}} \leqslant M, \quad \forall(X, u, p) \in \Lambda \tag{1.5}
\end{equation*}
$$

Set

$$
A_{i j}=\left\{A_{i j}^{h k}\right\} \quad \text { with } \quad A_{i j}^{h k}(X, u, p)=\int_{0}^{1} \frac{\partial a_{h}^{i}(X, u, \tau p)}{\partial p_{k}^{j}} d \tau
$$

The $A_{i j}$ are $N \times N$ matrices, measurable in $X$, continuous in $(u, p)$ and

$$
\begin{gather*}
A^{i}(X, u, p)=\sum_{j} A_{i j}(X, u, p) p^{j}  \tag{1.6}\\
E_{0} u=-\sum_{i j} D_{i}\left(A_{i j}(X, u, D u) D_{j} u\right)+\frac{\partial u}{\partial t} \tag{1.7}
\end{gather*}
$$

We will say that $E$ is quasi-linear if

$$
\begin{equation*}
A_{i j}=A_{i j}(X, u) \tag{1.8}
\end{equation*}
$$

We will say that the operator $E$ has linear principal part if

$$
\begin{equation*}
A_{i j}=A_{i j}(X) \tag{1.9}
\end{equation*}
$$

Let us suppose that the operator $E$ is strongly parabolic in the following sense: there exists $\gamma>0$ such that

$$
\begin{equation*}
\sum_{i j} \sum_{h k} \frac{\partial a_{h}^{i}(X, u, p)}{\partial p_{k}^{j}} \xi_{h}^{i} \xi_{k}^{j} \geqslant \nu\|\xi\|^{2} \tag{1.10}
\end{equation*}
$$

for every $(X, u, p) \in \Lambda$ and for any $\xi=\left(\xi^{1}, \ldots, \xi^{n}\right) \in R^{n N}$.
Denote by $H^{k}=H^{k, 2}$ and $H_{0}^{k}=H_{0}^{k, 2}$ the usual Sobolev spaces and set

$$
\begin{align*}
& a(u, \varphi)=\int_{Q} \sum_{i}\left(a^{i}(X, u, D u) \mid{ }_{S} D_{i} \varphi\right)_{N}-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right)_{N} d X  \tag{1.11}\\
& W(Q)=L^{2}\left(-T, 0, H_{0}^{1}(\Omega)\right) \cap H^{1}\left(-T, 0, L^{2}(\Omega)\right) \tag{1.12}
\end{align*}
$$

Throughout this paper, by a solution of the system

$$
E u=0 \quad \text { in } Q
$$

we will mean a vector

$$
\begin{equation*}
u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right) \tag{1.13}
\end{equation*}
$$

such that

$$
\begin{align*}
& a(u, \varphi)=\int_{Q}\left(B^{0}(X, u, D u) \mid \varphi\right) d X  \tag{1.14}\\
& \forall \varphi \in W(Q): \varphi(x,-T)=\varphi(x, 0)=0 \quad \text { in } \Omega\left(^{2}\right)
\end{align*}
$$

${ }^{2}$ ) Remark that $W(Q) \subset H^{1}(Q)$, so that there exist the traces $\varphi(x,-T)$ and $\varphi(x, 0)$ in $H^{\frac{1}{2}}(\Omega)$.

We define $q_{0}$ this way:

$$
\left\{\begin{array}{l}
q_{0}=\frac{2(n+2)}{n}, \quad \text { if } n>2  \tag{1.15}\\
q_{0} \text { is any number } \in[1,4), \quad \text { if } n=2 \\
q_{0}=4, \quad \text { if } n=1
\end{array}\right.
$$

then, it is known (see lemma 2.I) that

$$
W(Q) \subset L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right) \subset L^{\sigma_{0}}(Q)
$$

Therefore, to guarantee the existence of the integrals which appear in (1.14), it is sufficient to assume that the vectors $a^{i}$ and $B^{0}$ have the following growths that we will say controlled

$$
\begin{align*}
& \left\|a^{i}(X, u, p)\right\| \leqslant c\left(1+\|u\|^{\alpha}+\|p\|\right)  \tag{1.16}\\
& \left\|B^{0}(X, u, p)\right\| \leqslant c\left(1+\|u\|^{\beta}+\|p\|^{\nu}\right)\left(^{3}\right. \tag{1.17}
\end{align*}
$$

with

$$
\begin{align*}
& \begin{cases}1 \leqslant \alpha \leqslant \frac{n+2}{n} & \text { if } n>2 \\
1 \leqslant \alpha<2 & \text { if } n=2 \\
1 \leqslant \alpha \leqslant 2 & \text { if } n=1\end{cases}  \tag{1.18}\\
& \begin{cases}1 \leqslant \beta \leqslant \frac{n+4}{n} & \text { if } n>2 \\
1 \leqslant \beta<3 & \text { if } n=2 \\
1 \leqslant \beta \leqslant 3 & \text { if } n=1\end{cases}  \tag{1.19}\\
& \begin{cases}1 \leqslant \gamma \leqslant \frac{n+4}{n+2}, & \text { if } n>2 \\
1 \leqslant \gamma<\frac{3}{2}, & \text { if } n=2 \\
1 \leqslant \gamma \leqslant \frac{3}{2}, & \text { if } n=1\end{cases} \tag{1.20}
\end{align*}
$$

These growths assure that, if $u$ verifies assumption (1.13), then
(1.21) $\quad a^{i}(X, u, D u) \in L^{2}(Q) \quad$ and $\quad B^{0}(X, u, D u) \in L^{a_{0}^{\prime}(Q), \quad\left[\frac{1}{q_{0}}+\frac{1}{q_{0}^{\prime}}=1\right] . ~ . ~ . ~}$

If $\alpha=\beta=\gamma=1$, we will say that the growths (1.16), (1.17) are linear.
${ }^{(3)}$ More generally, in the right-hand side, the constant 1 may be replaced with appropriate integrable functions $f_{i}(X)$ and $f_{0}(X)$

$$
f_{i}(X) \in L^{2}(Q) \quad \text { and } \quad f_{0} \in L^{q_{0}^{\prime}}(Q), \quad \frac{1}{q_{0}}+\frac{1}{q_{0}^{\prime}}=1
$$

We observe that, from (1.6), (1.5), (1.2) it follows that

$$
\begin{equation*}
\left\|A^{i}(X, u, p)\right\| \leqslant M\|p\| \tag{1.22}
\end{equation*}
$$

$$
\begin{equation*}
\left\|B^{i}(X, u)\right\| \leqslant c\left(1+\|u\|^{\alpha}\right) \tag{1.23}
\end{equation*}
$$

In this paper, like in [5], we will suppose that the growths of the vectors $a^{i}$ and $B^{0}$ are strictly controlled, that is we will suppose that

$$
\begin{align*}
& \begin{cases}1 \leqslant \alpha<\frac{n+2}{n}, & \text { if } n \geqslant 2 \\
1 \leqslant \alpha<2, & \text { if } n=1\end{cases}  \tag{1.24}\\
& \begin{cases}1 \leqslant \beta<\frac{n+4}{n}, & \text { if } n \geqslant 2 \\
1 \leqslant \beta<3, & \text { if } n=1\end{cases}  \tag{1.25}\\
& \begin{cases}1 \leqslant \gamma<\frac{n+4}{n+2}, & \text { if } n \geqslant 2 \\
1 \leqslant \gamma<\frac{3}{2}, & \text { if } n=1\end{cases} \tag{1.26}
\end{align*}
$$

this aims to avoid some technical difficulties. Notwithstanding this I believe that all the results of the present paper are true also in the case of controlled growths, as it is proved in [2] for non-linear elliptic systems.

In this paper we will study the Hölder continuity, or the partial Hölder continuity, of the solutions of system $E u=0$ (as meant in (1.13), (1.14)). Clearly, the Hölder continuity is related to the parabolic metric

$$
\begin{equation*}
d(X, Y)=\max \left\{\|x-y\|,|t-\tau|^{2}\right\}, \quad \text { if } X=(x, t) \text { and } Y=(y, \tau) \tag{1.27}
\end{equation*}
$$

We recall that a vector $v: Q \rightarrow R^{N}$ is said to be partially $\mu$-Hölder continuous in $Q$, if there exists a subset $Q_{0} \subset Q$ ( $Q_{0}$ is the singular set of $v$ ), such that

$$
\begin{aligned}
& Q_{0} \text { is closed in } Q \\
& \text { meas } Q_{0}=0 \\
& v \in C^{0, \mu}\left(Q \backslash Q_{0}, d\right) .
\end{aligned}
$$

The partial Hölder continuity of the solutions is bein already studied for quasilinear systems with linear growth in [4], [14] and for quasi-linear systems with strictly controlled growth in [5], [13]. Here we want to prove, for the non-linear
parabolic systems of second order, results which are analogous to those proved in [1] and [2] for non-linear elliptic systems ( ${ }^{4}$ ).

The Hölder continuity and the partial Hölder continuity will be obtained, as it is usual by now, as a particular case of regularity, or partial regularity, in the $\mathfrak{L}^{2, \lambda}(Q, d)$ spaces (see [8], [6]).

For this purpose we will first consider the nonlinear systems of the following type:

$$
\begin{equation*}
-\sum_{i} D_{i} a^{i}(D u)+\frac{\partial u}{\partial t}=0 \quad \text { in } Q \tag{1.28}
\end{equation*}
$$

which satisfy the conditions (1.5), (1.10) and (1.16). Without any loss of generality, we can suppose that $a^{i}(0)=0$; then

$$
\begin{equation*}
\left\|a^{i}(p)\right\|=\left\|A^{i}(p)\right\| \leqslant M\|p\|, \quad \forall p \in R^{n N} \tag{1.29}
\end{equation*}
$$

In the theory of the $\mathfrak{L}^{2, \lambda}$-regularity for non-linear parabolic systems, those of type (1.28) play an analogous role to that played by linear systems, with constant coefficients and reduced to the principal part, in the theory of linear or quasi-linear systems (see [6], [4], [5]).

The solutions $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ of system (1.28) are locally differentiable (see section 3), i.e.

$$
\begin{equation*}
D_{i j} u \in L_{100}^{2}(Q) \quad \text { and } \quad \frac{\partial u}{\partial t} \in L_{1 \mathrm{coc}}^{2}(Q) \tag{1.30}
\end{equation*}
$$

and for every $Q(2 \sigma)=Q\left(X_{0}, 2 \sigma\right) \subset \subset Q$

$$
\begin{equation*}
\int_{Q(\sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X \leqslant \frac{c}{\sigma^{2}} \int_{Q(2 \sigma)}\|D u\|^{2} d X \tag{1.31}
\end{equation*}
$$

where $c$ does not depend on $\sigma$.
From this we get that the solutions of system (1.28) verify the fundamental estimates which follow (see section 5):

There exists $\varepsilon \in(0,1)$ such that $\forall Q(\sigma)=Q\left(X_{0}, \sigma\right) \subset \subset Q$ and $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\int_{Q(\lambda \sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X \leqslant c \lambda^{\varepsilon(i+2)} \int_{Q(\sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X . \tag{1.32}
\end{equation*}
$$

There exists $\varepsilon \in(0, n /(n+2))$ such that $\forall Q(\sigma) \subset \subset Q$ and $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\int_{Q(\lambda a)}\|D u\|^{2} d X \leqslant c \lambda^{2+\varepsilon(n+2)} \int_{Q(\sigma)}\|D u\|^{2} d X . \tag{1.33}
\end{equation*}
$$

[^0]There exists $\varepsilon \in(0, n /(n+2))$ such that $\forall Q(\sigma) \subset \subset Q$ and $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\int_{Q(\lambda \sigma)}\left\|u-u_{Q(\lambda \sigma)}\right\|^{2} d X \leqslant c \lambda^{4+\varepsilon(n+2)} \int_{Q(\sigma)}\left\|u-u_{Q(\sigma)}\right\|^{2} d X \tag{1.34}
\end{equation*}
$$

where the constants $e$ which appear in (1.32), (1.33), (1.34) do not depend on $\sigma$ and $\lambda$, and

$$
\begin{equation*}
u_{\Delta}=\int_{A} u(X) d X=\frac{1}{\operatorname{meas} A} \int_{A} u d X \tag{1.35}
\end{equation*}
$$

In particular (see section 6) from inequality (1.34) it follows that, if $n \leqslant 2$, then

$$
\begin{equation*}
u \in C^{0, \mu}(Q, d) \quad \text { with } \quad \mu=2-\frac{1-\varepsilon}{2}(n+2) \tag{1.36}
\end{equation*}
$$

Furthermore, if the derivatives $\partial a^{i} / \partial p_{k}^{j}$ are uniformly continuous in $R^{n N}$, then the vector $D u$ is partially $\mu$-Hölder continuous in $Q, \forall \mu \in(0,1)$, and, $Q_{0}$ being the singular set of $D u$,

$$
\begin{equation*}
H_{n+2-q}\left(Q_{0}\right)=0 \quad \text { for some } q>2 \tag{1.37}
\end{equation*}
$$

Here $H_{\beta}$ is the $\beta$-dimensional Hausdorfi measure with respect to the parabolic metric $d$ (see for instance (3.10) in [4]).

In section 7 we study the solutions of the strongly parabolic systems

$$
\begin{equation*}
-\sum_{i} D_{i} A^{i}(X, D u)+\frac{\partial u}{\partial t}=-\sum_{i} D_{i} B^{i}(X, u)+B^{0}(X, u, D u) \tag{1.38}
\end{equation*}
$$

still with strictly controlled growth.
We prove (theorems 7.I, 7.II) that, if $n \leqslant 2$ and the vectors $A^{i}(X, p)$ satisfy an uniform continuity condition with respect to $X$ (see (7.5)), then the result (1.36) holds again:

For a suitable $\varepsilon \in(0, n /(n+2))$

$$
\begin{equation*}
u \in C^{0, \mu}(Q, d) \quad \text { with } \quad \mu=2-\frac{1-\varepsilon}{2}(n+2) \tag{1.39}
\end{equation*}
$$

If the derivatives $\partial A^{i} / \partial p_{k}^{j}$ are uniformly continuous in $\bar{Q} \times R^{n N}$, then, whatever $n$ may be, the solutions of system (1.38) are partially $\mu$-Hölder continuous in $Q, \forall \mu \in$ $\in(0,1)$. If $Q_{0}$ is their singular set, one can merely say that

$$
\begin{equation*}
\text { meas } Q_{0}=0 \tag{1.40}
\end{equation*}
$$

(see theorem 7.IV).

In section 8 we study the solutions of the strongly parabolic systems of general type

$$
\begin{equation*}
-\sum_{i} D_{i} a^{i}(X, u, D u)=B^{0}(X, u, D u) \tag{1.41}
\end{equation*}
$$

which have strictly controlled growth.
One proves (theorem 8.II) that, if $n \leqslant 2$ and the vectors $A^{i}(X, u, p)$ satisfy an uniform continuity condition with respect to ( $X, u$ ) (see (8.6)), then $u$ is partially $\mu$-Hölder continuous in $Q$ with $\mu=2-(1-\varepsilon)(n+2) / 2$ and, $Q_{0}$ being its singular set,

$$
\begin{equation*}
H_{n}\left(Q_{0}\right)=0 \tag{1.42}
\end{equation*}
$$

Furthermore, if the derivatives $\partial a^{i} / \partial p_{k}^{j}$ are uniformly continuous in $\bar{\Lambda}$, then, for any $n$, the solutions of system (1.41) are partially $\mu$-Hölder continuous in $Q, \forall \mu \in$ $\in(0,1)$. About their singular set $Q_{0}$, one can merely say that

$$
\begin{equation*}
\text { meas } Q_{0}=0 \tag{1.43}
\end{equation*}
$$

(see theorem 8.IV).

## 2. - Some notations and preliminary results.

Where there is no fear of confusion we will write simply $B(\sigma)$ and $Q(\sigma)$ instead of $B\left(x^{0}, \sigma\right)$ and $Q\left(X_{0}, \sigma\right)$, respectively. We define $u_{Q(\sigma)}$ as in (1.35), and we set

$$
\begin{align*}
& |u|_{0, q, A}=\left(\int_{A}\|u\|^{q} d X\right)^{1 / Q}, \quad|u|_{0, A} \text { if } q=2  \tag{2.1}\\
& \tilde{\Phi}\left(u, X_{0}, \sigma\right)=\int_{Q\left(X_{0}, \sigma\right)}\|D u\|^{2}+\sigma^{-2}\left\|u-u_{Q(\sigma)}\right\|^{2} d X  \tag{2.2}\\
& \Phi\left(u, X_{0}, \sigma\right)=\int_{Q\left(X_{0}, \sigma\right)} 1+\|u\|^{\alpha_{0}}+\|D u\|^{2}+\sigma^{-2}\left\|u-u_{Q(\sigma)}\right\|^{2} d X \tag{2.3}
\end{align*}
$$

where $q_{0}$ is defined in (1.15).
Lemma 2.I. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$, then $u \in L^{q_{0}}(Q)$ and $\forall q \in\left[2, q_{0}\right]$

$$
\begin{equation*}
|u|_{0, q, Q}^{\alpha} \leqslant c(n, q) d_{\Omega}^{\delta} \cdot \sup _{(-T, 0]}|u|_{0, \Omega}^{q-2} \cdot \int_{Q}\|D u\|^{2}+d_{\Omega}^{-2}\|u\|^{2} d X \tag{2.4}
\end{equation*}
$$

where $d_{\Omega}$ is the diameter of $\Omega$ and

$$
\begin{equation*}
\delta=n+2-\frac{n q}{2} \tag{2.5}
\end{equation*}
$$

Proof. - If $n \geqslant 2$

$$
\begin{equation*}
\int_{\Omega}\|u\|^{q} d x=\int_{\Omega}\|u\|^{2} \cdot\|u\|^{\alpha-2} d x \leqslant|u|_{0, \Omega}^{q-2} \cdot\left(\int_{\Omega}\|u\|^{4 /(4-\alpha)} d x\right)^{(4-q) / 2} \tag{2.6}
\end{equation*}
$$

And, by Sobolev's theorem, we have

$$
\begin{array}{r}
\left(\int_{\Omega}\|u\|^{4 /(4-q)} d x\right)^{(4-q) / 2} \leqslant c(n, q)\left\{\int_{\Omega}\left\{\|D u\|+d_{\Omega}^{-1}\|u\|\right\}^{4 n /(n(4-q)+4)} d x\right\}^{(n(4-q)+4) / 2 n} \leqslant  \tag{2.7}\\
\leqslant c(n, q) d_{\Omega}^{(n(2-q)+4) / 2} \cdot \int_{\Omega}\|D u\|^{2}+d_{\Omega}^{-2}\|u\|^{2} d x .
\end{array}
$$

Inequality (2.4) easily follows from (2.6) and (2.7).
On the contrary, if $n=1$

$$
\begin{equation*}
\int_{\Omega}\|u\|^{\alpha} d x \leqslant \sup _{\Omega}\|u\|^{2} \cdot \int_{\Omega}\|u\|^{\alpha-2} d x \leqslant \sup _{\Omega}\|u\|^{2} \cdot \mid u u_{0, \Omega}^{\alpha-2} \cdot d_{\Omega}^{2-\alpha / 2} \tag{2.8}
\end{equation*}
$$

Moreover, by Sobolev's theorem,

$$
\begin{equation*}
\sup _{\Omega}\|u\|^{2} \leqslant c d_{\Omega} \int_{\Omega}\|D u\|^{2}+d_{\Omega}^{-2}\|u\|^{2} d x \tag{2.9}
\end{equation*}
$$

Inequality (2.4) follows again from (2.8) and (2.9).
Liemina 2.II. - If $u \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{1}(B(\sigma))\right) \cap H^{\frac{1}{2}}\left(t_{0}-\sigma^{2}, t_{0}, L^{2}(B(\sigma))\right.$, then

$$
\begin{equation*}
\tilde{\Phi}\left(u, X_{0}, \sigma\right) \leqslant c(n)\left\{\int_{Q(\sigma)}\|D u\|^{2} d X+\int_{t_{0}-\sigma^{2}}^{t_{0}} d \tau \int_{Q(\sigma)} \frac{\|u(x, \tau)-u(x, t)\|^{2}}{|t-\tau|^{2}} d x d t\right\} \tag{2.10}
\end{equation*}
$$

This lemma is well known (see for instance [4] lemma 2.I).
Lemma 2.III. - If $u \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{2}(B(\sigma))\right) \cap H^{1}\left(t_{0}-\sigma^{2}, t_{0}, L^{2}(B(\sigma))\right)$, then

$$
\begin{equation*}
\tilde{\Phi}\left(D u, X_{0}, \sigma\right) \leqslant c(n) \int_{Q(\sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2}+\left\|\frac{\partial u}{\partial t}\right\|^{2} d X \tag{2.11}
\end{equation*}
$$

Inequality (2.11) is well known too (see for instance [7] lemma 2.II).

Lemma 2.IV. - Let us suppose that $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$ and $\alpha$ satisfies the condition (1.24). Having set

$$
\begin{equation*}
\Psi\left(u, X_{0}, \sigma\right)=\int_{Q\left(X_{0}, \sigma\right)}\left(\mathbf{1}+\|u\|^{2 \alpha}\right) d X \tag{2.12}
\end{equation*}
$$

then, $\forall Q(\sigma) \subset Q$ and $\forall \lambda \in(0,1)$, we have the inequality

$$
\begin{equation*}
\Psi\left(u, X_{0}, \lambda \sigma\right) \leqslant c(n, \alpha) \lambda^{n+2} \Psi\left(u, X_{0}, \sigma\right)+C(u) \sigma^{n(1-\alpha)+2} \tilde{\Phi}\left(u, X_{0}, \sigma\right) \tag{2.13}
\end{equation*}
$$

where

$$
\begin{equation*}
C(u)=c(n, \alpha) \sup _{(-T, 0)}|u|_{0, \Omega}^{2(x-1)} \tag{2.14}
\end{equation*}
$$

Proof. - For every $\lambda \in(0,1)$

$$
\int_{Q(\lambda \sigma)}\|u\|^{2 \alpha} d X \leqslant c(n, \alpha) \lambda^{n+2} \int_{Q(\sigma)}\|u\|^{2 \alpha} d X+c(n, \alpha) \int_{Q(\sigma)}\left\|u-u_{Q(\sigma)}\right\|^{2 \alpha} d X .
$$

Inequality (2.13) follows from this estimate and from (2.4), where we assume $q=2 \alpha$.
Lemma 2.V. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$ and $B^{0}(X, u, p)$ verifies the growth condition (1.17), then, $\forall Q\left(X_{0}, \sigma\right) \subset Q$ and for every $r$, with $2(n+2) /(n+4) \leqslant$ $\leqslant r \leqslant q_{0} / \beta \wedge 2 / \gamma$

$$
\begin{equation*}
\left|B^{0}(X, u, D u)\right|_{0, r, Q(\sigma)}^{2} \leqslant C(u) \sigma^{\delta} \Phi\left(u, X_{0}, \sigma\right) \tag{2.15}
\end{equation*}
$$

where

$$
\begin{equation*}
\delta=2(n+2)\left(\frac{1}{r}-\frac{\beta}{q_{0}} \vee \frac{\gamma}{2}\right) \tag{2.16}
\end{equation*}
$$

and

$$
\begin{equation*}
C(u)=c(n)\left\{\int_{Q} 1+\|u\|^{q_{0}}+\|D u\|^{2} d X\right\}^{\left(2 \beta / \alpha_{0}\right) \vee \gamma-1} \tag{2.17}
\end{equation*}
$$

Proof. - It is easy to obtain the following inequalities:

$$
\begin{aligned}
&\left(\int_{Q(\sigma)}\left\|B^{0}\right\|^{r} d X\right)^{2 / r} \leqslant c(n) \sigma^{2(n+2)\left(1 / r-\beta / \alpha_{0} \vee \gamma / 2\right)}\left(\int_{Q(\sigma)}\left\|B^{0}\right\|^{\alpha_{0} / \beta \wedge 2 / \gamma} d X\right)^{2 \beta / \sigma_{0} \vee \gamma} \leqslant \\
& \leqslant c(n) \sigma^{\delta}\left(\int_{Q(\sigma)} 1+\|u\|^{\alpha_{0}}+\|D u\|^{2} d X\right) \leqslant \\
& \leqslant c(n) \sigma^{\delta} \Phi\left(u, X_{0}, \sigma\right)\left(\int_{Q} 1+\|u\|^{\alpha_{0}}+\|D u\|^{2} d X\right)^{\left(2 \beta / \sigma_{0}\right) \vee \gamma-1} .
\end{aligned}
$$

Let $A_{i j}(X), i j=1, \ldots, n$, be $N \times N$ matrices defined in $Q$, and suppose that

$$
\begin{gather*}
A_{i j} \in L^{\infty}(Q) \quad \text { and } \quad \sup _{Q}\left\{\sum_{i j}\left\|A_{i j}\right\|^{2}\right\}^{\frac{1}{2}}=M  \tag{2.18}\\
\sum_{i j}\left(A_{i j} \xi_{1} \mid \xi^{i}\right) \geqslant \nu\|\xi\|^{2}, \quad \nu>0, \quad \forall X \in Q \text { and } \forall \xi \in R^{n N} . \tag{2.19}
\end{gather*}
$$

Let $B^{i}(X), i=1, \ldots, n$, and $B^{0}(X)$ be vectors of $R^{N}$, such that

$$
\begin{equation*}
B^{i} \in L^{2}(Q) \quad \text { and } \quad B^{0} \in L^{2(n+2) /(n+4)}(Q) \tag{2.20}
\end{equation*}
$$

The following result is well known (see [11], [10], [12]):
Lemma 2.VI. - There exists a unique $u \in L^{2}\left(-T, 0, H_{0}^{1}(\Omega)\right)$, which is the solution of the Cauchy-Dirichlet [C.D.] problem:

$$
\begin{align*}
& \int_{Q} \sum_{i j}\left(A_{i j} D_{j} u \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q} \sum_{i}\left(B^{i} \mid D_{i} \varphi\right)+\left(B^{0} \mid \varphi\right) d X  \tag{2.21}\\
& \forall \varphi \in W(Q): \varphi(x, 0)=0 \quad \text { in } \Omega
\end{align*}
$$

and the following inequality holds

$$
\begin{align*}
& \int_{Q}\|D u\|^{2} d X+\int_{-T}^{0} d \tau \int_{Q} \frac{\|u(x, t)-u(x, \tau)\|^{2}}{|t-\tau|^{2}} d x d t \leqslant  \tag{2.22}\\
& \leqslant c(v, M)\left\{\sum_{i}\left|B^{i}\right|_{0, Q}^{2}+\left|B^{0}\right|_{0,2(n+2) /(n+4), Q}\right\} .
\end{align*}
$$

In particular, $\forall Q\left(X_{\mathbf{0}}, \sigma\right) \subset Q$

$$
\begin{equation*}
\tilde{\Phi}\left(u, X_{0}, \sigma\right) \leqslant c(v, M)\left\{\sum_{i}\left|B^{i}\right|_{0, Q}^{2}+\left|B^{0}\right|_{0,2(n+2)(n+4), Q}^{2}\right\} . \tag{2.23}
\end{equation*}
$$

More generally, in section 4 of [5] the following $L_{\text {loc }}^{\alpha}$-regularity result for the vector $D u$ is proved (5):

Lemma 2.VII. - There exist $\bar{q}>2$ and a continuous and increasing function $r(q)$, defined on $[2, \bar{q}]$, with these properties:

$$
\begin{equation*}
\frac{2(n+2)}{n+4} \leqslant r(q) \leqslant 2, \quad \lim _{\alpha \leftarrow 2} r(q)=\frac{2(n+2)}{n+4} \tag{2.24}
\end{equation*}
$$

${ }^{(5)}$ In [5] I considered the case $n>2$, but in case $n=1$ and $n=2$ the proof remains the same.
such that, if $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$ is a solution of system
(2.25) $\int_{Q} \sum_{i j}\left(A_{i j} D_{j} u \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q} \sum_{i}\left(B^{i} \mid D_{i} \varphi\right)+\left(B^{0} \mid \varphi\right) d X, \quad \forall \varphi \in C_{0}^{\infty}(Q)$
under the hypotheses (2.18), (2.19) and

$$
\begin{equation*}
B^{i} \in L^{q}(Q), \quad B^{0} \in L^{\gamma(\alpha)}(Q), \quad 2 \leqslant q \leqslant \bar{q} \tag{2.26}
\end{equation*}
$$

then, for every $Q\left(X_{0} 2 \sigma\right) \subset Q$ and $\forall \eta \in R^{N}$

$$
\begin{align*}
\left(f_{Q(\sigma)}\|D u\|^{q} d X\right)^{1 / \alpha} \leqslant & c\left\{f_{Q(2 \sigma)} \sum_{i}\left\|B^{i}\right\|^{q} d X\right\}^{1 / Q}+  \tag{2.27}\\
& +c \sigma\left\{\int_{Q(2 \sigma)}\left\|B^{0}\right\|^{(q)} d X\right\}^{1 / r(q)}+c\left\{\int_{Q(2 \sigma)}\|D u\|^{2}+\sigma^{-2}\|u-\eta\|^{2} d X\right\}^{\frac{1}{2}}
\end{align*}
$$

where the constants $c$ do not depend on $\sigma$.
Denote by $A_{i j}^{*}$ the adjoint of the matrix $A_{i j}$; set

$$
\begin{equation*}
A_{i j}^{+}=\frac{1}{2}\left(A_{i j}+A_{j i}^{*}\right), \quad A_{i j}^{-}=\frac{1}{2}\left(A_{i j}-A_{j i}^{*}\right) \tag{2.28}
\end{equation*}
$$

and define

$$
\begin{equation*}
M_{-}=\sup _{Q}\left\{\sum_{i j} \| A_{i j}^{-\|^{2}}\right\}^{\frac{1}{2}} . \tag{2.29}
\end{equation*}
$$

Lemma 2.VIII. - For every $\mu \geqslant 0$ and $\forall \xi \in R^{n N}$

$$
\begin{equation*}
\sup _{Q}\left\{\sum_{i}\left\|(M+\mu) \xi^{i}-\sum_{j} A_{i j} \xi^{i}\right\|^{2}\right\}^{\frac{1}{2}} \leqslant\left\{M-\nu+\sqrt{\mu^{2}+M_{-}^{2}}\right\}\|\xi\| \tag{2.30}
\end{equation*}
$$

Moreover, if $\mu>\left(M_{-}^{2}-v^{2}\right) / 2 v$, then

$$
\begin{equation*}
K(\mu)=\frac{M-\nu+\sqrt{\mu^{2}+M^{2}}}{M+\mu}<1 \tag{2.31}
\end{equation*}
$$

As it concerns inequality (2.30) see [3] section 1 and [Q] lemma 8.III, p. 88. To verify (2.31), an elementary calculation is enough.

Lencan 2.IX. - If $A_{i j}, i j=1, \ldots, n$, are $N \times N$ matrices which satisfy the conditions (2.18), (2.19), and if $u \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{1}(B(\sigma))\right)$ is a solution in $Q\left(X_{0}, \sigma\right)$ of system

$$
\begin{equation*}
\int_{Q(\sigma)} \sum_{i j}\left(A_{i j} D_{j} u \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=0, \quad \forall \varphi \in C_{0}^{\infty}(Q(\sigma)) \tag{2.32}
\end{equation*}
$$

then there exists $\varepsilon(\nu, M) \in(0,1)$, such that $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\int_{Q(\lambda \sigma)}\|D u\|^{2} d X \leqslant c(v, M) \lambda^{s(n+2)} \int_{Q(\sigma)}\|D u\|^{2} d X \tag{2.33}
\end{equation*}
$$

Proof. - Fix $\mu=\left(M^{2}-\nu^{2}\right) / \nu$. In $Q(\sigma)$ we decompose $u$ as $u=v+w$, where $w \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H_{0}^{1}(B(\sigma))\right)$ is the solution of the Oauchy-Dirichlet problem

$$
\begin{align*}
& \begin{array}{ll}
\int_{Q(\sigma)}(M+\mu) \sum_{i}\left(D_{i} w \mid D_{i} \varphi\right)-\left(w \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X= \\
& =\int_{Q(\sigma)} \sum_{i}\left((M+\mu) D_{i} u-\sum_{i} A_{i j} D_{j} u \mid D_{i} \varphi\right) d X,
\end{array}  \tag{2.34}\\
& \forall \varphi \in W(Q(\sigma)): \varphi\left(x, t_{0}\right)=0 \quad \text { in } B(\sigma)
\end{align*}
$$

whereas $v \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{1}(B(\sigma))\right)$ is a solution of system

$$
\begin{equation*}
\int_{Q(\sigma)}(M+\mu) \sum_{i}\left(D_{i} v \mid D_{i} \varphi\right)-\left(v \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=0, \quad \forall \varphi \in C_{0}^{\infty}(Q(\sigma)) \tag{2.35}
\end{equation*}
$$

From the linear theory, it is known that $w$ verifies the inequality

$$
\int_{Q(\sigma)}\|D w\|^{2} d X \leqslant \frac{1}{(M+\mu)^{2}} \int_{Q(\sigma)} \sum_{i}\left\|(M+\mu) D_{i} u-\sum_{j} A_{i j} D_{j} u\right\|^{2} d X
$$

therefore, by lemma 2.VIII,

$$
\begin{equation*}
\int_{Q(\sigma)}\|D w\|^{2} d X \leqslant K^{2}(\mu) \int_{Q(\sigma)}\|D u\|^{2} d X \tag{2.36}
\end{equation*}
$$

$v$ satisfies the fundamental inequality which follows (see [6] and [4], lemma 2.II)

$$
\begin{equation*}
\int_{Q(\lambda)}\|D v\|^{2} d X \leqslant c(\nu, M) \lambda^{n+2} \int_{Q(\sigma)}\|D v\|^{2} d X, \quad \forall \lambda \in(0,1) . \tag{2.37}
\end{equation*}
$$

From (2.36) and (2.37), it easily follows that $\forall \lambda \in(0,1)$

$$
\begin{equation*}
|D u|_{0, Q(\lambda \sigma)} \leqslant\left\{c(1+K) \lambda^{(n+2) / 2}+K\right\}|D u|_{0, Q(\sigma)} \tag{2.38}
\end{equation*}
$$

As $K \in(0,1)$, from (2.38), we get the estimate (2.33) by means of lemma 1.V, p. 12 of [Q].

One can prove the following Caccioppoli's type inequality:
Lemma 2.X. - If $A_{i j}, i j=1, \ldots, n$, are $N \times N$ matrices, which satisfy the conditions (2.18), (2.19), and if $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ is a solution in $Q$ of system

$$
\begin{equation*}
\int_{Q} \sum_{i j}\left(A_{i j} D_{j} u \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=0, \quad \forall \varphi \in C_{0}^{\infty}(Q) \tag{2.39}
\end{equation*}
$$

then, $\forall B\left(x^{0}, 2 \sigma\right) \subset \subset \Omega, \forall 2 a \in(0, T)$, and $\forall \eta \in R^{N}$

$$
\begin{equation*}
\int_{-a}^{0} d t \int_{B(\sigma)}\|D u\|^{2} d x \leqslant c(v, M)\left(\frac{1}{\sigma^{2}}+\frac{1}{a}\right) \int_{-2 a}^{0} d t \int_{B(2 \sigma)}\|u-\eta\|^{2} d x \tag{2.40}
\end{equation*}
$$

Proof. - Let $\theta(x) \in C_{0}^{\infty}\left(R^{n}\right)$ be a function with these properties
(2.41) $0 \leqslant \theta \leqslant 1, \quad \theta=1$ in $B(\sigma), \quad \theta=0$ in $R^{n} \backslash B\left(\frac{1}{4} \sigma\right), \quad\|D \theta\| \leqslant c \sigma^{-1}$.

Let $\varrho_{m}(t)$, with $m$ integer $>2 / a$, be a function defined on $R$ this way

$$
\begin{cases}\varrho_{m}(t)=1, & \text { if }-a \leqslant t \leqslant-\frac{2}{m}  \tag{2.币2}\\ \varrho_{m}(t)=0, & \text { if } t>-\frac{1}{m} \text { or } t<-2 a \\ \varrho_{m}(t)=\frac{t}{a}+2, & \text { if }-2 a \leqslant t \leqslant-a \\ \varrho_{m}(t)=-(m t+1), & \text { if }-\frac{2}{m} \leqslant t \leqslant-\frac{1}{m}\end{cases}
$$

Finally, let $\left\{g_{s}(t)\right\}$ be a sequence of symmetric mollifying functions

$$
\left\{\begin{array}{l}
g_{s}(t) \in C_{0}^{\infty}(R), \quad g_{s}(t) \geqslant 0, \quad g_{s}(t)=g_{s}(-t)  \tag{2.43}\\
\operatorname{supp} g_{s} \subset\left[-\frac{1}{s}, \frac{1}{s}\right] \\
\int_{R} g_{s}(t) d t=1
\end{array}\right.
$$

As (2.39) is true for any $\varphi \in W(Q): \varphi(x,-T)=\varphi(x, 0)=0$ in $\Omega$, then, if $s>$ $>m \vee 1 /(T-2 a)$, we can assume in (2.39)

$$
\begin{equation*}
\varphi(X)=\theta^{2} \varrho_{m}\left[\left(\varrho_{m}(u-\eta)\right) * g_{s}\right] \tag{2.44}
\end{equation*}
$$

and we get that

$$
\begin{align*}
& \int_{Q} \theta^{2} \varrho_{m} \sum_{i j}\left(A_{i j} D_{j} u \mid\left(\varrho_{m} D_{i} u\right) * g_{s}\right) d X+  \tag{2.45}\\
& +2 \int_{Q} \theta \varrho_{m} \sum_{i j}\left(A_{i j} D_{j} u \mid D_{i} \theta \cdot\left[\left(\varrho_{m}(u-\eta)\right) * g_{s}\right]\right) d X- \\
& -\int_{Q}\left(u-\eta \mid \theta^{2} \varrho_{m}^{\prime}\left[\left(\varrho_{m}(u-\eta)\right) * g_{s}\right]\right) d X=\int_{Q}\left(u-\eta \mid \theta^{2} \varrho_{m}\left[\left(\varrho_{m}(u-\eta)\right) * g_{s}\right]^{\prime}\right) d X .
\end{align*}
$$

By symmetry of the $g_{s}(t)$, the integral in the right-hand side equals zero; furthermore, when $s \rightarrow+\infty$, then

$$
\left[\varrho_{m}(u-\eta)\right] * g_{s} \rightarrow \varrho_{m}(u-\eta) \quad \text { in } L^{2}\left(-T, 0, H^{1}(\Omega)\right)
$$

And so, from (2.45), taking the limit for $s \rightarrow+\infty$, we obtain that

$$
\begin{align*}
& \int_{Q} \theta^{2} \varrho_{m}^{2} \sum_{i j}\left(A_{i j} D_{j} u \mid D_{i} u\right) d X=  \tag{2.46}\\
&=2 \int_{Q} \theta \varrho_{m}^{2} \sum_{i j}\left(A_{i j} D_{j} u \mid D_{i} \theta \cdot(u-\eta)\right) d X+\int_{Q} \theta^{2} \varrho_{m} \varrho_{m}^{\prime}\|u-\eta\|^{2} d X
\end{align*}
$$

We may estimate the integral in the left-hand side by the ellipticity condition (2.19), and we easily estimate the terms in the right-hand side by the Hölder ${ }^{i}$ s inequality. Therefore we obtain that $\forall \varepsilon>0$

$$
\begin{aligned}
& v \int_{Q} \theta^{2} \varrho_{m}^{2}\|D u\|^{2} d X \leqslant \varepsilon \int_{Q} \theta^{2} \varrho_{m}^{2}\|D u\|^{2} d X+ \\
&+c(\varepsilon, M) \int_{Q} \varrho_{m}^{2}\|D \theta\|^{2}\|u-\eta\|^{2} d X+\int_{Q} \theta^{2} \varrho_{m} \varrho_{m}^{\prime}\|u-\eta\|^{2} d X
\end{aligned}
$$

Choosing $\varepsilon$ sufficiently small and taking into account that $\varrho_{m} \varrho_{m}^{\prime} \leqslant 0$, if $t>-2 / m$, we get that

$$
\int_{-a}^{-2 / m} d t \int_{B(\sigma)}\|D u\|^{2} d x \leqslant e(v, M)\left(\frac{1}{\sigma^{2}}+\frac{1}{a}\right) \int_{-2 a}^{-2 / m} d t \int_{B(2 \sigma)}\|u-\eta\|^{2} d x
$$

Now the thesis, i.e. the (2.40), follows by taking the limit for $m \rightarrow+\infty$.
Let $a^{i}(p), i=1, \ldots, n$, be vectors of $R^{N}$ of class $C^{1}\left(R^{n N}\right)$, which satisfy the conditions (1.5), (1.10) and (1.29). Let us suppose that $B^{i}(X), i=1, \ldots, n$, and $B^{0}(X)$ are vectors of $R^{N}$, which satisfy condition (2.20). Then, we can prove the following existence lemma.

Lemma 2.XI. - For any $w \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ there exists a unique vector $u \in$ $\in L^{2}\left(-T, 0, H_{0}^{1}(\Omega)\right)$, which is the solution of the O.D. problem.

$$
\begin{align*}
& \int_{Q} \sum_{i}\left(a^{i}(\dot{D} u+D w) \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q} \sum_{i}\left(B^{i} \mid D_{i} \varphi\right)+\left(B^{0} \mid \varphi\right) d X  \tag{2.47}\\
& \forall \varphi \in W(Q): \varphi(x, 0)=0 \quad \text { in } \Omega
\end{align*}
$$

Moreover, we have the inequality

$$
\begin{align*}
\int_{Q}\|D u\|^{2} d X+\int_{-T}^{0} d \tau \int_{Q} \frac{\|u(x, t)-u(x, \tau)\|^{2}}{|t-\tau|^{2}} d x d t \leqslant  \tag{2.48}\\
\quad \leqslant c(v, M)\left\{\sum_{i}\left|B^{i}-a^{i}(D w)\right|_{0, Q}^{2}+\left|B^{0}\right|_{0,2(n+2) /(n+4), Q}^{2}\right\}
\end{align*}
$$

We give a proof for the reader's convenience.
Proof. - Fix $\mu=\left(M^{2}-\nu^{2}\right) / \nu$. For any $u \in L^{2}\left(-T, 0, H_{0}^{1}(\Omega)\right)$ the condition

$$
(M+\mu) D_{i} u-a^{i}(D u+D w) \in L^{2}(Q)
$$

holds, and then (see lemma 2.VI) there is a unique solution $U=\mathscr{G}(u) \in L^{2}(-T$, $0, H_{0}^{1}(\Omega)$ ) of C.D. problem

$$
\begin{align*}
\int_{Q}(M+\mu) \sum_{i} & \left(D_{i} U \mid D_{i} \varphi\right)-\left(U \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=  \tag{2.49}\\
& =\int_{Q} \sum_{i}\left([M+\mu] D_{i} u-a^{i}(D u+D w)+B^{i} \mid D_{i} \varphi\right)+\left(B^{0} \mid \varphi\right) d X
\end{align*}
$$

$$
\forall \varphi \in W(Q): \varphi(x, 0)=0 \quad \text { in } \Omega
$$

$\mathcal{G}$ is a contraction mapping sending the Banach space $L^{2}\left(-T, 0, H_{0}^{1}(\Omega)\right)$ into itself. In fact, if $U=\mathscr{G}(u), V=\mathcal{G}(v), \tilde{U}=U-V$ and $\tilde{u}=u-v$, then from (2.49) it follows that $\tilde{U} \in L^{2}\left(-T, 0, H_{0}^{1}(\Omega)\right)$ is the solution of the C.D. problem

$$
\begin{align*}
\int_{Q}(M+\mu) \sum_{i} & \left(D_{i} \tilde{U} \mid D_{i} \varphi\right)-\left(\tilde{U} \left\lvert\, \frac{\partial \varphi}{\partial \dot{t}}\right.\right) d X=  \tag{2.50}\\
& =\int_{Q} \sum_{i}\left([M+\mu] D_{i} \tilde{u}-a^{i}(D u+D w)+a^{i}(D v+D w) \mid D_{i} \varphi\right) d X
\end{align*}
$$

$\forall \varphi \in W(Q): \varphi(x, 0)=0 \quad$ in $\Omega$.
After the $N \times N$ matrices

$$
A_{i j}=\left\{A_{i j}^{h k}\right\} \quad \text { with } \quad A_{i j}^{k h}=\int_{0}^{1} \frac{\partial a_{h}^{i}(\tau D u+(1-\tau) D v+D w)}{\partial p_{k}^{i}} d \tau
$$

have been introduced, problem (2.50) becomes

$$
\begin{align*}
& \begin{array}{l}
\int_{Q}(M+\mu) \sum_{i}\left(D_{i} \tilde{U} \mid D_{i} \varphi\right)-\left(\tilde{U} \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X= \\
\quad=\int_{Q} \sum_{i}\left([M+\mu] D_{i} \tilde{u}-\sum_{i} A_{i j} D_{j} \tilde{u} \mid D_{i} \varphi\right) d X
\end{array}  \tag{2.51}\\
& \forall \varphi \in W(Q): \varphi(x, 0)=0 \quad \text { in } \Omega
\end{align*}
$$

As $A_{i j} \in L^{\infty}(Q)$ satisfy the conditions (2.18), (2.19), by lemma 2.VIII we get this inequality (see (2.36)):

$$
\begin{equation*}
\int_{Q}\|D \tilde{U}\|^{2} d X \leqslant K^{2}(\mu) \int_{Q}\|D \tilde{u}\|^{2} d X \tag{2.52}
\end{equation*}
$$

where $K(\mu)<1$. We conclude that $\mathscr{C}$ has a unique fixed point $u$ which is the solution of problem (2.47).

As far as inequality (2.48) is concerned, we argue as follows:
Introduce the $N \times N$ matrices

$$
A_{i j}=\left\{A_{i j}^{h k}\right\}, \quad \text { with } \quad A_{i j}^{h k}=\int_{0}^{1} \frac{\partial a_{h}^{i}(\tau \cdot D u+D w)}{\partial p_{k}^{j}} d \tau
$$

then problem (2.47) may be written this way

$$
\begin{align*}
& \int_{Q} \sum_{i j}\left(A_{i j} D_{j} u \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q} \sum_{i}\left(B^{i}-a^{i}(D w) \mid D_{i} \varphi\right)+\left(B^{0} \mid \varphi\right) d X  \tag{2.53}\\
& \forall \varphi \in W(Q): \varphi(x, 0)=0 \quad \text { in } \Omega
\end{align*}
$$

so that $u \in L^{2}\left(-T, 0, H_{0}^{1}(\Omega)\right)$ is the solution of a C.D. linear problem with coefficients $A_{i j}$ which satisfy the conditions (2.18) and (2.19). Then, from (2.22) inequality (2.48) follows.

$$
\text { THE CASE } A^{i}=A^{i}(p)
$$

## 3. - Local differentiability of the solutions.

Let $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ be a solution in $Q$ of system

$$
\begin{equation*}
-\sum_{i} D_{i} A^{i}(D u)+\frac{\partial u}{\partial t}=0 \tag{3.1}
\end{equation*}
$$

in the sense that

$$
\begin{equation*}
\int_{Q} \sum_{i}\left(a^{i}(D u) \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=0, \quad \forall \varphi \in C_{0}^{\infty}(Q) \tag{3.2}
\end{equation*}
$$

$A^{i}(p), i=1, \ldots, n$, are vectors of $R^{N}$, of class $O^{1}\left(R^{n N}\right)$, which satisfy the conditions (1.5), (1.10) and (1.29).

We prove the following
Theorem 3.I. - The vector u is locally differentiable in $Q$, i.e. there exist

$$
\begin{equation*}
D_{i j} u \in L_{\mathrm{loc}}^{2}(Q), \quad \frac{\partial u}{\partial t} \in L_{10 \mathrm{c}}^{2}(Q) \tag{3.3}
\end{equation*}
$$

and $\forall B\left(x^{0}, 2 \sigma\right) \subset \subset \Omega, \forall 2 a \in(0, T)$

$$
\begin{equation*}
\int_{-a}^{0} d t \int_{B(\sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2}+\left\|\frac{\partial u}{\partial t}\right\|^{2} d x \leqslant c(v, M)\left(\frac{1}{\sigma^{2}}+\frac{1}{a}\right) \int_{-2 a}^{0} d t \int_{B(2 \sigma)}\|D u\|^{2} d x \tag{3.4}
\end{equation*}
$$

Proof. - Let $\theta(x), \varrho_{m}(t)$ and $\left\{g_{s}(t)\right\}$ be defined as in (2.41), (2.42), (2.43); $\left\{g_{s}\right\}$ being a sequence of symmetric mollifying functions. Define

$$
\begin{equation*}
\tau_{r, h} u=u\left(x+h e^{r}, t\right)-u(X) \tag{3.5}
\end{equation*}
$$

where $\left\{e^{r}\right\}_{r=1, \ldots, n}$ is the standard base of $R^{n}$, and suppose that

$$
|h|<\frac{\sigma}{2}
$$

Since (3.2) is valid $\forall \varphi \in W(Q): \varphi(x,-T)=\varphi(x, 0)=0$ in $\Omega$, for each fixed $m$ and $\forall s>m \vee 1 /(T-2 a)$, we may assume in (3.2)

$$
\varphi=\tau_{\boldsymbol{r},-h}\left\{\theta^{2} \varrho_{m}\left[\left(\varrho_{m} \tau_{r, h} u\right) * g_{s}\right]\right\}
$$

and hence we obtain that

$$
\begin{align*}
\int_{\boldsymbol{Q}} \sum_{i}\left(\tau_{r, h} a^{i}(D u) \mid D_{i}\left\{\theta^{2} \varrho_{m}\left[\left(\varrho_{m} \tau_{r, h} u\right) * g_{s}\right]\right\}\right) & d X=  \tag{3.6}\\
= & =\int_{Q}\left(\tau_{r, n} u \mid \theta^{2}\left\{\varrho_{m}\left[\left(\varrho_{m} \tau_{r, n} u\right) * g_{s}\right]\right\}^{\prime}\right) d X
\end{align*}
$$

Account taken of symmetry of $g_{s}(t)$, it turns out that

$$
\begin{equation*}
\int_{\varrho}\left(\tau_{r, h} u \mid \theta^{2} \varrho_{m}\left[\left(\varrho_{m} \tau_{r, h} u\right) * g_{s}\right]^{\prime}\right) d X=0 \tag{3.7}
\end{equation*}
$$

If, moreover, we set

$$
A_{i j}=\left\{A_{i j}\right\}, \quad \text { with } \quad A_{i j}^{{ }^{b}}=\int_{0}^{1} \frac{\partial{a_{h}^{i}}_{\partial p_{k}^{j}}}{\partial}\left(D u+\eta \tau_{r, h} D u\right) d \eta
$$

we have that

$$
\begin{equation*}
\tau_{r, n} a^{i}(D u)=\sum_{j=1}^{n} A_{i j}\left(\tau_{r, n} D_{j} u\right) \tag{3.8}
\end{equation*}
$$

By keeping in mind (3.7) and (3.8), from (3.6) we obtain

$$
\begin{align*}
& \text { (3.9) } \quad \int_{Q} \theta^{2} \varrho_{m} \sum_{i j}\left(A_{i j} \tau_{r, h} D_{j} u \mid\left(\varrho_{m} \tau_{r, h} D_{i} u\right) * g_{s}\right) d X=  \tag{3.9}\\
& =-2 \int_{Q}^{Q} \theta \varrho_{m} \sum_{i j}\left(A_{i j} \tau_{r, h} D_{j} u \mid D_{i} \theta \cdot\left[\left(\varrho_{m} \tau_{r, h} u\right) * g_{s}\right]\right) d X+\int_{Q} \theta^{2} \varrho_{m}^{\prime}\left(\tau_{r, h} u \mid\left(\varrho_{m} \tau_{r, h} u\right) * g_{s}\right) d X .
\end{align*}
$$

When $s \rightarrow+\infty$, then

$$
\left(\varrho_{m} \tau_{r, h} u\right) * g_{s} \rightarrow \varrho_{m} \tau_{r, h} u \quad \text { in } L^{2}\left(-T, 0, H^{1}(\Omega)\right)
$$

Therefore, from (3.9), taking the limit for $s \rightarrow+\infty$, we get that

$$
\begin{align*}
A & =\int_{Q} \theta^{2} \varrho_{m}^{2} \sum_{i j}\left(A_{i j} \tau_{r, h} D_{j} u \mid \tau_{r, h} D_{i} u\right) d X=  \tag{3.10}\\
& =-2 \int_{Q} \theta \varrho_{m}^{2} \sum_{i!}\left(A_{i j} \tau_{r, h} D_{j} u \mid D_{i} \theta \cdot \tau_{r, h} u\right) d X+\int_{Q} \theta^{2} \varrho_{m} \varrho_{m}^{\prime}\left\|\tau_{r, h} u\right\|^{2} d X=B+C .
\end{align*}
$$

By hypothesis (1.10)

$$
\begin{equation*}
A \geqslant v \int_{Q} \theta^{2} \varrho_{m}^{2}\left\|\tau_{r, h} \cdot D u\right\|^{2} d X \tag{3.11}
\end{equation*}
$$

and moreover, by (1.5) together with the Hölderis inequality, we have for every $\varepsilon>0$

$$
\begin{equation*}
|B| \leqslant \varepsilon \int_{Q} \theta^{2} \varrho_{m}^{2}\left\|\tau_{r, h} D u\right\|^{2} d X+c(\varepsilon, M) \int_{Q}\|D \theta\|^{2} \varrho_{m}^{2}\left\|\tau_{r, h} u\right\|^{2} d X . \tag{3.12}
\end{equation*}
$$

Finally, as $\varrho_{m} \varrho_{m}^{\prime} \leqslant 0$ if $t>-2 / m$,

$$
\begin{equation*}
C \leqslant \frac{e}{a} \int_{-2 a}^{-2 / m} d t \int_{B\left(\frac{3}{2} \sigma\right)}\left\|\tau_{r, h} u\right\|^{2} d x \tag{3.13}
\end{equation*}
$$

From (3.10) ... (3.13), choosing $\varepsilon$ small enough, it follows that

$$
\begin{aligned}
& \int_{-a}^{-2 / m} d t \int_{B(\sigma)}\left\|\tau_{r, h} D u\right\|^{2} d x \leqslant c(v, M)\left(\frac{1}{\sigma^{2}}+\frac{1}{a}\right) \int_{-2 a}^{0} d t \int_{B\left(\frac{1}{2} \sigma\right)}\left\|\tau_{r, h} u\right\|^{2} d x \leqslant \\
& \leqslant c(v, M)\left(\frac{1}{\sigma^{2}}+\frac{1}{a}\right)|h|^{2} \int_{-2 a}^{0} d t \int_{B(2 \sigma)} D u \|^{2} d x
\end{aligned}
$$

and taking the limit for $m \rightarrow+\infty$.

$$
\begin{equation*}
\int_{-a}^{0} d t \int_{B(\sigma)}\left\|\tau_{r, h} D u\right\|^{2} d x \leqslant c(v, M)\left(\frac{1}{\sigma^{2}}+\frac{1}{a}\right)|h|^{2} \int_{-2 a}^{0} d t \int_{B(2 \sigma)}\|D u\|^{2} d x . \tag{3.14}
\end{equation*}
$$

From this, because of a well known Nirenberg's lemma (see for instance [Q], p. 26), we conclude that there exist $D_{r} D u \in L^{2}(B(\sigma) \times(-a, 0)), r=1, \ldots, n$, and the following inequality

$$
\begin{equation*}
\int_{-a}^{0} d t \int_{B(\sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d x \leqslant c(v, M)\left(\frac{1}{\sigma^{2}}+\frac{1}{a}\right) \int_{-2 a}^{0} d t \int_{B(2 \sigma)}\|D u\|^{2} d x \tag{3.15}
\end{equation*}
$$

holds. From this it easily follows that

$$
\begin{equation*}
\exists \frac{\partial u}{\partial t} \in L^{2}(B(\sigma) \times(-a, 0)) \tag{3.16}
\end{equation*}
$$

In fact, from (3.2) we get that, $\forall \varphi \in C_{0}^{\infty}(B(\sigma) \times(-a, 0))$

$$
\begin{equation*}
\int_{-a}^{0} d t \int_{B(\sigma)}\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d x=-\int_{-a}^{0} d t \int_{B(\sigma)}\left(\sum_{i} D_{i} a^{i}(D u) \mid \varphi\right) d x \tag{3.17}
\end{equation*}
$$

and, because of (1.5) and (3.15)

$$
\sum_{i} D_{i} a^{i}(D u)=\sum_{i j} \sum_{k} D_{i j} u_{k} \frac{\partial a^{i}(D u)}{\partial p_{k}^{j}} \in L^{2}(B(\sigma) \times(-a, 0))
$$

From (3.17) and (3.15) we can furthermore get

$$
\begin{equation*}
\int_{-a}^{0} d t \int_{B(\sigma)}\left\|\frac{\partial u}{\partial t}\right\|^{2} d x=\int_{-a}^{0} d t \int_{B(\sigma)}\left\|\sum_{i} D_{i} a^{i}(D u)\right\|^{2} d x \leqslant c(v, M)\left(\frac{1}{\sigma^{2}}+\frac{1}{a}\right) \int_{-2 a \cdot B(2 \sigma)}^{0} d t \int_{\|}\|D\|^{2} d x \tag{3.18}
\end{equation*}
$$

This completes the proof of the estimate (3.4).

## 4. - Poincarés type estimates for the solutions in $Q$ of system (3.1).

Let $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ be a solution in $Q$ of system (3.1), under the hypotheses (1.5), (1.10) and (1.29).

Let $Q\left(X_{0}, 2 \sigma\right) \subset \subset Q$. Because of theorem 3.I, the vector $u$ belongs to $L^{2}\left(t_{0}-4 \sigma^{2}\right.$, $\left.t_{0}, H^{2}(B(2 \sigma))\right) \cap H^{1}\left(t_{0}-4 \sigma^{2}, t_{0}, L^{2}(B(2 \sigma))\right)$.

Theorem 4.I. - The following Poincaré's type inequalities

$$
\begin{align*}
& \tilde{\Phi}\left(u, X_{0}, \sigma\right) \leqslant c(v, M) \int\|D u\|^{2} d X  \tag{4.1}\\
& \tilde{\Phi}\left(D u, X_{0}, \sigma\right) \leqslant c(\nu, M) \int_{Q(\sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X \tag{4.2}
\end{align*}
$$

hold ( $\tilde{\Phi}$ is defined in (2.2)).
Proof. - From lemma 2.II and estimate (3.4), where one assumes $a=\sigma^{2}$, inequality (4.1) follows by taking into account that

$$
\int_{t_{0}-\sigma^{2}}^{t_{0}} d \tau \int_{Q(\sigma)} \frac{\|u(x, t)-u(x, \tau)\|^{2}}{|t-\tau|^{2}} d x d t \leqslant c \sigma^{2} \int_{Q(\sigma)}\left\|\frac{\partial u}{\partial t}\right\|^{2} d X .
$$

Inequality (4.2) follows from lemma 2.III together with the fact that, in $Q(\sigma)$ we have

$$
\left\|\frac{\partial u}{\partial t}\right\|^{2}=\left\|\sum_{i} D_{i} a^{i}(D u)\right\|^{2} \leqslant c(M) \sum_{i j}\left\|D_{i j} u\right\|^{2}
$$

## 5. - Some fundamental estimates for the solutions in $Q$ of system (3.1).

Let $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ be a solution in $Q$ of system (3.1), under the hypotheses (1.5), (1.10) and (1.29). Let $Q\left(X_{0}, \sigma\right) \subset \subset Q$. Because of theorem 3.I it turns out that

$$
u \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{z}(B(\sigma))\right) \cap H^{1}\left(t_{0}-\sigma^{2}, t_{0}, L^{2}(B(\sigma))\right)
$$

From (3.2), assuming $\varphi=D_{s} \psi, s=1, \ldots, n$, with $\psi \in C_{0}^{\infty}(Q(\sigma))$, we obtain

$$
\int_{Q(\sigma)} \sum_{i}\left(D_{s} a^{i}(D u) \mid D_{i} \psi\right)-\left(D_{s} u \left\lvert\, \frac{\partial \psi}{\partial t}\right.\right) d X=0
$$

and setting

$$
A_{i j}=\left\{A_{i j}^{h k}\right\}, \quad \text { with } \quad A_{i j}^{h \hbar}(p)=\frac{\partial a_{k}^{i}(p)}{\partial p_{h}^{j}}
$$

We have

$$
\begin{align*}
& \int_{a(\sigma)} \sum_{i!}\left(A_{i j}(D u) D_{j} D_{s} u \mid D_{i} \psi\right)-\left(D_{s} u \left\lvert\, \frac{\partial \psi}{\partial t}\right.\right) d X=0  \tag{5.1}\\
& \forall \psi \in C_{0}^{\infty}(Q(\sigma)) \text { and } s=1, \ldots, u
\end{align*}
$$

Furthermore, we introduce

$$
\begin{align*}
& U=D u \\
& \mathscr{A}_{i j}(p)=\left\{\begin{array}{c:c:c}
A_{i j} & 0 & 0 \\
\hdashline 0 & \ddots & 0 \\
\hdashline 0 & 0 & A_{i j}
\end{array}\right\} n^{2} \text { blocks } \tag{5.2}
\end{align*}
$$

then, from (5.1) it follows that $U \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{1}(B(\sigma))\right)$ is a solution of system

$$
\begin{equation*}
\int_{Q(\sigma)} \sum_{i j}\left(\mathscr{A}_{i j}(\mathbb{U}) D_{j} U \mid D_{i} \Psi\right)-\left(U \left\lvert\, \frac{\partial \Psi}{\partial t}\right.\right) d X=0, \quad \forall \Psi \in C_{0}^{\infty}(Q(\sigma)) \tag{5.3}
\end{equation*}
$$

We observe that $\mathcal{A}_{i j}(p)$ are $n N \times n N$ matrices, bounded, continuous and elliptic, i.e.

$$
\begin{equation*}
\sum_{i j}\left(\mathcal{A}_{i j}(p) \xi^{i} \mid \xi^{i}\right) \geqslant v\|\xi\|^{2}, \quad \forall p \in R^{n N} \text { and } \forall \xi \in R^{N n^{2}} \tag{5.4}
\end{equation*}
$$

Then, we can prove some fundamental estimates for the vectors $u, D u$ and $D_{i j} u$.
Theorem 5.I. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ is a solution in $Q$ of system (3.2), then there exists an $\varepsilon \in(0,1)$, such that, $\forall Q\left(X_{0}, \sigma\right) \subset \subset Q$ and $\forall \lambda \in(0,1)$,

$$
\begin{equation*}
\int_{Q(\lambda \sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X \leqslant c(\nu, M) \lambda^{\varepsilon(n+2)} \int_{Q(\sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X \tag{5.5}
\end{equation*}
$$

Proof. - System (5.3) can be regarded as a linear, strongly parabolic, system of second order, with coefficients $\mathcal{A}_{i j}(U(X)) \in L^{\infty}(Q(\sigma))$. Therefore, estimate (5.5) is a consequence of inequality (2.33) of lemma 2.IX.

Theorem 5.II. - If $u \in L^{2}\left(-T, 0, H^{I}(\Omega)\right)$ is a solution in $Q$ of system (3.2), then there exists an $\varepsilon, 0<\varepsilon<n /(n+2)$, such that, $\forall Q\left(X_{0}, \sigma\right) \subset \subset Q$ and $\forall \lambda \in(0,1)$,

$$
\begin{equation*}
\int_{Q(\lambda \sigma)}\|D u\|^{2} d X \leqslant c(v, M) \lambda^{2+\varepsilon(n+2)} \int_{Q(\sigma)}\|D u\|^{2} d X \tag{5.6}
\end{equation*}
$$

Proof. - Let us suppose $0<\lambda<\tau<\frac{1}{2}$. Then,

$$
\begin{equation*}
\int_{Q(\lambda \sigma)}\|D u\|^{2} d X \leqslant c(n)\left(\frac{\lambda}{\tau}\right)^{n+2} \int_{Q(\tau \sigma)}\|D u\|^{2} d X+c \int_{Q(\tau \sigma)}\left\|D u-(D u)_{Q(\tau \sigma)}\right\|^{2} d X \tag{5.7}
\end{equation*}
$$

On the other hand, account taken of inequalities (4.2) and (5.5)

$$
\int_{Q(\tau \sigma)}\left\|D u-(D u)_{Q(\tau \sigma)}\right\|^{2} d X \leqslant c(\tau \sigma)^{2} \int_{Q(\tau \sigma)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X \leqslant c(v, M) \sigma^{2} \tau^{2+\varepsilon(n+2)} \int_{Q(\sigma / 2)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X
$$

where $\varepsilon(\nu, M) \in(0,1)$. In conclusion

$$
\begin{equation*}
\int_{Q(\lambda \sigma)}\|D u\|^{2} d X \leqslant c\left(\frac{\lambda}{\tau}\right)^{n+2} \int_{Q(\tau \sigma)}\|D u\|^{2} d X+c \sigma^{2} \tau^{2+\varepsilon(n+2)} \int_{Q(\sigma / 2)} \sum_{i j}\left\|D_{i i} u\right\|^{2} d X . \tag{5.8}
\end{equation*}
$$

Now chose $\varepsilon<n /(n+2)$; then by lemma 1.I, p. 7 of [Q]

$$
\int_{Q(\lambda, \sigma)}\|D u\|^{2} d X \leqslant c\left(\frac{\lambda}{\tau}\right)^{2+\varepsilon(n+2)} \int_{Q(\tau \sigma)}\|D u\|^{2} d X+c \sigma^{2} \lambda^{2+\varepsilon(n+2)} \int_{Q(\sigma / 2)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X
$$

Taking the limit for $\tau \rightarrow \frac{1}{2}$, we obtain that, $\forall 0<\lambda<\frac{1}{2}$,

$$
\int_{Q(\lambda \sigma)}\|D u\|^{2} d X \leqslant c \lambda^{2+\varepsilon(n+2)}\left\{\int_{Q(\sigma)}\|D u\|^{2} d X+\sigma_{Q(\sigma / 2)} \sum_{i j}\left\|D_{i j} u\right\|^{2} d X\right\}
$$

and, because of inequality (3.4)

$$
\begin{equation*}
\int_{Q(\lambda \alpha)}\|D\|^{2} d X \leqslant c \lambda^{2+\varepsilon(n+2)} \int_{Q(\sigma)}\|D u\|^{2} d X . \tag{5.9}
\end{equation*}
$$

This shows the thesis when $0<\lambda<\frac{1}{2}$, however (5.6) is clearly true also for $\frac{1}{2} \leqslant \lambda<1$ too.

Theorem 5.III. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ is a solution in $Q$ of system (3.2), then there exists an $\varepsilon, 0<\varepsilon<n /(n+2)$, such that, $\forall Q\left(X_{0}, \sigma\right) \subset \subset Q$ and $\forall \lambda \in(0,1)$,

$$
\begin{equation*}
\int_{Q(\lambda \sigma)}\left\|u-u_{Q(\lambda \sigma)}\right\|^{2} d X \leqslant c(\nu, M) \lambda^{4+\varepsilon(n+2)} \int_{Q(\sigma)}\left\|u-u_{Q(\sigma)}\right\|^{2} d X . \tag{5.10}
\end{equation*}
$$

Proof. - Let us suppose $0<\lambda<\frac{1}{4}$. Inequality (5.6) is valid

$$
\begin{equation*}
\int_{Q(2 \lambda \sigma)}\|D u\|^{2} d X \leqslant c(v, M) \lambda^{2+e(n+2)} \int_{Q(\sigma / 2)}\|D u\|^{2} d X . \tag{5.11}
\end{equation*}
$$

Also the Poincarés type inequality (4.1) is true

$$
\begin{equation*}
\int_{Q(\lambda \sigma)}\left\|u-u_{Q(\lambda \sigma)}\right\|^{2} d X \leqslant c(v, M) \lambda^{2} \sigma_{Q(2 \lambda \sigma)}^{2} \int_{\| D u}\| \|^{2} d X \tag{5.12}
\end{equation*}
$$

Finally, system (3.1) may be written in the form (see (1.6))

$$
\begin{equation*}
-\sum_{i j} D_{i}\left(A_{i j}(D u) D_{j} u\right)+\frac{\partial u}{\partial t}=0 \quad \text { in } Q \tag{5.13}
\end{equation*}
$$

where

$$
A_{i j}=\left\{A_{i j}^{h k}\right\}, \quad \text { with } \quad A_{i j}^{h k}(p)=\int_{0}^{1} \frac{\partial a_{h}^{i}(\tau p)}{\partial p_{l i}^{j}} d \tau
$$

Therefore, the system has the form of a linear, strongly parabolic, system with coefficients $A_{i j}(D u(X)) \in L^{\infty}(Q)$. Then, estimate (2.40) of lemma 2.X

$$
\begin{equation*}
\int_{Q(\sigma / 2)}\|D u\|^{2} d X \leqslant \frac{e(v, M)}{\sigma^{2}} \int_{Q(\sigma)}\left\|u-\dot{u}_{Q(\sigma)}\right\|^{2} d X \tag{5.14}
\end{equation*}
$$

holds. From (5.12), (5.11), (5.14), inequality (5.10) follows when $0<\lambda<\frac{1}{4}$; however inequality (5.10) trivially holds for $\frac{1}{4} \leqslant \lambda<1$ too.

Corollary 5.I. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ is a solution in $Q$ of system (3.2), there exists an $\varepsilon, 0<\varepsilon<n /(n+2)$, such that, $\forall Q\left(X_{0}, \sigma\right) \subset \subset Q$ and $\forall \lambda \in(0,1)$,

$$
\begin{equation*}
\tilde{\Phi}\left(u, X_{0}, \lambda \sigma\right) \leqslant c(v, M) \lambda^{2+\varepsilon(n+2)} \tilde{\Phi}\left(u, X_{0}, \sigma\right) \tag{5.15}
\end{equation*}
$$

In fact, (5.15) is a consequence of theorems 5.II and 5.III.
Consider now system

$$
\begin{equation*}
-\sum_{i} D_{i} A^{i}(D u)+\frac{\partial u}{\partial t}=-\sum_{i} D_{i} B^{i}(X), \quad \text { in } Q \tag{5.16}
\end{equation*}
$$

under the conditions (1.5), (1.10), (1.29) and the hypothesis

$$
\begin{equation*}
B^{i}(X) \in L^{2}(Q) \tag{5.17}
\end{equation*}
$$

Theorem 5.IV. - Let $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ be a solution of system (5.16), that is

$$
\begin{equation*}
\int_{Q} \sum_{i}\left(a^{i}(D u) \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q} \sum_{i}\left(B^{i} \mid D_{i} \varphi\right) d X, \quad \forall \varphi \in C_{0}^{\infty}(Q) \tag{5.18}
\end{equation*}
$$

Then, $\forall Q\left(X_{0}, \sigma\right) \subset \subset Q$ and $\forall \lambda \in(0,1)$,

$$
\begin{equation*}
\tilde{\Phi}(u, X, \lambda \sigma) \leqslant c(v, M)\left\{\lambda^{2+\varepsilon(n+2)} \tilde{\Phi}\left(u, X_{0}, \sigma\right)+\sum_{i}\left|B^{i}\right|_{0, \ell(\rho)}^{2}\right\} \tag{5.19}
\end{equation*}
$$

where, as usual, $\varepsilon \in(0, n /(n+2))$.

Proof. - In $Q(\sigma)$ we decompose $u$ as $u=v-w$, where $w \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H_{0}^{1}(B(\sigma))\right)$ is the solution of the C.D. problem
(5.20) $\quad \int_{Q(\sigma)} \sum_{i}\left(a^{i}(D w+D u) \mid D_{i} \varphi\right)-\left(w \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q(\sigma)} \sum_{i}\left(a^{i}(D u)-B^{i} \mid D_{i} \varphi\right) d X$, $\forall \varphi \in W(Q(\sigma)): \varphi\left(x, t_{0}\right)=0 \quad$ in $B(\sigma)$.

As $a^{i}-B^{i} \in L^{2}(Q)$, by lemma 2.XI such a $w$ exists and is unique. Moreover, $w$ verifies inequality (2.48). Hence $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\tilde{\Phi}\left(w, X_{0}, \lambda \sigma\right) \leqslant c(\nu, M) \sum_{i}\left|B^{i}\right|_{0, Q(\sigma)}^{2} \tag{5.21}
\end{equation*}
$$

Clearly $v \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{1}(B(\sigma))\right)$ is a solution of system

$$
\begin{equation*}
\int_{a(\sigma)} \sum_{i}\left(a^{i}(D v) \mid D_{i} \varphi\right)-\left(v \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=0, \quad \forall \varphi \in C_{0}^{\infty}(Q(\sigma)) \tag{5.22}
\end{equation*}
$$

Then, by corollary 5.I, there exists $\varepsilon \in(0, n /(n+2))$, such that $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\widetilde{\Phi}\left(v, X_{0}, \lambda \sigma\right) \leqslant c(v, M) \lambda^{2+\varepsilon(n+2)} \tilde{\Phi}\left(v, X_{0}, \sigma\right) \tag{5.23}
\end{equation*}
$$

As $u=v-w$, from (5.21) and (5.23) estimate (5.19) easily follows.

## HÖLDER CONTINUITY AND PARTIAL HÖLDER CONTINUITY

6.     - The case $A^{i}=A^{i}(p)$.

Consider now system

$$
\begin{equation*}
-\sum_{i} D_{i} a^{i}(D u)+\frac{\partial u}{\partial t}=0 \quad \text { in } Q \tag{6.1}
\end{equation*}
$$

under the hypotheses (1.5), (1.10) and (1.29). From theorem 5.III it follows that
Theorem 6.I. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right)$ is a solution in $Q$ of system (6.1), and $n \leqslant 2$, then
(6.2) $\quad u \in C^{0, \mu}(Q, d), \quad$ with $\quad \mu=2-\frac{1-\varepsilon}{2}(n+2), \quad\left[\varepsilon \in\left(0, \frac{n}{n+2}\right)\right]$
and for every cylinder $A \subset \subset Q$

$$
\begin{equation*}
[u]_{\mu, \bar{A}} \leqslant e|u|_{0, Q}\left({ }^{6}\right) \tag{6.3}
\end{equation*}
$$

where $c$ depends on $M, \nu$ and on the distance between $A$ and the parabolic boundary of $Q\left({ }^{\circ}\right)$.

In fact, from the fundamental estimate (5.10) it follows that for every cylinder $A \subset \subset Q$

$$
[u]_{\mathbb{L}^{2}, 4+\varepsilon(n+2)(A, d)} \leqslant c|u|_{0, Q} .
$$

If $n \leqslant 2$, then $4+\varepsilon(n+2)>n+2$, and thus (see [8], theorem 3.I)

$$
[u]_{\mu, \bar{A}} \leqslant c[u]_{\mathbb{E}^{2}, A+e(n+2)(A, d)} \leqslant c|u|_{0, \mu}
$$

If the derivatives $\partial^{i} a / \partial p_{k}^{j}$ are uniformly continuous in $R^{n N}$, then also the vector $D u$ is partially $\mu$-Hölder continuous in $Q, \forall \mu<1$, and this fact holds for any $n$. Indeed (see section 5) the vector $U=D u$, at least locally, is a solution of the quasilinear and strongly parabolic system

$$
\begin{equation*}
\int_{Q} \sum_{i i l}\left(\mathcal{A}_{i j}(U) D_{j} U \mid D_{i} \varphi\right)-\left(U \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=0, \quad \forall \varphi \in C_{0}^{\infty}(Q) \tag{6.4}
\end{equation*}
$$

where coefficients $\mathcal{A}_{i j}(p)$ are uniformly continuous in $R^{n N}$. Therefore, the following theorem holds (see [9], [4])

Theorem 6.II. - There exists a set $Q_{0} \subset Q$, closed in $Q$ and with measure zero, such that

$$
\begin{equation*}
U=D u \in C^{0, \mu}\left(Q \backslash Q_{0}, d\right), \quad \forall \mu<1 \tag{6.5}
\end{equation*}
$$

## Furthermore,

$$
\begin{equation*}
H_{n+2-q}\left(Q_{0}\right)=0 \quad \text { for a } q>2 \tag{6.6}
\end{equation*}
$$

By (3.18) of [4] and inequality (4.2), the singular set of the vector Du may be defined this way

$$
\begin{equation*}
Q_{0}=\left\{X \in Q: \lim _{\sigma \rightarrow 0}^{\prime} \sigma_{Q(X, \sigma)}^{-n} \int_{Q\left(X\left\|^{2}+\sum_{i j}\right\| D_{i j} u \|^{2} d Y>0\right\} . . . . ~ . ~} \| Y\right. \tag{6.7}
\end{equation*}
$$

$\left.{ }^{( }{ }^{6}\right)[u]_{\mu, \bar{A}}=\sup _{X, \bar{F} \in \bar{A}} \frac{\|u(X)-u(Y)\|}{d^{\mu}(X, Y)}$.
${ }^{(7)}$ I.e. $[\Omega \times\{-T\}] \cup[\partial \Omega \times(-T, 0)]$.

However, $u$ is a solution of system (5.13), strongly parabolic in $Q$ and with coefficients $A_{i j}(D u(X)) \in L^{\infty}(Q)$, whereas $U=D u$ is a solution of system (6.4), strongly parabolic and with coefficients $\mathcal{A}_{i j}(U(X)) \in L^{\infty}(Q)$. Therefore, because of lemma 2.VII and inequalities (4.1) and (4.2), there exists a $q>2$, such that

$$
\begin{align*}
\left\{\int_{Q(X, \sigma)}\|D u\|^{q}+\sum_{i j}\left\|D_{i j} u\right\|^{q} d Y\right\}^{1 / q} \leqslant c\{\tilde{\Phi}(u, X, 2 \sigma) & +\tilde{\Phi}(D u, X, 2 \sigma)\}^{\frac{1}{2}} \leqslant  \tag{6.8}\\
& \leqslant\left\{\int_{Q(X, 2 \sigma)}\|D u\|^{2}+\sum_{i j}\left\|D_{i j} u\right\|^{2} d Y\right\}^{\frac{1}{3}}
\end{align*}
$$

Equality (6.6) follows from (6.8) (see for instance [Q] theorem 0.I, p. 142).
Account taken of theorem 6.I, the following conjecture seems to be reasonable:
If $n>2$ and $Q_{0}^{*}$ is the singular set of the vector $u$, then

$$
\begin{equation*}
H_{n-2}\left(Q_{0}^{*}\right)=0 \tag{6.9}
\end{equation*}
$$

7.     - The case $A^{i}=A^{i}(X, p)$.

Consider the system

$$
\begin{equation*}
-\sum_{i} D_{i} A^{i}(X, D u)+\frac{\partial u}{\partial t}=-\sum_{i} D_{i} B^{i}(X, u)+B^{0}(X, u, D u), \quad \text { in } Q \tag{7.1}
\end{equation*}
$$

where $A^{i}(X, p)$ are vectors of $R^{N}$, which satisfy conditions (1.5), (1.10) and (1.29), whereas $B^{i}$ and $B^{0}$ are vectors of $R^{N}$, measurable in $X$ and continuous in $u$ and ( $u, p$ ) respectively, each having strictly controlled growth

$$
\begin{align*}
& \left\|B^{i}(X, u)\right\| \leqslant c\left(1+\|u\|^{\alpha}\right)  \tag{7.2}\\
& \left\|B^{o}(X, u, D u)\right\| \leqslant c\left(1+\|u\|^{\beta}+\|p\|^{\gamma}\right) \tag{7.3}
\end{align*}
$$

where $\alpha, \beta, \gamma$ are subject to the conditions (1.24), (1.25), (1.26).
Let $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$ be a solution of system (7.1)

$$
\begin{equation*}
\int_{Q} \sum_{i}\left(A^{i} \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q} \sum_{i}\left(B^{i} \mid D_{i} \varphi\right)+\left(B^{0} \mid \varphi\right) d X, \quad \forall \varphi \in C_{0}^{\infty}(Q) \tag{7.4}
\end{equation*}
$$

In order to study the Hölder regularity of the $u$ we consider two cases: $n \leqslant 2$ and $n>2$.

## The case $n \leqslant 2$.

Suppose that vectors $A^{i}$ satisfy the following uniform continuity condition in $X$ :
There exists a bounded non-negative funotion $\omega(\sigma)$, defined for $\sigma>0$, which is nondecreasing and goes to zero as $\sigma \rightarrow 0$, such that $\forall X, Y \in Q$ and $\forall p \in R^{n N}$

$$
\begin{equation*}
\sum_{i}\left\|A^{i}(X, p)-A^{i}(Y, p)\right\|^{2} \leqslant \omega(d(X, Y))\left(1+\|p\|^{2}\right) \tag{7.5}
\end{equation*}
$$

Fix $Q\left(X_{0}, 2 \sigma\right) \subset \subset Q$ and let $w \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H_{0}^{1}(B(\sigma))\right)$ be the solution in $Q(\sigma)$ of the C.D. problem

$$
\begin{align*}
\int_{Q(\sigma)} \sum_{i}\left(A^{i}\left(X_{0}, D w+D u\right) \mid D_{i} \varphi\right) & -\left(w \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=  \tag{7.13}\\
& =\int_{Q(\sigma)} \sum_{i}\left(A^{i}(X, D u) \mid D_{i} \varphi\right)-\left(B^{0}(X, u, D u) \mid \varphi\right) d X, \\
\forall \varphi \in W(Q(\sigma)): \varphi\left(x, t_{0}\right)=0 \quad & \text { in } B(\sigma) .
\end{align*}
$$

By lemma 2.XI, such a $w$ exists and is unique, in fact (see (1.21))

$$
A^{i}(X, D u) \in L^{2}(Q) \quad \text { and } \quad B^{0}(X, u, D u) \in L^{2(n+2) /(n+4)}(Q)
$$

Set $v=u+w$. Obviously, $v \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{1}(B(\sigma))\right)$ is a solution of system

$$
\begin{align*}
& \quad \int_{Q(\sigma)} \sum_{i}\left(A^{i}\left(X_{0}, D v\right) \mid D_{i} \varphi\right)-\left(v \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q(\sigma)} \sum_{i}\left(B^{i}(X, u) \mid D_{i} \varphi\right) d X,  \tag{7.14}\\
& \forall \varphi \in C_{0}^{\infty}(Q(\sigma))
\end{align*}
$$

Estimate on $w$.
Using lemmas 2.XI and 2.II, we get the following estimate on the vector $w$ : $\forall \lambda \in(0,1]$

$$
\begin{align*}
\tilde{\Phi}\left(w, X_{0}, \lambda \sigma\right) \leqslant c(v, M) \int_{Q(\sigma)} \sum_{i} \| A^{i}(X, D u) & -A^{i}\left(X_{0}, D_{l}\right) \|^{2} d X+  \tag{7.15}\\
& +c(v, M)\left|B^{0}(X, u, D u)\right|_{0,2(n+2) /(n+4), Q(\sigma)}^{2}
\end{align*}
$$

On the other hand, because of the hypothesis (7.5),

$$
\int_{Q(\sigma)} \sum_{i}\left\|A^{i}(X, D u)-A^{i}\left(X_{0}, D u\right)\right\|^{2} d X \leqslant \omega(\sigma) \Phi\left(u, X_{0}, \sigma\right)
$$

and taking into account lemma $2 . V$

$$
\left|B^{0}(X, u, D u)\right|_{0,2(n+2) /(n+4), Q(\sigma)}^{2} \leqslant C(u) \sigma^{n+4-2(n+2)\left(\beta / \alpha_{0}\right) \vee(\gamma / 2)} \Phi\left(u, X_{0}, \sigma\right)
$$

We conclude that, $\forall \lambda \in(0,1)$,

$$
\begin{equation*}
\tilde{\Phi}\left(w, X_{0}, \lambda \sigma\right) \leqslant 0(\sigma) \Phi\left(u, X_{0}, \sigma\right) \tag{7.16}
\end{equation*}
$$

where $o(\sigma)$ goes to zero in respect of $\sigma$.
Estimate on $v$. - By theorem 5.IV, we get the following estimate on $v$ : There exists an $\varepsilon \in(0, n /(n+2))$ such that $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\tilde{\Phi}\left(v, X_{0}, \lambda \sigma\right) \leqslant c(v, M)\left\{\lambda^{2+\varepsilon(n+2)} \tilde{\Phi}\left(v, X_{0}, \sigma\right)+\sum_{i}\left|B^{i}(X, u)\right|_{0, \ell(\sigma)}^{2}\right\} \tag{7.17}
\end{equation*}
$$

On the other hand (see (2.12))

$$
\sum_{i}\left|B^{i}(X, u)\right|_{0, \ell(\sigma)}^{2} \leqslant c \int_{Q\left(X_{0}, \sigma\right)}\left(1+\|u\|^{2 \alpha}\right) d X=c \Psi\left(u, X_{0}, \sigma\right)
$$

moreover, because of lemma 2.IV, $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\Psi\left(u, X_{0}, \lambda \sigma\right) \leqslant c \lambda^{n+2} \Psi\left(u, X_{0}, \sigma\right)+C(u l) \sigma^{n(1-\alpha)+2} \tilde{\Phi}\left(u, X_{0}, \sigma\right) \tag{7.18}
\end{equation*}
$$

Account taken of lemma 1.II, p. 8 of [Q], from (7.17) and (7.18) it follows that $\forall \lambda \in(0,1)$ and $\forall \varepsilon^{\prime} \in(0, \varepsilon)$

$$
\begin{align*}
\tilde{\Phi}\left(v, X_{0}, \lambda \sigma\right) \leqslant c(v, M) \lambda^{2+\varepsilon^{\prime}(n+2)} \tilde{\Phi}\left(v, X_{0}\right. & , \sigma)+  \tag{7.19}\\
& +c \Phi\left(u, X_{v}, \sigma\right)\left\{\lambda^{2+\varepsilon^{\prime}(n+2)}+\sigma^{n(1-\alpha)+2}\right\}
\end{align*}
$$

As $u=v-w$ in $Q(\sigma)$, from (7.16) and (7.19) we conclude with the theorem below
THEOREM 7.1. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$ is a solution of system (7.1), under the assumptions (1.5), (1.10), (1.29) and (7.2), (7.3), (7.5), then $\forall Q\left(X_{0}, \sigma\right) \subset \subset Q$ and $\forall \lambda \in(0,1)$ the following estimate holds

$$
\begin{equation*}
\Phi\left(u, X_{0}, \lambda \sigma\right) \leqslant c \Phi\left(u, X_{0}, \sigma\right)\left\{\lambda^{2+\varepsilon^{\prime}(n+2)}+0(\sigma)\right\} \tag{7.20}
\end{equation*}
$$

where $0(\sigma)$ goes to zero with $\sigma$.
Proof. - As $u=v-w$ in $Q(\sigma)$, from (7.16) and (7.19) we obtain that $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\widetilde{\Phi}\left(u, X_{0}, \lambda \sigma\right) \leqslant c \Phi\left(u, X_{0}, \sigma\right)\left\{\lambda^{2+\varepsilon^{\prime}(n+2)}+0(\sigma)\right\} \tag{7.21}
\end{equation*}
$$

where $0(\sigma) \rightarrow 0$ when $\sigma \rightarrow 0$. To the left-hand side of (7.21) we can add the integral

$$
\int_{\varrho(\lambda \sigma)} 1+\|u\|^{\alpha_{0}} d X
$$

8 - Annali di Matematica
because

$$
\int_{Q(\lambda \sigma)} 1+\|u\|^{\alpha_{0}} d X \leqslant c(n) \lambda^{n+2} \int_{Q(\sigma)} 1+\|u\|^{\alpha_{0}} d X+e(n) \int_{Q(\sigma)}\left\|u-u_{Q(\sigma)}\right\|^{\alpha_{0}} d X
$$

and from (6.37) of [5], if $n>2$, or from (2.4), if $n \leqslant 2$, we have

$$
\int_{Q(\sigma)}\left\|u-u_{Q(\sigma)}\right\|^{q_{0}} d X \leqslant C(u) 0(\sigma) \Phi\left(u, X_{0}, \sigma\right)
$$

where $0(\sigma)$ goes to zero in respect of $\sigma$.
Inequality (7.20) allows us to achieve the Hölder continuity in $Q$ of the vector $u$ when $n \leqslant 2$.

In fact, from (7.20) and from lemma 1.III, p. 9 of [Q], it follows that $\forall \varepsilon^{\prime}<\varepsilon$ there exists a $\sigma\left(\varepsilon^{\prime}\right)$ such that, $\forall \lambda \in(0,1)$ and $0<\sigma \leqslant \sigma\left(\varepsilon^{\prime}\right)$

$$
\begin{equation*}
\Phi\left(u, X_{0}, \lambda \sigma\right) \leqslant c \lambda^{2+\varepsilon^{\prime}(n+2)} \Phi\left(u, X_{0}, \sigma\right) \tag{7.22}
\end{equation*}
$$

This inequality is quite analogous to the fundamental estimate (5.15) which holds for the solutions of system (6.1). In particular, from (7.22) we obtain

$$
\begin{equation*}
\int_{Q(\lambda \sigma)}\left\|u-u_{Q(\lambda \sigma)}\right\|^{2} d X \leqslant e \lambda^{4+\varepsilon^{\prime}(n+2)} \sigma^{2} \Phi\left(u, X_{0}, \sigma\right) \tag{7.23}
\end{equation*}
$$

Therefore,

$$
\begin{equation*}
u \in \mathcal{S}_{\mathrm{loo}}^{2,4+\varepsilon^{\prime}(n+2)}(Q, d) \tag{7.24}
\end{equation*}
$$

and certainly it results $4+\varepsilon^{\prime}(n+2)>n+2$, if $n \leqslant 2$. In general, the validity of the previous inequality depends on the value of $\varepsilon$, which in its turn depends on the constants $\nu$ and $M$ of the system.

Theorem 7.II. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$ is a solution in $Q$ of system (7.1), under the assumptions (1.5), (1.10), (1.29) and (7.2), (7.3), (7.5), then

$$
\begin{equation*}
u \in C^{0, \mu}(Q, d), \quad \text { with } \quad \mu=2-\frac{1-\varepsilon}{2}(n+2) \tag{7.25}
\end{equation*}
$$

As it is known from (7.24), by theorem 3.I of [8], (7.25) follows.

The case $n>2$.
$\Delta s($ see (1.6) $)$

$$
A^{i}(X, p)=\sum_{j} A_{i j}(X, p) p^{j}
$$

system (7.1) may be written in the form

$$
\begin{equation*}
-\sum_{i j} D_{i} A_{i j}(X, D u) D_{j} u+\frac{\partial u}{\partial t}=-\sum_{i} D_{i} B^{i}(X, u)+B^{0}(X, u, D u) \tag{7.26}
\end{equation*}
$$

Let us suppose that the derivatives $\partial a^{i} j \partial p_{k}^{j}$, as well as the matrices $A_{i j}(X, p)$, are uniformly continuous in $\bar{Q} \times R^{n N}$. As the $\partial a^{i} / \partial p_{k}^{j}$ are also bounded (see (1.5)), it follows that there exists a non-negative function $\omega(\sigma)$, defined for $\sigma \geqslant 0$ with $\omega(0)=0$, non-decreasing, continuous, bounded and concave, such that $\forall X, Y \in Q$ and $\forall p$, $\bar{p} \in R^{n N}$

$$
\begin{equation*}
\left\{\sum_{i j}\left\|A_{i j}(X, p)-A_{i j}(Y, \bar{p})\right\|^{2}\right\}^{\frac{1}{2}} \leqslant \omega\left(d^{2}(X, Y)+\|p-\bar{p}\|^{2}\right) \tag{7.27}
\end{equation*}
$$

We premise a result of $L_{\mathrm{loc}}^{\alpha}$-regularity for the vector $D u$. This result can be proved for systems of the general type.

Lemma 7.I. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$ is a solution in $Q$ of the system

$$
\begin{equation*}
-\sum_{i} D_{i} A^{i}(X, u, D u)+\frac{\partial u}{\partial t}=-\sum_{i} D_{i} B^{i}(X, u)+B^{0}(X, u, D u) \tag{7.28}
\end{equation*}
$$

which is strongly parabolic, with strictly controlled growth, and satisfies hypothesis (1.5), then $\exists \bar{q}$
(7.

$$
2<\bar{q} \leqslant \frac{q_{0}}{\alpha}
$$

such $\frac{\text { in }}{}$ that $\forall q \in(2, \bar{q}]$ and $\forall Q\left(X_{0}, 2 \sigma\right) \subset \subset Q$, with $\sigma \leqslant 1$,

$$
\begin{equation*}
\left(\int_{Q(\sigma)}\|D u\|^{q} d X\right)^{2 / q} \leqslant c(u) \sigma^{(n+2)(2 / \alpha-1)} \Phi\left(u, X_{0}, 2 \sigma\right) \tag{7.30}
\end{equation*}
$$

where $O(u)$ is defined in (2.17) $\left(^{8}\right)$.
Proof. - As (see (1.6))

$$
A^{i}(X, u, p)=\sum_{j} A_{i j}(X, u, p) p^{i}
$$

system (7.28) can be regarded as a linear strongly parabolic system with coefficients $A_{i j}(X, u(X), D u(X)) \in L^{\infty}(Q)$.
${ }^{(8)}$ An analogous result for quasi-linear parabolic systems is proved in [5], section 5.

Because of lemma 2.I

$$
B^{i}(X, u) \in L^{q_{0} / \alpha}(Q) \quad \text { and } \quad B^{0}(X, u, D u) \in L^{\left(Q_{0} / \beta\right) \wedge(2 / \gamma)}(Q)
$$

Therefore, by lemma 2.VII, there exists $\bar{q}$

$$
\begin{equation*}
2<\bar{q} \leqslant \frac{q_{0}}{\alpha} \tag{7.31}
\end{equation*}
$$

such that $\forall q \in(2, \bar{q}]$ and $\forall Q\left(X_{\mathbf{0}}, 2 \sigma\right) \subset \subset Q$

$$
\begin{equation*}
\frac{2(n+2)}{n+4}<r(q)<\frac{q_{0}}{\beta} \wedge \frac{2}{\gamma} \tag{7.32}
\end{equation*}
$$

and

$$
\begin{align*}
&\left(f_{Q(\sigma)}\|D u\|^{Q} d X\right)^{2 / \alpha} \leqslant e\left(f_{Q(Q \sigma)} \sum_{i}\left\|B^{i}\right\|^{q} d X\right)^{2 / q}+  \tag{7.33}\\
&+c \sigma^{2}\left(f_{Q(2 \sigma)}\left\|B^{0}\right\|^{r(a)} d X\right)^{2 / r(q)}+c \sigma^{-(n+2)} \tilde{\Phi}\left(u, X_{0}, 2 \sigma\right) .
\end{align*}
$$

On the other hand, account taken of (7.31),

$$
\begin{equation*}
\left(f_{Q(2 \sigma)} \sum_{i}\left\|B^{i}\right\|^{d} d X\right)^{2 / q} \leqslant c \int_{Q(2 \sigma)} 1+\|u\|^{\alpha_{0}} d X \leqslant c \sigma^{-(n+2)} \Phi\left(u, X_{0}, 2 \sigma\right) \tag{7.34}
\end{equation*}
$$

and by lemma 2.V and (7.32),

$$
\begin{equation*}
\left(f_{Q(2 \sigma)}\left\|B^{0}\right\|^{r(\alpha)} d X\right)^{2 / r(\alpha)} \leqslant C(u) \sigma^{-2(n+2)\left(\left(\beta / q_{0}\right) \vee(\gamma / 2)\right)} \Phi\left(u, X_{0}, 2 \sigma\right) \tag{7.35}
\end{equation*}
$$

Since $\sigma \leqslant 1$, estimate (7.30) easily follows from (7.33), (7.34), (7.35).
Thát being stated, we prove the following theorem which, in case $n>2$, replaces theorem 7.I.

Theorem 7.III. - If $u$ is a solution of system (7.1), under the hypotheses (1.5), (1.10), (1.29), (7.2), (7.3) and if the derivatives $\partial a^{i} / \partial p_{k}^{j}$ are uniformly continuous in $\bar{Q} \times R^{n N}$, then $\forall Q\left(X_{0}, \sigma\right) \subset \subset Q$, with $\sigma \leqslant 2, \forall \lambda \in(0,1)$ and $\forall \varepsilon \in(0, n \alpha)$

$$
\begin{align*}
& \Phi\left(u, X_{0}, \lambda \sigma\right) \leqslant  \tag{7.36}\\
& \quad \leqslant A \Phi\left(u, X_{0}, \sigma\right)\left\{\lambda^{n+2-\varepsilon}+o(\sigma)+\left[\omega\left(\sigma^{2}+\int_{Q(\sigma)}\left\|D u-(D u)_{Q(\sigma)}\right\|^{2} d X\right)\right]^{1-2 / q}\right\}
\end{align*}
$$

where $o(\sigma)$ goes to zero in respect of $\sigma$.

Proof. - We argue as in theorem 7.I. System (7.1) can be written in the form (7.26). Fix $Q\left(X_{0}, 2 \sigma\right) \subset \subset Q$, with $\sigma \leqslant 1$, and, for the sake of simplicity, set

$$
\begin{equation*}
\bar{A}_{i j}=A_{i j}\left(X_{0},(D u)_{Q(\sigma)}\right) \tag{7.37}
\end{equation*}
$$

Let $w \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H_{0}^{1}(B(\sigma))\right)$ be the solution of the C.D. problem

$$
\begin{align*}
\int_{Q(\sigma)} \sum_{i, j}\left(\bar{A}_{i j} D_{j} w \mid D_{i} \varphi\right)-\left(w \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q(\sigma)} \sum_{i j}\left(\left[\bar{A}_{i j}-A_{i j}(X, D u)\right] D_{j} u \mid D_{i} \varphi\right) d X+  \tag{7.38}\\
+\int_{Q(\sigma)}\left(B^{0}(X, u, D u) \mid \varphi\right) d X, \quad \forall \varphi \in W(Q(\sigma)): \varphi\left(x, t_{0}\right)=0 \quad \text { in } B(\sigma) .
\end{align*}
$$

Clearly, $v=u-w \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{1}(B(\sigma))\right)$ is a solution of the system

$$
\begin{equation*}
-\sum_{i} D_{i}\left(\bar{A}_{i j} D_{j} v\right)+\frac{\partial v}{\partial t}=-\sum_{i} D_{i} B^{i}(X, u) \quad \text { in } Q(\sigma) \tag{7.39}
\end{equation*}
$$

Estimate on $v .-(7.39)$ is a linear system with constant coefficients; therefore, by lemma 2.II of [4], we have that $\forall \lambda \in(0,1)$

$$
\tilde{\Phi}\left(v, X_{0}, \lambda \sigma\right) \leqslant c(v, M)\left\{\lambda^{n+2} \tilde{\Phi}\left(v, X_{0}, \sigma\right)+\sum_{i}\left|B^{i}(X, u)\right|_{0, \ell(\sigma)}^{2}\right\}
$$

Since

$$
\sum_{i}\left|B^{i}(X, u)\right|_{0, Q(\sigma)}^{2} \leqslant c \int_{Q(\sigma)} 1+\| u^{2 \alpha} d X=c \Psi\left(u, X_{0}, \sigma\right)
$$

using lemma 2.IV and lemma 1.II, p. 8 of [Q], we conclude that $\forall \lambda \in(0,1)$ and $\forall \varepsilon \in(0, n \alpha)$
(7.40) $\tilde{\Phi}\left(v, X_{0}, \lambda \sigma\right) \leqslant \omega(v, M) \lambda^{n+2-\varepsilon} \tilde{\Phi}\left(v, X_{0}, \sigma\right)+c \Phi\left(u, X_{0}, \sigma\right)\left\{\lambda^{n+2-\varepsilon}+\sigma^{n(1-\alpha)+2}\right\}$.

Estimate on w. - Because of lemma 2.VI, we have thet $\forall \lambda \in(0,1]$

$$
\begin{align*}
\tilde{\Phi}\left(w, X_{0}, \lambda \sigma\right) \leqslant c(v, M) \int_{Q(\sigma)} \sum_{i j} \| A_{i j}(X, D u) & -\bar{A}_{i j}\left\|^{2} \cdot\right\| D u \|^{2} d X+  \tag{7.41}\\
& +c(v, M)\left|B^{0}(X, u, D u)\right|_{0,2(n+2) /(n+4), Q(\sigma)}^{2}
\end{align*}
$$

On the other hand, taking into account (7.27), lemma 7.I, the boundedness and concavity of $\omega$, we obtain

$$
\begin{align*}
\int_{Q(\sigma)} \sum_{i j} \| A_{i j}(X, D u)- & \bar{A}_{i j}\left\|^{2} \cdot\right\| D u\left\|^{2} d X \leqslant \int_{Q(\sigma)} \omega(\ldots)\right\| D u \|^{2} d X \leqslant  \tag{7.42}\\
& \leqslant c \sigma^{n+2}\left(f_{Q(\sigma)}\|D u\|^{q} d X\right)^{2 / a}\left(f_{Q(\sigma)} \omega(\ldots) d X\right)^{1-2 / \alpha} \leqslant \\
& \leqslant c(u) \Phi\left(u, X_{0}, 2 \sigma\right)\left[\omega\left(\sigma^{2}+\int_{Q(\sigma)} D u-(D u)_{Q(\sigma)} \|^{2} d X\right)\right]^{1-2 / a},
\end{align*}
$$

Finally, $\left|B^{0}\right|_{0,2(n+2)(n+4), Q(\sigma)}^{2}$ can be estimated as in lemma 2.V. Then, we conclude that $\forall \lambda \in(0,1]$

$$
\begin{equation*}
\tilde{\Phi}\left(w, X_{0}, \lambda \sigma\right) \leqslant c \Phi\left(u, X_{0}, 2 \sigma\right)\left\{o(\sigma)+\left[\omega\left(\sigma^{2}+\int_{Q(\sigma)}\left\|D u-(D u)_{Q(\sigma)}\right\|^{2} d X\right)\right]^{1-2 / q}\right\} \tag{7.43}
\end{equation*}
$$

As $u=v+w$ in $Q(\sigma)$, from (7.40) and (7.42) we conclude that $\forall \lambda \in(0,1)$ and $\forall \varepsilon>0$

$$
\tilde{\Phi}\left(u, X_{0}, \lambda \sigma\right) \leqslant c \Phi\left(u, X_{0}, 2 \sigma\right)\left\{\lambda^{n+2-\varepsilon}+0(\sigma)+[\omega(\ldots)]^{1-2 / q}\right\}
$$

and, from this, (7.36) follows as the integral

$$
\int_{Q(\lambda \sigma)} 1+\|u\|^{\alpha_{0}} d X
$$

can be added to the left-hand side for the same motivations we pleaded in the proof of theorem 7.I.

The following theorem on partial Hölder continuity of $u$ is a consequence of theorem 7.III.

Set

$$
\begin{equation*}
Q_{1}=\left\{X \in Q: \lim _{\sigma \rightarrow 0}^{\prime \prime} \int_{Q(X, \sigma)}\left\|D u-(D u)_{Q(X, \sigma)}\right\|^{2} d Y>0\right\} \tag{7.44}
\end{equation*}
$$

The properties of Lebesgue integral imply that

$$
\begin{equation*}
\text { meas } Q_{1}=0 \tag{7.45}
\end{equation*}
$$

Theorem 7.IV. - If $u$ is a solution of system (7.1), under the hypotheses (1.5), (1.10), (1.29), (7.2), (7.3), and if the derivatives $\partial a^{i} / \partial p_{k}^{j}$ are uniformly continuous in $\bar{Q} \times R^{n N}$, then there exists a set $Q_{0}$, closed in $Q$, with

$$
\begin{equation*}
Q_{0} \subset Q_{1}, \quad \text { and therefore } \quad \text { meas } Q_{0}=0 \tag{7.46}
\end{equation*}
$$

such that

$$
\begin{equation*}
u \in C^{0, \mu}\left(Q \backslash Q_{0}, d\right), \quad \forall \mu<1 \tag{7.47}
\end{equation*}
$$

This theorem may be proved by reasoning exactly as in the proof of theorem 5.I of [2].
8. - The case $A^{i}=A^{i}(X, u, p)$.

Consider now a system of the general type

$$
-\sum_{i} D_{i} a^{i}(X, u, D u)+\frac{\partial u}{\partial t}=B^{\mathrm{o}}(X, u, D u), \quad \text { in } Q
$$

which may be written in the form (see section 1)

$$
\begin{equation*}
-\sum_{i} D_{i} A^{i}(X, u, D u)+\frac{\partial u}{\partial t}=-\sum_{i} D_{i} B^{i}(X, u)+B^{0}(X, u, D u) \tag{j}
\end{equation*}
$$

where $A^{i}(X, u, p), B^{i}(X, u), B^{0}(X, u, p)$ are vectors of $R^{N}$, which satisfy conditions (1.5), (1.10) and have strictly controlled growths

$$
\begin{align*}
& \left\|A^{i}(X, u, p)\right\| \leqslant c(M)\|p\|  \tag{8.2}\\
& \left\|B^{i}(X, u)\right\| \leqslant c\left(1+\|u\|^{\alpha}\right)  \tag{8.3}\\
& \|B 1(X, u, p)\| \leqslant c\left(1+\|u\|^{\beta}+\|p\|^{\gamma}\right) \tag{8.4}
\end{align*}
$$

where $\alpha, \beta, \gamma$ are subject to the conditions (1.24), (1.25), (1.26).
Let $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$ be a solution of system (8.1) i.e.

$$
\begin{equation*}
\int_{Q} \sum_{i}\left(A^{i} \mid D_{i} \varphi\right)-\left(u \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=\int_{Q} \sum_{i}\left(B^{i} \mid D_{i} \varphi\right)+\left(B^{0} \mid \varphi\right) d X, \quad \forall \varphi \in C_{0}^{\infty}(Q) \tag{8.5}
\end{equation*}
$$

Also for these systems, in order to study the Hölder regularity of the vector $u$, we consider the cases $n \leqslant 2$ and $n>2$ separately.

## The case $n \leqslant 2$.

Our proof is quite analogous to that of the case $n \leqslant 2$ in section 7 .
Suppose that the vectors $A^{i}$ verify this uniform continuity condition with respect to $(X, u)$ (see (7.5)) :

There exists a non-decreasing, bounded, continuous, concave function $\omega(\sigma)$, defined for $\sigma \geqslant 0$ with $\omega(0)=0$, such that $\forall X, Y \in Q, \forall u, v \in R^{N}$ and $\forall p \in R^{n N}$

$$
\begin{equation*}
\sum_{i}\left\|A^{i}(X, u, p)-A^{i}(Y, v, p)\right\|^{2} \leqslant \omega\left(d^{2}(X, Y)+\|u-v\|^{2}\right)\|p\|^{2} \tag{8.6}
\end{equation*}
$$

This condition is easily fulfilled if, for instance, $A^{i} \in C^{1}(\bar{\Lambda})$ and, in agreement with (8.2),

$$
\begin{equation*}
\left\|\frac{\partial A^{i}}{\partial t}\right\|+\sum_{\varepsilon}\left\|\frac{\partial A^{i}}{\partial x_{s}}\right\|+\sum_{k}\left\|\frac{\partial A^{i}}{\partial u_{k}}\right\| \leqslant c\|p\| . \tag{8.7}
\end{equation*}
$$

In fact, from (8.2)

$$
\begin{equation*}
\left\|A^{i}(X, u, p)-A^{i}(Y, v, p)\right\| \leqslant c_{1}(M)\|p\| \tag{8.8}
\end{equation*}
$$

and by (8.7)

$$
\begin{aligned}
& (8.9) \quad\left\|A^{i}(X, u, p)-A^{i}(Y, v, p)\right\|= \\
& =\left\|\int_{0}^{1} \frac{d}{d \eta} A^{i}(\eta(X-Y)+Y, \eta(u-v)+v, p) d \eta\right\| \leqslant c_{2} \sqrt{T}\|p\| \cdot\left\{d^{2}(X, Y)+\|u-v\|^{2}\right\}^{\frac{1}{2}}
\end{aligned}
$$

Therefore, it is enough to assume

$$
\begin{equation*}
\omega(\sigma)=n c_{1}(M) \min \left\{c_{1}(M), c_{2} \sqrt{T} \sqrt{\sigma}\right\} \tag{8.10}
\end{equation*}
$$

Having fixed $Q\left(X_{0}, 2 \sigma\right) \subset \subset$, with $\mathrm{g} \leqslant 1$, we set, for simplicity,

$$
\begin{equation*}
\bar{A}^{i}(p)=A^{i}\left(X_{0}, u_{Q(\sigma)}, p\right) \tag{8.11}
\end{equation*}
$$

Let $w \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H_{0}^{1}(B(\sigma))\right)$ be the solution in $Q(\sigma)$ of the C.D. problem

$$
\begin{align*}
\int_{Q(\alpha)} \sum_{i}\left(\bar{A}^{i}(D w+D u) \mid D_{i} \varphi\right)- & \left(w \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=  \tag{8.12}\\
& =\int_{Q(\sigma)} \sum_{i}\left(A^{i}(X, u, D u) \mid D_{i} \varphi\right)-\left(B^{0}(X, u, D u) \mid \varphi\right) d X
\end{align*}
$$

$\forall \varphi \in W(Q(\sigma)): \varphi\left(x, t_{0}\right)=0 \quad$ in $B(\sigma)$.
Because of lemma 2.XI and of (1.21), $w$ exists and is unique.
Set $v=u+w$. Clearly $v \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H^{1}(B(\sigma))\right)$ is a solution of system

$$
\begin{align*}
& \int_{Q(\sigma)} \sum_{i}\left(\bar{A}^{i}(D v) \mid D_{i} \varphi\right)-\left(v \left\lvert\, \frac{\partial \varphi}{\partial t}\right.\right) d X=-\int \sum_{i}\left(B^{i}(X, u) \mid D_{i} \varphi\right) d X  \tag{8.13}\\
& \forall \varphi \in C_{0}^{\infty}(Q(\sigma))
\end{align*}
$$

Inequality (7.19) holds on $v$ i.e.: $\exists \varepsilon \in(0, n /(n+2))$ such that $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\tilde{\Phi}\left(v, X_{0}, \lambda \sigma\right) \leqslant e \lambda^{2+\varepsilon(n+2)} \tilde{\Phi}\left(v, X_{0}, \sigma\right)+e \Phi\left(u, X_{0}, \sigma\right)\left\{\lambda^{2+\varepsilon(x+2)}+o(\sigma)\right\} \tag{8.14}
\end{equation*}
$$

Inequality (7.15) holds on $w$, therefore, $\forall \lambda \in(0,1]$,

$$
\begin{equation*}
\tilde{\Phi}\left(w, X_{0}, \lambda \sigma\right) \leqslant o(\sigma) \Phi\left(u, X_{0}, \sigma\right)+c(v, M) \int_{Q(\sigma)} \sum_{i}\left\|A^{i}(X, u, D u)-\bar{A}^{i}(D u)\right\|^{2} d X \tag{8.15}
\end{equation*}
$$

On the other hand, taking into account hypothesis (8.6), lemma 7.I, the concavity and boundedness of $\omega$, we get

$$
\begin{align*}
\int_{Q(\sigma)} \sum_{i}\left\|A^{i}(X, u, D u)-\bar{A}^{i}(D u)\right\|^{2} d X & \leqslant \int_{Q(\sigma)} \omega\left(\sigma^{2}+\left\|u-u_{Q(\sigma)}\right\|^{2}\right)\|D u\|^{2} d X \leqslant  \tag{8.16}\\
& \leqslant c \sigma^{n+2}\left(f_{Q(\sigma)}\|D u\|^{q} d X\right)^{2 / q}\left(f_{Q(\sigma)} \omega(\ldots) d X\right)^{1-2 / Q} \leqslant \\
& \leqslant C(u) \Phi\left(u, X_{0}, 2 \sigma\right)\left[\omega\left(c \sigma^{-n} \Phi\left(u, X_{0}, \sigma\right)\right)\right]^{1-2 / q} .
\end{align*}
$$

We conclude that $\forall \lambda \in(0,1]$

$$
\begin{equation*}
\tilde{\Phi}\left(w, X_{0}, \lambda \sigma\right) \leqslant c \Phi\left(u, X_{0}, 2 \sigma\right)\left\{o(\sigma)+\left[\omega\left(c \sigma^{-n} \Phi\left(u, X_{0}, \sigma\right)\right)\right]^{1-2 / q}\right\} \tag{8.17}
\end{equation*}
$$

Therefore, the following theorem holds
TheOREM 8.I. - If $u \in L^{2}\left(-T, 0, H^{1}(\Omega)\right) \cap L^{\infty}\left(-T, 0, L^{2}(\Omega)\right)$ is a solution of system (8.1), under the hypotheses (1.5), (1.10), (8.2), (8.3), (8.4), (8.6), then there exists $\varepsilon \in(0, n /(n+2))$ such that $\forall Q\left(X_{0}, \sigma\right) \subset \subset Q$, with $\sigma<2$, and $\forall \lambda \in(0,1)$

$$
\begin{equation*}
\Phi\left(u, X_{0}, \lambda \sigma\right) \leqslant c \Phi\left(u, X_{0}, \sigma\right)\left\{\lambda^{2+e(n+2)}+o(\sigma)+\left[\omega\left(c \sigma^{-n} \Phi\left(u, X_{0}, \sigma\right)\right)\right]^{1-2 / \tau}\right\} \tag{8.18}
\end{equation*}
$$

where $o(\sigma)$ goes to zero with $\sigma$.
In fact, as $u=v-w$ in $Q(\sigma)$, from (8.14), (8.17) it follows that $\forall \lambda \in(0,1)$

$$
\tilde{\Phi}\left(u, X_{0}, \lambda \sigma\right) \leqslant c \Phi\left(u, X_{0}, 2 \sigma\right)\left\{\lambda^{2+\varepsilon(n+2)}+o(\sigma)+[\omega(\ldots)]^{1-2 / q}\right\}
$$

The previous inequality is trivial for $1 \leqslant \lambda<2$. Finally, to the left-hand side we can add the integral

$$
\int_{Q(\lambda \sigma)} 1+\|u\|^{\|_{0}} d X
$$

for the same reasons we pleaded in the proof of theorem 7.I.
From the previous theorem we draw forth the partial Hollder continuity of the vector $u$, by reasoning exactly as in [4] section 3 .

Set

$$
\begin{equation*}
Q_{0}=\left\{X \in Q: \lim _{\sigma \rightarrow 0}^{\prime} \sigma^{-n} \Phi(u, X, \sigma)>0\right\} \tag{8.19}
\end{equation*}
$$

we have that

$$
\begin{equation*}
H_{n}\left(Q_{0}\right)=0 \tag{8.20}
\end{equation*}
$$

(it is sufficient to argue as in theorem 2 of [9]).

Theorem 8.II. - If $u$ is a solution of system (8.1), under the hypotheses (1.5), (1.10), (8.2), (8.3), (8.4), (8.6), then $Q_{0}$ is closed in $Q$ and

$$
\begin{equation*}
u \in C^{0, \mu}\left(Q \backslash Q_{0}, d\right), \quad \forall \mu<2-\frac{1-\varepsilon}{2}(m+2) \tag{8.21}
\end{equation*}
$$

The case $n>2$.
Our proof is quite analogous to that of the case $n>2$ in section 7 .
System (8.1) can be written as follows (see (1.7))

$$
\begin{equation*}
-\sum_{i j} D_{i}\left(A_{i j}(X, u, D u) D_{j} u\right)+\frac{\partial u}{\partial t}=-\sum_{i} D_{i} B^{i}(X, u)+B^{0}(X, u, D u) \tag{8.22}
\end{equation*}
$$

Let us suppose that the derivatives $\partial a^{i} / \partial p_{k}^{j}$, and so the matrices $A_{i j}(X, u, p)$, are uniformly continuous in $\bar{\Lambda}$. Since they are also bounded (see (1.5)) it follows that there exists a non-decreasing, bounded, continuous and concave function $\omega(\sigma)$, defined for $\sigma \geqslant 0$ with $\omega(\sigma)=0$, such that $\forall(X, u, p),(Y, v, \bar{p}) \in \Lambda$

$$
\begin{equation*}
\sum_{i j}\left\|A_{i j}(X, u, p)-A_{i j}(Y, v, \bar{p})\right\|^{2} \leqslant \omega\left(d^{2}(X, Y)+\|u-v\|^{2}+\|p-\bar{p}\|^{2}\right) \tag{8.23}
\end{equation*}
$$

Fix $Q\left(X_{0}, 2 \sigma\right) \subset \subset Q$, with $\sigma \leqslant 1$, and, for the sake of simplicity, set

$$
\begin{equation*}
\bar{A}_{i j}=A_{i j}\left(X_{0}, u_{Q(\sigma)},(D u)_{Q(\sigma)}\right) \tag{8.24}
\end{equation*}
$$

Reasoning like in the case $n>2$ of section 7 , in $Q(\sigma)$ we write $u=v+w$, where $w \in L^{2}\left(t_{0}-\sigma^{2}, t_{0}, H_{0}^{1}(B(\sigma))\right)$ is the solution of C.D. problem (7.38), while $v \in L^{2}\left(t_{0}-\sigma^{2}\right.$, $\left.t_{0}, H^{1}(B(\sigma))\right)$ is a solution of system (7.39).

Vectors $v$ and $w$ must fulfil respectively inequalities (7.40) and (7.41), which enable us to conclude that, $\forall \lambda \in(0,1)$ and $\forall \varepsilon \in(0, \alpha n)$

$$
\begin{align*}
& \tilde{\Phi}\left(u, X_{0}, \lambda \sigma\right) \leqslant c \Phi\left(u, X_{0}, \sigma\right)\left\{\lambda^{n+2-\varepsilon}+o(\sigma)\right\}+  \tag{8.25}\\
& \quad+c(v, M) \int_{Q(\sigma)} \sum_{i j}\left\|A_{i j}(X, u, D u)-\bar{A}_{i j}\right\|^{2} \cdot\|D u\|^{2} d X
\end{align*}
$$

where $o(\sigma)$ goes to zero in respect of $\sigma$.
On the other hand, taking into account (8.23), lemma 7.I, the boundedness and concavity of $\omega$, by reasoning as in (8.14), we obtain that

$$
\begin{align*}
& \int_{Q(\sigma)} \sum_{i j}\left\|A_{i j}(X, u, D u)-\bar{A}_{i j}\right\|^{2} \cdot\|D u\|^{2} d X \leqslant  \tag{8.26}\\
& \quad \leqslant O(u) \Phi\left(u, X_{0}, 2 \sigma\right)\left[\omega\left(c \sigma^{-n} \Phi\left(u, X_{0}, \sigma\right)+\int_{Q(\sigma)}\left\|D u-(D u)_{Q(\sigma)}\right\|^{2} d X\right)\right]^{1-2 / a}
\end{align*}
$$

From (8.25), (8.26) we get that $\forall \lambda \in(0,1)$ and $\forall \varepsilon \in(0, \alpha n)$

$$
\begin{equation*}
\tilde{\Phi}\left(u, X_{0}, \lambda \sigma\right) \leqslant c \Phi\left(u, X_{0}, 2 \sigma\right)\left\{\lambda^{n+2-\delta}+o(\sigma)+[\omega(\ldots)]^{1-2 / q}\right\} \tag{8.27}
\end{equation*}
$$

This inequality is trivially true for $1 \leqslant \lambda<2$, moreover to the left-hand side we may add the integral

$$
\int_{Q(\lambda, \sigma)} 1+\|u\|^{\circ} d X
$$

for the motivations we pleaded in the proof of theorem 7.I.
We conclude with the following theorem
Theorem 8.III. - If $u$ is a solution of system (8.1), under the hypotheses (1.5), (1.10), (8.2), (8.3), (8.4) and if the derivatives $\partial a^{i} / \partial p_{k}^{j}$ are uniformly continuous in $\bar{\Lambda}$, then $\forall Q\left(X_{0}, \sigma\right) \subset \subset Q$, with $\sigma \leqslant 2, \forall \lambda \in(0,1)$ and $\forall \varepsilon \in(0, \alpha n)$
(8.28) $\quad \Phi\left(u, X_{0}, \lambda \sigma\right) \leqslant$

$$
\leqslant A \Phi\left(u, X_{0}, \sigma\right)\left\{\lambda^{n+2-\varepsilon}+o(\sigma)+\left[\omega\left(c \sigma^{-n} \Phi\left(u, X_{0}, \sigma\right)+\oint_{Q(\sigma)}\left\|D u-(D u)_{Q(\sigma)}\right\|^{2} d X\right)\right]^{1-2 / q}\right\}
$$

where $o(\sigma) \rightarrow 0$ when $\sigma \rightarrow 0$.
From the previous theorem, the partial Hölder continuity in $Q$, of the vector $u$, follows.

Set

$$
\begin{align*}
& Q_{1}=\left\{X \in Q: \lim _{\sigma \rightarrow 0} f\left\|D u-(D u)_{Q(\sigma)}\right\|^{2} d Y>0\right\}  \tag{8.29}\\
& Q_{2}=\left\{X \in Q: \lim _{\sigma \rightarrow 0}^{\prime} \sigma^{-n} \Phi(u, X, \sigma)>0\right\} \tag{8.30}
\end{align*}
$$

It turns out that

$$
\begin{equation*}
\operatorname{meas} Q_{1}=0 \tag{8.31}
\end{equation*}
$$

and (see [9], theorem 2)

$$
\begin{equation*}
H_{n}\left(Q_{2}\right)=0 \tag{8.32}
\end{equation*}
$$

Reasoning exactly as in theorem 5.I of [2] we prove that
Theorem 8.IV. - If u is a solution of system (8.1), under the hypotheses (1.5), (1.10), (8.2), (8.3), (8.4) and, moreover, if the derivatives $\partial a^{i} / \partial p_{k}^{j}$ are uniformly con-
tinuous in $\bar{\Lambda}$, then there exists a set $Q_{0}$, closed in $Q$,

$$
\begin{equation*}
Q_{2} \subset Q_{0} \subset Q_{1} \cup Q_{2} \quad\left(\text { hence meas } Q_{0}=0\right) \tag{8.33}
\end{equation*}
$$

such that

$$
\begin{equation*}
u \in O^{0, \mu}\left(Q \backslash Q_{0}, d\right), \quad \forall \mu<1 \tag{8.34}
\end{equation*}
$$

## REFERENCES

[Q] S. Campanato, Sistemi ellitici in forma divergenza. Regolarità allinterno, «Quaderni» Ann. Scuola Norm. Sup. Pisa, 1980.
[1] S. Campanato, Hölder continuity of the solutions of some nonlinear elliptic systems, Advances in Math., 42 (1983).
[2] S. Campanato, Hölder continuity and partial Hölder continuity results for $H^{1, q}$-solutions of non-linear elliptic systems with controlled growth, to appear in Rend. di Milano.
[3] S. Campanato, $L^{p}$-regularity for weak solutions of parabolio systems, Ann. Scuola Norm. Sup. Pisa, 7 (1980).
[4] S. Campanato, Partial Hölder continuity of solutions of quasi-linear parabolic systems of second order with linear growth, Rend. Sem. Mat. Univ. Padova, 64 (1981).
[5] S. Campanato, $L^{p}$-regularity and partial Hölder continuity for solutions of second order parabolic systems with strictly controlled growth, Ann. Mat. Pura Appl., 182 (1980).
[6] S. Campanato, Equazioni paraboliche del secondo ordine e spazi $\mathbb{C}^{2, \theta}(\Omega, \delta)$, Ann. Mat. Pura Appl., 73 (1966).
[7] P. Cannarsa, Second order non variational parabolic systems, Boll. Un. Mat. Ital., Analisi Funz. e Appl., 82, C.N. 1 (1981).
[8] G. Da Prato, Spazi $\mathcal{L}^{(p, \theta)}(\Omega, \delta)$ e loro proprietà, Ann. Mat. Pura Appl., 69 (1965).
[9] M. Giaquinta - E. Giusti, Partial regularity for the solutions to non-linear parabolio systems, Ann. Mat. Pura Appl., 97 (1973).
[10] 0. A. Ladyzensifaja - V. A. Solonnikov - N. N. Ural'ceva, Linear and quasilinear equations of parabolie type, Amer. Mathem. Soc. Translations of Mathem. Monographs, 1968.
[11] J. L. Lions, Equations differentielles operationnelles, Springer, 1961.
[12] J. L. Lions - E. Magenes, Problèmes aux limites non homogènes et applications, Dunod, 1968.
[13] M. Marino - A. Maugeri, $L^{p}$ theory and partial Hölder continuity for quasilinear parabolic systems of higher order with strietly controlled growth, to appear.
[14] A. Maugeri, Partial Hölder continuity for the derivatives of order ( $m-1$ ) of solutions to $2 m$ order quasilinear parabolic systems with linear growth, to appear.


[^0]:    ${ }^{(1)}$ In the elliptic case, quoted in the text, we have supposed a $q$-nonlinearity, with $q>1$, on the contrary here we confine ourselves to consider the case $q=2$.

