

Corrections · Berichtigungen

Rheol. Acta 17, 460 (1978)
 © 1978 Dr. Dietrich Steinkopff Verlag, Darmstadt
 ISSN 0035-4511 / ASTM-Coden: RHEAAK

School of Mathematical Sciences, The Flinders University of South Australia, Bedford Park (Australia)

Additions and Corrections to Algorithms for motions with constant stretch history-II.

Rheol. Acta 15, 577–578 (1976)

R. R. Huilgol

(Received March 10, 1978)

In a series of papers (1, 2, 3) the author has discussed motions with constant stretch history of various types. As is well known, in these flows, the strain history has the form

$$C_i(t-s) = e^{-sL_1(t)^T} e^{-sL_1(t)}, \quad [1]$$

where L_1^T is the transpose of L_1 . Now, suppose that L_1 commutes with L_1^T , i. e.,

$$L_1 L_1^T = L_1^T L_1. \quad [2]$$

Then

$$C_i(t-s) = e^{-sA_1(t)}, \quad [3]$$

where

$$A_1 = L_1 + L_1^T \quad [4]$$

is the first Rivlin-Ericksen tensor (4). Therefore, the condition [2] is sufficient that a given motion with constant stretch history be a simple extensional flow (5).

Now, let a velocity field v be such that its gradient L obeys $\dot{L} = 0$. Then, this motion has constant stretch history (2, 3). If, in addition, L obeys [2], i. e., $LL^T = L^T L$, then v is a simple extensional flow from what we have just seen.

In the literature, the example of a simple extensional flow is usually that due to Coleman and Noll (5):

$$\dot{x}_i = a_i x_i, \quad i = 1, 2, 3; \quad \text{no sum}; \quad [5]$$

$$a_1 + a_2 + a_3 = 0. \quad [6]$$

Whether [6] is satisfied or not, the velocity gradient of [5] is symmetric. We now show that

$$v = Qx, \quad Q Q^T = 1, \quad \dot{Q} = 0, \quad [7]$$

is a simple extensional flow. The proof is trivial because the velocity gradient Q obeys $\dot{Q} = 0$ and $Q Q^T = Q^T Q$, i. e., Q commutes with Q^T . It is clear that Q is an

orthogonal tensor and hence $\text{tr } Q \neq 0$, i. e., the velocity field in [7] is not isochoric. For an isochoric, unsymmetric velocity gradient example, see (1).

This note provides the author with an opportunity to point out that the correct solution to the differential equation

$$\dot{Q} Q^T = Z, \quad Z = -Z^T, \quad Q(0) = 1, \quad [8]$$

is given by (6)

$$Q(t) = 1 + \int_0^t Z(\tau) Q(\tau) d\tau. \quad [9]$$

In eqs. [8] of (1), [4.14] and [6.10] of (2) and [12] of (3), it was incorrectly stated that

$$Q(t) = \exp\left(\int_0^t Z(\tau) d\tau\right).$$

References

- 1) Huilgol, R. R., Rheol. Acta 14, 48–50 (1975).
- 2) Huilgol, R. R., Rheol. Acta 15, 120–129 (1976).
- 3) Huilgol, R. R., Rheol. Acta 15, 577–578 (1976).
- 4) Rivlin, R. S., J. L. Ericksen, J. Rational Mech. Anal. 4, 323–425 (1955).
- 5) Coleman, B. D., W. Noll, Phys. Fluids 5, 840–842 (1962).
- 6) Hochstadt, H., Differential Equations, pp. 76–79, Dover (New York 1975).

Author's address:

Dr. R. R. Huilgol
 School of Mathematical Sciences
 The Flinders University of South Australia
 Bedford Park, S. A. 5042 (Australia)