

## ERRATUM

Hiroshi Kinoshita: 1977, 'Theory of the Rotation of the Rigid Earth', *Celest. Mech.* 15, 227–326.

- p. 281, line 10 from the bottom: replace  $-\frac{1}{16}e\tilde{J}^4$  by  $-\frac{1}{16}e\tilde{J}^2$ ;
- p. 292, title of Table Ia: insert 3 before  $\sin^2 \beta$ ;
- p. 293, coefficient of argument (1, 0, 2, 0, 1): for -4956 read -84956;
- p. 293, coefficient of argument (1, 0, 0, 2, 1): for 1524 read -1524;
- p. 298, the last equations of (6.2): replace  $1/\sin I$  by  $1/\sin J$ ;
- p. 300, Equation (6.14): insert minus sign before  $k$ ;
- p. 300, Equation (6.15): insert minus sign before  $k$ ;
- p. 301, Equation (6.24): replace  $\Delta_s h_s$  by  $\Delta_s h_f$ ;
- p. 301, Equation (6.25): replace  $\Delta_s I_s$  by  $\Delta_s I_f$ ;
- p. 302, Equation (6.27): insert  $k$  before  $\sum_v$ ;
- p. 307, line 6: insert minus sign before  $\frac{3}{2} \frac{\kappa^2 M_{\zeta}}{a_{\zeta}^3} \dots$ ;
- p. 307, Equation (7.4): insert minus sign before  $\left( \frac{3}{2} \frac{\kappa^2 M_{\zeta}}{a_{\zeta}^3} \dots \right)^2$ ;
- p. 307, Equation (7.5): insert minus sign before  $\frac{3}{2} k_{\zeta}$ ;
- p. 307, Equation (7.5): delete minus sign before 0".026;
- p. 308, Equation (8.3): replace plus sign before  $M_3$  by minus sign;
- p. 324, the last line: replace  $F+D$  by  $F+\Omega$ .