## Erratum: Measurements of the Dynamic Input Impedance of a DC Squid\*

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(Received November 21, 1985)

The curves in Fig. 3 are labeled with incorrect values of  $I/I_0$ . Figure 3 should be replaced by the accompanying figure.

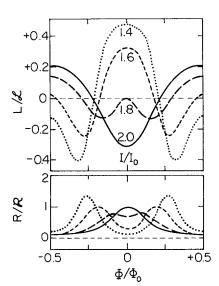


Fig. 3. Dynamic inductance  $L/\mathcal{L}$  and dynamic resistance  $R/\mathcal{R}$  obtained from the analog simulator for four different values of I, as a function of  $\Phi$ . The SQUID parameters were  $\beta = 1.0$ ,  $\beta_c \approx 0.2$ , and  $\Gamma \approx 0.06$ .

<sup>\*</sup>This paper appeared in J. Low Temp. Phys. 61, 237 (1985).