# On the Hydrodynamic Limit of a Ginzburg-Landau Lattice Model 

# The Law of Large Numbers in Arbitrary Dimensions 

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#### Abstract

Summary. A lattice system of interacting diffusion processes is investigated. The evolution is attractive and time reversible, the spin satisfies a conservation law. It is shown that the rescaled spin field converges in probability to the corresponding solution to a nonlinear diffusion equation.


## 1. Introduction

We are going to investigate the hydrodnamic behaviour of interacting diffusion processes satisfying a conservation law. The configuration space will be defined as a set, $\Omega$ of real sequences labelled by the points of the $d$-dimensional cubic lattice, $\mathbb{Z}^{d}$. If $\omega \in \Omega$ and $k \in \mathbb{Z}^{d}$ then $\omega_{k} \in \mathbb{R}$ denotes the spin at site $k$. The energy of the spin at site $k$ is given by

$$
\begin{equation*}
H_{k}(\omega)=V\left(\omega_{k}\right)+\frac{\alpha}{2} \sum_{|j-k|=1}\left(\omega_{j}-\omega_{k}\right)^{2}, \tag{1.1}
\end{equation*}
$$

where $\alpha$ is a nonnegative constant, while $V: \mathbb{R} \rightarrow \mathbb{R}$ is a convex function having three continuous derivatives such that $\left|1-V^{\prime \prime}(x)\right|<c$ for all $x \in \mathbb{R}$ with some $c<1$, and $V^{\prime \prime \prime}$ is bounded, too. The evolution is governed by the gradient of H,

$$
\begin{equation*}
\partial_{k} H=\partial_{k} H(\omega)=V^{\prime}\left(\omega_{k}\right)+\alpha \sum_{|j-k|=1}\left(\omega_{k}-\omega_{j}\right), \tag{1.2}
\end{equation*}
$$

in the following way. Along each oriented bond $k \rightarrow j$ there is a random current, $J_{k j}$ of the spin, and the temporal evolution is determined by the associated conservation law. More exactly, for each positively oriented bond we are given a standard Wiener process, $w_{k j}$, they are independent, and $w_{k j}+w_{j k}=0$ by convention. The currents admit a stochastic differential,

$$
\begin{equation*}
d J_{k j}=\frac{1}{2}\left[\partial_{k} H(\omega)-\partial_{j} H(\omega)\right] d t+d w_{k j}, \tag{1.3}
\end{equation*}
$$

[^0]and the evolution is defined by a system of stochastic differential equations,
\[

$$
\begin{equation*}
d \omega_{k}+\sum_{|j-k|=1} d J_{k j}=0, \quad k \in \mathbb{Z}^{d}, \quad \omega_{k}(0)=\sigma_{k} \tag{1.4}
\end{equation*}
$$

\]

We are interested in the asymptotic behaviour of the rescaled spin field

$$
\begin{equation*}
S^{\Sigma}\left(t, \varphi, \sigma^{\varepsilon}\right)=\varepsilon^{d} \sum_{k \in \mathbb{Z}^{d}} \varphi(\varepsilon k) \omega_{k}\left(t / \varepsilon^{2}\right) \tag{1.5}
\end{equation*}
$$

as $\varepsilon \rightarrow 0$ and the initial configuration, $\sigma^{\varepsilon}$ approaches some smooth profile, $\rho_{0}$ : $\mathbb{R}^{d} \rightarrow \mathbb{R}$. We show that $S^{\varepsilon}$ converges in probability to a nontrivial deterministic limit, $\int \varphi(x) \rho(t, x) d x$, and $\rho$, the limiting spin density, satisfies

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}=\operatorname{div}[D(\rho) \operatorname{grad} \rho(t, x)], \quad \rho(0, x)=\rho_{0}(x) \tag{1.6}
\end{equation*}
$$

where $D: \mathbb{R} \rightarrow \mathbb{R}$ is strictly positive and bounded.
The first attempt to derive the macroscopic equations of hydrodynamics from statistical mechanics is due to Morrey [18], a more general formulation of the problem goes back to Dobrushin [8], see [3, 4, 9] and the early papers $[17,22,23]$ on the subject. A survey of some mathematical and physical ideas and results is presented in [6]. The evolution (1.3)-(1.4) is a lattice version of the time dependent Ginzburg-Landau equation, sometimes it is called a CahnHilliard theory, see Spohn [26] for some further references on the physics literature. This paper is a continuation of the project outlined in [12, 13]. The proof of [14] is simplified and extended to arbitrary dimensions, we prove a law of large numbers for continuous functionals of the conserved field. The deterministic (zero temperature) case was discussed in [11]. Some related results on the one-dimensional, general zero range model were announced by Rost [24]. An extension of the law of large numbers to the one-dimensional continuum Ginzburg-Landau equation was obtained by Funaki [15]. Equilibrium fluctuations (the related central limit problem) were described by Spohn [26]. In a recent paper [16] Guo, Papanicolau and Varadhan [16] propose a new approach to the law of large numbers. This method is restricted to finite volumes, but it is fairly general in other respects. For example, the convexity of the self-potential $V$ implying attractivity of the evolution is not needed. Donsker and Varadhan [10] treat the associated large deviation problem by similar methods.

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## 2. Main Result

It is very convenient to embed our configuration space into a space of functions on $\mathbb{R}^{d}$, then the configurations will be interpreted as step functions. The topology
of this space will be specified by a family of weighted $\mathbb{L}^{2}$-norms, $|\cdot|_{r}, r \in \mathbb{R}$. The weight functions, $\theta_{r}: \mathbb{R}^{d} \rightarrow(0,1]$ are defined as follows. Let $\theta:[0, \infty) \rightarrow(0,1]$ be a nonincreasing and twice continuously differentiable function such that $\theta(u)=\frac{1}{2} e^{2-u}$ if $u \geqq 2, \theta(u)=1$ if $u \leqq 1$, while $\theta(u) \geqq e^{-u}$ and $0 \leqq-\theta^{\prime}(u) \leqq \theta(u)$ $\leqq \frac{1}{2} e^{2-u}$ for all $u \geqq 0$. Now $\theta_{r}(x)=[\theta(|x|)]^{r}$ for $x \in \mathbb{R}^{d}$ and $r \in \mathbb{R}$, and

$$
\begin{equation*}
|\sigma|_{r}^{2}=\int \theta_{r}(x)|\sigma(x)|^{2} d x \tag{2.1}
\end{equation*}
$$

whenever $\sigma: \mathbb{R}^{d} \rightarrow \mathbb{R}$ is measurable. The associated scalar product will be denoted as $\langle\cdot, \cdot\rangle_{r}$, the same notation will be used for vector valued functions. Introduce now $\mathbb{L}_{r}^{2}\left(\mathbb{R}^{d}\right)$ as the real Hilbert space of locally integrable $\sigma: \mathbb{R}^{d} \rightarrow \mathbb{R}$ with norm $|\cdot|_{r}$. Since $\theta_{r} \geqq \theta_{s}$ if $r \leqq s$, we have $\mathbb{L}_{s}^{2} \subset \mathbb{L}_{r}^{2}$ in this case. Since $\theta_{-r}=1 / \theta_{r}$, the spaces $\mathbb{L}_{r}^{2}$ and $\mathbb{L}_{-r}^{2}$ are the duals of each other with respect to the scalar product $\langle\cdot, \cdot\rangle_{0}$ of $\mathbb{L}_{0}^{2}\left(\mathbb{R}^{d}\right)=\mathbb{L}^{2}\left(\mathbb{R}^{d}\right)$. Define now $\mathbb{L}_{e}^{2}$ as the locally convex space with seminorms $|\cdot|_{r}, r>0$. This simply means that

$$
\begin{equation*}
\mathbb{L}_{e}^{2}=\bigcap_{r>0} \mathbb{L}_{r}^{2}\left(\mathbb{R}^{d}\right) \tag{2.2}
\end{equation*}
$$

and $\sigma_{n} \rightarrow \sigma$ in the (strong) topology of $\mathbb{L}_{e}^{2}$ iff $\left|\sigma_{n}-\sigma\right|_{r} \rightarrow 0$ for each $r>0$. The dual space of $\mathbb{L}_{e}^{2}$ is just

$$
\begin{equation*}
\mathbb{L}_{-e}^{2}=\bigcup_{r>0} \mathbb{L}_{-r}^{2}\left(\mathbb{R}^{d}\right), \tag{2.3}
\end{equation*}
$$

the elements of $\mathbb{L}_{-e}^{2}$ are represented as

$$
\begin{equation*}
\varphi=\varphi(\sigma)=\int \varphi(x) \sigma(x) d x, \quad \sigma \in \mathbb{L}_{e}^{2} \tag{2.4}
\end{equation*}
$$

The weak topology of $\mathbb{L}_{e}^{2}$ is given by a fundamental system of the neighborhoods of $0 \in \mathbb{L}_{e}^{2}$, namely

$$
\begin{equation*}
U_{\gamma}\left(\varphi_{1}, \varphi_{2}, \ldots, \varphi_{n}\right)=\left[\sigma \in \mathbb{L}_{e}^{2}:\left|\varphi_{k}(\sigma)\right|<\gamma, k=1,2, \ldots, n\right], \tag{2.5}
\end{equation*}
$$

where $\gamma>0$ and $\varphi_{k} \in \mathbb{L}_{-e}^{2}$. A subset $B$ of $\mathbb{L}_{e}^{2}$ is called a ball if

$$
\begin{equation*}
B=\left[\sigma \in \mathbb{L}_{e}^{2}:|\sigma|_{r} \leqq b_{r} \text { for all } r>0\right] \tag{2.6}
\end{equation*}
$$

with some $b_{r}<\infty$. It is easy to check that $\mathbb{L}_{e}^{2}$ is a reflexive space, and its balls are weakly compact. If $\Sigma \subset \mathbb{L}_{e}^{2}$ then $\mathbb{C}_{s}(\Sigma)$ and $\mathbb{C}_{w}(\Sigma)$ denote the spaces of strongly (weakly) continuous and bounded maps of $\Sigma$ into $\mathbb{R}$. The spaces of weakly differentiable $\lambda \in \mathbb{L}_{e}^{2}$ and $\varphi \in \mathbb{L}_{-e}^{2}$ with partial derivatives belonging to $\mathbb{L}_{e}^{2}$ and $\mathbb{L}_{-e}^{2}$, respectively, will be denoted by $\mathbb{H}_{e}^{1}$ and $\mathbb{H}_{-e}^{1}$.

The embedding of our process into $\mathbb{L}_{e}^{2}$ is based on the following correspondence between sequences and step functions. Let $C_{\varepsilon}(\varepsilon k)$ denote the Dirichlet cell of $\varepsilon \mathbb{Z}^{d}$ centered at $\varepsilon k, \varepsilon>0, k \in \mathbb{Z}^{d}$. More exactly, if $x_{i}$ and $k_{i}$ denote the coordinates of $x$ and $k$, then

$$
\begin{equation*}
C_{\varepsilon}(\varepsilon k)=\left[x \in \mathbb{R}^{d}:-\varepsilon / 2 \leqq x_{i}-\varepsilon k_{i}<\varepsilon / 2, i=1,2, \ldots, d\right] . \tag{2.7}
\end{equation*}
$$

Moreover, let $C_{\varepsilon}(x)=C_{\varepsilon}(\varepsilon k)$ if $x \in C_{\varepsilon}(\varepsilon k)$, and define $\Omega_{\varepsilon}$ as the space of $\omega \in \mathbb{L}_{e}^{2}$ such that $\omega(x)=\omega(y)$ whenever $x \in C_{\varepsilon}(y)$. For each $\varepsilon>0$ and $\omega \in \mathbb{L}_{e}^{2}$ there is a step function, $\omega^{\varepsilon}=I_{\varepsilon} \omega$ defined by

$$
\begin{equation*}
I_{\varepsilon} \omega(x)=\varepsilon^{-d} \int_{C_{s}(x)} \omega(y) d y \tag{2.8}
\end{equation*}
$$

that is, $\Omega_{\varepsilon}=I_{\varepsilon} \mathbb{L}_{e^{2}}^{2}$. On the other hand, if $\omega=\left(\omega_{k}\right)_{k \in \mathbb{Z}^{d}}$ is a sequence indexed by $\mathbb{Z}^{d}$, then $\omega^{\varepsilon}(x)=\omega_{k}$ iff $x \in C_{\varepsilon}(\varepsilon k)$ defines a step function $\omega^{\varepsilon} \in \Omega_{\varepsilon}$ for each $\varepsilon>0$, provided that

$$
\begin{equation*}
|\omega|_{r}=\left[\sum_{k \in \mathbb{Z}^{d}} I_{1} \theta_{r}(k) \omega_{k}^{2}\right]^{1 / 2}<\infty \tag{2.9}
\end{equation*}
$$

for each $r>0$. The space of such sequences will be denoted by $\Omega$, and the evolution law (1.3) will be considered in this configuration space. Since $\Omega$ and $\Omega_{1}$ are essentially identical, we are not going to make a sharp distinction between them.

The existence problem for (1.3) is almost trivial. Let $b_{k}=b_{k}(\omega)$ denote the drift of (1.3), and consider $b=\left(b_{k}(\omega)\right)_{k \in \mathbb{Z}^{d}}$ as a map on $\Omega$. It is easy to check that for each $r \in \mathbb{R}$ we have

$$
\begin{gather*}
|b(\omega)|_{r} \leqq L_{r}|\omega|_{r}  \tag{2.10}\\
|b(\omega)-b(\bar{\omega})|_{r} \leqq L_{r}|\omega-\bar{\omega}|_{r} \tag{2.11}
\end{gather*}
$$

for all $\omega, \bar{\omega} \in \Omega$ with some $L_{r}<\infty$. Since the martingale part of (1.3) does not depend on the configuration, the easiest iteration procedure can be used to construct continuous solutions in $\Omega$, and the very same methods yield smooth dependence on initial data. Although no stochastic calculus is needed at this point, for convenience we refer to the abstract results of Chapter VII in [5]. Let $\omega(t, \sigma)$ denote the solution to (1.3) with initial condition $\omega(0, \sigma)=\sigma \in \Omega$. The solution is a continuous process in $\Omega$ for each $\sigma \in \Omega$, and we have some constants, $K_{r}$ such that for $r>0$

$$
\begin{equation*}
\mathbb{E}\left[|\omega(t, \sigma)|_{r}^{2}\right] \leqq\left(|\sigma|_{r}^{2}+K_{r}\right) \exp \left(K_{r} t\right), \tag{2.12}
\end{equation*}
$$

see Theorem VII.2.1 in [5]. Moreover, the solution is a differentiable function of the initial data, and its derivatives satisfy the linearized equation associated with (1.3). For measurable and bounded $f: \Omega \rightarrow \mathbb{R}$ we define $\mathbb{P}^{t} f=\mathbb{P}^{t} f(\sigma)$ $=\mathbb{E}[f(\omega(t, \sigma))]$. If $f$ is a bounded cylinder function with continuous and bounded first and second derivatives, then $\mathbb{P}^{t} f$ is twice differentiable, and

$$
\begin{equation*}
\mathbb{P}^{\boldsymbol{t}} f(\sigma)=f(\sigma)+\int_{0}^{t} \mathbb{G} \mathbb{P}^{s} f(\sigma) d s \tag{2.13}
\end{equation*}
$$

where $\mathbb{G}$ denotes the formal generator of $\mathbb{P}^{t}$,

$$
\begin{equation*}
\mathbb{G} f=\frac{1}{2} \sum_{k|j-k|=1} \sum^{H_{j}} \partial_{j}\left[e^{-H_{j}}\left(\partial_{k} f-\partial_{j} f\right)\right] \tag{2.14}
\end{equation*}
$$

and $\partial_{k}$ denotes differentiation with respect to $\sigma_{k}$; see Theorems VII.3.3 and VII.4.1 in [5].

Since (1.3) is a conservation law, we expect that $\mathbb{P}^{t}$ has a whole family of stationary measures. Let $\mu_{\lambda}$ denote the Gibbs state on $\Omega$ with energy $H_{\lambda}=H$ $-\sum \lambda_{k} \sigma_{k}$, where $\lambda \in \Omega$ is arbitrary. This means that the conditional densities of $\mu_{\lambda}$ are specified as

$$
\begin{equation*}
\mu_{2}\left(d \sigma_{k} \mid \sigma_{j}, j \neq k\right)=Z_{k}^{-1} \exp \left[-H_{k}(\sigma)+\lambda_{k} \sigma_{k}\right] d \sigma_{k} \tag{2.15}
\end{equation*}
$$

where $Z_{k}$ is a normalizing factor depending on $\lambda_{k}$ and $\sigma_{j}$ with $|j-k|=1$. It is easy to verify that if $\lambda \in \Omega$ then $\mu_{\lambda}$ is unique, and $\mu_{\lambda}(\Omega)=1$, see [14] with some further references. In particular, if $\lambda_{k}=v$ for all $k \in \mathbb{Z}^{d}$, then a distinguishing notation, $\mu_{v}^{0}=\mu_{\lambda}$ will be used. Observe that (2.14) implies

$$
\begin{align*}
& \int f_{1}(\sigma) \mathbb{G} f_{2}(\sigma) \mu_{v}^{0}(d \sigma) \\
& \quad-\frac{1}{4} \sum_{k} \sum_{|j-k|=1} \int\left(\partial_{j} f_{1}-\partial_{k} f_{1}\right)\left(\partial_{j} f_{2}-\partial_{k} f_{2}\right) d \mu_{v}^{0} \tag{2.16}
\end{align*}
$$

for smooth cylinder functions. This Dirichlet form contains the main information on $\mathbb{P}^{t}$. For example, we obtain $\int \mathbb{G} f d \mu_{\lambda}=0$ for all smooth cylinder functions, whenever $\lambda$ is a harmonic sequence, i.e.

$$
\begin{equation*}
\lambda_{k}=\frac{1}{2 d} \sum_{|j-k|=1} \lambda_{j} \quad \text { for all } k \in \mathbb{Z}^{d} \tag{2.17}
\end{equation*}
$$

It is not difficult to show that every Gibbs state of this type is in fact a stationary measure of $\mathbb{P}^{t}$. The converse statement is more difficult to prove, the free energy method seems to be applicable. A direct calculation yields $\lambda_{k}=\int \partial_{k} H(\sigma) \mu_{\lambda}(d \sigma)$ suggesting the following expression for the diffusion coefficient $D$ of the limiting Eq. (1.6), see $[6,13]$. Indeed, if $\lambda=v^{\prime}$ is a constant, then the mean spin equals the derivative, $F^{\prime}$, of the equilibrium free energy, $F$ as a function of the chemical potential $v$. For brevity we only define $F^{\prime}: \mathbb{R} \rightarrow \mathbb{R}$ by

$$
\begin{equation*}
F^{\prime}(v)=\int \sigma_{k} \mu_{v}^{0}(d \sigma) \tag{2.18}
\end{equation*}
$$

Since $\mu_{v}^{0}$ is translation invariant, $F^{\prime}$ does not depend on $k$. We shall show that $F^{\prime}$ is strictly increasing, thus

$$
\begin{equation*}
D(u)=1 / 2 F^{\prime \prime}(v) \quad \text { if } u=F^{\prime}(v) \tag{2.19}
\end{equation*}
$$

defines $D$ for all $u \in \mathbb{R}$. Moreover, $D$ is continuous, and $0<c \leqq D(u) \leqq c_{2}<\infty$ with some constants, consequently (1.6) is uniquely solved in the following sense, see Sect. 7. For every $\sigma \in \mathbb{H}_{e}^{1}$ there exists a continuous trajectory, $\rho_{t} \in \mathbb{L}_{e}^{2}, t \geqq 0$ such that $\rho_{0}=\sigma$ and for each twice continuously differentiable $\varphi: \mathbb{R}^{d} \rightarrow \mathbb{R}$ with compact support we have

$$
\begin{equation*}
\int \varphi(x) \rho_{t}(x) d x=\int \varphi(x) \sigma(x) d x+\int_{0}^{t} \int E\left(\rho_{s}(x)\right) \Delta \varphi(x) d x d s \tag{2.20}
\end{equation*}
$$

where $E$ denotes the inverse function of $F^{\prime}$, that is, $E^{\prime}=D$.
The problem of hydrodynamic limit can be formulated in terms of a family of Markov processes, $\omega_{t}^{\varepsilon}, t \geqq 0, \varepsilon>0 ; \omega_{t}^{\varepsilon} \in \Omega_{\varepsilon}$ is defined by $\omega_{t}^{\varepsilon}(x)=\omega_{k}\left(t / \varepsilon^{2}\right)$ if $x \in C_{\varepsilon}(\varepsilon k)$, where $\omega=\left(\omega_{k}(t)\right)_{k \in \mathbb{Z}^{d}}$ is a strong solution to (1.4). The initial value of $\omega^{\varepsilon}$ will usually be denoted by $\sigma=\omega_{0}^{2}$, the rescaled spin field becomes $\varphi\left(\omega_{t}^{\varepsilon}\right)$, and the associated Markov semigroup is defined as

$$
\begin{equation*}
\mathbb{P}_{\varepsilon}^{t} g(\sigma)=\mathbb{E}\left[g\left(\omega_{t}^{\varepsilon}\right) \mid \omega_{0}^{\varepsilon}=\sigma\right], \quad \sigma \in \Omega_{\varepsilon}, \quad g \in \mathbb{C}_{s}\left(\Omega_{\varepsilon}\right) \tag{2.21}
\end{equation*}
$$

In the traditional formulation of the problem the initial configuration is random, it is distributed by a family of local equilibrium states, $\mu_{\lambda, \mathrm{s}}$, see [6]. The initial randomness is certainly necessary in the case of conservative (Hamiltonian) systems, this assumption is relevant also for the Guo-Papanicolau-Varadhan approach [16]. Due to the convexity of $V$, our model has very good ergodic properties: it seems that local equilibrium is established after time $\varepsilon^{-2}$, even if the initial distribution is deterministic, but we are not in a position to give an exact meaning to this conjecture. We can control the relaxation of our system to a local equilibrium only at a level of the law of large numbers. The following presentation of the main result is a little bit stronger than that proposed by Funaki [15].
Theorem 1. Suppose that $\omega_{0}^{\varepsilon}$ converges weakly in $\mathbb{L}_{e}^{2}$ to some $\rho_{0} \in \mathbb{H}_{e}^{1}$ as $\varepsilon \rightarrow 0$, then $\varphi\left(\omega_{t}^{\varepsilon}\right)$ converges in probability to $\varphi\left(\rho_{t}\right)$ for each $t>0$ and $\varphi \in \mathbb{H}_{-e}^{1}$, where $\rho_{\mathrm{t}}$ is specified as the weak solution to (1.6) with initial configuration $\rho_{0}$.

One of the most crucial features of our dynamics is the weakly continuous dependence of solutions on initial data, this property will be used to reduce Theorem 1 to the case of random initial configurations, and then to solve the problem. The simplest choice of the local equilibrium distributions is the following one. For $\varepsilon>0$ and $\lambda \in \mathbb{L}_{e}^{2}$ let $\mu_{\lambda, \varepsilon}=\mu_{\lambda_{\varepsilon}}$, where $\lambda^{\varepsilon} \in \Omega$ is defined by $\lambda_{k}^{\varepsilon}=I_{\varepsilon} \lambda(\varepsilon k)$ Remember that $\mu_{\lambda, \varepsilon}$ is originally defined on $\Omega$, but we can project it to $\Omega_{\varepsilon}$ by means of the usual correspondence $\sigma \rightarrow \sigma^{\varepsilon}$ between $\Omega$ and $\Omega_{\varepsilon}$, i.e. $\sigma^{\varepsilon}(x)=\sigma_{k}$ if $x \in C_{\varepsilon}(\varepsilon k)$. For notational convenience we assume that $\mu_{\lambda, \varepsilon}$ is defined on the Borel field of the whole space $\mathbb{L}_{e}^{2}$; of course, $\mu_{\lambda, \varepsilon}\left(\Omega_{\varepsilon}\right)=1$. Observe that $\mu_{\lambda, \varepsilon}$ satisfies a law of large numbers. We shall show that if $\varphi \in \mathbb{L}_{-e}^{2}$, then

$$
\begin{equation*}
\int \varphi(\sigma) \mu_{\lambda, \varepsilon}(d \sigma) \xrightarrow[\varepsilon \rightarrow 0]{\longrightarrow} \int \varphi(x) \rho_{0}(x) d x \tag{2.22}
\end{equation*}
$$

where $\rho_{0}(x)=F^{\prime}(\lambda(x))$, and $\varphi(\sigma)$ converges in probability to $\varphi\left(\rho_{0}\right)$ as $\varepsilon \rightarrow 0$. This statement is trivial if $\alpha=0$, because $\mu_{\lambda, \varepsilon}$ is a product measure in this particular case. If $\alpha>0$ then the convexity of $V$ implies that $\mu_{\lambda, \varepsilon}$ belongs to Dobrushin's uniqueness domain, thus it satisfies an exponential decay of correlations, see [17]. Therefore $\mu_{\lambda, \varepsilon}$ converges to the $\delta$-measure concentrated on in the sense that

$$
\begin{equation*}
\int g(\sigma) \mu_{\lambda, \varepsilon}(d \sigma) \xrightarrow[\varepsilon \rightarrow 0]{ } g\left(\rho_{0}\right) \quad \text { if } g \in \mathbb{C}_{w}\left(\mathbb{L}_{e}^{2}\right) \tag{2.23}
\end{equation*}
$$

Notice that (2.23) fails to hold for strongly continuous functions. The weak topology of $\mathbb{L}_{e}^{2}$ plays a fundamental role in the proofs, and this role is not a technical one: the law of large numbers is formulated in a natural way in terms of this weak topology. The second version of the main result maintains that (2.23) remains in force for positive times, too.
Theorem 2. If $g \in \mathbb{C}_{w}\left(\mathbb{L}_{e}^{2}\right)$ and $\lambda \in \mathbb{H}_{e}^{1}$ then

$$
\lim _{\varepsilon \rightarrow 0} \int_{\varepsilon} \mathbb{P}_{\varepsilon}^{t} g(\sigma) \mu_{\lambda, \varepsilon}(d \sigma)=g\left(\rho_{t}\right)
$$

where $\rho_{t}$ is the weak solution to (1.6) with initial condition $\rho_{0}=\rho_{0}(x)$ $=F^{\prime}(\lambda(x))$.

The ideas of the proof are outlined in the next section. Following [12] we prove Theorem 2 first for a more restricted class of functions, $\mathbb{D}_{L}\left(\mathbb{L}_{e}^{2}\right)$ to be defined in Sect. 7. The next step is the tightness of the family of time evolved measures, $\mu_{\lambda, \varepsilon} \mathbb{P}_{\varepsilon}^{t}$, whence the general case follows by the Stone-Weierstrass theorem. Finally, we derive Theorem 1 from Theorem 2 by means of the weakly continuous dependence of solutions on initial data, cf. Funaki [15].

The methods of this paper work under some more general conditions. The case of an external driving force, and a reaction term will be discussed in a forthcoming paper with Christian Maes. Systems with random, or macroscopically inhomogeneous conductivities can also be treated. The case of configuration dependent conductivities, that means correlated currents, is more difficult, but not absolutely hopeless.

## 3. On the Ideas of the Proof

The framework is fairly general, we want to expose the underlying particular structure, too. For each $\varepsilon>0$ we are given a Markov process $\mathbb{P}_{\varepsilon}^{t}$, and a family of initial distributions, $\mu_{\lambda, \varepsilon}, \lambda \in \Lambda=\mathbb{H}_{e}^{1}$. Let $\mathbb{G}_{\varepsilon}$ denote the formal generator of $\mathbb{P}_{\varepsilon}^{t}$, and consider the class $\mathbb{C}_{0}\left(\mathbb{L}_{e}^{2}\right) \subset \mathbb{C}_{w}\left(\mathbb{L}_{e}^{2}\right)$ consisting of functions of type $f(\sigma)$ $=h\left(\varphi_{1}(\sigma), \varphi_{2}(\sigma), \ldots, \varphi_{n}(\sigma)\right)$, where $h: \mathbb{R}^{n} \rightarrow \mathbb{R}$ and $\varphi_{k}: \mathbb{R}^{d} \rightarrow \mathbb{R}$ are twice continuously differentiable with compact supports. We want to have a statement of the following kind. For each $g \in \mathbb{C}_{0}\left(\mathbb{L}_{e}^{2}\right)$ and $\lambda \in \Lambda$ there exists a limit

$$
\begin{equation*}
\int \mathbb{P}_{\varepsilon}^{t} g(\sigma) \mu_{\lambda, \varepsilon}(d \sigma) \underset{\varepsilon \rightarrow 0}{ } \mathbb{P}^{t} \tilde{g}(\lambda) \tag{3.1}
\end{equation*}
$$

and the limit is specified as follows. The map $g \rightarrow \tilde{g}$ is given by

$$
\begin{equation*}
\tilde{g}(\lambda)=\lim _{\varepsilon \rightarrow 0} \int g(\sigma) \mu_{\lambda, \varepsilon}(d \sigma) \tag{3.2}
\end{equation*}
$$

while $\widetilde{\mathbb{P}}^{t}$ is a semigroup in $\mathbb{C}_{w}(\Lambda)$ specified by its formal generator

$$
\begin{equation*}
\widetilde{\mathbb{G}} \tilde{f}(\lambda)=\lim _{\varepsilon \rightarrow 0} \int \mathbb{G}_{\varepsilon} f(\sigma) \mu_{\lambda, \varepsilon}(d \sigma) \tag{3.3}
\end{equation*}
$$

Of course, this loosely formulated statement is too general, there is no theorem claiming that (3.2) and (3.3) imply (3.1). Nevertheless, we can go a little bit further. We summarize below the main steps of a proof we are going to materialize in the case of the Ginzburg-Landau model (1.3).

Introduce the resolvent, $\mathbb{R}_{z, \varepsilon}$ for $z>0, g \in \mathbb{C}_{0}\left(\mathbb{L}_{e}^{2}\right)$ and $\sigma \in \Omega_{\varepsilon}$,

$$
\begin{equation*}
\mathbb{R}_{z, \varepsilon} g(\sigma)=\int_{0}^{\infty} e^{-z t} \mathbb{P}_{\varepsilon}^{t} g(\sigma) d t \tag{3.4}
\end{equation*}
$$

From (2.13) we obtain that $f_{\varepsilon}=\mathbb{R}_{z, \varepsilon} g$ satisfies

$$
\begin{equation*}
g(\sigma)=z f_{\varepsilon}(\sigma)-\mathbb{G}_{\varepsilon} f_{\varepsilon}(\sigma), \quad \sigma \in \Omega_{\varepsilon} \tag{3.5}
\end{equation*}
$$

the resolvent equation, whence

$$
\begin{equation*}
\int g(\sigma) \mu_{\lambda, \varepsilon}(d \sigma)=z \int f_{\varepsilon}(\sigma) \mu_{\lambda, \varepsilon}(d \sigma)-\int \mathbb{G}_{\varepsilon} f_{\varepsilon}(\sigma) \mu_{\lambda, \varepsilon}(d \sigma) . \tag{3.6}
\end{equation*}
$$

Imagine now that we can use a compactness argument to pass to a limiting resolvent equation via (3.2) and (3.3) along some subsequence $\varepsilon_{n} \rightarrow 0$. This means that each term of (3.6) tends to the corresponding term of

$$
\begin{equation*}
\tilde{g}(\lambda)=z \widetilde{f}(\lambda)-\widetilde{\mathbb{C}} \tilde{f}(\lambda) \tag{3.7}
\end{equation*}
$$

for each $\lambda \in A$ and $z \geqq z_{0}$, where $z_{0}>0$ depends only on $g$. It is very relevant here that the subsequence may depend on $g$ and $z$, but it does not depend on $\lambda$. Let $\mathbb{R}_{z} \tilde{g}=\int_{0}^{\infty} e^{-z t} \tilde{\mathbb{P}}^{t} \tilde{g} d t$, then

$$
\begin{equation*}
z \mathbb{R}_{z} \tilde{g}-\mathbb{G} \mathbb{R}_{z} \tilde{g}=\tilde{g}, \tag{3.8}
\end{equation*}
$$

i.e., $\mathbb{R}_{z} g$ solves (3.7). Therefore, if $\tilde{h}=\tilde{f}-\mathbb{R}_{z} \tilde{g}$, then $\partial_{t} \widetilde{\mathbb{P}}^{t} \tilde{h}=\widetilde{\mathbb{P}}^{t} \widetilde{\mathbb{G}} \tilde{h}=z \widetilde{\mathbb{P}} \tilde{h}$, whence $\tilde{\mathbb{P}}^{t} \tilde{h}=\tilde{h} e^{z t}$. Since $\widetilde{\mathbb{P}}^{t}$ is a contraction semigroup, and $z>0$, this is possible only if $\widetilde{h}=0$, consequently

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \int_{0}^{\infty} e^{-z t} \int \mathbb{P}_{\varepsilon}^{t} g(\sigma) \mu_{\lambda, \varepsilon}(d \sigma) d t=\mathbb{R}_{z} \tilde{g}(\lambda) \tag{3.9}
\end{equation*}
$$

for all $\lambda \in \Lambda, g \in \mathbb{C}_{0}\left(\mathbb{L}_{e}^{2}\right)$ and $z \geqq z_{0}$.
Suppose now that the family $h_{\varepsilon}(t)=\int \mathbb{P}_{\varepsilon}^{t} g d \mu_{\lambda, \varepsilon}$ is equicontinuous at each $t>0$ as $\varepsilon \rightarrow 0$, at least if $\lambda$ and $g$ are fixed. Since $h_{\varepsilon}$ is uniformly bounded, by the Arzela-Ascoli criterion of compactness we can select a subsequence $\varepsilon_{n} \rightarrow 0$ in such a way that $h_{\varepsilon_{n}}$ converges uniformly on compact intervals of time to some limit, $h_{0}$. Thus, for $z>z_{0}$ we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \int_{0}^{\infty} e^{-z t} h_{\delta_{n}}(t) d t=\int_{0}^{\infty} e^{-z t} h_{0}(t) d t=\mathbb{R}_{z} \tilde{g} \tag{3.10}
\end{equation*}
$$

whence $h_{0}(t)=\widetilde{\mathbb{P}}^{t} \tilde{g}$ for all $t>0$ by the uniqueness of the Laplace transform, which implies (3.1). Now we can approximate weakly continuous functions by
smooth functions of class $\mathbb{C}_{0}\left(\mathbb{L}_{e}^{2}\right)$ via the Stone-Weierstrass theorem on the balls of $\mathbb{L}_{e}^{2}$, thus we can extend (3.1) to $g \in \mathbb{C}_{w}\left(\mathbb{L}_{e}^{2}\right)$ by means of the tightness of the time evolved measure $\mu_{\lambda, \varepsilon} \mathbb{P}_{\varepsilon}^{t}$. This follows by an a priori bound for the mean value of $\left|\omega_{t}^{z}\right|_{r}^{2}$ with some $r>0$.

The crucial step of the proof is certainly the compactness argument resulting in (3.7). Since we need the convergence of each term of (3.6) simultaneously for all $\lambda \in A$, we have to prove an Arzela-Ascoli criterion for $f_{\varepsilon}$ as a function of the initial configuration. Unfortunately, the strongly compact sets of $\mathbb{L}_{e}^{2}$ are not rich enough to carry the initial distributions, $\mu_{\lambda, \varepsilon}$, thus we have to show that some time averages, like $f_{\varepsilon}=\mathbb{R}_{z, \varepsilon} g$ are weakly equicontinuous functions of the initial data, $\sigma \in \mathbb{L}_{e}^{2}$. The very same continuity property allows us to conclude Theorem 1 from (3.1), cf. Funaki [15]. The proof of this compactness criterion reduces to a study of the linearized system of (1.3); its parabolic structure is the key of our investigations. Let us remark that (1.3) is attractive in a very strong sense, at least if $\alpha=0$. Indeed, if $\sigma_{k} \leqq \bar{\sigma}_{k}$ for all $k$, then $\omega_{k}(t, \sigma)$ $\leqq \omega_{k}(t, \bar{\sigma})$ for all $k$ and $t>0$. This strong attractivity breaks down if $\alpha>0$, thus we believe that the parabolicity of the linearized system is a useful, general condition for continuous spin systems.

Now we are in a position to enter into some further, more technical details. Taking into account (2.16), the Dirichlet form of $\mathbb{G}$ we can simplify (3.3) in a very radical way. We obtain that

$$
\begin{equation*}
\int \mathbb{G} f d \mu_{\lambda}=-\frac{1}{4} \sum_{k \in \mathbb{Z}^{a}} \sum_{|j-k|=1} \int\left(\lambda_{j}-\lambda_{k}\right)\left(\partial_{j} f-\partial_{k} f\right) d \mu_{\lambda} . \tag{3.11}
\end{equation*}
$$

This fundamental identity scales into

$$
\begin{equation*}
\int \mathbb{G}_{\varepsilon} f d \mu_{\lambda, \varepsilon}=-\frac{1}{2} \iint\left\langle\nabla_{\varepsilon} \lambda^{\varepsilon}(x), \nabla_{\varepsilon} \mathbb{D} f(x, \sigma)\right\rangle d x \mu_{\lambda, \varepsilon}(d \sigma) \tag{3.12}
\end{equation*}
$$

where $\lambda^{\varepsilon}=I_{\varepsilon} \lambda, \bar{V}_{\varepsilon}$ denotes the lattice approximation of the gradient of a function, $\langle\cdot, \cdot\rangle$ is the usual scalar product in $\mathbb{R}^{d}$, and $\mathbb{D} f$ is the functional derivative of $f$. More exactly, let $e_{1}, e_{2}, \ldots, e_{d}$ denote the unit vectors of our system of coordinates in $\mathbb{R}^{d}$, then

$$
\begin{equation*}
\nabla_{\varepsilon} \sigma(x)=\frac{1}{\varepsilon} \sum_{i=1}^{d} e_{i}\left[\sigma\left(x+\varepsilon e_{i}\right)-\sigma(x)\right] \tag{3.13}
\end{equation*}
$$

if $\sigma: \mathbb{R}^{\boldsymbol{d}} \rightarrow \mathbb{R}$ is a scalar, while

$$
\begin{equation*}
\nabla_{\varepsilon}^{*} \varphi(x)=\frac{1}{\varepsilon} \sum_{i=1}^{d}\left[\varphi_{i}\left(x-\varepsilon e_{i}\right)-\varphi_{i}(x)\right] \tag{3.14}
\end{equation*}
$$

if $\varphi=e_{1} \varphi_{1}+e_{2} \varphi_{2}+\ldots+e_{d} \varphi_{d}$ is a vector field. Notice that $\nabla_{\varepsilon}^{*}$ is a lattice approximation to $-\operatorname{div}$, and $\Delta_{\varepsilon}=-\nabla_{\varepsilon}^{*} \nabla_{\varepsilon}$, that is

$$
\begin{equation*}
\Delta_{\varepsilon} \varphi(x)=\varepsilon^{-2} \sum_{i=1}^{d}\left[\varphi\left(x+\varepsilon e_{i}\right)-2 \varphi(x)+\varphi\left(x-\varepsilon e_{i}\right)\right] . \tag{3.15}
\end{equation*}
$$

We are using the following notation of functional (variational) derivatives. Let $\Sigma \subset \mathbb{L}_{e}^{2}$ denote a convex set and define $\mathbb{D}_{s}(\Sigma)$ as the space of $f: \Sigma \rightarrow \mathbb{R}$ such that if $\sigma, \bar{\sigma} \in \Sigma$ and $\delta=\sigma-\bar{\sigma}$, then

$$
\begin{equation*}
f(\sigma)-f(\bar{\sigma})=\int_{0}^{1} \int \delta(x) \mathbb{D} f(x, \bar{\sigma}+q \delta) d x d q \tag{3.16}
\end{equation*}
$$

where $\mathbb{D} f: \Sigma \rightarrow \mathbb{L}_{-e}^{2}$ is strongly continuous. If $\Sigma$ is dense in $\mathbb{L}_{e}^{2}$ then $\mathbb{D} f$ is uniquely defined. If $\Sigma=\Omega_{\varepsilon}$, as in (3.12), then $\mathbb{D} f(x, \sigma)=\mathbb{D} f(y, \sigma)$ if $x \in C_{\varepsilon}(y)$ is a natural convention we accept, that is, $\mathbb{D} f(x, \sigma)=\varepsilon^{-d} \partial f(\sigma) / \partial \sigma(x)$ in this case.

Now we are in a position to identify the limit (3.1). In view of (2.25), $F^{\prime}$ defines a one-to-one map of $\mathbb{L}_{e}^{2}$ onto itself by $F^{\prime}(\lambda)(x)=F^{\prime}(\lambda(x))$, and the law of large numbers, see (2.23), implies that $\tilde{g}(\lambda)=g\left(F^{\prime}(\lambda)\right)$ if $g \in \mathbb{C}_{w}\left(\mathbb{L}_{e}^{2}\right)$. Similarily, if $\lambda \in \mathbb{H}_{e}^{1}$ and $f \in \mathbb{C}_{0}\left(\mathbb{L}_{e}^{2}\right)$, then from (3.12) by the chain rule we obtain

$$
\begin{align*}
\lim _{\varepsilon \rightarrow 0} \int \mathbb{G}_{\varepsilon} f d \mu_{\lambda, \varepsilon} & =-\frac{1}{2} \int\left\langle\operatorname{grad} \lambda(x), \operatorname{grad} \mathbb{D} f\left(x, F^{\prime}(\lambda)\right)\right\rangle d x \\
& =-\int\left\langle\operatorname{grad} \lambda(x), \operatorname{grad} \frac{\mathbb{D} \tilde{f}(x, \lambda)}{2 F^{\prime \prime}(\lambda(x))}\right\rangle d x \tag{3.17}
\end{align*}
$$

This means that $\widetilde{\mathbb{P}}^{t} \tilde{g}(\lambda)=\tilde{g}\left(\lambda_{t}\right)$, where $\lambda_{t}$ is a continuous trajectory in $\mathbb{L}_{e}^{2}$ satisfying

$$
\begin{equation*}
2 F^{\prime \prime}\left(\lambda_{t}(x)\right) \partial_{t} \lambda_{t}(x)=\Delta \lambda_{t}(x), \quad \lambda_{0}=\lambda \tag{3.18}
\end{equation*}
$$

in a weak sense. In view of the correspondence $\rho=F^{\prime}(\lambda)$, the Eqs. (1.6) and (3.18) are equivalent. Let us remark that (3.1)-(3.3) extend to some $g \notin \mathbb{C}_{w}\left(\mathbb{L}_{e}^{2}\right)$, but $\tilde{g} \neq g\left(F^{\prime}(\lambda)\right)$ in such cases, see [13]. Of course, both (2.23) and the solvability of (3.18) need a proof, but the crucial step is certainly the compactness argument allowing us to pass from (3.6) via (3.12) to (3.7). The basic ideas are exposed as follows.

In the spirit of passing from (3.11) to (3.12), we interpret the rescaled process $\omega_{t}^{\varepsilon}$ as a trajectory in $\Omega_{\varepsilon}$ satisfying

$$
\begin{equation*}
d \omega_{t}^{\varepsilon}=\frac{1}{2} \Delta_{\varepsilon} V^{\prime}\left(\omega_{t}^{\varepsilon}\right) d t-\frac{\alpha}{2} \varepsilon^{2} \Delta_{\varepsilon}^{2} \omega_{t}^{\varepsilon} d t+\nabla_{\varepsilon}^{*} d w_{t}^{\varepsilon}, \quad \omega_{0}^{\varepsilon}=\sigma \in \Omega_{\varepsilon} \tag{3.19}
\end{equation*}
$$

where $w_{t}^{\varepsilon}(x)=\varepsilon \sum e_{j-k} w_{k j}\left(t / \varepsilon^{2}\right)$ if $x \in C_{\varepsilon}(\varepsilon k)$, the sum being for $j=k+e_{i}$, $i=1,2, \ldots, d$. This means that the current, see (1.3) is considered as a vector. The linearized equation (first variational system) of (3.19) is obtained by differentiating both sides of (3.19) with respect to some parameter of the initial configuration. We get

$$
\begin{equation*}
\partial_{t} u_{t}(y)=\frac{1}{2} \Delta_{\varepsilon}\left[a_{t}(y) u_{t}(y)\right]-\frac{\alpha}{2} \Delta_{\varepsilon}^{2} u_{t}(y) \tag{3.20}
\end{equation*}
$$

where $\partial_{t}=\partial / \partial t, a_{t}(y)=V^{\prime \prime}\left(\omega_{t}^{\varepsilon}(y)\right)$. Let $p_{a}=p_{a}(s, x ; t, y), 0 \leqq s \leqq t, x, y \in \mathbb{R}^{d}$ denote the fundamental solution to (3.20), that is, $u_{t}=p_{a}(s, x ; t, \cdot)$ satisfies (3.20) for $t \geqq s$ with initial condition $p_{a}(s, x ; s, y)=\varepsilon^{-d}$ if $y \in C_{\varepsilon}(x)$, and $p_{a}(s, x ; s, y)=0$ if
$y \notin C_{\varepsilon}(x)$. Since $p_{a}$ is just the functional derivative of $\omega_{t}^{\varepsilon}(y)$ with respect to $\omega_{s}^{\varepsilon}$, by the chain rule we obtain a representation for $\mathbb{D R}_{z, \varepsilon}$ in terms of $p_{a}$, namely if $f_{\varepsilon}=\mathbb{R}_{z, \varepsilon} g, z>0$, then

$$
\begin{equation*}
\mathbb{D} f_{\varepsilon}(x, \sigma)=\mathbb{E}\left[Y_{z}^{\varepsilon}(0, x, \sigma, g) \mid \omega_{0}^{\varepsilon}=\sigma\right], \quad \sigma \in \Omega_{\varepsilon}, \quad g \in \mathbb{D}_{b}\left(\Omega_{\varepsilon}\right), \quad x \in \mathbb{R}^{d}, \tag{3.21}
\end{equation*}
$$

where

$$
\begin{equation*}
Y_{z}^{\varepsilon}(s, x, \sigma, g)=\int_{s}^{\infty} e^{z s-z t} \int p_{a}(s, x ; t, y) \mathbb{D} g\left(y, \omega_{t}^{\varepsilon}\right) d y d t \tag{3.22}
\end{equation*}
$$

In view of (3.16) and (3.22), the compactness criteria we need for $f_{\varepsilon}$ and $\nabla_{\varepsilon} \mathbb{D} f_{\varepsilon}$ can be reduced to some regularity properties of the fundamental solution, $p_{a}$. The very same estimates are sufficient to prove the equicontinuity of $\int \mathbb{P}_{\varepsilon}^{t} g d \mu_{\lambda, \varepsilon}$ as a function of $t>0$. In the next two sections we prove some a priori bounds for $Y_{z}^{\varepsilon}$ that do not depend on $\varepsilon>0$ and the Wiener processes $w_{t}^{\varepsilon}$, as well. Since (3.20) is a parabolic equation, we do not need too much information on its coefficient, measurability of $a_{t}$ and the obvious bound $\left|1-a_{t}(y)\right| \leqq c<1$ will do. The methods of [12-14] are simplified by using the backward equation associated with (3.20) and the perturbative treatment of the problem will be combined with interpolation of operators in a sense of M. Riesz and Stein.

## 4. The Energy Inequality

In this section we are going to develop $\mathbb{L}_{r}^{2}$-estimates for a backward equation associated with (3.20). Suppose that we are given two continuous trajectories in $\Omega_{\varepsilon}, a_{s}$ and $h_{s}, s \geqq 0$, such that $\left|a_{s}(x)-1\right| \leqq c$ for every $x$ and $s$ with some $c<1 ; z>0, \alpha \geqq 0, \varepsilon>0$ are arbitrary constants. We are interested in the following equation,

$$
\begin{equation*}
-\partial_{s} u_{s}+z u_{s}=\frac{1}{2} a_{s} \Delta_{\varepsilon} u_{s}-\frac{\alpha}{2} \varepsilon^{2} \Delta_{\varepsilon}^{2} u_{s}+h_{s} \tag{4.1}
\end{equation*}
$$

the reason is very simple. Our fundamental quantity, $Y_{z}^{\varepsilon}$ satisfies (4.1) with $a_{s}(x)$ $=V^{\prime \prime}\left(\omega_{s}^{\varepsilon}(x)\right)$ and $h_{s}(x)=\mathbb{D} g\left(x, \omega_{s}^{\varepsilon}\right)$.

We start with some elementary vector calculus on the lattice. Remember that if $u$ and $v$ are vector fields, then

$$
\begin{equation*}
\langle u, v\rangle_{r}=\int \theta_{r}(x)\langle u(x), v(x)\rangle d x \tag{4.2}
\end{equation*}
$$

and $|u|_{r}^{2}=\langle u, u\rangle_{r}$. In the forthcoming calculations the following properties of our weight function $\theta_{r}$ will be exploited. Since $-\theta^{\prime}(x) \leqq \theta(x)$ for every $x \geqq 0$, we have

$$
\begin{gather*}
\left|\operatorname{grad} \theta_{r}(x)\right| \leqq|r| \theta_{r}(x)  \tag{4.3}\\
\theta_{r}(y) \leqq \theta_{r}(x) \exp (|r x-r y|) \tag{4.4}
\end{gather*}
$$

for every $x, y \in \mathbb{R}^{d}$ and $r \in \mathbb{R}$, whence

$$
\begin{equation*}
\left|\theta_{r}(x)-\theta_{r}(y)\right| \leqq|r x-r y| \exp (|r x-r y|) \theta_{r / 2}(x) \theta_{r ; 2}(y) . \tag{4.5}
\end{equation*}
$$

The energy inequality for (4.1) can be localized by means of the following three lemmas.

Lemma 1. If $|\varepsilon r| \leqq 1$ and $|u|_{r}<\infty,|v|_{r}<\infty$ with some $r \in \mathbb{R}$, where $u: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$ is a vector field, while $v \in \mathbb{L}_{r}^{2}$ is a scalar, then for every $b>0$ we have

$$
\left|\left\langle u, \nabla_{\varepsilon} v\right\rangle_{r}-\left\langle\nabla_{\delta}^{*} u, v\right\rangle_{r}\right| \leqq \frac{1}{b}|u|_{r}^{2}+3 d b r^{2}|v|_{r}^{2}
$$

Proof. Let $u_{1}, u_{2}, \ldots, u_{d}$ denote the coordinates of $u$. Since $\nabla_{\varepsilon}^{*}$ is the formal adjoint of $\nabla_{\varepsilon}$ with respect to the usual scalar product $\langle\cdot, \cdot\rangle_{0}$, an easy calculation yields

$$
\begin{aligned}
\left\langle u, \nabla_{\varepsilon} v\right\rangle_{r} & =\int \nabla_{\varepsilon}^{*}\left[\theta_{r}(x) u(x)\right] v(x) d x \\
& =\left\langle\nabla_{\varepsilon}^{*} u, v\right\rangle_{r}+\frac{1}{\varepsilon} \sum_{i=1}^{d} \int\left[\theta_{r}\left(x-\varepsilon e_{i}\right)-\theta_{r}(x)\right] u_{i}(x) v(x) d x
\end{aligned}
$$

whence by (4.3), (4.5) and by the Schwarz inequality we obtain

$$
\left|\left\langle u, \nabla_{\varepsilon} v\right\rangle_{r}-\left\langle\nabla_{\varepsilon}^{*} u, v\right\rangle_{r}\right| \leqq 3 r \sum_{i=1}^{d}\left|u_{i}\right|_{r}|v|_{r}
$$

which completes the proof as $2 u v \leqq u^{2} / b+b v^{2}$.
Lemma 2. If $|\varepsilon r| \leqq 1$ and $u, v \in \mathbb{L}_{r}^{2}\left(\mathbb{R}^{d}\right)$, then for every $b>0$,

$$
\left\langle u, \Delta_{\varepsilon} v\right\rangle_{r} \leqq\left\langle\Delta_{\varepsilon} u, v\right\rangle_{r}+\frac{1}{b}|u|_{r}^{2}+9 b(r d / \varepsilon)^{2}|v|_{r}^{2}
$$

Proof. Since $\Delta_{\varepsilon}$ is a symmetric operator, we have

$$
\begin{aligned}
\left\langle u, \Delta_{\varepsilon} v\right\rangle_{r}= & \int \Delta_{\varepsilon}\left[\theta_{r}(x) u(x)\right] v(x) d x \\
= & \left\langle\Delta_{\varepsilon} u, v\right\rangle_{r}+\varepsilon^{-2} \sum_{i=1}^{d} \int\left[\theta_{r}\left(x+\varepsilon e_{i}\right)-\theta_{r}(x)\right] u\left(x+\varepsilon e_{i}\right) v(x) d x \\
& +\varepsilon^{-2} \sum_{i=1}^{d} \int\left[\theta_{r}\left(x-\varepsilon e_{i}\right)-\theta_{r}(x)\right] u\left(x-\varepsilon e_{i}\right) v(x) d x
\end{aligned}
$$

whence by (4.3), (4.5) and by the Schwarz inequality we get

$$
\left\langle u, \Delta_{\varepsilon} v\right\rangle_{r} \leqq\left\langle\Delta_{\varepsilon} u, v\right\rangle_{r}+6 d|r| \varepsilon^{-1}|u|_{r}|v|_{r},
$$

which implies the statement by a direct calculation.

Lemma 3. Let $u$ and $v$ be vector fields such that $|u|_{r}<\infty,|v|_{r}<\infty$, and $|\varepsilon r| \leqq 1$, then for each $b>0$ we have

$$
\left\langle u, \nabla_{\varepsilon} \nabla_{\varepsilon}^{*} v\right\rangle_{r} \leqq\left\langle\nabla_{\varepsilon} \nabla_{\varepsilon}^{*} u, v\right\rangle_{r}+\frac{1}{b}|u|_{r}^{2}+36 b(r d / \varepsilon)^{2}|v|_{r}^{2}
$$

Proof. In a very similar way as above, we obtain

$$
\begin{aligned}
\left\langle u, \nabla_{\varepsilon} \nabla_{\varepsilon}^{*} v\right\rangle_{r}= & \int\left\langle\nabla_{\varepsilon} \nabla_{\varepsilon}^{*}\left[\theta_{r}(x) u(x)\right], v(x)\right\rangle d x \\
= & \varepsilon^{-2} \sum_{i=1}^{d} \sum_{j=1}^{d} \int \theta_{r}\left(x+\varepsilon e_{j}-\varepsilon e_{i}\right) u_{i}\left(x+\varepsilon e_{j}-\varepsilon e_{i}\right) v_{j}(x) d x \\
& -\varepsilon^{-2} \sum_{i=1}^{d} \sum_{j=1}^{d} \int \theta_{r}\left(x-\varepsilon e_{i}\right) u_{i}\left(x-\varepsilon e_{i}\right) v_{j}(x) d x \\
& -\varepsilon^{-2} \sum_{i=1}^{d} \sum_{j=1}^{d} \int \theta_{r}\left(x+\varepsilon e_{j}\right) u_{i}\left(x+\varepsilon e_{j}\right) v_{j}(x) d x \\
& +\varepsilon^{-2} \sum_{i=1}^{d} \sum_{j=1}^{d} \int \theta_{r}(x) u_{i}(x) v_{j}(x) d x \\
\leqq & \left\langle\nabla_{\varepsilon} \nabla_{\varepsilon}^{*} u, v\right\rangle+12 \frac{r}{\varepsilon} \sum_{i=1}^{d} \sum_{j=1}^{d}|u|_{i}|v|_{j}
\end{aligned}
$$

where $u_{i}$ and $v_{j}$ are the coordinates of $u$ and $v$, respectively, which completes the proof.

Now we define the current of a configuration, that is, an inverse operator of the discrete divergence.

Lemma 4. To every $\sigma \in \Omega_{\varepsilon}$ there corresponds a vector field, $v=\mathbb{K}_{\varepsilon} \sigma$, such that the coordinates of $v$ belong to $\Omega_{\varepsilon},-\nabla_{\varepsilon}^{*} \mathbb{K}_{\varepsilon} \sigma=\sigma$ is an identity, and $\left|\mathbb{K}_{\varepsilon} \sigma\right|_{r}$ $\leqq K_{r}|\sigma|_{r / 2 d}$ if $r>0,|r \varepsilon| \leqq 1$, where $K_{r}$ depends only on $r$ and $d$.

Proof. In view of the additivity of $\mathbb{K}_{e}$, we may, and do assume that $\sigma$ vanishes outside of an octant, say

$$
0_{\varepsilon}^{+}=\left[x \in \mathbb{R}^{d}:\left\langle x, e_{q}\right\rangle \geqq-\varepsilon / 2, q=1,2, \ldots, d\right] .
$$

We define $v$ in terms of a directed random walk, $X_{n}$, on $\mathbb{Z}^{d}$ being a Markov chain such that $P\left[X_{n+1}=j \mid X_{n}=k\right]=1 / d$ if $j=k+e_{q}, q=1,2, \ldots, d$, all other jumps are excluded. Let $i, k \in \mathbb{Z}^{d}, j=k+e_{q}$ and denote $p_{i}(k, j)$ denote the probability that our walk, started from $i$, hits both $k$ and $j$; if $(k, j)$ is a negatively oriented bond, i.e. $j=k-e_{q}$, then $p_{i}(k, j)=-p_{i}(j, k)$ by convention. Observe that

$$
\sum_{j:|j-k|=1} p_{i}(k, j)=\left\{\begin{array}{ll}
0 & \text { if } i \neq k \\
1 & \text { if } i=k
\end{array},\right.
$$

therefore $\mathbb{K}_{\varepsilon} \sigma=v$ defined by

$$
v(x)=\varepsilon \sum_{q=1}^{d} e_{q} \sum_{i \in \mathbb{Z}^{d}} \sigma(\varepsilon i) p_{i}\left(k, k+e_{q}\right) \quad \text { if } x \in C_{\varepsilon}(\varepsilon k)
$$

satisfies $-\nabla_{\varepsilon}^{*} v=\sigma$. On the other hand, $p_{i}(k, j)=0$ if $k-i \notin 0_{\varepsilon}^{+}$, and if $\varphi(k)$ denotes the sum of the coordinate of $k \in \mathbb{Z}^{d}$, then

$$
\sum_{q=1}^{d} \sum_{\varphi(k)=m} p_{i}\left(k, k+e_{q}\right)=1 \quad \text { for } \varphi(i) \leqq m,
$$

while

$$
\sum_{q=1}^{d} \sum_{i \in 0_{\varepsilon}^{+}} p_{i}\left(k, k+e_{q}\right) \leqq 1+\varphi(k)
$$

thus the Cauchy inequality implies the statement by a direct calculation.
The main information on the dynamics is contained in
Lemma 5. Suppose that $a \in \Omega_{\varepsilon},|a(x)-1| \leqq c<1$ for all $x$, and let

$$
\mathbb{L}_{a} v=-z v-\frac{1}{2} \nabla_{\varepsilon}\left(a \nabla_{\varepsilon}^{*} v\right)+\frac{\alpha}{2} \varepsilon^{2} \nabla_{\varepsilon} \Delta_{\varepsilon} \nabla_{\varepsilon}^{*} v
$$

where $z \geqq 0, \alpha \geqq 0, \varepsilon>0$ and $v: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$ is a vector field. There exists a constant, $C$, depending only on $c, d, \alpha$ such that

$$
2\left\langle v, \mathbb{L}_{a} v+\nabla_{\varepsilon} h\right\rangle_{r}+2 z|v|_{r}^{2}+c(1-c)\left|\nabla_{\varepsilon}^{*} v\right|_{r}^{2} \leqq 2 C r^{2}|v|_{r}^{2}+C|h|_{r}^{2}
$$

whenever $h \in \Omega_{\varepsilon}$ and $|\varepsilon r| \leqq 1$.
Proof. Lemma 1 and Lemma 3 imply that

$$
\begin{aligned}
2\langle v, & \left.\mathbb{L}_{a} v+\nabla_{\varepsilon} h\right\rangle_{r}+2 z|v|_{r}^{2} \\
& \leqq \\
& -(1-c)\left|\nabla_{\varepsilon}^{*} v\right|_{r}^{2}-\alpha \varepsilon^{2}\left|\nabla_{\varepsilon} \nabla_{\varepsilon}^{*} v\right|_{r}^{2}+2\left\langle\nabla^{*} \mathrm{v}, h\right\rangle \\
& +(1+c) b_{1}^{-1}|v|_{r}^{2}+3 r^{2}(1+c) d b_{1}\left|\nabla_{\varepsilon}^{*} v\right|_{r}^{2}+b_{2}^{-1}|v|_{r}^{2} \\
& +3 d r^{2} b_{2}|h|_{r}^{2}+\alpha \varepsilon^{2} b_{3}^{-1}|v|_{r}^{2}+36 \alpha d^{2} r^{2} b_{3}\left|\nabla_{\varepsilon} \nabla_{\varepsilon}^{*} v\right|_{r}^{2} \\
\leqq & {\left[(1+c) b_{1}^{-1}+2 b_{2}^{-1}+\alpha \varepsilon^{2} b_{3}^{-1}\right]|v|_{r}^{2}+\left[b_{4}^{-1}+6 d r^{2} b_{2}\right]|h|_{r}^{2} } \\
& +\left[3(1+c) d r^{2} b_{1}+b_{4}-(1-c)\right]\left|\nabla_{\varepsilon}^{*} v\right|_{r}^{2} \\
& +\left[36 \alpha d^{2} r^{2} b_{3}-\alpha \varepsilon^{2}\right]\left|\nabla_{\varepsilon} \nabla_{\varepsilon}^{*} v\right|_{r}^{2}
\end{aligned}
$$

where $b_{1}, b_{2}, b_{3}, b_{4}$ are arbitrary positive numbers. The statement follows by setting $\quad b_{4}=(1-c)^{2} / 2, \quad b_{3}=(\varepsilon / 6 r d)^{2}, \quad b_{2}=1 / r^{2} \quad$ and $\quad b_{1}=(1-c)^{2}[6(1$ $\left.+c) d r^{2}\right]^{-1} . \square$

Suppose now that $u_{s}$ satisfies (4.1) for $s \leqq T \leqq \infty$, and $z \geqq z^{\prime} \geqq z_{r}=C r^{2},|\varepsilon r| \leqq 1$, then Lemma 5 implies immediately that

$$
\begin{align*}
& \left|\nabla_{\varepsilon} u_{0}\right|_{r}^{2}+c(1-c) \int_{0}^{T} \exp \left(2 z_{r} s-2 z^{\prime} s\right)\left|A_{\varepsilon} u_{s}\right|_{r}^{2} d s \\
& \quad \leqq \exp \left(2 z_{r} T-2 z^{\prime} T\right)\left|\nabla_{\varepsilon} u_{T}\right|_{r}^{2}+C \int_{0}^{T} \exp \left(2 z_{r} t-2 z^{\prime} t\right)\left|h_{t}\right|_{r}^{2} d t \tag{4.6}
\end{align*}
$$

Multiplying (4.1) by $2 u_{s}$, from Lemma 2 we obtain

$$
\begin{aligned}
-\partial_{s}\left|u_{s}\right|_{r}^{2}+2 z\left|u_{s}\right|_{r}^{2} \leqq & (1+c)\left|u_{s}\right|_{r}\left|\Delta_{\varepsilon} u_{s}\right|_{r}+2|u|_{r}\left|h_{s}\right|_{r} \\
& -\alpha \varepsilon^{2}\left|\Delta_{\varepsilon} u_{s}\right|_{r}^{2}+\frac{\alpha}{b} \varepsilon^{2}\left|u_{s}\right|_{r}^{2}+9 b \alpha(r d)^{2}\left|\Delta_{\varepsilon} u_{s}\right|_{r}^{2}
\end{aligned}
$$

whence by (4.6)

$$
\begin{align*}
\left|u_{0}\right|_{r}^{2} \leqq & \exp \left(2 z_{r} T-2 z^{\prime} T\right)\left[\left|u_{T}\right|_{r}^{2}+\left|\nabla_{\varepsilon} u_{T}\right|_{r}^{2}\right] \\
& +2 C \int_{0}^{T} \exp \left(2 z_{r} t-2 z^{\prime} t\right)\left|h_{t}\right|_{r}^{2} d t \tag{4.7}
\end{align*}
$$

(4.6) and (4.7) yield a priori bounds for $f_{\varepsilon}, \mathbb{D} f_{\varepsilon}, \nabla_{\varepsilon} \mathbb{D} f_{\varepsilon}$ and $\partial_{t} \int \mathbb{P}_{\varepsilon}^{t} g d \mu_{\lambda, \varepsilon}$. The weak equicontinuity of $f_{\varepsilon}$ is based on

Lemma 6. Let $B$ denote a ball of $\mathbb{L}_{e}^{2}$. For every $B$, and for each $\beta>0, r>0$ and $K<\infty$ there exists a weak neighborhood of 0 in $\mathbb{L}_{e}^{2}, U_{\gamma}\left(\varphi_{1}, \varphi_{2}, \ldots, \varphi_{n}\right)$, such that $\quad|\varphi(\delta)|<\beta \quad$ whenever $\quad \varphi \in \Omega_{\varepsilon}, \quad|\varphi|_{-r}+\left|\nabla_{\varepsilon} \varphi\right|_{-r} \leqq K \quad$ and $\delta \in B \cap U_{\gamma}\left(\varphi_{1}, \varphi_{2}, \ldots, \varphi_{n}\right)$.

Proof. Let $H_{r}(K)$ denote the set of $\varphi \in \mathbb{L}_{-r}^{2}$ such that $\varphi \in \Omega_{\varepsilon}$ for some $\varepsilon>0$ and $\left|\nabla_{\varepsilon} \varphi\right|_{-r}+|\varphi|_{-r} \leqq K$. Since $\left|I_{\varepsilon} \sigma\right|_{r} \leqq|\sigma|_{r}$, this definition makes sense. In view of the F. Riesz criterion of compactness, the set $H_{r}(K)$ is precompact in the strong topology of $\mathbb{L}^{2}\left(\mathbb{R}^{d}\right)$, and hence also in that of $\mathbb{L}_{-r / 2}^{2}\left(\mathbb{R}^{d}\right)$. Indeed, estimating $\int \theta_{-\boldsymbol{r} / 2}(x) \varphi^{2}(x) d x$ separately in the ball $\left[x \in \mathbb{R}^{d}:|x| \leqq 2 n / r\right]$, and outside of it, since $e^{-u} \leqq \theta(u) \leqq 5 e^{-u}$, we obtain that

$$
|\varphi|_{-r / 2}^{2} \leqq e^{n}|\varphi|_{0}^{2}+5^{r / 2} e^{-n}|\varphi|_{-r}^{2} \leqq 2 K 5^{r / 4}|\varphi|_{0}
$$

if $\varphi \in H_{r}(K)$. Therefore, for each $\gamma^{\prime}>0$ we can select a finite sequence, $\varphi_{1}, \varphi_{2}, \ldots, \varphi_{n}$ from $\mathbb{L}_{-\boldsymbol{r} / 2}^{2}$ in such a way that $\left|\varphi-\varphi_{k}\right|_{-\boldsymbol{r} / 2}<\gamma^{\prime}$ for each $\varphi \in H_{r}(K)$ with some $k=1,2, \ldots, n$. Let $\delta \in B \cap U_{\gamma^{\prime}}$, then

$$
|\varphi(\delta)| \leqq\left|\varphi(\delta)-\varphi_{k}(\delta)\right|+\left|\varphi_{k}(\delta)\right| \leqq \gamma^{\prime}+\gamma^{\prime} \sup _{\sigma \in B}|\sigma|_{-r / 2}
$$

which completes the proof.

To prove the equicontinuity of $\nabla_{\varepsilon} \mathbb{D} f_{\varepsilon}$, we have to compare two solutions, $u_{s}$ and $\bar{u}_{s}$ to (4.1) with different $a_{s}, h_{s}$ and $\bar{a}_{s}, \bar{h}_{s}$ corresponding to different initial configurations, $\sigma$ and $\bar{\sigma}$. Since

$$
a_{s} \Delta_{\varepsilon} u_{s}-\bar{a}_{s} \Delta_{\varepsilon} \bar{u}_{s}=\left(a_{s}-\bar{a}_{s}\right) \Delta_{\varepsilon} u_{s}+\bar{a}_{s} \Delta_{\varepsilon}\left(u_{s}-u_{s}\right),
$$

from (4.6)

$$
\begin{equation*}
\left|\nabla_{\varepsilon} u_{0}-\nabla_{\varepsilon} u_{0}\right|_{r}^{2} \leqq C \int_{0}^{\infty} e^{-\tilde{z} t}\left|h_{t}-\bar{h}_{t}\right|_{r}^{2} d s+C \int_{0}^{\infty} e^{-\bar{z} s}\left|\left(a_{s}-\bar{a}_{s}\right) \Delta_{\varepsilon} u_{s}\right|_{r}^{2} d s \tag{4.8}
\end{equation*}
$$

where $0 \leqq \tilde{z} \leqq 2 z-2 z_{r}$ and $|\varepsilon r| \leqq 1$. For the second term we need an $\mathbb{L}^{q}$-bound with some $q>2$.

## 5. Singular Integrals and Interpolation

In this section we investigate an integral operator, $P_{a, z}$,

$$
\begin{equation*}
P_{a, z} h(s, x)=\int_{0}^{\infty} e^{z s-z t} \int p_{a}(s, x ; t, y) h(t, y) d y d t \tag{5.1}
\end{equation*}
$$

where $z>0$ and $p_{a}$ denotes the fundamental solution of (3.20). Remember that $P_{a, z}$ depends also on $\varepsilon>0$, we need bounds that do not depend on $\varepsilon$. Let $\mathbb{R}_{+}^{d}$ $=[0, \infty) \times \mathbb{R}^{d}$, and introduce $\mathbb{L}_{r}^{q}\left(\mathbb{R}_{+}^{d}\right)$ as the space of locally integrable $h: \mathbb{R}_{+}^{d}$ $\rightarrow \mathbb{R}$ with norm

$$
\begin{equation*}
|h|_{r, q}=\left[\int_{0}^{\infty} \int \theta_{r}(y)|h(t, y)|^{q} d y d t\right]^{1 / q} \tag{5.2}
\end{equation*}
$$

We want to prove that $\Delta_{\varepsilon} P_{a, z}$ is a bounded map of $\mathbb{L}_{r}^{q}\left(\mathbb{R}_{+}^{d}\right)$ into itself, at least if $q>2$ is small enough.
Lemma 7. For each $q \geqq 2$ we have a constant, $C_{q}$ such that $C_{q} \rightarrow 2$ as $q \rightarrow 2$ and

$$
\left|\Delta_{\varepsilon} P_{1,0} h\right|_{0, q} \leqq C_{q}|h|_{0, q} \quad \text { if } h \in \mathbb{L}_{0}^{q}\left(\mathbb{R}_{+}^{d}\right)
$$

Proof. The main problem is that of the boundedness of $\Delta_{\varepsilon} P_{1,0}$, that is the point where singular integrals enter the stage, see the Appendix of [29]. Following this approach, the statement has been verified if $d=1$, see Lemma 5 in [14], but $p_{a}$ factorizes if $a=1$ :

$$
p_{1}(s, x ; t, y)=\prod_{i=1}^{d} J_{\varepsilon}\left(s, x_{i} ; t, y_{i}\right),
$$

where $x_{i}$ and $y_{i}$ denote the coordinates of $x, y \in \mathbb{R}^{d}$, and $J_{\varepsilon}$ is the associated one-dimensional kernel. Since the functions of type

$$
h(t, y)=\psi(t) \prod_{i=1}^{d} \varphi\left(y_{i}\right)
$$

are obviously dense in $\mathbb{L}_{0}^{q}\left(\mathbb{R}_{+}^{d}\right)$, the above factorization property reduces the statement to the one-dimensional case by a direct calculation.

In view of the Riesz-Thorin interpolation theorem, see [28], the proof is completed by showing that $C_{2}=2$ may be assumed. Since $P_{1,0} h$ satisfies (4.1) with $a_{s}=1$ and $z=0$, we have

$$
-\partial_{s}\left|\nabla_{\varepsilon} u_{s}\right|_{0}^{2}=-\left|\Delta_{\varepsilon} u_{s}\right|_{0}^{2}-\alpha \varepsilon^{2}\left|\nabla_{\varepsilon} \Delta_{\varepsilon} u_{s}\right|_{0}^{2}-2\left\langle\Delta_{\varepsilon} u_{s}, h_{s}\right\rangle_{0}
$$

whence $\left|\Delta_{\varepsilon} u\right|_{0,2} \leqq 2|h|_{0,2}$ by the Schwarz inequality.
Now we are in a position to prove the main tool of the compactness argument.

Lemma 8. Suppose that $a_{s}$ is a continuous trajectory in $\Omega_{\varepsilon}$ satisfying $\left|a_{s}(x)-1\right|$ $\leqq c<1$, and let $C$ and $C_{q}, q \geqq 2$ denote the constants of Lemma 5 and Lemma 7, respectively. If $c C_{q}<2$ then we have a constant, $M_{q}$, depending only on $q$ and c such that

$$
\left|\Delta_{\varepsilon} P_{a, z} h\right|_{r, q} \leqq M_{q}|h|_{r, q} \quad \text { for } h \in \mathbb{L}_{r}^{q}\left(\mathbb{R}_{+}^{d}\right), \quad z \geqq C r^{2}, \quad|\varepsilon r| \leqq 1
$$

Proof. The bounds (4.6), (4.7) imply that (4.1) is uniquely solved in $\mathbb{L}_{r}^{2}$ whenever $h \in \mathbb{L}_{r}^{2}\left(\mathbb{R}_{+}^{d}\right),|\boldsymbol{r} \varepsilon| \leqq 1, z \geqq C r^{2}$, and the solution is given by $u_{s}(x)=P_{a, z} h(s, x)$. Since $\Omega_{\varepsilon} \cap \mathbb{L}_{r}^{q}\left(\mathbb{R}^{d}\right)$ consists of bounded functions if $r \leqq 0$, this uniqueness result extends to all $q \geqq 2$ and $r \leqq 0$. In particular, as $a_{s}=1+\left(a_{s}-1\right)$, we have

$$
\begin{equation*}
P_{a, z} h=P_{1, z} h+\frac{1}{2} P_{1, z}(a-1) \Delta_{\varepsilon} P_{a, z} h \tag{5.3}
\end{equation*}
$$

where $a-1=a_{s}(x)-1$ is acting as a multiplication operator, whence

$$
\begin{equation*}
\left|P_{a, z} h\right|_{r, q} \leqq C_{q}|h|_{r, q}+\frac{1}{2} c C_{q}\left|P_{a, z} h\right|_{r, q}, \tag{5.4}
\end{equation*}
$$

at least if $r=z=0$, see Lemma 7. Letting $q$ go to two, we obtain the statement in this particular case, the general case follows by interpolation. Indeed, replacing $d t d x$ by $e^{-z t} d t \theta_{r}(x) d x$, and using the Stein interpolation theorem, see Theorem 4.1 in [27] or Theorem 2.11 in [26], we can extend Lemma 7 to all $z \geqq 0$ and $r \in \mathbb{R}$ with the same $C_{q}$, which completes the proof.

Now we are in a position to start the proof of Theorem 2.

## 6. The Compactness Criteria

This section summarizes the final information on the microscopic dynamics. Just as before, $\omega_{t}^{\varepsilon}$ and $\bar{\omega}_{t}^{\varepsilon}$ are different strong solutions to (3.19) with identical Wiener trajectories, $a_{t}=a_{t}(y)=V^{\prime \prime}\left(\omega_{t}^{\varepsilon}(y)\right),\left|a_{t}(y)-1\right| \leqq c<1, p_{a}$ denotes the fundamental solution to (4.1), and $K_{r}$ and $C$ are some universal constants, see Lemma 4 and Lemma 5.

We shall prove Theorem 2 first for some functions of class $\mathbb{D}_{L}$. Let $\Sigma \subset \mathbb{L}_{e}^{2}$ be convex, and denote $\mathbb{D}_{L}(\Sigma)$ the space of $g \in \mathbb{D}_{s}(\Sigma)$ for which we have some $r>0$ and $q>2$ such that

$$
\begin{gather*}
\|g\|=\sup _{\sigma \in \Sigma}|g(\sigma)|<\infty, \quad\|\mathbb{D} g\|_{-r}=\sup _{\sigma \in \Sigma}|\mathbb{D} g(\cdot, \sigma)|_{-r}<\infty,  \tag{6.1}\\
L_{r}(\mathbb{D} g)=\sup _{\sigma, \bar{\sigma} \in \Sigma}|\mathbb{D} g(\cdot, \sigma)-\mathbb{D} g(\cdot, \bar{\sigma})|_{-r}\left(|\sigma-\bar{\sigma}|_{r}\right)^{-1}<\infty,  \tag{6.2}\\
\|\mathbb{D} g\|_{-r, q}=\sup _{\sigma \in \Sigma}\left[\int \theta_{-r}(x)|\mathbb{D} g(x, \sigma)|^{q} d x\right]^{1 / q}<\infty . \tag{6.3}
\end{gather*}
$$

Theorem 1 can be extended to functions of class $\mathbb{D}_{w}^{\prime}(\Sigma)$ defined as the set of weakly continuous $g \in \mathbb{D}_{s}(\Sigma)$ such that besides (6.1), with the same $r>0$, we have

$$
\begin{equation*}
\left\|\nabla_{\varepsilon} \mathbb{D} g\right\|_{-r}=\sup _{\sigma \in \Sigma}\left|\nabla_{\varepsilon} \mathbb{D} g(\cdot, \sigma)\right|_{-r}<\infty \tag{6.4}
\end{equation*}
$$

Finally, let $g_{t}^{\varepsilon}(\sigma)=g\left(\omega_{t}^{\varepsilon}\right)$ if $\omega_{0}^{\varepsilon}=\sigma$, and

$$
\begin{equation*}
X_{z}^{\varepsilon}(\sigma, g)=\int_{0}^{\infty} e^{-z t} g\left(\omega_{t}^{\varepsilon}\right) d t \tag{6.5}
\end{equation*}
$$

then $\mathbb{D} g_{t}^{\varepsilon}(x, \sigma)=\int p_{a}(0, x ; t, y) \mathbb{D} g\left(y, \omega_{t}^{\varepsilon}\right) d y$, and $\quad Y_{z}^{\varepsilon}(0, x, \sigma, g)=\mathbb{D} X_{z}^{\varepsilon}(x, \sigma, g)$, see (3.22).
Lemma 9. Let $r<0,|r \varepsilon| \leqq 1, z>C r^{2}$ and $g \in \mathbb{D}_{s}\left(\Omega_{\varepsilon}\right)$, then
(i) $\left\|\mathbb{D} g_{t}^{\varepsilon}\right\|_{r}^{2}+\left\|\nabla_{\varepsilon} \mathbb{D} g_{t}^{\varepsilon}\right\|_{r}^{2} \leqq \exp \left(C r^{2} t\right)\left[\|\mathbb{D} g\|_{r}^{2}+2\left\|\nabla_{\varepsilon} \mathbb{D} g\right\|_{r}^{2}\right]$,
(ii) $\left\|\mathbb{D} X_{z}^{e}(\cdot, \cdot \cdot, g)\right\|_{r}^{2}+\left\|\nabla_{\varepsilon} \mathbb{D} X_{z}^{z}(\cdot, \cdot \cdot g)\right\|_{r}^{2} \leqq C\left(z-C r^{2}\right)^{-1}\|\mathbb{D} g\|_{r}^{2}$.

Proof. Both statements are direct consequences of (4.6) and (4.7). In the case of (i) we choose $z=0, T=t$ and $h=0$, while $T=\infty$ and $h_{t}(y)=\mathbb{D} g\left(y, \omega_{t}^{\varepsilon}\right)$ for (ii).

The following lemma is based on Lemma 4.
Lemma 10. Let $r>0, r \varepsilon \leqq 1, z \geqq C r^{2}$ and $g \in \mathbb{D}_{s}\left(\Omega_{\varepsilon}\right)$, then
(i) $c(1-c) \int_{0}^{\infty} e^{-\bar{z} t} \mathbb{E}\left[\left|\omega_{t}^{\varepsilon}\right|_{\mid r}^{2} \mid \omega_{0}^{\varepsilon}=\sigma\right] d t \leqq K_{r}^{2}|\sigma|_{r / 2 d}^{2}+\frac{5}{\tilde{z}}(2 d / r)^{d}$,
(ii) $c(1-c) \int_{0}^{\infty} e^{-\tilde{z} t}\left|\omega_{t}^{\varepsilon}-\bar{\omega}_{t}^{\varepsilon}\right|_{r}^{2} d t \leqq K_{r}^{2}\left|\omega^{\varepsilon}-\bar{\omega}^{\varepsilon}\right|_{r / 2 d}^{2}$,
(iii) $c(1-c) \int_{0}^{\infty} e^{-\tilde{z} t}\left|\int \mathbb{D} g_{t}^{\varepsilon}(x, \sigma) \Delta_{\varepsilon} \lambda(x) d x\right|_{r}^{2} d t \leqq\left|\nabla_{\varepsilon} \lambda\right|_{r}^{2}\|\mathbb{D} g\|_{-r}^{2}$.

Proof. Introduce the current, $v_{t}^{\varepsilon}$ of $\omega_{t}^{\varepsilon}$ by $v_{0}^{\varepsilon}=\mathbb{K}_{\varepsilon} \sigma$ and

$$
d v_{t}^{\varepsilon}(y)=\frac{1}{2} \nabla_{\varepsilon}\left[\hat{a}_{t}(y) \omega_{\imath}^{\varepsilon}(y)\right] d t-\frac{\alpha}{2} \varepsilon^{2} \nabla_{\varepsilon} \Delta_{\varepsilon} \omega_{t}^{\varepsilon}(y) d t-d w_{t}^{\varepsilon}(y),
$$

where $\hat{a}_{t}(y)=\left[V^{\prime}\left(\omega_{t}^{\varepsilon}(y)\right)-V^{\prime}(0)\right] / \omega_{t}^{\varepsilon}(y)$, thus $\omega_{t}^{\varepsilon}=-\nabla_{\varepsilon}^{*} v_{t}$, and the drift of $v_{i}^{\varepsilon} \exp ($ $-z t$ ) turns out to be $\mathbb{L}_{\hat{a}} v_{t}^{2}$, thus the Ito lemma, Lemma 5 and Lemma 4 imply (i) by a direct calculation. The proof of (ii) is quite similar, but even simpler; the current of $\left(\omega_{t}^{\varepsilon}--\bar{\omega}_{t}^{t}\right) e^{-z t}$ satisfies $\partial_{t} v=\mathbb{L}_{\tilde{a}} v$ with

$$
\tilde{a}_{t}(y)=\left[V^{\prime}\left(\omega_{t}^{\varepsilon}(y)\right)-V^{\prime}\left(\bar{\omega}_{t}^{\varepsilon}(y)\right)\right]\left[\omega_{t}^{\varepsilon}(y)-\bar{\omega}_{t}^{\varepsilon}(y)\right]^{-1}
$$

To prove (iii), let

$$
u_{t}(y)=\int p_{a}(0, x ; t, y) \Delta_{\varepsilon} \lambda(x) d x
$$

and let $v_{t}$ denote the solution to $\partial_{t} v_{t}=\mathbb{L}_{a} v_{t}$ with initial condition $v_{0}=\nabla_{\varepsilon} \lambda$, then $-\nabla_{\varepsilon}^{*} v_{t}=u_{t} e^{-z t}$, whence by Lemma 5

$$
c(1-c) \int_{0}^{\infty} e^{-\tilde{z} t}\left|u_{t}\right|_{r}^{2} d t \leqq\left|\widetilde{V}_{\varepsilon} \lambda\right|_{r}^{2}
$$

which completes the proof of (iii) by the Schwarz inequality.
The problems of weak equicontinuity reduce to Lemma 6; remember that $C_{q}$ denotes the constant of Lemma 7.
Lemma 11. For each $\beta>0, r<0, K<\infty, q>2$ such that $c C_{q}<2$, and for every ball $B \subset \mathbb{L}_{e}^{2}$ there exists a weak neighborhood $U=U_{\gamma}\left(\varphi_{1}, \varphi_{2}, \ldots, \varphi_{n}\right)$ of $0 \in \mathbb{L}_{e}^{2}$ such that if $|r \varepsilon q| \leqq q-2, z \geqq 2 C r^{2}, g \in \mathbb{D}_{s}\left(\Omega_{\varepsilon}\right), \sigma, \bar{\sigma} \in \Omega_{\varepsilon}, \delta=\sigma-\bar{\sigma}$, then $\delta \in B \cap U$ implies
(i) $\left|X_{z}^{\varepsilon}(\sigma, g)-X_{z}^{\varepsilon}(\bar{\sigma}, g)\right|<\beta$ whenever $\|\mathbb{D} g\|_{r} \leqq K$,
(ii) $\left|g_{t}^{\varepsilon}(\sigma)-g_{t}^{\varepsilon}(\bar{\sigma})\right|<\beta$ if $t+\|\mathbb{D} g\|_{r}+\left\|\nabla_{\varepsilon} \mathbb{D} g\right\|_{r} \leqq K$,
(iii) $\left|\mathbb{D} X_{z}^{\varepsilon}(\cdot, \sigma, g)-\mathbb{D} X_{z}^{\varepsilon}(\cdot, \bar{\sigma}, g)\right|_{r}^{2}+\left|\nabla_{\varepsilon} \mathbb{D} X_{z}^{\varepsilon}(\cdot, \sigma, g)-\nabla_{\varepsilon} \mathbb{D} X_{z}^{\varepsilon}(\cdot, \bar{\sigma}, g)\right|_{r}^{2}<\beta$ whenever $\|\mathbb{D} g\|_{r}+L_{r}(g)+\|\mathbb{D} g\|_{q r, q} \leqq K$.
Proof. In view of the definition of functional derivatives, we have

$$
X_{z}^{\varepsilon}(\sigma, g)-X_{z}^{\varepsilon}(\bar{\sigma}, g)=\int \delta(x) \int_{0}^{1} \mathbb{D} X_{z}^{\varepsilon}(x, \bar{\sigma}+u \delta, g) d u d x
$$

thus (ii) of Lemma 9 implies the conditions of Lemma 6, which proves (i). Similarily,

$$
g_{t}^{\varepsilon}(\sigma)-\mathrm{g}_{t}^{\varepsilon}(\bar{\sigma})=\int \delta(x) \int_{0}^{1} \mathbb{D} g_{t}^{\varepsilon}(x, \bar{\sigma}+u \delta) d u d x
$$

whence (ii) follows in the same way. The proof of (iii) is a little bit more involved. Using a decomposition $a \Delta_{\varepsilon} u-\bar{a} \Delta_{\varepsilon} \bar{u}=(a-\bar{a}) \Delta_{\varepsilon} u+\bar{a} \Delta_{\varepsilon}(u-\bar{u})$, from (4.6) and (4.7) we obtain that the left hand side of (iii) is bounded by $3 C J_{1}+(3 C / 4) J_{2}$, where

$$
\begin{gathered}
J_{1}=\int_{0}^{\infty} e^{-\tilde{z} t}\left|\mathbb{D} g\left(\cdot, \omega_{t}^{\varepsilon}\right)-\mathbb{D} g\left(\cdot, \bar{\omega}_{t}^{\varepsilon}\right)\right|_{r}^{2} d t \\
J_{2}=\int_{0}^{\infty} e^{-\tilde{z} s} \int \theta_{r}(x)\left|a_{s}(x)-\bar{a}_{s}(x)\right|^{2}\left[\Lambda_{\varepsilon} P_{a, z} h(s, x)\right]^{2} d x d s,
\end{gathered}
$$

$\tilde{z}=2 z-2 C r^{2}, a_{s}(x)=V^{\prime \prime}\left(\omega_{s}(x)\right), \bar{a}_{s}(x)=V^{\prime \prime}\left(\bar{\omega}_{s}(x)\right), h(t, y)=\mathbb{D} g\left(y, \omega_{t}^{\varepsilon}\right)$. In view of (6.2), the estimation of $J_{1}$ reduces to that of $J_{3}$,

$$
\begin{aligned}
J_{3} & =\int_{0}^{\infty} e^{-z t}\left|\omega_{t}^{\varepsilon}-\bar{\omega}_{t}^{\varepsilon}\right|_{-r}^{2} d t \\
& =\int \delta(x) \int_{0}^{\infty} e^{-z t} \int p_{\bar{a}}(0, x ; t, y) k(t, y) d y d t d x
\end{aligned}
$$

where $k(t, y)=\theta_{-r}(x)\left[\omega_{t}^{\varepsilon}(y)-\bar{\omega}_{t}^{e}(y)\right], r<0$, and $\tilde{a}$ is the same as in the proof of Lemma 10. From (ii) of Lemma 10 we obtain that $k$ is uniformly bounded in $\mathbb{L}_{-r}^{2}\left(\mathbb{R}_{+}^{d}\right)$, (4.6) and (4.7) imply the conditions of Lemma 6, that is, $J_{3}$ is small if $\delta \in B \cap U$.

The second term, $J_{2}$ can be estimated by means of Lemma 7 and Lemma 8. Using $\theta_{r}(x)=\theta_{2 r}(x) \theta_{-r}(x)$ and the Hölder inequality with powers $q /(q-2)$ and $q / 2$, we can bound $J_{2}$ by a product of two factors such that the second factor is controlled by Lemma 8, while the first one turns out to be a power, $1-2 / q$, of $J_{4}$,

$$
\begin{aligned}
J_{4} & =\int_{0}^{\infty} e^{-\tilde{z} t} \int \theta_{r^{\prime}}(y)\left|a_{t}(y)-\bar{a}_{t}(y)\right|^{2 q / q-2} d y d t \\
& =\int \delta(x) \int_{0}^{\infty} e^{-\tilde{z} t} \int p_{\tilde{a}}(0, x ; t, y) h(t, y) d y d t d x
\end{aligned}
$$

where $\tilde{a}$ and $\tilde{z}$ are the same as above, $r^{\prime}=-r q /(q-2)>0$, and

$$
h(t, y)=\theta_{r^{\prime}}(y)\left|V^{\prime \prime}\left(\omega_{t}^{\varepsilon}(y)\right)-V^{\prime \prime}\left(\bar{\omega}_{t}^{\varepsilon}(y)\right)\right|^{2 q / q-2}\left[\omega_{t}^{\varepsilon}(y)-\bar{\omega}_{t}^{\varepsilon}(y)\right]^{-1} .
$$

Since $V^{\prime \prime \prime}$ is bounded by assumption, this $h$ is uniformly bounded in $\mathbb{L}_{r^{\prime}}^{q}\left(\mathbb{R}_{+}^{d}\right)$, thus the proof of (iii) can be completed by repeating the argument above.

The results of this section are sufficient to select a uniformly convergent subsequence from $f_{\varepsilon}, \mathbb{D} f_{\varepsilon}$ and from $\nabla_{\varepsilon} \mathbb{D} f_{\varepsilon}$, too.

## 7. The Initial Distribution and the Limiting Equation

The a priori bounds summarized in the previous section allow us to select convergent subsequences from $f_{\varepsilon}$ and $\nabla_{\varepsilon} \mathbb{D} f_{\varepsilon}$ as $\varepsilon \rightarrow 0$, thus (3.2), the law of large numbers for $\mu_{\lambda, \varepsilon}$, is sufficient to pass to the limiting resolvent Eq. (3.7). The final identification of limit points of the resolvent, see (3.8) and (3.9), reduces then to the existence of the semigroup $\tilde{\mathbb{P}}^{t}$ defined by the limiting hydrodynamic Eq. (1.6).

The study of the inhomogeneous Gibbs states $\mu_{\lambda}$ will be based on an auxiliary dynamics having $\mu_{\lambda}$ as its only stationary state. For each $\lambda \in \Omega$ and $\sigma \in \Omega$ we define a Markov process $R(t)$ in $\Omega$ as the strong solution to

$$
\begin{equation*}
d R_{k}=\frac{1}{2}\left(\lambda_{k}-\partial_{k} H(R)\right) d t+d w_{k}, \quad R_{k}(0)=\sigma_{k}, \quad k \in \mathbb{Z}^{d} \tag{7.1}
\end{equation*}
$$

where $w_{k}, k \in \mathbb{Z}^{d}$ is a family of independent standard Wiener processes. Solutions to (7.1) can be constructed in the same, well known way, as to (1.4), see [5]. It is more remarkable that (7.1) is just the stochastic gradient dynamics associated with the energy function $H_{\lambda}=H(\sigma)-\sum \lambda_{k} \sigma_{k}$, thus $\mu_{\lambda}$ is a stationary measure of (7.1), provided that $\mu_{\lambda}$ does exist as a Gibbs state on $\Omega$.

Since $V$ is convex, it is quite easy to derive a priori bounds for (7.1). Using $2 z(x-2 z+y) \leqq x^{2}-2 z^{2}+y^{2}$ we obtain

$$
\begin{align*}
d R_{k}^{2} \leqq & \lambda_{k} R_{k} d t-(1-c) R_{k}^{2} d t+\frac{\alpha}{2} \sum_{|j-k|=1}\left(R_{j}^{2}-R_{k}^{2}\right) d t+d t+2 R_{k} d w_{k} \\
\leqq & (2-2 c)^{-2} \lambda_{k}^{2} d t-[c(1-c)+\alpha d] R_{k}^{2} d t \\
& +\frac{\alpha}{2} \sum_{|, j-k|=1} R_{j}^{2} d t+d t+2 R_{k} d w_{k} \tag{7.2}
\end{align*}
$$

We also have a fairly effective coupling for (7.1). Let $\bar{R}$ denote another solution with initial configuration $\bar{\sigma} \in \Omega$ and profile $\bar{\lambda} \in \Omega$, while the Wiener trajectories are the very same for both realizations. Like above, we obtain that $\delta_{k}=\left(R_{k}-\bar{R}_{k}\right)^{2}$ satisfies

$$
\begin{equation*}
d \delta_{k} / d t \leqq(2-2 c)^{-2}\left(\lambda_{k}-\bar{\lambda}_{k}\right)^{2}-[c(1-c)+\alpha d] \delta_{k}+\frac{\alpha}{2} \sum_{|j-k|=1} \delta_{j} \tag{7.3}
\end{equation*}
$$

In a stationary regime the left hand sides of (7.2) and (7.3) vanish in the mean, thus the following lemma can be used.

Lemma 12. Suppose that $0 \leqq b<1 / 2 d$, and $u, v \in \Omega$ satisfy

$$
\begin{equation*}
u_{k} \leqq v_{k}+b \sum_{i j-k j=1} u_{j} \quad \text { for } k \in \mathbb{Z}^{d} \tag{i}
\end{equation*}
$$

then $u_{k} \leqq \sum_{j \in \mathbb{Z}^{d}} J_{k-j} v_{j}$ for all $k$, where $J_{k} \geqq 0$ vanishes exponentially as $|k| \rightarrow \infty ; J$ is given by (7.4).

Proof. Since both $u_{k}$ and $v_{k}$ increase slower than any exponential rate, iterating (i) infinitely many times we obtain (ii) with

$$
\begin{equation*}
J_{k}=(2 \pi)^{-d} \int_{c_{2 \pi}(0)}\left[1-2 b \sum_{i=1}^{d} \cos \left\langle\omega, e_{i}\right\rangle\right]^{-1} \cos \langle\omega, k\rangle d \omega \tag{7.4}
\end{equation*}
$$

The positivity of $J$ is a direct consequence of its iterative construction, an exponential bound follows by integrating by parts.

All the information we need about $\mu_{\lambda}$ is summarized in

Proposition 1. For every $\lambda \in \Omega$ there exists a unique Gibbs state, $\mu_{\lambda}$, specified by (2.15) as a Borel probability on $\Omega$ such that
(i)

$$
\int \sigma_{k}^{2} \mu_{\lambda}(d \sigma) \leqq K \sum_{|j-k|=1} J_{k-j}\left(1+\lambda_{j}^{2}\right),
$$

where $K$ depends only on $c, \alpha, d$, and $b=\alpha[2 c(1-c)+2 \alpha d]^{-1}$. For $\lambda, \bar{\lambda} \in \Omega$ we have a joint distribution, $\mu_{\lambda, \bar{\lambda}}$ on $\Omega \times \Omega$ such that

$$
\begin{equation*}
\iint\left(\sigma_{k}-\bar{\sigma}_{k}\right)^{2} \mu_{\lambda, \bar{\lambda}}(d \sigma, d \bar{\sigma}) \leqq K \sum_{|j-k|=1} J_{k-j}\left(\lambda_{j}-\bar{\lambda}_{j}\right)^{2} \tag{ii}
\end{equation*}
$$

Consequently, if $\rho_{k}^{\lambda}=\int \sigma_{k} \mu_{\lambda}(d \sigma)$, then

$$
\begin{equation*}
\left|\rho_{k}^{\lambda}-F^{\prime}\left(\lambda_{k}\right)\right|^{2} \leqq K \sum_{|j-k|=1} J_{k-j}\left(\lambda_{k}-\lambda_{j}\right)^{2} \tag{iii}
\end{equation*}
$$

(iv)

$$
\int\left[\sum_{k \in \mathbb{Z}^{a}} \varphi_{k}\left(\sigma_{k}-\rho_{k}^{\lambda}\right)\right]^{2} \mu_{\lambda}(d \sigma) \leqq K \sum_{k \in \mathbb{Z}^{a}} \varphi_{k}^{2} .
$$

Finally, $F^{\prime}$ admits a Lipschitz continuous derivative, $F^{\prime \prime}$ is bounded, and it is bounded away from zero.

Proof. The basic idea is easy: since $V$ is convex, each $\mu_{\lambda}, \lambda \in \Omega$ belongs to the domain of Dobrushin uniqueness, cf. [7, 18]. In fact, we can follow a completely elementary argument. Suppose first that $\mu_{\lambda}$ has been defined already as a Gibbs state on $\Omega$, and let $\mathbb{G}^{\lambda}$ denote the generator of our auxiliary process, (7.1). The associated Dirichlet form can be written as

$$
\begin{equation*}
\int f_{1} \mathbb{G}^{\lambda} f_{2} d \mu_{\lambda}=-\frac{1}{2} \sum_{k \in \mathbb{Z} d} \int\left(\partial_{k} f_{1}\right) \partial_{k} f_{2} d \mu_{\lambda} \tag{7.5}
\end{equation*}
$$

Therefore, $\mu_{\lambda}$ is a stationary state of (7.1), thus (i) follows from (7.2) by Lemma 12. To prove (ii) we construct $\mu_{\lambda, \bar{\lambda}}$ first as a stationary state of the coupled evolution, then (ii) follows from (7.3) via Lemma 12. Since $\mu_{\lambda}$ is certainly well defined if $\lambda$ equals a constant outside of a finite volume, (i) and (ii) extend by continuity to all $\lambda \in \Omega$ involving also the existence and uniqueness of $\mu_{\lambda}$.

Suppose now that $\varphi: \Omega \rightarrow \mathbb{R}$ vanishes at an exponential rate, and let $\varphi(\sigma)$ $=\sum \varphi_{k} \sigma_{k}, F_{\varphi}(v)=\log \int \exp (v \varphi(\sigma)) \mu_{\lambda}(d \sigma)$, then

$$
\begin{gather*}
F_{\varphi}^{\prime}(v)=\int \varphi(\sigma) \exp \left(v \varphi(\sigma)-F_{\varphi}(v)\right) d \mu_{\lambda}=\int \varphi(\sigma) d \mu_{\lambda+v \varphi}  \tag{7.6}\\
F_{\varphi}(0)=\int\left[\sum \varphi_{k}\left(\sigma_{k}-\rho_{k}^{\lambda}\right)\right]^{2} \mu_{\lambda}(d \sigma) \tag{7.7}
\end{gather*}
$$

thus (ii) implies (iii), (iv), the uniform Lipschitz continuity of $F^{\prime}$ and the Lipschitz continuity of $F^{\prime \prime}$ by a direct calculation. To obtain a lower bound for $F^{\prime \prime}$, let
$\bar{R}_{n}=\sum\left(R_{k}-F^{\prime}(v)\right), \partial \bar{H}_{n}=\sum\left(\partial_{k} H-v\right)$, where both sums are over $C_{2 n}(0) \cap \mathbb{Z}^{d}$, and observe that

$$
\begin{align*}
F^{\prime \prime}(v) & =\lim _{n \rightarrow \infty}(2 n+1)^{-d} \int\left[\sum_{k \in C_{2 n}(0) \mathbb{Z}^{a}}\left(\sigma_{k}-F^{\prime}(v)\right)\right]^{2} \mu_{v}^{0}(d \sigma),  \tag{7.8}\\
d \bar{R}_{n}^{2} & =-\bar{R}_{n} \partial \bar{H}_{n} d t+\sum_{k \in C_{2 n}(0) \mathbb{Z}^{d}} 2 R_{n} d w_{k}+(2 n+1)^{d} d t \tag{7.9}
\end{align*}
$$

Starting (7.1) with initial distribution $\mu_{v}^{0}$, we obtain that $\int \bar{R}_{n} \partial \bar{H}_{n} d \mu_{v}^{o}=(1+2 n)^{d}$. Integrating by parts, we obtain an identity

$$
\int\left(\partial_{k} H-v\right)\left(\partial_{j} H-v\right) d \mu_{v}^{0}= \begin{cases}0 & \text { if }|j-k|>1  \tag{7.10}\\ 2 \alpha d+\int V^{\prime \prime}\left(\sigma_{k}\right) d \mu_{v}^{0} & \text { if } j=k \\ -\alpha & \text { if }|j-k|=1\end{cases}
$$

consequently

$$
\begin{aligned}
\int \bar{R}_{n}^{2} d \mu_{v}^{0} & \geqq 2 \int \bar{R}_{n} \hat{\partial} \bar{H}_{n} d \mu_{v}^{0}-\int \bar{H}_{n}^{2} d \mu_{v}^{0} \\
& \geqq 2(2 n+1)^{d}-(1+c+2 \alpha d)(2 n+1)^{d}+2 \alpha d(2 n-1)^{d}
\end{aligned}
$$

which proves $F^{\prime \prime}(v) \geqq 1-c$.
Now we turn to the existence problem of the limiting semigroup. In fact, we have two equations,

$$
\begin{gather*}
\partial_{t} \rho_{t}=\operatorname{div}\left[D\left(\rho_{t}\right) \operatorname{grad} \rho_{t}\right]  \tag{7.11}\\
2 F^{\prime \prime}\left(\lambda_{t}\right) \partial_{t} \lambda_{t}=\Delta \lambda_{t} \tag{7.12}
\end{gather*}
$$

they are related to each other by $\rho_{t}(x)=F^{\prime}\left(\lambda_{t}(x)\right)$ and $D(u)=1 / 2 F^{\prime \prime}(v)$ if $u=F^{\prime}(v)$. Suppose that $\rho_{t}$ and $\lambda_{t}$ are classical solutions, and $0<c_{1} \leqq D \leqq c_{2}$, then

$$
\begin{aligned}
\partial_{t}\left|\rho_{t}\right|_{r}^{2} & \leqq-2 c_{1}\left|\operatorname{grad} \rho_{t}\right|_{r}^{2}+2 r c_{2}\left|\rho_{t}\right|_{r}\left|\operatorname{grad} \rho_{t}\right|_{r} \\
& \leqq-c_{1}\left|\operatorname{grad} \rho_{t}\right|^{2}+\left(r c_{2} / c_{1}\right)^{2}\left|\rho_{t}\right|_{r}^{2}
\end{aligned}
$$

whence for all $r \geqq 0$ we obtain an energy inequality,

$$
\begin{equation*}
\left|\rho_{t}\right|_{r}^{2}+c_{1} \int_{0}^{t} \exp \left(c_{3} t-c_{3} s\right)\left|\operatorname{grad} \rho_{s}\right|_{r}^{2} d s \leqq \exp \left(c_{3} t\right)\left|\rho_{0}\right|_{r}^{2} \tag{7.13}
\end{equation*}
$$

where $c_{3}=\left(r c_{2} / c_{1}\right)^{2}$. The equation for $\operatorname{grad} \lambda_{t}$ is also self-adjoint, thus we have a second energy inequality, namely

$$
\begin{equation*}
\left|\operatorname{grad} \lambda_{t}\right|_{r}^{2}+c_{1} \int_{0}^{t} \exp \left(c_{3} t-c_{3} s\right)\left|\Delta \lambda_{s}\right|_{r}^{2} d s \leqq \exp \left(c_{3} t\right)\left|\operatorname{grad} \lambda_{0}\right|_{r}^{2} \tag{7.14}
\end{equation*}
$$

Proposition 2. For each $\lambda \in \mathbb{H}_{e}^{1}$ there exists a continuous trajectory, $\rho_{t} \in \mathbb{L}_{e}^{2}, t \geqq 0$ satisfying (2.20) with initial condition $\rho_{0}=\sigma \in \mathbb{H}_{e}^{1}$ given by $\sigma(x)=F^{\prime}(\lambda(x))$. Moreover, if $\lambda_{t}=\lambda_{t}(x)=E\left(\rho_{t}(x)\right)$, where $E$ is the inverse function of $F^{\prime}$, then $\lambda_{t} \in \mathbb{H}_{e}^{1}$, $\left|\operatorname{grad} \lambda_{t}\right|_{r}^{2} \leqq\left|\operatorname{grad} \lambda_{0}\right|_{r}^{2} \exp \left(c_{3} t\right)$ for all $t \geqq 0, r \geqq 0$, and there is no other weak solution having such properties.

Proof. For smooth initial data one can construct classical solutions by means of a Galerkin approximation, see [19]. If $\lambda_{0}$ varies in a bounded set of $\mathbb{H}_{e}^{1}$ then (7.13), (7.14) and the Riesz criterion of compactness show that $\rho_{t}$ remains in a strongly compact set of $\mathbb{L}_{e}^{2}$ for finite time. From (7.14) we see that $\rho_{t}$ is an equicontinuous function of time, thus the Arzela-Ascoli theorem implies the existence of weak solutions satisfying the desired $\mathbb{H}_{e}^{1}$-bound, see (7.13) and (7.14).

Suppose now that $\rho_{t}$ and $\bar{\rho}_{t}$ are weak solutions in the above sense, and $\rho_{0}=\bar{\rho}_{0}$. Let $\delta_{t}=\rho_{t}-\bar{\rho}_{t}$, and introduce $\omega_{t}$ by

$$
\begin{equation*}
\omega_{t}=\frac{1}{2} \int_{0}^{t} \operatorname{grad}\left[E\left(\rho_{s}\right)-E\left(\bar{\rho}_{s}\right)\right] d s \tag{7.15}
\end{equation*}
$$

Observe that $\operatorname{div} \omega_{t}=\delta_{t}$ in the weak sense. Indeed, for smooth $\varphi$

$$
\begin{gathered}
\int\left\langle\operatorname{grad} \varphi, \omega_{t}\right\rangle d x=\frac{1}{2} \int_{0}^{t} \int\left\langle\operatorname{grad} \varphi, \operatorname{grad}\left[E\left(\rho_{s}\right)-E\left(\bar{\rho}_{s}\right)\right]\right\rangle d x d s \\
\quad=-\frac{1}{2} \int_{0}^{t} \int[\Delta \varphi]\left[E\left(\rho_{s}\right)-E\left(\bar{\rho}_{s}\right)\right] d x d s=-\int \varphi(x) \delta_{t}(x) d x
\end{gathered}
$$

see (2.20), consequently

$$
\begin{aligned}
\partial_{t}\left|\omega_{t}\right|_{r}^{2} & =\int \theta_{r}(x)\left\langle\omega_{t}, \operatorname{grad}\left[E\left(\rho_{t}\right)-E\left(\bar{\rho}_{t}\right)\right]\right\rangle d x \\
& \leqq-2 c_{1}\left|\delta_{t}\right|_{r}^{2}+2 c_{2} r\left|\omega_{t}\right|_{r}\left|\delta_{t}\right|_{r} \leqq\left(c_{3} / 2\right)\left|\omega_{t}\right|_{r}^{2}
\end{aligned}
$$

whence $\omega_{t}=\delta_{t}=0$ by the Gronwall lemma.
Now we are in a position to complete the proof of the main result. Consider first the scaled distributions $\mu_{\lambda, \hat{\varepsilon}}$ corresponding to $\mu_{\lambda}$ with $\lambda_{k}=I_{\varepsilon} \lambda(\varepsilon k)$. (iii) of Proposition 1 implies (2.22), while (iv) and the Markov inequality show that $\varphi(\sigma)$ converges also in probability to $\int \varphi(x) \rho_{0}(x) d x$. In view of (i), $\mu_{\lambda, \varepsilon}$ is tight in the weak topology of $\mathbb{L}_{e}^{2}$, thus (2.23) extends from $\mathbb{C}_{0}\left(\mathbb{L}_{e}^{2}\right)$ even to $\mathbb{C}_{w}(\Sigma)$ by the Stone-Weierstrass approximation theorem, where $\Sigma$ is a union of the increasing balls $B_{n} \subset \mathbb{L}_{e}^{2}$ such that $\mu_{\lambda, \varepsilon}\left(B_{n}\right) \rightarrow 1$ uniformly in $\varepsilon>0$ as $n \rightarrow \infty$; thus we have (3.2), (3.3), and we can also pass to (3.7). The uniqueness of the limiting resolvent Eq. (3.7) follows from the existence of $\mathbb{P}^{t}$ as a strongly continuous contraction semigroup in $\mathbb{C}_{w}\left(\mathbb{H}_{e}^{1}\right)$, see Proposition 2. Some more technical details of the proof are given in the next section.

## 8. Proof of Theorems 1 and 2

First we prove a variant of Theorem 2.
Theorem 3. Suppose that $\lambda \in \mathbb{H}_{e}^{1}$ and $g^{\varepsilon} \in \mathbb{D}_{L}\left(\Omega_{\varepsilon}\right)$ for each $\varepsilon>0$ such that the norms (6.1)-(6.3) remain bounded as $\varepsilon \rightarrow 0$. If we have some $g \in \mathbb{D}_{s}\left(\mathbb{L}_{e}^{2}\right)$ such that

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \int g^{\varepsilon}(\sigma) \mu_{\lambda, \varepsilon}(d \sigma)=\tilde{g}(\lambda) \quad \text { for } \quad \lambda \in \mathbb{H}_{e}^{1} \tag{i}
\end{equation*}
$$

and $\rho_{t} \in \mathbb{H}_{e}^{1}, t \geqq 0$ solves $(2.20)$ with $\rho_{0}(x)=F^{\prime}(\lambda(x))$, then
(ii)

$$
\lim _{\varepsilon \rightarrow 0} \int \mathbb{P}_{\varepsilon}^{t} g^{\varepsilon}(\sigma) \mu_{\lambda, \varepsilon}(d \sigma)=\tilde{g}\left(\lambda_{t}\right)
$$

where $\lambda_{t} \in \mathbb{I}_{e}^{2}$ is defined by $\rho_{t}(x)=F^{\prime}\left(\lambda_{t}(x)\right) . \quad \square$
Proof. In view of (i) of Proposition 1, for every increasing sequence of balls $B_{n}$ of $\mathbb{L}_{e}^{2}$ we have another sequence of balls, $\bar{B}_{n} \subset \mathbb{L}_{e}^{2}$ such that if $\Sigma=\cup B_{n}, \bar{\Sigma}=\cup \bar{B}_{n}$, then $\lambda \in \Sigma$ implies $\mu_{\lambda, \varepsilon}(\bar{\Sigma})=1$ for all $\varepsilon>0$. The convention $g^{\varepsilon}(\sigma)=g^{\varepsilon}\left(I_{\varepsilon} \sigma\right)$ extends $g^{\varepsilon}$ to $\mathbb{L}_{e}^{2}$ in a trivial way. Consider the functions $f_{\varepsilon}: \mathbb{L}_{e}^{2} \times(0, \infty) \rightarrow \mathbb{R}$,

$$
f_{\varepsilon}(\sigma, z)=\int_{0}^{\infty} e^{-z t} \mathbb{P}_{\varepsilon}^{t} g^{\varepsilon}(\sigma) d t
$$

$\mathbb{D} f_{\varepsilon}: \mathbb{L}_{e}^{2} \times(0, \infty) \rightarrow \mathbb{L}_{-e}^{2}$ and $\nabla_{\varepsilon} \mathbb{D} f_{\varepsilon}: \mathbb{L}_{e}^{2} \times(0, \infty) \rightarrow \mathbb{L}_{-e}^{2}$. Lemma 9 and Lemma 11 imply that each of them is a bounded and equicontinuous function of $(\sigma, z) \in B$ $\times\left[z_{1}, z_{2}\right]$ if $B$ is a ball of $\mathbb{L}_{e}^{2}$, and $0<z_{1}<z_{2}<\infty$; therefore the Arzela-Ascoli theorem applies. We can select a subsequence, $\varepsilon_{n} \rightarrow 0$ such that $f_{\varepsilon}(\sigma, z) \rightarrow f(\sigma, z)$, $\mathbb{D} f_{\varepsilon}(\cdot, \sigma, z) \rightarrow h_{1}(\cdot, \sigma, z), \nabla_{\varepsilon} \mathbb{D} f_{\varepsilon}(\cdot, \sigma, z) \rightarrow h_{2}(\cdot, \sigma, z)$ along $\varepsilon_{n}$ for each $\sigma \in \bar{\Sigma}$ and $z>0$, and the convergence is uniform on compacts of type $\bar{B}_{m} \times\left[z_{1}, z_{2}\right] ; \mathbb{D} f_{\varepsilon}$ and $\nabla_{\varepsilon} \mathbb{D} f_{\varepsilon}$ converge in the topology of $\mathbb{L}_{-e}^{2}$. Moreover, $f, h_{1}$ and $h_{2}$ are continuous on each compact $\bar{B}_{m} \times\left[z_{1}, z_{2}\right]$, consequently the definition of functional derivatives implies that $f \in \mathbb{D}_{s}(\bar{\Sigma})$ and $h_{1}=\mathbb{D} f$. Similarily, as $\mathbb{D} f_{\varepsilon}$ and $\nabla_{\varepsilon} \mathbb{D} f_{\varepsilon}$ converge simultaneously, we see that $h_{1}$ is weakly differentiable, and $h_{2}=\operatorname{grad} h_{1}$. Since $\nabla_{\varepsilon} \lambda$ converges strongly to grad $\lambda$, Proposition 1 yields

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \int f_{\varepsilon_{n}}(\sigma, z) \mu_{\lambda, \varepsilon_{n}}(d \sigma)=f\left(\rho_{0}, z\right) \quad \text { if } z>0, \quad \lambda \in \Sigma \tag{8.1}
\end{equation*}
$$

where $\rho_{0}(x)=F^{\prime}(\lambda(x))$, while

$$
\begin{gather*}
\lim _{n \rightarrow \infty} \iint\left\langle\nabla_{\varepsilon_{n}} \lambda(x), \nabla_{\varepsilon_{n}} \mathbb{D} f_{\varepsilon_{n}}(x, \sigma, z)\right\rangle d x \mu_{\lambda, \varepsilon_{n}}(d \sigma) \\
\quad=\int\left\langle\operatorname{grad} \lambda(x), \operatorname{grad} \mathbb{D} f\left(x, \rho_{0}, z\right)\right\rangle d x \tag{8.2}
\end{gather*}
$$

for all $z>0$ and $\lambda \in \Sigma \cap \mathbb{H}_{e}^{1}$. This means that we can pass to the limiting resolvent Eq. (3.7), thus the uniqueness of solutions to (7.3)-(7.4) implies that

$$
f\left(\rho_{0}, z\right)=\int_{0}^{\infty} e^{-z t} \tilde{g}\left(\lambda_{t}\right) d t
$$

thus (iii) of Lemma 10 implies the equicontinuity of $\int \mathbb{P}_{\varepsilon}^{t} g^{\varepsilon} d \mu_{\lambda, \varepsilon}$ as a function of time, which completes the proof.

To conclude Theorem 2 from Theorem 3, we have to show that the family of time evolved measures, $\mu_{\lambda, \varepsilon} \mathbb{P}_{\varepsilon}^{\tau}, \varepsilon>0$, is a tight one.

Proof of Theorem 2. Let $h(t)=\int \mathbb{P}_{\varepsilon}^{t}|\sigma|_{r}^{2} \mu_{\lambda, \varepsilon}(d \sigma)$, then

$$
h^{\prime}(t)=2 \iiint\left(\Delta_{\varepsilon} \lambda(x)\right) p_{a}(0, x ; t, y) \theta_{r}(y) \omega_{\imath}^{\varepsilon}(y) d y d x d \mu_{\lambda, \varepsilon}
$$

where $a(t, y)=V^{\prime \prime}\left(\omega_{t}^{e}(y)\right)$. Lemma 10, Proposition 1 and the Schwarz inequality imply that if $r>0$ and $r \varepsilon \leqq 1$ then

$$
\int_{t}^{t+1}\left[h(t)+\left(h^{\prime}(t)\right)^{2}\right] d t \leqq C_{r}(\lambda, t), \quad t \geqq 0
$$

where the bound does not depend on $\varepsilon>0$. Therefore, again by the Schwarz inequality, $h(t) \leqq h(s)+C_{r}^{1 / 2}$ if $t<s \leqq t+1$, thus

$$
\begin{equation*}
\int \mathbb{E}\left[\left|\omega_{t}^{2}\right|_{r}^{2} \mid \omega_{0}^{\varepsilon}=\sigma\right] \mu_{\lambda, \varepsilon}(d \sigma) \leqq C_{r}(\lambda, t)+C_{r}^{1 / 2}(\lambda, t) \tag{8.3}
\end{equation*}
$$

This means that we can select a ball, $B_{\lambda, t}$ such that $\mu_{\lambda, \varepsilon} \mathbb{P}_{\varepsilon}^{t}\left(B_{\lambda, t}\right)$ is arbitrarily close to one for all $\varepsilon>0$, which completes the proof by the Stone-Weierstrass theorem.

The following statement is slightly stronger than Theorem 1.
Theorem 4. Let $g \in \mathbb{D}_{w}^{\prime}\left(\mathbb{L}_{e}^{2}\right)$ and suppose that $\omega_{0}^{\varepsilon} \in \Omega_{\varepsilon}$ converges weakly on $\mathbb{L}_{e}^{2}$ to some $\rho_{0} \in \mathbb{H}_{e}^{1}$, then $\mathbb{P}_{\varepsilon}^{t} g\left(\omega_{0}^{\varepsilon}\right) \rightarrow g\left(\rho_{t}\right)$ as $\varepsilon \rightarrow 0$, for each $t>0$, where $\rho_{t}$ solves (2.20) with initial condition $\rho_{0}$.

Proof. In view of (ii) of Lemma 11, for every ball $B$, and for each $\beta>0$ there exist a $\gamma>0$ and a finite sequence, $\varphi_{1}, \varphi_{2}, \ldots, \varphi_{n}$ from $\mathbb{L}_{-e}^{2}$ such that

$$
\begin{equation*}
\left|\mathbb{P}_{\varepsilon}^{t} g(\sigma)-\mathbb{P}_{\varepsilon}^{t} g\left(I_{\varepsilon} \rho_{0}\right)\right|<\beta \text { if } \sigma \in \Omega_{\varepsilon}, \sigma-\rho_{0} \in B,\left|\varphi_{k}(\sigma)-\varphi_{k}\left(\rho_{0}\right)\right|<\gamma \tag{8.4}
\end{equation*}
$$

for $k=1,2, \ldots, n$. Suppose first that $\rho_{0}=F^{\prime}(\lambda)$, and $\sigma$ is distributed by $\mu_{\lambda, \varepsilon}$; by the law of large numbers, see Proposition 1, it follows that

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0}\left[\int \mathbb{P}_{\varepsilon}^{t} g(\sigma) \mu_{\lambda, \varepsilon}(d \sigma)-\mathbb{P}_{\varepsilon}^{t} g\left(I_{\varepsilon} \rho_{0}\right)\right]=0 \tag{8.5}
\end{equation*}
$$

On the other hand, if $\sigma=\omega_{0}^{e}$, then $\varphi\left(\omega_{0}^{\varepsilon}\right) \rightarrow \varphi\left(\rho_{0}\right)$ for each $\varphi \in \mathbb{L}_{-e}^{2}$, thus $\omega_{0}^{e}$ is bounded in $\mathbb{L}_{e}^{2}$, consequently

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0}\left[\mathbb{P}_{\varepsilon}^{t} g\left(\omega_{0}^{\varepsilon}\right)-\mathbb{P}_{\varepsilon}^{t} g\left(I_{\varepsilon} \rho_{0}\right)\right]=0 \tag{8.6}
\end{equation*}
$$

which reduces the problem to Theorem 2.

Remark. The weak equicontinuity property expressed by (8.4) allows us to extend both Theorem 2 and Theorem 4 to all initial data, $\rho_{0}=F^{\prime}(\lambda)$ such that (2.20) is uniquely solved. It is not really interesting, but it seems to be nontrivial to decide if $g \in \mathbb{D}_{w}^{\prime}$ could be replaced by $g \in \mathbb{C}_{w}$ in Theorem 4.

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