

Two Results on Intersection Graphs of Polygons

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Abstract. Intersection graphs of convex polygons inscribed to a circle, so called polygon-circle graphs, generalize several well studied classes of graphs, e.g., interval graphs, circle graphs, circular-arc graphs and chordal graphs. We consider the question how complicated need to be the polygons in a polygon-circle representation of a graph.

Let $\text{cmp}(n)$ denote the minimum k such that every polygon-circle graph on n vertices is the intersection graph of k -gons inscribed to the circle. We prove that $\text{cmp}(n) = n - \log_2 n + o(\log_2 n)$ by showing that for every positive constant $c < 1$, $\text{cmp}(n) \leq n - c \log n$ for every sufficiently large n , and by providing an explicit construction of polygon-circle graphs on n vertices which are not representable by polygons with less than $n - \log n - 2 \log \log n$ corners. We also show that recognizing intersection graphs of k -gons inscribed in a circle is an NP-complete problem for every fixed $k \geq 3$.

1 Introduction

Intersection graphs of geometric objects, namely in the plane, are intensively studied both for their practical motivations and for interesting structural and algorithmic properties. Many hard (NP-complete in general) optimization problems become polynomially solvable when restricted to various classes of intersection graphs. Probably the oldest and simplest of these are interval graphs, intersection graphs of intervals on a line [4], whose structure is well understood, they are recognizable in linear time, and for which problems like clique, independent set, dominating set, chromatic number and many more are tractable. On the other end of the spectrum are string graphs, intersection graphs of arc-connected sets in the plane, which are hard to recognize [8], and whose recognition was only recently shown decidable [12,15] and then even more surprisingly in NP [16].

Geometric intersection graphs also provide a special kind of graph visualization. Vertices are represented as geometric objects and adjacencies are visualized by nonempty intersections. Overlapping regions are illustrative and enhance the visual understanding of the represented graph. String graphs are closely related to another graph drawing invariant, the *crossing number*, i.e., the minimum number of edge crossings in a drawing

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of a graph. Abstract topological graphs (cf. [10]) are graphs with specified pairs of edges which are allowed to cross in a feasible drawing. In this setting it may happen that multiple edge crossings occur in every feasible drawing, and an abstract topological graph may actually require exponential number of crossing points [11]. The crossing number of abstract topological graphs is closely related to the number of crossing points in representations of string graphs as intersection graphs of curves, and in fact in this way the decidability and NP-membership of string graphs were tackled.

Several well studied classes of graphs which directly generalize interval graphs involve geometric objects bound to a circle. Among these are *circle graphs*, intersection graphs of chords of a circle, and *circular arc graphs*, intersection graphs of intervals on the circle. Both these classes are recognizable in polynomial time (cf. [1,3,13] for circle graphs, [17,2] for circular arc graphs). A common generalization of these two are *polygon-circle graphs*, intersection graphs of convex polygons inscribed to the circle. This class was first suggested by M. Fellows [personal communication with the first author] in 1988, when it was pointed out that this class of graphs is closed under taking induced minors. Under a different name of *spider graphs*, polygon-circle graphs appeared in [7], where a polynomial time recognition algorithm was announced. Somewhat surprisingly, the algorithm was never published, and this fact creates certain doubts about its correctness. A structural property of graph classes which many intersection graphs possess is *near-perfectness* in the sense of Gyarfás [5]. A graph class is near-perfect if the chromatic number of each of its graphs is bounded by a function of the clique number of the graph. (For perfect graphs this function is identity, and from here the notion originates.) Polygon-circle graphs are near-perfect as shown in [9], and the bound presented therein improved the up to that date best bound for circle graphs and has not been improved since.

In the current paper we pay closer attention to the question of how complicated should be the polygons representing the vertices of a polygon-circle graph with n vertices. One can easily see that n -gons always suffice (hence no exponential surprises as in the case of string graphs), which means that polygon-circle graph recognition is definitely in NP. It is conceivable, however, that polygons with less corners would suffice. To be able to precisely formulate this question, we define the *complicacy* of a graph G as the minimum k such that G is the intersection graph of convex k -gons inscribed to a circle, and we denote this invariant by $\text{cmp}(G)$ (we set $\text{cmp}(G) = \infty$ if G is not a polygon-circle graph). We further define $\text{cmp}(n)$ to be the maximum of $\text{cmp}(G)$ over all polygon-circle graphs with n vertices. The main result in this direction is the following (here and throughout the paper, all logarithms are base 2):

Theorem 1. *We have $\text{cmp}(n) = n - \log n + o(\log n)$.*

The lower and upper bounds are proved separately in the next two sections. In the last section we consider the computational complexity of determining the complicacy of a graph with the following result:

Theorem 2. *For every fixed finite $k \geq 3$, it is NP-complete to decide whether $\text{cmp}(G) \leq k$ holds for an input graph G .*

This result, which answers an open problem listed at J. Spinrad's web page [14], is not in contradiction with the announced algorithm of Koebe for recognition of polygon-

circle graphs (i.e., deciding $\text{cmp}(G) < \infty$), but it definitely sheds new light on the problem of recognizing polygon-circle graphs. Note also that for $k = 2$, $\text{cmp}(G) \leq 2$ if and only if G is a circle graph, a polynomially decidable question.

2 Technical Notions and Observations

Throughout the paper we use small letters as a, b, u, v, \dots for vertices of the graph under consideration, and if R is a representation by polygons, R_v denotes the polygon representing vertex v . However, in figures, to avoid multiple subscripts, we will usually omit the symbol R . We assume that the bounding circle is fixed and whenever we speak about polygons, we automatically assume that the polygons are convex and have all corners placed on the circle.

If P is a polygon, then the connected parts obtained from the bounding circle by deleting the corners of P are referred to as the P -segments. If two polygons represent nonadjacent vertices, they must be disjoint and hence all corners of one of them lie within the same segment determined by the other one, and vice versa. In the following technical definition we assume that all polygons under consideration are disjoint.

Definition 1. We say that polygon P blocks polygon Q from polygon S if the corners of Q lie in a different P -segment than the corners of S . If a set S of polygons is such that none of them blocks any other two polygons from each other, we say that the polygons are positioned around the circle.

See Figure 1 for an illustrative example of blocking polygons, and a set of polygons positioned around the circle. Next we make the first simple but useful observation.

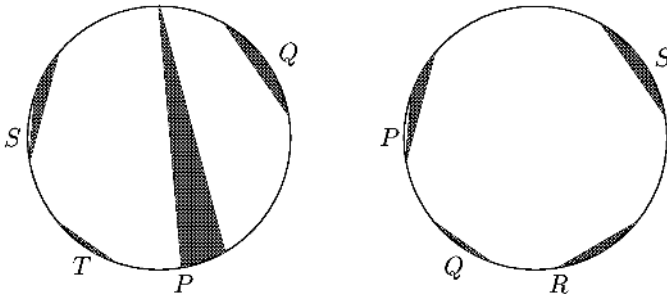


Fig. 1. In the left, polygon P blocks polygon Q from polygons S and T , in the right, all four polygons are positioned around the circle.

Proposition 1. In any representation R of the cycle C_{2k} with $2k$ vertices u_1, u_2, \dots, u_{2k} , the polygons $R_{u_{2i}} : i = 1, 2, \dots, k$ are positioned around the circle. If W'_k is the graph obtained from C_{2k} by adding a vertex v adjacent to $u_{2i}, i = 1, 2, \dots, k$ (i.e., W'_k is the wheel W_k with each rim edge subdivided), then R_v has at least k corners and $\text{cmp}(W'_k) \geq k$ (in fact, the complicacy of W'_k equals k).

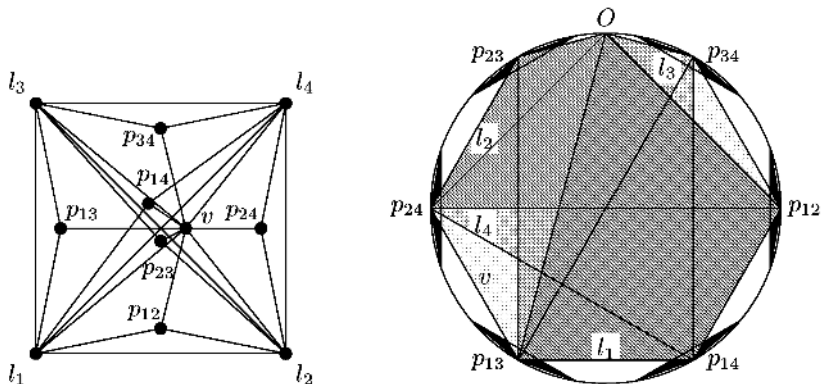


Fig. 2. An example of the lower bound construction for $\ell = 1$ and $n = 11$. We write simply p_{13} for $p_{\{1,3\}}$ etc.

Proof. For any three (even indexed) vertices u_{2i}, u_{2j}, u_{2h} of C_{2k} , there exists a path connecting u_{2j} and u_{2h} which does not contain any neighbor of u_{2i} . The union of the polygons representing vertices of this path is a connected subset of the disk bounded by the base circle, and hence (by the Jorda curve theorem) $R_{u_{2j}}$ must not be blocked from $R_{u_{2h}}$ by $R_{u_{2i}}$.

For the wheel graph W'_k , it follows that R_v must have at least k corners, to intersect all $R_{u_{2i}}, i = 1, 2, \dots, k$.

3 Complicacy of Representations – The Lower Bound

Theorem 3. For n large enough, we have $\text{cmp}(n) \geq n - \log n - 2 \log \log n$.

Proof. The proof is by constructing graphs of large complicacy by an explicit construction. Suppose n is large enough (how large will follow from the calculations in the proof). Let ℓ be the uniquely defined integer such that

$$1 + 2\ell + \binom{2\ell}{\ell} < n \leq 1 + 2(\ell + 1) + \binom{2\ell + 2}{\ell + 1}.$$

We construct the graph $G = (V, E)$ with vertex set

$$V = \{v\} \cup L \cup P,$$

where vertex v is adjacent to all other vertices, L is a clique of size $2\ell + 2$, and P is an independent set whose vertices are indexed by distinct $(\ell + 1)$ -element subsets of L . These indices will determine the adjacencies between vertices of P and L as follows. If $p_a \in P$ (with $a \subset L, |a| = \ell + 1$), we make p_a adjacent to all $x \in a$ and to no other vertices of L . (Note that G is not determined uniquely, it depends on the choice of the sets used for indexing the vertices from P . Any choice of distinct indices works.)

We claim that G is a polygon-circle graph and that $\text{cmp}(G) \geq |P|$. For the first part of the claim, choose a point O on the circle and position the polygons corresponding to the vertices of P around the circle (so that they do not block O from one another). Choose one corner of each of them as its reference point and represent each vertex x of L by the convex hull of the reference points of the vertices of P adjacent to x and of O . By making O a corner of each R_x we guarantee that every two polygons $R_u, R_w, u, w \in L$ intersect (L is a clique). Finally R_v will be the convex hull of O and the reference points of all polygons representing vertices of P . (Note that the auxiliary point O may not be necessary, e.g., in the case when for every two vertices in L , P contains a vertex adjacent to both of them.)

To argue that $\text{cmp}(G)$ is large, consider an optimal representation R of G . Note first that for $n > 5$ we have $\ell \geq 1$ and hence $\binom{2\ell}{\ell} \geq 2$. This means that $n > 2\ell + 3$ and indeed G contains all vertices of L .

The key observation is that the polygons $R_p, p \in P$ must be positioned around the circle. For suppose this is not the case, say R_{p_b} blocks R_{p_a} from R_{p_c} for some $a, b, c \in L$. Since these subsets are different but of equal size, there must be an $x \in a \setminus b$ and a $y \in c \setminus b$. By the definition of G , R_x intersects R_a and R_y intersects R_c , but none of R_x, R_y intersects R_b . But that means that R_b blocks R_x from R_y and these two polygons cannot intersect each other (though x and y belong to the clique L).

To intersect all polygons representing vertices of P , R_v must have at least $|P|$ corners, and hence $\text{cmp}(G) \geq |P| = n - 2\ell - 3$. The rest is a simple calculation.

Assume for contradiction that $\ell > \frac{\log n}{2} + \log \log n - \frac{3}{2}$. Then

$$n > \binom{2\ell}{\ell} > \frac{2^{2\ell}}{2\ell + 1} > \frac{n \log^2 n}{8(\log n + 2 \log \log n - 2)} > n$$

for large enough n (since $\lim_{n \rightarrow \infty} \frac{\log^2 n}{8(\log n + 2 \log \log n - 2)} = \infty$), a contradiction. Therefore (for every large enough n), $\ell \leq \frac{\log n}{2} + \log \log n - \frac{3}{2}$ and

$$\text{cmp}(G) \geq |P| = n - 2\ell - 3 \geq n - \log n - 2 \log \log n$$

as claimed.

4 Complicacy of Representations – The Upper Bound

Theorem 4. *For every positive constant $c < 1$, there exists an n_0 such that $\text{cmp}(n) \leq n - c \log n$ for every $n > n_0$.*

Proof. Let $G = (V, E)$ be a graph on n vertices and let $\text{cmp}(G) = k \geq 4$. Consider a polygon-circle representation R of G such that no two polygons share a corner and such that every polygon has at most k corners (this can be always achieved by splitting the corners). Let our representation have the minimum total number of corners among all such representations. Choose a vertex $v \in V$ such that R_v has k corners, and denote its corners v^1, v^2, \dots, v^k as they appear clockwise around the circle.

Based on this representation R , define A to be the set of vertices x such that R_x has all corners within two consecutive R_v -segments, i.e., such that R_x intersects R_v only in

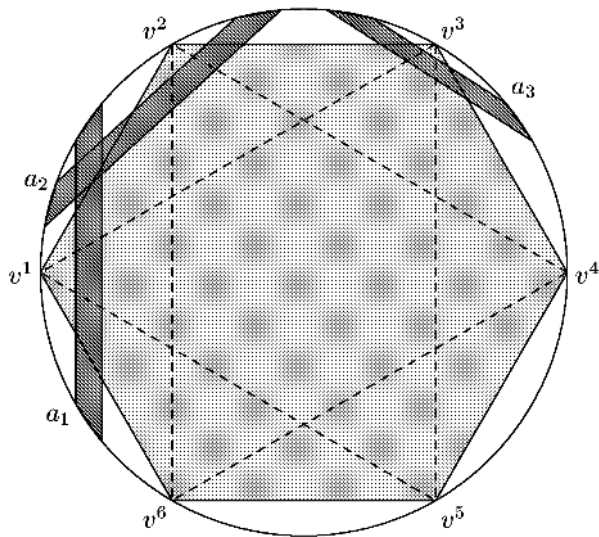


Fig. 3. Illustration to the choice of representatives of index classes.

the triangle $v^{i-1}v^i v^{i+1}$, for some i . For $x \in A$, denote this i by $j(x)$ and call it the *index* of x . We can see that for every i , there exists an $x \in A$ of index i . For if such a vertex did not exist for some i , we could reduce the number of corners in the representation by deleting the triangle $v^{i-1}v^i v^{i+1}$ from R_v , contradicting the choice of R .

Now assume that R' minimizes $\sum_{x \in A} j(x)$ among all representations with the same central polygon R_v , with the same total number of corners and with the same set A (when defined as above) as R . For the sake of simplicity we call R' again just R .

For every i , choose one vertex as a representative of the vertices of index i , and call it a_i . As argued above, a_i is well defined for every i . The intersection graph of the polygons $R_{a_i}, i = 1, 2, \dots, k$ is either a cycle or a disjoint union of paths, since a_i can only intersect a_{i-1} and/or a_{i+1} . We denote A_1 the set of those a_i that have no neighbors among the other a_h 's, and $A_2 = \{a_1, a_2, \dots, a_k\} \setminus A_1$. We then denote $B = (V \setminus \{v\}) \setminus (A_1 \cup A_2)$ and B_1 the set those vertices of B which are adjacent to at least one vertex of A_1 .

Next we claim that every two vertices of A_1 have different sets of neighbors. For suppose that $\{x|xa_i \in E\} = \{x|xa_j \in E\}$ for some $j < i$. Then the polygons representing the neighbors of a_i intersect one side of R_{a_j} , and hence both R_{a_i} and R_{a_j} could be replaced by two parallel chords (digons) placed close enough to this side. This would result in a new representation of the same graph, with the same position of R_v and the same set A , but with a strictly smaller sum of the indices of the vertices of A , contradicting the choice of R . See an illustrative example in Figure 4.

The immediate but very important consequence is that

$$|A_1| \leq 2^{|B_1|},$$

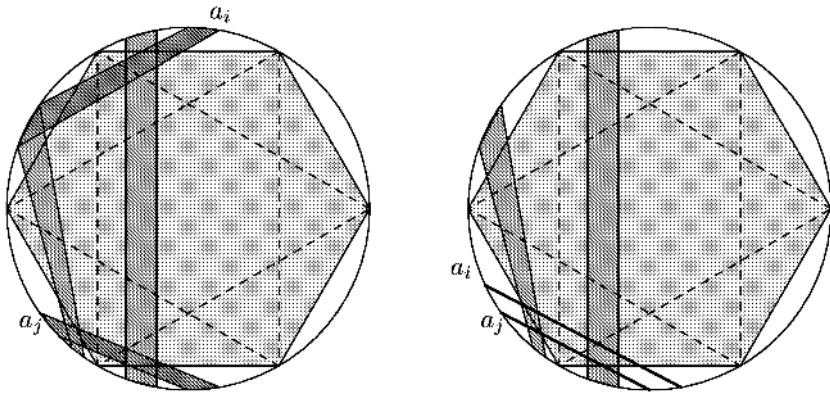


Fig. 4. Illustration to reducing the sum of indices of the A vertices.

since v is a common neighbor of all vertices in A_1 , and on the other hand no vertex of A_1 is adjacent to any other vertex of $A_1 \cup A_2$.

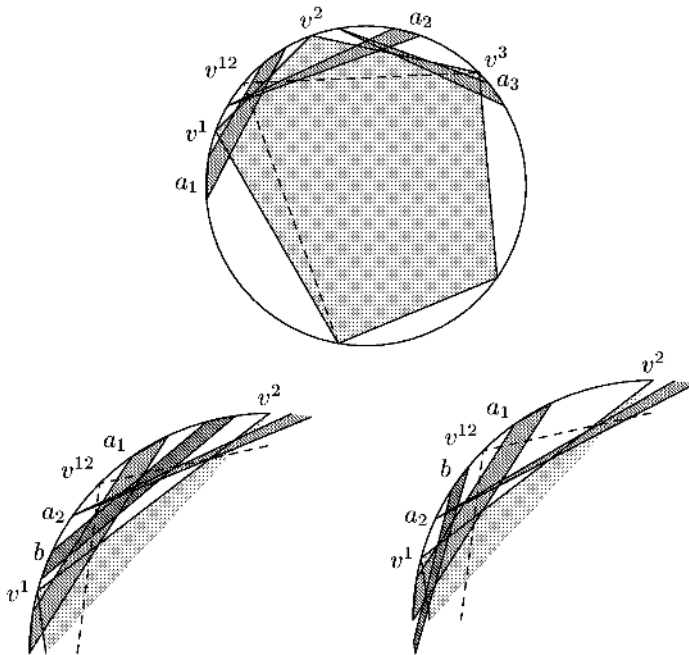


Fig. 5. Illustration to the construction of B_2 , the blocking set for A_2 .

Finally we attend to vertices of A_2 . Consider the example in Figure 5. If R_{a_1} and R_{a_2} intersect, they must intersect in the area bounded by the v^1v^2 side of R_v and the corresponding R_v -segment. Choose a point v^{12} in this segment between the leftmost corner of a_2 and the rightmost corner of a_1 . If we now replaced the central polygon R_v by the convex hull of v^{12}, v^3, \dots, v^k (i.e., the corners v^1 and v^2 are replaced by v^{12}), the new R_v (denoted by dashed lines in the figure) would still intersect both R_{a_1} and R_{a_2} , but the total number of corners would decrease. Since this is impossible by the choice of R , the new collection of polygons does not represent G anymore. There are only two possible reasons. Either the new R_v intersects a polygon R_b which is not supposed to be intersected (as in Figure 5 bottom left), or the new R_v loses intersection with some R_b that it previously crossed (as in Figure 5 bottom right). In the former case, R_b would lie fully within the segment v^1v^2 , in the latter one, $b \in A$ and its index is $j(b) = 1$ (or, symmetrically, $j(b) = 2$). In any case, we choose one such b and call it a witness for $(1, 2)$. Similarly, we choose a witness for every $(i, i + 1)$ such that $R_{a_i} \cap R_{a_{i+1}} \neq \emptyset$, and denote by B_2 the set of witnesses constructed in this way. By the construction, $B_2 \subset B$. It may happen, though, that one vertex of B_2 is a witness for two pairs (a witness of the latter type and index i could have been chosen both for the pair $(i - 1, i)$ and for $(i, i + 1)$). Given the fact that a path of t consecutive vertices from A_2 would involve $t - 1$ pairs, such a path would give rise to at least $\frac{t-1}{2}$ distinct witnesses, and we obtain the following inequality:

$$|A_2| \leq 3|B_2|.$$

(Note here, that B_1 and B_2 are not necessarily disjoint.)

Now we summarize

$$k = \text{cmp}(G) = |A_1| + |A_2| \leq 2^{|B_1|} + 3|B_2| \leq 2^{n-k} + 3(n - k)$$

(the last inequality follows from the fact that $A_1 \cup A_2 \cup B_1 \subset V$ and $A_1 \cup A_2 \cup B_2 \subset V$, while in each case the three summands are pairwise disjoint), and hence

$$2^n \geq 2^k(4k - 3n).$$

For $k > n - c \log n$ ($0 < c < 1$), we would get

$$2^n > 2^{n-c \log n}(4(n - c \log n) - 3n) = 2^n \frac{n - 4c \log n}{n^c} > 2^n$$

for every $n > n_0$ for some n_0 , as $\lim_{n \rightarrow \infty} \frac{n}{n^c} = \infty$ and $\lim_{n \rightarrow \infty} \frac{4c \log n}{n^c} = 0$. Which is the final long worked for contradiction.

The proof of Theorem 1 is now at hand. Consider the difference $f(n) = \text{cmp}(n) - n + \log n$. On one hand, Theorem 3 states that $f(n) \geq -2 \log \log n = o(\log n)$. On the other hand, Theorem 4 yields that for every $\varepsilon > 0$, $f(n) < \varepsilon \log n$ for every large enough n (by setting $c = 1 - \varepsilon$), and hence $f(n) = o(\log n)$.

5 Computational Complexity

We first restate Theorem 2 in a slightly stronger form:

Theorem 5. *For every fixed $k \geq 3$, it is NP-complete to decide if $\text{cmp}(G) \leq k$ for an input graph G , even if G is promised to have complicacy at most $k + 1$.*

Proof. We reduce from the following hypergraph coloring problem: Given a set \mathcal{T} of triples over a base set X , decide if the elements of X can be colored by three colors so that every triple $T \in \mathcal{T}$ receives all three colors. This problem is NP-complete as it contains the 3-edge colorability of cubic graphs as a subproblem, the latter being NP-complete by Holyer [6]. (By restricting to 3-edge colorability of bridgeless graphs, we may assume that X is colorable by 2 colors so that no triple $T \in \mathcal{T}$ is monochromatic.)

Given such a \mathcal{T} , we construct a graph $G_{\mathcal{T}} = (V, E)$ as follows. The vertex set will consist of a cycle of length $2k$ on vertices u_1, u_2, \dots, u_{2k} , a pair of vertices a_x, b_x for every $x \in X$, and a vertex c_T for each triple $T \in \mathcal{T}$. The c vertices form a clique and each of them is adjacent to all u vertices with even subscripts, to all b vertices, and to those a vertices which correspond to x 's belonging to the particular triple. The b vertices are further adjacent to their corresponding a vertices and to u_2, u_4, u_6 . Formally

$$\begin{aligned} V &= \{u_i | i = 1, 2, \dots, 2k\} \cup \{a_x, b_x | x \in X\} \cup \{c_T | T \in \mathcal{T}\} \\ E &= \{u_1 u_2, u_2 u_3, \dots, u_{2k} u_1\} \cup \{a_x b_x | x \in X\} \cup \{b_x u_i | x \in X, i = 2, 4, 6\} \\ &\cup \{b_x b_y | x, y \in X\} \cup \{c_T a_x | x \in T \in \mathcal{T}\} \cup \{c_T b_x | T \in \mathcal{T}, x \in X\} \\ &\cup \{c_T c_S | T, S \in \mathcal{T}\} \cup \{c_T u_i | T \in \mathcal{T}, i = 2, 4, 6, \dots, 2k\}. \end{aligned}$$

We claim that $G_{\mathcal{T}}$ is always a PC graph of complicacy at most $k + 1$, and its complicacy is (at most) k if and only if \mathcal{T} allows a coloring as desired.

Let R be a PC representation of $G_{\mathcal{T}}$. We first note that all polygons $R_{a_x}, x \in X$ must be positioned around the circle. For if one of them would block another two from each other, some R_x would block some R_y from R_{u_2} and the auxiliary polygon R_{b_y} would not be able to intersect both R_y and R_{u_2} .

As observed in Proposition 1, the polygons $R_{u_{2i}}, i = 1, 2, \dots, k$ are positioned around the circle, and only these vertices of the cycle are intersected by R_{c_T} 's. Since the polygons representing the b 's intersect (only) R_{u_2}, R_{u_4} and R_{u_6} , all the polygons representing the a vertices must lie in the segments determined by R_{u_2}, R_{u_4} and R_{u_6} . So color an element $x \in X$ by color i if R_{a_x} is blocked by R_{u_i} from the other $R_{u_j}, i, j = 2, 4, 6$. We claim that this is a good coloring. For if a triple $T \in \mathcal{T}$ contained two vertices of the same color, say x and y of color 2, the polygon R_{c_T} would need $k - 1$ corners for intersections with $R_{u_i}, i = 4, 6, \dots, 2k$, plus at least two more corners for intersections with R_x and R_y , that is at least $k + 1$ corners altogether.

On the other hand, given a feasible 3-coloring of X by colors 2,4,6, a representation by k -gons can be achieved by placing the polygons $R_{a_x}, x \in X$ around the circle such that polygons corresponding to vertices of color i are placed within the segment determined by the chord $R_{u_i}, i = 2, 4, 6$. Each c vertex can then be represented by

a k -gon with one corner in each segment determined by $R_{u_i}, i = 2, 4, 6, \dots, 2k$. An illustrative example is in Figure 6, where a triangle representing a triple $T = \{x, y, z\}$ is marked. For the sake of simplicity, we only illustrate the case $k = 3$, and the auxiliary polygons R_{b_x} are not shown (drawn with invisible ink).

Along the same lines it is seen that $\text{cmp}(G_{\mathcal{T}}) \leq k + 1$ if (X, \mathcal{T}) allows a 2-coloring without monochromatic triples.

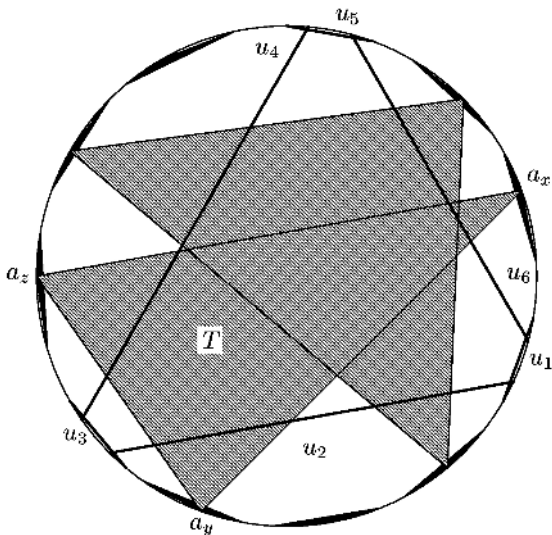


Fig. 6. Illustration to the NP-completeness proof.

One may ask for what function $f(n)$ of n it is still hard to decide if $\text{cmp}(G) \leq f(n)$ for an input polygon-circle graph G on n vertices (since we do not trust the polynomiality of polygon-circle graph recognition, we need to assume that the input graph comes with the promise of being a polygon-circle one). As we have seen in previous sections, $f(n)$ must be somewhat smaller than n so that we might expect NP-hardness. By a closer examination of the proof of Theorem 2 we see that we can get close to $\frac{n}{2}$:

Theorem 6. For every rational $c < \frac{1}{2}$, it is NP-complete to decide whether $\text{cmp}(G) \leq cn$ for an input graph G on n vertices.

Proof. Consider the previous construction of $G_{\mathcal{T}}$. If we start the reduction from 3-edge coloring of a graph with $2m$ vertices and $3m$ edges, we get

$$n = |V| = 2k + 2|X| + |\mathcal{T}| = 2k + 8m.$$

Hence setting $n = \frac{8m}{1-2c}$ (if $1 - 2c > 0$ is rational, we may start with sufficiently many copies of the cubic graph to make n an integer) we get

$$2k = n - 8m = 8m\left(\frac{1}{1-2c} - 1\right) = 2cn$$

and hence our previous proof shows that deciding

$$\text{cmp}(G_{\mathcal{T}}) \leq k = cn$$

is NP-complete.

6 Conclusion

Regardless of whether recognition of polygon-circle graphs turns out polynomial or NP-complete (if dichotomy is expected), our results about NP-hardness of polygon-circle graphs of bounded complicacy will be an interesting counterpart to the complexity of recognition of the whole class. We do hope that our paper will revitalize interest in the polygon-circle recognition problem as well.

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