Erratum to “Mixed Frequency Small Gain State Feedback Control with Application to Insulin Pumps”

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In the above paper [1], the formula (1) is incorrect. The corrected equation is as follows.

$$\dot{x}(t) = Ax(t) + B_1\omega_1(t) + B_2\omega_2(t) + Bu(t). \quad (1)$$

REFERENCES

- [1] X. N. Zhang and G. H. Yang, “Mixed frequency small gain state feedback control with application to insulin pumps,” *International Journal of Control, Automation, and Systems*, vol. 7, no. 2, pp. 319-324, April 2009.

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