Hedge-Algebras-Based Controller for Mechanisms of Relative Manipulation

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The references 1, 4 and reference 5 of the above the article has been corrected as follows:

1. Khoi, P. B., "Calculation and Simulation of the Program Motion of Mechanisms of Relative Manipulation (MRM)," Journal of Science and Technology, Vol. 3, pp. 19-28, 2009.
4. Khoi, P. B., "Applying Principle of Compatibility for Analyzing Forces of Mechanism of Relative Manipulation Robot," Ph.D. Thesis, IMASH, RAS, 1997.
5. Khoi, P. B., "Dynamical Investigation of Relation Manipulation Mechanisms in Mechanical Processing," Proc. of National Conference on Mechanics, pp. 181-190, 2004.

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