Erratum to: Haptic-based interactive path planning for a virtual robot arm

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Unfortunately, Ref. [8] “Mikchevitch, A., Antoine, F.: Haptically generated paths of an AFM-based nanomanipulator using potential field. In: 4th IEEE Conference on Nanotechnology, pp. 355–357 (2004)” has been published incorrectly. The correct reference is mentioned below:

Ammi, M., Ferreira, A.: “Haptically generated paths of an AFM-based nanomanipulator using potential fields”. In: 4th IEEE Conference on Nanotechnology, pp. 355–357 (2004)

The online version of the original article can be found under doi:[10.1007/s12008-010-0088-2](https://doi.org/10.1007/s12008-010-0088-2).

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