Progress of marine biofouling and antifouling technologies

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Adhesion of marine fouling organisms on artificial surfaces such as ship hulls causes many problems, including extra energy consumption, high maintenance costs, and increased corrosion. Therefore, marine antifouling is an important issue. In this review, physical and biochemical developments in the field of marine biofouling, which involves biofilm formation and macro-organism settlement, are discussed. The major antifouling technologies based on traditional chemical methods, biological methods, and physical methods are presented. The chemical methods include self-polishing types such as tributyltin (TBT) self-polishing copolymer coatings, which despite its good performance has been banned since 2008 because of its serious environmental impact. Therefore, other methods have been encouraged. These include coatings with copper compounds and biocide boosters to replace the TBT coatings. Biological extracts of secreted metabolites and enzymes are anticipated to act as antifoulants. Physical methods such as modification of surface topography, hydrophobic properties, and charge potential have also been considered to prevent biofouling. In this review, most of the current antifouling technologies are discussed. It is proposed that the physical antifouling technologies will be the ultimate antifouling solution, because of their broad-spectrum effectiveness and zero toxicity.

biofouling, antifouling technology, biofilm, adhesion mechanism

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In the marine industry, the accumulation of living organisms on artificial surfaces by adhesion, growth and reproduction is known as biofouling. Biofouling is a particular problem for underwater structures, such as pipelines, cables, fishing nets, and bridge pillars. The adverse effects of ship hull biofouling (Figure 1) include [1]: (i) Higher fuel consumption because the frictional resistance increased due to biofouling, making the hull rougher and the ship heavier. Fuel consumption increases of about 40% have been observed because of biofouling [2], and the cost of a one-way voyage from San Francisco to Yokohama has increased by about 77% due to ship's hull fouling [3]. (ii) More expensive and time consuming hull maintenance, because dry-docking operations need to be more frequent and longer with marine biofouling [3]. Moreover, these cleaning processes generate a large number of toxic substances that are discharged into the ocean. (iii) Increased ship hull corrosion

as the protective coating surface deteriorates because of metabolic and other biological process. This makes the hull surface more susceptible to corrosion and discoloration [4].

In the marine industry, biofouling is a huge problem, and research is focused on development of an effective antifouling solution. However, the mechanism of biological adhesion needs to be determined to allow development of antifouling strategies. In this review, an introduction to current marine fouling strategies is given, and different kinds of antifouling technologies are proposed according to the adhesion mechanism.

1 Biofouling organisms and their adhesion mechanism

More than 4000 kinds of marine biofouling species have been reported globally, most of which live primarily in the shallower water along the coast and in harbors that provide

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Figure 1 Heavy biofouling on the hulls of vessels.

abundant nutrients [1]. In general, marine adhesion organisms can be divided into two major categories. The first of these includes the microfouling or biofilm organisms, which are bacteria and diatoms. Biofilms are ubiquitous, as long as the surfaces are exposed to water. The other category includes macrofouling organisms such as algae and barnacles. The most important macro-fouling species are barnacles, mussels, polychaete worms, bryozoans and seaweed [5].

The biofouling process can be simplified as illustrated in Figure 2. First, through a simple physical reaction, a layer of conditioning film composed of organic materials such as protein, polysaccharide, and proteoglycan, is formed on the substrate surface. This step is short (1 min), and provides a stickier surface for microorganisms to adhere to [6].

The biofilm then develops as bacteria and microalgae adhere to the surface. Microorganism colonization involves two distinct steps: reversible adsorption, and irreversible adhesion. The former is governed mainly by physical effects such as Brownian motion, electrostatic interaction, gravity, water flow and van der Waals forces [7–10]. The latter occurs mainly through biochemical effects such as secretion of extracellular polymeric substances (EPS). During biofilm formation in the marine environment, diatoms are the most important contributors. It has been reported that microfouling alone can increase fuel consumption by up to 18%, and reduce the sailing speed by at least 20% [11].

After the formation and development of the biofilm,

larvae or spores of macrofoulers will attach to the surface. Two or three weeks later, these will finally evolve into a complex biological community. In marine immersion experiments, adhesion of macroorganisms usually occurs after biofilm formation [10,13]. However, this is not always the case [1,14], for instance the larvae of some species of bryozoans [15], polychaetes [16] and some other biofoulers [17] adhere before biofilm formation.

Therefore, the process of biofouling occurs by both physical reactions and biochemical reactions (Figure 3). The physical reactions are governed by factors such as electrostatic interaction and water flow, and lead to formation of the conditioning biofilm and adsorption of microorganisms. The biochemical reactions include EPS secretion, movement and secondary adhesion of microorganisms, formation of the biofilm, and adhesion of macrofoulers. Whereas the physical reactions are usually reversible, the biochemical reactions are effectively irreversible. Thus, it would be easier to prevent biofouling during the physical reactions rather than the biochemical reactions. Successful inhibition of the physical reactions would constrain the later biochemical reactions.

Current research on antifouling is focused on inhibition of adhesion of diatoms and bacteria to prevent biofilm formation, though such research has also encountered numerous obstacles [1]. Some of the macrofouling organisms have been also researched in detail. The adhesion strategies of the three kinds of biofouling organisms (bacteria, microalgae,

Figure 2 Temporal settlement of fouling organisms on a substrate surface [12].

Figure 3 Biofouling process and the formation of biofilm.

and macroorganisms) are discussed in sections 1.1–1.3.

1.1 Bacterial adhesion

Bacterial adhesion occurs as a result of the interaction of planktonic cells with the surface by physical reactions, such as electrostatic interactions [7], gravity [8] and water flow. After the initial reversible absorption, bacteria use extracellular polymers to temporarily adhere to the surface. These polymers are mainly glucose- and fructose-based polysaccharide fibrils [12]. The biofilm is formed when the bacterial communities secrete more EPS (Figure 4(a)). The biofilm is a highly organized community usually formed by a

number of similar or homologous and mixed species, which has beneficial effects for the microorganisms [19,20]. After maturation of the biofilms, they disperse cells into the water to expand the species (Figure 4(b)) [21].

The premise of the phenotypical change between reversible and irreversible states is a cell density-dependent system called quorum sensing. As the name indicates, the bacteria cell is able to sense that it is part of a concentration of cells of a certain size (the quorum), by recognition of specific low-molecular-weight signal compounds secreted and accumulated by the cells in the quorum. The quorum sensing system is important for many aspects of cell survival [22].

Figure 4 Biofilm formation. (a) SEM photographs of EPS produced by *Salmonella* (scale bar = 2 μm) [18]; (b) biofilm formation in five steps: initial adsorption, irreversible adhesion, maturation I, maturation II, and dispersion [21].

Generally speaking, the mass of cells in biofilms accounts for only 2%–5% of the total weight with the remainder contributed by the EPS matrix, which includes a variety of extracellular carbohydrates, proteins, nucleic acid, glycoprotein, phospholipids and other surfactants. The ratio of these various extracellular compounds excreted by various species is quite different [23,24], and even the same species secrete different EPS compounds under different circumstances [18]. Among those compounds, the polysaccharides are highly heterogeneous, containing different sorts of monosaccharide units and inorganic materials [25]. The secreted proteins, many of which are polymer-degrading enzymes, also have heterogeneous compositions, although there is evidence that different proteins share some common substances or features. For instance, the surface protein Bap [26], amyloid fibril and β -1,6-N-acetyl glucosamine [27–29], and the sequence GGDEF/EAL [18] are found in different proteins.

These factors illustrate the lack of many common features among different biofilms, which makes broad-spectrum antifouling a difficult target.

1.2 Microalgae adhesion

The major eukaryotic marine fouling microorganisms are diatoms, fungi, and protozoan, and the dominant organisms are diatoms [12,13].

Diatom adhesion is a more complicated process than that for bacteria. Because most of the diatoms lack flagella, they cannot actively approach a given surface, but passively land on the substratum. For example, benthic diatoms approach surfaces through the effects of either gravity [30] or water currents [31–33]. Plankton diatoms, which have almost the same specific gravity as seawater, land on surfaces mainly via turbulence [34]. Moreover, electrostatic interactions such as Coulomb attraction and electrostatic contact potential are also involved [35]. During contact between diatoms and a surface, van der Waals forces may also operate, and

this has been observed in other adhesive situations [36].

After the diatoms land on the surface, they actively form the initial reversible attachment called primary adhesion through secretion of EPS. The diatoms then reorient themselves and move along the surface into better positions based on their preferences, this process is called diatom gliding. Many scientists have focused on diatom gliding in the belief that this would help to understand the adhesion mechanism. However, Holland et al. [37] found no relation between adhesion and locomotion of diatoms. It is generally acknowledged that diatom gliding is the result of an actin-myosin motility system mediated by extracellular proteoglycans. Actin was first identified near the position of the raphe (Figure 5(a), (b)), and its involvement in cell motility has been the focus of many studies [38,39]. Later experiments proved that both anti-actin drugs and antibodies to cell surface proteoglycans inhibit diatom gliding [39,40]. However, the underlying mechanism generating force for diatom gliding is currently poorly understood. Some mechanical models for locomotion have been calculated in earlier studies [41,42], and some reasonable cell locomotion mechanisms have been proposed (Figure 5(c)) [43]. After diatom gliding, if the diatoms continue their life cycles in that position, they will form irreversible secondary adhesion by secreting a large amount of EPS [44–46]. Individual diatoms commonly generate EPS like stalks in this period [45,47,48].

EPS of diatoms is composed of carboxylated or sulfated acidic polysaccharides, which are involved in the primary adhesion, and proteoglycans, which are involved in diatom gliding and cross-linking stabilization of the biofilm matrix [40]. As with bacteria, EPS produced by different types of diatoms are diverse [49,50], and include various protein fractions and complex anionic polysaccharides with heterogeneous combinations of monosaccharide [45]. In addition, at least two types of mucilage can be detected for the same species of diatom [51,52]. However, some common features have been detected among different diatoms, such as

Figure 5 Actins in diatoms and proposed diatom locomotion mechanism. (a) Cell of *Craspedostauros australis* in girdle view [39]; (b) fluorescein (FITC) phalloidin stained cell of *C. australis* in also girdle view, which indicates F-actin along the raphe [39]; (c) proposed cell movement mechanism [43] involving: (i) secretion of mucilage strands at the central pore, and their attachment to membrane components and substratum; (ii) relative backward movement of the membrane components, which leads to forward displacement of the framework itself and of the cell as a whole; (iii) breaking of the mucilage strands, which forms a short-lived trail.

general structural components by time of flight-secondary ion mass spectrometry (TOF-SIMS) [53], and modular proteins and their supramolecular assemblies of adhesive nanofibers (ANFs) [54]. These common traits could be targeted in a method to combat diatom adhesion.

As mentioned above, we have some primary understanding of the mechanisms of diatom gliding and adhesion, though the hypotheses still lack theoretical support. For example, the mechanism by which the secreted mucilage and actin generate force is unknown. Aspects of diatom adhesion are even more uncertain, such as how it is initiated or inhibited, and cannot be explained by the established theory of mucilage secretion.

1.3 Macro-organism adhesion

The most problematic biofouling effects arise because of colonization of macroorganisms such as spores of macroalgae, barnacle larvae, bryozoans, molluscs, polychaete, tunicates, and coelenterates [12].

A common trait of macroorganism settlement is biofilm cueing. As early as 1963, it was shown that the increased diatom concentrations could induce maturation of barnacle larvae [55]. However, subsequent experiments have shown that biofilms do not facilitate settlement of all macroorganisms. This has been demonstrated in a variety of marine organisms such as barnacles, oysters, and *Ulva* [25] fed by bacteria [56] and diatoms [57]. Because of competition for nutrients and light, it is believed that microorganisms produce metabolites to repel specific macroorganisms [58].

Another common characteristic of macroorganism settlement is physiochemical cueing. Some experiments have shown that invertebrate larvae seem to be able to select suitable substrates, and their choice is determined by surface topography, water streaming conditions and chemical properties [25]. Moreover, it is generally accepted that larval settlement and metamorphosis are influenced by chemical cues originating from conspecific adults, prey organisms, and substrates [59].

Though the settlement of macroorganisms follows the above common guiding cues, adhesion mechanisms are quite different in specific organisms. Barnacles and *Ulva* have been investigated as representatives of invertebrate and macroalgae groups, respectively. The settlement mechanism of barnacles has been studied in great detail, and results indicate that the cyprid antennule consists of four segments that are responsible for crawling, attachment and sensory functions [60]. When an appropriate surface is found, the cyprid will adhere by secretion of granulated cement containing high concentrations of proteins. This cement embeds the antennular attachment organs and hardens because of protein polymerization. After stable settlement, cyprids metamorphose into juvenile barnacles, and finally become adults [61].

Ulva spores are another well-studied macroorganism, and

are extremely important in biofouling because of their abundance in seawater and adaptability to different environments [12]. The motile spores have four flagella and no polysaccharide-rich cell wall. Typically, *Ulva* spores adhere to the surfaces by secreting glycoprotein, and then retract the flagella and form a cell wall [62–64]. However, in some special conditions spores will exhibit abnormal pseudo-settlement [65]. Freshly released glycoprotein from *Ulva* spores has strong adhesion strength, and the spores cannot be removed under the speed of most vessels [66].

Protein adhesives from algae, mussels, and polychaetes have several features in common, including high contents of lysine, glycine and serine, and extensive polypeptide repeats with abundant dihydroxyphenylalanine (DOPA) side-chains, which will displace water molecules to facilitate strong adhesion [25,67]. However, they are quite different from the barnacle adhesives [68,69].

2 Antifouling methods

The severity of biofouling depends on a large number of parameters, including temperature, salinity, light, geography, depth, and voyage speed [1,70]. For example, biofouling is generally more serious in areas with high water temperature because this is the principal condition determining breeding periods and rates of growth of biofouling organisms [71]. Unfortunately, these important factors cannot be modified to a large extent. Therefore, to effectively prevent biofouling, a variety of coatings have been investigated to chemically inhibit the fouling organisms. From another point of view, during the development of microtechnology, the influence of microscale physical factors on biofouling has been researched and some new antifouling technologies have arisen that involve changing physical factors. In addition, microorganisms can secrete metabolites that inhibit the attachment of some macroorganisms [72], and concentrated extracts of these metabolites could also be effective antifouling agents.

In summary, antifouling methods can generally be divided into three categories: chemical, physical, and biological methods.

2.1 Traditional chemical methods

Biofouling has been recognized as problematic for more than 2000 years [73], and many kinds of antifouling methods have been investigated over this time [1]. Since the late 20th century, organic tin and its derivatives have been widely used as antifouling coatings because of their activity against a wide range of fouling species. Organotin compounds that have been used as antifoulants include tributyltin oxide (TBTO), and tributyltin fluoride. Those antifouling organotin compounds are powerful fungicides, and will completely inhibit the growth of most fouling

organisms at a very low concentration [74]. The paints containing these compounds can be classified as those with insoluble and soluble matrices, according to the chemical characteristics of the binder and their water solubility.

Insoluble matrix antifouling paints have a polymer matrix (such as vinyl and epoxy) that will not erode in water [1]. When the coating is immersed in seawater, the soluble toxic materials dissolve, which leaves a multiporous structure known as the leached layer. Seawater then penetrates deeper into the film and more poisonous materials dissolve in the water. The advantage of this kind of paint is that the structures are mechanically strong and stable to oxidation and photodegradation. Thus the coatings can be made very thick to increase the content of toxic materials. However, at some stage the leached layer will be so thick that water cannot penetrate any deeper, and the rate of release will fall under the minimum value required for antifouling (Figure 6(a)). Therefore, the lifespan of insoluble matrix antifouling paints is as short as 12–18 months [75].

To lengthen the lifespan of antifouling coatings, soluble matrix antifouling coatings were developed. As implied by the name, both the toxic materials and matrix, which contains a great amount of resin, can dissolve in seawater. In this case, the leached layer can be much thinner and toxic materials deeper in the film can be easily exposed to water, which lengthens the lifespan of the antifouling coating (Figure 6(b)) [1]. The release rate will exponentially increase as the sailing speed increases. However, during the static conditions that favor settlement of fouling organisms the pores of this coating can become blocked by insoluble salts, which greatly reduces the release of biocides [76]. In addition, because of the resin's brittleness and instability to

oxidation, its mechanical properties are inferior to those of insoluble matrix coatings.

2.2 Modern chemical antifouling methods

(i) Tributyltin self-polishing copolymer coatings. As noted in section 2.1, both insoluble and soluble matrix antifouling coatings have their deficiencies. Consequently, alternative coatings have been investigated. In 1974, Milne and Hails patented the first TBT self-polishing copolymer (TBT-SPC) technology, which provided an excellent antifouling effect that revolutionized the entire shipping industry [1].

TBT-SPC paints are based on acrylic polymer (usually methyl methacrylate) with TBT groups bound to the polymer backbone by an ester. When immersed in water, the soluble pigment particles (such as ZnO) begin to dissolve [77]. The polymer of TBT methacrylate and methyl methacrylate is hydrophobic, which prevents water from infiltrating the paint film. Therefore, water can only fill the pores generated by the dissolution of soluble pigment particles. Moreover, the carboxyl-TBT linkage is easily hydrolyzed in slightly alkaline environments such as in seawater (pH 7.5–8.5). This results in cleavage of the TBT portion from the copolymer, and releases the biocides into the water [74]. Once many TBT portions have been cleaved, the partially reacted brittle polymer backbone can be easily washed off by the moving seawater, which exposes a fresh coating surface (Figure 7(a),(b)) [74,78]. The hydrolysis process provides a low hull roughness (about 100 μm), so as not to increase the resistance of the ship's hull [1].

One of the major advantages of an antifouling coating such as this is that manipulating the polymer chemistry can

Figure 6 Method of release and biocide release rates of (a) insoluble matrix paints and (b) soluble matrix paints [1].

Figure 7 TBT-SPC system and cross-sectional SEM image. (a) Self-polishing TBT copolymer system [74]; (b) SEM image showing cross-section of TBT-SPC (magnification 5000 $\times$) [78].

control the polishing rate. Therefore, it is possible to balance high effectiveness and a long lifespan, and the coatings can be customized for ships operating under different conditions, such as duration of their idle periods and sailing speed [1]. It has been shown that release rate of TBT in seawater is almost constant with sailing speed, and thus high antifouling performance can be obtained even if the ship is not moving. In addition, the maintenance is convenient and low cost. Moreover, TBT-SPC paints have high mechanical strength, high stability to oxidation, and short drying times [74]. The unavoidable formation of biofilm does not largely affect the net biocide leaching and binder reaction rates [79]. Therefore, in general, the TBT-SPC antifouling coating was widely applied in the shipping industry before it was banned.

(ii) Tin-free SPC technology. As discussed earlier, TBT-SPC coatings have many advantages as antifouling coatings. However, the damaging effect of TBT on non-target organisms cannot be ignored. Consequently, TBT has been restricted as of the International Maritime Organization (IMO) conference in 1998, and these coatings have been banned from 1 January, 2008 [80]. Therefore, TBT-free systems have been commercially introduced.

Generally speaking, the tin-free antifouling coatings can be divided into two categories: controlled depletion systems (CDPs), and tin-free self-polishing copolymers (tin-free SPCs). The former coatings upgrade the traditional soluble matrix technology by incorporating modern reinforcing resins with the same antifouling mechanism as the conventional resin matrix paints. The latter coatings function in a similar manner to TBT-SPC but do not contain tin. Currently, these two types of paints are produced by many companies, including Ameron, Chugoku MP, and Hempel's MP [1]. The differences between CDPs and tin-free SPCs are illustrated in Table 1, and from these parameters we can see the performance of tin-free SPCs is better than the CDPs.

Tin-free SPCs react in a similar to organic tin SPCs, but their matrix material is mostly acrylic copolymer and non-tin metals such as copper, zinc, and silicon. For example, the Exion series from Kansai Paint [1] uses insoluble Zn acrylate, which hydrolyzes to soluble acidic polymer. The following reaction is assumed:

The Zn^{2+} is discharged into water for antifouling, and the soluble acidic polymers can be washed from the surface. Beside zinc, the majority of tin-free antifouling paints currently available contain copper, and some contain silver [81]. Currently, the major copper compounds used for antifouling include metallic copper, cuprous thiocyanate, and cuprous oxide [82,83]. Copper ions as Cu^{2+} have a major role in antifouling [1].

Compared with the broad-spectrum TBT antifouling coatings, copper-containing coatings can only target specific fouling organisms. Biological indicators differ widely with respect to copper sensitivity, and a general decreasing order of sensitivity would be: microorganisms > invertebrates > fish > bivalves > macroalgae [84]. Therefore, some booster biocides that are highly toxic to macroalgae, barnacles, and bryozoans are added to improve the antifouling properties. These biocides include Irgarol 1051 and Diuron [83,85], copper pyrithione and isothiazolone [1,86].

Undoubtedly, there is concern about the influence of copper containing coatings and booster biocides on the marine environment [85]. However, a number of scholars have highlighted that the boosters are biodegradable materials with short half-lives. Unfortunately, the heavy metals do bioaccumulate in the internal organs of marine life [87]. Generally speaking, there is no simple and nontoxic solution for the biofouling problem [88]. However, copper containing coatings are considered as a transition between toxic and non-toxic coatings.

(iii) Non-toxic antifouling technology. Although in the short term, no alternative antifouling technology seems capable of replacing biocide-based coatings, there are some non-toxic technologies that have been developed.

For instance, non-stick fouling-release compounds (such as silicone coatings) have been trialed for antifouling through release of macrofouling organisms when hydrodynamic conditions are sufficiently robust [1,37]. In this case, it appears that fluoropolymers and silicones possess the necessary properties for antifouling by release [1]. Some low surface energy coatings have also been prepared with modified acrylic resin and nano- SiO_2 [89]. However, accumulated fouling organisms are not as easily released as anticipated [37,90,91]. In addition, this method has many deficiencies, such as high cost, poor mechanical properties,

Table 1 Contrast of performance of CDPs and tin-free SPCs

	CDPs	Tin-free SPCs
Self-polishing	Poor	Smooth paint surface during sailing
Leached layer	Thick	Thin and stable
Biocide release	Hard to control, not constant	Continuous and constant at the same velocity and sea water conditions
Idle periods	Little activity	High activity
Lifetime duration	Short, up to 3 years	Long, 5 years
Maintenance	High cost, sealer coating needed	Low cost, re-coating directly

and the difficulty of recoating. Therefore the antifouling performance is limited, which leads to increased interest in other methods. Generally speaking, non-toxic antifouling technology research can explore either biological or physical methods.

Biological methods involve using a variety of enzymes or metabolites secreted by cells as substitutes for traditional biocides [23]. Because these organic secretions are biodegradable, they should be environmentally friendly [25].

Physical methods include electrolysis, radiation, and other physical methods to reduce biofouling. They can also utilize modification of surface physical properties, such as topography or charge potential, to minimize adhesion strength [1].

3 Biological methods

As mentioned in earlier, some organisms can secrete enzymes or metabolites to inhibit the growth of their competitors. These secretions have low-toxicity and are biodegradable, and have received much attention in recent years. Researchers have attempted to extract high concentrations of these secretions to use for biological antifouling. As early as 1999, it was reported that the active substances secreted by blue algae could inhibit the growth of diatoms [92]. Functional antifouling components have also been discovered in other organisms such as fungi [93], sponge [94] and some other bacteria [95,96].

The application of enzymes as antifouling agents has been successfully investigated recently. Many types of enzymes, such as oxidoreductases, transferases, hydrolase, lyase, isomerase, and ligase, have been reported to have antifouling capabilities [25,58,97–106]. From the perspective of enzymatic antifouling technology, biofouling problems are caused by the formation and reproduction of biofilms, and the adhesion of spores and larvae of macroorganisms. Therefore, the functions of enzymes for antifouling applications can be divided into the following four categories: degradation of adhesives used for settlement, disruption of the biofilm matrix, generation of deterrents/biocides, and interference with intercellular communication.

3.1 Enzymes that degrade adhesives used for settlement

In the case of macrofouling, proteins and proteoglycans have a dominant role in the adhesion process. As is widely known, proteases can hydrolyze peptide bonds at different sites, and this kind of enzyme can be used to degrade mucilage based on peptide and hence prevent biofouling. For example, the attachment of *Ulva* spores, barnacle cyprids and bryozoans can be effectively inhibited by serine protease [58,98]. It has been confirmed that this inhibition is caused by reduction of adhesive effectiveness rather than any toxic or deterrent effect [105].

In the case of microfouling, the process is more complicated [98,103], because polysaccharide-based adhesives are as important as proteins during secondary adhesion. Generally, polysaccharide degradation is executed by glycosylase. However, to degrade polysaccharides is difficult because the process is quite complex [106] and glycosylase can target only a limited range of linkages. Consequently, it would be difficult to choose an appropriate glycosylase for broad-spectrum antifouling [103].

3.2 Enzymes that disrupt the biofilm matrix

Because of the variety of EPS, biofilms are very complex and the disintegration of their polymeric networks would require very broad combinations of both hydrolases and lyases [25]. In addition, because biofilms are very adaptable to external conditions, the degradation of the crucial component will induce the generation of alternative components that will replace the original and establish a new network to proliferate the organisms [107]. This means that the biofilm will not disintegrate. Tests have shown that though alginase could detach a thin biofilm [108], it had no effect on an identical biofilm that was already fully established [107].

In summary, because of the complexity and adaptability of the biofilm, the antifouling method of disrupting the biofilm matrix may not be suitable and effective.

3.3 Enzymes that generate deterrents and biocides

In recent years, antifouling research has focused on the extraction of metabolites secreted by different marine animals or plants that have strong antifouling ability. Such antifouling compounds should be regarded as deterrents rather than toxins [23,25].

Some of the enzymes that have such effect include glucose oxidase, hexose oxidase, and haloperoxidase [25,99]. For instance, glucose and hexose oxidase is used to generate hydrogen peroxide to induce oxidative damage in living cells [109], and haloperoxidase catalyses the formation of hypohalogenic acids usually used in water treatment systems as disinfecting agents [25]. In addition, hydrogen peroxide will decompose into water and oxygen, and the rate of this process is quite high in seawater [110]. Hypohalogenic acids have similar characteristics, and could also be investigated in future as nontoxic and biodegradable antifouling substances [99].

3.4 Enzymes that interfere with intercellular communication

As discussed in section 1.1, quorum sensing has an important role in the formation of biofilms. Studies have shown that *N*-acyl homoserine lactones (AHL) are required for quorum sensing by some Gram-negative bacteria [22]. Therefore, elimination of AHL may thus prevent the

development of bacterial fouling [25]. AHL acylase degrades AHL, and as the concentration of this enzyme increases, biofilm formation is inhibited and the settlement of *Ulva* spores and polychaete larvae is affected [110,111]. Consequently, AHL acylases can also inhibit the settlement of macroorganisms to some extent.

3.5 Challenges for enzymatic antifouling methods

The seawater temperature ranges from -2°C to 30°C , which can largely affect enzyme catalytic activity and stability. In addition, each enzyme will itself decompose if the temperature is too high, and then the lifespan of the enzymatic antifouling coating will also decrease. Therefore, balancing of the effectiveness and lifespan will be a major challenge. Furthermore, the design of an appropriate coating matrix to contain the enzymes will be another crucial step for successful application [112]. In addition, the distribution of enzyme and its amount should also be analyzed in detail, because soluble enzymes will soon form a thick leaching layer.

4 Physical antifouling methods

4.1 Antifouling by electrolysis and radiation

Many methods for physically preventing biofouling have been investigated. Among them, the most common method is to produce hypochlorous acid (HClO), ozone bubbles, hydrogen peroxide or bromine through electrolysis of seawater [1,113,114]. Because of their strong oxidizing ability, HClO and other compounds will spread all over the ship's hull and eliminate areas of fouling organisms. However, some of these systems are not highly efficient because of a large voltage drop across the surface, and they will intensify the corrosion problems of steel. Consequently, titanium-supported anodic coating has been suggested because of its advantages such as having low decomposition tension, higher current efficiency, lower energy consumption [115], although the development of this has been limited. Antifouling could also be achieved by microcosmic electrochemical methods, which are based on direct electron transfer between an electrode and the microbial cells. This causes electrochemical oxidation of the intercellular substances, but is expensive and the efficiency has not been established [25].

The antifouling abilities of vibration methods, such as acoustic technology, have also been confirmed [116]. Hydroids, barnacles and mussels can be inhibited to some extent by either external vibration sources or piezoelectric coatings [117]. However, the huge power consumption of these methods is difficult to overcome.

Finally, other studies have evaluated magnetic fields, ultraviolet radiation and radioactive coatings [1], but these methods are not practical in application. An additional potential method involves the use of substrates with different

colors, which affect the attachment and growth of spores and worms [118,119].

4.2 Antifouling by modification of surface topography and hydrophobic properties

As stated in section 1.1, biofilm is mainly formed by microorganisms, including bacteria and microalgae, which are approximately $1\text{--}100\text{ }\mu\text{m}$ in size. At this scale it is possible to precisely modify the surface microstructure. Therefore, in recent years, varying surface characteristics, including surface roughness, topography, hydrophobic behavior, and lubricity, have been investigated for antifouling application [120]. To simplify the models used in these studies most researchers regard diatoms or bacteria as representative adhesion organisms.

Because of material properties, surface wettability has a large impact on the adhesion of biofouling organisms. Study has shown that fouling diatoms [37] adhere more strongly to a hydrophobic polydimethylsiloxane (PDMSE) surface than to glass. For other fouling organisms such as bacteria and *Ulva* spores, if the surface contact angle is greater than the adhesion is stronger [121–124]. However, the strength of attachment of *Ulva* spores is greater to hydrophilic than hydrophobic surfaces [66,125]. Moreover, hydrophilic surfaces are thought to be capable of antifouling. For example, antifouling behaviors are exhibited when adding metal nanoparticles such as TiO_2 , because the photocatalytic activities introduced by solar ultraviolet will make the surface more hydrophilic so that the formed biofilm is washed more easily [126]. However, some species studied have exhibited opposite adhesion behavior on the same sets of surfaces, highlighting the importance of differences in cell-surface interactions [32,66]. Therefore, the differences in settlement and adhesion behavior have inspired the development of a surface that presents both hydrophilic and hydrophobic domains to settling (attaching) cells and organisms. Different patterns of such surfaces have also been evaluated [127, 128].

Surface topography also affects the adhesion of fouling organisms. It has been shown that rougher surfaces increase adhesion of *Pseudomonas* [129]. Furthermore, Scardino et al. proposed the attachment point theory (Figure 8), which indicates that more attachment points during adhesion results in stronger more prolific adhesion [130,131]. This theory is consistent with the settlement of barnacle cyprids [132].

The effects of feature size, geometry and roughness on the settlement of zoospores of *Ulva* were evaluated using engineered micro topographies in PDMSE. The results identified an engineered roughness index (ERI) that can influence antifouling [133]. ERI could be calculated as: $\text{ERI}=(r \cdot d_f)/f_D$, based on Wenzel's roughness factor (r), the depressed surface fraction (f_D), and the degree of freedom of spore movement (d_f). Different surface topographies (Figure

Figure 8 Attachment point theory experiments, which illustrate that the adhesion strength is highest in (a) and (b) (multiple attachment points) and lowest in (d) (least attachment points) [130].

9(a)) have different ERIs, and that with the largest ERI (Sharklet AF™) will perform most effectively as an antifoulant. It was proposed that the responses were governed by the same underlying thermodynamic principles as wettability [134]. The Sharklet AF surface was also tested with other organisms such as *Staphylococcus aureus* (Figures 9(b) and (c)) and appeared to have effective antifouling performance [135]. The effectiveness of designed nanoforce gradients for antifouling applications was tested with *Ulva*, and the results showed the surfaces with nanoforce gradients ranging from 125–374 nN all greatly reduced spore settlement [136].

Multivariate methods were used to identify relationships between bacterial attachment, water transport, and the surface properties of modified polysulfone (MPS) membranes, which showed that the interrelations were quite complicated [137]. In summary, the research into modification of surface topography to achieve antifouling is still at the experimental stage. The identification of effective antifouling topographies typically occurs through trial-and-error rather than predictive models. Although some empirical principles such as attachment point theory and the ERI index have been proposed, these theories are not sufficient to explain the real situation. Therefore, these formulas are not expected to guide the development of antifouling methods.

4.3 Antifouling by changing the zeta potential

As mentioned in section 1, microbial adhesion is compli-

cated and influenced by many physical reactions, while electrostatic interactions are expected to have a major role [138]. Therefore, potentials of the surfaces or microfouling organisms have been measured to determine the relationship between them.

It is well known that bacterial cell surfaces possess net negative electrostatic charge because of ionized phosphoryl and carboxylate substituents on outer cell envelope macromolecules that are exposed to the extracellular environment. The influence of peripheral electronegativity can be assessed based on the measurement of zeta potential (Figure 10(a)), which is most often determined by estimating the electrophoretic mobility of cells in an electric field [139]. ZPs of many microorganisms have been measured in different physiological states [140], such as for *Chlorella* (ZP=−17.4 to −19.8 mV, independent of pH from 4–10), diatom *Nitzschia* (ZP=−28 mV, stationary phase) [141], and *Pseudomonas sp.* (ZP=−46.9 mV) [140]. Microorganisms are negatively charged over a large pH range (Figure 10(a)), and in natural sea water (pH 7–8) will carry a negative charge [142]. As a result, electrostatic interaction between cells and metal cations promotes the adhesion process.

In some other industries, varying the pH of the suspension and hence shifting the surface charges of the bacterial cells has been used as an effective method to reduce biofouling [143]. However, it is impractical in the case of marine fouling. Consequently, attempts have been made to modify the charge potential of the surfaces to inhibit the cells from attaching to them to some extent. Fouling by

Figure 9 Spore attachment on surfaces with different topographies. (a) SEM images of engineered topographies on PDMSE surface and corresponding spore settlement data [133]. Uniform surface of circular pillars (ERI=5.0) or wide ridges (ERI=6.1) reduced settlement by more than 30%. A multi-featured topography consisting of pillars and equilateral triangles (ERI=8.7) reduced spore settlement by 58%. The largest reduction 77%, was obtained with the Sharklet AF topography (ERI=9.5). SEM images of *S. aureus* on smooth PDMSE (b) and Sharklet AF surface (c) after 21 d [136].

Figure 10 Zeta potential with diatom cells. (a) Cross-section representation depicting the various solvent layers surrounding a bacterial cell [139], and zeta potentials of two *picocyanobacterial* strains as a function of pH [142]; (b) fouling coverage of *P. aeruginosa* vs. zeta potential of nylon membranes after various periods of time [129].

Pseudomonas aeruginosa was minimal when the surface charge was minimized, and increased with increasing charge (positive or negative) (Figure 10(b)) [129]. *Ulva* spores were demonstrated to have a reduced tendency to settle on negatively charged surfaces of polytetrafluoroethylene (PTFE) [64]. Many other phenomena observed during microorganism settlement on self-assembled monolayers [121,144] can be partly explained by electrostatic interactions [145,146]. Discharge treatment can be used to create carboxylic acid groups on polymer surfaces [147], which can also be discussed in terms of the repulsive electrostatic interactions [148].

4.4 Challenges for physical antifouling methods

In summary, in most cases there are no convincing theories to explain different antifouling performance by modification of surface zeta potential, topography, and wettability. Consequently, many experiments investigating various parameters are insufficient for solving biofouling problems. Detailed information on the biological adhesion mechanism is required as the biofouling process is a complex biochemical problem rather than a pure physical problem.

5 Conclusions

In general, biofouling on marine structures is characterized by two critical events: the formation of biofilms, which includes reversible physical adsorption, irreversible secondary adhesion, and then proliferation of the microorganisms; and the settlement and growth of spores or larvae of macroorganisms. In most cases, it is easier for macroorganisms to settle on specific biofilms through cueing than on the surface

without biofilms. Thus, it is important to research ways to prevent biofilm formation. Because diatoms are the dominant organisms in biofilms, they have been widely evaluated in a variety of experiments as a representative of microorganisms.

Many kinds of antifouling technologies have been investigated to counteract the marine foulers. For instance, TBT-SPC is one of the most effective antifouling methods. However, biocide-based antifouling coatings are environmentally unsuitable, and research on non-toxic coatings is of importance. This research generally focuses on physical methods, including electrolysis and radiation, modification of surface structures and wettability, or change in the charge potential of surfaces. The alternative is biological methods, including using enzymes or metabolites secreted by cells to replace toxic biocides.

In the case of biological methods, the current situation shows that enzymes degrading adhesives (proteases and glycosylases) and enzymes interfering with intercellular communication (acylase) can effectively prevent biofouling. The former approach is mainly targeted at macroorganisms and the latter at microorganisms, and some kind of combination of both enzymes will possibly produce a better result. Further documentation of trials on marine crafts should be obtained, and the various enzymes should be directly tested after design and manufacture of enzymatic coatings.

In the case of physical methods, broad-spectrum antifouling could be performed. Currently, the most successful method is the modification of surface topography, and Sharklet AF has demonstrated to be effective against a variety of fouling organisms. However, the understanding of such mechanisms is still very poor. Although some empirical theories such as attachment point theory and the ERI principle have been proposed, there is a lack of convincing

explanations focused on the biological process of adhesion. Consequently, it is difficult to apply these results to industrial application. To resolve this, the association between the physical properties of the surface and biochemical process of adhesion needs to be determined.

Although the secretions of organisms such as enzymes and metabolites are biodegradable, it is difficult to anticipate their impact on the marine environment if they are broadly applied on ships. A high concentration of secretions could influence the surrounding marine conditions. In contrast, it is guaranteed that physical methods will not affect the environment. Therefore, physical technologies should be explored more in the future as they are feasible, effective, durable and nontoxic.

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