RETRACTION NOTE

Retraction Note to: Cascade controller design and stability analysis in FES-aided upper arm stroke rehabilitation robotic system

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This article has been retracted by the Editor-in-Chief of Nonlinear Dynamics. The stability analysis, which comprises the three-page entirety of Section 4, is an equation-by-equation copy, included without credit or citation, of Section III.C of the paper “Freeman,

Christoper, Tong, Daisy, Meadmore, Katie, Hughes, Ann-Marie, Rogers, Eric and Burrbridge, Jane (2012) [FES based Rehabilitation of the Upper Limb using Input/Output Linearization and ILC](#). In: 2012 American Control Conference, Montréal, 27–29 June 2012, pp. 4825–4830”.

The online version of the original article can be found under doi:[10.1007/s11071-014-1726-1](https://doi.org/10.1007/s11071-014-1726-1).

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