Erratum to: Parameter identification of electronic throttle using a hybrid optimization algorithm

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Presented here are the correct versions of Figs. 8(a), 8(b), 9(a) and 9(b).

Fig. 8 Set-points tracking performance of ETC system with the identified parameter values, angle **(a)** and errors of angle **(b)**

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Fig. 9 Set-points tracking performance of ETC system with the identified parameter values, angle (a) and errors of angle (b)