RETRACTED ARTICLE: Self-calibration of redundantly actuated PKM via motion reverse points: optimization procedure

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This article has been retracted by the author and the Editor-in-Chief per the Committee on Publication Ethics (COPE) guidelines on redundant publication. The article shows an overlap with the following sources: Latest Advances in Robot Kinematics, Springer 2012, ISBN 978-94-007-4619-0 Compu-

tational Kinematics, Proceedings of the 6th International Workshop on Computational Kinematics (CK2013), Springer 2014, ISBN 978-94-007-7213-7 The online version of this article contains the full text of the retracted article as electronic supplementary material.

Electronic supplementary material The online version of this article (doi:[10.1007/s11012-015-0321-y](https://doi.org/10.1007/s11012-015-0321-y)) contains supplementary material, which is available to authorized users.

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