Correction to: Walking Stabilization Control for Humanoid Robots on Unknown Slope Based on Walking Sequences Adjustment

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The original version of this manuscript unfortunately contained errors.

On page 14, “Grant No. 51175383” should be “Grant No. 51675385.” The correct line should read: This research is supported by the National Foundation of China (Grant No. 51675385).

On page 16, the line “Jiatao Ding received the B.S. degree in Mechanical Design, Manufacture and Automation in 2010 from Wuhan University, China” should be “Jiatao Ding received the B.S. degree in Mechanical Design, Manufacture and Automation in 2014 from Wuhan University, China.”

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