ERRATUM

Erratum to: Optimal Capture of a Tumbling Object in Orbit Using a Space Manipulator

Angel Flores-Abad · Lin Zhang ·
Zheng Wei · Ou Ma

Published online: 9 November 2016
© Springer Science+Business Media Dordrecht 2016

Erratum to: J Intell Robot Syst
DOI 10.1007/s10846-016-0417-1

The original version on this paper contained an error.

The τ shown in equation 11 should be changed to $\dot{\theta}$. The correct formula is given below.

$$\mathbf{x} = \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} = \begin{bmatrix} \theta \\ \dot{\theta} \end{bmatrix}$$

The online version of the original article can be found at
<http://dx.doi.org/10.1007/s10846-016-0417-1>.

A. Flores-Abad (✉)
Mechanical Engineering Department, University of Texas
at El Paso, El Paso, TX 79968, USA
e-mail: afloresabad@utep.edu

L. Zhang · O. Ma
Department of Mechanical and Aerospace Engineering,
New Mexico State University, Las Cruces, NM 88003, USA

Z. Wei
Department of Mathematics and Statistics, University
of Massachusetts Amherst, Amherst, MA 01002, USA