Erratum to: Models of passive and active dendrite motoneuron pools and their differences in muscle force control

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Equations (1), (2), and (3) in the published paper are inconsistent with the electrical diagram shown in Fig. 1 (c). The following ought to be used instead:

$$\dot{V}_x(t) = -\frac{1}{C_x} \{g_{L,x}[V_x(t) - E_L] + g_c[V_x(t) - V_y(t)] + I_{ion,x}(t) + I_{syn,x}(t)\} \quad (1)$$

$$I_{ions,S}(t) = \overline{g_{Na}}m^3(t)h(t)[V_S(t) - E_{Na}] + \overline{g_{Kf}}n^4(t)[V_S(t) - E_K] + \overline{g_{Ks}}q^2(t)[V_S(t) - E_K] \quad (2)$$

$$I_{ion,D}(t) = \gamma\{\overline{g_{Ca}}p(t)[V_D(t) - E_{Ca}]\} \quad (3)$$

The online version of the original article can be found at <http://dx.doi.org/10.1007/s10827-012-0398-4>.

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