

## Superforms in five-dimensional, $N = 1$ superspace

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**ABSTRACT:** We examine the five-dimensional super-de Rham complex with  $N = 1$  supersymmetry. The elements of this complex are presented explicitly and related to those of the six-dimensional complex in  $N = (1, 0)$  superspace through a specific notion of dimensional reduction. This reduction also gives rise to a second source of five-dimensional supercycles that is based on the relative cohomology of the two superspaces. In the process of investigating these complexes, we discover various new features including branching and fusion (loops) in the super-de Rham complex, a natural interpretation of “Weil triviality”,  $p$ -cocycles that are not supersymmetric versions of closed bosonic  $p$ -forms, and the opening of a “gap” in the complex for  $D > 4$  in which we find a multiplet of superconformal gauge parameters.

**KEYWORDS:** Extended Supersymmetry, Superspaces

**ARXIV EPRINT:** [1412.4086](https://arxiv.org/abs/1412.4086)

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**Contents**

<b>1</b>	<b>Introduction</b>	<b>1</b>
<b>2</b>	<b>A retrospective &amp; prospective perspective</b>	<b>3</b>
<b>3</b>	<b>Closed five-dimensional superforms</b>	<b>6</b>
3.1	The five-dimensional 1-form	6
3.2	The five-dimensional 2-form	7
3.2.1	An alternative 2-cocycle	8
3.3	The five-dimensional 3-cocycle	9
3.4	The five-dimensional 4- and 5-forms	10
<b>4</b>	<b>Dimensional reduction</b>	<b>11</b>
4.1	Relative cohomology	12
<b>5</b>	<b>Field content in 5D</b>	<b>15</b>
5.1	The vector multiplet ( $p = 2$ )	15
5.2	The tensor multiplet ( $p = 3$ )	16
5.3	The linear multiplet ( $p = 4$ )	17
5.4	Reducible multiplets	18
<b>6</b>	<b>Conclusions</b>	<b>19</b>
<b>A</b>	<b>Five-dimensional, <math>N = 1</math> superspace</b>	<b>20</b>

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**1 Introduction**

The subject of  $p$ -forms over superspace manifolds (“super  $p$ -forms”) had its beginnings in 1977 when a number of authors [1–5] led by J. Wess noted that within the context of supergravity and supersymmetric gauge theories, the usual notion of 1-forms could possess extensions in superspace. The first two works considered the formal structure and definitions of super  $p$ -forms for only the  $p = 1$  case. There was no guidance provided on the extension of super  $p$ -forms to  $p > 1$ . In that same year, the problem of establishing an integration theory for super  $p$ -forms was begun [4, 5]. In this early, more general discussion of super  $p$ -forms with  $p > 1$  there appears to have been little, if any, attention paid to the role of constraints.

This situation changed in 1980 when it was shown [6] how to construct an entire  $N = 1$  four-dimensional super-de Rham complex of super  $p$ -forms (with  $0 < p < 4$ ) over a supermanifold. Furthermore, for the first time a set of constraints required for the irreducibility of the supermultiplets for each value of  $p$  was established.

During this period some authors turned their attention to the problem of establishing a theory of integration for super  $p$ -forms on supermanifolds and significant formal progress was made [7–11]. However, in 1997 one of the authors (SJG) put forth the “Ectoplasmic Integration Theory (EIT)” [12–15] that stressed the role of super  $p$ -form constraints in integration theory.

The basis for the EIT approach is an assertion about topology. It is suggested that the integration theory over a supermanifold requires that the entire supermanifold is, at the level of topology, essentially indistinguishable from its bosonic submanifold. This is referred to as “the ethereal conjecture” and immediately leads to an integration theory that necessarily includes elements of cohomology. As super  $p$ -forms are inextricably linked to cohomological calculations, the EIT approach demands an integration theory where super  $p$ -forms play a prominent role.

The EIT approach is more than just a formal statement of the properties of super  $p$ -forms and their theory of integration. In its initial presentations, it was shown to solve a problem related to superspace density measures that had been stated by Zumino. This was done on the basis of the ethereal conjecture and led to a superspace analog of Stokes’ Theorem, modified appropriately to hold for both rigid and local supermanifolds. By now, the EIT approach has led to a number of practical results that include:

- (1) a highly efficient derivation of supergravity density measures [16–19],
- (2) a superspace formulation for 4D,  $N = 8$  supergravity counterterms [20],
- (3) a covariant formulation of 4D,  $N = 4$  supergravity anomalies/divergences [21, 22],
- (4) complete formulations of integration on supermanifolds with boundaries [23],
- (5) a supergravity derivation of a minimal unitary representation of the string effective action [24, 25], and
- (6) establishing the relationship between superspace integration theory and the picture-changing formalism of superstring theory [26].

We believe these all speak powerfully to the motivations behind efforts to understand as fully as possible the structure of super-de Rham complexes in general.

We begin this article with a review of superforms in four-dimensional,  $N = 1$  superspace in section 2. In section 3, we work out the cocycles of the de Rham complex of five-dimensional,  $N = 1$  superspace. This is done sequentially by obstructing the closure conditions on a  $p$ -cocycle to get a  $(p + 1)$ -coboundary. In the process, we generate the supersymmetric version of closed de Rham  $p$ -forms for all values of  $p$  except for  $p = 3$  where we find a 3-cocycle that can be interpreted as a multiplet of superconformal gauge parameters instead.

In section 4 these cocycles are related to those in the corresponding six-dimensional complex *via* dimensional reduction. In this reduction, we find a second type of cocycle in the relative cohomology arising from the embedding of the five-dimensional superspace in the six-dimensional one. The missing 3-form can then be interpreted as the 3-cocycle of this

$p$	$p$ -form
0	$\varphi$
1	$A_a$
2	$t_{ab}$
3	$\mathcal{X}_{abc}$
4	$\mathcal{Y}_{abcd}$

**Table 1.** 4D,  $N = 0$   $p$ -form complex.

$p$	Field-Strength	Gauge Variation Function
0	$\partial_a \varphi$	$c_0$
1	$\partial_a A_b - \partial_b A_a$	$\partial_a \lambda$
2	$\partial_a t_{bc} + \partial_b t_{ca} + \partial_c t_{ab}$	$\partial_a \lambda_b - \partial_b \lambda_a$
3	$\partial_a \mathcal{X}_{bcd} - \partial_b \mathcal{X}_{cda} + \partial_c \mathcal{X}_{dab} - \partial_d \mathcal{X}_{abc}$	$\partial_a \lambda_{bc} + \partial_b \lambda_{ca} + \partial_c \lambda_{ab}$
4	0	$\partial_a \lambda_{bcd} - \partial_b \lambda_{cda} + \partial_c \lambda_{dab} - \partial_d \lambda_{abc}$

**Table 2.** 4D,  $N = 0$  field strengths & gauge variations.

Degree	Field-Strength	Gauge Variation Function
$p$	$\frac{1}{p!} \partial_{[a_1} \mathcal{P}_{ a_2 \dots a_{p+1}]}$	$\frac{1}{(p-1)!} \partial_{[a_1} \lambda_{ a_2 \dots a_{p-1}]}$

**Table 3.** 4D,  $N = 0$  field strengths & gauge variations.

relative complex. Finally, in section 5 we examine the component fields of the multiplets defined by  $p$ -form field-strengths for  $p = 2, 3, 4$ . The 2-form and 4-form are the well-known vector and linear multiplets, respectively and are in the super-de Rham complex, whereas the 3-form as found in the relative complex is an on-shell tensor multiplet. Our conventions and some useful identities for this superspace are provided in appendix A.

## 2 A retrospective & prospective perspective

There exists a well-known hierarchy of  $p$ -forms in four-dimensional spacetime where for each value of  $p$  there exists a field, respectively denoted in table 1 by  $\varphi$ ,  $A_a$ ,  $t_{ab}$ ,  $\mathcal{X}_{abc}$ , and  $\mathcal{Y}_{abcd}$ . Each such field component is completely antisymmetric on the exchange of its vector indices and describes a gauge field with field-strength and gauge transformation shown in table 2.

It is seen that all the field-strengths and gauge variations can be collectively written in the forms given in table 3, but in the special case of  $p = 0$ , the gauge variation is not a local function. Instead the quantity  $c_0$  is a modulus parameter implying the absence of a potential function for the scalar field  $\varphi$ .

The results first given in [6] established the existence of a complex among *constrained* super  $p$ -form superfields as an extension of the non-supersymmetric structures above and

$p$	$p$ -form Superfield
0	$\Gamma$
1	$\Gamma_A$
2	$\Gamma_{AB}$
3	$\Gamma_{ABC}$
4	$\Gamma_{ABCD}$

**Table 4.** 4D,  $N = 1$   $p$ -form complex.

$p$	Prepotential	Field Strength SF	Gauge Variation SF
0	$\Phi$	$i\frac{1}{2}(\Phi - \bar{\Phi})$	$c_0$
1	$V$	$i\bar{D}^2 D_\alpha V$	$i\frac{1}{2}(\Lambda - \bar{\Lambda})$
2	$V_\alpha$	$\frac{1}{2}(D^\alpha V_\alpha + \bar{D}^{\dot{\alpha}} \bar{V}_{\dot{\alpha}})$	$i\bar{D}^2 D_\alpha \Lambda$
3	$V'$	$D^2 V'$	$\frac{1}{2}(D^\alpha \Lambda_\alpha + \bar{D}^{\dot{\alpha}} \bar{\Lambda}_{\dot{\alpha}})$
4	$\Phi'$	0	$D^2 \Lambda$

**Table 5.** 4D,  $N = 1$  de Rham complex.

are summarized in the following table. Super  $p$ -forms in general possess “super vector” indices that take on bosonic and fermionic values as in  $A = (a, \alpha, \dot{\alpha})$ . The analogous fields are displayed in table 4, where each of the quantities denoted by  $\Gamma$  is now a superfield. In the work of [6] a complete listing of all the irreducible Lorentz representations for each of the super  $p$ -forms can be found. Each super  $p$ -form possesses a Bianchi identity, field-strength superfield and a corresponding gauge variation that are  $N = 1$  extensions of the results in table 3. These take the forms given in equations (2.7) through (2.9) of [6].

The major discovery in [6] was to identify a complex of 4D,  $N = 1$  *prepotentials* for the  $p$ -forms, shown in table 5. These prepotentials had been known in both super Yang-Mills (the familiar  $V$ ) and supergravity (the familiar  $H^a$ ) for some time. Thus, the result was established that gauge 4D,  $N = 1$   $p$ -form superfields also have prepotentials and themselves form a complex without reference to the  $p$ -forms in table 4.

These prepotentials appear in the geometrical  $p$ -form superfields *via* the following equations

- $p = 1$

$$\begin{aligned} \Gamma_\alpha &= i D_\alpha V \quad , \quad V = \bar{V} \quad , \\ \Gamma_a &= \frac{1}{4} \sigma_a^{\alpha\dot{\beta}} \left[ D_\alpha \quad , \quad \bar{D}_{\dot{\beta}} \right] V \quad , \end{aligned}$$

- $p = 2$

$$\begin{aligned} \Gamma_{\alpha\beta} &= \Gamma_{\alpha\dot{\beta}} = 0 \quad , \\ \Gamma_{\alpha b} &= i \sigma_{b\alpha\dot{\gamma}} \bar{V}^{\dot{\gamma}} \quad , & D_a \bar{V}_{\dot{\beta}} &= 0 \\ \Gamma_{ab} &= i \frac{1}{4} \left[ (\sigma_{ab})^{\gamma\delta} D_\gamma V_\delta + (\bar{\sigma}_{ab})^{\dot{\gamma}\dot{\delta}} \bar{D}_{\dot{\gamma}} \bar{V}_{\dot{\delta}} \right] \quad . \end{aligned}$$

$p$	Prepotential	Field-Strength SF	Gauge Variation SF
0	$\chi^{\alpha(ij)}_k$	$D_{\alpha k} \chi^{\alpha(jk)}_i + \bar{D}_{\dot{\alpha}}^k \bar{\chi}^{\dot{\alpha}j}_{(ik)}$	--
1	$V_i{}^j$	$\bar{D}^{(4)} D_{ij}^{(2)} C^{ik} V_k{}^j$	$D_{\alpha k} \chi^{\alpha(jk)}_i + \bar{D}_{\dot{\alpha}}^k \bar{\chi}^{\dot{\alpha}j}_{(ik)}$
2	$\Phi$	$i(C^{jk} D^{(2)}_{ik} \Phi - C_{ik} \bar{D}^{(2)jk} \bar{\Phi})$	$\bar{D}^{(4)} D_{ij}^{(2)} C^{ik} V_k{}^j$

**Table 6.** Known partial 4D,  $N = 2$  complex.

- $p = 3$

$$\begin{aligned}
 \Gamma_{\alpha\beta\gamma} &= \Gamma_{\alpha\beta c} = \Gamma_{\alpha\beta\dot{\nu}} = 0 \quad , \\
 \Gamma_{\alpha\dot{\beta}c} &= i \sigma_{c\alpha\dot{\beta}} V' \quad , \quad V' = \bar{V}' \quad , \\
 \Gamma_{abc} &= -i \frac{1}{2} (\sigma_{bc})_{\alpha\dot{\delta}} \bar{D}^{\dot{\delta}} V' \quad , \\
 \Gamma_{abc} &= \frac{1}{4} \varepsilon_{abcd} \sigma^{d\beta\dot{\gamma}} [D_{\beta}, \bar{D}_{\dot{\gamma}}] V' \quad ,
 \end{aligned}$$

- $p = 4$

$$\begin{aligned}
 \Gamma_{\alpha\beta\gamma\delta} &= \Gamma_{\alpha\beta\dot{\gamma}\delta} = \Gamma_{\alpha\beta\gamma d} = \Gamma_{\alpha\beta\dot{\gamma} d} = \Gamma_{\alpha\dot{\beta}cd} = D_{\alpha} \bar{\Phi}' = 0 \quad , \\
 \Gamma_{\alpha\beta cd} &= i \frac{1}{2} (\sigma_{cd})_{\alpha\beta} \bar{\Phi}' \quad , \quad \Gamma_{\beta def} = -\frac{1}{4} \varepsilon_{defg} \sigma^g_{\beta\dot{\gamma}} \bar{D}^{\dot{\gamma}} \bar{\Phi}' \quad , \\
 \Gamma_{abcd} &= i \varepsilon_{abcd} (D^2 \Phi' - \bar{D}^2 \bar{\Phi}') \quad ,
 \end{aligned}$$

A major unfinished task in supersymmetric field theory is to construct this complex of prepotentials for all dimensions and all degrees of extension.

There is a close relation between the 4D,  $N = 2$  and 5D,  $N = 1$  superspaces. Thus, the works of [27] and [28] are closely related to our present considerations. As the formulation of [27] involves harmonics and as we will not venture in that direction in this work, we restrict our review to the portion of the work of [28] that is relevant here.

The work of [28] gave an incomplete presentation of the obstruction complex. It explicitly treated the cases of  $p = 1$  and  $p = 2$  and made an implication for the case of  $p = 0$ , but the higher values of  $p$  were not treated. These results are summarized in table 6.

Given the superfields that appear in this table, there are several points to note. The superfield  $\chi^{\alpha(ij)}_k$  is a spinorial prepotential that is symmetric on the  $i$  and  $j$  indices. At the time this partial complex was presented, it was not known how to use  $\chi^{\alpha(ij)}_k$  to construct a supermultiplet of propagating fields. This is to be contrasted with the case of  $N = 1$  where the superfield that appears in the  $p = 1$  obstruction superfield transformation can be used to describe  $N = 1$  supermatter. However, in the work of [29] it was shown that such a superfield is capable of describing a type of  $N = 2$  hypermultiplet in analogy with superfield  $N = 1$ ,  $p = 1$  gauge parameter. The superfield  $V_i{}^j$  is often called the ‘‘Mezincescu prepotential’’ as it first appeared in the work of [30]. It is a hermitian traceless matrix

on its isospin indices  $i$  and  $j$ . Finally, the superfield  $\Phi$  in table 6 is chiral  $\bar{D}_\alpha^i \Phi = 0$  with respect to 4D,  $N = 2$  supersymmetry.

With the story and background of four-dimensional superforms firmly in mind, we now move towards the complex of forms in five-dimensional,  $N = 1$  superspace. Although the logical conclusion of this line of investigation is the construction of the complex at the level of prepotentials, the first step in the process is the construction of the complex at the level of field-strength superfields. As such, we will content ourselves in this work with the derivation of the constraints on the superfields to which the would-be prepotentials are the unconstrained solutions. Already at this level, we will encounter some unexpected complications and elucidate some features of the five-dimensional super-de Rham complex. As mentioned previously, these include branching in the the complex (section 3.2), the existence of a second “relative cohomology” complex (section 4.1), and even  $p$ -cocycles that are not the supersymmetrization of  $p$ -forms (section 5.4). As will become apparent, these features are expected to manifest generically in superspaces with  $D > 4$ .

### 3 Closed five-dimensional superforms

In this section, we work out the super-de Rham cocycles arising by identifying suitable constraints and obstructing them, starting with the closed 1-form in section 3.1. The components of the  $p^{\text{th}}$  cocycle are related by the superspace Bianchi identities [31–33]

$$0 = \frac{1}{p!} D_{[A_1} \omega_{A_2 \dots A_{p+1}]} + \frac{1}{2!(p-1)!} T_{[A_1 A_2]}^C \omega_{C|A_3 \dots A_{p+1}].} \quad (3.1)$$

This collection is graded by increasing engineering dimension with the component  $\omega_{\underline{\alpha}_1 \dots \underline{\alpha}_r, a_1 \dots a_s}$  having dimension  $\frac{r}{2} + s$ . This allows the determination of the higher-dimension components of the cocycle in terms of the lowest non-vanishing one(s). This lowest non-vanishing component will be a superfield, possibly in a non-trivial (iso-)spin representation.

In addition to determining the components of the cocycle in terms of this defining superfield, the Bianchi identities generally impose a series of constraints on it, again organized by engineering dimension. As we will see, the highest of these can be obstructed, thereby defining a cocycle of degree 1 higher in the complex. The complex can branch if it happens that there is more than one constraint on the defining superfield in the highest dimension (as we will see explicitly when passing from the 1-cocycle to the 2-cocycle) and we work out the components of each of the resulting cocycles.

#### 3.1 The five-dimensional 1-form

We begin the construction on the de Rham complex with the 1-form  $\omega_A = A_A$ . Closure of  $A$  is equivalent to the Bianchi identity

$$0 = 2D_{[A} A_{B]} + T_{AB}^C A_C. \quad (3.2)$$

The closure condition with the lowest engineering dimension has  $AB = \hat{\alpha}i\hat{\beta}j$ :

$$0 = D_{\hat{\alpha}i} A_{\hat{\beta}j} + D_{\hat{\beta}j} A_{\hat{\alpha}i} - 2i\varepsilon_{ij}(\Gamma^{\hat{a}})_{\hat{\alpha}\hat{\beta}} A_{\hat{a}}. \quad (3.3)$$

Since it is symmetric on composite spinor indices, (anti-)symmetrizing on the (iso-)spin indices gives three irreducible parts corresponding to the scalar, anti-symmetric tensor, and vector representations. The first two give the constraints

$$D^{\hat{\alpha}i}A_{\hat{\alpha}i} = 0 \quad \text{and} \quad D_{(\hat{\alpha}(i}A_{\hat{\beta})j)} = 0, \quad (3.4)$$

while the third determines the vector component of  $A$  in terms of its spinor component

$$A_{\psi} = -\frac{i}{8}D^i\Gamma_{\psi}A_i. \quad (3.5)$$

If we attempt to partially solve these constraints as  $A_{\hat{\alpha}i} = D_{\hat{\alpha}i}U + D_{\hat{\alpha}}^jU_{ij}$ , then they demand that  $D_{\hat{a}\hat{b}}^2U_{ij} = 0$  and  $D_{ij}^2U^{ij} = 0$ , respectively, while  $U$  remains unconstrained.<sup>1</sup> The components are then given as

$$A_{\hat{\alpha}i} = D_{\hat{\alpha}i}U + D_{\hat{\alpha}}^jU_{ij} \quad \text{and} \quad A_{\hat{a}} = \partial_{\hat{a}}U - \frac{i}{4}D_{\hat{a}ij}^2U^{ij}. \quad (3.6)$$

The dimension- $\frac{3}{2}$  Bianchi identity is solved identically through use of the dimension-1 constraints. The dimension-2 Bianchi identity already holds as well, since

$$\partial_{[\hat{a}}A_{\hat{b}]} = -\frac{i}{4}\partial_{[\hat{a}}D_{\hat{b}]ij}^2U^{ij} = \frac{1}{16}[D_{ij}^2, D_{\hat{a}\hat{b}}^2]U^{ij} = 0. \quad (3.7)$$

Thus, the components (3.6) and constraints (3.4) together give a closed 1-form field-strength in five dimensions.

### 3.2 The five-dimensional 2-form

The closed 2-form  $F = dA$  is the exterior derivative of a gauge 1-form  $A$  and can be interpreted, therefore, as the obstruction to the 1-form's closure. By setting the lowest component of  $F$  to be the obstruction to the scalar constraint in (3.4), we have

$$F_{\hat{\alpha}i\hat{\beta}j} = (dA)_{\hat{\alpha}i\hat{\beta}j} =: 2i\varepsilon_{ij}\varepsilon_{\hat{\alpha}\hat{\beta}}\mathcal{W}, \quad (3.8)$$

for some dimension-1 field-strength  $\mathcal{W}$ . Now that we have the lowest component of  $F$ , the remaining components and any constraints on  $\mathcal{W}$  follow uniquely from (3.1). For purposes of exposition, we will give a fairly in-depth look at the calculations that go into this analysis in this section, but we will suppress the analogous steps in the following sections.

To begin, consider the dimension- $\frac{3}{2}$  condition

$$0 = D_{\hat{\alpha}i}F_{\hat{\beta}j\hat{\gamma}k} + 2i\varepsilon_{ij}(\Gamma^{\hat{a}})_{\hat{\alpha}\hat{\beta}}F_{\hat{\gamma}k\hat{a}} + (\underline{\alpha\beta\gamma}). \quad (3.9)$$

Here  $\underline{\alpha} \equiv \hat{\alpha}i$  and the notation  $(\underline{\cdot})$  denotes the remaining cyclic permutations of the enclosed composite indices. Plugging in  $F_{\hat{\alpha}i\hat{\beta}j}$ , we find that  $F_{\hat{\alpha}i\hat{a}}$  is fixed to be

$$F_{\hat{\alpha}i\hat{a}} = -(\Gamma_{\hat{a}})_{\hat{\alpha}}^{\hat{\beta}}D_{\hat{\beta}i}\mathcal{W}. \quad (3.10)$$

---

<sup>1</sup>These constraints can be solved in terms of unconstrained prepotentials (cf. e.g. ref. [30]), but we will not need their solution here.



The dimension-2 condition, upon plugging in the known components and expanding the  $DD$  terms with (A.6), becomes

$$0 = \left[ -i\varepsilon_{ij}(\Gamma_{\hat{a}}\Gamma^{\hat{b}})_{\hat{\beta}\hat{\alpha}}\partial_b - \frac{1}{2}\varepsilon_{ij}(\Gamma_{\hat{a}}\Sigma^{\hat{b}\hat{c}})_{\hat{\beta}\hat{\alpha}}D_{\hat{b}\hat{c}}^2 + \frac{1}{2}(\Gamma_{\hat{a}}\Gamma^{\hat{b}})_{\hat{\beta}\hat{\alpha}}D_{\hat{b}ij}^2 - \frac{1}{2}(\Gamma_{\hat{a}})_{\hat{\beta}\hat{\alpha}}D_{ij}^2 + (\underline{\alpha\beta}) \right] \mathcal{W} - 2i\varepsilon_{ij}\varepsilon_{\hat{\alpha}\hat{\beta}}\partial_a\mathcal{W} + 2i\varepsilon_{ij}(\Gamma^{\hat{b}})_{\hat{\alpha}\hat{\beta}}F_{\hat{b}\hat{a}}. \quad (3.11)$$

The  $(\underline{\alpha\beta})$  symmetry kills the final term in the  $DD$  expansion and allows the  $\partial\mathcal{W}$  terms to cancel. Additionally, it restricts the irreducibles in the remaining two terms of the  $DD$  expansion, leaving behind the relation

$$0 = [-\varepsilon_{ij}(\Gamma^{\hat{b}})_{\hat{\beta}\hat{\alpha}}D_{\hat{a}\hat{b}}^2 - 2(\Sigma_{\hat{a}}^{\hat{b}})_{\hat{\alpha}\hat{\beta}}D_{\hat{b}ij}^2] \mathcal{W} + 2i\varepsilon_{ij}(\Gamma^{\hat{b}})_{\hat{\alpha}\hat{\beta}}F_{\hat{b}\hat{a}}. \quad (3.12)$$

Because of the (anti-)symmetry in the  $ij$  indices, this is actually two separate conditions with one defining the component  $F_{\hat{a}\hat{b}}$  and the other putting a restriction on  $\mathcal{W}$ . The former yields

$$F_{\hat{a}\hat{b}} = -\frac{i}{2}D_{\hat{a}\hat{b}}^2\mathcal{W}, \quad (3.13)$$

while the latter requires

$$D_{\hat{a}ij}^2\mathcal{W} = 0. \quad (3.14)$$

From (A.6), this is equivalent to

$$D_{\hat{\alpha}}^{(i}D_{\hat{\beta}}^{j)}\mathcal{W} = \frac{1}{4}\varepsilon_{\hat{\alpha}\hat{\beta}}D^{\hat{\gamma}(i}D_{\hat{\gamma}}^{j)}\mathcal{W}. \quad (3.15)$$

Continuing with the dimension- $\frac{5}{2}$  condition, we substitute the components of  $F$  to find

$$D_{\hat{\alpha}i}D_{(\hat{\beta}}^kD_{\hat{\gamma})k}\mathcal{W} = 4i\hat{\phi}_{\hat{\delta}(\hat{\beta}\varepsilon_{\hat{\gamma})\hat{\alpha}}}D_i^{\hat{\delta}}\mathcal{W} - 4i\hat{\phi}_{\hat{\alpha}(\hat{\beta}}D_{\hat{\gamma})i}\mathcal{W}. \quad (3.16)$$

Through a bit of  $\Gamma$ -matrix algebra this can be shown to come directly from (3.14) by expanding and simplifying

$$(\Gamma_{\hat{a}})_{\hat{\alpha}\hat{\beta}}(\Gamma_{\hat{b}})_{\hat{\gamma}\hat{\delta}}(\Sigma^{\hat{a}\hat{b}})_{\hat{\rho}\hat{\tau}}D^{\hat{\beta}i}D_{(i}D_{\hat{j})}^{\hat{\delta}}\mathcal{W} = 0. \quad (3.17)$$

The dimension-3 closure condition, like the dimension- $\frac{5}{2}$  condition (3.16), holds identically since

$$\varepsilon_{\hat{a}\hat{b}}^{\hat{c}\hat{d}\hat{e}}\partial_{\hat{c}}F_{\hat{d}\hat{e}} = -\frac{i}{2}\varepsilon_{\hat{a}\hat{b}}^{\hat{c}\hat{d}\hat{e}}\partial_{\hat{c}}D_{\hat{d}\hat{e}}^2\mathcal{W} = \frac{1}{12}[D_{\hat{a}ij}^2, D_{\hat{b}}^{2ij}]\mathcal{W} = 0. \quad (3.18)$$

Thus, the only constraint on  $\mathcal{W}$  is (3.14) which, as we review in section 5.1, identifies it as the field-strength of the off-shell vector multiplet in five dimensions.

### 3.2.1 An alternative 2-cocycle

Instead of obstructing the first constraint in (3.4), we may define

$$\tilde{F}_{\underline{\alpha\beta}} = (\Sigma^{\hat{a}\hat{b}})_{\hat{\alpha}\hat{\beta}}C_{\hat{a}\hat{b}ij} \quad (3.19)$$

and proceed with this as our lowest component. Repeating the previous analysis, the remaining components are found to be

$$\tilde{F}_{\underline{\alpha}\hat{a}} = \frac{i}{12}\varepsilon_{\psi}^{\hat{a}\hat{b}\hat{c}\hat{d}}(\Sigma_{\hat{a}\hat{b}})_{\hat{\alpha}}^{\hat{\beta}}D_{\hat{\beta}}^j C_{\hat{c}\hat{d}ij} \quad \text{and} \quad \tilde{F}_{\hat{a}\hat{b}} = -\frac{1}{48}\varepsilon_{\hat{a}\hat{b}}^{\hat{c}\hat{d}\hat{e}}D_{\hat{c}ij}^2 C_{\hat{d}\hat{e}}^{ij}. \quad (3.20)$$

The dimension-1 field-strength  $C_{\hat{a}\hat{b}ij}$  is constrained by the dimension- $\frac{3}{2}$  Bianchi identity to satisfy

$$(\Sigma_{\hat{a}\hat{b}})_{(\hat{\alpha}\hat{\beta}}D_{\hat{\gamma})(i}C_{j\hat{k})}^{\hat{a}\hat{b}} = 0 \quad (3.21)$$

and by the dimension-2 Bianchi identity to satisfy

$$6i\partial^{\hat{b}}C_{\hat{a}\hat{b}ij} + D_{(i}^{2\hat{b}k}C_{j)k\hat{a}\hat{b}} - 2D_{\hat{a}\hat{b}\hat{c}}^2 C_{ij}^{\hat{b}\hat{c}} = 0. \quad (3.22)$$

The first of these, (3.21), can be re-cast in the form

$$\Pi_{\hat{a}\hat{b}\hat{\alpha}}^{\hat{c}\hat{d}\hat{\beta}}D_{\hat{\beta}(i}C_{\hat{c}\hat{d}j\hat{k})} = 0, \quad (3.23)$$

where

$$\Pi_{\hat{a}\hat{b}\hat{\alpha}}^{\hat{c}\hat{d}\hat{\beta}} := \delta_{[\hat{a}}^{\hat{c}}\delta_{\hat{b}]}^{\hat{d}}\delta_{\hat{\alpha}}^{\hat{\beta}} + \frac{1}{5}(\Sigma_{\hat{a}\hat{b}}\Sigma^{\hat{c}\hat{d}})_{\hat{\alpha}}^{\hat{\beta}} \quad (3.24)$$

is the projection operator onto the  $\Sigma$ -traceless subspace of the (2-form) $\otimes$ (spinor) representation space. With these constraints in place, the top two Bianchi identities (at dimensions  $\frac{5}{2}$  and 3) do not imply any new conditions on  $C_{\hat{a}\hat{b}ij}$ .

### 3.3 The five-dimensional 3-cocycle

We have obstructed the closure of the 1-form potential in two independent ways and found that each of these is obstructed in turn. The new constraints (3.14) and (3.22) are both dimension-2, vector-valued, isotriplet superfields. To generate the 3-form, we obstruct the closure of the 2-form as  $H = dF$  in either incarnation. The components of  $H$  are then uniquely determined to be

$$\begin{aligned} H_{\underline{\alpha}\beta\gamma} &= 0, & H_{\underline{\alpha}\hat{b}\hat{a}} &= (\Sigma_{\hat{a}\hat{b}})_{\hat{\alpha}\hat{\beta}}H_{ij}^{\hat{b}}, \\ H_{\underline{\alpha}\hat{a}\hat{b}} &= \frac{i}{12}\varepsilon_{\hat{a}\hat{b}}^{\hat{c}\hat{d}\hat{e}}(\Sigma_{\hat{c}\hat{d}})_{\hat{\alpha}}^{\hat{\beta}}D_{\hat{\beta}}^j H_{\hat{e}ij}, & H_{\hat{a}\hat{b}\hat{c}} &= \frac{1}{48}\varepsilon_{\hat{a}\hat{b}\hat{c}}^{\hat{d}\hat{e}}D_{\hat{d}ij}^2 H_{\hat{e}}^{ij}, \end{aligned} \quad (3.25)$$

where the dimension-2 field  $H_{\hat{a}ij}$  satisfies the condition

$$(\Sigma_{\hat{a}\hat{b}})_{(\hat{\alpha}\hat{\beta}}D_{\hat{\gamma})(i}H_{j\hat{k})}^{\hat{a}\hat{b}} = 0 \quad (3.26)$$

at dimension  $\frac{5}{2}$  and

$$D_{\hat{a}k(i}^2 H_{j)}^{\hat{a}k} + 6i\partial_{\hat{a}}H_{ij}^{\hat{a}} = 0 \quad (3.27)$$

at dimension 3.

The way in which the constraints “fit together” here is fairly interesting. At dimension  $\frac{5}{2}$ , it is not difficult to see that (3.26) is equivalent to

$$\Pi_{\hat{a}\hat{\alpha}}^{\hat{b}\hat{\beta}}D_{\hat{\beta}(i}H_{j\hat{k})}^{\hat{a}\hat{b}} = 0, \quad (3.28)$$

where

$$\Pi_{\hat{a}\hat{\alpha}}^{\hat{b}\hat{\beta}} := \delta_{\hat{a}}^{\hat{b}}\delta_{\hat{\alpha}}^{\hat{\beta}} + \frac{1}{5}(\Gamma_{\hat{a}}\Gamma^{\hat{b}})_{\hat{\alpha}}^{\hat{\beta}} \quad (3.29)$$

is a projection operator, this time onto the  $\Gamma$ -traceless subspace of the (vector) $\otimes$ (spinor) representation. The question, then, is: what part of the dimension-3 Bianchi identity does this already imply, and what part is an independent constraint? If we look at the dimension-3 closure condition more carefully, we find three independent conditions: equation (3.27) and the following two ‘‘constraints’’

$$0 = D_{(\hat{a}k(i}H_{\hat{b})j)}^k - 4i\partial_{(\hat{a}}H_{\hat{b})ij} - \text{trace}, \quad (3.30)$$

$$0 = D_{[\hat{a}k(i}H_{\hat{b}]j)}^k - 4i\partial_{[\hat{a}}H_{\hat{b}]ij} - \frac{1}{6}\varepsilon_{\hat{a}\hat{b}\hat{c}\hat{d}\hat{e}}D^{\hat{e}k}(\Sigma^{\hat{c}\hat{d}})_{\hat{\xi}}^{\hat{\gamma}}D_{\hat{\gamma}k}H_{ij}^{\hat{e}}. \quad (3.31)$$

However, these two conditions follow from (3.28) in the form

$$D_{\hat{\xi}}^k(\Gamma^{\hat{c}})^{\hat{\xi}\hat{\alpha}}\Pi_{\hat{a}\hat{\alpha}}^{\hat{b}\hat{\gamma}}D_{\hat{\gamma}(k}H_{\hat{b}i)j)} = 0 \quad (3.32)$$

by taking the appropriate index (anti-)symmetrizations. Since the  $\Pi$ -projector only spits out parts that are symmetric-traceless and anti-symmetric, it leaves (3.27) untouched and we find it as an independent constraint at dimension 3.

### 3.4 The five-dimensional 4- and 5-forms

Having found that the constraint (3.27) on the 3-form at dimension 3 is independent of the lower-dimensional conditions (3.26), we can obstruct the closure of that form by introducing a Lorentz-singlet, iso-spin triplet superfield  $G_{ij}$  of dimension 3. In terms this superfield, the closed 4-form  $G$  has components

$$\begin{aligned} G_{\alpha\beta\gamma\delta} &= 0, & G_{\alpha\beta\gamma\hat{a}} &= 0, \\ G_{\alpha\beta\hat{a}\hat{b}} &= (\Sigma_{\hat{a}\hat{b}})_{\hat{\alpha}\hat{\beta}}G^{ij}, & G_{\alpha\hat{a}\hat{b}\hat{c}} &= \frac{i}{12}\varepsilon_{\hat{a}\hat{b}\hat{c}}^{\hat{d}\hat{e}}(\Sigma_{\hat{d}\hat{e}})_{\hat{\alpha}}^{\hat{\beta}}D_{\hat{\beta}}^jG^{ij}, \\ G_{\hat{a}\hat{b}\hat{c}\hat{d}} &= -\frac{1}{48}\varepsilon_{\hat{a}\hat{b}\hat{c}\hat{d}}^{\hat{e}}D_{\hat{e}ij}^2G^{ij}, \end{aligned} \quad (3.33)$$

in agreement with reference [23]. At dimension  $\frac{7}{2}$ , the condition

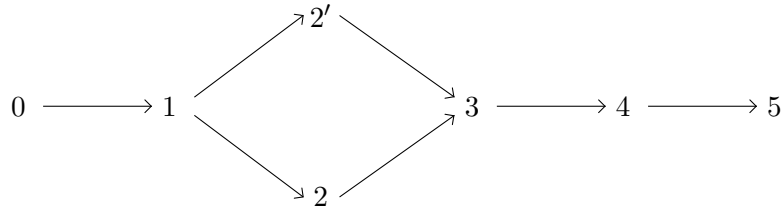
$$D_{\hat{\alpha}(i}G_{jk)} = 0 \quad (3.34)$$

is imposed. All remaining Bianchi identities are then satisfied, with the dimension-5 condition coming from

$$\partial^{\hat{a}}(\star G)_{\hat{a}} = \partial^{\hat{a}}D_{\hat{a}ij}^2G^{ij} = \frac{3i}{16}D_{ijk}^{3\hat{\alpha}}D_{\hat{\alpha}}^kG^{ij} = 0, \quad (3.35)$$

where  $\star G$  stands for the bosonic Hodge dual of the 4-form components  $G_{\hat{a}\hat{b}\hat{c}\hat{d}}$ .

To complete the complex, we proceed in the established way by obstructing the 4-form’s defining condition as  $K = dG$ . Note that this is slightly different than the previous obstructions since now the lowest component  $K$  stays at the same level as that of  $G$ . This



**Figure 1.** The general “obstruction structure” of the five-dimensional super-de Rham complex as constructed in this article.

is required for the lowest Bianchi identity to be satisfied. We then have a closed 5-form  $K$  with components

$$\begin{aligned}
K_{\underline{\alpha}\beta\gamma\underline{\delta}\sigma} &= 0, & K_{\underline{\alpha}\beta\gamma\underline{\delta}\hat{a}} &= 0, & K_{\underline{\alpha}\beta\gamma\hat{a}\hat{b}} &= (\Sigma_{\hat{a}\hat{b}})_{\hat{\alpha}\hat{\beta}} K_{\hat{\gamma}ijk}, \\
K_{\underline{\alpha}\beta\hat{a}\hat{b}\hat{c}} &= -\frac{i}{48} \varepsilon_{\hat{a}\hat{b}\hat{c}}^{\hat{d}\hat{e}} (\Sigma_{\hat{d}\hat{e}})_{\hat{\alpha}}^{\hat{\gamma}} (3D_{\hat{\gamma}}^k K_{\hat{\beta}ijk} - D_{\hat{\beta}}^k K_{\hat{\gamma}ijk}), \\
K_{\underline{\alpha}\hat{a}\hat{b}\hat{c}\hat{d}} &= -\frac{1}{192} \varepsilon_{\hat{a}\hat{b}\hat{c}\hat{d}}^{\hat{e}} (2D_{\hat{e}}^{2jk} K_{\hat{\alpha}ijk} + (\Sigma_{\hat{e}\hat{f}})_{\hat{\alpha}}^{\hat{\beta}} D^{2\hat{f}jk} K_{\hat{\beta}ijk}), \\
K_{\hat{a}\hat{b}\hat{c}\hat{d}\hat{e}} &= \frac{i}{768} \varepsilon_{\hat{a}\hat{b}\hat{c}\hat{d}\hat{e}} D_{\hat{\alpha}ijk}^3 K^{\hat{\alpha}ijk},
\end{aligned} \tag{3.36}$$

where the dimension- $\frac{5}{2}$  field  $K_{\hat{\alpha}ijk}$  satisfies the condition

$$D_{(\hat{\alpha}(i} K_{\hat{\beta})jkl)} = 0 \tag{3.37}$$

through which all the other Bianchi identities are satisfied.

With this, we have found the structure of all the cocycles in super-de Rham complex of the five-dimensional,  $N = 1$  superspace. In the process, we found that the sequence splits, giving rise to two 2-cocycles due to the existence of two independent constraints (3.4) on the components of the 1-cocycle. These 2-cocycles each have a constraint on their components at dimension 2 that that are isomorphic as superfield representations: both equations (3.14) and (3.22) are iso-spin triplets of vectors. Because of this, the 3-cocycle resulting from obstructing these equations is unique and the branching fuses. Its dimension-3 constraint (3.27) is unique as a superfield representation and can be sourced to uniquely define the iso-spin triplet field-strength  $G_{ij}$  of the 4-cocycle. This uniqueness persists to the 5-cocycle. We summarize this structure of the five-dimensional,  $N = 1$  super-de Rham complex in figure 1.

## 4 Dimensional reduction

For the computation of the 4- and 5-forms in the previous section, an alternative to the usual procedure was employed that allowed us to determine the components and constraints on the forms by reducing them from a higher-dimensional complex. The observation is that the five-dimensional,  $N = 1$  de Rham complex has a simple interpretation as a specific part of the dimensional reduction of of the six-dimensional,  $N = (1, 0)$  de Rham complex studied in [34, 35]. To see this, consider the generic form of a Bianchi identity for a closed

$p$ -form  $\omega$  in flat 6D superspace. This identity is formally identical to (3.1) as the formula makes no explicit reference to the dimension. Written in  $5 + 1$  dimensions this splits into two equations:

$$0 = \frac{1}{p!} D_{[A_1} \omega_{A_2 \dots A_{p+1}]} + \frac{1}{2!(p-1)!} T_{[A_1 A_2]}^C \omega_{C|A_3 \dots A_{p+1}} + \frac{1}{2!(p-1)!} T_{[A_1 A_2]}^6 \omega_{6|A_3 \dots A_{p+1}}, \tag{4.1}$$

$$0 = \frac{1}{p!} \partial_6 \omega_{[A_1 \dots A_p]} - \frac{1}{(p-1)!} D_{[A_1} \omega_{6|A_2 \dots A_p]} + \frac{1}{(p-1)!} T_{6[A_1]}^C \omega_{C|A_2 \dots A_p} - \frac{1}{2!(p-2)!} T_{[A_1 A_2]}^C \omega_{6C|A_3 \dots A_p}. \tag{4.2}$$

Restricting the vector indices to five dimensions and setting  $\partial_6$  and  $T_{6A}^B$  to zero suggests the following definitions: the five-dimensional  $p$ -form

$$(\alpha_p)_{A_1 \dots A_p} := \omega_{A_1 \dots A_p} \tag{4.3}$$

and the five-dimensional  $(p-1)$ -form

$$(\beta_{p-1})_{A_1 \dots A_{p-1}} = \omega_{6A_1 \dots A_{p-1}}. \tag{4.4}$$

The  $(5+1)$ -dimensional closure conditions then give, in an index-free notation,

$$d\alpha_p = c_2 \wedge \beta_{p-1} \quad \text{and} \quad d\beta_{p-1} = 0, \tag{4.5}$$

where  $c_{\alpha\beta} = T_{\alpha\beta}^6 = \varepsilon_{ij} \varepsilon_{\hat{\alpha}\hat{\beta}}$  is the only non-zero component of the constant 2-form  $c_2$ .

The first thing to notice here is that although two forms come from this reduction, only  $\beta_{p-1}$  is closed. Looking back to the complex worked out in section 3, the  $\beta_{p-1}$  forms—as they came from six dimensions—are precisely those forms that we studied in section 3. For ease of comparison, we have collected the schematic form of the five- and six-dimensional cocycles in table 7. For clarity of presentation, we have suppressed real numerical factors and are using  $\star$  to schematically denote factors of  $\varepsilon_{a_1 \dots a_D}$ . The precise forms of the  $\Pi$ -projectors are given in (3.24) and (3.29) for five dimensions and in [35] for six.

Note that the branching structure of the five-dimensional de Rham complex represented by figure 1 descends from a similar branching in the six-dimensional complex where there are two irreducible constraints for the closed 2-form.<sup>2</sup>

#### 4.1 Relative cohomology

Returning to the remaining equation in the reduction (4.5), we note that it is possible to construct another closed 5D  $p$ -form by solving the closure condition  $d\beta_{p-1} = 0$  as  $\beta_{p-1} = d\theta_{p-2}$  and using this to define the shifted superform

$$\alpha'_p := \alpha_p - c_2 \wedge \theta_{p-2}. \tag{4.6}$$

The structure of these forms is illustrated in figure 3.

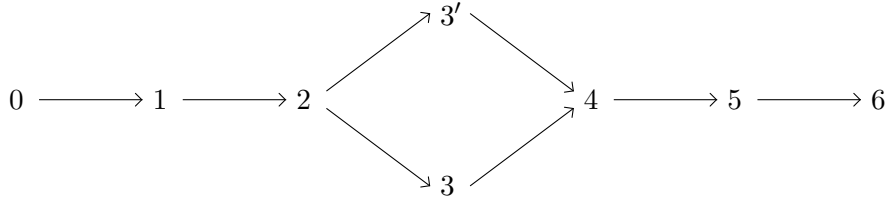
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<sup>2</sup>The second 3-form presented in the table appeared only as a composite 3-form in reference [35].

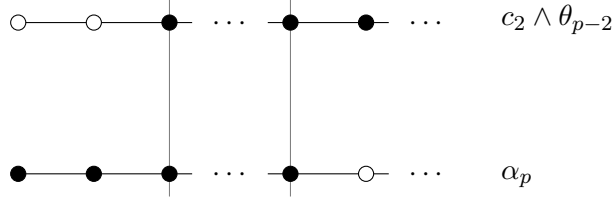
SIX DIMENSIONS	p = 2	p = 3	p = 4	p = 5	
	$F_{\underline{ab}} = 0$ $F_{\underline{a}\alpha} = i(\gamma_{\alpha})_{\alpha\beta} W_i^\beta$ $F_{\alpha b} = D^{\gamma\delta} \gamma_{ab} W_i^\gamma$	$\tilde{H}_{\underline{ab}\gamma} = 0$ $\tilde{H}_{\underline{a}\beta\alpha} = (\gamma_{abc})_{\alpha\beta} C_{ij}^{bc}$ $\tilde{H}_{\underline{ab}\alpha} = i\epsilon_{ij}(\gamma_{\alpha})_{\alpha\beta} \Phi$ $\tilde{H}_{\underline{ab}\alpha} = (\gamma_{ab})_{\alpha}{}^{\beta} D_{\beta k} \Phi$ $\tilde{H}_{abc} = iD_{abc}^2 \Phi$	$G_{\underline{ab}\gamma\delta} = 0$ $G_{\underline{ab}\gamma\alpha} = 0$ $G_{\underline{ab}\alpha\beta} = (\gamma_{abc})_{\alpha\beta} G_{ij}^c$ $G_{\underline{ab}cd} = \star i(\gamma_{cde})_{\alpha}{}^{\beta} D_{\beta}^j G_{fij}$ $G_{\underline{abcd}} = \star D_{\underline{ab}ij}^2 G_{ij}^c$	$K_{\underline{ab}\gamma\delta\epsilon} = 0$ $K_{\underline{ab}\gamma\delta\alpha} = 0$ $K_{\underline{ab}\gamma\alpha\beta} = 0$ $K_{\underline{abc}\delta abc} = (\gamma_{abc})_{\alpha\beta} K_{ij}$ $K_{\underline{abcd}e} = \star i(\gamma_{cef})_{\alpha}{}^{\beta} D_{\beta}^j K_{ij}$ $K_{\underline{abcde}} = \star D_{\underline{ab}ij}^2 K_{ij}^c$	
	$D_i W^i = 0$ $D_{(\underline{c}} \tilde{\gamma}_{ab} W_{j)} = 0$	$i\delta^{\beta} C_{\underline{ab}ij} + D_{(\underline{c}}^{2bk} C_{j)kab} + D_{\underline{abc}}^2 C_{ij}^{bc} = 0$ $\Pi_{\underline{ab}\alpha}^{cd\beta} D_{\beta(\underline{c}} C_{adk)} = 0$	$\Pi_{\underline{ab}\alpha}^{b\beta} D_{\beta(\underline{c}} G_{bjk)} = 0$ $D_{\underline{ab}k(\underline{c}} G_{j)}^2 + i\partial_a G_{ij}^a = 0$	$D_{\alpha(\underline{c}} K_{j)k} = 0$	
FIVE DIMENSIONS	p = 1	p = 2	p = 3	p = 4	
	$A_{\underline{\alpha}} = D_{\underline{\alpha}} U + D_{\underline{a}}^j U_{ij}$ $A_{\underline{a}} = \partial_{\underline{a}} U + iD_{\underline{ab}}^2 U_{ij}$	$\tilde{F}_{\underline{ab}} = \epsilon_{ij} \epsilon_{\alpha\beta} W$ $\tilde{F}_{\underline{a}\alpha} = i(\Gamma_{\underline{a}})_{\alpha}{}^{\beta} D_{\beta k} W$ $\tilde{F}_{\underline{ab}} = D_{\underline{ab}}^2 W$	$\tilde{H}_{\underline{ab}\gamma} = 0$ $\tilde{H}_{\underline{ab}\alpha} = (\Sigma_{\underline{ab}})_{\alpha\beta} H_{ij}^{\beta}$ $\tilde{H}_{\underline{ab}\alpha} = \star i(\Sigma_{\underline{cd}})_{\alpha}{}^{\beta} D_{\beta}^j H_{\underline{c}dij}$ $\tilde{H}_{\underline{ab}c} = \star D_{\underline{ab}ij}^2 C_{de}^{ij}$	$G_{\underline{ab}\gamma\delta} = 0$ $G_{\underline{ab}\gamma\alpha} = 0$ $G_{\underline{ab}\alpha\beta} = (\Sigma_{\underline{ab}})_{\alpha\beta} G_{ij}$ $G_{\underline{ab}bc} = \star i(\Sigma_{\underline{cd}})_{\alpha}{}^{\beta} D_{\beta}^j G_{ij}$ $G_{\underline{abcd}} = \star D_{\underline{ab}ij}^2 G_{ij}^c$	$D_{\alpha(\underline{c}} G_{j)k} = 0$
	$D_{\underline{a}}^2 U_{ij} = 0$ $D_{\underline{ab}}^2 U_{ij} = 0$	$i\delta^{\beta} C_{\underline{ab}ij} + D_{(\underline{c}}^{2bk} C_{j)kab} + D_{\underline{abc}}^2 C_{ij}^{bc} = 0$ $\Pi_{\underline{ab}\alpha}^{cd\beta} D_{\beta(\underline{c}} C_{adk)} = 0$	$\Pi_{\underline{ab}\alpha}^{b\beta} D_{\beta(\underline{c}} H_{bjk)} = 0$ $D_{\underline{ab}k(\underline{c}} H_{j)}^2 + i\partial_a H_{ij}^a = 0$	$D_{\alpha(\underline{c}} G_{j)k} = 0$	

**Table 7.** The structure of the five- and six-dimensional de Rham cocycles.

Interestingly, we recognize this as the form that comes from the relative cohomology construction of a closed 5-form in reference [23]. The fact that their  $L_6 = c_2 \wedge G_4$  exhibits Weil triviality as  $L_6 = dK_5$  and  $L_6 = c_2 \wedge dh_3$  is then a direct consequence of the fact that  $G_4$  and  $K_5$  come to 5D together as a relative cohomology pair from the dimensional reduction of the 6D 5-form.



**Figure 2.** The general “obstruction structure” of the six-dimensional super-de Rham complex as constructed in reference [35].



**Figure 3.** Filled nodes are the non-zero components of the indicated forms, with the struts indicating which components of the  $\alpha_p$  are “corrected” by  $c_2 \wedge \theta_{p-2}$  to allow the form  $\alpha'_p$  to close without vanishing. Higher-dimensional components are on the left.

To illustrate this relative cohomology construction and its origin from dimensional reduction, consider the case of the relative 3-form. It is obtained by reducing the six-dimensional 3-form  $H \rightarrow (H, F)$  to a five-dimensional 3-form  $H$  and 2-form  $F$ . The resulting closed 2-form  $F$  is solved in terms of its potential  $A$ , which is used to correct the non-closed part  $H$  of the 3-form as expressed by equation (4.6). The closed 3-form  $H'$  arising from this construction has components

$$\begin{aligned} H'_{\underline{\alpha}\underline{\beta}\underline{\gamma}} &= -\varepsilon_{(\underline{\alpha}\underline{\beta})\underline{\gamma}}, & H'_{\underline{\alpha}\underline{\beta}\hat{a}} &= -\varepsilon_{ij}(\Gamma_{\hat{a}})_{\hat{\alpha}\hat{\beta}}\Phi - \varepsilon_{ij}\varepsilon_{\hat{\alpha}\hat{\beta}}A_{\hat{a}}, \\ H'_{\underline{\alpha}\hat{a}\hat{b}} &= \frac{i}{4}(\Sigma_{\hat{a}\hat{b}})_{\hat{\alpha}}^{\hat{\beta}}D_{\hat{\beta}i}\Phi, & H'_{\hat{a}\hat{b}\hat{c}} &= \frac{3}{8}D_{\hat{a}\hat{b}\hat{c}}^2\Phi. \end{aligned} \quad (4.7)$$

The dimension-2 Bianchi identity fixes

$$\Phi = \frac{i}{24}D^{\hat{\alpha}i}A_{\hat{\alpha}i} \quad \text{and} \quad A_{\hat{a}} = -\frac{i}{24}D^i\Gamma_{\hat{a}}A_i, \quad (4.8)$$

thus defining all of the components in terms of the spinor potential  $A_{\hat{\alpha}i}$ . The constraints imposed by  $dH' = 0$  on this potential can be presented as

$$D_{(\hat{\alpha}(i}A_{\hat{\beta})j)} = 0, \quad (4.9)$$

$$6(\Gamma_{\hat{a}})_{\hat{\alpha}}^{\hat{\beta}}D_{\hat{\beta}i}\Phi + 3(\Sigma_{\hat{a}\hat{b}})_{\hat{\alpha}}^{\hat{\beta}}D_{\hat{\beta}i}A^{\hat{b}} - (\Sigma_{\hat{a}\hat{b}})_{\hat{\alpha}}^{\hat{\beta}}\partial^{\hat{b}}A_{\hat{\beta}i} = 0, \quad (4.10)$$

$$D_{ij}^2\Phi = 0. \quad (4.11)$$

It is illuminating to see precisely how this procedure works. The 1-form  $A$  allows the form to “get off the ground” by giving  $H_{\underline{\alpha}\underline{\beta}\underline{\gamma}}$  a piece to ensure that the lowest Bianchi identity holds even with a scalar superfield sitting inside  $H_{\underline{\alpha}\underline{\beta}\hat{a}}$ . However, this is not enough:

if we were to continue the analysis with only  $A_{\underline{\alpha}}$  and not  $A_{\hat{a}}$  we would find that the final component  $H_{\hat{a}\hat{b}\hat{c}}$  vanishes. Instead, the  $A_{\hat{a}}$  component avoids this so that the higher components satisfy the higher Bianchi identities without trivializing.

An interesting feature of this construction is that, although we are attempting to describe a closed 3-form field-strength, the lower components of this form are not gauge-invariant under  $A_{\hat{\alpha}i} \mapsto A_{\hat{\alpha}i} + D_{\hat{\alpha}i}\Lambda$  (for some gauge parameter  $\Lambda$ ). Nevertheless, the field  $\Phi$  is invariant under this transformation so the top two components of  $H'$  are invariant (as are the constraints). This is a generic feature of the relative cohomology construction that comes from solving the closure condition on the form  $\beta_{p-1}$  and using its potential  $\theta_{p-2}$  in the definition of the closed form  $\alpha'_p$ .

## 5 Field content in 5D

The utility of the superforms derived above (and in general) lies in their natural accommodation of gauge structure. If we let  $A$  be an abelian gauge  $(p - 1)$ -form, then its field-strength  $F$  is simply defined as the  $p$ -form

$$F = dA. \tag{5.1}$$

This field-strength is invariant under the gauge transformation  $\delta A = d\lambda$  for any  $(p - 2)$ -form  $\lambda$ , and is itself identically closed. With the complex laid out in section 3, we now turn to the field content of the gauge multiplets it defines.

### 5.1 The vector multiplet ( $p = 2$ )

The theory of a closed, five-dimensional 2-form has at its core a dimension-1 field-strength  $\mathcal{W}$  that satisfies the constraint (3.15), identifying it as the field-strength for the five-dimensional vector multiplet of [36, 37], as we now review.

Before delving into components and counting degrees of freedom, there are two things to note. The first is that by elementary computation,

$$D_{\hat{\alpha}}^{(i} D_{\hat{\beta}}^{j)} \mathcal{W} = \frac{1}{4} \varepsilon_{\hat{\alpha}\hat{\beta}} D^{\hat{\gamma}(i} D_{\hat{\gamma}}^{j)} \mathcal{W} \Rightarrow D_{\hat{\alpha}}^{(i} D_{\hat{\beta}}^j D_{\hat{\gamma}}^{k)} \mathcal{W} = 0. \tag{5.2}$$

This will be used later when we look at the degrees of freedom in this multiplet. The second thing to note is that by acting on (3.15) with  $D_i^{\hat{\alpha}}$ , we obtain for the spinor  $\lambda$  in  $\mathcal{W}$ ,

$$\not{D}_{\hat{\alpha}}^{\hat{\beta}} \lambda_{\hat{\beta}i} = -\frac{i}{2} D_{ij}^2 \lambda_{\hat{\alpha}}^j \neq 0. \tag{5.3}$$

Thus, this multiplet is off-shell. This may seem curious given that the six-dimensional 3-form field-strength theory from which this form reduces is on-shell, but note that the obstruction to the Dirac equation in (5.3) is an operator that does not exist in six dimensions.

Turning now to the field content, we write the  $\theta$ -expansion of  $\mathcal{W}$  as [37]

$$\mathcal{W} = \phi + i\theta^{\hat{\alpha}i} \lambda_{\hat{\alpha}i} + \frac{i}{2} \theta^{\hat{\alpha}i} \theta_{\hat{\alpha}}^j X_{ij} + i\theta^{\hat{\alpha}i} \theta_i^{\hat{\beta}} F_{\hat{\alpha}\hat{\beta}} + \mathcal{O}(\theta^3). \tag{5.4}$$



The degrees of freedom in  $\mathcal{W}$  are, then,

fields	$\phi$	$\lambda_i^{\hat{\alpha}}$	$X_{ij}$	$F^{\hat{\alpha}\hat{\beta}}$
on-shell	1	4	0	3
off-shell	1	8	3	4

(5.5)

since  $F_{\hat{a}\hat{b}} = (\Sigma_{\hat{a}\hat{b}})^{\hat{\alpha}\hat{\beta}} F_{\hat{\alpha}\hat{\beta}} = -\frac{i}{2} D_{\hat{a}\hat{b}}^2 \mathcal{W}$  and is the field-strength of a dynamical vector due to the dimension-3 Bianchi identity (3.18). In order to determine the on-shell degrees of freedom for the iso-triplet  $X_{ij}$ , we first need to know whether there are any new fields at higher order in  $\theta$ . To do so, we use the dimension- $\frac{5}{2}$  Bianchi identity (3.16) and consider what components might live in  $DDD\mathcal{W}$ . To wit, suppose  $DDD$  were totally anti-symmetric in spinor indices. If not totally symmetric in isospin, the anti-symmetric spinor + anti-symmetric isospin components would form partial derivatives. However, if it were totally symmetric in isospin, then it would vanish by (5.2). Therefore the only possible remaining source of new components is  $DDD$  with at least one symmetric pair of spinor indices. But these are exactly the terms that (3.16) rules out. Thus, the fields laid out in (5.5) are the only ones to be found and higher components are simply derivatives of the lower ones. Then because supersymmetry is required to hold on-shell,  $X_{ij}$  is relegated to the role of auxiliary field and cannot carry any on-shell degrees of freedom. So with this information about the component fields, the action takes the form

$$\mathcal{L} = \frac{1}{2} \left( -\partial^{\hat{a}} \phi \partial_{\hat{a}} \phi + i \lambda^i \not{\partial} \lambda_i + \frac{1}{2} X^{ij} X_{ij} - \frac{1}{2} F^{\hat{a}\hat{b}} F_{\hat{a}\hat{b}} - \lambda^i [\phi, \lambda_i] \right). \quad (5.6)$$

### 5.2 The tensor multiplet ( $p = 3$ )

In section 5.4 we will discuss the interpretation of the 3-cocycle  $H$  of section 3.3. Instead we consider in this section the matter content of the relative cohomology 3-form  $H'$  of section 4.1. Acting on the constraint (4.10) with  $D_{\hat{c}}^{\hat{\alpha}}$ , and using (4.9) we find that

$$D_{\hat{a}i}^2 \Phi = 0. \quad (5.7)$$

This can be combined with the condition (4.11) to give the superfield constraint<sup>3</sup>

$$D_{\hat{\alpha}}^{(i} D_{\hat{\beta}}^{j)} \Phi = 0. \quad (5.8)$$

From this it is straightforward to check that the  $\theta$ -expansion of  $\Phi$ ,

$$\Phi = \phi + \theta_i^{\hat{\alpha}} \chi_{\hat{\alpha}}^i + \theta^{\hat{\alpha}i} \theta_i^{\hat{\beta}} T_{\hat{\alpha}\hat{\beta}} + \mathcal{O}(\theta^3), \quad (5.9)$$

stops giving new fields beyond the  $\theta^2$ -level. Unfortunately, this means that the multiplet is an on-shell tensor multiplet with the degrees of freedom

fields	$\phi$	$\chi_i^{\hat{\alpha}}$	$T^{\hat{\alpha}\hat{\beta}}$
on-shell	1	4	3

(5.10)


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<sup>3</sup>In the dimensional reduction to  $D = 4$ , this gives the superspace description of the vector-tensor multiplet as it is presented in [38].

where  $T_{\hat{\alpha}\hat{\beta}} = \frac{1}{2}(\Sigma^{\hat{a}\hat{b}})_{\hat{\alpha}\hat{\beta}}T_{\hat{a}\hat{b}}$  is dual to the 3-form field-strength  $F_{\hat{a}\hat{b}\hat{c}}$  of a 2-form gauge field. (Alternatively, we may observe that (5.8) takes the form of the vector multiplet constraint (3.14) combined with its equation of motion  $D_{ij}^2\mathcal{W} = 0$  [37].) These component fields imply that an action takes the form

$$\mathcal{L} = \frac{1}{2} \left( -\partial^{\hat{a}}\phi \partial_{\hat{a}}\phi + i\chi^i \not{\partial}\chi_i + \frac{1}{6}F^{\hat{a}\hat{b}\hat{c}}F_{\hat{a}\hat{b}\hat{c}} \right). \tag{5.11}$$

### 5.3 The linear multiplet ( $p = 4$ )

The supermultiplet content described by a closed, five-dimensional 4-form is contained inside a superfield  $G_{ij}$  subject to the analyticity constraint

$$D_{\hat{\alpha}(i}G_{jk)} = 0. \tag{5.12}$$

This is the five-dimensional,  $N = 1$  linear multiplet, the four-dimensional  $N = 2$  version of which was discovered in [39].<sup>4</sup> The  $\theta$ -expansion is

$$G_{ij} = \varphi_{ij} + 2\theta_{(i}\psi_{j)} + 2i\theta_i\Gamma^{\hat{a}}\theta_jV_{\hat{a}} + \theta_i\theta_jM + \text{derivatives}, \tag{5.13}$$

where  $\varphi_{ij}$  is an iso-triplet of scalars,  $\psi_{\hat{\alpha}}^i$  is a doublet of Weyl fermions,  $V_{\hat{a}}$  is a vector field-strength, and  $M$  is a real auxiliary scalar. Additionally, the constraint (5.12) requires that  $\partial_{\hat{a}}V^{\hat{a}} = 0$ . This condition can be solved as

$$V^{\hat{a}} = \varepsilon^{\hat{a}\hat{b}\hat{c}\hat{d}\hat{e}}\partial_{\hat{b}}E_{\hat{c}\hat{d}\hat{e}} \tag{5.14}$$

for a gauge 3-form  $E$ . The degrees of freedom carried by these fields are

fields	$\varphi_{ij}$	$\psi_{\hat{\alpha}}^i$	$E^{\hat{a}\hat{b}\hat{c}}$	$M$
on-shell	3	4	1	0
off-shell	3	8	4	1

(5.15)

and so the supermultiplet is off-shell. Finally, the action for this multiplet is

$$\mathcal{L} = \frac{1}{2} \left( \frac{1}{2}\partial_{\hat{a}}\varphi^{ij}\partial^{\hat{a}}\varphi_{ij} - V^{\hat{a}}V_{\hat{a}} + i\psi^i\not{\partial}\psi_i + M^2 \right). \tag{5.16}$$

The component field content of this section also indicates a relation to the results of [28, 40]. When one reduces the component field content of the 3-form  $E_{\hat{c}\hat{d}\hat{e}}$  to four dimensions, one obtains a 2-form gauge field  $E_{cd5}$  and a four-dimensional gauge 3-form  $E_{cde}$ . Then the  $N = 1$  supermultiplet content is seen to be  $(\varphi_{22}, \psi_2, E_{cd5})$  and  $(\varphi_{11}, \varphi_{12}, \psi_1, E_{cde}, M)$ . The first of these is a  $N = 1$  tensor multiplet and the second is a variant formulation of a  $N = 1$  chiral supermultiplet [41]. The latter of these contains one 0-form auxiliary field  $M$  and a 3-form auxiliary field  $E_{cde}$ .

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<sup>4</sup>A five-dimensional formulation is given in [40] but they do not examine the field content before reducing to a centrally-extended 4D,  $N = 2$  superspace.

### 5.4 Reducible multiplets

We have found that the procedure of obstructing the Bianchi identities of an irreducible supersymmetric multiplet describing a  $p$ -form generally fails to give an irreducible multiplet describing a  $(p + 1)$ -form. To distinguish these cases, we will refer to the elements of the super-de Rham complex as constructed here as “ $p$ -cocycles”. When these have an interpretation as an irreducible supermultiplet containing a closed bosonic  $p$ -form, we will call them closed (super-) $p$ -forms.

Examples of cocycles that are not closed forms were found in section 3.2.1 for  $p = 2$  and in section 3.3 for  $p = 3$ . In the first case, there were two 2-cocycles, one of which is a closed 2-form. In the latter, however, there was no de Rham 3-cocycle that could be interpreted as a 3-form. (For this, we had to pass to the 3-cocycle of the relative cohomology of section 4.1.) From the four-dimensional perspective, this is a new phenomenon: at least in the case of 4D,  $N = 1$ , every  $p$ -cocycle is a closed  $p$ -form.

What, then, is the interpretation of such cocycles? A clue is to be found by scrutinizing the constraints on the field-strengths of cocycles that are closed forms. In very low degree, the  $p$ -cocycles are guaranteed to be forms since we can always start with a scalar superfield and take its derivative to get an exact 1-form. Similarly, in high degree, specifically co-dimension 1, the  $(D - 1)$ -cocycle has the interpretation of a closed  $(D - 1)$ -form because its analyticity implies that it contains a conserved vector field-strength, as described in section 5.3. When  $D \leq 4$ , the 2-form field-strength (guaranteed to exist as the Maxwell field-strength), sits directly beneath the  $D - 1 = 3$ -form field-strength. However, when  $D > 4$  a gap opens up between  $p = 2$  and  $p = D - 1$  and it is in this gap that we find a cocycle that is not guaranteed to have an interpretation as a closed form. In fact, both of the non-form cocycles we have found are naturally associated to the co-dimension-1 form of sections 3.4 and 5.3, as we can see from the progression of constraints

$$\Pi_{\hat{a}\hat{b}\hat{\alpha}}^{\hat{c}\hat{d}\hat{\beta}} D_{\hat{\beta}(i} C_{\hat{c}\hat{d}jk)} \stackrel{(3.23)}{=} 0, \quad \Pi_{\hat{a}\hat{\alpha}}^{\hat{b}\hat{\beta}} D_{\hat{\beta}(i} H_{\hat{b}jk)} \stackrel{(3.27)}{=} 0, \quad \text{and} \quad \Pi_{\hat{\alpha}}^{\hat{\beta}} D_{\hat{\beta}(i} G_{jk)} \stackrel{(3.34)}{=} 0, \quad (5.17)$$

where the  $\Pi$ s are the projectors (cf. eqs. (3.24)), (3.29), and taking  $\Pi_{\hat{\alpha}}^{\hat{\beta}} := \delta_{\hat{\alpha}}^{\hat{\beta}}$ ) onto the anti-symmetric tensor, vector, and scalar representations, respectively.

Alternatively, it is not the expectation that there be a closed form interpretation of the cocycle that fails inasmuch as it is that the cocycle may be required to be a *composite* closed form. Consider, for example, the 2-cocycle  $A \wedge A'$  constructed by wedging two different 1-forms. The lowest component of this product generally contains both the 2-form part  $\sim A^{\hat{a}i} A'_{\hat{a}i}$  from section 3.2 and the 2'-cocycle part  $\sim A_{(\hat{\alpha}(i} A'_{\hat{\beta})j)}$  from section 3.2.1. Therefore, the existence of the 2'-cocycle is required by the fact that differential forms form a differential graded algebra with respect to the  $\wedge$ -product.

We conclude with a related observation for which we do not yet have a complete explanation: the 3-cocycle  $H$  of section 3.3 satisfies the constraints of one of the five-dimensional,  $N = 1$  conformal supergravity torsions worked out in reference [42]. Specifically, this superspace contains a dimension-1 torsion  $C_{\hat{a}ij}$  constrained by the dimension- $\frac{3}{2}$  Bianchi identities to satisfy equation (3.26). Under local superconformal transformations,  $\delta C_{\hat{a}ij} = \sigma C_{\hat{a}ij} - i D_{\hat{a}i}^2 \sigma$ . The first term is the transformation of a superconformal primary

field of weight 1 and the inhomogeneous term indicates that  $C$  is a connection for local superconformal transformations. In this sense, the cocycle  $H_{\hat{a}ij} \sim D_{\hat{a}ij}^2 \sigma$  describes the gauge parameters of local superconformal transformations in five-dimensional superspace.<sup>5</sup>

## 6 Conclusions

In this article we have constructed the super-de Rham complex in five-dimensional,  $N = 1$  superspace and related it to the complex of six-dimensional,  $N = (1, 0)$  superspace *via* dimensional reduction. This turned out to be only one part of the reduced complex, with the remaining part serving as an additional source of closed superforms coming from the relative cohomology of the two superspaces. A surprising feature of the five-dimensional complex is that the 3-form field-strength  $H$  does not describe an irreducible supermultiplet serving as the supersymmetrization of a closed bosonic 3-form. Instead, the “missing” tensor multiplet arises from the relative cohomology construction of section 4.1.

We concluded our excursion in 5D by investigating the field content described by the  $p$ -form field-strengths for  $p = 2, 3, 4$  which were, respectively, an off-shell vector multiplet, an on-shell tensor multiplet, and an off-shell linear multiplet (with gauge 3-form). The 4-form field-strength also automatically solved a problem left open from the work of [28]; namely, by dimensional reduction of the results in section 5.3 we have found the 4D,  $N = 2$  supermultiplet containing a component level 3-form gauge field.

In this paper we have taken steps to fill in our understanding of eight-supercharge superspaces as we bracket our work with the extensive literature on  $\mathbb{R}^{4|8}$  and the six-dimensional complex of [35]. However, we have also uncovered questions that should extend beyond specific superspaces and hint towards a more universal understanding of superforms. In the associated works [43, 44] we study the problem noted in section 3.3 of determining how constraints fit together inside Bianchi identities generically and examine the dimensional reduction for embedded superspaces  $\mathbb{R}^{D-1|n} \hookrightarrow \mathbb{R}^{D|n}$ .

Finally, we note that this work has introduced new curiosities about how superforms may be used to discover superfield formulations of gauge supermultiplets. In higher dimensions it appears to now be an open question as to how certain gauge theories can be constructed. The example we encountered in five dimensions is that the superform description of an off-shell tensor multiplet in ordinary 5D,  $N = 1$  superspace (i.e. without central charge and/or harmonics) remains unknown. If we try to obtain such a superform by either of the dimensional reduction paths laid out in section 4, we obtain a multiplet of superconformal gauge parameters or an on-shell tensor multiplet. If we instead start in 4D,  $N = 2$  superspace with the vector-tensor multiplet, this lifts to five dimensions by becoming the on-shell tensor multiplet.

There are also other extensions to flat superspace that may be considered; 4D,  $N = 2$  centrally-extended superspaces have been considered in [40, 45] and have a close relationship with 5D,  $N = 1$  given that the central charge can be considered a  $\partial_5$  term. Centrally-extended 5D superspace was investigated in [46] where the central charge was gauged and several superforms were constructed; their relationship to the forms presented here is also

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<sup>5</sup>The analogous thing happens in six dimensions in terms of the 4-cocycle.

of interest. Curved superspaces are another avenue for future study as we consider how such spaces fit into the general discussion of superform constraints and dimensional reduction. Work on these topics is underway at the present time as we continue our march towards understanding the geometry of superspace and its relationship to the structure of gauge theories in arbitrary dimension with any number of supersymmetries.

### Acknowledgments

This work was partially supported by the National Science Foundation grants PHY-0652983 and PHY-0354401 and the University of Maryland Center for String & Particle Theory. SR was also supported by the Maryland Summer Scholars program and the Davis Foundation and participated in the 2013 and 2014 Student Summer Theoretical Physics Research Sessions. WDL3 thanks the Simons Center for Geometry and Physics for hospitality during the XII Simons Workshop.

### A Five-dimensional, $N = 1$ superspace

Our five-dimensional notation and conventions were first given in [37] and are designed to reduce to those of [32] in 4D. Using the “mostly-plus” flat metric  $\eta_{\hat{a}\hat{b}}$ , for  $\hat{a}, \hat{b} \in \{0, 1, 2, 3, 5\}$ , our  $\Gamma$ -matrices  $\Gamma_{\hat{a}} = (\Gamma_a, \Gamma_5)$ , with  $a \in \{0, 1, 2, 3\}$ , are chosen to satisfy the algebra

$$\{\Gamma_{\hat{a}}, \Gamma_{\hat{b}}\} = -2\eta_{\hat{a}\hat{b}}\mathbf{1}. \tag{A.1}$$

In order to completely span the space of  $4 \times 4$  matrices we introduce the symmetric matrices  $\Sigma_{\hat{a}\hat{b}} := -\frac{1}{4}[\Gamma_{\hat{a}}, \Gamma_{\hat{b}}]$  to complement the anti-symmetric spinor metric  $\varepsilon_{\hat{\alpha}\hat{\beta}}$  and anti-symmetric, traceless  $\Gamma$ -matrices.

We also have the useful identities for  $A_{ij} = A_{[ij]}$ :

$$A_{ij} = \frac{1}{2}\varepsilon_{ij}A^k{}_k \quad \text{and} \quad A^{ij} = -\frac{1}{2}\varepsilon^{ij}A^k{}_k, \tag{A.2}$$

where  $\varepsilon_{ij}$  is the isospinor metric. The algebra of 5D,  $N = 1$  superspace is then

$$\{D_{\hat{\alpha}}^i, D_{\hat{\beta}}^j\} = -2i\varepsilon^{ij}\not{\theta}_{\hat{\alpha}\hat{\beta}}, \tag{A.3}$$

where, for reference, the  $D$ s are explicitly defined as

$$D_{\hat{\alpha}i} := \partial_{\hat{\alpha}i} - i\not{\theta}_{\hat{\alpha}\hat{\beta}}\theta_i^{\hat{\beta}}. \tag{A.4}$$

The irreducible  $D^2$  operators in five dimensions are normalized as follows:

$$D_{ij}^2 := \frac{1}{2}D_{(i}D_{j)}, \quad D_{\hat{a}ij}^2 := \frac{1}{2}D_{(i}\Gamma_{\hat{a}}D_{j)}, \quad \text{and} \quad D_{\hat{a}\hat{b}}^2 := \frac{1}{2}D^i\Sigma_{\hat{a}\hat{b}}D_i. \tag{A.5}$$

Note that here we use the contraction convention  $\psi^{\hat{\alpha}i}\chi_{\hat{\alpha}i} = \psi\chi$ . With these operators, we can expand a generic  $DD$  object as

$$D_{\hat{\alpha}i}D_{\hat{\beta}j} = i\varepsilon_{ij}\not{\theta}_{\hat{\alpha}\hat{\beta}} - \frac{1}{2}\varepsilon_{ij}(\Sigma^{\hat{a}\hat{b}})_{\hat{\alpha}\hat{\beta}}D_{\hat{a}\hat{b}}^2 + \frac{1}{2}\varepsilon_{\hat{\alpha}\hat{\beta}}D_{ij}^2 + \frac{1}{2}(\Gamma^{\hat{a}})_{\hat{\alpha}\hat{\beta}}D_{\hat{a}ij}^2. \tag{A.6}$$

We also define the shorthand

$$D_{\hat{a}\hat{b}\hat{c}}^2 := -\frac{1}{12}\varepsilon_{\hat{a}\hat{b}\hat{c}}^{\hat{d}\hat{e}}D_{\hat{d}\hat{e}}^2 \quad (\text{A.7})$$

so that

$$\varepsilon_{\hat{a}\hat{b}}^{\hat{c}\hat{d}\hat{e}}D_{\hat{c}\hat{d}\hat{e}}^2 = D_{\hat{a}\hat{b}}^2. \quad (\text{A.8})$$

Straightforward  $D$ -pushing with the algebra (A.3) yields the following commutators

$$[D^{2ij}, D_{\hat{a}ij}^2] = 12i\partial^{\hat{b}}D_{\hat{a}\hat{b}}^2, \quad (\text{A.9})$$

$$[D_{\hat{a}}^{2ij}, D_{\hat{b}ij}^2] = 72i\partial^{\hat{c}}D_{\hat{a}\hat{b}\hat{c}}^2, \quad (\text{A.10})$$

$$[D_{ij}^2, D_{\hat{a}\hat{b}}^2] = -4i\partial_{[\hat{a}}D_{\hat{b}]ij}^2 \quad (\text{A.11})$$

which are useful in the calculations of section 3.

It will also be helpful to note some elementary facts about  $D^3$  operators. As shown by Koller [47], in six dimensions there are only two linearly independent  $D^3$ s; namely,  $D_{\hat{a}ijk}^3$  and  $\tilde{D}_{\hat{a}\hat{c}i}^3$ . In five dimensions the vector component of  $\tilde{D}^3$  splits, and so we have three:

$$\tilde{D}_{\hat{a}\hat{c}i}^3 := \{D_{\hat{a}}^j, D_{ij}^2\}, \quad \tilde{D}_{\hat{a}\hat{c}i}^3 := \{D_{\hat{a}}^j, D_{\hat{a}ij}^2\}, \quad D_{\hat{a}ijk}^3 := \{D_{\hat{a}(i}, D_{jk}^2\} = 2D_{\hat{a}(i}D_{jk}^2). \quad (\text{A.12})$$

These definitions lead to the relations

$$\begin{aligned} \{D_{\hat{a}i}, D_{jk}^2\} &= D_{\hat{a}ijk}^3 + \frac{2}{3}\varepsilon_{i(j}\tilde{D}_{k)\hat{a}}^3, \\ \{D_{\hat{a}i}, D_{\hat{a}jk}^2\} &= -(\Gamma_{\hat{a}})_{\hat{a}}^{\hat{\beta}}D_{\hat{\beta}ijk}^3 + \frac{2}{3}\varepsilon_{i(j}\tilde{D}_{k)\hat{a}\hat{a}}^3, \\ \{D_{\hat{a}i}, D_{\hat{a}\hat{b}}^2\} &= \frac{2}{3}(\Gamma_{[\hat{a}})_{\hat{a}}^{\hat{\beta}}\tilde{D}_{\hat{b}]\hat{\beta}i}^3 + \frac{2}{3}(\Sigma_{\hat{a}\hat{b}})_{\hat{a}}^{\hat{\beta}}\tilde{D}_{\hat{\beta}i}^3, \end{aligned} \quad (\text{A.13})$$

where we have used the fact that<sup>6</sup>

$$(\Gamma^{\hat{a}})_{\hat{a}}^{\hat{\beta}}\tilde{D}_{\hat{a}\hat{\beta}i}^3 = -\tilde{D}_{\hat{a}\hat{c}i}^3. \quad (\text{A.14})$$

We can now expand a generic  $DDD$  object by decomposing any two  $D$ s using (A.6) and then writing the  $DD^2$  terms as  $[D, D^2] + \{D, D^2\}$ .

Finally, we note the following  $\Gamma$ -matrix identities that follow directly from (A.1) as worked out in [48]: the completeness relation

$$\varepsilon_{\hat{\alpha}\hat{\beta}\hat{\gamma}\hat{\delta}} = \frac{1}{2}(\Gamma^{\hat{a}})_{\hat{\alpha}\hat{\beta}}(\Gamma_{\hat{a}})_{\hat{\gamma}\hat{\delta}} + \frac{1}{2}\varepsilon_{\hat{\alpha}\hat{\beta}}\varepsilon_{\hat{\gamma}\hat{\delta}}, \quad (\text{A.15})$$

the trace identities

$$\text{tr } \Gamma^{\hat{a}}\Gamma^{\hat{b}} = -4\eta^{\hat{a}\hat{b}} \quad \text{and} \quad \text{tr } \Sigma^{\hat{a}\hat{b}}\Sigma_{\hat{c}\hat{d}} = -2\delta_{[\hat{c}}^{\hat{a}}\delta_{\hat{d}]}^{\hat{b}}, \quad (\text{A.16})$$

and the expansions

$$\begin{aligned} (\Gamma^{\hat{a}})_{\hat{\alpha}}^{\hat{\gamma}}(\Gamma^{\hat{b}})_{\hat{\gamma}}^{\hat{\beta}} &= -\eta^{\hat{a}\hat{b}}\delta_{\hat{\alpha}}^{\hat{\beta}} - 2(\Sigma^{\hat{a}\hat{b}})_{\hat{\alpha}}^{\hat{\beta}}, \\ (\Gamma^{\hat{a}})_{\hat{\alpha}}^{\hat{\gamma}}(\Sigma^{\hat{b}\hat{c}})_{\hat{\gamma}}^{\hat{\beta}} &= -\frac{1}{2}\varepsilon^{\hat{a}\hat{b}\hat{c}\hat{d}\hat{e}}(\Sigma_{\hat{d}\hat{e}})_{\hat{\alpha}}^{\hat{\beta}} + \eta^{\hat{a}[\hat{b}}(\Gamma^{\hat{c}]}_{\hat{\alpha}})^{\hat{\beta}}. \end{aligned} \quad (\text{A.17})$$

<sup>6</sup>This is consistent with the 6D condition  $(\tilde{\gamma}^a)^{\alpha\beta}\tilde{D}_{\alpha\beta i}^3 = 0$ .

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