

18 HOOKS AND SKEW-HOOKS

Hooks play an important part in the representation theory of \mathfrak{S}_n , but it is not clear in terms of modules why they have a rôle at all! For example, it would be nice to have a direct proof of the Hook formula for dimensions (section 20), without doing all the work required for the standard basis of the Specht module.

The (i,j) -hook may be regarded as the intersection of an infinite Γ shape (having the (i,j) -node at its corner) with the diagram.

18.1 EXAMPLE $\begin{matrix} X & X & X & X \\ X & X & X & X \\ X & X & X & \end{matrix}$ The $(2,2)$ -hook is $\begin{matrix} X & X & X & X \\ X & \otimes & \otimes & \otimes \\ X & \otimes & X & \end{matrix}$

and the hook graph is $\begin{matrix} 6 & 5 & 4 & 2 \\ 5 & 4 & 3 & 1 \\ 3 & 2 & 1 & \end{matrix}$

18.2 DEFINITIONS

(i) The (i,j) -hook of $[\mu]$ consists of the (i,j) -node along with the $\mu_i - j$ nodes to the right of it (called the arm of the hook) and the $\mu_j' - i$ nodes below it (called the leg of the hook).

(ii) The length of the (i,j) -hook is $h_{ij} = \mu_i + \mu_j' + 1 - i - j$

(iii) If we replace the (i,j) -node of $[\mu]$ by the number h_{ij} for each node, we obtain the hook graph.

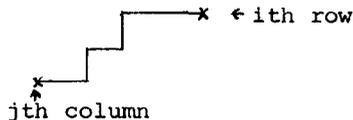
(iv) A skew-hook is a connected part of the rim of $[\mu]$ which can be removed to leave a proper diagram.

18.3 EXAMPLE $\begin{matrix} X & X & X & X \\ X & X & \text{---} & X \\ X & \text{---} & \text{---} & \end{matrix}$ and $\begin{matrix} X & X & X & X \\ X & X & \text{---} & X \\ X & X & \text{---} & \end{matrix}$ show the only two

skew 4-hooks in $[4^2, 3]$. The diagram also has one skew 6-hook, two skew 5-hooks, two skew 3-hooks, two skew 2-hooks, and two skew 1-hooks. Comparing this with the hook graph, we have illustrated:

18.4 LEMMA There is a natural 1-1 correspondence between the hooks of $[\mu]$ and the skew-hooks of $[\mu]$.

Proof: The skew hook



corresponds to the (i,j) -hook.