

# Riemannian Metrics on Tangent Bundles (\*).

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**Summary.** – Some « natural » metrics on the tangent and on the sphere tangent bundle of Riemannian manifold are constructed and studied via the moving frame method.

## 1. – Introduction.

The tangent bundle  $TM$  of a Riemannian manifold  $(M, g)$  admits a natural Riemannian metric: the *Sasaki metric*  $g_s$ .

In order to define  $g_s$  we consider two vectors  $X$  and  $Y$  tangent to  $TM$  at the point  $(p, v)$ . Suppose that  $X$  and  $Y$  are tangent at the time  $t = 0$  to the curves  $\tilde{\alpha}(t) = (\alpha(t), V(t))$  and  $\tilde{\beta}(t) = (\beta(t), W(t))$  respectively. Denote with  $DV/dt$  and  $DW/dt$  the covariant derivatives of the vector fields  $V(t)$  and  $W(t)$  along  $\alpha(t)$  and  $\beta(t)$ , then  $g_s$  is defined by:

$$(1.1) \quad g_s|_{(p,v)}(X, Y) = g_p(\dot{\alpha}(0), \dot{\beta}(0)) + g_p\left(\left.\frac{DV}{dt}\right|_0, \left.\frac{DW}{dt}\right|_0\right).$$

$g_s$  is perhaps the most natural metric on  $TM$  depending only on the Riemannian structure on  $M$ , but it is extremely rigid. For instance,  $g_s$  has constant scalar curvature if and only if  $g$  is flat. Therefore, the Sasaki metric is locally homogeneous, or locally symmetric, or Einstein only if it is flat (see n. 3). But, if we consider  $TM$  as a vector bundle associated with  $OM$  we may easily construct other interesting metrics on  $TM$ .

In section 4 we discuss this general construction and we shall prove that the Sasaki metric can be obtained in this way. We also give an explicit expression of a complete metric  $g_{CG}$  introduced by CHEEGER and GROMOLL in [CG].

If  $(M, g)$  is the standard  $n$ -sphere, the metric  $g_{CG}$  has non negative curvature and  $S^n$  is the soul of  $(TS^n, g_{CG})$ .

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In section 5 we study the spherical tangent bundle  $T_1M = \{(p, v) \in TM / \|v\| = 1\}$  endowed with the induced Sasaki metric  $g'_s$ . It is interesting to observe that  $(T_1M, g'_s)$  is an homogeneous Riemannian space if  $(M, g)$  is a rank one symmetric space (see n. 5).

$T_1M$  can be regarded as an hypersurface of  $TM$ , thus the Levi Civita connection and the curvature tensor of  $g'_s$  could be computed using Gauss equation. Instead, we prefer to identify  $T_1M$  with a quotient of  $OM$  and make use of the moving frame method (see n. 6). In section 6 we study the spherical tangent bundle  $T_1S^n$  of the standard  $n$ -sphere generalising the results obtained in [KS].

Section 7 deals with deformations of the metric  $g'_s$ . We prove that the Einstein metric defined on  $T_1S^n$  by S. KOBAYASHI ([KO<sub>1</sub>], [Je]) can be obtained deforming  $g'_s$  along the direction of the canonical contact form on  $T_1S^n$ .

We are indebted to O. KOWALSKI for the remark 4.3 and several useful discussions.

## 2. – The Sasaki metric.

Let  $(M, g)$  be an  $n$ -dimensional Riemannian manifold with tangent bundle  $TM$  and natural projection  $\pi: TM \rightarrow M$ .

A curve  $\tilde{\gamma}: I \rightarrow TM, t \rightarrow (\gamma(t), V(t))$  is *horizontal* if the vector field  $V(t)$  is parallel along  $\gamma = \pi \circ \tilde{\gamma}$ . A vector on  $TM$  is *horizontal* if it is tangent to an horizontal curve, or *vertical* if is tangent to a fiber.

Let  $\gamma: I \rightarrow M, t \rightarrow \gamma(t)$  be a curve through the point  $p = \gamma(0)$ .

For each tangent vector  $v \in T_pM$  there exists a unique horizontal curve  $\gamma^H: I \rightarrow TM$  through  $(p, v)$  which projects onto  $\gamma$ . This curve is defined by:

$$\gamma^H(t) = (\gamma(t), V(t)),$$

where  $V(t)$  is the parallel vector field along  $\gamma$  with  $V(0) = v$ . The curve  $\gamma^H$  is called an *horizontal lift* of  $\gamma$ .

The horizontal lift of a vector field  $X$  on  $M$  is the unique vector field  $X^H$  on  $TM$  which is horizontal and which projects onto  $X$ .

Let  $(e_1, \dots, e_n)$  be an orthonormal frame field defined on the open set  $U \subset M$ , and let  $(x^1, \dots, x^n)$  be a local coordinate system on  $U$ . We define a local coordinate system  $(x^1, \dots, x^n, v^1, \dots, v^n)$  on  $\pi^{-1}(U)$  as follows:

$$(2.1) \quad x^i(p, v) = x^i(p), \quad v^i(p, v) = v^i, \quad (p, v) \in \pi^{-1}(U),$$

where  $v = \sum_i v^i e_i(p)$ . We denote with  $\Gamma_j^i$  the local 1-forms defined by:

$$(2.2) \quad \nabla_X e_j = \sum_i \Gamma_j^i(X) e_i.$$

It is easy to verify that the horizontal lift  $X^H$  of a vector field  $X$  on  $M$  is given, in terms of the local coordinate system above, as follows:

$$(2.3) \quad X^H = X - \sum_{ij} \Gamma_j^i(X) v^j \frac{\partial}{\partial v^i}.$$

The *vertical lift*  $X^V$  is defined by:

$$(2.4) \quad X^V = \sum_i X^i \frac{\partial}{\partial v^i}.$$

Horizontal and vertical vectors generate two complementary distributions on  $TM$ : the *horizontal distribution* and the *vertical distribution*. Those two distributions are orthogonal with respect to  $g_s$ .

From (1.1) we obtain:

$$(2.5) \quad \begin{cases} g_s(X^H, Y^H) = g_s(X^V, Y^V) = g(X, Y) \circ \pi, \\ g_s(X^H, Y^V) = 0, \end{cases}$$

for each pair of vector fields  $X$  and  $Y$  on  $M$ .

Clearly (2.5) uniquely determines the Sasaki metric. Then, according to (2.5) we have that  $(e_1^H, \dots, e_n^H, e_1^V, \dots, e_n^V)$  is an orthonormal frame field on  $\pi^{-1}(U)$  and its dual coframe is given by:

$$(2.6) \quad \pi^* e^1, \dots, \pi^* e^n, \quad Dv^1, \dots, Dv^n,$$

where  $e^i$  denotes the 1-form defined by  $e^i(e_k) = \delta_k^i$ , and  $Dv^i$  is given by

$$(2.7) \quad Dv^i = dv^i + \sum_j v^j \pi^*(\Gamma_j^i).$$

From (2.6) and (2.7) we have the following

PROPOSITION 2.1. – *The Sasaki metric  $g_s$  can be written as follows:*

$$(2.8) \quad g_s = \sum_i \pi^*(e^i)^2 + \sum_i (Dv^i)^2.$$

REMARK 2.1. – Observe that the metric induced on the fiber  $\pi^{-1}(p)$  is the Euclidean metric. In fact (2.6) and (2.7) imply that the restriction of  $g_s$  on  $\pi^{-1}(p)$  is given by the quadratic form  $\sum_i (dv^i)^2$ . Hence  $g_s$  is the only metric on  $TM$  satisfying the following conditions:

- a) horizontal and vertical distributions are orthogonal;
- b) the metric induced on the fibers is Euclidean;
- c) the projection  $\pi$  is a Riemannian submersion.

The fibers are also *totally geodesic* ([BE], p. 47).

REMARK 2.2. – Let  $(e'_1, \dots, e'_n)$  be an orthonormal frame defined on the open set  $V \subset M$ , and suppose that

$$(2.9) \quad e'_i = \sum_j a_i^j e_j \quad \text{on } U \cap V.$$

Then we have:

$$(2.10) \quad e_i'^H = \sum_j (a_i^j \circ \pi) e_j^H, \quad e_i'^V = \sum_j (a_i^j \circ \pi) e_j^V \quad \text{on } \pi^{-1}(U \cap V).$$

This implies that  $TM$  admits a natural  $O(n) \times O(n)$  structure. Since  $O(n) \times O(n)$  is a closed subgroup of  $U(2n)$ , we can also deduce that  $TM$  admits an almost complex structure  $J$  compatible with  $g_s$ . (For more details on the almost Hermitian manifold  $(TM, g_s, J)$  see [DO], [YI] and [BE], pp. 46-48).

### 3. – The curvature of the Sasaki metric.

The curvature of  $g_s$  has been computed by several authors with different methods (see [KW], [YI]). Proposition (2.1) permits the use of the moving frame method and of the structure equations of E. CARTAN.

First we put

$$(3.1) \quad \varphi^i = \pi^* e^i, \quad \varphi^{n+i} = Dv^i, \quad i = 1 \dots n,$$

and we observe that  $(\varphi^i, \dots, \varphi^{2n})$  is an orthonormal coframe field. The local 1-forms  $\varphi_B^A$  of the Levi Civita connection of  $g_s$  are given by:

$$(3.2) \quad \begin{cases} d\varphi^A = - \sum_B \varphi_B^A \wedge \varphi^B, \\ \varphi_B^A + \varphi_A^B = 0. \end{cases}$$

The curvature forms  $\Phi_B^A$  can be computed by using the formula:

$$(3.3) \quad \Phi_B^A = d\varphi_B^A + \sum_C \varphi_C^A \wedge \varphi_B^C.$$

From (3.2) and (3.3) we find:

$$(3.4) \quad \begin{cases} 2\varphi_j^i = 2\pi^* \Gamma_j^i + \sum_{l,m} v^m R_{ijml} \varphi^{n+l}, \\ 2\varphi_{n+j}^i = -2\varphi_i^{n+j} = \sum_{m,l} v^m R_{ilmj} \varphi^l, \\ \varphi_{n+j}^{n+i} = \pi^* \Gamma_i^j. \end{cases}$$

$$(3.5) \quad \left\{ \begin{array}{l} 4\Phi_j^i = \sum_{rs} \left( 2R_{ijrs} - \sum_{mlq} v^m v^l R_{ijmq} R_{rslq} - \sum_{mlq} v^m v^l R_{irmq} R_{jslq} \right) \varphi^r \wedge \varphi^s + \\ \quad + 2 \sum_{rsm} v^m (\nabla_r R)_{ijms} \varphi^r \wedge \varphi^{n+s} + \sum_{rs} \left( 2R_{ijrs} - \sum_{ml} v^m v^l R_{iqmr} R_{jals} \right) \varphi^{n+r} \wedge \varphi^{n+l}, \\ 4\Phi_{n+j}^i = -4\Phi_i^{n+j} = 2 \sum_r v^m (\nabla_r R)_{ismj} \varphi^r \wedge \varphi^s + \\ \quad + \sum_{rs} \left( 2R_{irjs} - \sum_{lmq} v^m v^l R_{iqms} R_{arls} \right) \varphi^r \wedge \varphi^{n+s}, \\ 4\Phi_{n+j}^{n+i} = \sum_{rs} \left( 2R_{ijrs} - \sum_{lmq} v^m v^l R_{qrmj} R_{asli} \right) \varphi^r \wedge \varphi^s. \end{array} \right.$$

In the formulae (3.4) and (3.5) we have written  $R_{ijlm}$ ,  $(\nabla_r R)_{ijlm}$ ... instead of  $R_{ijlm} \circ \pi$ ,  $(\nabla_r R)_{ijlm} \circ \pi$ ..., and  $R_{ijlm}$ ,  $(\nabla_r R)_{ijlm}$ ... denote the components of the curvature tensor  $R$  and its covariant derivative  $\nabla R$  with respect the local frame  $(e_1, \dots, e_n)$ .

Now we may state the following lemma:

LEMMA 3.1. - *Let  $\bar{\tau}$  be the scalar curvature of  $g_s$  then:*

$$(3.6) \quad \bar{\tau} = \tau \circ \pi - \frac{1}{4} \sum R_{ijmq} R_{ijlq} v^m v^l.$$

where  $\tau$  is the scalar curvature of  $g$ .

PROOF. - Let  $\bar{R}$  denote the curvature tensor of  $g_s$ . Then its components with respect to the local frame  $(E_1, \dots, E_{2n}) = (e_1^H, \dots, e_n^H, e_1^V, \dots, e_n^V)$  are given by:

$$(3.7) \quad \bar{R}_{ABCD} = 2\Phi_B^A(E_C, E_D).$$

Using (3.5) we find:

$$\begin{aligned} \bar{R}_{ijij} &= R_{ijij} - \frac{3}{4} \sum_{lmq} R_{ijmq} R_{ijlq} v^m v^l, \\ \bar{R}_{i\ n+j\ i\ n+j} &= \frac{1}{4} \sum_{lmq} R_{iamj} R_{ialj} v^m v^l, \\ \bar{R}_{n+i\ n+j\ n+i\ n+j} &= 0. \end{aligned}$$

Then (3.6) follows.

The next proposition is an immediate consequence of (3.6).

PROPOSITION 3.2. -  *$(TM, g_s)$  has constant scalar curvature if and only if  $(M, g)$  is locally Euclidean.*

COROLLARY 3.3. -  *$(TM, g_s)$  is locally homogeneous if and only if  $g_s$  is locally Euclidean.*

In particular (see [KW])  $(TM, g_s)$  is locally symmetric if and only if  $g_s$  is locally Euclidean.

Corollary 3.3 is still true assuming  $(TM, g_s)$  curvature homogeneous (see [SI]). In fact this assumption implies that the scalar curvature is constant.

COROLLARY 3.4. – *The Sasaki metric is Einstein if and only if it is locally Euclidean.*

#### 4. – Other metrics on tangent bundles.

Let  $\psi: OM \times \mathbb{R}^n \rightarrow TM$  be the map defined by:

$$(4.1) \quad \psi: (u, \xi) \rightarrow \left( q, \sum_i \xi^i u_i \right),$$

where  $u = (q, u_1, \dots, u_n)$  and  $\xi = (\xi^1, \dots, \xi^n)$ .  $\psi$  defines a submersion whose fiber are diffeomorphic to  $O(n)$ . This map is the canonical projection onto  $TM$  regarded as the vector bundle with standard fiber  $\mathbb{R}^n$  associated to  $O(M)$ . Therefore,  $TM$  is identified with  $OM \times \mathbb{R}^n / O(n)$ , where the orthogonal group  $O(n)$  acts on the right on  $OM$  as follows:

$$(4.2) \quad (u, \xi) a = (ua, a^{-1}\xi) = \left( q, \sum_i a_1^i u_i, \dots, \sum_i a_n^i u_i, \sum_i a_1^i \xi^i, \dots, \sum_i a_n^i \xi^i \right).$$

Let now  $Q$  be a symmetric, semi-positive defined, tensor field of type  $(2, 0)$  and rank  $2n$  on  $OM \times \mathbb{R}^n$ . Moreover, we assume that  $Q$  is *basic* for  $\psi$ . This means that  $Q$  is  $O(n)$ -invariant, and  $Q(X, Y) = 0$  if  $X$  is tangent to a fiber of  $\psi$ .

Under these assumptions, there is a unique Riemannian metric  $g_\psi$  on  $TM$  such that  $\psi^*(g_\psi) = Q$ . This metric is determined by the formula

$$g_u|_{(u,v)}(X, Y) = Q|_{(u,\xi)}(X', Y'),$$

where  $(u, \xi)$  belongs to the fiber  $\psi^{-1}(p, v)$ ,  $X$  and  $Y$  are elements of  $T_{(u,v)}(TM)$ ,  $X', Y'$  are tangent vectors of  $OM \times \mathbb{R}^n$  at  $(u, \xi)$  with  $d\psi(X') = X$  and  $d\psi(Y') = Y$ .

We observe that is easier to assign  $Q$  than to define directly  $g_\psi$  on  $TM$  since  $OM \times \mathbb{R}^n$  is parallelizable.

Let  $\theta = (\theta^1, \dots, \theta^n)$  denote the *canonical 1-form* on  $OM$ , and let  $p$  be the natural projection  $OM \xrightarrow{p} M$ .

Then, according to the definition we get:

$$(4.4) \quad dp_u(X) = \sum_i \theta^i(X) u_i, \quad u = (q, u_1, \dots, u_n).$$

If we denote with  $\omega = (\omega_j^i)$  the  $so(n)$ -valued differential form defined by the Levi Civita connection of  $g$ , then we find that:

$$\theta^i, \quad i = 1, \dots, n; \quad \omega_k^h, \quad 1 \leq h < k \leq n; \quad d\xi^i, \quad i = 1, \dots, n,$$

is an *absolute parallelism* on  $OM \times \mathbb{R}^n$ .

We recall two facts:

$$(4.5) \quad R_a^*(\theta^i) = \sum_h (a^{-1})_h^i \theta^h,$$

$$(4.6) \quad R_a^*(\omega_j^i) = \sum_{hk} (a^{-1})_h^i \omega_k^h a_j^k,$$

for each  $a \in O(n)$ . Moreover, the forms  $\omega_j^i$  are related to the local 1-forms  $\Gamma_j^i$  defined in (2.2) as follows:

$$(4.7) \quad \omega_j^i = \sum_h (\psi_\sigma^{-1})_h^i d(\psi_\sigma)_j^h + \sum_{hk} (\psi_\sigma^{-1})_h^i (p^* \Gamma_k^h) (\psi_\sigma)_j^k.$$

$\psi_\sigma$  denotes the  $O(n)$ -valued function on  $p^{-1}(U)$  given by:

$$(4.8) \quad (\psi_\sigma)_j^i(u) = g(e_i|_{p(u)}, u_j).$$

(4.7) can also be written in matrix form as follows:

$$(4.9) \quad \omega = \psi_\sigma^{-1} d\psi_\sigma + \psi_\sigma^{-1} (p^* \Gamma) \psi_\sigma.$$

Finally, it will be useful later on to note that:

$$(4.10) \quad p^* e^i = \sum_j (\psi_\sigma)_j^i \theta^j.$$

LEMMA 4.1. - *The vertical distribution of  $\psi$  is defined by:*

$$\begin{cases} \theta^i = 0, \\ D\xi^i = d\xi^i + \sum_j \xi^j \omega_j^i = 0. \end{cases}$$

PROOF. - Let  $X$  be a vertical vector of  $\psi$ , then  $X$  is tangent at  $t = 0$  to a curve of the form:

$$\alpha(t) = (ue^{tA}, e^{-tA}\xi), \quad A \in so(n).$$

Then  $X = \dot{\alpha}(0) = A^*|_u - A\xi$ ,  $A^*$  is the fundamental vector field on  $OM$  generated by  $A$ . It follows that

$$\theta^i(X) = 0,$$

and

$$D\xi^i(X) = -d\xi^i(A\xi) + \sum_j \xi^j \omega_j^i(A^*_u) = -\sum_j A_j^i \xi^j + \sum_j A_j^i \xi^j = 0.$$

The converse is obvious.

In particular we see that any basic symmetric form  $Q$  on  $OM \times \mathbb{R}^n$  is a second order polynomial in  $\theta^i$  and  $D\xi^i$  whose coefficient yield  $Q$  invariant under the  $O(n)$ -action.

For instance, consider

$$(4.11) \quad Q_s = \sum_i (\theta^i)^2 + \sum_i (D\xi^i)^2.$$

From (4.2) and (4.6) we find:

$$(4.12) \quad R_a^*(D\xi^i) = \sum_h (a^{-1})_h^i D\xi^h.$$

Hence  $Q_s$  is basic (see (4.5)).

PROPOSITION 4.2. – *The metric induced by the quadratic form  $Q_s$  is the Sasaki metric.*

PROOF. – First, we observe that the diagram

$$\begin{array}{ccc} OM \times \mathbb{R}^n & \xrightarrow{\psi} & TM \\ \downarrow & & \downarrow \pi \\ OM & \xrightarrow{p} & M \end{array}$$

commutes. Then, using (4.7) we get:

$$(4.13) \quad \psi^*(Dv^i) = \sum_j (\psi_U)_j^i D\xi^j.$$

Because (4.10) and because  $\psi_U$  is  $O(n)$ -valued, we see that  $\psi^*(g_s) = Q_s$ .

Consider now the quadratic form

$$(4.14) \quad g_{OM} = \sum_i (\theta^i)^2 + \sum_{h < k} (\omega_k^h)^2 + \sum_j (d\xi^j)^2.$$

$g_{OM}$  is a metric defined on  $OM \times \mathbb{R}^n$ ; moreover, from (4.5), (4.6) and (4.2), we find that  $O(n)$  is a group of isometries for  $g_{OM}$ .

Hence the metric  $g_{OM}$  projects onto a unique metric  $g_{CG}$  on  $TM$  so that the projection  $\psi$  becomes a Riemannian submersion.  $g_{CG}$  is the metric of Cheeger and Gromoll (see [CG]).

If we assume that  $g$  is complete, we have that  $\sum_i (\theta^i)^2 + \sum_{h < k} (\omega_k^h)^2$  is a complete Riemannian metric on  $OM$  (indeed  $p$  is a Riemannian submersion). Then it follows that  $g_{OM}$  and  $g_{CG}$  are both complete Riemannian metrics.

REMARK 4.1. – If  $(M, g)$  is the standard sphere  $(S^n, \text{can})$ , then  $OM = O(n+1)$  and  $\sum_i (\theta^i)^2 + \sum_{h < k} (\omega_k^h)^2$  is a biinvariant metric (see n. 6). Since  $g_{OM}$  is the product



of two Riemannian metrics with non-negative sectional curvatures, then  $g_{OM}$  itself has non-negative sectional curvature. Now, from O'Neill's formula it follows that the CHEEGER GROMOLL metric  $g_{CG}$  has non-negative curvature (see [CG]).

PROPOSITION 4.3. – The metric  $g_{CG}$  is induced by the tensor field

$$(4.15) \quad Q_{CG} = \sum_i (\theta^i)^2 + \frac{1}{1 + \|\xi\|^2} \left( \sum_i (D\xi^i)^2 + \left( \sum_m \xi^m D\xi^m \right)^2 \right).$$

PROOF. – Let  $V_\psi$  be the vertical distribution of  $\psi$ , then its orthogonal complement  $H_\psi$  is defined by the equation:

$$(4.16) \quad \omega_k^h = \xi^k d\xi^h - \xi^h d\xi^k.$$

Thus, the restriction of  $g_{OM}$  on  $H_\psi \times H_\psi$  agrees with the restriction of the tensor field given by

$$(4.17) \quad S = \sum_i (\theta^i)^2 + \sum_{h < k} (\xi^k d\xi^h - d\xi^h \xi^k)^2 + \sum_j (d\xi^j)^2.$$

We observe that:

$$(4.18) \quad \sum_i \xi^i d\xi^i = \sum_i \xi^i D\xi^i.$$

From (4.16) and (4.18) we find that:

$$(4.19) \quad d\xi^i|_{H_\psi} = (1 + \|\xi\|^2)^{-1} \left( D\xi^i + \xi^i \sum_m \xi^m D\xi^m \right)|_{H_\psi}.$$

Replacing (4.19) in (4.17), we get:

$$S|_{H_\psi \times H_\psi} = Q_{CG}|_{H_\psi \times H_\psi}.$$

Since  $\psi$  is a Riemannian submersion, we have:  $\psi^* g_{CG} = g_{OM}|_{H_\psi \times H_\psi}$ . We thus proved (4.15).

REMARK 4.2. – From (4.15) we have a local expression of  $g_{CG}$ , namely:

$$(4.20) \quad g_{CG} = g + \frac{1}{1 + \|v\|^2} \left\{ \sum_m (Dv^m)^2 + \left( \sum_m v^m Dv^m \right)^2 \right\}.$$

Therefore, the metric induced on the fiber is

$$(4.21) \quad g_F = \frac{1}{1 + \|v\|^2} \left\{ \sum_m (dv^m)^2 + \left( \sum_m v^m dv^m \right)^2 \right\}$$

which is not flat.

If  $\dim M = 2$ , we get

$$(4.22) \quad g_F = dr^2 + (1 + r^2)^{-1} r^2 d\alpha^2,$$

where  $v^1 = r \cos \alpha$ ,  $v^2 = r \sin \alpha$  (see [CE], p. 146).

REMARK 4.3. – The Cheeger-Gromoll metric on  $TM$  is uniquely determined at the point  $(p, u)$  by the following conditions:

$$(4.23) \quad \begin{aligned} g_{CG}(X^H, Y^H) &= g_p(X, Y), \\ g_{CG}(X^V, Y^V) &= (1 + \|u\|^2)^{-1} (g_p(X, Y) + g_p(X, u)g_p(Y, u)), \\ g_{CG}(X^H, Y^V) &= 0, \end{aligned}$$

where  $X, Y \in T_p M$ , and  $X^H, X^V$  are the horizontal and the vertical lifts of  $X$  (see n. 2). It is a «natural metric» on  $TM$  in the sense of [KWS].

## 5. – The group of isometries of $g_s$ .

Let  $G = I(M, g)$  denote the group of isometries of  $(M, g)$ . There are two natural left actions of  $G$  on  $TM$  and on  $OM$  defined by:

$$(5.1) \quad L_a(q, v) = a(q, v) = (aq, dL_a(v)), \quad a \in G, (q, v) \in TM,$$

$$(5.2) \quad L_a(u) = au = (aq, dL_a(u_1), \dots, dL_a(u_n)), \quad a \in G, u \in OM,$$

where  $dL_a$  denotes the differential of the map  $L_a: M \rightarrow M, q \rightarrow aq$ .

PROPOSITION 5.1. –  $g_s$  is a  $G$ -invariant metric on  $TM$ .

PROOF. – First we extend the action (5.2) on  $OM \times \mathbb{R}^n$  by setting:

$$(5.3) \quad L_a(u, \xi) = a(u, \xi) = (au, \xi).$$

The canonical 1-form  $\theta$  and the Levi Civita connection form  $\omega$  are  $G$ -invariant, i.e.

$$(5.4) \quad L_a^*(\theta^i) = \theta^i,$$

$$(5.5) \quad L_a^*(\omega_j^i) = \omega_j^i.$$

Since  $G$  acts trivially on  $\mathbb{R}^n$ , the differential forms  $D\xi^i$  are  $G$ -invariant. The projection  $\psi: OM \rightarrow TM$  commutes with the actions (5.1) and (5.2):

$$\psi \circ L_a = L_a \circ \psi, \quad a \in G.$$

From (4.11) we have that  $\psi^*(g_s)$  is a  $G$ -invariant quadratic form. But:

$$\psi^*(L_a^* g_s) = L_a^*(\psi^* g_s) = \psi^* g_s.$$

Since  $\psi$  is a submersion, we obtain for each  $a$  in  $G$

$$L_a^*(g_s) = g_s.$$

This proves the proposition.

REMARK 5.1. – The same arguments hold if we exchange  $g_s$  with  $g_{CG}$ , hence the Cheeger-Gromoll metric  $g_{CG}$  is  $G$ -invariant.

Let  $u_0$  be an orthonormal frame, and let  $\sigma_{u_0}$  be the map defined by

$$(5.6) \quad \sigma_{u_0}: G \rightarrow OM, \quad a \rightarrow au_0.$$

Since the action (5.2) is free, the map  $\sigma_{u_0}$  is an imbedding (see [KN], Vol. I, p. 4). Therefore  $\dim G \leq \dim OM = \frac{1}{2}n(n+1)$ , and the equality holds if and only if  $(M, g)$  is isometric to one of the following spaces of constant curvature:

- i) the  $n$ -dimensional Euclidean space  $\mathbb{R}^n$ ;
- ii) the  $n$ -dimensional sphere  $S^n$ ;
- iii) the  $n$ -dimensional real projective space  $\mathbb{R}P^n$ ;
- iv) the  $n$ -dimensional hyperbolic space  $\mathbb{H}^n$

(see [KO<sub>2</sub>], p. 46). In these cases the group  $G$  is transitive on  $T_1 M$ .

This property is characteristic of two-point homogeneous spaces, in fact we have

PROPOSITION 5.2 ([WO], p. 289). –  $G$  is transitive on the spherical tangent bundle if and only if  $(M, g)$  is a two-point homogeneous space.

From prop. (5.1) we see that  $(T_1 M, g'_s)$  is an homogeneous Riemannian space if  $(M, g)$  is two-point homogeneous, although  $(TM, g_s)$  is never homogeneous unless  $g_s$  is flat.

REMARK 5.2. – The orbits of the action (5.1) are  $M$ , regarded as the zero section of  $TM$ , and the spherical tangents bundles  $T_r M$  of radius  $r, r > 0$ . Then  $(TM, g_s)$  is a Riemannian space of *cohomogeneity one*. The spherical bundles  $T_r M$  are the principal orbits of the action, moreover  $T_r M$  is a submanifold with *constant mean curvature* [SA], whereas  $M$  is totally geodesic.

REMARK 5.3. – The tangent bundle  $TG$  of every Lie group  $G$  has a natural Lie group structure. Under the identification  $TG = G \times \mathfrak{g}$  the product is defined by:

$$(5.7) \quad (a, A)(b, B) = (ab, B + Ad(b^{-1})A), \quad a, b \in G; \quad A, B \in \mathfrak{g}.$$

If  $G$  acts on  $M$ ,  $TG$  acts on the tangent bundle  $TM$  as follows:

$$(5.8) \quad L_{(a,A)}(q, v) = (aq, dL_a(v) + (Ad(a)A)^*|_{aq})$$

where, for each  $X \in \mathfrak{g}$ ,  $X^*$  denotes the induced fundamental vector-field on  $M$ . If  $G$  is transitive on  $M$ , then  $TG$  is transitive on  $TM$ . Clearly this does not mean that if  $g$  is a  $G$ -invariant metric on  $M$ , then  $g_s$  is  $TG$ -invariant. In fact,  $L_{(e,A)}$  is an isometry of  $(TM, g_s)$  if and only if  $\nabla_X A^* = 0$  for each vector field  $X$  on  $M$ .

## 6. - Tangent sphere bundle.

In section 5 we have already noted that the tangent sphere bundle of a two point homogeneous space endowed with the metric  $g'_s$  is a Riemannian homogeneous space. In this section we will investigate the tangent sphere bundle  $T_1 S^n$  of the standard  $n$ -sphere, equipped with the induced Sasaki metric, and we will generalize some of the results proven in [KS].

First we need some general facts concerning the tangent sphere bundle of a Riemannian manifold.

Consider the map  $\psi_n: OM \rightarrow T_1 M$  defined by:

$$(6.1) \quad \psi_n: (q, u_1, \dots, u_n) \rightarrow (q, u_n)$$

(see [CH<sub>1</sub>], p. 36). This map is a submersion whose fibers are diffeomorphic with  $O(n-1)$ , identified to the subgroup of  $O(n)$  of the matrices  $\begin{pmatrix} a & 0 \\ 0 & 1 \end{pmatrix}$ ,  $a \in O(n-1)$ .

Then  $T_1 M$  can be regarded as the quotient space  $OM/O(n-1)$  and  $\psi_n$  is the natural projection. Now we shall prove the following proposition:

**PROPOSITION 6.1.** - *Let  $g'_s$  be the induced Sasaki metric on  $T_1 M$ , then we have*

$$\psi_n^*(g'_s) = \sum_i (\theta^i)^2 + \sum_i (\omega_n^i)^2.$$

**PROOF.** - First we observe that the following diagram

$$\begin{array}{ccccc} OM & \xrightarrow{\psi_n} & T_1 M & \xhookrightarrow{i} & TM \\ & \searrow p & & \swarrow \pi & \\ & & M & & \end{array}$$

commutes. Hence, using (4.9) and (4.10) we get:

$$(6.2) \quad (i \circ \psi_n)^*(\pi^* e^i) = p^*(e^i) = \sum_j (\psi_n)_j^i \theta^j,$$

$$(6.3) \quad (i \circ \psi_n)^*(\pi^* \Gamma) = p^*(\Gamma) = \psi_n \omega \psi_n^{-1} - d\psi_n \psi_n^{-1}.$$

Because  $(v^i \circ \psi_n)(u) = v^i(u_n) = (\psi_n^i)_n(u)$ , we obtain:

$$(6.4) \quad (i \circ \psi_n)^*(Dv^i) = \sum_j (\psi_n^i)_j \omega_n^j.$$

Since  $\psi_n^*(g'_s) = \psi_n^*(i^* g_s) = (i \circ \psi_n)^* g_s$  and  $\psi_n$  is an  $O(n)$ -valued function, the formulae (6.2), (6.3) and (6.4) imply proposition (6.1).

REMARK 6.1. - It is an elementary matter to check that the quadratic form  $Q = \sum_i (\theta^i)^2 + \sum_i (\omega_n^i)^2$  is  $O(n-1)$ -invariant and  $Q(X, Y) = 0$  if one of  $X$  and  $Y$  is vertical for  $\psi_n$ . Hence  $Q$  is *basic*. As for n. 4, we may characterize  $g'_s$  as the only metric on  $T_1 M$  satisfying  $\psi_n^*(g'_s) = Q$ .

Moreover, from proposition 4.3 it follows that the metric  $g'_{\text{CG}}$  induced on  $T_1 M$  by the Cheeger-Gromoll metric is uniquely characterized by the following condition:

$$\psi_n^*(g'_{\text{CG}}) = \sum (\theta^i)^2 + \frac{1}{2} \sum_i (\omega_n^i)^2.$$

PROPOSITION 6.2. -  $(T_1 S^n, g'_s)$  is isometric to the *Stiefel manifold*  $SO(n+1)/SO(n-1)$  equipped with a metric induced from a biinvariant one on  $SO(n+1)$ .

PROOF. - Let  $O_+(S^n)$  denote the bundle of positive orthonormal frames on  $S^n$ . Let  $u_0$  be a point of  $O_+(S^n)$  and let  $p$  be the canonical projection from  $SO(n+1)$  onto  $S^n$ , then the diagram

$$\begin{array}{ccccc} SO(n+1) & \xrightarrow{\sigma_{u_0}} & O_+(S^n) & \xrightarrow{\psi_n} & T_1 S^n \subset T S^n \\ & \searrow \hat{p} & \downarrow p & \swarrow \pi & \\ & & S^n = SO(n+1)/SO(n) & & \end{array}$$

commutes. Hence  $T_1 S^n$  is diffeomorphic to the Stiefel manifold  $SO(n+1)/SO(n-1)$ .

Indeed, a point of  $T_1 S^n$  is given by a pair of orthonormal vectors in  $\mathbb{R}^{n+1}$ . To conclude the proof we must check a few facts.

First consider the 1-forms on  $SO(n+1)$  defined by:

$$(6.5) \quad \bar{\theta}^i = \sigma_{u_0}^* \theta^i, \quad i = 1, \dots, n,$$

$$(6.6) \quad \bar{\omega}_i^j = \sigma_{u_0}^* (\omega_j^i), \quad 1 \leq i < j \leq n.$$

FACT 1. -  $\{\bar{\theta}^i, \bar{\omega}_i^j\}$ ,  $1 \leq h < j \leq n$  are left-invariant and linearly independent 1-forms, therefore they are Maurer-Cartan forms of  $SO(n+1)$ .

PROOF. — Let  $SO(n+1)$  act on  $O_+(M)$  (see (5.2)). Then, for each  $a, b \in SO(n+1)$ , we have:

$$(6.7) \quad \sigma_{u_a} \circ L_a = L_a \circ \sigma_{u_a},$$

where in the left hand side of (6.7)  $L_a$  denotes the left translation of  $SO(n+1)$ .

Then we get

$$L_a^*(\theta)^i = (\sigma_{u_a} \circ L_a)^* \theta^i = \sigma_{u_a}^* L_a^* \theta^i.$$

In the same way,

$$L_a^*(\omega_j^i) = \sigma_{u_a}^* L_a^*(\omega_j^i).$$

Since  $SO(n+1)$  acts as an isometry group on  $S^n$ , the canonical 1-form and the connection form  $\omega$  are  $SO(n+1)$ -invariant. This implies Fact 1.

Taking the structure equations of  $S^n$  and making use of  $\Omega_j^i = \theta^i \wedge \theta^j$  one may see that  $\bar{\theta}^i$  and  $\bar{\omega}_j^i$  satisfy the following equations:

$$(6.8) \quad \begin{cases} d\bar{\theta}^i = - \sum_h \bar{\omega}_h^i \wedge \bar{\theta}^h, \\ d\bar{\omega}_j^i = \bar{\theta}^i \wedge \bar{\theta}^j - \sum_h \bar{\omega}_h^i \wedge \bar{\omega}_j^h. \end{cases}$$

FACT 2. — Let  $\bar{g}$  denote the quadratic-form  $\sum_i (\bar{\theta}^i)^2 + \sum_{i < j} (\bar{\omega}_j^i)^2$ , then  $2n\bar{g} = -B$ , where  $B$  is the Killing form of  $SO(n+1)$ . Therefore  $\bar{g}$  is a biinvariant metric on  $SO(n+1)$ .

PROOF. —  $so(n+1)$  is isomorphic with the Lie algebra of left invariant vector fields on  $SO(n+1)$ . An explicit isomorphism can be defined taking the dual basis  $\{\bar{E}_k, \bar{E}_i^j\}$  of  $\{\bar{\theta}^k, \bar{\omega}_i^j\}$ , hence any left invariant vector field  $X$  can be written in the form:

$$(6.9) \quad X = \sum_i \bar{\theta}^i(X) \bar{E}_i + \sum_{i < j} \bar{\omega}_j^i(X) \bar{E}_i^j.$$

The isomorphism is given by the mapping:

$$X \rightarrow (A, \xi),$$

where

$$(A, \xi) = \begin{pmatrix} A & \xi \\ -x_\xi & 0 \end{pmatrix}, \quad A = (\bar{\omega}_j^i(X)), \quad x_\xi = (\bar{\theta}^1(X), \dots, \bar{\theta}^n(X)).$$

Then the Killing form is given by.

$$B(X, X') = -n \operatorname{tr} (A, \xi) \circ (A', \xi') = -2n \left\{ \sum_{i,j} \bar{\omega}_j^i(X) \bar{\omega}_i^j(X') + \sum_i \bar{\theta}^i(X) \bar{\theta}^i(X') \right\}, \quad \text{q.e.d.}$$

Proposition (6.2) follows from Facts 1 and 2, and from proposition (6.1).

REMARK 6.2. - The above proposition implies that  $T_1 S^n$  with the metric  $g'_s$  is a *normal* Riemannian homogeneous space, therefore  $(T_1 S^n, g'_s)$  is *naturally reductive*. A naturally reductive decomposition of  $so(n+1)$  is given by

$$(6.10) \quad so(n+1) = \mathfrak{m} \oplus \mathfrak{k},$$

where

$$(6.11) \quad \mathfrak{m} = \left\{ \begin{pmatrix} 0 & \eta & \xi \\ -{}^x\eta & 0 & \alpha \\ -{}^x\xi & -\alpha & 0 \end{pmatrix} = (\eta, \xi, \alpha) / {}^x\xi, {}^x\eta \in \mathbb{R}^n, \alpha \in \mathbb{R} \right\},$$

and

$$(6.12) \quad \mathfrak{k} = \left\{ \begin{pmatrix} B & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} / B \in so(n-1) \right\}.$$

The geodesics of  $(T_1 S^n, g'_s)$  through the origin  $(q_0, u_0) = \psi_n \sigma_{u_0}(e)$  are orbits of 1-parameter subgroups generated by elements  $X$  belonging to  $\mathfrak{m}$ . In the two-dimensional case all geodesics are closed (see [KS]). Of course, for  $n \geq 3$  this property is no longer true. For instance, the curve

$$\gamma(t) = \exp(tX)$$

where  $X = (\eta, \xi, 0)$ ,  ${}^x\eta = (0, \dots, a, 0)$ ,  ${}^x\xi = (0, \dots, 0, b)$  and  $a/b$  irrational, is a geodesic, dense in a torus contained in  $T_1 S^n$ , which is not closed.

## 7. - Deformation of the metric $g'_s$ .

In section 6 we noted that on the spherical tangent bundle  $T_1 M$  we may define Riemannian metrics in analogy with section 4 (see remark 6.1). For instance, since  $\theta^n$  is an invariant differential form under the  $O(n-1)$  action on  $OM$ , and since  $\theta^n$  vanishes on the vertical vectors of the fibration  $\psi_n$ , we may deduce that the quadratic form

$$(7.1) \quad Q_t = \sum_{i=1}^{n-1} (\theta^i)^2 + t^2 (\theta^n)^2 + \sum_i (\omega_n^i)^2, \quad t \neq 0,$$

induces a metric tensor  $g_t$  on  $T_1M$  which is uniquely determined by the condition  $\psi_n^*(g_t) = Q_t$ .

In this section we will show that if  $(M, g)$  is a space of constant sectional curvature  $\sigma = 1$ , then the metric  $g_t$  is Einstein when  $t^2 = 2/n(n-1)$ . Hence  $g'_s = g_1$  can be an Einstein metric only if  $\dim M = 2$ . Indeed (see [KS]), the Riemannian manifold  $(T_1S^2, g'_s)$  is isometric to the real projective space  $RP^3$  endowed with a metric of constant positive curvature  $\frac{1}{4}$ .

The Einstein metrics  $g_t, t^2 = 2/n(n-1)$ , on  $T_1S^n$  was defined by S. KOBAYASHI in [KO<sub>1</sub>] as a particular case of Einstein metrics on  $S^1$ -principal bundles. This construction was generalized by G. JENSEN ([Je]) to other homogeneous spaces, for instance if  $M$  is a Stiefel manifold.

Since  $\psi_n^*$  is injective, the Riemann and the Ricci curvature tensors are uniquely determined by their pull-backs on  $OM$ . Therefore we will work on  $OM$ , leaving the computational details to the reader.

First we put:

$$(7.2) \quad \varphi^i = \theta^i, \quad \varphi^n = t\theta^n, \quad \varphi^{n+i} = \omega_n^i, \quad i = 1, \dots, n-1.$$

From now on we shall employ the following ranges of indices:

$$i, j, k, h, \dots = 1, \dots, n-1; \quad A, B, C \dots = 1, \dots, 2n-1; \quad a, b, c \dots = 1, \dots, n.$$

We consider the following equations:

$$(7.3) \quad \begin{cases} d\varphi^A = - \sum_B (\varphi_t)_B^A \wedge \varphi^B, \\ (\varphi_t)_B^A + (\varphi_t)_A^B = 0. \end{cases}$$

To compute the differentials  $d\varphi^A$  we make use of (7.2) and of the structure equations for the metric  $g$  on  $M$ . Recall that the structure equations of  $g$  can be written as follows:

$$(7.4) \quad \begin{cases} d\theta^a = - \sum_b \omega_b^a \wedge \theta^b \\ \Omega_b^a = d\omega_b^a + \sum_c \omega_c^a \wedge \omega_b^c. \end{cases}$$

The 1-forms  $(\theta^a)_{a=1, \dots, n}$ ,  $(\omega_b^a)_{a, b=1, \dots, n}$  are respectively  $\mathbb{R}^n$ -valued and  $so(n)$ -valued differential forms globally defined on  $OM$ . Moreover:

$$(7.5) \quad 2\Omega_b^a = \sum_{ad} \bar{R}_{abcd} \theta^c \wedge \theta^d,$$

where  $\bar{R}_{abcd}$  must be regarded as real-valued functions on  $OM$  related to the Riemann curvature tensor  $R$  by the formula:

$$(7.6) \quad \bar{R}_{abcd}(u) = R|_{x(u)}(u_a, u_b, u_c, u_d), \quad u \in OM.$$



Now, using Cartan's lemma we see that (7.3) uniquely characterize the forms  $(\varphi_i)_B^A$ : It is a routine matter to deduce the following expression:

$$(7.7) \quad \begin{cases} (\varphi_i)_j^i = \omega_j^i + \frac{1}{2} \sum_h \bar{R}_{ijnh} \varphi^{n+h}, \\ (\varphi_i)_n^i = -(\varphi_i)_i^n = \frac{t^2+1}{2t} \varphi^{n+i} - \frac{1}{2t} \sum_h \bar{R}_{nin h} \varphi^{n+h}, \\ (\varphi)_{n+j}^i = -(\varphi_i)_{n+j}^{n+i} = -\frac{1}{2} \sum_h \bar{R}_{hinj} \varphi^h + \frac{t^2-1}{2t} \delta_j^i \varphi^n - \frac{1}{2t} \bar{R}_{ninj} \varphi^n, \\ (\varphi_i)_{n+j}^n = -(\varphi_i)_{n+j}^{n+i} = \frac{t^2-1}{2t} \varphi^j + \frac{1}{2t} \sum_h \bar{R}_{nhnj} \varphi^h, \\ (\varphi_i)_{n+j}^{n+i} = \omega_j^i. \end{cases}$$

Let  $(\Phi_i)_B^A$  be the forms given by the equation:

$$(7.8) \quad (\Phi_i)_B^A = d(\varphi_i)_B^A + \sum_C (\varphi_i)_C^A \wedge (\varphi_i)_B^C.$$

Then

$$(7.9) \quad R_t = 2 \sum (\Phi_i)_B^A \otimes (\varphi^A \wedge \varphi^B)$$

is the pull-back of the Riemann curvature tensor of  $g_t$ . The pull-back of the Ricci tensor is given by

$$(7.10) \quad \varrho_t = \sum_{A,B} (\varrho_t)_{AB} \varphi^A \otimes \varphi^B,$$

where the components  $(\varrho_t)_{AB}$  are given by the formula:

$$(7.11) \quad \begin{cases} (\varrho_t)_{ij} = \bar{R}_{ij} - \frac{t^4-1}{2t^2} \delta_{ij} - \frac{1}{2t^2} \sum_k \bar{R}_{nink} \bar{R}_{njnk} - \frac{1}{2} \sum_{kr} \bar{R}_{irnk} \bar{R}_{jrnk}, \\ (\varrho_t)_{in} = \frac{4t - (t-1)^2(t+1)}{4t^2} \bar{R}_{in} - \frac{1}{2t} \sum_{kr} \bar{R}_{irnk} \bar{R}_{nrnk}, \\ (\varrho_t)_{in+j} = \frac{1}{2t} (\nabla_n \bar{R})_{ninj} - \frac{1}{2} \sum_r (\nabla_r \bar{R})_{irnj}, \\ (\varrho_t)_{nn} = \frac{t^4-1}{2t^2} (n-1) + \frac{1}{t^2} \bar{R}_{nn} - \frac{1}{2t^2} \sum_{rs} \bar{R}_{nrns} \bar{R}_{nrns}, \\ (\varrho_t)_{nn+j} = -\frac{1}{2} \sum_r (\nabla_r \bar{R})_{nrnj}, \\ (\varrho_t)_{n+i \ n+j} = \left\{ (n-2) - \frac{(t^2-1)^2}{2t^2} \right\} \delta_{ij} + \frac{1}{2t^2} \sum_r \bar{R}_{nrni} \bar{R}_{nrnj} + \frac{1}{4} \sum_{rs} \bar{R}_{rsni} \bar{R}_{rsnj}, \end{cases}$$

with

$$(7.12) \quad d(\bar{R}_{abcd}) = \sum_{m=1}^n \{ (\nabla_m \bar{R})_{abcd} \theta^m + \bar{R}_{mbcd} \omega_a^m + \bar{R}_{amcd} \omega_b^m + \bar{R}_{abmd} \omega_c^m + \bar{R}_{abcm} \omega_d^m \}.$$

If  $(M, g)$  is a space of constant curvature  $\lambda$ , (7.11) may be re-written as follows:

$$(7.13) \quad \begin{cases} (\varrho_t)_{ij} = -\frac{t^4 - 2\lambda(n-1)t^2 + \lambda^2 - 1}{2t^2} \delta_{ij}, \\ (\varrho_t)_{nn} = \frac{t^4 - (\lambda-1)^2}{2t^2} (n-1), \\ (\varrho_t)_{n+j, n+j} = -\frac{t^4 - 2(n-1)t^2 - \lambda^2 + 1}{2t^2} \delta_{ij}. \end{cases}$$

where the components that do not appear in (7.13) vanish identically on  $OM$ . From (7.13) we obtain

PROPOSITION 7.1. - *Let  $(M, g)$  be a space of constant curvature  $\lambda$ , then  $(T_1M, g_t)$  is an Einstein space if either  $\lambda = 1$ , and  $t^2 = 2((n-1)/n)$  or else  $\lambda = 0$  and  $n = 1$ ,  $t^2 = 1$ .*

Naturally, the latter case is trivial.

REMARK 7.1. - Equation (7.1) may be written in the form

$$(7.14) \quad Q_t = \sum_a (\theta^a)^2 + \sum_i (\omega_n^i)^2 + (t^2 - 1)(\theta^n)^2.$$

Therefore,

$$(7.15) \quad g_t = g'_s + (t^2 - 1)\gamma,$$

where  $\gamma$  is the 1-form induced on  $T_1M$  by  $\theta^n$ . Since  $\psi_n^*(\gamma) = \theta^n$ , we get

$$(7.16) \quad \gamma|_{(\alpha, v)}(X) = g_\alpha(d\pi(X), v), \quad X \in T_{(\alpha, v)}(T_1M).$$

Then  $\gamma$  is the restriction to  $T_1M$  of the Liouville form of  $TM$  (see [BE], p. 21), i.e.  $\gamma$  is the canonical contact form on  $T_1M$  (see [CH<sub>2</sub>] or [BL]).

Thus the Einstein metric on  $T_1S^n$  defined by Kobayashi can be obtained by deforming the induced Sasaki metric  $g'_s$  along the direction of the canonical contact form of  $T_1S^n$ .

Clearly the projection  $\pi: T_1S^n \rightarrow S^n$  is no longer a Riemannian submersion. This is the price to be paid for an Einstein metric. In context, see CALABI [CA] where the construction of Kähler metrics on holomorphic vector bundles is discussed.

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