Notice

Corrigenda to “Local structure of feasible sets in nonlinear programming, Part III: Stability and sensitivity”

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1. Eq. (1.8) requires a sign correction, to read

$$\begin{aligned} x_{yp}(y, p)(r)(q) = & -A(y, p)^{-1}D^{-}\{h_{xx}[x(y, p), p][x_p(y, p)q][x_y(y, p)r] \\ & + h_{xp}[x(y, p), p][x_y(y, p)r][q]\}. \end{aligned} \quad (1.8)$$

2. Eq. (3.7) should read

$$\text{minimize}\{\langle \phi_y(0, p_0) - w, y \rangle + \frac{1}{2}\langle y, \phi_{yy}(0, p_0)y \rangle \mid y \in T_0 \cap K\}. \quad (3.7)$$