Erratum to: Fast Fourier-Based Block-Matching Algorithm for Sonar Tracks Registration in a Multiresolution Framework

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Erratum to:

Chapter 1 in: L. Jaulin et al. (eds.), *Marine Robotics and Applications, Ocean Engineering & Oceanography* 10, https://doi.org/10.1007/978-3-319-70724-2_1

In the original version of the book, the following corrections have been incorporated in Chapter 1:

In page 3, the sentence “Indeed, while the former is obviously close to one, the latter can be neglected due to the INS heading drift which has experimentally been shown to be much slower than velocity and acceleration ones.” has been replaced with “Indeed, we assume that these global parameters can be modeled through our block-matching formulation.”

Table 1.1 has been updated with new corrections.

The updated online version of this chapter can be found at https://doi.org/10.1007/978-3-319-70724-2_1