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New proof on exponential convergence for cellular neural networks with time-varying delays

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Abstract

In this paper, we deal with a class of cellular neural networks with time-varying delays. Applying differential inequality strategies without assuming the boundedness conditions on the activation functions, we obtain a new sufficient condition that ensures that all solutions of the considered neural networks converge exponentially to the zero equilibrium point. We give an example to illustrate the effectiveness of the theoretical results. The results obtained in this paper are completely new and complement the previously known studies of Tang (*Appl. Math. Lett.* 21:872–876, 2008).

MSC: 34K20; 34C25; 34K14

Keywords: Cellular neural networks; Exponential convergence; Time-varying delay; Time-varying coefficients

1 Introduction

It is well known that cellular neural networks have attracted broad attention in numerous scientific fields due to their potential application prospect in psychophysics, speech, perception, robotics, pattern recognition, signal and image processing, optimization and population dynamics, and so on [2–6]. Noting that the design of cellular neural depends largely on the global exponential convergence natures, a lot of authors investigated the global exponential convergence of the equilibria and periodic solutions for cellular neural networks, and many outstanding achievements have been stated. For example, Zhang [7] focused on the exponential convergence for cellular neural networks with continuously distributed leakage delays. Applying the Lyapunov function method and differential inequality strategies, sufficient conditions that ensure that all solutions of the networks convergence exponentially to the zero equilibrium point are obtained. Liu [8] investigated the convergence for HCNNs with delays and oscillating coefficients in leakage terms. Using some suitable integral inequality technique, the authors established some sufficient conditions to ensure that all solutions of the networks convergence exponentially to the zero equilibrium point, Zhao and Wang [9] presented some sufficient conditions for exponential convergence via the Lyapunov functional method and differential inequality strategies for a SICNN with leakage delays and continuously distributed delays of neutral type. Chen

and Yang [10] established an exponential convergence criteria for HRNNs with continuously distributed delays in the leakage terms by using the Lyapunov functional method and differential inequality strategies. For more results on this topic, we refer the readers to [11–42].

In 2008, Tang [1] considered the following delayed cellular neural networks with time-varying coefficients:

$$\begin{aligned}
 x'_i(t) = & -c_i(t)x_i(t) + \sum_{j=1}^n a_{ij}(t)f_j(x_j(t - \tau_{ij}(t))) \\
 & + \sum_{j=1}^n b_{ij}(t) \int_0^\infty K_{ij}(u)g_j(x_j(t - u)) du + I_i(t),
 \end{aligned}
 \tag{1.1}$$

where $i = 1, 2, \dots, n, t \in \mathbb{R}, n$ corresponds to the number of units in a neural network, $x_i(t)$ denotes the state vector of the i th unit at the time $t, c_i(t) > 0$ denotes the rate with which the i th unit will reset its potential to the resting state in isolation when disconnected from the network and external inputs at the time $t, a_{ij}(t)$ and $b_{ij}(t)$ represent the connection weights at the time $t, \tau_{ij}(t) \geq 0$ denotes the transmission delay of the i th unit along the axon of the j th unit at the time $t, I_i(t)$ denotes the external bias on the i th unit at the time t, f_j and g_j are activation functions of signal transmission, and $K_{ij}(u)$ corresponds to the transmission delay kernel. Mathematical analysis technique was applied under the following conditions:

(A1) For each $j \in \{1, 2, \dots, n\}$, there exist nonnegative constants \bar{L}_j and L_j such that

$$|f_j(u)| \leq \bar{L}_j|u|, \quad |g_j(u)| \leq L_j|u| \quad \text{for all } u \in \mathbb{R}.$$

(A2) For $i \in \{1, 2, \dots, n\}$, there exist constants $T_0 > 0, \eta > 0, \lambda > 0$, and $\xi_0 > 0$ such that

$$\begin{aligned}
 & -[c_i(t) - \lambda]\xi_i + \sum_{j=1}^N |a_{ij}(t)|e^{\lambda\tau} \bar{L}_j \xi_j + \sum_{j=1}^N |b_{ij}(t)| \int_0^\infty K_{ij}(u)e^{\lambda u} du L_j \xi_j \\
 & < -\eta < 0 \quad \text{for all } t > T_0,
 \end{aligned}$$

where $\tau = \max_{1 \leq i, j \leq n} \{\sup_{t \in \mathbb{R}} \tau_{ij}(t)\}$.

(A3) For $i \in \{1, 2, \dots, n\}, I_i(t) = O(e^{-\lambda t})$.

Some sufficient conditions ensuring that all solutions of system (1.1) converge exponentially to zero equilibrium point were obtained. Here we would like to point out that Tang [1] investigated the exponential convergence by assuming that the leakage term coefficient functions $c_i(t)$ are not oscillating, that is, $c_i(t) > 0, i = 1, 2, \dots, n$. However, in many cases, oscillating coefficients usually occur in linearizations of population dynamics models due to seasonal fluctuations, for example, in winter the death rate maybe greater than the birth rate [5, 43]. Thus the study on the exponential convergence for cellular neural networks with oscillating coefficients in the leakage terms has important principle value and important realistic significance.

In this paper, we further consider the exponential convergence for cellular neural networks (1.1). The initial conditions associated with (1.1) are given by

$$x_i(s) = \varphi_i(s), \quad s \in (-\infty, 0], \varphi_i \in BC, i = 1, 2, \dots, n,
 \tag{1.2}$$

where BC denotes the set of all real-valued bounded and continuous functions defined on $(-\infty, 0]$. Differently from the assumptions in [1], we establish other sufficient conditions that guarantee that all solutions of the considered neural networks converge exponentially to the zero equilibrium point. We believe that this research on the exponential convergence for cellular neural networks plays an important role in designing the cellular neural networks with time-varying delays. Our results are new and a good complement to the work of [1].

For simplicity, we denote by R^p ($R = R^1$) the set of all p -dimensional real vectors (real numbers). Set $x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T \in R^n$. For any $x(t) \in R^n$, we let $|x|$ denote the absolute value vector given by $|x| = (|x_1|, |x_2|, \dots, |x_n|)^T$ and define $\|x\| = \max_{1 \leq i \leq n} |x_i(t)|$. For $f \in BC$, we denote $f^+ = \sup_{t \in R} |f(t)|$ and $f^- = \inf_{t \in R} |f(t)|$. Let $\tau^+ = \max_{1 \leq i, j \leq n} \{\sup_{t \in R} \tau_{ij}(t)\}$.

Throughout this paper, we assume that the following conditions are satisfied:

(H1) For $i = 1, 2, \dots, n$, there exist constants $\bar{c}_i > 0$ and $M > 0$ such that

$$e^{-\int_s^t c_i(u) du} \leq M e^{-(t-s)\bar{c}_i} \quad \text{for all } t, s \in R \text{ such that } t - s \geq 0.$$

(H2) For $j = 1, 2, \dots, n$, there exist positive constants L_j^f and L_j^g such that

$$\begin{aligned} |f_j(u) - f_j(v)| &\leq L_j^f |u - v|, & |g_j(u) - g_j(v)| &\leq L_j^g |u - v|, \\ f_j(0) &= 0, & g_j(0) &= 0 \end{aligned}$$

for $u, v \in R$.

(H3) For $i, j = 1, 2, \dots, n$, the delay kernel $K_{ij} : [0, \infty) \rightarrow R$ is continuous and absolutely integrable.

(H4) For $i = 1, 2, \dots, n$, there exists a positive constant μ_0 such that

$$I_i(t) = O(e^{-\mu_0 t}) \quad (t \rightarrow +\infty), \quad \frac{MG_i}{\bar{c}_i} < 1,$$

where

$$G_i = \sum_{j=1}^n a_{ij}^+ L_j^f + \sum_{j=1}^n b_{ij}^+ L_j^g \int_0^\infty K_{ij}(u) du.$$

The remainder of the paper is organized as follows. In Sect. 2, we establish a sufficient condition which ensures the exponential convergence of all solutions of the considered neural networks. In Sect. 3, we give an example that illustrates the theoretical findings. The paper ends with a brief conclusion in Sect. 4.

2 Global exponential convergence

Theorem 2.1 *If (H1)–(H4) hold, then for every solution $x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T$ of system (1.1) with any initial value conditions (1.2), there exists a positive constant λ such that $x_i(t) = O(e^{-\lambda t})$ as $t \rightarrow +\infty$, $i = 1, 2, \dots, n$.*

Proof We first define the continuous function

$$\Theta_i(\epsilon) = -\bar{c}_i + \epsilon + M \left[\sum_{j=1}^n a_{ij}^+ L_j^f e^{\epsilon \tau^+} + \sum_{j=1}^n b_{ij}^+ L_j^g \int_0^\infty K_{ij}(u) e^{\epsilon u} du + \epsilon \right], \tag{2.1}$$

where $\epsilon \in [0, \min\{\mu_0, \min_{1 \leq i \leq n} \bar{c}_i\})$. By (H4) we get

$$\begin{aligned} \Theta_i(0) &= -\bar{c}_i + M \left[\sum_{j=1}^n a_{ij}^+ L_j^f + \sum_{j=1}^n b_{ij}^+ L_j^g \int_0^\infty K_{ij}(u) du \right] \\ &= \bar{c}_i \left(\frac{MG_i}{\bar{c}_i} - 1 \right) < 0, \quad i = 1, 2, \dots, n. \end{aligned} \tag{2.2}$$

In view of the continuity of $\Theta_i(\epsilon)$, we can choose a constant $\lambda \in [0, \min\{\mu_0, \min_{1 \leq i \leq n} \bar{c}_i\})$ such that

$$\begin{aligned} -\bar{c}_i + \lambda + M \left[\sum_{j=1}^n a_{ij}^+ L_j^f e^{\lambda \tau^+} + \sum_{j=1}^n b_{ij}^+ L_j^g \int_0^\infty K_{ij}(u) e^{\lambda u} du + \lambda \right] \\ = (\bar{c}_i - \lambda) \left(\frac{M\gamma_i}{\bar{c}_i - \lambda} - 1 \right) < 0, \quad i = 1, 2, \dots, n, \end{aligned} \tag{2.3}$$

where

$$\gamma_i = \sum_{j=1}^n a_{ij}^+ L_j^f e^{\lambda \tau^+} + \sum_{j=1}^n b_{ij}^+ L_j^g \int_0^\infty K_{ij}(u) e^{\lambda u} du + \lambda.$$

Let $x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T$ be the solution of system (1.1) with any initial value $\varphi(t) = (\varphi_1(t), \varphi_2(t), \dots, \varphi_n(t))^T$ satisfying (1.2) and $\|\varphi\|_0 = \sup_{t \leq 0} \max_{1 \leq i \leq n} |\varphi_i(t)|$. For any $\epsilon > 0$, we have

$$\|x(t)\| < (\|\varphi\|_0 + \epsilon) e^{-\lambda t} < \Omega (\|\varphi\|_0 + \epsilon) e^{-\lambda t} \quad \text{for all } t \in (-\infty, 0], \tag{2.4}$$

where Ω is a sufficiently large constant such that

$$\|I_i(t)\| < \lambda \Omega (\|\varphi\|_0 + \epsilon) e^{-\lambda t} \quad \text{for all } t \in R \tag{2.5}$$

and

$$\Omega > \frac{\bar{c}_i - \lambda}{\gamma_i} + 1, \quad i = 1, 2, \dots, n. \tag{2.6}$$

It follows from (2.3) and (2.6) that

$$\frac{1}{\Omega} - \frac{\bar{c}_i - \lambda}{\gamma_i} < 0, \quad \frac{M\gamma_i}{\bar{c}_i - \lambda} < 1, \quad i = 1, 2, \dots, n. \tag{2.7}$$

Now we will prove that

$$\|x(t)\| < \Omega (\|\varphi\|_0 + \epsilon) e^{-\lambda t} \quad \text{for all } t > 0. \tag{2.8}$$

If (2.8) does not hold, then there must exist i and t_0 such that

$$\begin{cases} \|x(t_0)\| = |x_i(t_0)| = \Omega (\|\varphi\|_0 + \epsilon) e^{-\lambda t_0}, \\ \|x(t)\| < \Omega (\|\varphi\|_0 + \epsilon) e^{-\lambda t} \quad \text{for all } t \in (-\infty, t_0). \end{cases} \tag{2.9}$$

Notice that

$$\begin{aligned}
 x'_i(s) + c_i(s)x_i(s) &= \sum_{j=1}^n a_{ij}(s)f_j(x_j(s - \tau_{ij}(s))) \\
 &\quad + \sum_{j=1}^n b_{ij}(s) \int_0^\infty K_{ij}(u)g_j(x_j(s - u)) \, du \\
 &\quad + I_i(s), \quad s \in [0, t], t \in [0, t_0].
 \end{aligned}
 \tag{2.10}$$

Multiplying both sides of (2.10) by $e^{-\int_0^s c_i(u) \, du}$ and then integrating on $[0, t]$, we have

$$\begin{aligned}
 x_i(t) &= x_i(0)e^{-\int_0^t c_i(u) \, du} + \int_0^t e^{-\int_s^t c_i(u) \, du} \left[\sum_{j=1}^n a_{ij}(s)f_j(x_j(s - \tau_{ij}(s))) \right. \\
 &\quad \left. + \sum_{j=1}^n b_{ij}(s) \int_0^\infty K_{ij}(u)g_j(x_j(s - u)) \, du + I_i(s) \right], \quad t \in [0, t_0],
 \end{aligned}
 \tag{2.11}$$

and

$$\begin{aligned}
 |x_i(t_0)| &= \left| x_i(0)e^{-\int_0^{t_0} c_i(u) \, du} + \int_0^{t_0} e^{-\int_s^{t_0} c_i(u) \, du} \left[\sum_{j=1}^n a_{ij}(s)f_j(x_j(s - \tau_{ij}(s))) \right. \right. \\
 &\quad \left. \left. + \sum_{j=1}^n b_{ij}(s) \int_0^\infty K_{ij}(u)g_j(x_j(s - u)) \, du + I_i(s) \right] \right|.
 \end{aligned}
 \tag{2.12}$$

By (H1)–(H4) and (2.12) we get

$$\begin{aligned}
 |x_i(t_0)| &\leq M(\|\varphi\|_0 + \varepsilon)e^{-\bar{c}_i t_0} + \int_0^{t_0} M e^{-(t_0-s)\bar{c}_i} \left[\sum_{j=1}^n a_{ij}^+ L_j^f e^{\lambda \tau^+} \Omega(\|\varphi\|_0 + \varepsilon)e^{-\lambda s} \right. \\
 &\quad \left. + \sum_{j=1}^n b_{ij}^+ L_j^g \int_0^\infty K_{ij}(u)e^{\lambda u} \, du \Omega(\|\varphi\|_0 + \varepsilon)e^{-\lambda s} + \lambda \Omega(\|\varphi\|_0 + \varepsilon)e^{-\lambda s} \right] ds \\
 &\leq \Omega(\|\varphi\|_0 + \varepsilon) \left\{ \frac{M e^{-\bar{c}_i t_0}}{\Omega} + \int_0^{t_0} M e^{-(t_0-s)\bar{c}_i} e^{-\lambda s} \left[\sum_{j=1}^n a_{ij}^+ L_j^f e^{\lambda \tau^+} \right. \right. \\
 &\quad \left. \left. + \sum_{j=1}^n b_{ij}^+ L_j^g \int_0^\infty K_{ij}(u)e^{\lambda u} \, du + \lambda \right] ds \right\}.
 \end{aligned}
 \tag{2.13}$$

By (2.3), (2.6), (2.7), and (2.13) we have

$$\begin{aligned}
 |x_i(t_0)| &\leq \Omega(\|\varphi\|_0 + \varepsilon) \left[\frac{M e^{-\bar{c}_i t_0}}{\Omega} + e^{-\bar{c}_i t_0} \int_0^{t_0} e^{(\bar{c}_i - \lambda)s} \, ds \gamma_i \right] M \\
 &= \Omega(\|\varphi\|_0 + \varepsilon) e^{-\lambda t_0} \left[\frac{M e^{(\lambda - \bar{c}_i)t_0}}{\Omega} + \frac{\gamma_i}{\bar{c}_i - \lambda} (1 - e^{(\lambda - \bar{c}_i)t_0}) \right] M \\
 &= \Omega(\|\varphi\|_0 + \varepsilon) e^{-\lambda t_0} \left[\left(\frac{1}{\Omega} - \frac{\gamma_i}{\bar{c}_i - \lambda} \right) e^{(\lambda - \bar{c}_i)t_0} + \frac{\gamma_i}{\bar{c}_i - \lambda} \right] M
 \end{aligned}$$

$$\begin{aligned}
 &< \Omega (\|\varphi\|_0 + \varepsilon) e^{-\lambda t_0} \frac{\gamma_i}{\bar{c}_i - \lambda} M \\
 &< \Omega (\|\varphi\|_0 + \varepsilon) e^{-\lambda t_0},
 \end{aligned}
 \tag{2.14}$$

which contradicts (2.9). So (2.8) holds. Letting $\varepsilon \rightarrow 0^+$, it follows from (2.8) that

$$\|\mathbf{x}(t)\| < \Omega \|\varphi\|_0 e^{-\lambda t} \quad \text{for all } t > 0.
 \tag{2.15}$$

The proof of Theorem 2.1 is complete. □

Remark 2.1 Tang [1] analyzed the exponential convergence for cellular neural network model (1.1) under conditions (A1)–(A3). In this paper, we discuss the exponential convergence for cellular neural network model (1.1) under conditions (H1)–(H4). Moreover, the analysis method is different from that in [1].

3 Example

In this section, we present an example to verify the analytical predictions obtained in the previous section. Consider the following cellular neural networks with time-varying delays:

$$\begin{cases}
 x'_1(t) = -c_1(t)x_1(t) + \sum_{j=1}^2 a_{1j}(t)f_j(x_j(t - \tau_{1j}(t))) \\
 \quad + \sum_{j=1}^2 b_{1j}(t) \int_0^\infty K_{1j}(u)g_j(x_j(t - u)) du + I_1(t), \\
 x'_2(t) = -c_2(t)x_2(t) + \sum_{j=1}^2 a_{2j}(t)f_j(x_j(t - \tau_{2j}(t))) \\
 \quad + \sum_{j=1}^2 b_{2j}(t) \int_0^\infty K_{2j}(u)g_j(x_j(t - u)) du + I_2(t), \\
 x'_3(t) = -c_3(t)x_3(t) + \sum_{j=1}^2 a_{3j}(t)f_j(x_j(t - \tau_{3j}(t))) \\
 \quad + \sum_{j=1}^2 b_{3j}(t) \int_0^\infty K_{3j}(u)g_j(x_j(t - u)) du + I_3(t),
 \end{cases}
 \tag{3.1}$$

where $g_j(x) = f_j(x) = 0.03 \sin x^2$ ($j = 1, 2, 3$) and

$$\begin{bmatrix} a_{11}(t) & a_{12}(t) \\ b_{11}(t) & b_{12}(t) \end{bmatrix} = \begin{bmatrix} 0.2 + 0.4 \sin 4500t & 0.2 + 0.3 \sin 4500t \\ 0.1 + 0.4 \cos 4500t & 0.1 + 0.4 \cos 4500t \end{bmatrix},$$

$$\begin{bmatrix} a_{21}(t) & a_{22}(t) \\ b_{21}(t) & b_{22}(t) \end{bmatrix} = \begin{bmatrix} 0.1 + 0.4 \cos 5000t & 0.2 + 0.3 \cos 5000t \\ 0.2 + 0.2 \cos 5000t & 0.1 + 0.4 \sin 5000t \end{bmatrix},$$

$$\begin{bmatrix} a_{31}(t) & a_{32}(t) \\ b_{31}(t) & b_{32}(t) \end{bmatrix} = \begin{bmatrix} 0.2 + 0.3 \sin 6000t & 0.1 + 0.2 \cos 6000t \\ 0.1 + 0.2 \sin 6000t & 0.2 + 0.3 \sin 6000t \end{bmatrix},$$

$$\begin{bmatrix} K_{11}(u) & K_{12}(u) \\ K_{21}(u) & K_{22}(u) \\ K_{31}(u) & K_{32}(u) \end{bmatrix} = \begin{bmatrix} |\sin u|e^{-u} & |\sin u|e^{-u} \\ |\sin u|e^{-u} & |\sin u|e^{-u} \\ |\sin u|e^{-u} & |\sin u|e^{-u} \end{bmatrix},$$

$$\begin{bmatrix} c_1(u) & I_1(u) \\ c_2(u) & I_2(u) \\ c_3(u) & I_3(u) \end{bmatrix} = \begin{bmatrix} 0.2 + 3 \sin 6000t & e^{-2t} \sin t \\ 0.1 + 2 \sin 4000t & e^{-3t} \sin t \\ 0.1 + 2 \cos 5000t & e^{-5t} \sin t \end{bmatrix},$$

$$\begin{bmatrix} \tau_{11}(u) & \tau_{12}(u) \\ \tau_{21}(u) & \tau_{22}(u) \\ \tau_{31}(u) & \tau_{32}(u) \end{bmatrix} = \begin{bmatrix} 0.2 \sin^3 t & 0.4 \sin^3 t \\ 0.1 \sin^3 t & 0.3 \sin^3 t \\ 0.2 \sin^3 t & 0.4 \sin^3 t \end{bmatrix}.$$

Then $\bar{c}_1 = 0.2, \bar{c}_2 = 0.1, \bar{c}_3 = 0.1, L_j^f = L_j^g = 0.03$, and

$$\begin{bmatrix} a_{11}^+ & a_{12}^+ \\ b_{11}^+ & b_{12}^+ \end{bmatrix} = \begin{bmatrix} 0.6 & 0.5 \\ 0.5 & 0.5 \end{bmatrix},$$

$$\begin{bmatrix} a_{21}^+ & a_{22}^+ \\ b_{21}^+ & b_{22}^+ \end{bmatrix} = \begin{bmatrix} 0.5 & 0.5 \\ 0.4 & 0.5 \end{bmatrix},$$

$$\begin{bmatrix} a_{31}^+ & a_{32}^+ \\ b_{31}^+ & b_{32}^+ \end{bmatrix} = \begin{bmatrix} 0.5 & 0.3 \\ 0.3 & 0.5 \end{bmatrix}.$$

Let $M = e^{0.01}$. Then

$$\begin{aligned} G_1 &= \sum_{j=1}^2 a_{1j}^+ L_j^f + \sum_{j=1}^2 b_{1j}^+ L_j^g \int_0^\infty K_{1j}(u) \, du \\ &= (0.6 + 0.5) \times 0.03 + (0.5 + 0.5) \times 0.03 \times 0.5 \\ &= 0.0480, \end{aligned}$$

$$\begin{aligned} G_2 &= \sum_{j=1}^2 a_{2j}^+ L_j^f + \sum_{j=1}^2 b_{2j}^+ L_j^g \int_0^\infty K_{2j}(u) \, du \\ &= (0.5 + 0.5) \times 0.03 + (0.4 + 0.5) \times 0.03 \times 0.5 \\ &= 0.0313, \end{aligned}$$

$$\begin{aligned} G_3 &= \sum_{j=1}^2 a_{3j}^+ L_j^f + \sum_{j=1}^2 b_{3j}^+ L_j^g \int_0^\infty K_{3j}(u) \, du \\ &= (0.5 + 0.3) \times 0.03 + (0.3 + 0.5) \times 0.03 \times 0.5 \\ &= 0.0360, \end{aligned}$$

$$\frac{MG_1}{\bar{c}_1} = \frac{e^{0.01} \times 0.0480}{0.2} = 0.2425 < 1,$$

$$\frac{MG_2}{\bar{c}_2} = \frac{e^{0.01} \times 0.0313}{0.2} = 0.3160 < 1,$$

$$\frac{MG_3}{\bar{c}_3} = \frac{e^{0.01} \times 0.0360}{0.2} = 0.3640 < 1.$$

Thus all the conditions of Theorem 2.1 are satisfied. So we can conclude that all solutions of (3.1) converge exponentially to the zero equilibrium point $(0, 0, 0)^T$. This result is shown by computer simulation in Figs. 1–3.

4 Conclusions

In this paper, we are concerned with a class of cellular neural networks with time-varying delays. Using the differential inequality under the unboundedness conditions of the activation functions, we establish a sufficient condition guaranteeing that all solutions of the considered neural networks converge exponentially to the zero equilibrium point. The obtained sufficient condition is easy to check in practice. The results derived in this paper

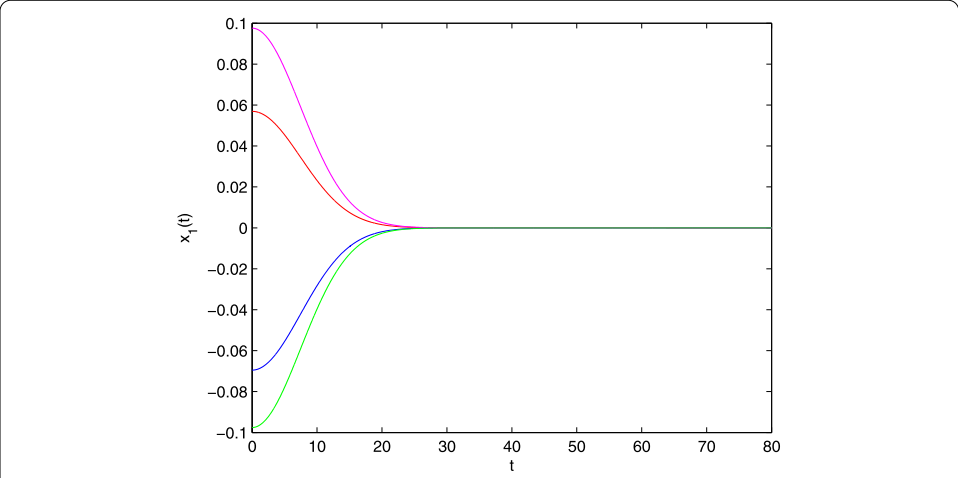


Figure 1 Time history of model (3.1)

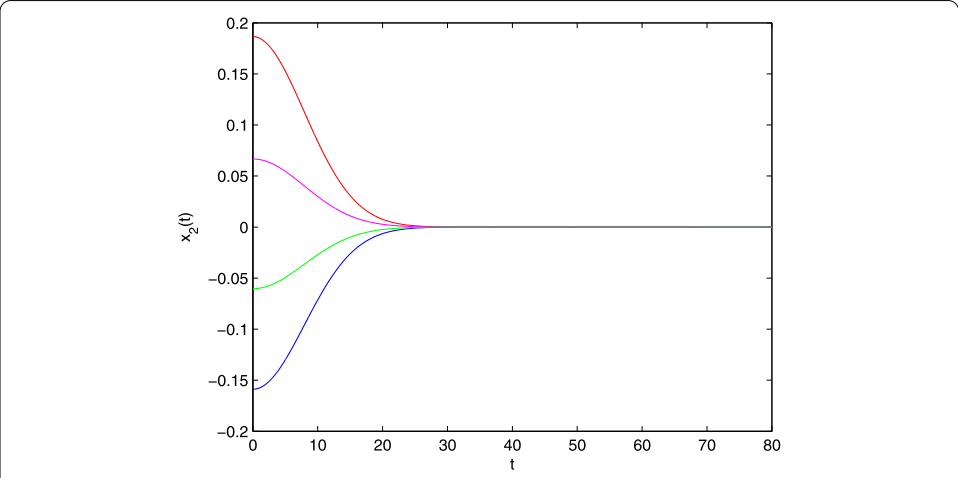


Figure 2 Time history of system (3.1)

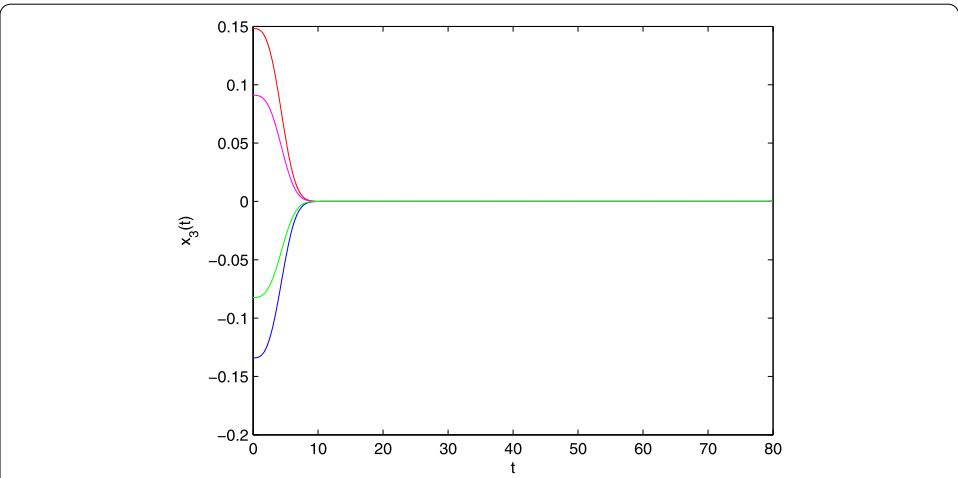


Figure 3 Time history of model (3.1)

are completely new and complement the previously known ones [1]. We present an example to illustrate the effectiveness of our theoretical results. The obtained results play a key role in designing neural networks and can be applied in many areas such as artificial intelligence, image recognition, disease diagnosis, and so on. Recently, pseudo-almost periodic solutions of cellular neural networks have also become a hot issue. However, there are rare results on pseudo-almost periodic solutions of cellular neural networks, which are worth studying in near future.

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Availability of data and materials

Not applicable.

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

Both authors have read and approved the final manuscript.

Authors' information

Changjin Xu's research interests are the bifurcation theory of delayed differential equations. Peiluan Li's research topics are nonlinear systems, functional differential equations, boundary value problems.

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