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ERRATUM

Erratum to: On Controllability Problems of High-Order Dynamical Multi-Agent Systems

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Erratum to: Arab J Sci Eng (2014) 39:4261–4267 DOI 10.1007/s13369-014-0973-2

The original version of this article unfortunately contains a mistake.

The correct form of the second paragraph in Sect. 1 should be:

"The results in the current paper form an extension to our previous works [15–18]. The novel features here are twofold: (1) A methodology is introduced for controllability analysis, which can transform a graph topology into equivalent forms. Based on this methodology, it will be shown in detail that any controllable graph with a single leader can be transformed into a path. (2) The controllability problem of heterogeneous multi-agent systems is also discussed."

The online version of the original article can be found under doi:10.1007/s13369-014-0973-2.

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