



Pressure transient analysis of a finite-conductivity multiple fractured horizontal well in linear composite gas reservoirs

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Abstract: Faulted gas reservoirs are very common in reality, where some linear leaky faults divide the gas reservoir into several reservoir regions with distinct physical properties. This kind of gas reservoirs is also known as linear composite (LC) gas reservoirs. Although some analytical/semi-analytical models have been proposed to investigate pressure behaviors of producing wells in LC reservoirs based on the linear composite ideas, almost all of them focus on vertical wells and studies on multiple fractured horizontal wells are rare. After the pressure wave arrives at the leaky fault, pressure behaviors of multiple fractured horizontal wells will be affected by the leaky faults. Understanding the effect of leaky faults on pressure behaviors of multiple fractured horizontal wells is critical to the development design. Therefore, a semi-analytical model of finite-conductivity multiple fractured horizontal (FCMFH) wells in LC gas reservoirs is established based on Laplace-space superposition principle and fracture discrete method. The proposed model is validated against commercial numerical simulator. Type curves are obtained to study pressure characteristics and identify flow regimes. The effects of some parameters on type curves are discussed. The proposed model will have a profound effect on developing analytical/semi-analytical models for other complex well types in LC gas reservoirs.

Key words: semi-analytical model; linear composite gas reservoir; multiple fractured horizontal well; finite-conductivity hydraulic fracture; pressure behavior

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1 Introduction

Faults are very common in various gas reservoirs, and some leaky faults have an important influence on the development of faulted gas

reservoirs. Owing to the existence of leaky faults, the gas reservoirs are usually divided into several reservoir regions with different properties, and the gas in one reservoir region can flow cross the faults and go into other reservoir regions. Therefore, the influence of leaky faults on fluid flow has attracted

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much attention. Linear composite (LC) model is considered as a reasonable approximation for describing fluid flow in hydrocarbon-bearing reservoirs separated by linear faults [1, 2]. In the last few decades, composite models, mainly including radial composite (RC) models and linear composite (LC) models, have been widely investigated and applied to various oil and gas reservoirs with variable reservoir properties. However, most of studies focus on RC models [3–5] and studies on LC models are few.

Pressure transient analysis is considered as a good way to analyze fluid flow characteristics and reservoir/well properties [6-15]. Pressure response of vertical wells in LC reservoirs has been investigated since the early 1960s. BIXEL et al [16] proposed the first analytical model of vertical wells in LC reservoirs and studied the impact of the fault on pressure behaviors. YAXLEY [1] developed an analytical model for LC reservoirs with a partially communicating fault. AMBASTHA et al [17] extended the LC model for infinite reservoirs to the one for finite strip reservoirs. BOURGEOIS et al [18] developed an analytical model for 3-zone LC reservoirs. KUCHUK et al [19] further developed an analytical model for n-zone LC reservoirs. ANDERSON [20] proposed an explicit analytical solution for fluid flow in infinite aquifers with a fault, and investigated the effect of the anisotropic fault. EZULIKE et al [21] developed an analytical model of horizontal wells in LC reservoirs, and investigated pressure behaviors of horizontal wells. ZEIDOUNI [22, 23] proposed analytical and semi-analytical models of vertical wells multilayer reservoirs with a leaky fault, respectively. FENG et al [24] developed an analytical model of a vertical well in a dual-porosity LC reservoir, and studied the characteristic of pressure behaviors. Considering fault permeability alteration, MOLINA et al [2] proposed an analytical model of vertical wells in LC reservoirs and used it to detect the fault reactivation. However, until now, almost all of analytical/semi-analytical models for LC reservoirs were aimed at vertical wells, and the studies on complex well types in LC reservoirs are rare. Compared with the establishment of analytical/ semi-analytical RC models for complex well types, it is much more difficult to establish analytical/ semi-analytical LC models for complex well types. Therefore, there are still significant challenges in establishing analytical/semi-analytical models for complex well types in LC reservoirs, for example, multiple fractured horizontal (MFH) wells with finite-conductivity hydraulic fractures.

Horizontal well in combination with hydraulic fracturing is considered as a good means of developing various oil/gas reservoirs, especially low-permeability oil/gas reservoirs. In the last decade, tight oil/gas reservoirs have captured the attention of people owing to the enormous oil/gas reserves, and MFH well has been extensively employed to develop these ultra-low-permeability reservoirs. Of course, the MFH well is not merely applied to low-permeability reservoirs; it is also used to develop some mid/high-permeability reservoirs because it can significantly increase production at low cost. Therefore, a variety of analytical/semi-analytical models have proposed to study pressure behaviors of MFH wells in various reservoirs, such as homogeneous reservoirs [25], dual porosity reservoirs [26], triple porosity reservoirs [27], fractal reservoirs [28], and radial composite reservoirs [29, 30].

To our knowledge, there are few analytical/semi-analytical models of MFH wells in LC reservoirs. Although some composite linear-flow models, which mainly include 3-linear flow model [31], 5-linear flow model [32], and other improved versions [33, 34], were proposed to deal with fluid flow in the stimulated reservoir volume near the MFH well, these composite linear-flow models divide the reservoir into several linear flow regions, which cannot reflect the complete characteristics of fluid flow in LC reservoirs. Therefore, it is still difficult to develop efficient and accurate analytical/semi-analytical models of MFH wells in LC reservoirs.

In this work, we derived the Laplace-space point source solution for LC gas reservoirs, and then proposed a semi-analytical model of finite-conductivity multiple fractured horizontal (FCMFH) wells in LC gas reservoirs based on Laplace-space superposition principle and fracture discrete method. The proposed semi-analytical model was validated against numerical simulation. Finally, pressure transient analysis of FCMFH wells in LC gas reservoirs was studied in detail.

2 Model descriptions

Figure 1 shows the schematic of an FCMFH well in an LC gas reservoir with a fault. As shown,

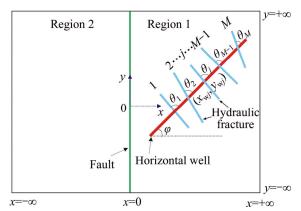


Figure 1 Schematic of FCMFH well in LC gas reservoir with a fault

an infinite gas reservoir is divided into two regions, i.e., Region 1 (x>0) and Region 2 (x<0), by a fault. An FCMFH well can be located at arbitrary position in Region 1. The proposed model is described as follows:

- 1) Each reservoir region (i.e., Region 1 or Region 2) is homogeneous and isotropic reservoir, but the two regions can have different properties (e.g., porosity, permeability, and rock compressibility). The properties of both the two regions are independent of pressure.
- 2) The gas reservoir, which has a uniform thickness for Region 1 and Region 2, is bounded by upper and lower impermeable layers. The fault is assumed to be located at x=0 and infinitely extended along the y-axis. The fault is considered as a partially communicating interface, where flux is continuous and pressure can be discontinuous. The orientation of the horizontal well can be arbitrary direction, and the angle between the horizontal well and x-axis is set as φ .
- 3) Hydraulic fractures completely vertically penetrate the gas reservoir, and the number of hydraulic fractures is assumed to be M. Each hydraulic fracture symmetrically distributes about the horizontal well and can intersect with the horizontal well with any angle (e.g., θ_j for the jth hydraulic fracture). The coordinates of the intersection between the jth hydraulic fracture and horizontal well are set to be (x_{wj}, y_{wj}) . Gas flow within each finite-conductivity hydraulic fracture is viewed as an incompressible linear flow.
- 4) Gas flow in LC gas reservoirs is assumed to be isothermal single-phase flow, which follows the Darcy law. Initial reservoir pressure is uniformly distributed in Region 1 and Region 2.

3 Mathematical models

3.1 Seepage model for LC gas reservoirs

If a point source is assumed to be located at coordinates (x_w, y_w) in Region 1 and gas is withdrawn from the point source with flow rate $q_{sc}(t)$, gas flow in the LC gas reservoir can be described by the following governing equations (Appendix A):

$$\frac{\partial}{\partial x} \left(\frac{k_1 p_1}{\mu Z} \frac{\partial p_1}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{k_1 p_1}{\mu Z} \frac{\partial p_1}{\partial y} \right) - \frac{p_{\text{sc}} T q_{\text{sc}}}{T_{\text{sc}} h} \delta \left(x - x_{\text{w}} \right) \delta \left(y - y_{\text{w}} \right)$$

$$= \frac{\phi_1 C_{t1} p_1}{Z} \frac{\partial p_1}{\partial t}, x > 0 \tag{1}$$

$$\frac{\partial}{\partial x} \left(\frac{k_2 p_2}{\mu Z} \frac{\partial p_2}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{k_2 p_2}{\mu Z} \frac{\partial p_2}{\partial y} \right) = \frac{\phi_2 C_{12} p_2}{Z} \frac{\partial p_2}{\partial t}, x < 0$$
(2)

where subscripts 1 and 2 represent Region 1 and Region 2, respectively; k is the permeability, m^2 ; μ is the gas viscosity, $Pa \cdot s$; p is the reservoir pressure, Pa; Z is the deviation factor of natural gas; x and y are the coordinates, m; p_{sc} is the pressure at standard condition, Pa; T is the gas reservoir temperature, K; q_{sc} is the production rate of the point source at standard condition, m^3/s ; T_{sc} is the temperature at standard condition, K; h is the reservoir thickness, m; δ is Dirac delta function; x_w , y_w are the coordinates of the point source, m; ϕ is the porosity; C_t is the total compressibility, Pa^{-1} ; t is the time, s.

In order to linearize Eqs. (1) and (2), the pseud-pressure is introduced as:

$$\psi_j = \psi(p_j) = \int_0^{p_j} \frac{2p}{uZ} dp, \ j = 1, 2$$
 (3)

Substituting Eq. (3) into Eqs. (1) and (2), one can derive that:

$$k_{1} \frac{\partial^{2} \psi_{1}}{\partial x^{2}} + k_{1} \frac{\partial^{2} \psi_{1}}{\partial y^{2}} - \frac{2 p_{sc} T q_{sc}}{T_{sc} h} \delta(x - x_{w}) \delta(y - y_{w})$$

$$= \phi_{1} C_{t1} \mu \frac{\partial \psi_{1}}{\partial t}, \ x > 0$$
(4)

$$k_2 \frac{\partial^2 \psi_2}{\partial x^2} + k_2 \frac{\partial^2 \psi_2}{\partial y^2} = \phi_2 C_{12} \mu \frac{\partial \psi_2}{\partial t}, \ x < 0$$
 (5)

Gas viscosity μ in both Eqs. (4) and (5) is the function of pressure, which is usually estimated at the initial reservoir pressure, i.e., $\mu = \mu(p_i) = \mu_i$. Then,

Eqs. (4) and (5) become respectively:

$$k_{1} \frac{\partial^{2} \psi_{1}}{\partial x^{2}} + k_{1} \frac{\partial^{2} \psi_{1}}{\partial y^{2}} - \frac{2 p_{sc} T q_{sc}}{T_{sc} h} \delta(x - x_{w}) \delta(y - y_{w})$$

$$= \phi_{1} C_{t1} \mu_{i} \frac{\partial \psi_{1}}{\partial t}, \ x > 0$$
(6)

$$k_2 \frac{\partial^2 \psi_2}{\partial x^2} + k_2 \frac{\partial^2 \psi_2}{\partial y^2} = \phi_2 C_{12} \mu_i \frac{\partial \psi_2}{\partial t}, \ x < 0$$
 (7)

Introducing dimensionless variables (see Table 1), Eqs. (6) and (7) are rewritten as, respectively:

$$\frac{\partial^{2} \psi_{1D}}{\partial x_{D}^{2}} + \frac{\partial^{2} \psi_{1D}}{\partial y_{D}^{2}} + 2\pi q_{D} \delta \left(x_{D} - x_{wD}\right) \delta \left(y_{D} - y_{wD}\right)$$

$$= \frac{\partial \psi_{1D}}{\partial t_{D}}, x_{D} > 0$$
(8)

$$\frac{\partial^2 \psi_{2D}}{\partial x_D^2} + \frac{\partial^2 \psi_{2D}}{\partial y_D^2} = \frac{1}{\eta} \frac{\partial \psi_{2D}}{\partial t_D}, \ x_D < 0$$
 (9)

Table 1 Definitions of dimensionless variables for FCMFH wells in LC gas reservoirs

FCMFH wells in LC gas reservoirs		
Nomenclature	Definition	
Dimensionless time	$t_{\rm D} = \frac{k_{\rm l}t}{\phi_{\rm l}\mu_{\rm i}C_{\rm tl}L^2}$	
Dimensionless pseud-pressure	$\psi_{jD} = \frac{\pi k_1 h T_{sc}}{Q_{sc} p_{sc} T} (\psi_i - \psi_j),$ where $j=1, 2, f$	
Dimensionless length	$x_{\mathrm{D}} = \frac{x}{L}, \ y_{\mathrm{D}} = \frac{y}{L}, L_{\mathrm{fD}j} = \frac{L_{\mathrm{fj}}}{L},$	
Mobility ratio	where $j=1, 2, \dots, M$ $\lambda = \left(\frac{k_2}{\mu_i}\right) / \left(\frac{k_1}{\mu_i}\right)$	
Diffusivity ratio	$\eta = \left(\frac{k_2}{\phi_2 C_{t2} \mu_i}\right) / \left(\frac{k_1}{\phi_1 C_{t1} \mu_i}\right)$	
Dimensionless production rate of point source	$q_{\mathrm{D}} = \frac{q_{\mathrm{sc}}}{Q_{\mathrm{sc}}}$	
Dimensionless fracture flux density	$q_{ ext{fD}} = rac{q_{ ext{f}}L}{Q_{ ext{sc}}}$	
Dimensionless wellbore storage coefficient	$C_{\rm D} = \frac{C}{2\pi\phi_{\rm l}C_{\rm tl}hL^2}$	
Dimensionless fracture conductivity coefficient	$C_{\rm fD} = \frac{k_{\rm f} w_{\rm f}}{k_{\rm l} L}$	

Note: L is the reference length chosen as $L = \sum_{j=1}^M L_{\mathrm{f}j} / M$ in this study, m.

Dimensionless outer boundary conditions

$$\lim_{x_{\rm D} \to +\infty} \psi_{\rm 1D}(x_{\rm D}, y_{\rm D}, t_{\rm D}) = \lim_{x_{\rm D} \to -\infty} \psi_{\rm 2D}(x_{\rm D}, y_{\rm D}, t_{\rm D}) = 0$$
(10)

$$\lim_{y_{\rm D} \to \pm \infty} \psi_{1\rm D}(x_{\rm D}, y_{\rm D}, t_{\rm D}) = \lim_{y_{\rm D} \to \pm \infty} \psi_{2\rm D}(x_{\rm D}, y_{\rm D}, t_{\rm D}) = 0$$
(11)

Dimensionless interface boundary conditions

$$\left. \frac{\partial \psi_{1D} \left(x_{D}, y_{D}, t_{D} \right)}{\partial x_{D}} \right|_{x_{D} = 0} = \lambda \left. \frac{\partial \psi_{2D} \left(x_{D}, y_{D}, t_{D} \right)}{\partial x_{D}} \right|_{x_{D} = 0}$$
(12)

$$S_{\rm F} \frac{\partial \psi_{\rm 1D}(x_{\rm D}, y_{\rm D}, t_{\rm D})}{\partial x_{\rm D}} \bigg|_{x_{\rm D}=0} = \psi_{\rm 1D}(x_{\rm D}, y_{\rm D}, t_{\rm D}) \bigg|_{x_{\rm D}=0} - \psi_{\rm 2D}(x_{\rm D}, y_{\rm D}, t_{\rm D}) \bigg|_{x_{\rm D}=0}$$
(13)

where λ is the mobility ratio defined in Table 1; S_F is the skin factor across the fault.

Dimensionless initial conditions

$$\psi_{1D}(x_D, y_D, t_D)\Big|_{t_D=0} = \psi_{2D}(x_D, y_D, t_D)\Big|_{t_D=0} = 0$$
 (14)

Taking Laplace transform of Eqs. (8)–(14) with respect to (w.r.t.) t_D and infinite Fourier transform w.r.t. y_D respectively, the Laplace-space point source solution for LC gas reservoirs is able to be derived as (Appendix B):

$$\overline{\psi}_{1D}(x_{D}, y_{D}, s) = \overline{q}_{D} \int_{0}^{\infty} \left[e^{-\sqrt{a_{1}}|x_{D} - x_{wD}|} + a_{3} e^{-\sqrt{a_{1}}(x_{D} + x_{wD})} \right].$$

$$\frac{\cos(\omega y_{wD})\cos(\omega y_{D}) + \sin(\omega y_{wD})\sin(\omega y_{D})}{\sqrt{a_{1}}} d\omega$$
(15)

where

$$a_1 = \omega^2 + s \tag{16}$$

$$a_2 = \omega^2 + \frac{s}{\eta} \tag{17}$$

$$a_{3} = \frac{\sqrt{a_{1}} + S_{F}\lambda\sqrt{a_{1}a_{2}} - \lambda\sqrt{a_{2}}}{\sqrt{a_{1}} + S_{F}\lambda\sqrt{a_{1}a_{2}} + \lambda\sqrt{a_{2}}}$$
(18)

Based on superposition principle in Laplace space [35, 36], pressure response at arbitrary position in Region 1 caused by an MFH well is obtained by integrating Eq. (15) along the line segments of all hydraulic fractures:

$$\overline{\psi}_{1D}(x_{D}, y_{D}, s) = \sum_{j=1}^{M} \int_{-L_{fDj}}^{L_{fDj}} \overline{q}_{fD} \cdot \int_{0}^{\infty} \left\{ e^{-\sqrt{a_{1}}|x_{D} - x_{wDj} - \alpha\cos(\theta_{j} + \varphi)|} + a_{3}e^{-\sqrt{a_{1}}[x_{D} + x_{wDj} + \alpha\cos(\theta_{j} + \varphi)]} \right\} \cdot \left\{ \left\{ \cos\left\{ \omega[y_{wDj} + \alpha\sin(\theta_{j} + \varphi)] \right\} \cos(\omega y_{D}) + \sin\left\{ \omega[y_{wDj} + \alpha\sin(\theta_{j} + \varphi)] \right\} \sin(\omega y_{D}) \right\} / \sqrt{a_{1}} \right\} d\omega d\alpha \tag{19}$$

where M is the number of hydraulic fractures; θ_j is the angle between the jth hydraulic fracture and horizontal well, (°); φ is the angle between the horizontal well and x-axis, (°); $L_{\text{fD}j}$ is the dimensionless half-length of the jth hydraulic fracture; q_{fD} is the dimensionless fracture flux density; $x_{\text{wD}j}$ and $y_{\text{wD}j}$ are the dimensionless coordinates of the intersection between the jth hydraulic fracture and horizontal well.

3.2 Seepage model for hydraulic fractures

Gas flow within each finite-conductivity hydraulic fracture of FCMFH wells is usually viewed as an incompressible linear flow. The seepage model of gas flow within the jth hydraulic fracture is established based on coordinate system (x_j, y_j) (see Figure 2) (Appendix C):

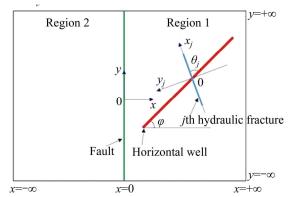


Figure 2 Relationship diagram of different coordinate systems

$$\frac{\partial^2 \psi_{\text{fD}}\left(x_{\text{D}j}, t_{\text{D}}\right)}{\partial x_{\text{D}i}^2} - \frac{2\pi}{C_{\text{fD}}} q_{\text{fD}}\left(x_{\text{D}j}, t_{\text{D}}\right) = 0 \tag{20}$$

$$\left. \frac{\partial \psi_{\text{fD}} \left(x_{\text{D}j}, t_{\text{D}} \right)}{\partial x_{\text{D}j}} \right|_{x_{\text{D}j} \to 0^{-}} = \frac{2\pi}{C_{\text{fD}}} \int_{-L_{\text{fD}j}}^{0^{-}} q_{\text{fD}} \left(x_{\text{D}j}, t_{\text{D}} \right) dx_{\text{D}j} \quad (21)$$

$$\left. \frac{\partial \psi_{\text{fD}} \left(x_{\text{D}j}, t_{\text{D}} \right)}{\partial x_{\text{D}j}} \right|_{x_{\text{D}i} \to 0^{+}} = -\frac{2\pi}{C_{\text{fD}}} \int_{0^{+}}^{L_{\text{D}j}} q_{\text{fD}} \left(x_{\text{D}j}, t_{\text{D}} \right) dx_{\text{D}j} \quad (22)$$

Equations (20)–(22) can be used to obtain the pressure at any position within the hydraulic fractures, which is expressed as follows:

$$\psi_{\text{wDH}}(t_{\text{D}}) - \psi_{\text{fD}}(x_{\text{D}j}, t_{\text{D}}) = \frac{2\pi}{C_{\text{fD}}} \left[x_{\text{D}j} \int_{0^{-}}^{-L_{\text{fD}j}} q_{\text{fD}}(x_{\text{D}j}, t_{\text{D}}) dx_{\text{D}j} - \int_{0^{-}}^{x_{\text{D}j}} \int_{0^{-}}^{\alpha} q_{\text{fD}}(\beta, t_{\text{D}}) d\beta d\alpha \right]$$
for $-L_{\text{fD}j} \le x_{\text{D}j} \le 0$; (23)

$$\psi_{\text{wDH}}(t_{\text{D}}) - \psi_{\text{fD}}(x_{\text{D}j}, t_{\text{D}}) = \frac{2\pi}{C_{\text{fD}}} \left[x_{\text{D}j} \int_{0^{+}}^{L_{\text{D}j}} q_{\text{fD}}(x_{\text{D}j}, t_{\text{D}}) dx_{\text{D}j} - \int_{0^{+}}^{x_{\text{D}j}} \int_{0^{+}}^{\alpha} q_{\text{fD}}(\beta, t_{\text{D}}) d\beta d\alpha \right]$$

$$(24)$$

for $0 \le x_{\mathrm{D}j} \le L_{\mathrm{fD}j}$, where ψ_{wDH} is the dimensionless wellbore pseud-pressure.

3.3 Semi-analytical model of an FCMFH well in LC gas reservoirs

The solution for gas flow in LC gas reservoirs (i.e., Eq. (19)) can be combined with the solution for gas flow in hydraulic fracture (i.e., Eqs. (23) and (24)) by the following expression:

$$\psi_{\text{1D}}(x_{\text{D}}, y_{\text{D}}, t_{\text{D}}) = \psi_{\text{fD}}(x_{\text{D}j}, t_{\text{D}}), (-L_{\text{fD}j} \le x_{\text{D}j} \le L_{\text{fD}j})$$
(25)

where $x_D = x_{wDj} + x_{Dj} \cos(\theta_j + \varphi)$ and $y_D = y_{wDj} + x_{Dj} \sin(\theta_j + \varphi)$.

Substituting Eq. (25) into Eqs. (23) and (24) and taking the Laplace transform w.r.t. t_D , one can derive that:

$$\overline{\psi}_{\text{wDH}}(s) - \overline{\psi}_{\text{1D}}(x_{\text{D}}, y_{\text{D}}, s) =
\frac{2\pi}{C_{\text{fD}}} \left[x_{\text{D}j} \int_{0^{-}}^{-L_{\text{D}j}} \overline{q}_{\text{fD}}(x_{\text{D}j}, s) dx_{\text{D}j} -
\int_{0^{-}}^{x_{\text{D}j}} \int_{0^{-}}^{\alpha} \overline{q}_{\text{fD}}(\beta, s) d\beta d\alpha \right]$$
(26)

for $-L_{fDi} \le x_{Di} \le 0$;

$$\overline{\psi}_{\text{wDH}}(s) - \overline{\psi}_{\text{1D}}(x_{\text{D}}, y_{\text{D}}, s) =
\frac{2\pi}{C_{\text{fD}}} \left[x_{\text{D}j} \int_{0^{+}}^{L_{\text{fD}j}} \overline{q}_{\text{fD}}(x_{\text{D}j}, s) dx_{\text{D}j} -
\int_{0^{+}}^{x_{\text{D}j}} \int_{0^{+}}^{\alpha} \overline{q}_{\text{fD}}(\beta, s) d\beta d\alpha \right]$$
(27)

for $0 \le x_{\mathrm{D}j} \le L_{\mathrm{fD}j}$, where $\overline{\psi}_{\mathrm{1D}}(x_{\mathrm{D}}, y_{\mathrm{D}}, s)$ is presented in Eq. (19).

The production rate of the FCMFH well is the sum of the flow rates from all the hydraulic fractures, which is expressed as:

$$Q_{\rm sc} = \sum_{j=1}^{M} \int_{-L_{fj}}^{L_{fj}} q_{\rm f}(x_j, t) dx_j$$
 (28)

Introducing the dimensionless variables (as shown in Table 1) and taking the Laplace transform w.r.t. t_D , Eq. (28) can be rewritten as:

$$\sum_{j=1}^{M} \int_{-L_{\text{ID}j}}^{L_{\text{ID}j}} \overline{q}_{\text{fD}}(x_{\text{D}j}, s) dx_{\text{D}j} = \frac{1}{s}$$
 (29)

Equations (26), (27) and (29) associating with Eq. (19) form a mathematical model of an FCMFH well in LC reservoirs in Laplace space. However, the proposed model is difficult to be analytically solved, and thus fracture discrete method is used to derive the semi-analytical solution. Each of hydraulic fractures is discretized into several segments. As shown in Figure 3, the two wings of the *j*th hydraulic fracture are discretized into N_j segments with the same length, respectively, and thus the total number of segments for an FCMFH well is $2\sum_{j=1}^{M} N_j$. The flux is uniformly distributed in

each segment. The mid-point coordinates of the *i*th segment of the *j*th hydraulic fracture, $(x_{mi,j}, y_{mi,j})$, are

$$\begin{cases} x_{\text{m}i,j} = x_{\text{w}j} - \left(i - \frac{1}{2}\right) \Delta L_{fj} \cos\left(\theta_{j} + \varphi\right) \\ y_{\text{m}i,j} = y_{\text{w}j} - \left(i - \frac{1}{2}\right) \Delta L_{fj} \sin\left(\theta_{j} + \varphi\right) \\ 1 \leq j \leq M, \ 1 \leq i \leq N_{j} \end{cases}$$

$$\begin{cases} x_{\text{m}i,j} = x_{\text{w}j} + \left(i - N_{j} - \frac{1}{2}\right) \Delta L_{fj} \cos\left(\theta_{j} + \varphi\right) \\ y_{\text{m}i,j} = y_{\text{w}j} + \left(i - N_{j} - \frac{1}{2}\right) \Delta L_{fj} \sin\left(\theta_{j} + \varphi\right) \end{cases}$$

$$1 \leq j \leq M, \ N_{j} + 1 \leq i \leq 2N_{j}$$

$$(31)$$

where $\Delta L_{fj} = L_{fj}/N_j$ is the fracture-segment length of the *j*th hydraulic fracture, m.

The coordinates $(x_{mi,j}, y_{mi,j})$ are transformed into the dimensionless form as follows:

$$\begin{cases} x_{\text{mD}i,j} = x_{\text{wD}j} - \left(i - \frac{1}{2}\right) \Delta L_{\text{fD}j} \cos\left(\theta_{j} + \varphi\right) \\ y_{\text{mD}i,j} = y_{\text{wD}j} - \left(i - \frac{1}{2}\right) \Delta L_{\text{fD}j} \sin\left(\theta_{j} + \varphi\right) \end{cases}, \\ 1 \leq j \leq M, \ 1 \leq i \leq N_{j}$$

$$\begin{cases} x_{\text{mD}i,j} = x_{\text{wD}j} + \left(i - N_{j} - \frac{1}{2}\right) \Delta L_{\text{fD}j} \cos\left(\theta_{j} + \varphi\right) \\ y_{\text{mD}i,j} = y_{\text{wD}j} + \left(i - N_{j} - \frac{1}{2}\right) \Delta L_{\text{fD}j} \sin\left(\theta_{j} + \varphi\right) \end{cases},$$

$$1 \leq j \leq M, \ N_{j} + 1 \leq i \leq 2N_{j}$$

$$(33)$$

where $x_{\text{mD}i,j}=x_{\text{m}i,j}/L$, $y_{\text{mD}i,j}=y_{\text{m}i,j}/L$, $x_{\text{wD}j}=x_{\text{w}j}/L$, $y_{\text{wD}j}=y_{\text{w}i}/L$, and $\Delta L_{\text{fD}i}=\Delta L_{\text{fi}i}/L$.

The distance between the coordinates (x_{wj}, y_{wj}) and the coordinates (x_{wj+1}, y_{wj+1}) is defined as:

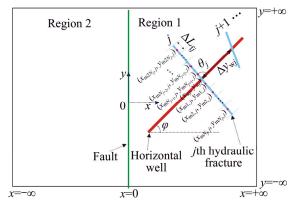


Figure 3 Discretization diagram of jth hydraulic fracture

$$\Delta y_{wj} = \sqrt{\left(x_{wj+1} - x_{wj}\right)^2 + \left(y_{wj+1} - y_{wj}\right)^2},$$

$$j = 1, 2, \dots, M - 1$$
(34)

If hydraulic fractures are discretized, Eqs. (26), (27) and (29) associating with Eq. (19) can be rewritten in the discrete form:

$$\overline{\psi}_{\text{wDH}}(s) - \sum_{j=1}^{M} \sum_{i=1}^{2N_{j}} \overline{\psi}_{1\text{D}i,j}(x_{\text{mD}\nu,k}, y_{\text{mD}\nu,k}, s) + \frac{2\pi}{C_{\text{fD}}} \left\{ \sum_{n=1}^{\nu-1} \overline{q}_{\text{fD}n,k}(s) \cdot [(\nu - n) \cdot \Delta L_{\text{fD}k}^{2}] + \frac{\Delta L_{\text{fD}k}^{2}}{8} \cdot \overline{q}_{\text{fD}\nu,k}(s) \right\} = \left\{ \left[2\pi \left[(x_{\text{mD}\nu,k} - x_{\text{wD}k})^{2} + (y_{\text{mD}\nu,k} - y_{\text{wD}k})^{2} \right]^{\frac{1}{2}} \right] / C_{\text{fD}} \right\} \sum_{n=1}^{N_{k}} \overline{q}_{\text{fD}n,k}(s) \Delta L_{\text{fD}k},$$

$$1 \le k \le M, \ 1 \le \nu \le N_{k} \tag{35}$$

$$\overline{\psi}_{\text{wDH}}(s) - \sum_{j=1}^{M} \sum_{i=1}^{2N_{j}} \overline{\psi}_{1\text{D}i,j}(x_{\text{mD}v,k}, y_{\text{mD}v,k}, s) + \frac{2\pi}{C_{\text{fD}}} \left\{ \sum_{n=N_{k}+1}^{v-1} \overline{q}_{\text{fD}n,k}(s) \cdot [(v-n) \cdot \Delta L_{\text{fD}k}^{2}] + \frac{\Delta L_{\text{fD}k}^{2}}{8} \cdot \overline{q}_{\text{fD}v,k}(s) \right\} = \left\{ \left[2\pi \left[(x_{\text{mD}v,k} - x_{\text{wD}k})^{2} + (y_{\text{mD}v,k} - y_{\text{wD}k})^{2} \right]^{\frac{1}{2}} \right] / C_{\text{fD}} \right\} \cdot \sum_{n=N_{k}+1}^{2N_{k}} \overline{q}_{\text{fD}n,k}(s) \Delta L_{\text{fD}k}, \\ 1 \le k \le M, N_{k} + 1 \le v \le 2N_{k} \tag{36}$$

$$\sum_{i=1}^{M} \sum_{j=1}^{2N_{j}} \left[\overline{q}_{\text{ID}i,j}(s) \cdot \Delta L_{\text{ID}j} \right] = \frac{1}{s}$$
(37)

where $q_{\text{fD}i,j}$ is the dimensionless fracture flux density of the *i*th segment of the *j*th hydraulic

fracture;
$$\overline{\psi}_{1\text{D}i,j}(x_{\text{mD}v,k}, y_{\text{mD}v,k}, s)$$
 is given as:
$$\overline{\psi}_{1\text{D}i,j}(x_{\text{mD}v,k}, y_{\text{mD}v,k}, s) = \int_{-\Delta L_{\text{m}j}/2}^{\Delta L_{\text{m}j}/2} \overline{q}_{\text{fD}i,j}(s) \cdot \int_{0}^{\infty} \left\{ e^{-\sqrt{a_{1}}|x_{\text{mD}v,k}-x_{\text{mD}i,j}-\alpha\cos(\theta_{j}+\varphi)|} + a_{3}e^{-\sqrt{a_{1}}[x_{\text{mD}v,k}+x_{\text{mD}i,j}+\alpha\cos(\theta_{j}+\varphi)]} \right\} \cdot \left\{ \left[\cos\left[\omega\left[y_{\text{mD}i,j}+\alpha\sin(\theta_{j}+\varphi)\right]\right] \cdot \cos(\omega y_{\text{mD}v,k}) + \sin\left[\omega\left[y_{\text{mD}i,j}+\alpha\cos(\theta_{j}+\varphi)\right]\right] \cdot \right\} \cdot \left\{ \left[\cos\left[\omega\left[y_{\text{mD}i,j}+\alpha\sin(\theta_{j}+\varphi)\right]\right] \cdot \left[\cos\left[\omega\left[y_{\text{mD}i,j}+\alpha\sin(\theta_{j}+\varphi)\right]\right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \sin\left[\omega\left[y_{\text{mD}i,j}+\alpha\cos(\theta_{j}+\varphi)\right]\right] \cdot \left[\cos(\omega y_{\text{mD}i,j}) + \cos(\omega y_{\text{mD}v,k}) + \sin\left[\omega\left[y_{\text{mD}i,j}+\alpha\cos(\theta_{j}+\varphi)\right]\right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{\text{mD}v,k}) + \cos(\omega y_{\text{mD}v,k}) \right] \cdot \left[\cos(\omega y_{$$

Equations (35)–(38) consist of
$$\left(2\sum_{j=1}^{M} N_j + 1\right)$$

linear equations with $\left(2\sum_{j=1}^{M}N_{j}+1\right)$ unknowns, i.e.,

 $\alpha \sin(\theta_j + \varphi) \left[\sin(\omega y_{\text{mD}\nu,k}) \right] / \sqrt{a_1} d\omega d\alpha$

 $\overline{\psi}_{\text{wDH}}(s)$ and $\overline{q}_{\text{ID}i,j}(s)$ $(1 \le j \le M, \ 1 \le i \le 2N_j)$. By solving the linear equations, the dimensionless wellbore pseud-pressure in Laplace space $\overline{\psi}_{\text{wDH}}(s)$ is obtained. To incorporate the impact of the wellbore storage and skin, Duhamel's principle is used as follows [37, 38]:

$$\overline{\psi}_{\text{wD}}(s) = \frac{s\overline{\psi}_{\text{wDH}}(s) + S}{s + s^2 C_{\text{D}} \left[s\overline{\psi}_{\text{wDH}}(s) + S \right]}$$
(39)

where S is the skin factor near the wellbore; $C_{\rm D}$ is the dimensionless wellbore storage coefficient defined in Table 1. Finally, the numerical Laplace inversion method [39] is employed to transform the Laplace-space pseud-pressure $\bar{\psi}_{\rm wD}(s)$ to the real-space pseud-pressure $\psi_{\rm wD}(t_{\rm D})$.

4 Model validation

The proposed semi-analytical model is validated by comparing with numerical results generated by the Saphir numerical simulator in this section. The schematic of the numerical model is shown in Figure 4, from which it is seen that an FCMFH well is located in Region 1 of an LC gas reservoir separated by a fault. The dimensionless size of the LC gas reservoir is set as a large value (i.e., 4000×4000), which could avoid the boundary effect within the simulation time. The unstructured grid system (i.e., Voronoi grid), which is automatically generated by the Saphir numerical simulator, is applied to the spatial discretization of the numerical model (see Figure 5). The input parameters used for numerical simulations are

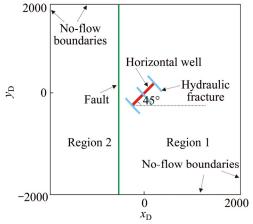


Figure 4 Schematic of an FCMFH well in an LC gas reservoir with a fault

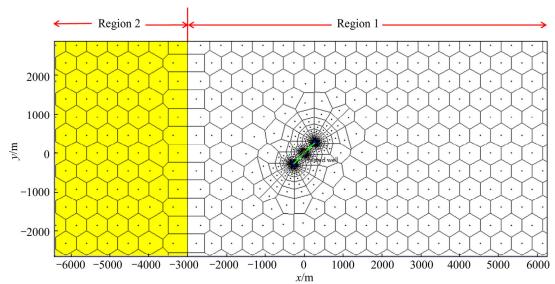


Figure 5 Local spatial discretization of numerical model of an FCMFH well in an LC gas reservoir with a fault by using Saphir numerical simulator

mainly collected from the published literature [40] and are listed in Table 2. Figure 6 shows the comparison of the results obtained by the proposed model and Saphir numerical simulator. It is seen

Table 2 Basic data for numerical simulations

Parameter	Value
Reservoir thickness, h/m	7.62
Porosity of Region 1, ϕ_1	0.075
Gas viscosity at the initial reservoir pressure, μ_i /(mPa·s)	0.0252
Total compressibility of Region 1, C_{t1}/MPa^{-1}	1.43×10 ⁻²
Permeability of Region 1, k_1/mD	0.05
Initial reservoir pressure, p _i /MPa	44.8
Gas reservoir temperature, T/K	412.04
Number of hydraulic fractures, M	3
Half-length of j th hydraulic fracture, L_{fj} /m	40
Angle between <i>j</i> th hydraulic fracture and horizontal well, $\theta_j/(^\circ)$	90
Angle between the horizontal well and x -axis, $\varphi/(^{\circ})$	45
Distance between the horizontal well center and the fault, x_w/m	3000
Fracture spacing, $\Delta y_{\rm w}/$ m	400
Dimensionless fracture conductivity coefficient, $C_{\rm fD}$	20
Production rate of the FCMFH well at standard condition, $Q_{sc}/(m^3 \cdot d^{-1})$	5000
Mobility ratio, λ	0.2
Diffusivity ratio, η	1
Skin factor across the fault, $S_{\rm F}$	0
Skin factor near the wellbore, S	0
Dimensionless wellbore storage coefficient, C_D	0

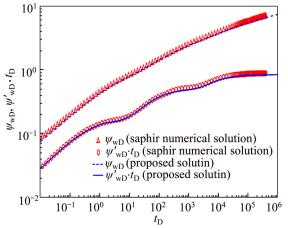


Figure 6 Comparison of results obtained by proposed model and Saphir numerical simulator (M=3, L_f =40 m, S=0, C_D =0, C_f D=20, θ_f =90°, φ =45°, η =1, λ =0.2, S_f =0, x_w =3000 m, y_w =0 m, Δy_w = Δy_{w1} = Δy_{w2} =400 m)

that the proposed solution agrees excellently with Saphir numerical solution, demonstrating that the proposed semi-analytical model is able to be used to investigate the pressure characteristics of an FCMFH well in LC gas reservoirs with a fault.

5 Type curves and sensitivity analysis

The proposed model is employed to obtain the dimensionless wellbore pseud-pressure (DWPP) and dimensionless wellbore pseud-pressure derivative (DWPPD) of an FCMFH well in LC gas reservoirs. Type curve of an FCMFH well in LC gas reservoirs is plotted to study the characteristics of transient pressure responses and identify flow regimes. The effects of some parameters on the DWPP and DWPPD responses are analyzed in detail.

5.1 Type curves

Figure 7 shows type curve of an FCMFH well in LC gas reservoirs with a fault. Type curve consists of the DWPP curve (i.e., $\psi_{\rm wD}$ versus $t_{\rm D}/C_{\rm D}$ curve) and the DWPPD curve (i.e., $\psi'_{\rm wD} \cdot t_{\rm D}/C_{\rm D}$ versus $t_{\rm D}/C_{\rm D}$ curve). It is observed from Figure 7 that the type curve can be divided into nine parts, which correspond to nine flow regimes as follows:

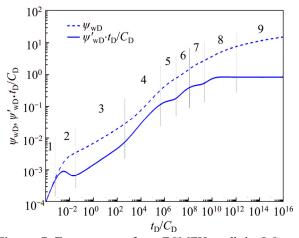


Figure 7 Type curve of an FCMFH well in LC gas reservoirs with a fault (M=3, L_{fj} =40 m, S=10⁻³, C_D =10⁻⁶, C_{fD} =20, θ_j =90°, φ =45°, η =1, λ =0.2, S_F =1000, x_w =3000 m, y_w =0 m, Δy_w = Δy_{w1} = Δy_{w2} =400 m)

1) Wellbore storage flow period (WSFP): DWPP curve and DWPPD curve show the same straight line with unit slope. During the WSFP, the produced gas is all from the wellbore-storage gas, and the gas in the reservoir has not entered into the

wellbore.

- 2) Transitional flow period after WSFP (TFP-WSFP): DWPPD curve exhibits a "hump", which is mainly affected by the seepage capability near the wellbore. During this period, the gas in the reservoir begins to flow into the wellbore, and the pressure wave travels in the reservoir area near the wellbore.
- 3) Bilinear flow period (BFP): DWPPD curve exhibits a 0.25-slope straight line. During the BFP, the two linear flows take place together: one is within the hydraulic fracture; the other is perpendicular to the reservoir-fracture contact surface (see Figure 8(a)).
- 4) First linear flow period (FLFP): DWPPD curve shows a 0.5-slope straight line. During the FLFP, the linear flow perpendicular to the reservoir-fracture contact surface takes place, and the linear flow of each hydraulic fracture cannot interact with each other (see Figure 8(b)).
- 5) First pseudo-radial flow period (FPRFP): DWPPD curve exhibits a horizontal line. During the FPRFP, the pseudo-radial flow independently takes place around each of hydraulic fractures (see Figure 8(c)).
- 6) Second linear flow period (SLFP): DWPPD curve exhibits a straight line with a 0.5 slope. In the SLFP, pressure waves caused by adjacent hydraulic

- fractures have interacted with each other, and a linear flow occurs along the direction of hydraulic fractures (see Figure 8(d)).
- 7) Second pseudo-radial flow period (SPRFP): DWPPD curve shows a horizontal line with the magnitude being 0.5. During the SPRFP, the pseudo-radial flow toward the FCMFH well occurs in Region 1 and the pressure wave has not reached the fault (see Figure 8(e)).
- 8) Transitional flow period after SPRFP (TFP-SPRFP): DWPPD curve appears as a step. During the TFP-SPRFP, the pressure wave has arrived at the fault but has not transmitted into Region 2 totally. The flow period is mainly affected by the properties of the fault and Region 2, which will be analyzed in detail later.
- 9) Third pseudo-radial flow period (TPRFP): DWPPD curve shows a horizontal line with a constant value, whose magnitude is dependent on the properties of Region 2. During the TPRFP, the pressure wave has totally transmitted into Region 2 and the pseudo-radial flow toward the FCMFH well takes place in the whole gas reservoir including Region 1 and Region 2 (see Figure 8(f)).

It should be noted that not all the flow regimes described above exist for FCMFH wells in LC gas reservoirs with a fault. Depending on the reservoir/well properties, some of these flow

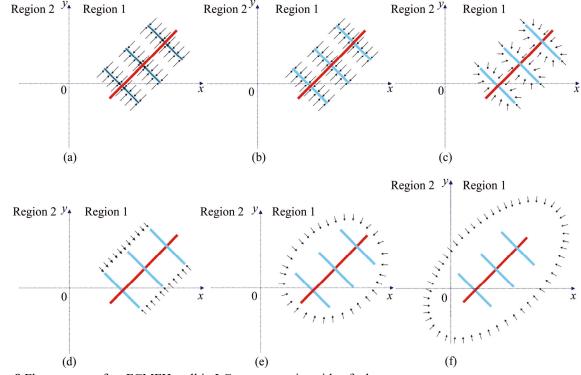


Figure 8 Flow pattern of an FCMFH well in LC gas reservoirs with a fault

regimes may be absent. Therefore, sensitivity analysis will be conducted in the next subsection to study the effect of some parameters on the pressure behaviors.

5.2 Sensitivity analysis

Figure 9 shows the effect of skin factor across the fault (S_F) on the DWPP and DWPPD responses of an FCMFH well in LC gas reservoirs with a fault, from which it is seen that the S_F merely affects the flow periods after the pressure wave has arrived at the fault, i.e., TFP-SPRFP and TPRFP. Increasing the S_F will result in a longer duration of the TFP-SPRFP and a later start time of the TPRFP. The reason of this phenomenon is that a larger S_F represents a larger flow resistance across the fault. If the flow resistance across the fault increases, the drawdown pressure should be enhanced to keep the production rate unchanged, and the transmission time of the pressure wave across the fault should become longer.

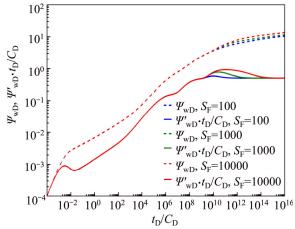


Figure 9 Effect of skin factor across fault ($S_{\rm F}$) on type curve of an FCMFH well in LC gas reservoirs with a fault (M=3, $L_{\rm fj}$ =40 m, S=10⁻³, $C_{\rm D}$ =10⁻⁶, $C_{\rm fD}$ =20, $\theta_{\rm j}$ =90°, φ =45°, η =1, λ =1, $x_{\rm w}$ =3000 m, $y_{\rm w}$ =0 m, $\Delta y_{\rm w}$ = $\Delta y_{\rm w1}$ = $\Delta y_{\rm w2}$ =400 m)

Figure 10 shows the effect of the distance between the horizontal well center and the fault (x_w) on the DWPP and DWPPD responses of an FCMFH well in LC gas reservoirs with a fault. It is observed that the x_w affects the duration of the SPRFP and the start time of the TFP-SPRFP. The smaller the x_w is, the shorter the duration of the SPRFP is and the earlier the start time of the TFP-SPRFP becomes. It is noted that if the FCMFH well is located near the fault, the SPRFP may

disappear. The reason is that as the x_w becomes smaller, the pressure wave reaches the fault earlier.

Figure 11 shows the effect of mobility ratio (λ) on the DWPP and DWPPD responses of an FCMFH well in LC gas reservoirs with a fault. Based on the definition of the λ (as shown in Table 1), the λ represents the flow capability of Region 2 compared with Region 1. The flow capability of Region 2 increases with increasing λ . It is clear from Figure 11 that λ has an impact on pressure responses of FCMFH wells after the pressure wave reaches the fault, and the DWPP and DWPPD increase with decreasing λ . The cause of this phenomenon is that the decrease of λ reduces the flow capability of Region 2, and thus the drawdown

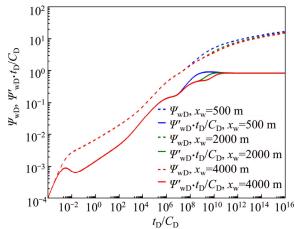


Figure 10 Effect of distance between horizontal well center and fault (x_w) on type curve of an FCMFH well in LC gas reservoirs with a fault (M=3, L_f =40 m, S=10⁻³, C_D =10⁻⁶, C_f =20, θ_f =90°, φ =45°, η =1, λ =0.2, S_F =1000, y_w =0 m, Δy_w = Δy_w 1= Δy_w 2=400 m)

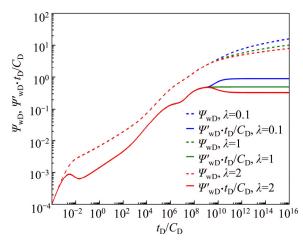


Figure 11 Effect of mobility ratio (λ) on type curve of an FCMFH well in LC gas reservoirs with a fault (M=3, L_f =40 m, S=10⁻³, C_D =10⁻⁶, C_f D=20, θ_f =90°, φ =45°, η =1, S_F =0, x_w =3000 m, y_w =0 m, Δy_w = Δy_{w1} = Δy_{w2} =400 m)

pressure should be enhanced to keep the production rate unchanged.

Figure 12 shows the effect of diffusivity ratio (η) on the DWPP and DWPPD responses of an FCMFH well in LC gas reservoirs with a fault. According to the definition of η (see Table 1), η is inversely proportional to $(\phi_2 C_{12})/(\phi_1 C_{t1})$ under the same other parameters (e.g., the same λ). The storage capability of Region 2 increases with decreasing η . It is seen from Figure 12 that η mainly has an impact on the TFP-SPRFP, where the DWPP and DWPPD decrease with decreasing η . The reason is that decreasing η improves the storage capability of Region 2, and thus the drawdown pressure must decrease to maintain the fixed production rate.

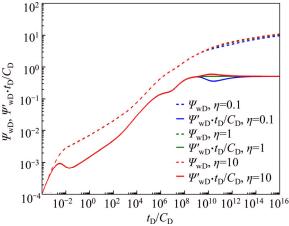


Figure 12 Effect of diffusivity ratio (η) on type curve of an FCMFH well in LC gas reservoirs with a fault (M=3, L_f =40 m, S=10⁻³, C_D =10⁻⁶, C_f D=20, θ_f =90°, φ =45°, λ =1, S_F =0, x_w =3000 m, y_w =0 m, Δy_w = Δy_w 1= Δy_w 2=400 m)

Figure 13 shows the effect of dimensionless fracture conductivity coefficient (C_{fD}) on the DWPP and DWPPD responses of an FCMFH well in LC gas reservoirs with a fault. It is clear that $C_{\rm fD}$ primarily affects the early-time flow periods including TFP-WSFP, BFP, and FLFP. As $C_{\rm fD}$ increases, the DWPP and DWPPD decrease, the BFP lasts shorter, and the FLFP appears earlier. The reason is that increasing $C_{\rm fD}$ causes the increase of the hydraulic-fracture permeability; in other words, increasing $C_{\rm fD}$ leads to the improvement of the seepage capability near the wellbore. Therefore, in order to keep the production rate constant, the drawdown pressure of the FCMFH well should decrease with increasing $C_{\rm fD}$. Furthermore, with the improvement of the hydraulic-fracture permeability,

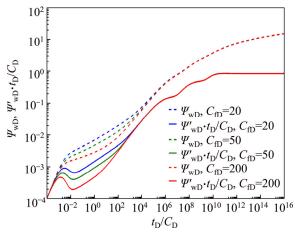


Figure 13 Effect of dimensionless fracture conductivity coefficient ($C_{\rm fD}$) on type curve of an FCMFH well in LC gas reservoirs with a fault (M=3, $L_{\rm fj}$ =40 m, S=10⁻³, $C_{\rm D}$ =10⁻⁶, $\theta_{\rm j}$ =90°, φ =45°, η =1, λ =0.2, $S_{\rm F}$ =1000, $x_{\rm w}$ =3000 m, $y_{\rm w}$ =0 m, $\Delta y_{\rm w}$ = $\Delta y_{\rm w1}$ = $\Delta y_{\rm w2}$ =400 m)

the BFP lasts shorter and then the FLFP begins earlier.

Figure 14 shows the effect of fracture spacing $(\Delta y_{\rm w})$ on the DWPP and DWPPD responses of an FCMFH well in LC gas reservoirs with a fault. It is obvious that $\Delta y_{\rm w}$ has an effect on the flow periods from FPRFP to SPRFP. As $\Delta y_{\rm w}$ decreases, the duration of the FPRFP gets shorter, and the SLFP and SPRFP begin earlier. If $\Delta y_{\rm w}$ is small enough, the FPRFP may be masked by the SLFP and SPRFP. This is because that as $\Delta y_{\rm w}$ decreases, the interference between adjacent hydraulic fractures occurs earlier.

It is noted that some differences are observed

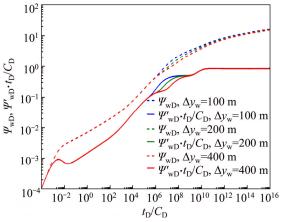


Figure 14 Effect of fracture spacing ($\Delta y_{\rm w}$) on type curve of an FCMFH well in LC gas reservoirs with a fault (M=3, $L_{\rm fj}$ =40 m, S=10⁻³, $C_{\rm D}$ =10⁻⁶, $C_{\rm fD}$ =20, $\theta_{\rm j}$ =90°, φ =45°, η =1, λ =0.2, $S_{\rm F}$ =1000, $x_{\rm w}$ =3000 m, $y_{\rm w}$ =0 m, $\Delta y_{\rm w}$ = $\Delta y_{\rm w1}$ = $\Delta y_{\rm w2}$)

at some intermediate-time flow periods in Figures 9, 10, 12 and 14. The explanations are given as follows: S_F only has an effect on the TFP-SPRFP and TPRFP (as shown in Figure 9); x_w mainly affects the SPRFP and TFP-SPRFP (as shown in Figure 10); η mainly has an impact on the TFP-SPRFP (as shown in Figure 12); Δy_w mainly has an effect on the FPRFP, SLFP, and SPRFP (as shown in Figure 14).

Figure 15 shows the effect of the number of hydraulic fractures (M) on the DWPP and DWPPD responses of an FCMFH well in LC gas reservoirs with a fault. It is clear that M mainly has an impact on the flow periods (i.e., from TFP-WSFP to SPRFP) that the pressure wave has not reached the fault. As M increases, the DWPP and DWPPD decrease. The reason is that increasing M means the improvement of the seepage capability near the wellbore, and thus the drawdown pressure of FCMFH wells with a fixed production rate should decrease with increasing M.

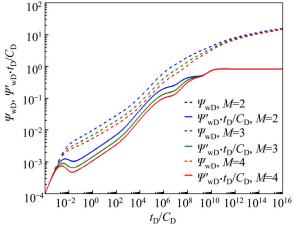


Figure 15 Effect of number of hydraulic fractures (*M*) on type curve of an FCMFH well in LC gas reservoirs with a fault ($L_{\rm f}$ =40 m, S=10⁻³, $C_{\rm D}$ =10⁻⁶, $C_{\rm fD}$ =20, $\theta_{\rm f}$ =90°, φ =45°, η =1, λ =0.2, $S_{\rm F}$ =1000, $x_{\rm w}$ =3000 m, $y_{\rm w}$ =0 m, $\Delta y_{\rm w}$ = $\Delta y_{\rm w_f}$ =400 m)

6 Conclusions

- 1) A semi-analytical model of FCMFH wells in LC gas reservoirs is proposed based on Laplace-space superposition principle and fracture discrete method. The proposed model is validated against the results obtained by Saphir numerical simulator.
- 2) Type curves of an FCMFH well in LC gas reservoirs are obtained to conduct the pressure

transient analysis based on the established model. It is found that there are nine possible flow regimes in the whole production process of the FCMFH well. Before the pressure wave reaches the fault, the first seven flow periods (i.e., from WSFP to SPRFP) appear one after another; after the pressure wave arrives at the fault, the last two flow periods (i.e., TFP-SPRFP and TPRFP) just turn up.

- 3) The effects of some parameters on type curves and flow regimes are discussed in detail. It is found that dimensionless fracture conductivity coefficient, fracture spacing, and number of hydraulic fractures mainly affect the pressure behaviors before the pressure wave reaches the fault; skin factor across the fault, mobility ratio, and diffusivity ratio only have an impact on the pressure behaviors after the pressure wave arrives at the fault.
- 4) The proposed model provides an efficient method to obtain pressure responses of FCMFH wells in LC gas reservoirs. It is also helpful to further develop analytical/semi-analytical models for other complex well types in LC gas reservoirs.

Appendix A Derivation of governing equations for point source in LC gas reservoirs

Based on mass conservation, continuity equations for LC gas reservoirs with a point source located at (x_w, y_w) are given as:

$$-\frac{\partial(\rho_{1}\nu_{x1})}{\partial x} - \frac{\partial(\rho_{1}\nu_{y1})}{\partial y} - \frac{\rho_{sc}q_{sc}}{h}\delta(x - x_{w})\delta(y - y_{w})$$

$$= \frac{\partial(\rho_{1}\phi_{1})}{\partial t}, x > 0$$
(A1)

$$-\frac{\partial(\rho_2 \nu_{x2})}{\partial x} - \frac{\partial(\rho_2 \nu_{y2})}{\partial y} = \frac{\partial(\rho_2 \phi_2)}{\partial t}, \ x < 0$$
 (A2)

where subscript 1 and 2 represent Region 1 and Region 2, respectively; ρ is the gas density, kg/m³; v_x is the x-direction gas velocity, m/s; v_y is the y-direction gas velocity, m/s; ρ_{sc} is the gas density at standard condition, kg/m³; q_{sc} is the production rate of the point source at standard condition, m³/s; h is the reservoir thickness, m; δ is Dirac delta function; v_x , v_y are the coordinates, m; v_y , v_y are the coordinates of the point source, m; v_y is the porosity; v_y is the time, s.

According to the Darcy law, the gas velocities in the x and y directions are described by, respectively:

$$v_{xj} = -\frac{k_j}{\mu} \frac{\partial p_j}{\partial x} \tag{A3}$$

$$v_{yj} = -\frac{k_j}{\mu} \frac{\partial p_j}{\partial y} \tag{A4}$$

where subscript j=1, 2 represents Region 1 and Region 2, respectively; k is the permeability, m^2 ; μ is the gas viscosity, Pa·s; p is the reservoir pressure, Pa.

The equation of state for real gas is given as follows:

$$\rho_j = \frac{p_j M_g}{ZRT} \tag{A5}$$

where subscript j=1, 2 represents Region 1 and Region 2, respectively; M_g is the gas molar mass, kg/mol; Z is the deviation factor of natural gas; R is the universal gas constant, $J/(\text{mol} \cdot K)$; T is the gas reservoir temperature, K.

The gas compressibility and rock compressibility are defined, respectively, as:

$$C_{\rm g} = \frac{1}{p_i} - \frac{1}{Z} \frac{\partial Z}{\partial p_i} \tag{A6}$$

$$C_{ij} = \frac{1}{\phi_j} \frac{\partial \phi_j}{\partial p_j} \tag{A7}$$

where subscript j=1, 2 represents Region 1 and Region 2, respectively; C_g is the gas compressibility, Pa^{-1} ; C_r is the rock compressibility, Pa^{-1} .

Substituting Eqs. (A3)–(A7) into Eqs. (A1) and (A2) yields that:

$$\frac{\partial}{\partial x} \left(\frac{k_1 p_1}{\mu Z} \frac{\partial p_1}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{k_1 p_1}{\mu Z} \frac{\partial p_1}{\partial y} \right) - \frac{p_{sc} T q_{sc}}{T_{sc} h} \delta \left(x - x_w \right) \delta \left(y - y_w \right)$$

$$= \frac{\phi_1 C_{t_1} p_1}{Z} \frac{\partial p_1}{\partial t}, \quad x > 0 \tag{A8}$$

$$\frac{\partial}{\partial x} \left(\frac{k_2 p_2}{\mu Z} \frac{\partial p_2}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{k_2 p_2}{\mu Z} \frac{\partial p_2}{\partial y} \right) = \frac{\phi_2 C_{t2} p_2}{Z} \frac{\partial p_2}{\partial t}, \ x < 0$$
(A9)

where C_{t1} and C_{t2} are the total compressibility of Region 1 and Region 2, respectively, which are defined by C_{tj} = C_g + C_{tj} , j=1, 2. It is noted that C_{t1} and C_{t2} are actually the functions of pressure, but they are usually treated as constants for engineering applications, i.e., C_{t1} = C_{t1} (p_i) and C_{t2} = C_{t2} (p_i).

Appendix B Derivation of Laplace-space point source solution for LC gas reservoirs

1) Laplace transform of Eqs. (8)–(14) w.r.t. t_D

$$\begin{split} \frac{\partial^2 \overline{\psi}_{1D}}{\partial x_D^2} + \frac{\partial^2 \overline{\psi}_{1D}}{\partial y_D^2} + 2\pi \overline{q}_D \delta \left(x_D - x_{wD} \right) \delta \left(y_D - y_{wD} \right) \\ = s \overline{\psi}_{1D}, \ x_D > 0 \end{split} \tag{B1}$$

$$\frac{\partial^2 \overline{\psi}_{2D}}{\partial x_D^2} + \frac{\partial^2 \overline{\psi}_{2D}}{\partial y_D^2} = \frac{s}{\eta} \overline{\psi}_{2D}, \ x_D < 0$$
 (B2)

$$\lim_{x_{\rm D} \to +\infty} \overline{\psi}_{\rm 1D}(x_{\rm D}, y_{\rm D}, s) = \lim_{x_{\rm D} \to -\infty} \overline{\psi}_{\rm 2D}(x_{\rm D}, y_{\rm D}, s) = 0 \quad (B3)$$

$$\lim_{y_{\rm D} \to \pm \infty} \overline{\psi}_{\rm 1D}(x_{\rm D}, y_{\rm D}, s) = \lim_{y_{\rm D} \to \pm \infty} \overline{\psi}_{\rm 2D}(x_{\rm D}, y_{\rm D}, s) = 0 \quad (B4)$$

$$\frac{\partial \overline{\psi}_{1D}(x_{D}, y_{D}, s)}{\partial x_{D}}\bigg|_{x_{D}=0} = \lambda \frac{\partial \overline{\psi}_{2D}(x_{D}, y_{D}, s)}{\partial x_{D}}\bigg|_{x_{D}=0}$$
(B5)

$$S_{\mathrm{F}} \frac{\partial \overline{\psi}_{\mathrm{1D}}(x_{\mathrm{D}}, y_{\mathrm{D}}, s)}{\partial x_{\mathrm{D}}} \bigg|_{x_{\mathrm{D}} = 0} = \overline{\psi}_{\mathrm{1D}}(x_{\mathrm{D}}, y_{\mathrm{D}}, s) \bigg|_{x_{\mathrm{D}} = 0} - \overline{\psi}_{\mathrm{2D}}(x_{\mathrm{D}}, y_{\mathrm{D}}, s) \bigg|_{x_{\mathrm{D}} = 0}$$
(B6)

where s is the Laplace transform variable; $\overline{\psi}_{1D}$, $\overline{\psi}_{2D}$ and \overline{q}_{D} are the corresponding Laplace-space variables of ψ_{1D} , ψ_{2D} and q_{D} , respectively, which are given as:

$$\overline{\psi}_{1D}(x_D, y_D, s) = \int_0^\infty \psi_{1D}(x_D, y_D, t_D) e^{-st_D} dt_D$$
 (B7)

$$\bar{\psi}_{2D}(x_D, y_D, s) = \int_0^\infty \psi_{2D}(x_D, y_D, t_D) e^{-st_D} dt_D$$
 (B8)

$$\overline{q}_{\mathrm{D}}(s) = \int_{0}^{\infty} q_{\mathrm{D}}(t_{\mathrm{D}}) \mathrm{e}^{-st_{\mathrm{D}}} \mathrm{d}t_{\mathrm{D}}$$
(B9)

2) Infinite Fourier transform of Eqs. (B1)–(B6) w.r.t. y_D

$$\frac{\partial^2 \tilde{\psi}_{1D}}{\partial x_D^2} - (\omega^2 + s) \tilde{\psi}_{1D} + 2\pi \bar{q}_D e^{-i\omega y_{wD}} \delta(x_D - x_{wD}) = 0,$$

$$x_D > 0$$
(B10)

$$\frac{\partial^2 \tilde{\psi}_{2D}}{\partial x_D^2} - \left(\omega^2 + \frac{s}{\eta}\right) \tilde{\psi}_{2D} = 0, \ x_D < 0$$
 (B11)

$$\lim_{x_{\rm D} \to +\infty} \tilde{\psi}_{\rm 1D}(x_{\rm D}, \omega, s) = \lim_{x_{\rm D} \to -\infty} \tilde{\psi}_{\rm 2D}(x_{\rm D}, \omega, s) = 0 \qquad (B12)$$

$$\frac{\partial \tilde{\psi}_{1D}(x_{D}, \omega, s)}{\partial x_{D}}\bigg|_{x=0} = \lambda \frac{\partial \tilde{\psi}_{2D}(x_{D}, \omega, s)}{\partial x_{D}}\bigg|_{x=0}$$
(B13)

$$S_{F} \frac{\partial \tilde{\psi}_{1D}(x_{D}, \omega, s)}{\partial x_{D}} \bigg|_{x_{D}=0} = \tilde{\psi}_{1D}(x_{D}, \omega, s) \bigg|_{x_{D}=0} - \tilde{\psi}_{2D}(x_{D}, \omega, s) \bigg|_{x_{D}=0}$$
(B14)

where ω is the Fourier transform variable; $\bar{\psi}_{1D}$ and $\bar{\psi}_{2D}$ are the corresponding Fourier-space variables of $\bar{\psi}_{1D}$ and $\bar{\psi}_{2D}$, respectively, which are defined as:

$$\tilde{\overline{\psi}}_{1D}(x_D, \omega, s) = \int_{-\infty}^{\infty} \overline{\psi}_{1D}(x_D, y_D, s) e^{-i\omega y_D} dy_D$$
 (B15)

$$\tilde{\overline{\psi}}_{2D}(x_D, \omega, s) = \int_{-\infty}^{\infty} \overline{\psi}_{2D}(x_D, y_D, s) e^{-i\omega y_D} dy_D$$
 (B16)

Equations (B10)–(B14) consist of ordinary differential equations w.r.t. x_D , which are able to be analytically solved as follows:

$$\widetilde{\psi}_{1D}(x_D, \omega, s) = \frac{\pi \overline{q}_D e^{-i\omega y_{wD}}}{\sqrt{a_1}} \left(e^{-\sqrt{a_1}|x_D - x_{wD}|} + a_3 e^{-\sqrt{a_1}(x_D + x_{wD})} \right)$$
(B17)

$$\tilde{\psi}_{2D}(x_{D}, \omega, s) = \frac{2\pi \bar{q}_{D} e^{-i\omega y_{wD}} e^{-\sqrt{a_{1}} x_{wD} + \sqrt{a_{2}} x_{D}}}{\sqrt{a_{1}} + S_{F} \lambda \sqrt{a_{1} a_{2}} + \lambda \sqrt{a_{2}}}$$
(B18)

where

$$a_1 = \omega^2 + s \tag{B19}$$

$$a_2 = \omega^2 + \frac{s}{\eta} \tag{B20}$$

$$a_{3} = \frac{\sqrt{a_{1}} + S_{F}\lambda\sqrt{a_{1}a_{2}} - \lambda\sqrt{a_{2}}}{\sqrt{a_{1}} + S_{F}\lambda\sqrt{a_{1}a_{2}} + \lambda\sqrt{a_{2}}}$$
(B21)

3) Inverse Fourier transform of Eq. (B17) w.r.t.

$$\overline{\psi}_{1D}(x_{D}, y_{D}, s) = \frac{\overline{q}_{D}}{2} \int_{-\infty}^{\infty} \left[e^{-\sqrt{a_{1}}|x_{D} - x_{wD}|} + a_{3} e^{-\sqrt{a_{1}}(x_{D} + x_{wD})} \right].$$

$$\left\{ \left\{ \left[\cos(\omega y_{wD}) - i \sin(\omega y_{wD}) \right] \right\} - \left[\cos(\omega y_{D}) + i \sin(\omega y_{D}) \right] \right\} / \sqrt{a_{1}} d\omega$$
(B22)

Equation (B22) is obtained based on the expression of inverse Fourier transform:

$$\overline{\psi}_{\rm 1D}(x_{\rm D}, y_{\rm D}, s) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \widetilde{\psi}_{\rm 1D}(x_{\rm D}, \omega, s) e^{i\omega y_{\rm D}} d\omega \qquad (B23)$$

It is obvious that the integrand in Eq. (B22) is the product of two parts (i.e., A_1 and A_2):

$$A_1 = e^{-\sqrt{a_1}|x_D - x_{wD}|} + a_3 e^{-\sqrt{a_1}(x_D + x_{wD})}$$
(B24)

$$A_{2} = \left\{ \left[\cos(\omega y_{\text{wD}}) - i\sin(\omega y_{\text{wD}}) \right] \cdot \left[\cos(\omega y_{\text{D}}) + i\sin(\omega y_{\text{D}}) \right] \right\} / \sqrt{a_{1}} \right\}$$
(B25)

Equation (B25) can be rewritten as the sum of two parts:

$$A_2 = A_{21} + A_{22} \tag{B26}$$

where

$$A_{21} = \left\{ \left[\cos(\omega y_{\text{wD}}) \cos(\omega y_{\text{D}}) + \sin(\omega y_{\text{wD}}) \sin(\omega y_{\text{D}}) \right] \right\} / \sqrt{a_1} \right\}$$
(B27)

$$A_{22} = \left\{ \left[\cos(\omega y_{\text{wD}}) \sin(\omega y_{\text{D}}) - \sin(\omega y_{\text{wD}}) \cos(\omega y_{\text{D}}) \right] \right\} / \sqrt{a_1} \right\}$$
(B28)

It is noted that A_1 in Eq. (B24) and A_{21} in Eq. (B27) are even functions of ω , A_{22} in Eq. (B28) is odd function of ω .

Considering the odevity of functions and the symmetry of integral domain, Eq. (B22) can be simplified as:

$$\overline{\psi}_{1D}(x_{D}, y_{D}, s) = \overline{q}_{D} \int_{0}^{\infty} \left[e^{-\sqrt{a_{1}}|x_{D} - x_{wD}|} + a_{3}e^{-\sqrt{a_{1}}(x_{D} + x_{wD})} \right] \cdot \left\{ \left[\cos(\omega y_{wD}) \cos(\omega y_{D}) + \sin(\omega y_{wD}) \sin(\omega y_{D}) \right] / \sqrt{a_{1}} \right\} d\omega$$
(B29)

Appendix C Derivation of dimensionless model for gas flow within a hydraulic fracture

Because of a very small volume within hydraulic fracture compared with the reservoir volume, gas flow within hydraulic fractures is usually viewed as an incompressible linear flow. To study the linear flow within hydraulic fractures, the coordinate system (x_j, y_j) for the jth hydraulic fracture is employed to establish the dimensionless model for gas flow within the jth hydraulic fracture (see Figure 2). The governing equation of gas flow within the jth hydraulic fracture can be described as [41]:

$$\frac{\partial}{\partial x_{j}} \left[\frac{p_{f}}{\mu Z} \frac{\partial p_{f}(x_{j}, y_{j}, t)}{\partial x_{j}} \right] + \frac{\partial}{\partial y_{j}} \left[\frac{p_{f}}{\mu Z} \frac{\partial p_{f}(x_{j}, y_{j}, t)}{\partial y_{j}} \right] = 0$$
(C1)

where
$$-L_{fj} \le x_j \le L_{fj}$$
, $-\frac{w_f}{2} \le y_j \le \frac{w_f}{2}$; L_{fj} is the

half-length of the *j*th hydraulic fracture, m; w_f is the hydraulic fracture width, m; p_f is the pressure in hydraulic fractures, Pa.

Introducing the pseud-pressure:

$$\psi_{\rm f} = \psi(p_{\rm f}) = \int_0^{p_{\rm f}} \frac{2p}{\mu Z} \mathrm{d}p \tag{C2}$$

Equation (C1) becomes:

$$\frac{\partial}{\partial x_{j}} \left[\frac{\partial \psi_{f}(x_{j}, y_{j}, t)}{\partial x_{j}} \right] + \frac{\partial}{\partial y_{j}} \left[\frac{\partial \psi_{f}(x_{j}, y_{j}, t)}{\partial y_{j}} \right] = 0 \quad (C3)$$

The fracture flux density of the *j*th hydraulic fracture is described by:

$$q_{\rm f}\left(x_j,t\right) = \frac{hk_1T_{\rm sc}}{2p_{\rm sc}T} \left[\frac{\partial \psi_1\left(x_j,y_j,t\right)}{\partial y_j} \right|_{y_j = \frac{w_{\rm f}}{2}} -$$

$$\frac{\partial \psi_1(x_j, y_j, t)}{\partial y_j}\bigg|_{y_j = -\frac{w_f}{2}}$$
 (C4)

where $-L_{fj} \le x_j \le L_{fj}$, and q_f is the fracture flux density at standard condition, m^2/s .

Considering the incompressible linear flow within hydraulic fractures, the wellbore conditions can be described as:

$$h \int_{-\frac{w_{\mathrm{f}}}{2}}^{\frac{w_{\mathrm{f}}}{2}} \frac{k_{\mathrm{f}} T_{\mathrm{sc}}}{2 p_{\mathrm{sc}} T} \frac{\partial \psi_{\mathrm{f}} \left(x_{j}, y_{j}, t \right)}{\partial x_{j}} \mathrm{d}y_{j} \bigg|_{x_{j} \to 0^{-}} =$$

$$- \int_{-L_{\mathrm{fj}}}^{0^{-}} q_{\mathrm{f}} \left(x_{j}, t \right) \mathrm{d}x_{j} \qquad (C5)$$

$$h \int_{-\frac{w_{\mathrm{f}}}{2}}^{\frac{w_{\mathrm{f}}}{2}} \frac{k_{\mathrm{f}} T_{\mathrm{sc}}}{2 p_{\mathrm{sc}} T} \frac{\partial \psi_{\mathrm{f}} \left(x_{j}, y_{j}, t \right)}{\partial x_{j}} \mathrm{d}y_{j} \bigg|_{x_{j} \to 0^{+}} =$$

$$\int_{0^{+}}^{L_{\mathrm{fj}}} q_{\mathrm{f}} \left(x_{j}, t \right) \mathrm{d}x_{j} \qquad (C6)$$

where k_f is the permeability of hydraulic fracture, m^2 .

The boundary conditions of the reservoir-fracture contact surface can be described based on the mass conservation:

$$\frac{k_{\rm f}T_{\rm sc}}{2p_{\rm sc}T} \frac{\partial \psi_{\rm f}(x_{j}, y_{j}, t)}{\partial y_{j}} \bigg|_{y_{j} = \frac{w_{\rm f}}{2}} = \frac{k_{1}T_{\rm sc}}{2p_{\rm sc}T} \frac{\partial \psi_{\rm 1}(x_{j}, y_{j}, t)}{\partial y_{j}} \bigg|_{y_{j} = \frac{w_{\rm f}}{2}} \tag{C7}$$

$$\frac{k_{\rm f}T_{\rm sc}}{2p_{\rm sc}T} \frac{\partial \psi_{\rm f}(x_{j}, y_{j}, t)}{\partial y_{j}} \bigg|_{y_{j} = -\frac{w_{\rm f}}{2}} =$$

$$\frac{k_1 T_{\text{sc}}}{2 p_{\text{sc}} T} \frac{\partial \psi_1(x_j, y_j, t)}{\partial y_j} \bigg|_{y_j = -\frac{w_f}{2}}$$
(C8)

Owing to the hydraulic fracture width being very small, the y_j -direction pressure variation within the jth hydraulic fracture is usually neglected, and the y_j -direction average pressure is introduced as:

$$\psi_{f}(x_{j},t) = \frac{1}{w_{f}} \int_{-\frac{w_{f}}{2}}^{\frac{w_{f}}{2}} \psi_{f}(x_{j},y_{j},t) dy_{j}, -L_{fj} \leq x_{j} \leq L_{fj}$$
(C9)

With the aid of Eqs. (C7)–(C9), Eq. (C3) can be rewritten as:

$$\frac{\partial^{2} \psi_{\mathbf{f}}\left(x_{j},t\right)}{\partial x_{j}^{2}} + \frac{k_{1}}{w_{\mathbf{f}}k_{\mathbf{f}}} \left[\frac{\partial \psi_{1}\left(x_{j},y_{j},t\right)}{\partial y_{j}} \bigg|_{y_{j} = \frac{w_{\mathbf{f}}}{2}} - \frac{1}{2} \left(\frac{\partial \psi_{1}\left(x_{j},y_{j},t\right)}{\partial y_{j}} \right) \right]_{y_{j} = \frac{w_{\mathbf{f}}}{2}} - \frac{1}{2} \left(\frac{\partial \psi_{1}\left(x_{j},y_{j},t\right)}{\partial y_{j}} \right) \left(\frac{\partial \psi$$

$$\left. \frac{\partial \psi_1(x_j, y_j, t)}{\partial y_j} \right|_{y_j = -\frac{w_t}{2}} = 0 \tag{C10}$$

Substituting Eq. (C4) into Eq. (C10) yields that:

$$\frac{\partial^2 \psi_f\left(x_j,t\right)}{\partial x_i^2} + \frac{2p_{sc}T}{w_f k_f h T_{sc}} q_f\left(x_j,t\right) = 0$$
 (C11)

Based on Eq. (C9), Eqs. (C5) and (C6) can be rewritten as:

$$hw_{\rm f} \left. \frac{k_{\rm f} T_{\rm sc}}{2 p_{\rm sc} T} \frac{\partial \psi_{\rm f} \left(x_j, t \right)}{\partial x_j} \right|_{x_j \to 0^-} = -\int_{-L_{\rm fj}}^{0^-} q_{\rm f} \left(x_j, t \right) dx_j \quad (C12)$$

$$hw_{\rm f} \left. \frac{k_{\rm f} T_{\rm sc}}{2p_{\rm sc} T} \frac{\partial \psi_{\rm f} \left(x_j, t\right)}{\partial x_j} \right|_{x_j \to 0^+} = \int_{0^+}^{L_{\rm fj}} q_{\rm f} \left(x_j, t\right) dx_j \qquad \text{(C13)}$$

Considering the dimensionless variables (see Table 1), Eqs. (C11)–(C13) are rewritten in dimensionless form:

$$\frac{\partial^2 \psi_{fD}\left(x_{Dj}, t_D\right)}{\partial x_{Dj}^2} - \frac{2\pi}{C_{fD}} q_{fD}\left(x_{Dj}, t_D\right) = 0 \tag{C14}$$

$$\frac{\partial \psi_{fD}\left(x_{Dj}, t_{D}\right)}{\partial x_{Dj}}\bigg|_{x_{Dj} \to 0^{-}} = \frac{2\pi}{C_{fD}} \int_{-L_{fDj}}^{0^{-}} q_{fD}\left(x_{Dj}, t_{D}\right) dx_{Dj} \tag{C15}$$

$$\frac{\partial \psi_{\text{fD}}\left(x_{\text{D}j}, t_{\text{D}}\right)}{\partial x_{\text{D}j}} \bigg|_{x_{\text{D}j} \to 0^{+}} = -\frac{2\pi}{C_{\text{fD}}} \int_{0^{+}}^{L_{\text{fD}j}} q_{\text{fD}}\left(x_{\text{D}j}, t_{\text{D}}\right) dx_{\text{D}j} \tag{C16}$$

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中文导读

线性复合气藏有限导流多段压裂水平井压力动态分析

摘要:断块气藏是一种在现实中非常常见的气藏,该类气藏被一些线性滤失断层分割成多个具有不同物性的储层区域,这类气藏也被称为线性复合气藏。虽然目前已有一些解析/半解析模型用于研究线性复合气藏中生产井的压力动态,但是大部分成果针对直井,而对多段压裂水平井研究得较少。当压力波传播到滤失断层后,多段压裂水平井的压力动态将会受到滤失断层的影响,因此,弄清楚滤失断层对多段压裂水平井压力动态的影响对开发断块气藏非常重要。基于 Laplace 空间的叠加原理和裂缝离散方法,本文建立了线性复合气藏有限导流多段压裂水平井的半解析模型。通过与商业数值模拟器进行结果对比,检验了该模型的可靠性。绘制了线性复合气藏中有限导流多段压裂水平井的压力动态典型曲线,研究了压力动态特征,开展了流动阶段划分,并分析了不同参数对压力动态典型曲线的影响。本文建立的模型有助于进一步发展线性复合气藏中其他复杂井型的解析/半解析模型。

关键词: 半解析模型; 线性复合气藏; 多段压裂水平井; 有限导流压裂裂缝; 压力动态