



Erratum to: Adaptive robust simultaneous stabilization of multiple n -degree-of-freedom robot systems

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Published online: 7 February 2022

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Erratum to:
Control Theory and Technology
<https://doi.org/10.1007/s11768-021-00076-6>

In the published article the following funders information is missing:

This work was supported by the National Natural Science Foundation of China (G61773015, G61877028, G61803230), the Key Research and Development Plan of Shandong Province (2019JZZY020712), the Natural Science Foundation of Shandong Province (ZR2019MF032), A Project of Shandong Province Higher Educational Science and Technology Program (J18KA330, J18KA348), and the Jinan Engineering Laboratory-Intelligent Control and Cloud Platform and Implementation Plan of “1251” Talent Training Project of Shandong Jiaotong University.

The original article can be found online at <https://doi.org/10.1007/s11768-021-00076-6>.

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