

ERRATUM

Erratum to: Robust motion control of a two-wheeled inverted pendulum with an input delay based on optimal integral sliding mode manifold

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The authors' names were incorrect in the initial, online publication. The names have been corrected in the online publication, and they are correct in this erratum too.

The online version of the original article can be found under doi:[10.1007/s11071-016-2811-4](https://doi.org/10.1007/s11071-016-2811-4).

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