# Optimal partition problems for the fractional Laplacian 

Antonella Ritorto ${ }^{1}$ (D)

Received: 15 March 2017 / Accepted: 2 August 2017 / Published online: 16 August 2017
© Fondazione Annali di Matematica Pura ed Applicata and Springer-Verlag GmbH Germany 2017


#### Abstract

In this work, we prove an existence result for an optimal partition problem of the form


$$
\min \left\{F_{s}\left(A_{1}, \ldots, A_{m}\right): A_{i} \in \mathcal{A}_{s}, A_{i} \cap A_{j}=\emptyset \text { for } i \neq j\right\}
$$

where $F_{S}$ is a cost functional with suitable assumptions of monotonicity and lower semicontinuity, $\mathcal{A}_{s}$ is the class of admissible domains and the condition $A_{i} \cap A_{j}=\emptyset$ is understood in the sense of Gagliardo $s$-capacity, where $0<s<1$. Examples of this type of problem are related to fractional eigenvalues. As the main outcome of this article, we prove some type of convergence of the $s$-minimizers to the minimizer of the problem with $s=1$, studied in [5].

Keywords Fractional partial equations • Fractional capacities • Optimal partition
Mathematics Subject Classification 35R11 • 49Q10

## 1 Introduction

Throughout this article, we consider $\Omega \subset \mathbb{R}^{n}$ to be a fixed Lipschitz domain, that is an open bounded subset of $\mathbb{R}^{n}$ with Lipschitz boundary. Fix $0<s<1$ and $m \in \mathbb{N}$. We consider optimal partition problems of the form

$$
\begin{equation*}
\min \left\{F_{s}\left(A_{1}, \ldots, A_{m}\right): A_{i} \in \mathcal{A}_{s}(\Omega), A_{i} \cap A_{j}=\emptyset \text { for } i \neq j\right\} \tag{1.1}
\end{equation*}
$$

where $F_{s}$ is a cost functional which satisfies some lower semicontinuity and monotonicity assumptions and $\mathcal{A}_{s}(\Omega)$ denotes the class of admissible domains.

[^0]Optimal partition problems were studied by several authors: Bucur, Buttazzo and Henrot [5], Bucur and Velichkov [6], Caffarelli and Lin [8], Conti, Terracini and Verzini [9,10], Helffer, Hoffmann-Ostenhof and Terracini [19], among others.

In [8], Caffarelli and Lin established the existence of classical solutions to an optimal partition problem for the Dirichlet eigenvalue, as well as the regularity of free interfaces. One more recent work about regularity of solutions to optimal partition problems involving eigenvalues of the Laplacian is [23], where Ramos, Tavares and Terracini used the existence result of [5] and proved that the free boundary of the optimal partition is locally a $C^{1, \alpha_{-}}$ hypersurface up to a residual set.

Conti, Terracini and Verzini proved in [9] the existence of the minimal partition for a problem in N -dimensional domains related to the method of nonlinear eigenvalues introduced by Nehari in [21]. Moreover, they showed some connections between the variational problem and the behavior of competing species systems with large interaction.

Tavares and Terracini proved in [26] the existence of infinitely many sign-changing solutions for the system of $m$-Schrödinger equations with competition interactions and the relation between the energies associated and an optimal partition problem which involves $m$-eigenvalues of the Laplacian operator.

In a recent work [16], we studied a general shape optimization problem where $m=1$.
To mention some references which have to do with optimal partition problems involving fractional operators, we suggest to look through [27], [29], and references therein too.

A class of optimal partition problems involving the half-Laplacian operator and a subcritical cost functional was considered by Zilio in [29]. That work encompasses findings about optimal regularity of the density-functions which characterize the partitions, for the entire set of minimizers. Besides, a numerical-related scheme and its consequences are shown.

In [27], Terracini-Verzini-Zilio consider a class of competition-diffusion nonlinear systems involving the half-Laplacian, including the fractional Gross-Pitaevskii system.

For more references related to optimal partition problems see, for instance, $[1,2,4,7,10$, 18,22,25]

The goal of this article is to prove the existence of an optimal partition for the problem (1.1), where $F_{s}$ is decreasing in each coordinate and lower semicontinuous for a suitable notion of convergence in $\mathcal{A}_{s}(\Omega)$, which is the set of admissible domains. This existence result is carried out in Sect. 3. The dependence on $s$ is related to the Gagliardo $s$-capacity measure and the fractional Laplacian operator $(-\Delta)^{s}$, and we will detail that and other preliminaries in Sect. 2.

We follow the ideas given by Bucur, Buttazzo and Henrot in [5], where the existence of solution to (1.1) in the case $s=1$ was proved.

Furthermore, we prove convergence of minimums and optimal partition shapes to those of the case $s=1$, studied in [5]. This last aim is accomplished in Sect. 4, and we consider it the most interesting contribution of this work.

At the end, we include "Appendix" with useful properties of $s$-capacity. Most of those results we suppose are well known. Despite that, we decided to incorporate them for completeness.

## 2 Preliminaries and statements

### 2.1 Notations and preliminaries

Given $s \in(0,1)$ we consider the fractional Laplacian, that for smooth functions $u$ is defined as

$$
\begin{aligned}
(-\Delta)^{s} u(x) & :=c(n, s) \text { p.v. } \int_{\mathbb{R}^{n}} \frac{u(x)-u(y)}{|x-y|^{n+2 s}} d y \\
& =-\frac{c(n, s)}{2} \int_{\mathbb{R}^{n}} \frac{u(x+z)-2 u(x)+u(x-z)}{|z|^{n+2 s}} d z .
\end{aligned}
$$

where $c(n, s):=\left(\int_{\mathbb{R}^{n}} \frac{1-\cos \zeta_{1}}{|\zeta|^{n+2 s}} d \zeta\right)^{-1}$ is a normalization constant.
The constant $c(n, s)$ is chosen in such a way that the following identity holds,

$$
(-\Delta)^{s} u=\mathcal{F}^{-1}\left(|\xi|^{2 s} \mathcal{F}(u)\right),
$$

for $u$ in the Schwarz class of rapidly decreasing and infinitely differentiable functions, where $\mathcal{F}$ denotes the Fourier transform. See [14, Proposition 3.3].

The natural functional setting for this operator is the fractional Sobolev space $H^{s}\left(\mathbb{R}^{n}\right)$ defined as

$$
\begin{aligned}
H^{s}\left(\mathbb{R}^{n}\right) & :=\left\{u \in L^{2}\left(\mathbb{R}^{n}\right): \frac{u(x)-u(y)}{|x-y|^{\frac{n}{2}+s}} \in L^{2}\left(\mathbb{R}^{n} \times \mathbb{R}^{n}\right)\right\} \\
& =\left\{u \in L^{2}\left(\mathbb{R}^{n}\right): \int_{\mathbb{R}^{n}}\left(1+|\xi|^{2 s}\right)|\mathcal{F}(u)(\xi)|^{2} d \xi<\infty\right\}
\end{aligned}
$$

which is a Banach space endowed with the norm $\|u\|_{s}^{2}:=\|u\|_{2}^{2}+[u]_{s}^{2}$, where the term

$$
[u]_{s}^{2}:=\iint_{\mathbb{R}^{n} \times \mathbb{R}^{n}} \frac{|u(x)-u(y)|^{2}}{|x-y|^{n+2 s}} d x d y
$$

is the so-called Gagliardo semi-norm of $u$.
To contemplate the boundary condition, we work in $H_{0}^{s}(\Omega)$, which is the closure of $C_{c}^{\infty}(\Omega)$ in the norm $\|\cdot\|_{s}$. As we are dealing with a Lipschitz domain $\Omega, H_{0}^{s}(\Omega)$ coincides with the space of functions vanishing outside $\Omega$, i.e.,

$$
H_{0}^{s}(\Omega)=\left\{u \in H^{s}\left(\mathbb{R}^{n}\right): u=0 \text { in } \mathbb{R}^{n} \backslash \Omega\right\}
$$

See [17, Corollary 1.4.4.5] for a proof of the identity above.
Definition 2.1 Given $A \subset \Omega$, for any $0<s<1$, we define the Gagliardo $s$-capacity of $A$ relative to $\Omega$ as

$$
\operatorname{cap}_{s}(A, \Omega)=\inf \left\{[u]_{s}^{2}: u \in C_{c}^{\infty}(\Omega), u \geq 1 \text { in a neighborhood of } A\right\} .
$$

We say that a subset $A$ of $\Omega$ is an s-quasi-open subset of $\Omega$ if there exists a decreasing sequence $\left\{G_{k}\right\}_{k \in \mathbb{N}}$ of open sets such that $\lim _{k \rightarrow \infty} \operatorname{cap}_{s}\left(G_{k}, \Omega\right)=0$ and $A \cup G_{k}$ is an open set.

We denote by $\mathcal{A}_{s}(\Omega)$ the class of all $s$-quasi-open subsets of $\Omega$.
In the case $s=1$ the definitions are completely analogous with $\|\nabla u\|_{2}^{2}$ instead of $[u]_{s}^{2}$.
We say that a property $P(x)$ holds $s$-quasi everywhere on $E \subset \Omega$ ( $s$-q.e. on $E$ ), if $\operatorname{cap}_{s}(\{x \in E: P(x)$ does not hold $\}, \Omega)=0$.

A function $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is said $s$-quasi-continuous if there exists a decreasing sequence $\left\{G_{k}\right\}_{k \in \mathbb{N}}$ of open sets such that $\lim _{k \rightarrow \infty} \operatorname{cap}_{s}\left(G_{k}, \Omega\right)=0$ and $\left.u\right|_{\mathbb{R}^{n} \backslash G_{k}}$ is continuous.

The following theorem allows us to work with $s$-quasi-continuous functions instead of the classical fractional Sobolev ones.

Theorem 2.2 (Theorem 3.7, [28]) For every function $u \in H_{0}^{s}(\Omega)$ there exist a unique $\tilde{u}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ s-quasi-continuous function such that $u=\tilde{u}$ a.e. in $\mathbb{R}^{n}$.

From this point, we identify a function $u \in H_{0}^{S}(\Omega)$ with its $s$-quasi-continuous representative.

For $A \in \mathcal{A}_{s}(\Omega)$, we consider the fractional Sobolev space

$$
H_{0}^{s}(A):=\left\{u \in H_{0}^{s}(\Omega): u=0 s \text {-q.e. in } \mathbb{R}^{n} \backslash A\right\} .
$$

To go into detail about $s$-capacity we refer the reader, for instance, to [24,28].

### 2.2 Statements

Given $A \in \mathcal{A}_{s}(\Omega)$, we denote by $u_{A}^{s} \in H_{0}^{s}(A)$ the unique weak solution to

$$
\begin{equation*}
(-\Delta)^{s} u_{A}^{s}=1 \quad \text { in } A, \quad u_{A}^{s}=0 \quad \text { in } \mathbb{R}^{n} \backslash A \tag{2.1}
\end{equation*}
$$

With this notation, we define the following notion of set convergence.
Definition 2.3 (Strong $\gamma_{s}$-convergence) Let $\left\{A_{k}\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)$ and $A \in \mathcal{A}_{s}(\Omega)$. We say that $A_{k} \xrightarrow{\gamma_{s}} A$ if $u_{A_{k}}^{s} \rightarrow u_{A}^{s}$ strongly in $L^{2}(\Omega)$.

Let $m \in \mathbb{N},\left\{\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)^{m}$ and $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{s}(\Omega)^{m}$. We say $\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \xrightarrow{\gamma_{s}}\left(A_{1}, \ldots, A_{m}\right)$ if $A_{i}^{k} \xrightarrow{\gamma_{s}} A_{i}$ for every $i=1, \ldots, m$.

Definition 2.4 (Weak $\gamma_{s}$-convergence) Let $\left\{A_{k}\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)$ and $A \in \mathcal{A}_{s}(\Omega)$. We say that $A_{k} \stackrel{\gamma_{s}}{\rightharpoonup} A$ if there exists a function $u \in L^{2}(\Omega)$ such that $u_{A_{k}}^{s} \rightarrow u$ strongly in $L^{2}(\Omega)$ and $A=\{u>0\} \in \mathcal{A}_{s}(\Omega)$.

Let $m \in \mathbb{N}$ and $\left\{\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)^{m}$ and $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{s}(\Omega)^{m}$. We say $\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \stackrel{\gamma_{s}}{\sim}\left(A_{1}, \ldots, A_{m}\right)$ if $A_{i}^{k} \stackrel{\gamma_{s}}{\longrightarrow} A_{i}$ for every $i=1, \ldots, m$.

Remark 2.5 We want to emphasize the difference between strong and weak $\gamma_{s}$-convergence. In the weak $\gamma_{s}$-convergence, the $L^{2}(\Omega)$-limit function $u$ of the sequence $\left\{u_{A_{k}}^{s}\right\}_{k \in \mathbb{N}}$ is not required to be a solution of (2.1) in $A$ (the weak $\gamma_{s}$-limit), i.e., it is not required that $u \neq u_{A}^{S}$. That is the main hassle we should get through to arrive at the compactness result on $\mathcal{A}_{s}(\Omega)$, in Sect. 3.1.

Let $m \in \mathbb{N}$ be fixed and $0<s \leq 1$. Let $F_{s}: \mathcal{A}_{s}(\Omega)^{m} \rightarrow[0, \infty]$ be such that

- $F_{s}$ is weak $\gamma_{s}$-lower semicontinuous, that is,

$$
F_{s}\left(A_{1}, \ldots, A_{m}\right) \leq \liminf _{k \rightarrow \infty} F_{s}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)
$$

for every $\left\{\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)\right\}_{k \in \mathbb{N}} \subset A_{s}(\Omega)^{m}$ and $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{s}(\Omega)^{m}$ such that $\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \xrightarrow{\gamma_{s}}\left(A_{1}, \ldots, A_{m}\right)$.

- $F_{s}$ is decreasing, that is, for every $\left(A_{1}, \ldots, A_{m}\right),\left(B_{1}, \ldots, B_{m}\right) \in \mathcal{A}_{s}(\Omega)^{m}$ such that $A_{i} \subset B_{i}$ for $i=1, \ldots, m$, we have

$$
F_{s}\left(A_{1}, \ldots, A_{m}\right) \geq F_{s}\left(B_{1}, \ldots, B_{m}\right)
$$

Under these assumptions, we are able to recover the existence result of [5], for the fractional case. Rigorously speaking, we have the following theorem.

Theorem 2.6 Let $F_{s}: \mathcal{A}_{s}(\Omega)^{m} \rightarrow[0, \infty]$ be a decreasing and weak $\gamma_{s}$-lower semicontinuous functional. Then, there exists a solution to

$$
\begin{equation*}
\min \left\{F_{s}\left(A_{1}, \ldots, A_{m}\right): A_{i} \in \mathcal{A}_{s}(\Omega), \operatorname{cap}_{s}\left(A_{i} \cap A_{j}, \Omega\right)=0 \text { for } i \neq j\right\} \tag{2.2}
\end{equation*}
$$

The proof of Theorem 2.6 is carried out in Sect. 3 and we use ideas from [5] and [16].
Now, we present the main point of this article, that is the convergence of minimums and optimal partition shapes to those of the case $s=1$.

Once we know the existence of an optimal partition shape for each $0<s<1$, we want to analyze the limit of these minimizers and its minimum values when $s \uparrow 1$. To this aim, we need a suitable relationship between the cost functionals $F_{s}, 0<s \leq 1$ and a notion of set convergence.

Let us start with the notion of set convergence. For $A \in \mathcal{A}_{1}(\Omega)$, we introduce the analogous notation $u_{A}^{1} \in H_{0}^{1}(A)$ for the unique weak solution to

$$
-\Delta u_{A}^{1}=1 \text { in } A, \quad u_{A}^{1}=0 \text { in } \mathbb{R}^{n} \backslash A .
$$

Definition 2.7 ( $\gamma$-convergence) Let $0<s_{k} \uparrow 1,\left\{A_{k}\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s_{k}}(\Omega)$ and $A \in \mathcal{A}_{1}(\Omega)$. We say that $A_{k} \xrightarrow{\gamma} A$ if $u_{A_{k}}^{s_{k}} \rightarrow u_{A}^{1}$ strongly in $L^{2}(\Omega)$.

Let $m \in \mathbb{N},\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \in \mathcal{A}_{s_{k}}(\Omega)^{m}$ and $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{1}(\Omega)^{m}$. We say that $\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \xrightarrow{\gamma}\left(A_{1}, \ldots, A_{m}\right)$ if $u_{A_{i}^{k}}^{s_{k}} \rightarrow u_{A_{i}}^{1}$ strongly in $L^{2}(\Omega)$, for every $i=1, \ldots, m$.

Let $m \in \mathbb{N}$ and $0<s \leq 1$. Let $F_{s}: \mathcal{A}_{s}(\Omega)^{m} \rightarrow[0, \infty]$ be decreasing and weak $\gamma_{s}$-lower semicontinuous functionals. Then, there exists $\left(A_{1}^{s}, \ldots, A_{m}^{s}\right)$ solution to

$$
\begin{equation*}
m_{s}:=\min \left\{F_{s}\left(B_{1}, \ldots, B_{m}\right): B_{i} \in \mathcal{A}_{s}(\Omega), \operatorname{cap}_{s}\left(B_{i} \cap B_{j}, \Omega\right)=0 \text { for } i \neq j\right\} . \tag{2.3}
\end{equation*}
$$

The case $s=1$ was solved in [5]. For $0<s<1$, apply Theorem 2.6.
Assume the following hypotheses over the cost functionals:
$\left(H_{1}\right)$ Continuity. For every $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{1}(\Omega)^{m}$,

$$
F_{1}\left(A_{1}, \ldots, A_{m}\right)=\lim _{s \uparrow 1} F_{s}\left(A_{1}, \ldots, A_{m}\right) .
$$

$\left(H_{2}\right)$ Liminf inequality. For every $0<s_{k} \uparrow 1$, $\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \in \mathcal{A}_{s_{k}}(\Omega)^{m}$ and $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{1}(\Omega)^{m}$ such that $\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \xrightarrow{\gamma}\left(A_{1}, \ldots, A_{m}\right)$,

$$
F_{1}\left(A_{1}, \ldots, A_{m}\right) \leq \liminf _{k \rightarrow \infty} F_{S_{k}}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)
$$

These conditions $\left(H_{1}\right)-\left(H_{2}\right)$ are natural and analogous to those consider in [16], where a similar shape optimization problem was studied with $m=1$.

Now, we are able to establish the main result.
Theorem 2.8 Letm $\in \mathbb{N}$ be fixed and $0<s \leq 1$. Let $F_{s}: \mathcal{A}_{s}(\Omega)^{m} \rightarrow[0, \infty]$ be a decreasing and weak $\gamma_{s}$-lower semicontinuous functional, and such that $\left(H_{1}\right)-\left(H_{2}\right)$ are verified. Then,

$$
\begin{equation*}
m_{1}=\lim _{s \uparrow 1} m_{s}, \tag{2.4}
\end{equation*}
$$

where $m_{s}$ is defined in (2.3).
Moreover, if $\left(A_{1}^{s}, \ldots, A_{m}^{s}\right)$ is a minimizer of (2.3), then, there exist a subsequence $0<$ $s_{k} \uparrow 1,\left(\tilde{A}_{1}^{s_{k}}, \ldots, \tilde{A}_{m}^{s_{k}}\right) \in \mathcal{A}_{s_{k}}(\Omega)^{m}$ and $\left(A_{1}^{1}, \ldots, A_{m}^{1}\right) \in \mathcal{A}_{1}(\Omega)^{m}$ such that $\tilde{A}_{i}^{s_{k}} \supset A_{i}^{s_{k}}$ and

$$
\left(\tilde{A}_{1}^{s_{k}}, \ldots, \tilde{A}_{m}^{s_{k}}\right) \xrightarrow{\gamma}\left(A_{1}^{1}, \ldots, A_{m}^{1}\right),
$$

where $\left(A_{1}^{1}, \ldots, A_{m}^{1}\right)$ is a minimizer of (2.3) with $s=1$.
The proof of Theorem 2.8 is carried out in Sect. 4, and we use again ideas from [16].

### 2.3 Examples

Given $A \in \mathcal{A}_{s}(\Omega)$, consider the problem

$$
\begin{equation*}
(-\Delta)^{s} u=\lambda^{s} u \quad \text { in } A, \quad u \in H_{0}^{s}(A) \tag{2.5}
\end{equation*}
$$

where $\lambda^{s} \in \mathbb{R}$ is the eigenvalue parameter. It is well known that there exists a discrete sequence $\left\{\lambda_{k}^{s}(A)\right\}_{k \in \mathbb{N}}$ of positive eigenvalues of (2.5) approaching $+\infty$ whose corresponding eigenfunctions $\left\{u_{k}^{s}\right\}_{k \in \mathbb{N}}$ form an orthogonal basis in $L^{2}(A)$. Moreover, the following variational characterization holds for the eigenvalues

$$
\begin{equation*}
\lambda_{k}^{s}(A)=\min _{u \perp W_{k-1}} \frac{c(n, s)}{2} \frac{[u]_{s}^{2}}{\|u\|_{2}^{2}}, \tag{2.6}
\end{equation*}
$$

where $W_{k}$ is the space spanned by the first $k$ eigenfunctions $u_{1}^{s}, \ldots, u_{k}^{s}$.
Due to (2.6) and the stability result proved in [3, Theorem 1.2], we know that $\lambda_{k}^{s}(A) \rightarrow$ $\lambda_{k}^{1}(A)$, when $s \uparrow 1$, for every $k \in \mathbb{N}$.

Consider functionals $F_{s}\left(A_{1}, \ldots, A_{m}\right)=\Phi_{s}\left(\lambda_{k_{1}}^{s}\left(A_{1}\right), \ldots, \lambda_{k_{m}}^{s}\left(A_{m}\right)\right)$. Theorem 2.6 claims that for every $\left(k_{1}, \ldots, k_{m}\right) \in \mathbb{N}^{m}$, the minimum

$$
\min \left\{\Phi_{s}\left(\lambda_{k_{1}}^{s}\left(A_{1}\right), \ldots, \lambda_{k_{m}}^{s}\left(A_{m}\right)\right): A_{i} \in \mathcal{A}_{s}(\Omega), \operatorname{cap}_{s}\left(A_{i} \cap A_{j}, \Omega\right) \text { for } i \neq j\right\}
$$

is achieved, where $\Phi_{s}: \mathbb{R}^{m} \rightarrow \overline{\mathbb{R}}$, is increasing in each coordinate and lower semicontinuous.
Moreover, if $\Phi_{s}\left(t_{1}, \ldots, t_{m}\right) \rightarrow \Phi_{1}\left(t_{1}, \ldots, t_{m}\right)$ for every $\left(t_{1}, \ldots, t_{m}\right) \in \mathbb{R}^{m}$ and

$$
\Phi_{1}\left(t_{1}, \ldots, t_{m}\right) \leq \liminf _{k \rightarrow \infty} \Phi_{s_{k}}\left(t_{1}^{k}, \ldots, t_{m}^{k}\right)
$$

for every $\left(t_{1}^{k}, \ldots, t_{m}^{k}\right) \rightarrow\left(t_{1}, \ldots, t_{m}\right)$, then Theorem 2.8 together with the existence result of [5] imply that

$$
\begin{aligned}
& \min \left\{\Phi_{1}\left(\lambda_{k_{1}}\left(A_{1}\right), \ldots, \lambda_{k_{m}}\left(A_{m}\right)\right): A_{i} \in \mathcal{A}_{1}(\Omega), \operatorname{cap}_{1}\left(A_{i} \cap A_{j}, \Omega\right)=0 \text { for } i \neq j\right\} \\
& =\lim _{s \uparrow 1} \min \left\{\Phi_{s}\left(\lambda_{k_{1}}^{s}\left(A_{1}\right), \ldots, \lambda_{k_{m}}^{s}\left(A_{m}\right)\right): A_{i} \in \mathcal{A}_{s}(\Omega), \operatorname{cap}_{s}\left(A_{i} \cap A_{j}, \Omega\right)=0 \text { for } i \neq j\right\} .
\end{aligned}
$$

## 3 Proof of Theorem 2.6

In this section, we adapted the ideas from [5], where the authors consider the Laplacian operator, to recover their results for the fractional case. Despite the similarity of the proofs, we include them for the reader's convenience and recalling that in the context of this article we need the nonlocal tools proved in [16].

### 3.1 Certain compactness on $\mathcal{A}_{s}(\boldsymbol{\Omega})$

Consider $\mathcal{K}_{s}$ given by

$$
\begin{equation*}
\mathcal{K}_{s}:=\left\{w \in H_{0}^{s}(\Omega): w \geq 0,(-\Delta)^{s} w \leq 1 \text { in } \Omega\right\} \tag{3.1}
\end{equation*}
$$

Proposition 3.1 (Proposition 3.3 and Lemma 3.5, [16]) $\mathcal{K}_{s}$ is convex, closed and bounded in $H_{0}^{s}(\Omega)$. Moreover, if $u, v \in \mathcal{K}_{s}$, then, $\max \{u, v\} \in \mathcal{K}_{s}$.

Proposition 3.2 (Lemma 3.2, [16]) Given $A \in \mathcal{A}_{s}(\Omega), u_{A}^{s}$ is the solution to

$$
\max \left\{w \in H_{0}^{s}(\Omega): w \leq 0 \text { in } \mathbb{R}^{n} \backslash A,(-\Delta)^{s} w \leq 1 \text { in } \Omega\right\}
$$

Moreover, $u_{A}^{s} \in \mathcal{K}_{s}$, for every $A \in \mathcal{A}_{s}(\Omega)$.
From now on, we understand the identity $A=\left\{u_{A}^{s}>0\right\}$ in the sense of the Gagliardo $s$-capacity, thanks to Proposition A. 5 .

Remark 3.3 The class $\mathcal{A}_{s}(\Omega)$ is sequentially pre-compact with respect to the weak $\gamma_{s^{-}}$ convergence. Indeed, given a sequence $\left\{A_{k}\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)$, we know that $\left\{u_{A_{k}}^{s}\right\}_{k \in \mathbb{N}} \subset \mathcal{K}_{s}$. By Proposition 3.1, there exists a subsequence $\left\{u_{A_{k_{j}}}^{s}\right\}_{j \in \mathbb{N}} \subset\left\{u_{A_{k}}^{s}\right\}_{k \in \mathbb{N}}$ and a function $u \in \mathcal{K}_{s}$ such that $u_{A_{k_{j}}}^{s} \rightarrow u$ strongly in $L^{2}(\Omega)$. Denote by $A:=\{u>0\}$. Then, $A_{k_{j}} \xrightarrow{\gamma_{s}} A$.

Next proposition allows us to pass from the weak $\gamma_{s}$-convergence to the strong one, if we are willing to enlarge the sequence involved.
Proposition 3.4 Let $\left\{A_{k}\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)$ and $A, B \in \mathcal{A}_{s}(\Omega)$ be such that $A_{k} \stackrel{\gamma_{s}}{\stackrel{ }{*}} A \subset B$.
Then, there exists a subsequence $\left\{A_{k_{j}}\right\}_{j \in \mathbb{N}} \subset\left\{A_{k}\right\}_{k \in \mathbb{N}}$ and a sequence $\left\{B_{k_{j}}\right\}_{j \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)$ such that $A_{k_{j}} \subset B_{k_{j}}$ and $B_{k_{j}} \xrightarrow{\gamma_{s}} B$.

Proof Since $A_{k} \xrightarrow{\gamma_{s}} A \subset B$, we know that $u_{A_{k}}^{s} \rightarrow u$ strongly in $L^{2}(\Omega)$, where $\{u>0\}=A$. As a consequence of Proposition 3.1, $u \in \mathcal{K}_{s}$. Moreover, by Proposition 3.2, $u \leq u_{A}^{s}$. Since $A \subset B, u_{A}^{S} \leq u_{B}^{S}$. Then, $u \leq u_{B}^{S}$.

Denote by $B^{\varepsilon}=\left\{u_{B}^{s}>\varepsilon\right\}$ and consider $\left\{u_{A_{k} \cup B^{\varepsilon}}^{s}\right\}_{k \in \mathbb{N}} \subset \mathcal{K}_{s}$. Again by Proposition 3.1, there exists a subsequence $\left\{A_{k_{j}}\right\}_{j \in \mathbb{N}} \subset\left\{A_{k}\right\}_{k \in \mathbb{N}}$ such that $u_{A_{k_{j}} \cup B^{\varepsilon}}^{s} \rightarrow u^{\varepsilon}$ strongly in $L^{2}(\Omega)$.

Due to the convergence $u_{A_{k_{j}}}^{s} \rightarrow u$ strongly in $L^{2}(\Omega)$ and $u \leq u_{B}^{s}$, we conclude from [16, Lemma 3.6], $u^{\varepsilon} \leq u_{B}^{s}$.

Inside the proof of [16, Lemma 3.7], it was shown that $\left(u_{B}^{s}-\varepsilon\right)^{+} \leq u_{B^{\varepsilon}}^{s}$. Since $B^{\varepsilon} \subset$ $A_{k_{j}} \cup B^{\varepsilon}$, it follows that $u_{B^{\varepsilon}}^{s} \leq u_{A_{k_{j}} \cup B^{\varepsilon}}^{s}$. So, taking the limit $j \rightarrow \infty$, we obtain

$$
\left(u_{B}^{s}-\varepsilon\right)^{+} \leq u_{B^{\varepsilon}}^{s} \leq u^{\varepsilon} \leq u_{B}^{s} .
$$

The sequence $\left\{u^{\varepsilon}\right\}_{\varepsilon>0}$ is contained in $\mathcal{K}_{s}$. So, by Proposition 3.1, up to a subsequence, we know it has a weak limit in $H_{0}^{S}(\Omega)$. But, the previous inequality tells that this weak limit should be $u_{B}^{s}$. In addition, $u^{\varepsilon} \rightarrow u_{B}^{s}$ strongly in $L^{2}(\Omega)$.

Thus, there exists a sequence $\varepsilon_{j} \downarrow 0$ such that $u_{A_{k_{j}} \cup B^{\varepsilon_{j}}}^{s} \rightarrow u_{B}^{s}$ strongly in $L^{2}(\Omega)$. That is, $A_{k_{j}} \cup B^{\varepsilon_{j}}=: B_{k_{j}} \xrightarrow{\gamma_{s}} B$, where $\left\{B_{k_{j}}\right\}_{j \in \mathbb{N}}$ is the enlarged sequence.

### 3.2 An auxiliary functional

Fix $m \in \mathbb{N}$ and $0<s<1$. Let $F_{s}: \mathcal{A}_{s}(\Omega)^{m} \rightarrow[0, \infty]$ be a decreasing and strong $\gamma_{s}$-lower semicontinuous functional.

We define a functional $G_{s}: \mathcal{K}_{s}^{m} \rightarrow[0, \infty]$

$$
\begin{equation*}
G_{s}\left(w_{1}, \ldots, w_{m}\right):=\inf \left\{\liminf _{k \rightarrow \infty} J_{s}\left(w_{1}^{k}, \ldots, w_{m}^{k}\right): w_{i}^{k} \rightarrow w_{i} \text { strongly in } L^{2}(\Omega)\right\} \tag{3.2}
\end{equation*}
$$

where $J_{s}: \mathcal{K}_{s}^{m} \rightarrow[0, \infty]$ is defined as

$$
J_{s}\left(w_{1}, \ldots, w_{m}\right):=\inf \left\{F_{s}\left(A_{1}, \ldots, A_{m}\right): A_{i} \in \mathcal{A}_{s}(\Omega), u_{A_{i}}^{s} \leq w_{i} \text { for } i=1, \ldots, m\right\}
$$

and $\mathcal{K}_{s}$ was given in (3.1).
We will show that $G_{s}$ satisfies the following properties:
$\left(G_{1}\right) G_{s}$ is decreasing on $\mathcal{K}_{s}^{m}$, that is $G_{s}\left(u_{1}, \ldots, u_{m}\right) \geq G_{s}\left(v_{1}, \ldots, v_{m}\right)$, if $u_{i} \leq v_{i}$ for every $i=1, \ldots, m$.
$\left(G_{2}\right) G_{s}$ is lower semicontinuous on $\mathcal{K}_{s}$ with respect to the strong topology on $L^{2}(\Omega)$, $\left(G_{3}\right) G_{s}\left(u_{A_{1}}^{s}, \ldots, u_{A_{m}}^{s}\right)=F_{s}\left(A_{1}, \ldots, A_{m}\right)$ for every $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{s}(\Omega)^{m}$.

The conditions $\left(G_{1}\right)$ and $\left(G_{2}\right)$ are easy to check, and it is the content of next proposition.

Proposition 3.5 With the notation above, $G_{s}$ satisfies $\left(G_{1}\right)$ and $\left(G_{2}\right)$.
Proof By construction, it is clear that $G_{s}$ verifies $\left(G_{2}\right)$.
To prove $\left(G_{1}\right)$, let $\left(u_{1}, \ldots, u_{m}\right),\left(v_{1}, \ldots, v_{m}\right) \in \mathcal{K}_{s}^{m}$ such that $u_{i} \leq v_{i}$ for every $i=$ $1, \ldots, m$.

Take $\left\{u_{i}^{k}\right\}_{k \in \mathbb{N}} \subset \mathcal{K}_{s}$ such that $u_{i}^{k} \rightarrow u_{i}$ strongly in $L^{2}(\Omega)$ for every $i=1, \ldots, m$ and

$$
G_{s}\left(u_{1}, \ldots, u_{m}\right)=\lim _{k \rightarrow \infty} J_{s}\left(u_{1}^{k}, \ldots, u_{m}^{k}\right) .
$$

Consider $v_{i}^{k}:=\max \left\{v_{i}, u_{i}^{k}\right\}$ for every $i=1, \ldots, m$ and $k \in \mathbb{N}$. By Proposition 3.1, we obtain that $v_{i}^{k} \in \mathcal{K}_{s}$. In addition, $v_{i}^{k} \rightarrow \max \left\{v_{i}, u_{i}\right\}=v_{i}$ strongly in $L^{2}(\Omega)$, for every $i=1, \ldots, m$. Thus, noticing that $J_{s}$ is decreasing, we have

$$
G_{s}\left(v_{1}, \ldots, v_{m}\right) \leq \liminf _{k \rightarrow \infty} J_{s}\left(v_{1}^{k}, \ldots, v_{m}^{k}\right) \leq \lim _{k \rightarrow \infty} J_{s}\left(u_{1}^{k}, \ldots, u_{m}^{k}\right)=G_{s}\left(u_{1}, \ldots, u_{m}\right) .
$$

Now, we prove the most important property of $G_{s}$, which is the connection with the cost functional $F_{s}$.

Proposition 3.6 The functional $G_{s}$ satisfies $\left(G_{3}\right)$.
Proof By definition of $G_{s}$ (3.2), it is clear that $G_{s}\left(u_{A_{1}}^{s}, \ldots, u_{A_{m}}^{s}\right) \leq F_{s}\left(A_{1}, \ldots, A_{m}\right)$, for every $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{s}(\Omega)^{m}$.

To obtain the other inequality, it is enough to prove that for every sequence $\left\{u_{i}^{k}\right\}_{k \in \mathbb{N}} \subset$ $\mathcal{K}_{s}(\Omega)$ such that $u_{i}^{k} \rightarrow u_{A_{i}}^{s}$ strongly in $L^{2}(\Omega)$ for $i=1, \ldots, m$, we have

$$
F_{s}\left(A_{1}, \ldots, A_{m}\right) \leq \liminf _{k \rightarrow \infty} J_{s}\left(u_{1}^{k}, \ldots, u_{m}^{k}\right)
$$

By definition of $J_{s}$, there exists $\left\{\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)^{m}$ such that

$$
\begin{equation*}
u_{A_{i}^{k}}^{s} \leq u_{i}^{k} \text { for } i=1, \ldots, m, \text { and } F_{s}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \leq J_{s}\left(u_{1}^{k}, \ldots, u_{m}^{k}\right)+\frac{1}{k} . \tag{3.3}
\end{equation*}
$$

By Remark 3.3, there exists $v_{i} \in \mathcal{K}_{s}$ such that $u_{A_{i}^{k}}^{s} \rightarrow v_{i}$ strongly in $L^{2}(\Omega)$, up to a subsequence. That is, $A_{i}^{k} \stackrel{\gamma_{s}}{\sim} B_{i}:=\left\{v_{i}>0\right\} \in \mathcal{A}_{s}(\Omega)$, for every $i=1, \ldots, m$.

Moreover, taking the limit in $u_{A_{i}^{k}}^{s} \leq u_{i}^{k}$, we obtain that $v_{i} \leq u_{A_{i}}^{s}$ for every $i=1, \ldots, m$. In addition, we have $B_{i} \subset A_{i}=\left\{u_{A_{i}}^{s}>0\right\}$. We are able to apply Proposition 3.4, to obtain the existence of subsequences $\left\{A_{i}^{k_{j}}\right\}_{j \in \mathbb{N}},\left\{B_{i}^{k_{j}}\right\}_{j \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)$ such that $A_{i}^{k_{j}} \subset B_{i}^{k_{j}}$ and $B_{i}^{k_{j}} \xrightarrow{\gamma_{s}} A_{i}$.

Now, by using the strong $\gamma_{s}$-lower semicontinuity and decreasing property of $F_{s}$ and (3.3), we conclude

$$
\begin{aligned}
F_{s}\left(A_{1}, \ldots, A_{m}\right) & \leq \liminf _{j \rightarrow \infty} F_{s}\left(B_{1}^{k_{j}}, \ldots, B_{m}^{k_{j}}\right) \\
& \leq \liminf _{j \rightarrow \infty} F_{s}\left(A_{1}^{k_{j}}, \ldots, A_{m}^{k_{j}}\right) \\
& \leq \liminf _{j \rightarrow \infty} J_{s}\left(u_{1}^{k_{j}}, \ldots, u_{m}^{k_{j}}\right),
\end{aligned}
$$

which implies the remaining inequality $F_{s}\left(A_{1}, \ldots, A_{m}\right) \leq G_{s}\left(u_{A_{1}}^{s}, \ldots, u_{A_{m}}^{s}\right)$.
The decreasing property of a functional $F_{s}$ makes equivalent its weak and strong $\gamma_{s}$-lower semicontinuity, which is the content of next theorem.
Theorem 3.7 Let $m \in \mathbb{N}$ and $0<s<1$. Let $F_{s}: \mathcal{A}_{s}(\Omega)^{m} \rightarrow[0, \infty]$ be a decreasing functional. Then, the following assertions are equivalent
$1 F_{s}$ is weakly $\gamma_{s}$-lower semicontinuous.
$2 F_{s}$ is strong $\gamma_{s}$-lower semicontinuous.
Proof Since every strongly $\gamma_{s}$-convergent sequence $\left\{A_{k}\right\}_{k \in \mathbb{N}}$ is, in addition, weakly $\gamma_{s^{-}}$ convergent, $(1) \Rightarrow(2)$ is clear. (See definitions and Proposition A.5). Let us see the converse.

Now, suppose $F_{s}$ is strongly $\gamma_{s}$-lower semicontinuous. To arrive at the weakly $\gamma_{s}$-lower semicontinuity of $F_{s}$ from the strong one, the strategy is to take into account the auxiliary functional $G_{s}$ defined in (3.2) and its properties.

Fix $\left\{\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)^{m}$ and $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{s}(\Omega)^{m}$ such that

$$
\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \stackrel{\gamma_{s}}{\xrightarrow{( }}\left(A_{1}, \ldots, A_{m}\right)
$$

That means $u_{A_{i}^{k}}^{s} \rightarrow u_{i}$ strongly in $L^{2}(\Omega)$ and $A_{i}=\left\{u_{i}>0\right\}$, for $i=1, \ldots, m$.
Since for every $i=1, \ldots, m,\left\{u_{A_{i}^{k}}^{s}\right\}_{k \in \mathbb{N}} \subset \mathcal{K}_{s}$, by Proposition 3.1, $u_{i} \in \mathcal{K}_{s}$. Moreover, by Proposition 3.2, $u_{i} \leq u_{A_{i}}^{s}$. Then, we can use ( $G_{3}$ ), the decreasing property of $G_{s}$, so that we obtain

$$
\begin{equation*}
G_{s}\left(u_{A_{1}}^{s}, \ldots, u_{A_{m}}^{s}\right) \leq G_{s}\left(u_{1}, \ldots, u_{m}\right) . \tag{3.4}
\end{equation*}
$$

On the other hand, by recalling $\left(G_{1}\right)$, the relationship between $F_{s}$ and $G_{s}$, we get the following identities

$$
\begin{equation*}
F_{s}\left(A_{1}, \ldots, A_{m}\right)=G_{s}\left(u_{A_{1}}^{s}, \ldots, u_{A_{m}}^{s}\right) \quad \text { and } \quad F_{s}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)=G_{s}\left(u_{A_{1}^{k}}^{s}, \ldots, u_{A_{m}^{k}}^{s}\right), \tag{3.5}
\end{equation*}
$$

for every $k \in \mathbb{N}$.
Now, due to $\left(G_{2}\right)$ (the $L^{2}(\Omega)$-lower semicontinuity of $\left.G_{s}\right)$ in addition to $u_{A_{i}^{k}}^{s} \rightarrow u_{i}$ strongly in $L^{2}(\Omega)$ for every $i=1, \ldots, m$, we connect (3.4) and (3.5) to conclude that

$$
\begin{aligned}
F_{s}\left(A_{1}, \ldots, A_{m}\right) & =G_{s}\left(u_{A_{1}}^{s}, \ldots, u_{A_{m}}^{s}\right) \leq G_{s}\left(u_{1}, \ldots, u_{m}\right) \\
& \leq \liminf _{k \rightarrow \infty} G_{s}\left(u_{A_{1}^{k}}^{s}, \ldots, u_{A_{m}^{k}}^{s}\right) \\
& =\liminf _{k \rightarrow \infty} F_{s}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) .
\end{aligned}
$$

Since $\left\{\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)\right\}_{k \in \mathbb{N}}$ is an arbitrary weak $\gamma_{s}$-convergent sequence, we get that $F_{s}$ is weak $\gamma_{s}$-lower semicontinuous, as we desired.

### 3.3 Existence of an optimal partition

With the help of the previous outcomes of this section, we are able to prove existence of a minimal partition shape for (2.2).

Proof of Theorem 2.6 Denote by

$$
\alpha:=\inf \left\{F_{s}\left(A_{1}, \ldots, A_{m}\right): A_{i} \in \mathcal{A}_{s}(\Omega), \operatorname{cap}_{s}\left(A_{i} \cap A_{j}, \Omega\right)=0 \text { for } i \neq j\right\} .
$$

Let $\left\{\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)\right\}_{k \in \mathbb{N}} \subset \mathcal{A}_{s}(\Omega)^{m}$ be such that

$$
\operatorname{cap}_{s}\left(A_{i}^{k} \cap A_{j}^{k}, \Omega\right)=0 \text { for } i \neq j, \text { and } \lim _{k \rightarrow \infty} F_{s}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)=\alpha .
$$

By Remark 3.3, there exist $A_{1} \in \mathcal{A}_{s}(\Omega)$ and a subsequence $\left\{A_{1}^{k_{j}}\right\}_{j \in \mathbb{N}} \subset\left\{A_{1}^{k}\right\}_{k \in \mathbb{N}}$ such that $A_{1}^{k_{j}} \stackrel{\gamma_{s}}{\longrightarrow} A_{1}$. Now, consider $\left\{A_{2}^{k_{j}}\right\}_{j \in \mathbb{N}}$ and apply again Remark 3.3. Thus, there exist $A_{2} \in \mathcal{A}_{s}(\Omega)$ and a subsequence $\left\{A_{2}^{k_{j_{l}}}\right\}_{l \in \mathbb{N}} \subset\left\{A_{2}^{k_{j}}\right\}_{j \in \mathbb{N}}$ such that $A_{i}^{k_{j_{l}}} \stackrel{\gamma_{s}}{-} A_{i}$ for $i=1,2$. Repeating this argument, we find a sequence $\left\{\left(A_{1}^{k}, \ldots, \mathcal{A}_{m}^{k}\right)\right\}_{k \in \mathbb{N}}$ and $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{s}(\Omega)$ such that $A_{i}^{k} \stackrel{\gamma_{s}}{\sim} A_{i}$ for every $i=1, \ldots, m$.

Since $F_{s}$ is weak $\gamma_{s}$-lower semicontinuous, we obtain

$$
\begin{equation*}
F_{S}\left(A_{1}, \ldots, A_{m}\right) \leq \liminf _{k \rightarrow \infty} F_{S}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)=\alpha \tag{3.6}
\end{equation*}
$$

To finish the proof, let us see $\operatorname{cap}_{s}\left(A_{i} \cap A_{j}, \Omega\right)=0$ for $i \neq j$ be satisfied.
Let $i, j \in\{1, \ldots, m\}$ be such that $i \neq j$. Notice that this product $u_{A_{i}^{k}}^{s} \cdot u_{A_{j}^{k}}^{s}$ is an $s$ continuous function too, by Lemma A.1, and $u_{A_{i}^{k}}^{s} \cdot u_{A_{j}^{k}}^{s}=0 s$-q.e. in $\mathbb{R}^{n} \backslash\left(A_{i}^{k} \cap A_{j}^{k}\right)$. Moreover, since $\operatorname{cap}_{s}\left(A_{i}^{k} \cap A_{j}^{k}, \Omega\right)=0$, we have $u_{A_{i}^{k}}^{s} \cdot u_{A_{j}^{k}}^{s}=0 s$-q.e. in $\mathbb{R}^{n}$.

By [28, Lemma 3.8], there exist subsequences $\left\{u_{A_{i}^{k}}^{s}\right\}_{k \in \mathbb{N}}$ and $\left\{u_{A_{j}^{k}}^{s}\right\}_{k \in \mathbb{N}}$, denoted with the same index, which converge $s$-q.e. to $u_{i}$ and $u_{j}$, respectively. Then, passing to the limit, we obtain $u_{i} \cdot u_{j}=0 s$-q.e. in $\mathbb{R}^{n}$. That is $\operatorname{cap}_{s}\left(\left\{u_{i} \cdot u_{j} \neq 0\right\}, \Omega\right)=0$. But, $\left\{u_{i} \cdot u_{j} \neq 0\right\}=A_{i} \cap A_{j}$.

We have shown that $\left(A_{1}, \ldots, A_{m}\right)$ is admissible for the minimization problem (2.2) and recalling (3.6) the result is proved.

Due to Theorems 3.7 and 2.6 , we can establish the next immediate corollary.
Corollary 3.8 Let $F_{s}: \mathcal{A}_{s}(\Omega)^{m} \rightarrow[0, \infty]$ be a decreasing and strong $\gamma_{s}$-lower semicontinuous functional. Then, there exists a solution to (2.2).

## 4 Proof of Theorem 2.8

This is the main part of the article, where we study the behavior of optimal partition shapes obtained in Sect. 3 and their minimum values. Again, we use some results from [16].

Lemma 4.1 (Lemma 4.1, [16]) Let $0<s_{k} \uparrow 1$ and let $u_{k} \in \mathcal{K}_{s_{k}}$. Then, there exists $u \in$ $H_{0}^{1}(\Omega)$ and a subsequence $\left\{u_{k_{j}}\right\}_{j \in \mathbb{N}} \subset\left\{u_{k}\right\}_{k \in \mathbb{N}}$ such that $u_{k_{j}} \rightarrow u$ strongly in $L^{2}(\Omega)$.

Moreover, if $u_{k} \in \mathcal{K}_{s_{k}}$ is such that $u_{k} \rightarrow u$ strongly in $L^{2}(\Omega)$, then $u \in \mathcal{K}_{1}$.
Next proposition gives an idea of the limit behavior of $u_{A}^{S}$ when the domains also are varying with $s$.

Proposition 4.2 (Proposition 4.5, [16]) Let $0<s_{k} \uparrow 1, A^{k} \in \mathcal{A}_{s_{k}}(\Omega)$ be such that $u_{A^{k}}^{s_{k}} \rightarrow u$ strongly in $L^{2}(\Omega)$. Then, there exist $\tilde{A}^{k} \in \mathcal{A}_{s_{k}}(\Omega)$ such that $A^{k} \subset \tilde{A}^{k}$ and $\tilde{A}^{k} \gamma$-converges to $A:=\{u>0\}$.

Now we are ready to prove the main result of this article.
Proof of Theorem 2.8 First, notice that $m_{1}$ is achieved by [5, Theorem 3.2].
Let $0<s_{k} \uparrow 1$. By Theorem 2.6, there exists $\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \in \mathcal{A}_{s_{k}}(\Omega)^{m}$ such that

$$
\begin{equation*}
\operatorname{cap}_{s_{k}}\left(A_{i}^{k} \cap A_{j}^{k}, \Omega\right)=0 \text { for } i \neq j \text { and } F_{s_{k}}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)=m_{k}, \tag{4.1}
\end{equation*}
$$

where $m_{k}=m_{s_{k}}$ defined in (2.2).
Let $\left(A_{1}, \ldots, A_{m}\right) \in \mathcal{A}_{1}(\Omega)^{m}$ be such that $\operatorname{cap}_{1}\left(A_{i} \cap A_{j}, \Omega\right)=0$ for $i \neq j$. Since $0<s_{k} \uparrow 1$, we can assume $0<\varepsilon_{0}<s_{k} \uparrow 1$, for some fixed $\varepsilon_{0}$.

Now, recalling Corollary A. 7 and Remark A.8, we know that $\left(A_{1}, \ldots, A_{m}\right)$ belongs to

$$
\left\{\left(B_{1}, \ldots, B_{m}\right): B_{i} \in \mathcal{A}_{s_{k}}(\Omega), \operatorname{cap}_{s_{k}}\left(B_{i} \cap B_{j}, \Omega\right)=0 \text { for } i \neq j\right\}
$$

for every $k \in \mathbb{N}$. This fact and condition $\left(H_{1}\right)$ imply that

$$
\limsup _{k \rightarrow \infty} F_{s_{k}}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right) \leq \lim _{k \rightarrow \infty} F_{s_{k}}\left(A_{1}, \ldots, A_{m}\right)=F_{1}\left(A_{1}, \ldots, A_{m}\right)
$$

It follows that

$$
\begin{equation*}
\limsup _{k \rightarrow \infty} m_{k} \leq m_{1} . \tag{4.2}
\end{equation*}
$$

To see the remaining inequality, let us denote $u_{i}^{k}:=u_{A_{i}^{k}}^{s_{k}} \in \mathcal{K}_{s_{k}}$. By Lemma 4.1, there is $u_{i} \in \mathcal{K}_{1}$ such that, up to a subsequence, $u_{i}^{k} \rightarrow u_{i}$ strongly in $L^{2}(\Omega)$ and a.e. in $\Omega$.

Denote by $A_{i}:=\left\{u_{i}>0\right\} \in \mathcal{A}_{1}(\Omega)$ for every $i=1, \ldots, m$. We claim that $\operatorname{cap}_{1}\left(A_{i} \cap\right.$ $\left.A_{j}, \Omega\right)=0$ for $i \neq j$.

Indeed, let $i \neq j$ be fixed. For each $k \in \mathbb{N}$, due to Lemma A. 2 and (4.1), we know that

$$
\left|\left\{u_{i}^{k} \cdot u_{j}^{k} \neq 0\right\}\right|=\left|A_{i}^{k} \cap A_{j}^{k}\right| \leq C\left(n, s_{k}\right) \operatorname{cap}_{s_{k}}\left(A_{i}^{k} \cap A_{j}^{k}, \Omega\right)=0 .
$$

Then, $u_{i}^{k} \cdot u_{j}^{k}=0$ a.e. in $\mathbb{R}^{n}$. Since $u_{l}^{k} \rightarrow u_{l}$ a.e. in $\Omega$ for $l=1,2$, we conclude $u_{i} \cdot u_{j}=0$ a.e in $\Omega$, it is still true in $\mathbb{R}^{n} \backslash \Omega$ considering that they belong to $H_{0}^{s}(\Omega)$. So, $u_{i} \cdot u_{j}=0$ a.e. in $\mathbb{R}^{n}$.

Reminding that we are working with 1 -quasi-continuous representative functions in $H_{0}^{1}(\Omega)$, the previous identity $u_{i} \cdot u_{j}=0$ a.e. in $\mathbb{R}^{n}$ and [20, Lemma 3.3.30] tells that $u_{i} \cdot u_{j}=0$ 1-q.e. in $\mathbb{R}^{n}$. That means $\operatorname{cap}_{1}\left(A_{i} \cap A_{j}, \Omega\right)=0$.

Consequently, $\left(A_{1}, \ldots, A_{m}\right)$ is admissible to the problem 2.2 with $s=1$ and we obtain $m_{1} \leq F_{1}\left(A_{1}, \ldots, A_{m}\right)$.

Moreover, by Proposition 4.2, there exists $\tilde{A}_{i}^{k} \in \mathcal{A}_{s_{k}}(\Omega)$ such that $A_{i}^{k} \subset \tilde{A}_{i}^{k}$ and $\left(\tilde{A}_{1}^{k}, \ldots, \tilde{A}_{m}^{k}\right) \gamma$-converges to $\left(A_{1}, \ldots, A_{m}\right)$.

Finally, from condition $\left(H_{2}\right)$ and the decreasing property of $F_{s_{k}}$, we conclude that

$$
\begin{aligned}
m_{1} & \leq F_{1}\left(A_{1}, \ldots, A_{m}\right) \leq \liminf _{k \rightarrow \infty} F_{s_{k}}\left(\tilde{A}_{1}^{k}, \ldots, \tilde{A}_{m}^{k}\right) \\
& \leq \liminf _{k \rightarrow \infty} F_{s_{k}}\left(A_{1}^{k}, \ldots, A_{m}^{k}\right)=\liminf _{k \rightarrow \infty} m_{k} .
\end{aligned}
$$

Therefore, from previous conclusion and (4.2) we have the identity (2.4), so that the results follow.

Acknowledgements This paper was partially supported by Grants UBACyT 20020130100283BA, CONICET PIP 11220150100032CO and ANPCyT PICT 2012-0153. The author wants to thank Prof. Julián Fernández Bonder for helpful conversations.
A. Ritorto is a doctoral fellow of CONICET.

## Appendix A. Some useful properties of $s$-capacity

The following lemmas address some basic properties of $s$-capacity and $s$-quasi-continuous functions. We suppose those results are well known, and we include them for completeness.

Lemma A. 1 Let $u, v: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be s-quasi-continuous functions. Then, the product $u \cdot v$ is also an s-quasi-continuous function.

Proof By definition, there exist decreasing sequences $\left\{A_{k}\right\}_{k \in \mathbb{N}}$ and $\left\{B_{k}\right\}_{k \in \mathbb{N}}$ of open sets such that $\lim _{k \rightarrow \infty} \operatorname{cap}_{s}\left(A_{k}, \Omega\right)=\lim _{k \rightarrow \infty} \operatorname{cap}_{s}\left(B_{k}, \Omega\right)=0$ and $\left.u\right|_{\mathbb{R}^{n} \backslash A_{k}},\left.v\right|_{\mathbb{R}^{n} \backslash B_{k}}$ are continuous.

Consider $C_{k}:=A_{k} \cup B_{k}$. Then, $\left\{C_{k}\right\}_{k \in \mathbb{N}}$ is a decreasing sequence of open sets such that $\lim _{k \rightarrow \infty} \operatorname{cap}_{s}\left(C_{k}, \Omega\right)=0$, since $\operatorname{cap}_{s}\left(C_{k}, \Omega\right) \leq \operatorname{cap}_{s}\left(A_{k}, \Omega\right)+\operatorname{cap}_{s}\left(B_{k}, \Omega\right)$ by [28, Proposition 3.6]. Moreover, $\left.(u \cdot v)\right|_{\mathbb{R}^{n} \backslash C_{k}}$ is continuous.

Next lemma gives a relation between the Lebesgue measure and the $s$-capacity of a subset $A \subset \Omega$. The proof is easy and follows [15, Section 4.7, Theorem 2 VI], where it was shown with the classical capacity measure ( $s=1$ ).

Lemma A. 2 For every $A \subset \Omega,|A| \leq C(\Omega, s)$ cap $_{s}(A, \Omega)$, where $C(\Omega, s)$ is the Poincaré's constant in $H_{0}^{s}(\Omega)$.

Proof For every $\varepsilon>0$, there exists a function $u_{\varepsilon} \in H_{0}^{S}(\Omega)$ such that $u_{\varepsilon} \geq 1$ a.e. in a neighborhood of $A$ and

$$
\left[u_{\varepsilon}\right]_{s}^{2} \leq \operatorname{cap}_{s}(A, \Omega)+\varepsilon
$$

On the other hand, by Poincaré's inequality,

$$
|A|=\int_{A} 1 d x \leq \int_{\mathbb{R}^{n}} u_{\varepsilon}^{2} d x \leq C(\Omega, s)\left[u_{\varepsilon}\right]_{s}^{2} \leq C(\Omega, s)\left(\operatorname{cap}_{s}(A, \Omega)+\varepsilon\right)
$$

Take the limit $\varepsilon \downarrow 0$ to obtain the result.
For every $A \in \mathcal{A}_{s}(\Omega)$, we will show that $A=\left\{u_{A}^{s}>0\right\}$ in the sense of cap $_{s}(\cdot, \Omega)$. To prove this aim, we need some previous results which are modifications from [11, Lemma 2.1] and [12, Proposition 5.5].

Lemma A. 3 Let $A \in \mathcal{A}_{s}(\Omega)$, Then, there exists an increasing sequence $\left\{v_{k}\right\}_{k \in \mathbb{N}} \subset H_{0}^{s}(\Omega)$ of nonnegative functions, such that $\sup _{k \in \mathbb{N}} v_{k}=1_{A} s$-q.e. on $\Omega$.

We omit the proof since it is completely analogous to that of [11, Lemma 2.1].
We prove a density result in $H_{0}^{S}(A)$, for $A \in \mathcal{A}_{s}(\Omega)$, which is similar to [12, Proposition 5.5].

Lemma A. 4 Let $A \in \mathcal{A}_{s}(\Omega)$. Then, $\left\{\varphi u_{A}^{s}: \varphi \in C_{c}^{\infty}(\Omega)\right\}$ is dense in $H_{0}^{s}(A)$.

Proof In order to prove the lemma, it is sufficient to see that we can approximate any nonnegative function $w \in H_{0}^{s}(A)$ with $(-\Delta)^{s} w \in L^{\infty}(\Omega)$, since $L^{\infty}(\Omega)$ is dense in $H^{-s}(\Omega)$ and $w=w^{+}-w^{-}$. Indeed, for an arbitrary function $w \in H_{0}^{s}(\Omega)$, we know that $(-\Delta)^{s} w=: f \in H^{-s}(\Omega)$.

Denote by $f:=(-\Delta)^{s} w$. Then,

$$
(-\Delta)^{s} w \leq\|f\|_{L^{\infty}(\Omega)}=\|f\|_{L^{\infty}(\Omega)}(-\Delta)^{s} u_{A}^{s} \quad \text { in } A .
$$

By comparison, we obtain $0 \leq w \leq c u_{A}^{s}$, where $c:=\|f\|_{L^{\infty}(\Omega)}$.
For every $\varepsilon>0$, consider $(w-c \varepsilon)^{+} \in H_{0}^{s}(\Omega)$. Thus,

$$
\begin{equation*}
\left\{(w-c \varepsilon)^{+}>0\right\} \subset\left\{u_{A}^{s}>\varepsilon\right\} . \tag{A.1}
\end{equation*}
$$

Notice that $u_{A}^{s} \in L^{\infty}(\Omega)$ by [13, Theorem 4.1]. Observe that, using (A.1), $\varepsilon<u_{A}^{s} \leq$ $\left\|u_{A}^{s}\right\|_{L^{\infty}(\Omega)}$ in $\left\{(w-c \varepsilon)^{+}>0\right\}$. Then, the function $\frac{(w-c \varepsilon)^{+}}{u_{A}^{s}}$ belongs to $H_{0}^{s}(\Omega)$. So, there exists a sequence $\left\{\varphi_{k}^{\varepsilon}\right\}_{k \in \mathbb{N}} \subset C_{c}^{\infty}(\Omega)$ such that $\varphi_{k}^{\varepsilon} \rightarrow \frac{(w-c \varepsilon)^{+}}{u_{A}^{s}}$ strongly in $H_{0}^{s}(\Omega)$, when $k \rightarrow \infty$. Therefore, $\varphi_{k}^{\varepsilon} u_{A}^{s} \rightarrow(w-c \varepsilon)^{+}$strongly in $H_{0}^{s}(\Omega)$, when $k \rightarrow \infty$.

On the other hand, $(w-c \varepsilon)^{+} \rightarrow w$ strongly in $H_{0}^{s}(\Omega)$, when $\varepsilon \downarrow 0$.
Consequently, by a diagonal argument, there exist subsequences $\varepsilon_{j} \downarrow 0$ and $\left\{\varphi_{k_{j}}^{\varepsilon_{j}}\right\}_{j \in \mathbb{N}} \subset$ $C_{c}^{\infty}(\Omega)$ such that $\varphi_{k_{j}}^{\varepsilon_{j}} u_{A}^{s} \rightarrow w$ strongly in $H_{0}^{s}(\Omega)$.

The following proposition is an essential component to relate domains and functions. It also contributes to the proofs of principal results Theorems 2.6 and 2.8.

Proposition A. 5 Let $A \in \mathcal{A}_{s}(\Omega)$. Then, $A=\left\{u_{A}^{s}>0\right\}$ in sense of cap $(\cdot, \Omega)$. That is, $\operatorname{cap}_{s}\left(A \triangle\left\{u_{A}^{s}>0\right\}, \Omega\right)=0$.

Proof It is clear that $u_{A}^{s}=0 s$-q.e. on $\mathbb{R}^{n} \backslash A$. So, $\left\{u_{A}^{s}>0\right\} \subset A$.
To see $A \subset\left\{u_{A}^{s}>0\right\}$, we use the previous lemmas.
By Lemma A.3, there exists an increasing sequence $\left\{v_{k}\right\}_{k \in \mathbb{N}} \subset H_{0}^{s}(\Omega)$ of nonnegative functions, such that $\sup _{k \in \mathbb{N}} v_{k}=1_{A} s$-q.e. on $\Omega$.

For every $v_{k}$, by Lemma A.4, there exists a sequence $\left\{\varphi_{j}^{k}\right\}_{j \in \mathbb{N}} \in C_{c}^{\infty}(\Omega)$ such that $\varphi_{j}^{k} u_{A}^{s} \rightarrow$ $v_{k}$ strongly in $H_{0}^{s}(\Omega)$ and $s$-q.e., when $j \rightarrow \infty$. Since $\varphi_{j}^{k} u_{A}^{s}=0 s$-q.e. in $\left\{u_{A}^{s}=0\right\}$, then $v_{k}=0 s$-q.e. in $\left\{u_{A}^{s}=0\right\}$. Therefore, $1_{A}=0 s$-q.e. in $\left\{u_{A}^{s}=0\right\}$, which implies $A \subset\left\{u_{A}^{s}>0\right\}$.

Now, we prove a key estimate used in Sect. 4, which is a simply remark following the proof of [14, Proposition 2.2]. Notice that we are interested in finding a positive constant connecting in some sense $\operatorname{cap}_{s}(\cdot, \Omega)$ and $\operatorname{cap}_{1}(\cdot, \Omega)$. But, we also want that this constant does not depend on $s$. As our goal in Sect. 4 is related to the limit case $s \uparrow 1$, we can assume $0<\varepsilon_{0}<s<1$ for some $\varepsilon_{0}$ and that will be enough to obtain this desired and independent constant.

As we said before, the proof of next lemma follows [14, Proposition 2.2] and, despite the similarity, it is included since we want to analyze how the constant depends on $s$.

Lemma A. 6 Let $\varepsilon_{0}>0$ and $\varepsilon_{0}<s<1$. Then, there exits a constant $C>0$ such that for every $u \in H_{0}^{1}(\Omega)$

$$
(1-s)[u]_{s}^{2} \leq C\|\nabla u\|_{L^{2}(\Omega)}^{2} .
$$

and $C=C\left(\Omega, n, \varepsilon_{0}\right)$ does not depend on $s$.

Proof Let $u \in C_{c}^{\infty}(\Omega)$, we split $[u]_{s}^{2}$ into two pieces.
For the first part, use the change of variable $z=y-x$ and observe that for $z \in B_{1}(0) \backslash\{0\}$ and $\varphi(t):=u(x+t z)$ for $t \in[0,1]$ we estimate

$$
\frac{|u(x+z)-u(x)|}{|z|}=\frac{\left|\int_{0}^{1} \varphi^{\prime}(t) d t\right|}{|z|}=\frac{\left|\int_{0}^{1} \nabla u(x+t z) \cdot z d t\right|}{|z|} \leq \int_{0}^{1}|\nabla u(x+t z)| d t .
$$

Now, use the previous remark and Jensen's inequality to obtain

$$
\begin{aligned}
\int_{\mathbb{R}^{n}} \int_{\mathbb{R}^{n} \cap\{|y-x|<1\}} \frac{|u(x)-u(y)|^{2}}{|x-y|^{n+2 s}} d x d y & =\int_{\mathbb{R}^{n}} \int_{B_{1}(0)} \frac{|u(x)-u(z+x)|^{2}}{|z|^{n+2 s}} d z d x \\
& =\int_{\mathbb{R}^{n}} \int_{B_{1}(0)} \frac{|u(x)-u(z+x)|^{2}}{|z|^{2}|z|^{n+2(s-1)}} d z d x \\
& \leq \int_{\mathbb{R}^{n}} \int_{B_{1}(0)}\left(\int_{0}^{1} \frac{|\nabla u(x+t z)|}{|z|^{\frac{n}{2}+s-1}} d t\right)^{2} d z d x \\
& \leq \int_{B_{1}(0)} \frac{1}{|z|^{n+2(s-1)}} \int_{0}^{1}\|\nabla u\|_{L^{2}(\Omega)}^{2} d t d z \\
& \leq\|\nabla u\|_{L^{2}(\Omega)}^{2} \int_{B_{1}(0)} \frac{1}{|z|^{n+2(s-1)}} d z \\
& =\frac{\left|B_{1}(0)\right|}{2(1-s)}\|\nabla u\|_{L^{2}(\Omega)} .
\end{aligned}
$$

For the remaining part, use $|a-b|^{2} \leq 2\left(a^{2}+b^{2}\right)$ and easily follows

$$
\begin{aligned}
\int_{\mathbb{R}^{n}} \int_{\mathbb{R}^{n} \cap\{|y-x| \geq 1\}} \frac{|u(x)-u(y)|^{2}}{|x-y|^{n+2 s}} d x d y & \leq 2 \int_{\mathbb{R}^{n}} \int_{\mathbb{R}^{n} \cap\{|y-x| \geq 1\}} \frac{|u(x)|^{2}+|u(y)|^{2}}{|x-y|^{n+2 s}} d x d y \\
& \leq 4 \int_{\mathbb{R}^{n}} \int_{\mathbb{R}^{n} \cap\{|y-x| \geq 1\}} \frac{|u(x)|^{2}}{|x-y|^{n+2 s}} d x d y \\
& \leq \int_{\mathbb{R}^{n}}|u(x)|^{2}\left(\int_{\{|z| \geq 1\}} \frac{1}{|z|^{n+2 s}} d z\right) d x \\
& =\frac{\left|B_{1}(0)\right|}{2 s}\|u\|_{L^{2}(\Omega)} \\
& \leq \frac{\left|B_{1}(0)\right|}{2 \varepsilon_{0}} C_{1}(\Omega, n)\|\nabla u\|_{L^{2}(\Omega)},
\end{aligned}
$$

where $C_{1}(\Omega, n)$ is the constant of classical Poincare's inequality in $H_{0}^{1}(\Omega)$.
Then, put together the two estimates to conclude

$$
\begin{aligned}
(1-s)[u]_{s}^{2} & \leq(1-s)\left(\frac{C_{1}(\Omega, n)}{2 \varepsilon_{0}}+\frac{1}{2(1-s)}\right)\left|B_{1}(0)\right|\|\nabla u\|_{L^{2}(\Omega)} \\
& \leq\left(\frac{C_{1}(\Omega, n)}{2 \varepsilon_{0}}+\frac{1}{2}\right)\left|B_{1}(0)\right|\|\nabla u\|_{L^{2}(\Omega)} \\
& =C\left(\Omega, n, \varepsilon_{0}\right)\|\nabla u\|_{L^{2}(\Omega)} .
\end{aligned}
$$

Automatically, we obtain an estimate relating the $s$-capacity and the 1-capacity.

Corollary A. 7 Let $\varepsilon_{0}>0$ and $\varepsilon_{0}<s<1$. Then, there exits a constant $C>0$ such that for every $A \subset \Omega$

$$
(1-s) \operatorname{cap}_{s}(A, \Omega) \leq \operatorname{Ccap}_{1}(A, \Omega),
$$

and $C=C\left(\Omega, n, \varepsilon_{0}\right)$ does not depend on $s$.
We deduce other useful remark from Lemma A.6: Every 1-quasi open set is also an $s$-quasi-open, for $0<s<1$.

Remark A. 8 For every $0<s<1, \mathcal{A}_{1}(\Omega) \subset \mathcal{A}_{s}(\Omega)$. Moreover, if $0<s<t \leq 1$, then $\mathcal{A}_{t}(\Omega) \subset \mathcal{A}_{s}(\Omega)$.

Proof Let $A \in \mathcal{A}_{1}(\Omega)$. There exists a decreasing sequence of open sets $\left\{G_{k}\right\}_{k \in \mathbb{N}}$ such that $A \cup G_{k}$ is open and $\operatorname{cap}_{1}\left(G_{k}, \Omega\right) \rightarrow 0$.

Let $0<s<1$. By Corollary A.7, $\operatorname{cap}_{s}\left(G_{k}, \Omega\right) \rightarrow 0$. Then, $A \in \mathcal{A}_{s}(\Omega)$.
To prove $\mathcal{A}_{t}(\Omega) \subset \mathcal{A}_{s}(\Omega)$ for $0<s<t \leq 1$, use definitions of capacity and [14, Proposition 2.1].

## References

1. Bonnaillie-Noël, V., Léna, C.: Spectral minimal partitions of a sector. Discret. Contin. Dyn. Syst. Ser. B 19(1), 27-53 (2014)
2. Bozorgnia, F.: Optimal partitions for first eigenvalues of the Laplace operator. Numer. Methods Partial Differ. Equ. 31(3), 923-949 (2015)
3. Brasco, L., Parini, E., Squassina, M.: Stability of variational eigenvalues for the fractional p-Laplacian. Discret. Contin. Dyn. Syst. 36(4), 1813-1845 (2016)
4. Bucur, D., Buttazzo, G.: Variational Methods in Shape Optimization Problems, Progress in Nonlinear Differential Equations and Their Applications 65. Birkhäuser Boston Inc, Boston, MA (2005)
5. Bucur, D., Buttazzo, G., Henrot, A.: Existence results for some optimal partition problems. Adv. Math. Sci. Appl. 8(2), 571-579 (1998)
6. Bucur, D., Velichkov, B.: Multiphase shape optimization problems. SIAM J. Control Optim. 52(6), 35563591 (2014)
7. Buttazzo, G.: Spectral optimization problems. Rev. Mat. Complut. 24(2), 277-322 (2011)
8. Cafferelli, L.A., Lin, F.H.: An optimal partition problem for eigenvalues. J. Sci. Comput. 31(1-2), 5-18 (2007)
9. Conti, M., Terracini, S., Verzini, G.: An optimal partition problem related to nonlinear eigenvalues. J. Funct. Anal. 198(1), 160-196 (2003)
10. Conti, M., Terracini, S., Verzini, G.: On a class of optimal partition problems related to the Fučík spectrum and to the monotonicity formulae. Calc. Var. Partial Differ. Equ. 22(1), 45-72 (2005)
11. Dal Maso, G., Garroni, A.: New results on the asymptotic behavior of Dirichlet problems in perforated domains. Math. Models Methods Appl. Sci. 4(3), 373-407 (1994)
12. Dal Maso, G., Murat, F.: Asymptotic behaviour and correctors for Dirichlet problems in perforated domains with homogeneous monotone operators. Ann. Scuola Norm. Sup. Pisa Cl. Sci. (4) 24(2), 239290 (1997)
13. Di Blasio, G., Volzone, B.: Comparison and regularity results for the fractional Laplacian via symmetrization methods. J. Differ. Equ. 253(9), 2593-2615 (2012)
14. Di Nezza, E., Palatucci, G., Valdinoci, E.: Hitchhiker's guide to the fractional Sobolev spaces. Bull. Sci. Math. 136(5), 521-573 (2012)
15. Evans, L.C., Gariepy, R.F.: Measure Theory and Fine Properties of Functions. Textbooks in Mathematics, revised edn. CRC Press, Boca Raton, FL (2015)
16. Fernandez Bonder, J., Ritorto, A., Salort, A.M.: Shape optimization problems for nonlocal operators, ArXiv e-prints (2016)
17. Grisvard, P.: Elliptic problems in nonsmooth domains, Classics in Applied Mathematics, vol. 69, Society for Industrial and Applied Mathematics (SIAM), Philadelphia, PA: Reprint of the 1985 original [MR0775683]. With a foreword by Susanne C., Brenner (2011)
18. Helffer, B., Hoffmann-Ostenhof, T.: On a magnetic characterization of spectral minimal partitions. J. Eur. Math. Soc. (JEMS) 15(6), 2081-2092 (2013)
19. Helffer, B., Hoffmann-Ostenhof, T., Terracini, S.: On spectral minimal partitions: the case of the sphere. In: Around the research of Vladimir Maz'ya. III, Int. Math. Ser. (N. Y.), vol. 13, pp. 153-178. Springer, New York(2010)
20. Henrot, A., Pierre, M.: Variation et optimisation de formes. Mathématiques \& Applications (Berlin) [Mathematics \& Applications], vol. 48. Springer, Berlin. Une analyse géométrique. [A geometric analysis] (2005)
21. Nehari, Z.: Characteristic values associated with a class of non-linear second-order differential equations. Acta Math. 105, 141-175 (1961)
22. Osting, B., White, C.D., Oudet, É.: Minimal Dirichlet energy partitions for graphs. SIAM J. Sci. Comput. 36(4), A1635-A1651 (2014)
23. Ramos, M., Tavares, H., Terracini, S.: Extremality conditions and regularity of solutions to optimal partition problems involving Laplacian eigenvalues. Arch. Ration. Mech. Anal. 220(1), 363-443 (2016)
24. Shi, S., Xiao, J.: On fractional capacities relative to bounded open Lipschitz sets. Potential Anal. 45(2), 261-298 (2016)
25. Snelson, S.: Regularity and long-time behavior of nonlocal heat flows. Calc. Var. Partial Differ. Equ. 54(2), 1705-1723 (2015)
26. Tavares, H., Terracini, S.: Sign-changing solutions of competition-diffusion elliptic systems and optimal partition problems. Ann. Inst. H. Poincaré Anal. Non Linéaire 29(2), 279-300 (2012)
27. Terracini, S., Verzini, G., Zilio, A.: Uniform Hölder bounds for strongly competing systems involving the square root of the laplacian. J. Eur. Math. Soc. (JEMS) 18(12), 2865-2924 (2016)
28. Warma, M.: The fractional relative capacity and the fractional Laplacian with Neumann and Robin boundary conditions on open sets. Potential Anal. 42(2), 499-547 (2015)
29. Zilio, A.: Optimal regularity results related to a partition problem involving the half-Laplacian. In: Pratelli, A., Leugering, G. (eds.) New Trends in Shape Optimization. International Series of Numerical Mathematics, vol.166, pp. 301-314. Birkhäuser/Springer, Cham (2015)

[^0]:    Antonella Ritorto aritorto@dm.uba.ar

    1 Departamento de Matemática, FCEN - Universidad de Buenos Aires and IMAS - CONICET, Buenos Aires, Argentina

