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Retinal oxygen distribution and the role of neuroglobin

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Abstract The retina is the tissue layer at the back of the eye that is responsible for light detection. Whilst equipped with a rich supply of oxygen, it has one of the highest oxygen demands of any tissue in the body and, as such, supply and demand are finely balanced. It has been suggested that the protein neuroglobin (Ngb), which is found in high concentrations within the retina, may help to maintain an adequate supply of oxygen via the processes of transport and storage. We construct mathematical models, formulated as systems of reaction–diffusion equations in one-dimension, to test this hypothesis. Numerical simulations show that Ngb may play an important role in oxygen transport, but not in storage. Our models predict that the retina is most susceptible to hypoxia in the regions of the photoreceptor inner segment and inner plexiform layers, where Ngb has the potential to prevent hypoxia and increase oxygen uptake by 30–40 %. Analysis of a simplified model confirms the utility of

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Ngb in transport and shows that its oxygen affinity (P_{50} value) is near optimal for this process. Lastly, asymptotic analysis enables us to identify conditions under which the piecewise linear and quadratic approximations to the retinal oxygen profile, used in the literature, are valid.

Keywords Asymptotics · Facilitated diffusion · Hypoxia · Oxygen transport · Reaction–diffusion equations

Mathematics Subject Classification 92B05 · 92C30 · 35K57

1 Introduction

The retina is the ocular tissue which detects visual information. Despite being well vascularised, it has a high oxygen demand (Anderson and Saltzman 1964; Anderson 1968; Yu and Cringle 2001; Wangsa-Wirawan and Linsenmeier 2003) placing it in danger of hypoxia (oxygen deprivation). In this paper we construct reaction–diffusion models for retinal oxygen distribution and use them to examine the role of the protein neuroglobin (Ngb) in the prevention of hypoxia.

The retina extends from the optic disc to the ora serrata and has a multilayered structure, consisting of numerous cell-types (see Fig. 1a). The retina consists of the following layers, beginning with the outermost layer: the retinal pigment epithelium (RPE), the photoreceptor layer, consisting of the outer and inner segments (OSs and ISs), the outer nuclear layer (ONL), the outer plexiform layer (OPL), the inner nuclear layer (INL), the inner plexiform layer (IPL), the ganglion cell layer (GCL), the nerve

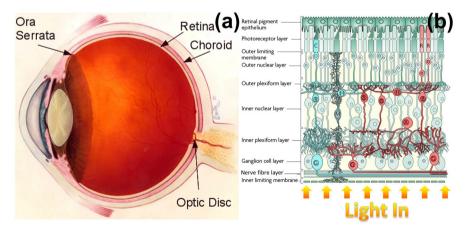


Fig. 1 Diagrams of the human eye and retina. **a** Diagram of the (*right*) human eye, viewed in the transverse plane. Figure reproduced, with modifications, from http://www.nei.nih.gov/health/coloboma/coloboma. asp, courtesy: National Eye Institute, National Institutes of Health (NEI/NIH). **b** Diagram of the human retina, showing the retinal layers and cell types. The diagram is oriented such that the top lies outermost and the bottom innermost in the eye. *R* rod photoreceptor, *C* cone photoreceptor, *H* horizontal cell, *B* bipolar cell, *M* Müller glial cell, *A* amacrine cell, *G* ganglion cell. Figure reproduced, with permission and modifications, from Swaroop et al. (2010)

fibre layer (NFL) and the inner limiting membrane (ILM) (see Fig. 1b). The outer retina extends from the RPE to the middle of the OPL, where the photoreceptors synapse with bipolar and horizontal cells, whilst the inner retina spans the region between the inner OPL and the ILM. Photoreceptors are responsible for the detection of light and can be characterised as either rods or cones. Following light detection the visual signal is transmitted via the neurons of the inner retina to the optic nerve and then to the brain.

Oxygen is supplied to the retina via two separate vascular systems: the choriocapillaris and the retinal capillaries. The choriocapillaris is a capillary layer which lies directly outward from the RPE and which supplies the outer retina with oxygen. It forms the innermost layer of the choroid and is supplied and drained by blood vessels lying deeper in this tissue. The retinal circulation supplies the inner retina with oxygen and is supplied and drained by the central retinal artery and vein. Throughout most of the mid-peripheral retina, the retinal circulation consists of two capillary layers, one deep and the other superficial (Oyster 1999; Pournaras et al. 2008; Kur et al. 2012). Therefore, in this paper, we shall consider only the two retinal capillary layer scenario.

Whilst the oxygen distribution across the human retina has not been measured, it has been measured for a variety of mammals including rats (Yu et al. 1994, 1999, 2000, 2004), rabbits (Stefánsson 1988), cats (Alder et al. 1983; Linsenmeier 1986; Linsenmeier and Yancey 1989; Haugh et al. 1990; Linsenmeier and Braun 1992; Braun et al. 1995; Linsenmeier and Padnick-Silver 2000; Padnick-Silver and Linsenmeier 2003) and monkeys (Yu et al. 2005; Birol et al. 2007, see also Yu and Cringle 2001, 2005; Wangsa-Wirawan and Linsenmeier 2003, for reviews). Under dark conditions (dark adaptation, DA) the photoreceptor ISs consume oxygen at twice the rate at which they consume oxygen under light conditions (light adaptation, LA). As a result, the retinal oxygen profile drops under DA, meaning that the retina is more likely to experience hypoxia under DA. Hypoxia is detrimental to cells, both in limiting oxidative metabolism and in increasing the production of reactive oxygen species, upsetting the redox potential and leading to oxidative stress and damage (Kohen and Nyska 2002).

Birol et al. (2007) have measured oxygen profiles across the retina of the macaque monkey under DA and LA. The outer retina is normoxic (healthy) under LA and near-hypoxic (just above the hypoxic threshold, see Sect. 2.1) under DA, whilst the inner retina may be near-hypoxic under either LA or DA, depending upon local retinal capillary density (see Fig. 2, where the inner retina is normoxic under LA and near-hypoxic under DA in this case). Since the macaque retina is physiologically similar to that of the human, it is likely that the human retina is also vulnerable to hypoxia, especially under DA. Thus any factor that promotes retinal oxygenation may be vital in preventing or minimising retinal hypoxia and hence cell death.

Burmester et al. (2000) discovered a new vertebrate globin protein which they named neuroglobin because of its preferential expression in the cells of the nervous system, including the retina. Ngb has a similar structure and molecular mass to that of myoglobin (Mb) (Burmester and Hankeln 2009) and, as such, it has been proposed that Ngb, like Mb, may play a role in oxygen transport and storage (Burmester et al. 2000; Burmester and Hankeln 2004, 2009).

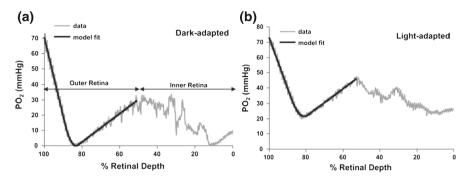


Fig. 2 Retinal oxygen profiles. Graphs show the oxygen distribution across the perifoveal retina of a macaque monkey under DA (**a**) and LA (**b**). The retina is normoxic under LA, whilst near-hypoxic regions are present in both the inner and outer retina under DA. *Grey lines* show the profiles measured using an oxygen-sensitive microelectrode, whilst *black lines* show a piecewise linear and quadratic approximation fitted to the outer retinal profile. Figure reproduced, with permission, from Birol et al. (2007)

Despite its oxygen binding properties, it is far from certain that Ngb plays a significant role in oxygen transport and storage, and opinion as to the main function of Ngb remains divided (Burmester and Hankeln 2009).

In this paper we investigate the possible role of Ngb in oxygen transport and storage in the human retina. The question we wish to address is this: could Ngb prevent tissue hypoxia by transporting oxygen from regions of high oxygen tension to regions of low oxygen tension, or by providing a temporary store of oxygen during a period when oxygen is scarce?

A number of mathematical models for retinal oxygen distribution have been constructed (see for instance, Dollery et al. 1969; Linsenmeier 1986; Stefánsson 1988; Haugh et al. 1990; Linsenmeier and Braun 1992; Braun et al. 1995; Linsenmeier and Padnick-Silver 2000; Cringle and Yu 2002; Yu and Cringle 2002). The majority of these models fit piecewise linear and quadratic polynomials to oxygen profiles measured using oxygen sensitive microelectrodes. They assume that the oxygen concentration is at steady-state and are posed on one-dimensional domains, oriented in a radial direction, across the width of the retina. They assume that the rate of oxygen uptake is constant in each model layer (where model layers incorporate various cellular layers) and so reduce to solving $\frac{d^2c}{dx^2} = Q$ in each layer, where *c* is the oxygen concentration, *x* is the distance across the retina and *Q* is the rate of oxygen uptake. In those layers in which Q > 0, the profile is quadratic and in those layers in which Q = 0, the profile is linear. In Sect. 4.3 we perform an asymptotic analysis to determine conditions under which the assumption of a constant rate of oxygen uptake is valid, and, in so doing, aim to place existing models on a stronger theoretical foundation.

To the best of our knowledge, only one mathematical model of retinal oxygen distribution incorporating Ngb has been developed (Fago et al. 2004b). This model contains three layers spanning the outer retina, between the choriocapillaris and the deep retinal capillaries. Unlike the models mentioned above, a Michaelis–Menten term is used for the rate of oxygen uptake. The proportion of Ngb molecules in their oxygen bound and unbound states are assumed to be at quasi-steady-state at all times. The

model predicts that Ngb concentrations would have to exceed 100 μ M to be effective in oxygen storage and to be greater than 300 μ M to be effective in oxygen transport. Since they assume that the Ngb concentration does not exceed 100 μ M, Fago et al. conclude that Ngb does not play a significant role in either the transport or storage of oxygen. However, based upon our reasoning in the Online Resource, we argue that Ngb concentrations could reach, and, perhaps, significantly exceed, these concentrations in some locations. In what follows we expand Fago et al.'s model to account for both the inner and outer retina, dropping the quasi-steady-state assumption and exploring the full range of biologically realistic Ngb concentrations.

The remainder of this paper is structured as follows. In Sect. 2 we derive timedependent and steady-state models on single and eight layer geometries for the dynamics of oxygen and Ngb within the retina. In Sect. 3 we present the results for the single layer model. In Sect. 4 we present the results for the eight layer model. Lastly, in Sect. 5, we summarise our findings and discuss possible directions for future research.

2 Model formulation

In this section we derive two models for the oxygen and Ngb concentrations across the retina. The first model treats the retina as a single cell layer, whilst the second model captures details of its structure and geometry by decomposing it into four cell layers, spread across eight model layers. The single layer model is a toy model, used to ascertain, for a general case, whether Ngb has the potential to play a significant role in oxygen transport and storage, whilst the second model is used to investigate Ngb's role in the human retina.

We develop time-dependent and steady-state versions of each of these models. The time-dependent versions are used to investigate the oxygen storage properties of Ngb, whilst the steady-state versions are used to investigate the oxygen transport properties of Ngb.

Ngb is a 'hexacoordinate' globin, with the sixth coordination position of the heme group occupied by an internal histidine molecule in the absence of an external ligand (Burmester and Hankeln 2004, 2009; Fago et al. 2004b). This means that in order for oxygen to bind to Ngb, the histidine molecule must first unbind from the heme group.

Writing C, N, N_H and N_O for oxygen, Ngb, Ngb-His and Ngb-O₂ respectively, the reaction scheme may be written as

$$N \underset{k_{h}}{\overset{k_{h}^{+}}{\rightleftharpoons}} N_{H}, \tag{1}$$

$$N + C \underset{k_{0}^{-}}{\overset{k_{0}^{+}}{\rightleftharpoons}} N_{O}, \qquad (2)$$

where k_h^+ , k_h^- , k_o^+ and k_o^- are the forward and reverse rate constants for the different reactions (see Table 1 for values).

Parameter	Description	Value	Source
Ĩ	Minimum retinal width	80 µm	Webvision, http:// webvision.med.utah. edu/
k	Oxygen solubility in retinal tissue	$\begin{array}{c} 2.4\times10^{-5}\ \text{LO}_2(\text{L}\\ \text{tissue mmHg})^{-1} \end{array}$	Linsenmeier and Braun (1992)
ĉ	Typical oxygen concentration at the choriocapillaris	$60 \text{ mmHg} (5.8 \times 10^{-5} \text{ M})$	Wangsa-Wirawan and Linsenmeier (2003) Birol et al. (2007)
ñ	Average Ngb concentration across the retina	100 μΜ	Schmidt et al. (2003)
D_o	Oxygen diffusion coefficient	$1.97 \times 10^{-9} \text{ m}^2 \text{ s}^{-1}$	Roh et al. (1990)
D_n	Ngb diffusion coefficient	$1.73 \times 10^{-11} \text{ m}^2 \text{ s}^{-1}$	Jürgens et al. (1994)
			McGuire and Secomb (2001)
L	Retinal width	80–320 µm	Webvision, http:// webvision.med.utah. edu/
C _C	Oxygen concentration at the choriocapillaris	$\begin{array}{c} 60 \text{ mmHg (typically)} \\ (5.8\times10^{-5} \text{ M}) \end{array}$	Wangsa-Wirawan and Linsenmeier (2003)
			Birol et al. (2007)
n _T	Ngb concentration	0– 4000 μM	Schmidt et al. (2003, 2005)
			Bentmann et al. (2005)
			Ostojić et al. (2006, 2008)
			Rajendram and Rao (2007)
Q	Maximum rate of oxygen uptake	0-20 mlO ₂ (100 g tissue min) ⁻¹ (0 to 1.33×10^{-4} M s ⁻¹)	Haugh et al. (1990)
			Cringle and Yu (2002); Birol et al. (2007)
			Wangsa-Wirawan and Linsenmeier (2003)
γ	Michaelis constant	1 mmHg (9.6 × 10 ⁻⁷ M)	Costa et al. (1997); Richmond et al. (1999)
			McGuire and Secomb (2001)
			Goldman (2008)
k_o^+	Rate constant of oxygen binding to Ngb	$170 \times 10^{6} \text{ M}^{-1} \text{ s}^{-1}$	Kiger et al. (2004)
k_o^-	Rate constant of oxygen dissociation from Ngb	0.7 s^{-1}	Kiger et al. (2004)

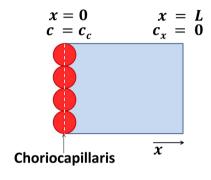
 Table 1
 Dimensional parameters associated with the single layer model (see Eqs. (3)–(8))

Parameter	Description	Value	Source
$\overline{k_h^+}$	Rate constant of histidine binding to Ngb	1800 s^{-1}	Kiger et al. (2004)
k_h^-	Rate constant of histidine dissociation from Ngb	$0.6 \ {\rm s}^{-1}$	Kiger et al. (2004)

Table 1 continued

Where two sets of units are stated, the first set was specified in the reference and the second, in brackets, uses units consistent with the dimensional model

Fig. 3 Single layer model diagram. Oxygen is supplied to the tissue via the choriocapillaris at x = 0 and the net-flux of oxygen at x = L is zero



2.1 Single layer model

We begin by formulating a system of four partial differential equations (PDEs) for the concentrations of O₂, c(x, t), Ngb, n(x, t), Ngb-His, $n_h(x, t)$ and Ngb-O₂, $n_o(x, t)$, on a one-dimensional domain $x \in (0, L)$ and for time $t \in (0, \infty)$. We choose a domain orientation perpendicular to the wall of the eye, which cuts across the retinal layers, starting at x = 0, where the RPE meets the choriocapillaris and ending at x = L, at the ILM, where the retina meets the vitreous humour (see Fig. 3).

Using the principle of mass balance and applying the law of mass action to the reaction scheme (1)–(2), we derive the following PDE for oxygen,

$$\frac{\partial c}{\partial t} = \underbrace{D_o \frac{\partial^2 c}{\partial x^2}}_{\text{diffusion}} - \underbrace{\frac{Qc}{\gamma + c}}_{\substack{\text{uptake by}\\ \text{retinal tissue}}} + \underbrace{k_o^- n_o - k_o^+ nc}_{\substack{\text{unbinding from and}\\ \text{binding to Ngb}}}, \tag{3}$$

where D_o is the oxygen diffusion coefficient, which is assumed to be constant (Roh et al. 1990). The rate of oxygen uptake is known to be near constant above hypoxic levels, but falls rapidly to zero as oxygen levels fall below a critical oxygen concentration (Goldman 2008). Since we are interested in the role of Ngb in preventing tissue hypoxia, it is important that our oxygen uptake term captures this concentration dependence (Goldman 2008). Thus we use a Michaelis–Menten term for the oxygen uptake (see Wilson et al. 1988; Costa et al. 1997), where Q is the maximum rate of oxygen uptake by the retinal tissue (achieved in the limit as $c \to \infty$) and γ is the

Michaelis constant, the concentration of oxygen at which the rate of oxygen uptake is Q/2. The inclusion of oxygen dependence in the uptake term represents an important difference between this model of retinal oxygen distribution and most existing ones (see, for example, Dollery et al. 1969; Stefánsson 1988; Haugh et al. 1990; Linsenmeier and Braun 1992; Braun et al. 1995; Cringle and Yu 2002; Yu and Cringle 2002, an exception being Fago et al. 2004b). We also interpret γ as being the *hypoxic threshold*: regions in which oxygen concentrations drop below this value are considered to be hypoxic (Richmond et al. 1999; McGuire and Secomb 2001, see also the Online Resource for further details).

Proceeding similarly, we derive PDEs for Ngb (n), Ngb-His (n_h) , and Ngb-O₂ (n_o) ,

$$\frac{\partial n}{\partial t} = D_n \frac{\partial^2 n}{\partial x^2} + k_h^- n_h + k_o^- n_o - k_h^+ n - k_o^+ nc, \qquad (4)$$

$$\frac{\partial n_h}{\partial t} = D_n \frac{\partial^2 n_h}{\partial x^2} + k_h^+ n - k_h^- n_h, \tag{5}$$

$$\frac{\partial n_o}{\partial t} = D_n \frac{\partial^2 n_o}{\partial x^2} + k_o^+ nc - k_o^- n_o.$$
(6)

In (4)–(6) we assume that the diffusion coefficients for Ngb, Ngb-His and Ngb-O₂ are identical since they are almost identical in molecular weight and structure (see Keener and Sneyd 1998, where a similar assumption is made about Mb).

We close Eqs. (3)–(6) by imposing the following initial and boundary conditions:

$$c(x, 0) = c_{init}(x), \quad n(x, 0) = n_{init}(x),$$

$$n_h(x, 0) = n_{h_{init}}(x), \quad n_o(x, 0) = n_{o_{init}}(x),$$

$$c(0, t) = c_c, \frac{\partial n}{\partial x}(0, t) = \frac{\partial n_h}{\partial x}(0, t) = \frac{\partial n_o}{\partial x}(0, t) = 0,$$

$$\frac{\partial c}{\partial x}(L, t) = \frac{\partial n}{\partial x}(L, t) = \frac{\partial n_h}{\partial x}(L, t) = \frac{\partial n_o}{\partial x}(L, t) = 0.$$
(8)

In (8) c_c is the oxygen concentration in that part of the retina which abuts the choriocapillaris. We use a Dirichlet boundary condition at x = 0, rather than a Robin boundary condition, since the fenestrated capillaries of the choriocapillaris are highly permeable to low molecular weight substances such as oxygen (Törnquist et al. 1990). For simplicity, the flux of oxygen at the ILM (x = L) is assumed to be zero. This is reasonable since the rate of oxygen consumption by the vitreous is negligible (Stefánsson 1988; Cringle and Yu 2002). We could alternatively have used Robin boundary conditions; however, in the absence of better data, this added complexity is unjustified. Due to their size, Ngb, Ngb-His and Ngb-O₂ are unable to leave the cells of the retina and, hence, we impose zero-flux boundary conditions for these species at x = 0, L. See Table 1 for parameter values (where a single value for Q is chosen from the range displayed in the table for any given simulation).

2.1.1 Non-dimensionalisation

To simplify the subsequent analysis, we recast the system in non-dimensional form, scaling the independent variables, dependent variables and initial conditions as:

$$\begin{aligned} x^* &= \frac{x}{\tilde{L}}, \quad t^* &= \frac{D_o}{\tilde{L}^2}t, \quad c^* &= \frac{c}{\tilde{c}}, \quad n^* &= \frac{n}{\tilde{n}}, \quad n^*_h &= \frac{n_h}{\tilde{n}}, \quad n^*_o &= \frac{n_o}{\tilde{n}} \\ c^*_{init} &= \frac{c_{init}}{\tilde{c}}, \quad n^*_{init} &= \frac{n_{init}}{\tilde{n}}, \quad n^*_{h_{init}} &= \frac{n_{h_{init}}}{\tilde{n}}, \quad n^*_{o_{init}} &= \frac{n_{o_{init}}}{\tilde{n}}, \end{aligned}$$

where \tilde{L} is the minimum retinal width, \tilde{c} is a typical oxygen concentration at the choriocapillaris and \tilde{n} is the average Ngb concentration across the retina (see Table 1). (We scale c and c_{init} with \tilde{c} , rather than c_c , and x and t with \tilde{L} , rather than L, so that results using different values of c_c and L can be compared more easily.) We define the following non-dimensional parameters:

$$L^{*} = \frac{L}{\tilde{L}}, \quad c_{c}^{*} = \frac{c_{c}}{\tilde{c}}, \quad D = \frac{D_{n}}{D_{o}}, \quad Q^{*} = \frac{\tilde{L}^{2}}{D_{o}\tilde{c}}Q, \quad \gamma^{*} = \frac{\gamma}{\tilde{c}},$$

$$\alpha = \frac{\tilde{c}}{\tilde{n}}, \quad k_{1} = \frac{\tilde{L}^{2}\tilde{n}}{D_{o}}k_{o}^{+}, \quad k_{2} = \frac{\tilde{L}^{2}\tilde{n}}{D_{o}\tilde{c}}k_{o}^{-}, \quad k_{3} = \frac{\tilde{L}^{2}}{D_{o}}k_{h}^{+}, \quad k_{4} = \frac{\tilde{L}^{2}}{D_{o}}k_{h}^{-}.$$

Dropping the stars, the system (3)–(6) becomes

$$\frac{\partial c}{\partial t} = \frac{\partial^2 c}{\partial x^2} - \frac{Qc}{\gamma + c} + k_2 n_o - k_1 nc, \qquad (9)$$

$$\frac{\partial n}{\partial t} = D \frac{\partial^2 n}{\partial x^2} + k_4 n_h + \alpha k_2 n_o - k_3 n - \alpha k_1 nc, \tag{10}$$

$$\frac{\partial n_h}{\partial t} = D \frac{\partial^2 n_h}{\partial x^2} + k_3 n - k_4 n_h, \tag{11}$$

$$\frac{\partial n_o}{\partial t} = D \frac{\partial^2 n_o}{\partial x^2} + \alpha k_1 nc - \alpha k_2 n_o, \tag{12}$$

with initial and boundary conditions as in (7) and (8). See Table 2 for non-dimensional parameter values.

2.1.2 Steady-state formulation

At steady-state, summation and integration of (10)–(12) subject to the zero-flux boundary conditions yields $n + n_h + n_o = \text{constant} = n_T$, where n_T , the total Ngb concentration, is given. Thus the total quantity of Ngb in its three forms is locally conserved across the domain. We use this identity to eliminate eq. (10), writing $n = n_T - n_h - n_o$ in Eqs. (9), (11) and (12), to obtain the steady-state boundary

Table 2 Non-dimensional parameters associated with the	Parameter	Value
single layer model (see Eqs. (7)–(12))	L	1–4
	C _C	1
	n _T	0–40
	D	8.78×10^{-3}
	Q	0–7.52
	γ	0.017
	α	0.58
	k_1	55,200
	k_2	3.95
	<i>k</i> ₃	5,850
Values given to an accuracy of at most three significant figures	<u>k</u> 4	1.95

value problem:

$$0 = \frac{d^2c}{dx^2} - \frac{Qc}{\gamma + c} + k_2 n_o - k_1 (n_T - n_h - n_o)c,$$
(13)

$$0 = D\frac{d^2n_h}{dx^2} + k_3(n_T - n_h - n_o) - k_4n_h,$$
(14)

$$0 = D \frac{d^2 n_o}{dx^2} + \alpha k_1 (n_T - n_h - n_o)c - \alpha k_2 n_o,$$
(15)

for c = c(x), $n_h = n_h(x)$ and $n_o = n_o(x)$, with boundary conditions as in (8). We note that when D = 0, $k_2 n_o - k_1 (n_T - n_h - n_o)c = 0$ (by Eq. (15)), so that Eq. (13) becomes $0 = d^2 c/dx^2 - Qc/(\gamma + c)$. This is the same form taken by the oxygen equation in the absence of Ngb. Therefore, although $D \ll 1$, Ngb diffusion plays an important role and cannot be neglected.

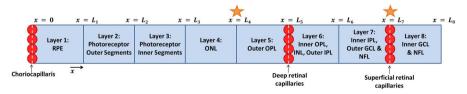


Fig. 4 Eight layer model diagram. Oxygen is supplied to the tissue via the choriocapillaris and retinal capillaries and the net-flux of oxygen at $x = L_8$ is zero. The flux of Ngb between layers is zero, except at those boundaries marked with stars, across which the concentration and flux of Ngb is continuous. RPE retinal pigment epithelium, ONL outer nuclear layer, OPL outer plexiform layer, INL inner nuclear layer, IPL inner plexiform layer, GCL ganglion cell layer, NFL nerve fibre layer

2.2 Eight layer model

In this section we develop a detailed model to take account of the complex, multilayered structure of the human retina.

We decompose our model retina into eight layers as follows: layer 1 contains the RPE; layer 2, the photoreceptor OSs; layer 3, the photoreceptor ISs; layer 4, the ONL; layer 5, the outer half of the OPL; layer 6, the inner half of the OPL, the INL and the outer half of the IPL; layer 7, the inner half of the IPL, and the outer half of the GCL and NFL and layer 8, the inner half of the GCL and NFL (see Fig. 4). (Note that whilst Cringle and Yu (2002) also divide the model retina into 8 layers, their layers are arranged differently, incorporating different tissue layers.) We label the ends of each model layer by L_i , where $i \in \{1, 2, ..., 8\}$ and $0 < L_1 < L_2 < \cdots < L_8$.

The number and arrangement of layers have been chosen to allow us to account for the differing oxygen demands of the various retinal layers, to allow the incorporation of vasculature along the boundaries between layers and to allow for the containment of Ngb within certain layers. The model includes all three vascular layers: the choriocapillaris (on the left-hand boundary of layer 1), the deep retinal capillaries (on the boundary between layers 5 and 6), and the superficial retinal capillaries (on the boundary between layers 7 and 8, see Fig. 4). The deep and superficial retinal capillary layers are both laminar, passing through the OPL and GCL/NFL (Chan et al. 2012; Kur et al. 2012; Tan et al. 2012).

As with the single layer model, the following non-dimensional equations hold in each retinal layer:

$$\frac{\partial c}{\partial t} = \frac{\partial^2 c}{\partial x^2} - \frac{Q_i c}{\gamma + c} + k_2 n_o - k_1 n c, \tag{16}$$

$$\frac{\partial n}{\partial t} = D \frac{\partial^2 n}{\partial x^2} + k_4 n_h + \alpha k_2 n_o - k_3 n - \alpha k_1 nc, \qquad (17)$$

$$\frac{\partial n_h}{\partial t} = D \frac{\partial^2 n_h}{\partial x^2} + k_3 n - k_4 n_h, \tag{18}$$

$$\frac{\partial n_o}{\partial t} = D \frac{\partial^2 n_o}{\partial x^2} + \alpha k_1 nc - \alpha k_2 n_o, \tag{19}$$

where Q_i (1, ..., 8) denotes the maximum rate of oxygen uptake in each layer. Guided by Roh et al. (1990), we suppose that the oxygen diffusion coefficient is constant across the retina and we make the same assumption for the diffusivity of Ngb.

The initial conditions for the eight layer model are the same as in (7). The oxygen boundary conditions for the eight layer model are as follows:

$$c(0,t) = c_{c}, \quad \frac{\partial c}{\partial x}(L_{8},t) = 0, \quad [c(L_{i},t)]_{-}^{+} = 0, \quad \text{for } i = 1, \dots, 7,$$

$$\left[\frac{\partial c}{\partial x}(L_{i},t)\right]_{-}^{+} = \begin{cases} 0, & \text{for } i = 1, \dots, 4 \text{ and } 6, \\ \hat{h}_{i}(c(L_{i},t) - c_{v}), & \text{for } i = 5 \text{ and } 7. \end{cases}$$
(20)

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where \hat{h} represents the permeability of the retinal capillaries (the dimensional version has the units of permeability, that is ms⁻¹) and also accounts for their density, whilst c_v is the concentration of oxygen in the retinal capillaries (see the Online Resource for more details). The '-' and '+' subscripts and superscripts indicate that the quantity is evaluated on the left- and right-hand sides of the boundary respectively.

Thus we impose Dirichlet and zero-flux boundary conditions at the left- and righthand ends of the domain respectively, as for the single layer model, with continuity of concentration and flux at all internal boundaries except those at which the capillaries lie, where the flux is discontinuous (see Eq. (20)).

We impose zero-flux boundary conditions upon Ngb, Ngb-His and Ngb-O₂ at $x = 0, L_1, L_5, L_6$ and L_8 since these represent boundaries between cell layers and Ngb molecules are too large to pass through cell membranes (Ngb only existing intracellularly). As can be seen from Fig. 3a, b of the Online Resource, Ngb is highly concentrated within the photoreceptor ISs (layer 3), whilst being absent from the photoreceptor OSs (layer 2) and present in comparatively low concentrations within the ONL (layer 4). It is not known what prevents Ngb from diffusing from layer 3, into layers 2 and 4; however, it may be that the narrow connecting cilium prevents Ngb from diffusing between layers 2 and 3. Therefore, we also impose zero-flux boundary conditions upon Ngb, Ngb-His and Ngb-O₂ at $x = L_2$ and L_3 , in order to maintain the localisation of Ngb within the ISs. The concentration and flux of Ngb, Ngb-His and Ngb-O₂ are continuous across $x = L_4$ and L_7 since these *model* boundaries occur within cell layers, there being nothing to physically prevent these species from diffusing across these boundaries.

2.2.1 Steady-state formulation

As with the single layer model, the following non-dimensional equations define the steady-state distributions for c = c(x), $n_h = n_h(x)$ and $n_o = n_o(x)$ in each retinal layer:

$$0 = \frac{d^2c}{dx^2} - \frac{Q_ic}{\gamma + c} + k_2 n_o - k_1 (n_{T_i} - n_h - n_o)c, \qquad (21)$$

$$0 = D \frac{d^2 n_h}{dx^2} + k_3 (n_{T_i} - n_h - n_o) - k_4 n_h,$$
(22)

$$0 = D \frac{d^2 n_o}{dx^2} + \alpha k_1 (n_{T_i} - n_h - n_o)c - \alpha k_2 n_o,$$
(23)

where Q_i and n_{T_i} (1, ..., 8) denote the maximum rate of oxygen uptake in each layer and the total Ngb concentration in each layer respectively. The boundary conditions are the same as for the time-dependent eight layer model (see (20) above).

The dimensional and non-dimensional parameters associated with the eight layer model are presented in Tables 3 and 4 respectively (where the upper and lower values for Q_3 correspond to DA and LA respectively). Those parameters used in the eight layer model which are the same as in the single layer model are stated in Tables 1 and 2.

Parameter	Description	Value	Source
<i>L</i> ₁	Positions of the boundaries between retinal layers	5 µm	Yu et al. (1994) Webvision, http:// webvision.med.utah. edu/
L_2		27.5 μm	
L_3		50 µm	
L_4		100 µm	
L_5		106.5 µm	
L_6		193.5 µm	
L_7		237.5 µm	
L_8		250 µm	
n_{T_i} (<i>i</i> = 1, 4,, 8)	Typical Ngb concentrations in each retinal layer	2 μΜ	Schmidt et al. (2003, 2005)
n_{T_2}		0 μΜ	Bentmann et al. (2005)
n_{T_3}		200–4000 μM	Ostojić et al. (2006, 2008)
5			Rajendram and Rao (2007)
Q_1	Maximum rate of oxygen uptake by each retinal layer	4.5 mlO ₂ (100 g tissue min) ⁻¹ (3 × 10 ⁻⁵ M s ⁻¹)	
$Q_i \ (i = 2, 4)$		$\begin{array}{c} 0 \text{ mlO}_2 \\ (100 \text{ g tissue min})^{-1} \end{array}$	Haugh et al. (1990)
Q_3		10–20 mlO ₂	Cringle and Yu (2002)
		$(100 \text{ g tissue min})^{-1}$ (6.67 × 10 ⁻⁵ to 1.33 × 10 ⁻⁴ M s ⁻¹)	Wangsa-Wirawan and Linsenmeier (2003)
		4 10	Birol et al. (2007)
$Q_i \ (i=5,\ldots,8)$		$\begin{array}{c} 4 \text{ mlO}_2 \\ (100 \text{ g tissue min})^{-1} \\ (2.67 \times 10^{-5} \text{ M s}^{-1}) \end{array}$	
\hat{h}_5	Permeability of the deep retinal capillaries	$6.5 \times 10^{-5} \text{ ms}^{-1}$ (typically)	Gillies et al. (1995)
\hat{h}_7	Permeability of the	$1.3 \times 10^{-4} \text{ m s}^{-1}$ (typically) superficial retinal capillaries	Tan et al. (2012)
c_v	Oxygen concentration in	40 mmHg (typically)	Hardarson et al. (2009)
- 0	the retinal capillaries	$(3.84 \times 10^{-5} \text{ M})$	Hardarson and Stefánsson (2010)

 Table 3 Dimensional parameters associated with the eight layer model (see Eqs. (16)–(23))

Where two sets of units are stated, the first set was specified in the reference and the second, in brackets, uses units consistent with the dimensional model

Parameter	Value
L_1	0.063
L_2	0.34
<i>L</i> ₃	0.63
L_4	1.25
L_5	1.33
L ₆	2.42
L ₇	2.97
L ₈	3.13
$n_{T_i} \ (i = 1, 4, \dots, 8)$	0.02
n_{T_2}	0
n_{T_3}	2-40
Q1	1.69
$Q_i \ (i = 2, 4)$	0
<i>Q</i> ₃	3.76-7.52
$Q_i \ (i=5,\ldots,8)$	1.50
\hat{h}_5	2.64
\hat{h}_7	5.28
c_v	0.67

Values given to an accuracy of at most three significant figures

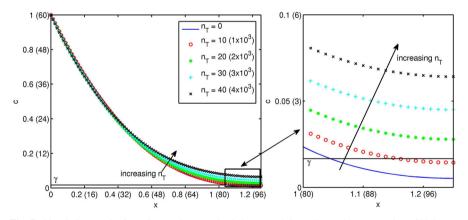


Fig. 5 Simulation results from the steady-state single layer model. As the total concentration of Ngb, n_T , is increased, the steady-state oxygen concentration at x = L increases above the hypoxic threshold, γ . Equations (8) and (13)–(15) were solved using the FEM with 101 mesh points. Dimensional values are given in brackets for $x \ (\mu m)$, $c \ (mmHg)$ and $n_T \ (\mu M)$. Parameter values: $L = 1.25 \ (100 \ \mu m)$, $c_c = 1 \ (60 \ mmHg)$ and $Q = 1.88 \ (3.33 \times 10^{-5} \ Ms^{-1})$. Remaining parameter values as in Table 2

Table 4Non-dimensionalparameters associated witheight layer model (seeEqs. (16)–(23))

3 Single layer model results

3.1 Numerical solutions to the steady-state problem: oxygen transport

We begin by presenting results for the steady-state single layer problem, where we investigate the role of Ngb in oxygen transport. The equations for the single layer model, (8) and (13)–(15), were solved using the finite element method (FEM). We validated our FEM solutions to the steady-state problem by checking that they matched the steady-state solutions to the time-dependent problem, (7)–(12), solved using the method of lines. In what follows, all variable and parameter values are given in their non-dimensional form, unless stated otherwise.

Figure 5 shows how increasing the total concentration of Ngb in the retina, n_T , affects the steady-state oxygen distribution. Increased Ngb levels result in a minor decrease in the oxygen concentration in the well oxygenated region of the tissue near x = 0, but a significant increase in the oxygen concentration near x = L. The decrease in oxygen concentration near the choriocapillaris is insignificant since oxygen is rich here; however, the increase in oxygen concentration near x = L represents a significant alleviation of hypoxia. Indeed, the oxygen concentration does not pass beneath the hypoxic threshold, γ , for $n_T \ge 12$, where $n_T = 16$ is the maximum biologically realistic value for a domain of this length.

3.2 Analysis of a simplified single layer model

In this section we develop and analyse a simplified version of the single layer model at steady-state. We use the simplified model to investigate Ngb's effect upon the domain length that can be supported under normoxic conditions and upon the minimum oxygen concentration when oxygen levels do not become hypoxic. (Keener and Sneyd 1998, Chapter 2, perform a similar analysis for a problem involving the facilitated diffusion of oxygen by Mb in a slab reactor, the main difference being that their equations lack an oxygen uptake term.)

To simplify our analysis we make two changes: we replace the Michaelis–Menten term, $Qc/(\gamma + c)$, with a step function $QH(c - \gamma)$, so that the rate of oxygen uptake is equal to zero when $c < \gamma$ and Q when $c \ge \gamma$. Secondly, we set $\tilde{n} = 58 \mu$ M, so that $\alpha = 1$. This alternative choice for the non-dimensionalisation does not affect the

Parameter	Value
n _T	0–69.4
α	1
k_1	31,800
k_2	2.27

 Table 5
 Non-dimensional parameters associated with the simplified single layer model (see Eqs. (24)–(26))

Only those parameter values that change have been listed, all other parameter values remain as in Table 2. (Values given to an accuracy of at most three significant figures)

behaviour of the system, it merely simplifies the analysis presented below (allowing cancellation of the kinetic terms). The non-dimensional parameters n_T , k_1 and k_2 also change, attaining the values stated in Table 5, whereas all other parameter values remain as in Table 2.

Following these simplifications, Eqs. (13)–(15) take the form

$$0 = \frac{d^2c}{dx^2} - QH(c - \gamma) + k_2 n_o - k_1 nc,$$
(24)

$$0 = D\frac{d^2n_h}{dx^2} + k_3n - k_4n_h,$$
(25)

$$0 = D\frac{\mathrm{d}^2 n_o}{\mathrm{d}x^2} + k_1 nc - k_2 n_o, \tag{26}$$

where $n = n_T - n_o - n_h$. We impose the boundary conditions (8) to close the system.

We begin by considering the case where the retina becomes hypoxic, such that $c(x) \le \gamma$ for $x_c \le x \le L$. Adding Eqs. (24) and (26), applying the zero-flux boundary condition for n_o at x = 0 and integrating between 0 and x supplies

$$0 = \frac{\mathrm{d}c}{\mathrm{d}x}(x) - \frac{\mathrm{d}c}{\mathrm{d}x}(0) + D\frac{\mathrm{d}n_o}{\mathrm{d}x}(x) - Q\underbrace{\int_0^x H(c-\gamma)\mathrm{d}\tilde{x}}_{=min(x,x_c)},\tag{27}$$

where x_c is the maximum domain length that can be supported under normoxic conditions, such that $c(x_c) = \gamma$. Applying the zero-flux boundary conditions for *c* and n_o at x = L, we find that $\frac{dc}{dx}(0) = -Qx_c$. Rearranging Eq. (27), we obtain the following expression for J(x), the flux of oxygen (in its bound and unbound forms):

$$J(x) = -\left(\frac{\mathrm{d}c}{\mathrm{d}x} + D\frac{\mathrm{d}n_o}{\mathrm{d}x}\right) = Q(x_c - \min(x, x_c)). \tag{28}$$

Integrating Eq. (28) between 0 and x_c , we obtain the following expression:

$$J_A = \int_0^{x_c} J(x) dx = (c_c - \gamma) + D(n_o(0) - n_o(x_c)) = \frac{Qx_c^2}{2},$$
 (29)

where J_A is a conserved quantity equal to the area under the curve J(x). We seek an expression for x_c , in order to determine the contribution of Ngb to the domain length that can be supported under normoxia. We proceed by deriving leading order approximations for $n_o(0)$ and $n_o(x_c)$ in terms of $c(0) = c_c$ and $c(x_c) = \gamma$ respectively. Expanding the dependent variables in regular power series in terms of the small parameter $\varepsilon = 0.1$ and substituting into Eqs. (24)–(26), we retain the (dominant) leading order terms and neglect higher order terms.

We begin by re-scaling the variables and parameters, fixing $\varepsilon = 0.1$ to separate the various scales. We scale $c = \varepsilon c^*$, since c is of this order across most of the retina (see, for instance, Fig. 5), $D = \varepsilon^2 D^*$, $\gamma = \varepsilon^2 \gamma^*$, $k_1 = \varepsilon^{-4} k_1^*$ and $k_3 = \varepsilon^{-3} k_3^*$.

In Appendix 1 we show that *n* is bounded above by $\alpha k_2 n_T/k_3$. Using the alternative non-dimensionalisation adopted in this section, this becomes $k_2 n_T/k_3 \approx \varepsilon^3 n_T$ (where the changes in α and k_2 cancel). Whilst n_o and n_h vary across the domain, they are of the same order of magnitude, and so, at leading order, they satisfy the conservation relation $n_o + n_h = n_T$. Assuming that $2 \le n_T \le 69.4$, the Ngb terms can be scaled in one of two ways, depending upon the size of n_T :

- Scaling 1: for $2 \le n_T < 7$ we scale $n = \varepsilon^3 n^*$, where $n_h = O(1)$, $n_o = O(1)$ and $n_T = O(1)$.
- Scaling 2: for $7 \le n_T \le 69.4$ we scale $n = \varepsilon^2 n^*$, $n_h = \varepsilon^{-1} n_h^*$, $n_o = \varepsilon^{-1} n_o^*$ and $n_T = \varepsilon^{-1} n_T^*$.

In both cases $n/n_T = O(\varepsilon^3)$, $n_h/n_T = O(1)$ and $n_o/n_T = O(1)$. In what follows we work with the first scaling, noting that the leading order solution under the second scaling is the same. Applying Scaling 1 to Eqs. (24)–(26) we obtain:

$$0 = \varepsilon \frac{d^2 c^*}{dx^2} - Q H^* (c^* - \gamma^*) + k_2 n_o - k_1^* n^* c^*,$$
(30)

$$0 = \varepsilon^2 D^* \frac{d^2 n_h}{dx^2} + k_3^* n^* - k_4 n_h,$$
(31)

$$0 = \varepsilon^2 D^* \frac{d^2 n_o}{dx^2} + k_1^* n^* c^* - k_2 n_o,$$
(32)

where $H^*(c^* - \gamma^*) = H(c - \gamma)$. Upon dropping the stars, Eqs. (31) and (32) provide

$$k_3n - k_4n_h = 0, \quad k_1nc - k_2n_o = 0, \tag{33}$$

at leading order. Substituting the second of these equations into (30), the dominant balance involves the diffusion and uptake terms. For $x \ge x_c$, $QH(c - \gamma) = 0$, so that, after applying $c(x_c) = \gamma$, together with the zero-flux boundary condition at x = L, we find that $c(x) = \gamma$ for $x \in [x_c, L]$. For $x \in [0, x_c)$, $c > \gamma$, so that $QH(c - \gamma) > 0$, and we must scale $x = \varepsilon^{\frac{1}{2}}x^*$ to attain a dominant balance between the diffusion and uptake terms, resulting in a quadratic oxygen profile in this region. Applying this scaling to Eqs. (31) and (32) retrospectively, we see that the leading order equations in (33) are preserved. Formally, there is also a boundary layer at x = 0, to allow us to satisfy the boundary conditions there (though there is no sharp change in the solution in this region).

We use (33), together with the leading order conservation relation $n_h + n_o = n_T$, to derive an expression for n_o in terms of *c* as follows

$$n_o = \frac{n_T c}{P_{50} + c}, \text{ where } P_{50} := \frac{k_2 k_3}{k_1 k_4}.$$
 (34)

 P_{50} is the oxygen concentration at which exactly half of the Ngb molecules are in their oxygen bound form, that is at which $n_o = n_T/2$ (= n_h at leading order). This expression for P_{50} differs from that used by Kiger et al. (2004), where $P_{50} = k_2(k_3 + k_4)/(k_1k_4)$. Kiger et al.'s expression can be obtained by considering the unscaled,

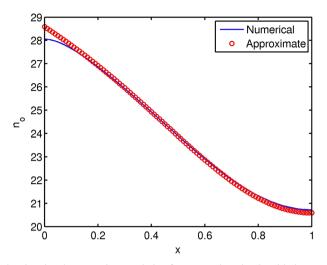


Fig. 6 Graph showing that the approximate solution for n_o matches closely with the numerical solution. The numerical solution was obtained by solving Eqs. (8) and (24)–(26) using the FEM, with 101 mesh points. The approximate solution was obtained using the numerical solution for c in Eq. (34). Parameter values: L = 1, $c_c = 1$, $n_T = 34.7$ and Q = 1.50. Remaining parameter values as in Tables 2 and 5. Parameters and variables are in their unscaled form

spatially homogeneous versions of Eqs. (24)–(26) with Q = 0. However, since $k_4 \ll k_3$ (in their unscaled form), the difference between these two expressions is small. As Fig. 6 reveals, the approximate solution for n_o in Eq. (34) matches closely with the numerical solution.

Substituting for n_o from (34) into (29) we obtain

$$J_{A} = (c_{c} - \gamma) \left(1 + \underbrace{\frac{P_{50}Dn_{T}}{(P_{50} + c_{c})(P_{50} + \gamma)}}_{\text{Ngb contribution}} \right) = \frac{Qx_{c}^{2}}{2}.$$
 (35)

Rearranging Eq. (35), we may derive an expression for x_c , the maximum domain length that can be supported under normoxic conditions, as follows

$$x_{c} = \sqrt{\frac{2(c_{c} - \gamma)}{Q} \left(1 + \frac{P_{50}Dn_{T}}{(P_{50} + c_{c})(P_{50} + \gamma)}\right)}.$$
(36)

If $n_T = \gamma = 0$ then (36) reduces to the expression derived by Dollery et al. (1969) for the maximum tissue length that can be supported by a single vascular bed. It can be seen both from Eq. (36) and from Fig. 7a that Ngb increases the size of x_c . For $c_c = 1$ and $n_T = 34.7$ (our predicted maximum Ngb concentration for domains of this length, assuming a maximal retinal width of 320 μ m, and that Ngb is absent from all other retinal layers), x_c is 11 % longer than it would be in the absence of Ngb. Further, Ngb makes a proportionally larger contribution to x_c as c_c decreases (see Fig. 7a), for

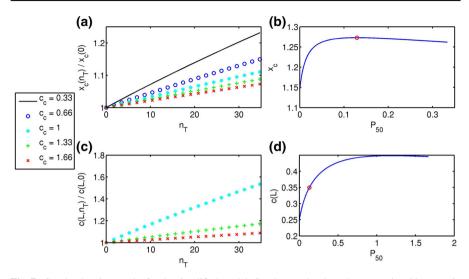


Fig. 7 Graphs showing results for the simplified model. Graphs **a** and **c** show the proportional increase in x_c and c(L) respectively, due to the action of Ngb, the effect being more pronounced for lower values of c_c . Graphs **b** and **d** show the effect of P_{50} upon x_c and c(L) respectively. The value of the dependent variable at $P_{50} = \sqrt{\gamma c_c}$ is marked with a *circle* in each case. The value of x_c is maximal at $P_{50} = \sqrt{\gamma c_c}$; however, c(L) takes its maximum value for some $P_{50} > \sqrt{\gamma c_c}$. Graphs **a** and **b** were obtained using solutions to (36) and graphs **c** and **d** were obtained using solutions to (39). Parameter values: Q = 1.50, **c**-**d** L = 1, **b**, **d** $c_c = 1$ and $n_T = 34.7$. Remaining parameter values as in Tables 2 and 5. The key on the left applies to graphs **a** and **c** only

instance, when $n_T = 34.7$ and $c_c = 0.33$, x_c is 23 % larger than it would be in the absence of Ngb.

Differentiating Eq. (36) with respect to P_{50} , we find that x_c achieves a global maximum at $P_{50,max} = \sqrt{\gamma c_c}$. Figure 7b shows the dependence of x_c upon P_{50} , with the maximum value of x_c , at which $P_{50} = P_{50,max}$, marked with a circle. It can be seen that the curve is fairly flat in the vicinity of $P_{50,max}$ such that x_c remains near maximal for a small decrease, or even quite a large increase, in P_{50} away from $P_{50,max}$. Further, x_c decreases sharply as P_{50} approaches zero for $P_{50} < 0.05$. This result is surprising since it is usually assumed that Ngb would be a more effective oxygen transporter if it had a lower P_{50} value: our analysis reveals that as P_{50} decreases below $P_{50,max}$. Ngb will become less effective in oxygen transport. For $c_c = 1$, $P_{50,max} = 0.129 = 7.44 \,\mu\text{M} = 7.75 \,\text{mmHg}$, which is within the range of measured values in the literature (see Table 3 of the Online Resource).

So far we have assumed that the retina becomes hypoxic at some location, $x = x_c < L$. If instead, oxygen levels are normoxic throughout the domain, that is $x_c > L$, then we may derive an expression for c(x = L), the minimum oxygen concentration. Equation (28) becomes

$$J(x) = -\left(\frac{\mathrm{d}c}{\mathrm{d}x} + D\frac{\mathrm{d}n_o}{\mathrm{d}x}\right) = Q(L-x). \tag{37}$$

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Integrating (37) between 0 and L and substituting for n_o from (34) we obtain

$$J_A = (c_c - c(L)) \left(1 + \frac{P_{50} Dn_T}{(P_{50} + c_c)(P_{50} + c(L))} \right) = \frac{QL^2}{2}.$$
 (38)

This equation can be rearranged to give the following expression for c(L):

$$c(L) = \frac{-A + \sqrt{A^2 - 4B}}{2},$$
(39)

where we have chosen the positive root to satisfy the condition that $c(L) = c_c$ when $Q = n_T = 0$ (see Eq. (38)), and

$$A = P_{50} + \frac{QL^2}{2} + \frac{P_{50}Dn_T}{P_{50} + c_c} - c_c, \quad B = P_{50}\left(\frac{QL^2}{2} - \frac{Dn_Tc_c}{P_{50} + c_c} - c_c\right).$$
(40)

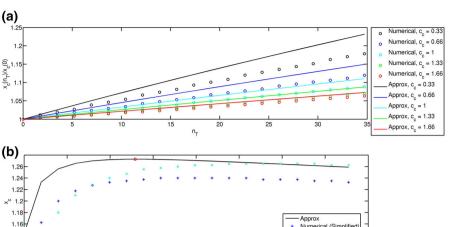
Figure 7c shows that Ngb acts to increase c(L), making a proportionally larger contribution for lower c_c . Indeed, for L = 1, $c_c = 1$, $n_T = 34.7$ (our predicted maximum Ngb concentration for domains of length L = 1) and Q = 1.50, c(L) is 53 % higher than what it would be in the absence of Ngb.

Plotting c(L) against P_{50} shows that the maximum value of c(L) does not correspond with $P_{50} = \sqrt{\gamma c_c}$, but instead lies at a P_{50} significantly above this value (this relationship was found to hold for all combinations of parameter values tested, see Fig. 7d). It may be that the optimum P_{50} lies somewhere above $\sqrt{\gamma c_c}$, since x_c decreases slowly as P_{50} increases beyond $\sqrt{\gamma c_c}$, but c(L) increases more rapidly. In both cases a decrease in P_{50} below $\sqrt{\gamma c_c}$ is disadvantageous, counter to the prevailing assumption that lower P_{50} values improve Ngb's effectiveness in oxygen transport.

3.2.1 Comparing numerical and approximate solutions

In deriving an analytical solution for x_c we have made two simplifying assumptions: (i) that the Michaelis–Menten term for oxygen uptake may be approximated by a step function and (ii) that n_o can be approximated as a function of c (Eq. (34)). In this section we compare the approximate analytical solutions with the numerical solutions to the full (Eqs. (8) and (13)–(15)) and simplified (Eqs. (8) and (24)–(26)) problems. When solving the simplified problem numerically, we replace the step function in (24), $H(c - \gamma)$, with the modified hyperbolic function, $\frac{1}{2}(\tanh((c - \gamma)/\delta) + 1)$, where $\delta = 0.001$, so as to avoid the numerical difficulties resulting from a discontinuity in the governing equations.

Figure 8a compares the approximate solution to the numerical solution to the full problem, for the proportional increase in x_c due to Ngb (the numerical solution to the simplified problem provides a closer match to the approximate solution, but is omitted for clarity), whilst Fig. 8b compares the results for the approximate solution and the numerical solutions to the simplified and full models, for the dependence of x_c upon P_{50} . The difference between results is at most $O(\varepsilon)$ (where $\varepsilon = 0.1$) in all cases, as expected for a leading order approximation. The numerical solution to the simplified



0.25

0.3

Numerical (Simplified Numerical (Full)

0.35

0.4

Fig.8 Graphs comparing numerical and approximate solutions to the single layer model. Graph **a** compares the results for the proportional increase in x_c , due to the action of Ngb, from the approximation (36) and the solution to the full problem (8) and (13)–(15). In general the approximate solution overestimates the numerical solution, particularly for small values of c_c . Graph **b** compares the results for the effect of P_{50} upon x_c from the approximation (36), the solution to the simplified problem (8) and (24)–(26) and the solution to the full problem (8) and (13)–(15); the value of x_c at $P_{50} = \sqrt{\gamma c_c}$ is marked with a *circle*. The numerical solutions to the simplified and full problems lie mostly beneath the approximate solution. The numerical solutions to the full and simplified problems were obtained using the FEM with 801 mesh points. Parameter values: L = 2 and Q = 1.50; **b** $c_c = 1$ and $n_T = 34.7$. Remaining parameter values as in Tables 2 and 5

0.2 P₅₀

problem achieves its maximum for P_{50} slightly above $\sqrt{\gamma c_c}$, whilst the numerical solution to the full problem achieves its maximum for $P_{50} \approx 0.28 = 16.7$ mmHg. This is approximately twice $\sqrt{\gamma c_c} = 0.13 = 7.7$ mmHg, and lies at the upper end of the range of measured values in the literature (see Table 3 of the Online Resource, where the bracketed P_{50} values are the ones consistent with the parameters used in our model). Unlike the approximate and simplified numerical solutions, the prediction of x_c from the full numerical solution initially decreases as P_{50} increases from 0 (this result was verified using the Matlab routine pdepe to solve the time-dependent problem (7)–(12), allowing it to settle to steady-state). Whilst this results in a local maximum at $P_{50} = 0$, the global maximum remains at $P_{50,max,numeric} > 0$. Therefore, we have a reasonable agreement between the numerical solutions to the full and simplified problems and our approximations.

4 Eight layer model results

1.1

0

0.05

0.1

0.15

4.1 Numerical solutions to the steady-state problem: oxygen transport

As with the single layer model, we solved the steady-state eight layer model, (20)–(23), using the FEM. We validated our FEM solutions to the steady-state problem by checking that they matched the steady-state solution to the time-dependent problem,

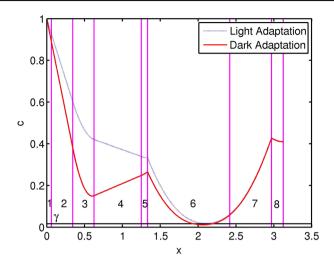


Fig. 9 Simulation results from the eight layer model showing the oxygen distribution in the healthy human retina under LA and DA in the absence of Ngb. The spatial extent of the different layers is depicted by *the vertical lines*, whilst the hypoxic threshold, $c = \gamma$, is denoted by *a horizontal line*. The oxygen concentration in the outer retina (layers 1–5) and layer 6 is significantly lower under DA due to the increased rate of oxygen uptake by the photoreceptor ISs. Equations (20)–(23) were solved using the FEM with 501 mesh points. Under LA $Q_3 = 3.76$, whereas under DA $Q_3 = 7.52$. In both cases $n_{T_i} = 0$ (i = 1, ..., 8). Remaining parameter values as in Tables 2 and 4

(7) and (16)–(20), solved using the method of lines. We now return to the nondimensionalisation described in Sect. 2 (as opposed to that adopted in Sect. 3.2).

Figure 9 shows the oxygen profile across a healthy human retina under LA (dotted curve) and DA (solid curve) in the absence of Ngb. The boundaries between model layers are shown by vertical lines and the layers are labelled 1–8, whilst a horizontal line marks the hypoxic threshold, γ . The only difference between LA and DA in our model is that the rate of oxygen uptake by the photoreceptor ISs, Q_3 , under DA is double that under LA. As a result, the oxygen concentration in the outer retina (layers 1–5) and in layer 6, is significantly lower under DA than under LA, whereas the oxygen concentration in layers 7 and 8 remains relatively unaffected.

The parameters used to generate this plot are either taken directly from the literature, or estimated from the literature, except for the permeabilities of the deep and superficial retinal capillaries, \hat{h}_5 and \hat{h}_7 . These are chosen to yield oxygen profiles similar to those measured in the rat (see Yu et al. 1994, Figure 2(a)) and macaque (see Fig. 2) retinas (which are physiologically and biochemically similar to the human retina), whilst satisfying the constraint $\hat{h}_7 = 2\hat{h}_5$, since the superficial retinal capillary bed has twice the density of the deep retinal capillary bed (Tan et al. 2012, see the Online Resource for more details). Therefore, our simulations of the retinal oxygen profile in humans constitute testable predictions.

Since the oxygen profile in the inner retina of the macaque may descend to near hypoxic levels (see Fig. 2a), we choose the permeabilities such that the inner retinal oxygen profile descends beneath the hypoxic threshold in the absence of Ngb under DA. This allows us to test whether Ngb could prevent hypoxia in such a scenario,

raising the oxygen profile to levels similar to those seen in the healthy macaque. Further, as we vary \hat{h}_5 and \hat{h}_7 between 0.2–3.1 and 0.4–6.2 respectively (under DA, results not shown) we find that the outer retina will remain normoxic provided c_c is not significantly reduced, whilst the inner retina (layers 6–8) will remain hypoxic, achieving its minimum in layer 6, as is the case in Fig. 9.

We note that whilst Fig. 9 matches well with the oxygen profile seen in rats (see, for example, Yu and Cringle 2002), our model places the minimum inner retinal oxygen concentration at a position outward from that measured in the macaque (see Fig. 2). However, in the absence of measurements for the retinal oxygen profile in humans with which to compare our results, it is not clear that any modification of the model would be an improvement.

In Fig. 10 we show that Ngb may prevent inner retinal hypoxia. The parameters chosen are the same as those for Fig. 9 under DA (for which the inner retina is hypoxic in the absence of Ngb). The solid curve shows the oxygen profile in the absence of Ngb (this is the same as the solid curve in Fig. 9) and the dotted curve shows the oxygen profile in the presence of Ngb, when Ngb is most heavily concentrated in layers 3, 6, 7 and 8. This Ngb distribution corresponds with that found in the retina of the rat by Bentmann et al. (2005) (see Online Resource). The average Ngb concentration across the retina in this simulation is approximately 432 µM, which is larger than the average of $100-200 \,\mu$ M measured in the mouse retina by Schmidt et al. (2003). However, since Ngb is confined to the cytosol (the fluid compartment of cells excluding the nucleus and organelles) of retinal cells, it may be that Ngb could reach an average concentration in the cytosol much greater than 200 μ M, without the average concentration of Ngb across the whole retina exceeding this value. As such, the Ngb concentration in our model should be interpreted as the concentration in the cytosol. It can be seen that the addition of Ngb raises the oxygen profile in the inner retina, increasing the minimum in layer 6 so that it no longer passes beneath the hypoxic threshold, $c = \gamma$. (In this case, our model predicts an average inner retinal oxygen level of 8.5 mmHg, which is within the range of values measured by Birol et al. (2007) in the rhesus monkey.) This corresponds to an increase in the minimum rate of oxygen uptake in the inner retina from 40.1 to 53.3 % of Q_6 , the maximum rate of oxygen uptake in this region (see Eq. (21)).

In Fig. 11 we decrease c_c , c_v , \hat{h}_5 and \hat{h}_7 (the oxygen concentration at the choriocapillaris and in the retinal capillaries, and the permeabilities of the deep and superficial retinal capillaries respectively) so that the outer retina is hypoxic in the absence of Ngb, more closely representing the macaque retina under DA (Birol et al. 2007). It is found that if Ngb is concentrated primarily in the photoreceptor ISs ($L_2 < x < L_3$), then it may prevent outer retinal hypoxia (raising the outer retinal minimum oxygen concentration to 1.1 mmHg, which falls within the range 1.3 ± 0.2 mmHg measured by Yu et al. (2005) in the macaque). This corresponds to an increase in the minimum rate of oxygen uptake in the outer retina from 36.8 to 51.8 % of Q_3 , the maximum rate of oxygen uptake in this region (see Eq. (21)). We remark that the inner retina is hypoxic in both cases since there is insufficient Ngb in this region. In this case, the average concentration of Ngb across the retina is approximately 362 μ M.

There is some variability between measured retinal oxygen distributions, particularly within the inner retina. Therefore, whilst it is beyond the scope of the present

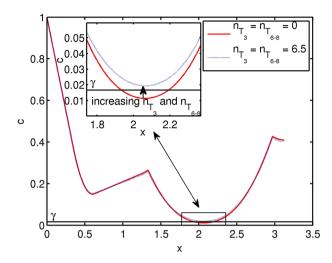


Fig. 10 Simulation results from the eight layer model showing how the presence of Ngb in the inner retinal layers may prevent inner retinal hypoxia under DA. Key: Ngb absent (*solid curve* $n_{T_1} = 0$, i = 1, ..., 8); Ngb present (*dotted curve* $n_{T_1} = n_{T_4} = n_{T_5} = 0.02$, $n_{T_2} = 0$ and $n_{T_3} = n_{T_6} = n_{T_7} = n_{T_8} = 6.50$). Equations (20)–(23) were solved using the FEM with 501 mesh points. Parameter values: $Q_3 = 7.52$. Remaining parameter values as in Tables 2 and 4

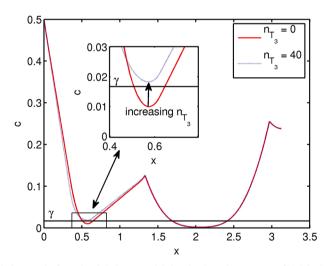


Fig. 11 Simulation results from the eight layer model showing how the presence of Ngb in the photoreceptor ISs may prevent outer retinal hypoxia under DA. Key: Ngb absent (*solid curve* $n_{T_i} = 0, i = 1, ..., 8$); Ngb present (*dotted curve* $n_{T_1} = n_{T_i} = 0.02, n_{T_2} = 0, n_{T_3} = 40, i = 4, ..., 8$). Equations (20)–(23) were solved using the FEM with 501 mesh points. Parameter values: $c_c = 0.5, Q_3 = 7.52, \hat{h}_5 = 2.03, \hat{h}_7 = 4.06$ and $c_v = 0.5$. Remaining parameter values as in Tables 2 and 4

work, we note that a detailed parameter sensitivity analysis would provide a valuable extension, allowing us to determine the range of scenarios under which Ngb is effective in preventing or alleviating hypoxia.

4.2 Numerical solutions to the time-dependent problem: oxygen storage

Simulations were run for both the single and eight layer models to determine the maximum period of time for which Ngb could buffer the retina against hypoxia, following either an increase in the rate of oxygen uptake, Q, or a decrease in the oxygen supply, c_c or c_v (results not shown). It was found that Ngb could prevent hypoxia for no more than a few seconds and hence we conclude that it is unlikely to play a significant role in oxygen storage.

4.3 Asymptotic analysis of the neuroglobin-free problem

In this section we perform an asymptotic analysis of the Ngb-free, steady-state problem, in order to validate the piecewise linear and quadratic approximations to the oxygen profile used by Braun et al. (1995), Cringle and Yu (2002) and others. For this purpose, we consider the parameter values to be of the same order of magnitude as those used in Fig. 9, as these represent standard conditions for the human retina. In the absence of Ngb there is no reason to distinguish between layers 6 and 7, since the purpose of the boundary between these layers was to ensure that Ngb could not pass between them. Therefore, we now group layers 6 and 7 together, labelling this new merged layer, 'layer 6*', and relabel 'layer 8' as 'layer 7*'. The details of the analysis can be found in Appendix 2.

To summarise, we have found that c(x) is quadratic in layers 1, 3, 5 and 7* at leading order, that it is linear in layers 2 and 4, and may be approximated by quadratics in layer 6*. That is,

$$c(x) = \begin{cases} \frac{Q_i x^2}{2} + A_i x + B_i, & \text{for } i \in \{1, 3, 5, 7^*\}, \\ A_i x + B_i, & \text{for } i \in \{2, 4\}, \\ \frac{Q_{6^*}}{2} (L_5 - x)^2 + \sqrt{2Q_{6^*}c_L}(L_5 - x) + c_L, & \text{left-hand, layer } 6^*, \\ \left(1 + \frac{Q_{6^*}(x_{min} - x)^2}{2(\gamma + c_{min})}\right) c_{min}, & \text{central, layer } 6^*, \\ \frac{Q_{6^*}}{2} (x - L_{6^*})^2 + \sqrt{2Q_{6^*}c_R}(x - L_{6^*}) + c_R, & \text{right-hand, layer } 6^*, \end{cases}$$

where x_{min} and c_{min} , the position and size respectively, of the local minimum in layer 6^{*}, are given by Eqs. (66) and (67) respectively in Appendix 2, $c_L = c(L_5)$, $c_R = c(L_{6^*})$ and the A_i s and B_i s are constants of integration. The equations contain 14 unknowns $(A_1 \cdots A_5, A_{7^*}, B_1 \cdots B_5, B_{7^*}, c_L$ and $c_R)$, which can be found by imposing the 14 boundary conditions upon the external and internal boundaries $(c(0) = c_c, c_x(L_{7^*}) = 0$ and the concentration and flux conditions across the internal boundaries

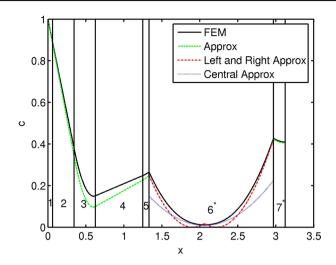


Fig. 12 Comparison of the approximate solution with the FEM solution to the full problem. The approximate solution matches well with the FEM solution, though it is less accurate in layers 3 and 4. The left-hand solution in layer 6* is plotted from $x = L_5$ to $x = x_{min}$, the right-hand solution is plotted from $x = x_{min}$ to $x = L_{6*}$ and the central solution is plotted throughout layer 6*. The spatial extent of the different layers is depicted by the *vertical lines*. Parameter values are the same as those used in Fig. 9 for the dark adapted case

at $x = L_i$, for $i = 1, ..., 6^*$). The approximation is continuous, except within layer 6^{*}, where it is not possible to obtain continuity between the left-hand, central and right-hand approximations. The accuracy of the approximation can be improved using iteration, resulting in slight modifications to the values of some of the unknowns listed above, as described in Appendix 2.

Figure 12 compares the approximate solution with the finite element solution to the full problem using the same parameter values as in Fig. 9 for the dark adapted case. The approximate solution agrees reasonably well with the FEM solution, though it underestimates it, particularly in layers 3 and 4. The approximate value of x_{min} , $x_{min}^{app} = 2.0625$ (4 d.p.), is very close to the FEM value, $x_{min}^{FEM} = 2.0625$ (4 d.p.), with an error of $O(10^{-5})$, whilst the approximate value of c_{min} , $c_{min}^{app} = 0.0091$ (4 d.p.), is less close to the FEM value, $c_{min}^{FEM} = 0.0114$ (4 d.p.), though it is of the same order of magnitude, with an error of $O(10^{-3})$.

This analysis shows that the piecewise linear and quadratic profiles used by Braun et al. (1995), Cringle and Yu (2002) and others are valid, provided the oxygen concentration is O(1) or $O(\varepsilon)$. If the oxygen concentration drops to $O(\varepsilon^2)$, that is, if it becomes hypoxic or near-hypoxic, a quadratic approximation is valid; however, the coefficients of the quadratic are not the same as those based on the assumption of constant oxygen uptake used in the literature. In this case the coefficients must be modified, as outlined above. We also note that when fitting curves to measured oxygen profiles, the value of Q in those layers where $c = O(\varepsilon^2)$ will be underestimated when using a constant oxygen uptake assumption since $c/(\gamma + c)$ is significantly less than unity in these regions.

5 Discussion

The retina is one of the most oxygen hungry tissues in the human body, such that, despite being well vascularised, it is frequently at risk of hypoxia. In this paper we have investigated the part that may be played by the protein Ngb in the prevention of hypoxia, through its roles in oxygen transport and storage.

Single and eight layer models of the retina were derived in one spatial dimension for both the steady-state and time-dependent problems associated with oxygen transport and storage respectively (Sect. 2).

The single layer model is a toy model, such that, whilst it does not capture the complex physiology and cellular compartmentalisation of the retina, it provides a useful starting point for investigating the role of Ngb in oxygen transport and storage for a more generic scenario. Examination of the steady-state single layer model (Sect. 3.1) demonstrated that Ngb acts by removing oxygen from oxygen rich regions and redistributing it to oxygen poor regions, with the potential to eliminate or alleviate hypoxia.

Steady-state solutions of the eight layer model revealed that Ngb may play an important role in oxygen transport in the human retina (Sect. 4.1). Whilst the effect of Ngb on the oxygen profile is subtle, an increase in the oxygen concentration through the hypoxic threshold, γ , may result in a significant increase in the rate of oxygen uptake (as much as 30–40 %) since the Michaelis–Menten curve is steepest in a neighbourhood of $c = \gamma$. It was found that Ngb may prevent inner retinal hypoxia, provided it is sufficiently concentrated in this region. Similarly, if the outer retina is vulnerable to hypoxia, then outer retinal hypoxia may be avoided, provided Ngb is present in sufficient quantities in the photoreceptor ISs.

Whilst our model oxygen profiles may differ from the, as yet unmeasured, human retinal oxygen profiles and whilst there is some inter-individual variability, the eight layer model shows that Ngb could in principle prevent or alleviate hypoxia in the human retina, provided Ngb is appropriately distributed. Detailed measurements of the cytosolic Ngb concentration in different cellular layers of the retina are needed in order to determine whether Ngb is present in the quantities that we suggest are necessary for Ngb to play a significant role in oxygen transport.

We expect Ngb to be most highly concentrated in those layers of the retina that are most vulnerable to hypoxia. This would mean that Ngb distribution would differ between species, as retinal oxygen distribution differs between species, and perhaps within individual eyes, as oxygen supply and demand vary with eccentricity. The most closely related species in which retinal oxygen and Ngb distributions have been measured are the mouse and rat, where it was found that Ngb is indeed most highly concentrated in those regions where oxygen is most scarce (Yu et al. 1994; Schmidt et al. 2003, 2005). Further studies are needed to confirm whether this holds true in other species. The only study to date to examine the relationship between Ngb distribution and eccentricity in the human retina found no differences in the patterns of immunoreactivity for Ngb between the central and peripheral retina (Ostojić et al. 2008); however, this does not exclude the possibility that, whilst Ngb may be present within the same retinal layers across the retina, it may be distributed differently between

those layers for different eccentricities. Further experimental work is required to test this prediction.

We also note that Ngb in one region of the retina can play a protective role in preventing hypoxia in another region, even if Ngb cannot pass between these two regions. This is evident in Fig. 10, where Ngb in layer 7 ($x \in [2.42, 2.97]$) raises the oxygen concentration on the left-hand side of the layer, so that it is at a higher concentration as it enters layer 6, a region vulnerable to hypoxia. Therefore, whilst Bentmann et al. (2005) observe that the distribution of cytoglobin (a protein that has also been proposed to play a role in oxygen transport within the retina, Burmester et al. 2002; Trent and Hargrove 2002) is unrelated to mitochondria distribution and oxygen consumption, this does not imply that cytoglobin cannot play a role in oxygen transport and storage, since it does not need to be colocalised with mitochondria containing regions in order to increase the oxygen supply to these regions. Having said this, the compartmentalisation of Ngb within the retina does reduce its capacity to transport oxygen across the retina, since oxygen-bound Ngb will often meet a barrier before reaching an oxygen poor region where it can deposit its oxygen. In other words, if Ngb is confined within a narrow region across which the drop in oxygen concentration is small, then Ngb will have a less pronounced effect than if allowed to move across a larger region where the drop in oxygen concentration is large and hence across which the drop in Ngb oxygen saturation is large.

Ngb must be present in high concentrations and the duration of unfavourable parameter fluctuations brief in order for Ngb to be of significant benefit in oxygen storage (Sect. 4.2). If there was a scenario in which c_c or Q oscillated on the time scale of a few seconds, and particularly if the periods of recovery were longer than the periods of challenge, then Ngb could prevent or reduce hypoxia to a significant degree (results not shown); however, as far as we are aware, no such scenario exists. Thus, whilst the model parameters may differ between individuals, it is highly unlikely that any situation could obtain in which Ngb could store oxygen on the timescale of minutes to hours that would be necessary for it to play a significant role in the prevention of hypoxia via oxygen storage.

Therefore we conclude that Ngb may play an important role in oxygen transport, but it is unlikely to play an important role in oxygen storage.

The conclusion that Ngb may play an important role in oxygen transport is further supported by our analysis of the simplified single layer model (Sect. 3.2). This demonstrated that Ngb increases the maximum domain length that can be supported under normoxia, x_c , and the minimum oxygen concentration in a normoxic domain, c(L). It was found that the proportional contribution of Ngb to these quantities is larger for lower values of c_c , the oxygen concentration at the choriocapillaris. This is consistent with the idea that Ngb has an important role in oxygen transport, particularly when the oxygen supply is limited.

The analysis also indicated that x_c is maximised for an oxygen affinity of $P_{50,max} = \sqrt{\gamma c_c}$, decreasing sharply as $P_{50} \rightarrow 0$ and decreasing gradually initially as P_{50} increases past its optimum value. This trend was confirmed by the numerical solution to the full problem; however, the P_{50} value for which x_c is maximised was shown to be approximately twice that predicted by the analysis. It is surprising that the optimum P_{50} value should be so high, since it is assumed in the literature that a lower P_{50}

value will result in more efficient oxygen transport. For c_c in the range 20–100 mmHg (the maximum expected range in humans and other mammals), the numerical solution to the full problem predicts that $P_{50,max,numeric} = 9.5 - 17.9 (\pm 2)$ mmHg, whereas a P_{50} corresponding to that of Mb (0.9–2.2 mmHg) is generally thought to be preferable in the literature (see for instance Burmester and Hankeln 2004, 2009). Four of the eight measured values of Ngb P_{50} presented in Table 3 of the Online Resource (relevant P_{50} values in brackets) fall within our predicted range, meaning that the oxygen affinity has the value one would expect if Ngb plays a role in oxygen transport. Therefore, the fact that Ngb has a higher P_{50} value than Mb is advantageous, rather than problematic, for oxygen transport (suggesting that natural selection may have tuned this parameter to its present value). Indeed, given the shallow gradient of the curve in Fig. 8b for $P_{50} > P_{50,max,numeric}$, oxygen transport would remain near-optimal even for P_{50} values significantly higher than $P_{50,max,numeric}$. We note also that these results suggest that the P_{50} value of Ngb may differ between species, varying according to the square root of the average oxygen concentration at the capillaries. Further experimental work is required to test this prediction.

A tractable analytical expression for the P_{50} value which maximises c(L) in a normoxic domain could not be obtained; however, numerical solution with a range of parameter values suggests that the optimal P_{50} value lies consistently above that which optimises x_c , that is above $P_{50,max,numeric}$. This suggests that the overall optimal P_{50} value may lie a little above $P_{50,max,numeric}$.

In addition to illustrating the general principle that Ngb's oxygen transport properties may be optimised for a higher P₅₀ value than that taken by Mb, the scenarios captured by the simplified single layer model may occur at several points in the human retina. For instance, in both layers 3 and 6, the oxygen profile may drop from a normoxic concentration at one end of the layer, to hypoxic levels within the layer, whilst in layer 8, the oxygen concentration remains normoxic across the layer, satisfying a zero-flux boundary condition at $x = L_8$.

Lastly, asymptotic analysis of the steady-state Ngb-free problem (Sect. 4.3) demonstrated that the assumption of a constant rate of oxygen uptake is valid, provided the oxygen concentration is $O(\varepsilon)$ (where $\varepsilon = 0.1$, corresponding to ≈ 6 mmHg), or larger. This places existing models for retinal oxygen distribution on a stronger theoretical foundation. If the oxygen concentration drops to hypoxic or near-hypoxic levels, at $O(\varepsilon^2)$, then the oxygen profile can still be approximated using a quadratic, but the coefficients will be different from those which result from the constant rate of oxygen uptake assumption.

This work could be extended in several ways. The magnitude of the histidine dissociation rate, k_h^- , could be made to vary according to the oxygen concentration, so that Ngb's oxygen affinity decreases in hypoxia and increases in normoxia, to examine the extent to which this enhances the oxygen transport and storage properties of Ngb (see the Online Resource and Hamdane et al. 2003, for details). Models could be developed to examine the potential role of Ngb at other eccentricities within the human retina, or in other species, by adjusting the parameters relating to geometry, oxygen supply and oxygen demand. Also, cytoglobin could be included in the models, to determine whether it significantly augments the oxygen transport and storage properties of Ngb. The model could also be extended to 2D or 3D, and more detailed descriptions of cell metabolism and blood flow incorporated.

In conclusion, although Ngb's transport function results in only a minor shift in the oxygen profile, this can result in a significant rise in oxygen uptake and may be enough to prevent hypoxia if supply and demand are finely balanced. Ngb is unlikely to be important for oxygen storage. Contrary to the prevailing assumption, the fact that Ngb has a higher P_{50} value than Mb is not evidence against its role in oxygen transport, and indeed many of the P_{50} values measured thus far are near optimal for oxygen transport. Finally, the assumption of a piecewise constant rate of oxygen uptake, used in previous studies, is valid, provided oxygen levels do not drop to $O(\varepsilon^2)$.

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Appendix 1: Placing a bound on the concentration of pentacoordinate neuroglobin

It was found in all single and eight layer model simulations that the concentration of pentacoordinate Ngb, n, at any given point in space is significantly lower than that of hexacoordinate Ngb, n_h , or oxygen bound Ngb, n_o , at that point. In this appendix we derive a bound on n to explain why this is the case.

Beginning with the time-dependent equation for n, Eq. (10), we can re-write it in the form

$$\frac{\partial n}{\partial t} = D \frac{\partial^2 n}{\partial x^2} + f(x,t) - \left(\frac{1}{\kappa} + g(x,t)\right)n,\tag{42}$$

where $1/\kappa = k_3$, $f(x, t) = k_4n_h + \alpha k_2n_o \ge 0$ and $g(x, t) = \alpha k_1c \ge 0$. Whether we are using the single or the eight layer model, this equation will be defined on a finite domain, which we can denote as $x \in [0, L]$ without loss of generality. As usual, we impose zero-flux boundary conditions at either end of the domain.

Consider the function M = M(t) which satisfies

$$\frac{\mathrm{d}M}{\mathrm{d}t} = \left(\max_{x,t}(f(x,t)) + \beta\right) - \frac{1}{\kappa}M,\tag{43}$$

where the constant $\beta > 0$ is arbitrarily small. This can be written as

$$\frac{\mathrm{d}M}{\mathrm{d}t} = F - \frac{1}{\kappa}M,\tag{44}$$

where $F = (\max_{x,t} (f(x, t)) + \beta) > f(x, t) \ge 0$ is a constant. We close the system by imposing the initial condition

$$M(0) = \max_{x} (n(x, 0)).$$
(45)

Solving this initial-value problem using the integrating factor method we obtain

$$M(t) = e^{-\frac{t}{\kappa}} M(0) + \kappa F(1 - e^{-\frac{t}{\kappa}}).$$
(46)

Taking the limit as t tends to infinity we find that

$$\lim_{t \to \infty} M(t) = \kappa F. \tag{47}$$

Let u(x, t) := n(x, t) - M(t), then

$$\frac{\partial u}{\partial t} - D \frac{\partial^2 u}{\partial x^2} = (f - F) - \frac{u}{\kappa} - gn, \qquad (48)$$

from Eqs. (42) and (44). Since (f - F) < 0 and $gn \ge 0$ we have that

$$\frac{\partial u}{\partial t} - D \frac{\partial^2 u}{\partial x^2} + \frac{u}{\kappa} < 0, \tag{49}$$

and therefore

$$\frac{\partial}{\partial t} \left(e^{\frac{t}{\kappa}} u \right) - D \frac{\partial^2}{\partial x^2} \left(e^{\frac{t}{\kappa}} u \right) < 0.$$
(50)

Defining $v(x, t) := e^{\frac{t}{\kappa}} u(x, t)$, we have that

$$\frac{\partial v}{\partial t} - D \frac{\partial^2 v}{\partial x^2} < 0, \tag{51}$$

with initial condition

$$v(x,0) = n(x,0) - \max_{x}(n(x,0)),$$
(52)

and zero-flux boundary conditions.

By the maximum principle for parabolic PDEs we have that v must achieve its maximum on one of the boundaries x = 0, x = L or t = 0 (Ockendon et al. 2003). Suppose that v takes its maximum value on x = 0 for some $t = t_1 > 0$. Since $n_x(0, t_1) = 0$ by the zero-flux boundary condition and since $M_x(t_1) = 0$, as M is independent of x, this implies that $u_x(0, t_1) = 0$ and so $v_x(0, t_1) = 0$. Therefore, in order for this point to be a maximum, we require both that $v_t(0, t_1) = 0$ and $v_{xx}(0, t_1) \le 0$. This implies that $v_t(0, t_1) - Dv_{xx}(0, t_1) \ge 0$, which contradicts (51). Therefore, the maximum cannot lie on the boundary x = 0. Using a similar argument we can show that the maximum cannot lie on the boundary x = L. Therefore, the maximum must lie on the boundary t = 0. As a check we can see that if the maximum lies on the boundary t = 0 for some $x = x_1$, where $0 < x_1 < L$, then we must have that $v_t(x_1, 0) \le 0$, $v_x(x_1, 0) = 0$ and $v_{xx}(x_1, 0) \le 0$. Thus (51) may be satisfied, provided $|v_t(x_1, 0)| > D|v_{xx}(x_1, 0)|$.

Since v(x, t) takes its maximum value on t = 0 this means that $v(x, t) \le \max_x(v(x, 0)) = \max_x(n(x, 0) - \max_x(n(x, 0))) = \max_x(n(x, 0)) - \max_x(n(x, 0))$

= 0. Therefore $u \leq 0$, which implies that $n \leq M$. Therefore, by (47), we have that at steady-state $n \leq \kappa F$. Taking the limit as β tends to zero, we find $n \leq \kappa \max_{x,t} (f(x,t)) = \kappa \max_{x,t} (k_4 n_h + \alpha k_2 n_o) \leq \kappa \alpha k_2 n_T = \frac{\alpha k_2 n_T}{k_3} \approx 4 n_T \times 10^{-4}$. This bound was found to be satisfied in all simulations.

Appendix 2: Asymptotic analysis

In the absence of Ngb, Eqs. (21)–(23) reduce to a single equation for oxygen:

$$0 = \frac{\mathrm{d}^2 c}{\mathrm{d}x^2} - \frac{Q_i c}{\gamma + c},\tag{53}$$

for Q_i (1, ..., 7^{*}).

In layers 2 and 4, $Q_2 = Q_4 = 0$, so that an exact analytical solution to Eq. (53) may be obtained. In all other layers, Q_i is strictly positive, so that an exact analytical solution cannot be derived. In these layers we look instead for a leading order solution. Since the value of Q_i is not, in general, continuous between layers, we cannot use standard matching techniques to construct a solution which is valid across all layers. Instead we use patching, ensuring that the solution in each layer satisfies the boundary conditions between it and the adjoining layers (see Bender and Orszag 1999, pgs. 335–336 for a discussion of patching).

We construct an asymptotic expansion for c(x):

$$c(x) \sim c_0(x) + \varepsilon c_1(x) + O(\varepsilon^2), \tag{54}$$

choosing $\varepsilon = 0.1$, so as to provide a clear separation between the various scales, and introduce $\gamma^* = \varepsilon^{-2}\gamma$ so that $\gamma^* = O(1)$. We also note that $Q_i = O(1)$ for $i \in \{1, 3, 5, 6^*, 7^*\}$ and that $Q_2 = Q_4 = 0$. Applying the scaling on γ , Eq. (53) becomes

$$0 = \frac{\mathrm{d}^2 c}{\mathrm{d}x^2} - \frac{Q_i c}{\varepsilon^2 \gamma^* + c}.$$
(55)

We now consider the leading order solution to Eq. (55) within each layer, grouping layers that have the same scaling.

Layer 1

In layer 1, c = O(1), as can be seen in Fig. 9, and Eq. (55) supplies, at leading order,

$$c(x) \sim c_0(x) = \frac{Q_1 x^2}{2} + A_1 x + B_1,$$
(56)

where A_1 and B_1 are constants.

Layers 2 and 4

In layers 2 and 4, $Q_2 = Q_4 = 0$, so that Eq. (55) can be solved exactly to yield

$$c(x) = A_i x + B_i, \tag{57}$$

for i = 2, 4, where A_i and B_i are constants.

Layers 3, 5 and 7*

In layers 3, 5 and 7^{*}, $c = O(\varepsilon)$, as can be seen in Fig. 9. Rescaling oxygen as $c = \varepsilon c^*$, we then rescale x as $x = \varepsilon^{1/2} x_i^* + L_{i-1}$ in order to achieve a dominant balance, so that, after returning to our original scaling on c and x we have, at leading order,

$$c(x) \sim \frac{Q_i x^2}{2} + A_i x + B_i, \tag{58}$$

for $i \in \{3, 5, 7^*\}$, where A_i and B_i are constants.

Layer 6*

The situation in layer 6^{*} is less straightforward. On the left- and right-hand sides of layer 6^{*}, $c = O(\varepsilon)$, whereas, toward the centre of the layer, in a neighbourhood around the local minimum, $c = O(\varepsilon^2)$. Where $c = O(\varepsilon)$, we could scale *c* and *x* as in layers 3, 5 and 7^{*}; however, in the central region, where $c = O(\varepsilon^2)$, we would regain Eq. (53) in the dominant balance after dropping the stars. Since seeking leading order solutions does not allow us to avoid dealing with Eq. (53), we instead retain Eq. (53) across the whole of layer 6^{*} and use quadrature methods to derive approximate analytical solutions for the oxygen profile in this layer.

We will derive separate approximations to the oxygen profile for the left-hand side, centre and right-hand side of layer 6^{*}, in order to account for the variation in *c* between $O(\varepsilon)$ and $O(\varepsilon^2)$. We will also derive approximations to the minimum oxygen concentration in layer 6^{*}, c_{min} , and its position, x_{min} .

Multiplying Eq. (53) by dc/dx and integrating between x_{min} and x, we find that

$$\frac{\mathrm{d}c}{\mathrm{d}x} = \pm \sqrt{2Q_{6^*}} \sqrt{c - c_{min} - \gamma \log\left(\frac{\gamma + c}{\gamma + c_{min}}\right)},\tag{59}$$

where we take the positive (negative) root to the right (left) of x_{min} , since the gradient of the oxygen profile is positive (negative) there. We note that the values of c_{min} and x_{min} are unknown at this stage.

We begin by seeking the left-hand and right-hand approximations near L_5 and L_{6*} respectively. For the left-hand approximation, we integrate Eq. (59) between x and L_5

to obtain

$$\int_{c(x)}^{c_L} \left(s - c_{min} - \gamma \log\left(\frac{\gamma + s}{\gamma + c_{min}}\right) \right)^{-\frac{1}{2}} \mathrm{d}s = \sqrt{2Q_{6^*}}(x - L_5), \tag{60}$$

where $c_L = c(x = L_5)$ is unknown at this stage. Since $c \approx c_L$ in the left-hand region, where $c_L = O(\varepsilon)$, and since $c_{min} = O(\varepsilon^2)$ and $\gamma = O(\varepsilon^2)$ (see Fig. 9 for values of c_L and c_{min}), we may approximate the integrand by $s^{-\frac{1}{2}}$ to obtain the left-hand approximation as

$$c(x) \approx \frac{Q_{6^*}}{2} (L_5 - x)^2 + \sqrt{2Q_{6^*}c_L}(L_5 - x) + c_L.$$
(61)

In a similar way, we obtain the right-hand approximation:

$$c(x) \approx \frac{Q_{6^*}}{2} (x - L_{6^*})^2 + \sqrt{2Q_{6^*}c_R} (x - L_{6^*}) + c_R, \tag{62}$$

where $c_R = c(x = L_{6^*})$ is unknown at this stage. Both c_L and c_R may be found by applying the boundary conditions as described at the end of this section.

To derive the central approximation, valid in the neighbourhood of x_{min} , we integrate Eq. (59) between x_{min} and x. Writing $\log((\gamma + s)/(\gamma + c_{min})) = \log(1 + (s - c_{min})/(\gamma + c_{min}))$, we expand the integrand (which is the same as in Eq. (60)) about $s = c_{min}$, in powers of $(s - c_{min})/(\gamma + c_{min})$, where s is the variable of integration and $|(s - c_{min})/(\gamma + c_{min})| \ll 1$. Retaining only the first term and neglecting higher order terms, we obtain the central solution:

$$c(x) \approx \left(1 + \frac{Q_{6^*}(x_{min} - x)^2}{2(\gamma + c_{min})}\right) c_{min},$$
 (63)

in which x_{min} and c_{min} are presently unknown.

To determine x_{min} , we integrate Eq. (59) between the limits x_{min} and L_5 , and x_{min} and L_{6^*} , to obtain the following pair of equations:

$$\int_{c_{min}}^{c_L} \left(s - c_{min} - \gamma \log \left(\frac{\gamma + s}{\gamma + c_{min}} \right) \right)^{-\frac{1}{2}} \mathrm{d}s = \sqrt{2Q_{6^*}} (x_{min} - L_5), \quad (64)$$

$$\int_{c_{min}}^{c_R} \left(s - c_{min} - \gamma \log \left(\frac{\gamma + s}{\gamma + c_{min}} \right) \right)^{-\frac{1}{2}} \mathrm{d}s = \sqrt{2Q_{6^*}} (L_{6^*} - x_{min}).$$
(65)

Subtracting Eq. (64) from Eq. (65), and noting that $\min(c_L, c_R) < s < \max(c_L, c_R)$ in the integrand, where $c_L = O(\varepsilon)$, $c_R = O(\varepsilon)$, $c_{min} = O(\varepsilon^2)$ and $\gamma = O(\varepsilon^2)$ (see Fig. 9 for values of c_L , c_R and c_{min}), we may approximate the integrand by $s^{-\frac{1}{2}}$ to obtain

$$x_{min} \approx \frac{L_5 + L_{6^*}}{2} - \left(\frac{\sqrt{c_R} - \sqrt{c_L}}{\sqrt{2Q_{6^*}}}\right).$$
 (66)

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We obtain an implicit expression for c_{min} , by substituting for x_{min} from Eq. (66) into Eq. (64):

$$\int_{c_{min}}^{c_L} \left(s - c_{min} - \gamma \log \left(\frac{\gamma + s}{\gamma + c_{min}} \right) \right)^{-\frac{1}{2}} \mathrm{d}s$$
$$\approx \sqrt{\frac{Q_{6^*}}{2}} (L_{6^*} - L_5) - (\sqrt{c_R} - \sqrt{c_L}), \tag{67}$$

where the integral must be calculated numerically. With x_{min} and c_{min} specified by (66) and (67) respectively, we can use Eq. (63) to calculate the central solution.

Using iteration to improve accuracy

We can iteratively improve the accuracy of our approximation using the exact derivative, given by Eq. (59), in the oxygen-flux boundary conditions at $x = L_{6^*}$ and $x = L_{7^*}$, given by Eq. (20), to yield:

$$0 = \sqrt{2Q_{6^*}} \sqrt{c_L - c_{min} - \gamma \log\left(\frac{\gamma + c_L}{\gamma + c_{min}}\right)} + (Q_5 L_5 + A_5(c_L)) - \hat{h}_5(c_v - c_L),$$

$$0 = \sqrt{2Q_{6^*}} \sqrt{c_R - c_{min} - \gamma \log\left(\frac{\gamma + c_R}{\gamma + c_{min}}\right)} + Q_{7^*}(L_{7^*} - L_{6^*}) - \hat{h}_{6^*}(c_v - c_R).$$
(69)

The constant c_{min} takes the value calculated by solving (67), using the original values of c_L and c_R , whilst the constant A_5 is a function of c_L , given by:

$$A_5(c_L) = \frac{1}{L_5} \left[c_L - c_c - \frac{1}{2} \left(Q_5(L_5^2 + L_4^2) + Q_3(L_2^2 - L_3^2) - Q_1L_1^2 \right) \right].$$
(70)

Equations (68)–(69) can be solved numerically, using the Matlab routine fsolve, to find updated values for c_L and c_R . The updated c_L and c_R can then be used to calculate an updated value for c_{min} , using Eq. (67). We may then repeat the iteration, using the updated value of c_{min} in Eqs. (68)–(70), to find new values for c_L and c_R . Once the solution has converged, the final values of c_L and c_R can then be used to calculate improved values for $A_1, \ldots, A_5, B_{7^*}, x_{min}$ and c_{min} , by applying the boundary conditions to Eq. (41) as described in Sect. 4.3 and using Eqs. (66) and (67).

It was found that iteration results in a small improvement in the accuracy of the approximation and that the solution does not change significantly (by $O(10^{-4})$ or

greater) after the third iteration. Therefore, we use the parameters generated by the third iteration for the approximate solution in Sect. 4.3.

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