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Integral Equations and Operator Theory



Uni-asymptotic Linear systems and Jacobi Operators

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Abstract. A family $\{U_s\}_{s\in S}$ of bounded linear operators in a normed space X is *uni-asymptotic*, when all its trajectories $\{U_sx\}_{s\in S}$ with $x \neq 0$ have the same norm-asymptotic behavior (see 1.5); $\{U_s\}_{s\in S}$ is *tight*, when the operator norm and the minimal modulus of U_s have the same asymptotic behavior (see 1.6). We prove that uni-asymptoticity is equivalent to tightness if dim $X < +\infty$, and that the finite dimension is essential. Some other conditions equivalent to uni-asymptoticity are provided, including asymptotic formulae for the operator norm and for the trajectories, expressed in terms of determinants det U_s (see Theorem 1.7). We find a connection of these abstract results with some results and notions from spectral theory of Jacobi operators, e.g., with the *H*-class property for transfer matrix sequence.

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0. Introduction

Many mathematical models describing "real" processes are built on the basis of some families of operators. Typically, when we want to define a dynamical system—a mathematical model for time dynamics of a real process, we try to find a family $\{U_s\}_{s\in S}$ of operators $U_s : X \longrightarrow X$, which "codes the process mathematically". Then $\{U_s\}_{s\in S}$ has the following "real" interpretation:

If the initial state of the process was $x \in X$, then the state of the process at the time moment $s \in S$ is $U_s x$.

¹In this paper we identify indexed family $\{f_s\}_{s \in S}$ with the function on S given by: $S \ni s \longmapsto f_s$.

Above S represents the set of "admissible moments of time", and X—the set of "admissible states" for the process. Hence, in this paper, for fixed $x \in X$, we use the name *trajectory* (or *orbit*), when we consider the family $\{U_sx\}_{s\in S}$ of elements of X, obtained by a family $\{U_s\}_{s\in S}$ of operators. Let us stress, however, that the actual role of the mathematical objects X, S, $\{U_s\}_{s\in S}$ and $\{U_sx\}_{s\in S}$ can be essentially different than their typical role as above—that is, as in mathematical descriptions of some real processes, e.g, in physics etc. As we shall see in Sect. 2 (see 2.28), those objects can be also useful for mathematical description of some "purely mathematical" processes for purely mathematical goals.

In this paper we consider only the *linear case*, i.e., X is a Banach space here and all the operators U_s are linear (and we shall mainly assume finite dimension of X). However, some notions introduced here have also sense in non-linear case, and they could be worth future research.

Section 1 is devoted to some abstract studies of so-called *uni-asymptotic* families of operators, i.e., such families $\{U_s\}_{s\in S}$ that all its non-zero trajectories $\{U_sx\}_{s\in S}$ have "the same norm-asymptotic behavior". This precisely means, that for any non-zero initial conditions $x, y \in X$ we have

$$\|U_s x\| \asymp_s \|U_s y\|$$

(see 0.3). Although the word "asymptotic" may not fit well to the above definition for the general S, it makes sense for some ordered S-s, e.g., for $S = \mathbb{N}_{n_0}$ (see 0.1). The name "uni-asymptotic" is used also for linear spaces consisting of some functions $f = \{f(s)\}_{s \in S}$ from S into X, with a natural analogic meaning.

This section contains the main results of the paper—Theorems 1.5 and 1.7 on some equivalent conditions for uni-asymptoticity in finite dimension. One of the most important observations is that the uni-asymptoticity is equivalent to tightness, where $\{U_s\}_{s\in S}$ is *tight*, when the operator norm and the minimal modulus of U_s have the same asymptotic behavior (see 1.6). Examples showing the necessity of the dim $X < \infty$ assumption are also provided. They show as well, that the apparent similarity of the problem to the Banach–Steinhaus theorem is misleading. Another equivalent condition are asymptotic formulae for each non-zero trajectory and for the operator norm $||U_s||$, expressed in terms of determinants det U_s (see (ii), (iii) in Theorem 1.7). This seems to be a simple and, at the same time, unknown result, with a potentially wide application.

Section 2 is an illustration of the above abstract results. It helps in better understanding of some spectral results for Jacobi operators (matrices). Here each U_s , for $s \in S := \mathbb{N}_2$, is an appropriate product (see 2.28) of the so-called *transfer matrices* for Jacobi operator J in infinite dimensional Hilbert space $l^2(\mathbb{N})$. We consider also a more general case—so-called block Jacobi operator, where the Hilbert space is $l^2(\mathbb{N}, \mathbb{C}^d)$ with any $d \geq 1$. The dimension of X is 2 for "classical" (scalar) Jacobi case, and $X = \mathbb{C}^{2d}$ in block Jacobi case, so it has nothing to do with the infinite dimension of the Hilbert space. The trajectories are nearly related to generalized eigenvectors of Jacobi operator J—namely, they are so-called 2d - generalized eigenvectors². We show here that the uni-asymptoticity of $\{U_n\}_{n \in \mathbb{N}_2}$ is just equivalent to the well-known H-class property of the transfer matrix family, and we describe the asymptotic behaviour of the norms of the vector terms of the above "eigenvectors", when the H-class property holds—see Theorem 2.7. It is expressed in a simple way by the determinants of the weight terms for J (see 2.29). Such a behaviour of the norms of the vector terms for the scalar d = 1 case was described before (without using the name H-classs) by some authors—see e.g. [12]. Note also, that thanks to subordination theory [5], the uni-asymptoticity of the set of 2-generalized eigenvectors (for the scalar case d = 1) is closely related to the absolute continuity of J—see Theorem 2.5.

0.1. Notation

We introduce here some notation used in the paper. The remaining notation is introduced "locally". Let us denote:

$$\mathbb{C}_* := \{ z \in \mathbb{C} : z \neq 0 \}, \ R_+ := \{ t \in \mathbb{R} : t > 0 \}, \ \mathbb{N}_{n_0} := \{ n \in \mathbb{Z} : n \ge n_0 \}.$$
(0.1)

For an arbitrary set S and $f, g: S \longrightarrow \mathbb{C}$ we define:

$$f \prec g \iff \exists_{C \in \mathbb{R}_+} \forall_{s \in S} |f(s)| \le C|g(s)|;$$
 (0.2)

$$f \asymp g \iff \exists_{c,C \in \mathbb{R}_+} \forall_{s \in S} \ c|g(s)| \le |f(s)| \le C|g(s)|,$$
 (0.3)

i.e., $f \asymp g$ iff $(f \prec g \text{ and } g \prec f)$. We shall use also alternative notations:

$$f(s) \prec g(s), f(s) \prec_s g(s), f(s) \underset{s \in S}{\prec} g(s)$$

and analogically for the \approx symbol.

Let X be a (real or complex) normed space with the norm || ||, and suppose that dim X > 0. As usual, the same symbol || || is used here also for the operator norm in the space of bounded linear operators $\mathcal{B}(X)$ —i.e. $||A|| := \sup_{\|x\|=1} ||Ax\|$ for $A \in \mathcal{B}(X)$. We denote:

$$X_* := \{ x \in X : x \neq 0 \},$$

$$\mathbb{S}_X := \{ x \in X : ||x|| = 1 \},$$

$$\mathcal{B}_*(X) := \{ A \in \mathcal{B}(X) : \operatorname{Ker}(A) = \{ 0 \} \}.$$

We shall use also the symbol $\Downarrow \Downarrow$ for the so-called *minimum modulus*³ of A:

$$\Downarrow A \Downarrow := \inf_{\|x\|=1} \|Ax\|.$$

Recall that if $A \in \mathcal{B}_*(X)$ and $\operatorname{Ran}(A) = X$, then

$$\|A^{-1}\| = \Downarrow A \Downarrow^{-1}, \tag{0.4}$$

which covers also the case of $||A^{-1}|| = +\infty$ with the convention $0^{-1} := +\infty$.

²The name \mathbb{C}^2 -vector-generalised eigenvector was also used for d = 1—see, e.g., [10]

³Note that it is equall to the minimal s-number of A. And it is **not** a norm in $\mathcal{B}(X)$, if dim X > 1.

1. Uni-asymptotic Results for Abstract Linear Systems

1.1. Uni-asymptoticity and Tightness

Consider an "abstract" family $\{U_s\}_{s\in S}$ of bounded linear operators in a normed space X, where S is a non-empty "index" set. Typically $S = \mathbb{N}$ or \mathbb{N}_{n_0} for some "starting index" n_0 , however the cardinality as well as any extra structure of S is not important now. Let us recall again, that any indexed family $\{\text{object}_s\}_{s\in S}$ is identified here with the function on S acting by the formula: " $s \ni S \mapsto \text{object}_s$ ").

We distinguish several specific properties of such operator families. The main notion for us is here the *uni-asymptoticity*.

Definition 1.1. Let $\{U_s\}_{s\in S}$ be a family of operators from $\mathcal{B}(X)$.

• $\{U_s\}_{s\in S}$ is uni-asymptotic iff

$$\forall_{x,y\in X_*} \quad \|U_s x\| \asymp_s \|U_s y\|; \tag{1.5}$$

• $\{U_s\}_{s\in S}$ is tight iff

$$\Downarrow U_s \Downarrow \asymp_s \|U_s\|. \tag{1.6}$$

The name "uni-asymptotic" will be used here also in somewhat different situation—for some sets F of functions $f = \{f(s)\}_{s \in S}$ from S into X. Let \mathbb{O} be the constant 0-vector function on S.

Definition 1.2. Let F be a set of some functions from S into X. F is *uni-asymptotic* iff

$$\forall_{f,g\in F\setminus\{\mathbb{O}\}} \quad \|f(s)\| \asymp_s \|g(s)\|. \tag{1.7}$$

These two kinds of "uni-asymptoticity" are closely related. For a family $\{U_s\}_{s\in S}$ of operators from $\mathcal{B}(X)$ consider the set of all its trajectories (orbits):

Orb
$$(\{U_s\}_{s\in S}) := \{\{U_s x\}_{s\in S} : x \in X\}.$$

By the linearity of the operators, Orb $({U_s}_{s\in S})$ is also a linear subspace of the space of all the functions from S into X. By the above definitions we immediately get:

Fact 1.3. $\{U_s\}_{s\in S}$ is uni-asymptotic iff $\operatorname{Orb}(\{U_s\}_{s\in S})$ is uni-asymptotic.

Let us also note the following properties of families of operators.

Fact 1.4. Let $\{U_s\}_{s \in S}$ be a family of operators from $\mathcal{B}(X)$.

1. $\{U_s\}_{s\in S}$ is uni-asymptotic iff

$$\forall_{x,y\in\mathbb{S}_X} \quad \|U_s x\| \prec_s \|U_s y\|; \tag{1.8}$$

- 2. If $\{\lambda_s\}_{s\in S}$ is a family of non-zero numbers and $\{V_s\}_{s\in S} := \{\lambda_s U_s\}_{s\in S}$, then $\{U_s\}_{s\in S}$ is uni-asymptotic iff $\{V_s\}_{s\in S}$ is uni-asymptotic; $\{U_s\}_{s\in S}$ is tight iff $\{V_s\}_{s\in S}$ is tight;
- 3. If $\{U_s\}_{s\in S}$ is uni-asymptotic, then

$$\forall_{s\in S} \quad (U_s \in \mathcal{B}_*(X) \quad or \quad U_s = 0); \tag{1.9}$$

4. If $\{U_s\}_{s\in S}$ is tight, then it is uni-asymptotic.

Proof. The parts 1. and 2. are obvious. To prove the part 3. suppose that $\{U_s\}_{s\in S}$ is uni-asymptotic and $U_s \notin \mathcal{B}_*(X)$ for some $s \in S$. So, let $0 \neq x_0 \in \text{Ker}U_s$. Then for any $x \in X_*$ we have $||U_sx|| \leq C_x ||U_sx_0|| = 0$ for some $C_x \in \mathbb{R}_+$, i.e., $U_s = 0$. To get the part 4. suppose that $\{U_s\}_{s\in S}$ is tight and choose $C \in \mathbb{R}_+$ such that $||U_s|| \leq C \ U_s \downarrow$ for any $s \in S$. For $x, y \in \mathbb{S}_X$ and for any $s \in S$ we have

$$|U_s x|| \le ||U_s|| \le C \quad ||U_s y|| \le C ||U_s y||,$$

i.e., by the part 1., $\{U_s\}_{s\in S}$ is uni-asymptotic.

The main result of this part says that in the finite dimensional case the above point 4. can be essentially strengthened.

Theorem 1.5. Suppose that dim $X < +\infty$ and $\{U_s\}_{s \in S}$ is a family of operators from $\mathcal{B}(X)$. Then $\{U_s\}_{s \in S}$ is uni-asymptotic iff it is tight.

Proof. By Fact 1.4.4. it suffices to prove " \Longrightarrow ". We include some remarks in this proof, showing whether the dim $X < +\infty$ assumption is important or not for the actual part of the proof. Suppose that $\{U_s\}_{s\in S}$ is uni-asymptotic. Consider first the special case with extra assumption that $U_s \in \mathcal{B}_*(X)$ for any $s \in S$. So, choosing an arbitrary $x_0 \in X_*$ we can define a "rescaling number" $\lambda_s := \|U_s x_0\|^{-1} \neq 0$ for each $s \in S$. By Fact 1.4.2. it suffices to prove that $\{V_s\}_{s\in S} := \{\lambda_s U_s\}_{s\in S}$ is tight. However, observe that

$$\forall_{s\in S} \|V_s x_0\| = \|\lambda_s U_s x_0\| = \lambda_s \|U_s x_0\| = 1, \tag{1.10}$$

and, also by Fact 1.4.2., $\{V_s\}_{s \in S}$ is uni-asymptotic. So applying this for any vector $x \in X_*$ and for $y = x_0$, let us choose $c_x, C_x \in \mathbb{R}_+$ such that

$$\forall_{s \in S} \ c_x = c_x \|V_s x_0\| \le \|V_s x\| \le C_x \|V_s x_0\| = C_x.$$
(1.11)

Hence, in particular, the family $\{V_s\}_{s\in S}$ is bounded in $\mathcal{B}(X)$ (as follows e.g. from Banach–Steinhaus theorem, but here it is an even more elementary fact, because dim $X < +\infty$)—so, choose $C \in \mathbb{R}_+$ such that

$$\forall_{s\in S} \|V_s\| \le C. \tag{1.12}$$

We shall prove now, that there exists $\epsilon \in \mathbb{R}_+$ such that $\epsilon \leq \Downarrow V_s \Downarrow$ for any $s \in S$. Suppose, that it is not true. Thus, there exists a sequence $\{s_n\}_{n\geq 1}$ of indices from S such that $\Downarrow V_{s_n} \Downarrow \longrightarrow 0$. For each $n \in \mathbb{N}$ choose v_n in X with $||v_n|| = 1$, such that

$$\|V_{s_n}v_n\| \le \frac{3}{2} \quad \forall V_{s_n} \Downarrow . \tag{1.13}$$

 $(\frac{3}{2}$ can be replaced by 1, by dim $X < +\infty$, but this constant has no importance). We have

$$\|V_{s_n}v_n\| \longrightarrow 0. \tag{1.14}$$

It is only now, that we will essentially use the dim $X < +\infty$ assumption: we choose a convergent subsequence $\{v_{k_n}\}_{n\geq 1}$ of $\{v_n\}_{n\geq 1}$, i.e., $k_n \longrightarrow +\infty$ and $||v_{k_n} - v|| \longrightarrow 0$ for some $v \in X$ with ||v|| = 1. But by (1.12) and (1.11)

$$\begin{aligned} \|V_{s_{k_n}}v_{k_n}\| &= \|V_{s_{k_n}}v + V_{s_{k_n}}(v_{k_n} - v)\| \ge \|V_{s_{k_n}}v\| - \|V_{s_{k_n}}(v_{k_n} - v)\| \\ &\ge c_v - C\|v_{k_n} - v\| \longrightarrow c_v, \end{aligned}$$

but $c_v > 0$, hence we get a contradiction with (1.14). This finishes the proof of the special case.

Now, we go back to the general case, and we define $S_1 := \{s \in S : U_s \in \mathcal{B}_*(X)\}$ and $S_2 := S \setminus S_1$. By Fact 1.4.3. we have $\Downarrow U_s \Downarrow = 0 = ||U_s||$ for any $s \in S_2$, i.e., $\Downarrow U_s \Downarrow \asymp_{s \in S_2} ||U_s||$. But also $\Downarrow U_s \Downarrow \asymp_{s \in S_1} ||U_s||$ by the special case just proven, so finally $\Downarrow U_s \Downarrow \asymp_{s \in S} ||U_s||$.

The finite dimension assumption was important not only for the above proof. The assumption that X is a Banach space is **not sufficient**.

Example 1.6. Consider $S = \mathbb{N}$ and for any $s \in S$ define $F_s : \mathbb{N} \longrightarrow \mathbb{R}$ by

$$F_s(k) := \begin{cases} s - (k - 1) & \text{for } k \le s \\ 1 & \text{for } k > s. \end{cases}$$
(1.15)

In particular we have

$$F_s(1) = s, \quad F_s(s) = 1 \quad \text{and} \quad 1 \le F_s(k) \le s \quad \text{for any} \quad k \in \mathbb{N}.$$
 (1.16)

Consider now some $p \in [1; +\infty)$ and the space $X := \ell^p = \ell^p(\mathbb{N})$ of "power *p*-summable" sequences. Let us study the family $\{U_s\}_{s\in S}$, where U_s is the multiplication by F_s operator in X, i.e., $U_s x := F_s \cdot x$ for any sequence $x \in X$ and any $s \in S$. By (1.16)

$$||U_s|| = \sup_{k \in \mathbb{N}} |F_s(k)| = s, \qquad \forall U_s \Downarrow = \inf_{k \in \mathbb{N}} |F_s(k)| = 1.$$
 (1.17)

For each x with ||x|| = 1 fix some $k_0 := k_0(x)$ such that $|x_{k_0}| > 0$. Then again by (1.16), for such x and for any $s < k_0$ we have

$$||U_s x|| \ge |x_{k_0}| = \frac{|x_{k_0}|}{s} \cdot s \ge \frac{|x_{k_0}|}{k_0} \cdot s.$$

On the other hand, if $s \ge k_0$, then by (1.15)

$$||U_s x|| \ge (1+s-k_0)|x_{k_0}| = \frac{1+s-k_0}{s}|x_{k_0}| \cdot s \ge \frac{|x_{k_0}|}{k_0} \cdot s,$$

because for $s \ge k_0$ we have $\frac{1+s-k_0}{s} = 1 - \frac{k_0-1}{s} \ge 1 - \frac{k_0-1}{k_0} = \frac{1}{k_0}$. Finally, if ||x|| = 1, then

$$\|U_s x\| \ge \frac{|x_{k_0}|}{k_0} \cdot s$$

holds for any $s \in \mathbb{N}$. But by (1.16) we also have $||U_s x|| \leq s ||x|| = s$. Hence

$$||U_s x|| \asymp_s s.$$

Thus $\{U_s\}_{s\in S}$ is uni-asymptotic, but (1.17) shows that it is not tight. Note also, that the same arguments work also for the similar example with $X = \ell^{\infty}$ —the standard space of bounded sequences.

1.2. Uni-asymptoticity and Determinants

We find here the "actual size" of the norms of the vectors from the trajectories for the uni-asymptotic finite dimensional case. It is described in a simple way by the determinants of the operators U_s .

Theorem 1.7. If dim $X = m \in \mathbb{N}$ and det $U_s \neq 0$ for any $s \in S$, then $TFCAE^4$

- (i) $\{U_s\}_{s \in S}$ is uni-asymptotic
- (ii) $\forall_{x \in X_*} \|U_s x\| \asymp_s |\det U_s|^{1/m}$ (iii) $\|U_s\| \asymp_s |\det U_s|^{1/m}$
- (iii') $||U_s|| \prec_s |\det U_s|^{1/m}$
- (iv) $\{U_s\}_{s\in S}$ is tight.

We shall use the following simple lemma in the proof of this result.

Lemma 1.8. If dim $X = m \in \mathbb{N}$, then:

- 1. $\forall_{U \in \mathcal{B}(X)} \quad \Downarrow U \Downarrow \leq |\det U|^{1/m} \leq ||U||,$
- 2. there exists a positive constant C_m such that

$$\forall_{U \in \mathcal{B}_*(X)} \quad ||U^{-1}|| \le C_m \frac{||U||^{m-1}}{|\det U|},$$

3. for any fixed linear base $e := \{e_i\}_{i=1,\dots,m}$ of X consisting of norm-one vectors, the formula

 $||U||_e := \max\{||Ue_j|| : j = 1, \dots, m\}, \quad U \in \mathcal{B}(X),$

defines a norm in $\mathcal{B}(X)$, and there exists a positive constant D_e such that

$$\forall_{U\in\mathcal{B}(X)} \quad \|U\|_e \le \|U\| \le D_e \|U\|_e.$$

Proof. Let $\lambda_1, \ldots, \lambda_m$ be all the eigenvalues of U (taking into account their algebraic multiplicities) and for each $j = 1, \ldots, m$ let x_j be some normalized eigenvector for U and λ_i . By the definitions of $\| \|$ (—the operator norm) and $\Downarrow \Downarrow$, we have

$$||U|| \le ||Ux_j|| = |\lambda_j| = ||Ux_j|| \le ||U||, \quad j = 1, \dots, m.$$

Now, multiplying all the *m* inequalities "side-by-side" and using det U = $\lambda_1 \cdot \ldots \cdot \lambda_m$, we get part 1. of the lemma.

To get part 2. consider first m by m scalar matrices. Observe, that defining $||A||_{\max} := \max\{|A_{ij}| : i, j = 1, \dots, m\}$ for any matrix A (here A_{ij}) is the term of A from *i*-th row and *j*-th column) we get a certain norm in the matrix space. By Cramer's rule, if A is invertible, then $(A^{-1})_{ij} = \frac{(A_C)_{ji}}{\det A}$, where A_C denotes the matrix of cofactors of A. Applying "the permutation formula" for the determinant to the terms of A_C , we get

$$|(A_C)_{ji}| \le (m-1)! (||A||_{\max})^{m-1}.$$

Hence $||A^{-1}||_{\max} \leq (m-1)! \frac{(||A||_{\max})^{m-1}}{|\det A|}$ for any invertible A. Now, fixing a linear base in X to establish a linear isomorphism between $\mathcal{B}(X)$ and m by m

⁴The following conditions are (mutually) equivalent.

scalar matrix space, we use it to transfer $\| \|_{\max}$ onto a norm in $\mathcal{B}(X)$. Finally, the equivalence of any two norms for $\mathcal{B}(X)$ (it is a m^2 -dimensional space) proves the assertion of part 2. Note that we have used here also det $U = \det A$ for A being the matrix of U for the fixed base.

To obtain part 3., we first easily check that $\| \|_e$ satisfies all the conditions for norm. Then the estimate $\|U\|_e \leq \|U\|$ follows just from the fact that the norm on the RHS is the operator norm and that the base vectors have been normalized. The second estimate with some constant D_e follows just again from the equivalence of all the norms for $\mathcal{B}(X)$.

Proof of Theorem 1.7. Observe that "(iii) \implies (iii')" follows directly from Lemma 1.8.1. Let us prove "(ii) \iff (iii)". Suppose (ii). By Lemma 1.8.3. and by (ii) used to all the *m* vectors of a fixed normalized base *e* we get

$$||U_s|| \le C ||U_s||_e \le C' |\det U_s|^{1/n}$$

for any $s \in S$ with some constants C, C'. Hence, using also Lemma 1.8.1., we get (iii). Now, we suppose (iii) and let $x \in X_*$. We thus have

$$||U_s x|| \le ||x|| ||U_s|| \le ||x|| C |\det U_s|^{1/m}$$

for any $s \in S$ with some constant C. To get the "opposite direction" estimate, we can assume that ||x|| = 1. Then by Lemma 1.8.2. for any $s \in S$ we have

$$1 = ||x|| = ||(U_s)^{-1}U_s x|| \le ||U_s x|| ||(U_s)^{-1}|| \le C_m ||U_s x|| \frac{||U_s||^{m-1}}{|\det U_s|},$$

and by (iii), for some constant C' > 0 and for any $s \in S$

$$||U_s x|| \ge (C_m)^{-1} \frac{|\det U_s|}{||U_s||^{m-1}} \ge C' \frac{|\det U_s|}{\left(|\det U_s|^{1/m}\right)^{m-1}} = C' |\det U_s|^{1/m},$$

and (ii) is proved.

By Theorem 1.5 we have also "(i) \iff (iv)", so it suffices to prove "(ii) \implies (i)" and "(iv) \implies (iii)". But the former is obvious by the transitivity of \asymp_s relation, and the latter follows directly from Lemma 1.8.1.

As we could see, there is a lot of equivalent ways to express uniasymptoticity in the finite dimensional case. On the other hand, Example 1.6 shows that none of these ways work for general Banach space X and general family $\{U_s\}_{s \in S}$ cases. Thus the natural **open problem** could be formulated:

To find some equivalent criteria for uni-asymptoticity for some special kinds of familes $\{U_s\}_{s\in S}$ of operators acting in infinite dimensional Banach spaces X. E. g., for discrete semigroups (with $S = \mathbb{N}_0$), for C_0 -semigroups (with $S = [0; +\infty)$) and others.

2. Uni-asymptoticity in Spectral Studies of Jacobi Operators

2.1. Jacobi Operators: Generalized Eigenvectors and 2*d*-generalized Eigenvectors

Let us start from recalling the notions of block Jacobi matrix and operator (see, e.g., [2,6,13] and citations therein) and its particular "scalar" case. Let

 $d \geq 1$ and let $A_1, B_1, A_2, B_2, \ldots$ be $d \times d$ self-adjoint real matrices. We consider the semi-infinite "block-tri-diagonal matrix" of the form:

$$\mathcal{J} = \begin{pmatrix} B_1 & A_1 & & & \\ A_1 & B_2 & A_2 & & \\ & A_2 & B_3 & A_3 & \\ & & A_3 & B_4 & \ddots \\ & & & \ddots & \ddots \end{pmatrix}.$$

 \mathcal{J} is called *block Jacobi matrix*, and in the main case d = 1 it is just *Jacobi matrix* (also: *scalar J. m.*). Sequences $\{A_k\}_{k\geq 1}$, $\{B_k\}_{k\geq 1}$ are called *weight* and *diagonal* sequence, respectively, and here it is assumed that

$$\det A_k \neq 0, \quad k = 1, \dots \tag{2.18}$$

We identify the matrix \mathcal{J} with the formal Jacobi operator \mathcal{J} , acting in the linear space ℓ of **all** the sequences of \mathbb{C}^d -vectors $u = \{u(k)\}_{k\geq 1}$ by the formula:

$$(\mathcal{J}u)(k) := A_{k-1}u(k-1) + B_ku(k) + A_ku(k+1), \quad k \ge 1,$$

where we denote additionally $A_0 := 0, u(0) := 0$ to get also sense of the formula for k = 1. We distinguish here the block Jacobi **matrix** (= formal operator) \mathcal{J} and the block Jacobi operator J—being our main object here. Roughly speaking, J is just "the restriction" of \mathcal{J} to the Hilbert space $\ell^2 = \ell^2(\mathbb{N}, \mathbb{C}^d) := \{u \in \ell : ||u||_{\ell^2} < +\infty\}$ with $||u||_{\ell^2} := \left(\sum_{k=1}^{+\infty} ||u(k)||_{\mathbb{C}^d}^2\right)^{\frac{1}{2}}$ for $u = \{u(k)\}_{k\geq 1} \in \ell$. Precisely (note the different notation: J and \mathcal{J}): $D(J) := \{u \in \ell^2 : \mathcal{J}u \in \ell^2\}$ and $J := \mathcal{J}| D(J)$, i.e., J is the so-called maximal operator for \mathcal{J} in ℓ^2 . It is bounded self-adjoint operator in ℓ^2 , when $\{A_k\}_{k\geq 1}$, $\{B_k\}_{k\geq 1}$ are bounded. But if at least one of $\{A_k\}_{k\geq 1}, \{B_k\}_{k\geq 1}$ is unbounded, then J is unbounded and its self-adjointness may require additional assumptions. Note, that there are several well-known assumption of this kind, e.g., the generalized Carleman condition $\sum_{n=1}^{+\infty} \frac{1}{||A_n|||} = +\infty$ (see [1,6] for some more information related to the self-adjointness problem for block Jacobi operators). So, in particular, if the weight sequence is bounded, then J is always self-adjoint, regardless of whether the diagonal sequence is bounded or not. In the present paper the self-adjoint case of J is most important for us.

Consider now $\lambda \in \mathbb{C}$ and $u \in \ell$.

Definition 2.1. u is a generalized eigenvector of J for λ

iff
$$(\mathcal{J}u)(k) = \lambda u(k), \text{ for } k \ge 2.$$
 (2.19)

We use abbreviation GEV for "generalized eigenvector".

Note that k = 1 is omitted above and we do not require that u is in D(J) (nor in ℓ^2). (2.19) is equivalent to

$$u(k+1) = -A_k^{-1} \left[A_{k-1}u(k-1) + (B_k - \lambda)u(k) \right], \quad k \ge 2, \tag{2.20}$$

which allows to construct easily the unique GEV u (for λ), starting from **any** pair of \mathbb{C}^d vectors u(1), u(2). Denote:

$$GEV(\lambda) := \{ u : u \text{ is a GEV of } J \text{ for } \lambda \}.$$

We have dim $GEV(\lambda) = 2d$. Let us rewrite (2.20) into a \mathbb{C}^{2d} -vector form:

$$x(k+1) = T_k(\lambda)x(k), \qquad k \ge 2,$$
 (2.21)

where

$$x(k) := \begin{pmatrix} u(k-1) \\ u(k) \end{pmatrix} \in \mathbb{C}^{2d}$$
(2.22)

for a sequence u of \mathbb{C}^d -vectors and $T_k(\lambda)$ is the k-th transfer matrix (of the size $2d \times 2d$)

$$T_k(\lambda) := \begin{pmatrix} 0 & I \\ -A_k^{-1}A_{k-1} & A_k^{-1}(\lambda - B_k) \end{pmatrix}.$$
 (2.23)

Hence, if $x = \{x(k)\}_{k \ge 2}$ and $u = \{u(k)\}_{k \ge 2}$ are related by (2.22), then (2.20) is equivalent to (2.21). We define

Definition 2.2. x is a 2*d*-generalized eigenvector of J for λ iff (2.21) holds. $\overrightarrow{GEV(\lambda)}$ denotes the 2*d*-dimensional space of all 2*d*-generalized eigenvectors of J for λ .

Obviously

$$\overrightarrow{GEV(\lambda)} = \left\{ \left\{ \begin{pmatrix} u(k-1) \\ u(k) \end{pmatrix} \right\}_{k \ge 2} : u \in GEV(\lambda) \right\}.$$
(2.24)

Some methods used in spectral studies of scalar Jacobi operators are based on the general idea of finding relations between asymptotic properties of sequences from $GEV(\lambda)$ or $\overrightarrow{GEV(\lambda)}$ and spectral properties of J. Let us stress that the above word "asymptotic" can have many particular meanings. Different spectral results could be related to different kinds of asymptotic properties. And for some asymptotic properties the use of 2*d*-generalized eigenvectors can be more suitable than the use of generalized eigenvectors see, e.g., [10]. These methods, however, are less developed in the case of block Jacobi operators (with d > 1).

2.2. H-Class and Spectral Results for Scalar Jacobi Operator

The notion of *H*-class for sequences of 2×2 scalar matrices was introduced to study the absolutely continuous spectrum of scalar Jacobi operators—see, e.g., [3,9]. In a natural way, with any *m*, it can be extended to sequences $\{C_n\}_{n>n_0}$ of $m \times m$ complex matrices:

Definition 2.3. $\{C_n\}_{n \ge n_0} \in H$ iff

$$\exists_{M>0} \forall_{n \ge n_0} \ \|C_n \cdot \ldots \cdot C_{n_0}\|^m \le M \prod_{k=n_0}^n |\det C_k|.$$
 (2.25)

Note that the above requirement is quite strong, since for **any** $\{C_n\}_{n\geq n_0}$ the opposite direction estimate with respect to (2.25) holds. Namely, by Lemma 1.8.1.,

$$\prod_{k=n_0}^{n} |\det C_k| = |\det(C_n \cdot \ldots \cdot C_{n_0})| \le ||C_n \cdot \ldots \cdot C_{n_0}||^m.$$
(2.26)

So, we easily get an equivalent formulation of *H*-class definition, expressed in asymptotic terms " \approx " used in this paper.

Corollary 2.4. $\{C_n\}_{n\geq n_0} \in H$ iff $||C_n \cdot \ldots \cdot C_{n_0}|| \asymp_n (\prod_{k=n_0}^n |\det C_k|)^{\frac{1}{m}}$.

Consider now (block) Jacobi operator J, and define

 $H(J){:=}\{\lambda\in R:\ \{T_k(\lambda)\}_{k\geq 2}\in H\}$

we call it the *H*-set for *J*. It should be noted, that in the scalar case d = 1 the spectral character of H(J) can be described via subordination theory of Gilbert–Pearson–Khan [5].

Theorem 2.5. (see [9]) If d = 1, and J is self-adjoint, then J is absolutely continuous⁵ in Int(H(J)) and $\overline{Int(H(J))} \subset \sigma_{ac}(J)$.

2.3. H-Class and Uni-asymptoticity

The concept of H-class turns out to be closely related to our uni-asymptoticity notion.

Consider a sequence $\{C_n\}_{n>n_0}$ of $m \times m$ complex matrices and define:

$$U_n := C_n \cdot \ldots \cdot C_{n_0}, \quad n \ge n_0. \tag{2.27}$$

We get now

Corollary 2.6. If det $C_n \neq 0$ for any $n \geq n_0$, then

 $\{C_n\}_{n\geq n_0} \in H$ iff $\{U_n\}_{n\geq n_0}$ is uni-asymptotic.

Proof. It suffices to use Corollary 2.4 and Theorem 1.7 ((i) \iff (iii)).

Now we shall use this result to the sequence of transfer matrices for (block) Jacobi operator J. So, for fixed $\lambda \in \mathbb{C}$ we consider the dynamical system $\{U_s(\lambda)\}_{s\in S}$ with:

$$X := \mathbb{C}^{2d}, \quad S := \mathbb{N}_2,$$

and with

$$U_n(\lambda) := T_n(\lambda) \cdots T_2(\lambda) \quad \text{for } n \ge 2$$
 (2.28)

(see 2.23). We get

⁵By the definition (see, e.g., [11]), a self-adjoint operator A is is absolutely continuous when it coincides with its absolutely continuous part. The name "A has purely absolutely continuous spectrum" is also often used for such cases (note, however, that this name could be slightly misleading, because this property of A is not a property of its spectrum only). If $E_A(\cdot)$ denotes the projection-valued spectral resolution (measure) of A, and D is a Borel subset of \mathbb{R} , then A is absolutely continuous in D (or A has purely absolutely continuous spectrum in D) iff the scalar spectral measure $(E_A(\cdot)x, x)$ is absolutely continuous with respect to the Lebesgue measure for any $x \in \operatorname{Ran} E_A(D)$. Note that, in general, the last property does not guarantee that the spectrum of A and the set D have non-empty intersection, even for non-empty open D.

Theorem 2.7. For any $\lambda \in \mathbb{C}$ TFCAE:

- 1. $\{T_n(\lambda)\}_{n>2} \in H;$
- 2. $\{U_n(\lambda)\}_{n>2}^{-}$ is uni-asymptotic;
- 3. $\overrightarrow{GEV(\lambda)}$ is uni-asymptotic;
- 4. for any non-zero $\{x(n)\}_{n\geq 2} \in \overrightarrow{GEV(\lambda)}$

$$||x(n)|| \asymp_n \left(\frac{1}{\sqrt[d]{|\det A_{n-1}|}}\right)^{\frac{1}{2}}.$$
 (2.29)

Proof. We start from two simple observations on the "shifted" family of matrices $\{\widetilde{U}_n(\lambda)\}_{n\geq 2}$, given by

$$\widetilde{U}_n(\lambda) := \begin{cases} I & \text{for } n = 2\\ U_{n-1}(\lambda) & \text{for } n \ge 3. \end{cases}$$

First observe, that by Definition 2.2 and by (2.21),

$$\overrightarrow{GEV(\lambda)} = \left\{ \left\{ \widetilde{U}_n(\lambda)\alpha \right\}_{n \ge 2} : \ \alpha \in \mathbb{C}^{2d} \right\}.$$
(2.30)

By part 1. of Fact 1.4 we get the second observation:

 $\{U_n(\lambda)\}_{n\geq 2}$ is uni-asymptotic iff $\{\widetilde{U}_n(\lambda)\}_{n\geq 2}$ is uni-asymptotic. (2.31) The equivalence of 1. and 2. follows from Corollary 2.6. By our first observation, 2. is equivalent to the uni-asymptoticity of $\{\widetilde{U}_n(\lambda)\}_{n\geq 2}$. Hence the second observation and Fact 1.3 give the equivalence of 2. and 3.

Now, let us use Theorem 1.7 ((i) \iff (ii)) to the family $\{\tilde{U}_n(\lambda)\}_{n\geq 2}$. We also have

$$|\det \widetilde{U}_n(\lambda)| = |\det U_{n-1}(\lambda)| = \prod_{k=2}^{n-1} |\det T_k(\lambda)| = \prod_{k=2}^{n-1} \left| \frac{\det A_{k-1}}{\det A_k} \right|$$
$$= \left| \frac{\det A_1}{\det A_{n-1}} \right|$$

for $n \ge 3$, by (2.23). This gives us the equivalence of 2. and 4. (—note that here "m := 2d").

Remark 2.8.

1. The uni-asymptoticity results mean also the estimate from below, not only from above. Therefore condition 4. of Theorem 2.7 gives both: the above and below norm estimate for **each** non-zero 2*d*-generalized eigenvector by the RHS of (2.29). The idea of such "both sides norm estimates" has been used by many authors to construct Weyl sequences (see, e.g., [4,7]). For instance, in [8] such method allows to get results on the essential spectrum $\sigma_{\rm ess}(J)$ for **scalar** Jacobi operators of the form $J = J_0 + P$, where $\operatorname{Int}(H(J_0))$ is non-empty and P is a perturbation of some special kind. If P = 0, such results are obvious from the point of view of subordination theory methods (see e.g., Theorem 2.5)—just because " $\sigma_{\rm ac}(J)$ information is stronger, than the $\sigma_{\rm ess}(J)$ one". And if $P \neq 0$, the method starts to be important, because $Int(H(J_0 + P))$ can be empty, which means that Theorem 2.5 is useless.

2. Nevertheless, subordinacy does not work in d > 1 case. This is why, in case of **block** Jacobi operators, essential spectrum results and methods are in a sense more significant, than in the scalar case. For instance, if d > 1, then it make sense to check, whether $\sigma_{ess}(J_0)$ contains $Int(H(J_0))$. The methods used in [8] for P = 0 were based on construction of Weyl sequences by "deforming" generalized eigenvectors of J_0 . And in fact, the methods can be extended from d = 1 to any d. However, we need some extra assumptions on behaviour of the norms $||A_n||$ and determinants det A_n of the weight terms of J. Those extra assumptions can have various forms. As an example, we announce here the following result:

If J is self-adjoint, W, V are scalar sequences satisfying

- 1. W(n), V(n) are monotonic in n,
- 2. $W(n) \longrightarrow +\infty, \frac{W(n)}{n} \longrightarrow 0,$ 3. $W(2n) \prec_n W(n), V(2n) \asymp_n V(n),$
- and $||A_n|| \asymp_n W(n)$, det $A_n \asymp_n V(n)$, then $H(J) \subset \sigma_{\text{ess}}(J)$.

The detailed proof of the above one, and of some other versions, will be placed in the paper in preparation. The general idea is based on mimicking the proof of [8, Th. 2.1]. However, some problems are related to the fact, that the uni-asymptoticity of $GEV(\lambda)$ does not result in the uni-asymptoticity of $GEV(\lambda)$ (even for d = 1!). If d = 1, then this problem can be omited by the appropriate choice of the initial condition for this generalized eigenvector, which is used to construct the Weyl sequences. But for d > 1 it is not possible, and this is why some extra assumptions (e.g. (1), (2), (3) above) are needed.

- 3. Let us note some recent papers of Świderski. They contain very interesting approach, leading in particular also to uni-asymptoticity results for 2-generalized eigenvectors in scalar case (together with some extra " λ -uniform" properties)—see [12]. The paper [13] provides some spectral results, including also some essential spectrum results for the block case. Instead of a construction of Weyl sequences, the method is based on checking that there is no any generalized eigenvector in $\ell^2(\mathbb{N}, \mathbb{C}^d)$.
- 4. Due to "the gap" between the scalar and the block case spectral results, the natural **open question** arises:

Is there any relation of the set H(J) with $\sigma_{ac}(J)$ for d > 1?

Basic analysis of simplest examples with diagonal blocks shows, that any possible relation should be much more delicate, than for d = 1. Using very informal language: we could suspect that H(J) could be related somehow to a special kind of "multiplicity-d absolute continuity" for J. To explain this more precisely, let us assume that all the blocks A_n, B_n are diagonal, J is selfadjoint and that H(J) is non-empty. Then, by Theorems 2.5 and 1.7, one can easily prove the following assertion:

There exist d scalar self-adjoint Jacobi operators $J^{(1)}, \ldots, J^{(d)}$ with the weight sequences $\left\{a_n^{(1)}\right\}_{n\geq 1}, \ldots, \left\{a_n^{(d)}\right\}_{n\geq 1}$, respectively, such that

- (i) J is unitary equivalent to $J^{(1)} \oplus \ldots \oplus J^{(d)}$,
- (ii) $J^{(j)}$ is absolutely continuous in $\operatorname{Int}(H(J))$ and $\overline{\operatorname{Int}(H(J))} \subset \sigma_{\operatorname{ac}}(J^{(j)})$ for any $j = 1, \ldots, d$,
- (iii) $a_n^{(i)} \approx_n a_n^{(j)}$ for any $i, j = 1, \dots, d$.

Note that in the above "trivial" diagonal case the scalar operator $J^{(j)}$ can be defined simply by the diagonal terms of the blocks of J: its *n*-th weight $a_n^{(j)}$ is just the *j*-th diagonal term of A_n and its *n*-th diagonal term is just the *j*-th diagonal term of B_n (also the unitary opreator which gives (i) is easy to guess). Surely, the assertion will not change, if we assume that any two blocks of J commute, instead of assumming the diagonality of all blocks (since there exsists a common diagonalization for all blocks in this case). And the important problem starts, when we reject the assumption of commutativity...

Thus, let us end with a more concrete formulation of the above open question:

Is the above assertion with (i), (ii), (iii) also true in the general case of self-adjoint J (without the commutativity of blocks assumption)? And if it is not true, which parts of the assertion could be preserved?

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