# A Classification of Riemannian Manifolds with Structure Group Spin (7) (*). 

Marisa Fernández

Summary. - Riemannian manifolds with structure group Spin (7) are 8-dimensional and have a distinguished 4-form. In this paper, the covariant derivative of the fundamental 4 -form is studied, and it is shown that there are precisely four classes of such manifolds.

## 1. - Introduction.

An interesting little studied class of manifolds are the 8-dimensional Riemannian manifolds with holonomy group Spin (7) [2].

For such a Riemannian manifold $M$, Bonan [3] proved that its dimension must be 8 and its Ricci curvature zero. Moreover, ([5], [11], [12], [13], [14]) there exists a representation of Spin (7) on each tangent space of $M$ defined by means of a 3 -fold parallel vector cross product.

The 3 -fold vector cross products $P$ can be considered as a natural generalization of the almost-complex structures ([4], [8], [13], [14], [15]). Here, in the place of the Kähler form, one has a fundamental 4 -form $\varphi$ which, in special circumstances, for example when $P$ is parallel and $M$ is compact, generates cohomology in dimension 4.

There are no known nonflat examples of manifolds with holonomy group Spin (7). Here we consider instead the class $w$ of all 8 -dimensional Riemannian manifolds $M$ for which the bundle of orthonormal frames with structure group $0(8)$ can be reduced to Spin (7). The existence of such reduction is equivalent to the existence of a 3 -fold vector cross product on $M[13]$. Then, the class $W$ contains all parallelizable 8 -dimensional manifolds and is analogous to the class of almost Hermitian manifolds [17], and to the class of Riemannian manifolds with structure group $G_{2}$ [9]. Within the class $W$ one can search for analogs to the classes of almost Kähler and locally conformally equivalent to Kähler manifolds as well as analogs to some other special types of almost Hermitian manifolds.

This search, done in a systematic way by using the method in [9] and [17], is the principal subject of this paper. The idea is to study the representation of Spin (7) on the space $W$ of tensors having the same symmetries as the covariant

[^0]derivative $\nabla \varphi$ of the fundamental 4 -form $\varphi$, next decompose this representation into irreducible components, and then associate a subclass of $w$ with each invariant subspace of $W$.

In fact, by using the theory of root systems of semisimple Lie algebras, we show that the representation of $\operatorname{Spin}(7)$ on $W$ has only two irreducible components: $W=W_{1} \oplus W_{2}$. Thus, there are a total of 4 invariant subspaces of $W$, and hence 4 subclasses of $\mathcal{W}$. The manifolds with parallel vector cross products are in the class $\mathcal{P}$ corresponding to $\{0\}$. In contrast to what happens in the case of almost Hermitian manifolds [17] and the Riemannian manifolds with structure group $G_{2}$ [9], the following conditions are equivalent:
i) $\nabla P=0$;
ii) $\nabla_{X}(P)(X, Y, Z)=0, \quad$ for all $X, Y, Z \in \mathscr{X}(M)$;
iii) $d \varphi=0$;
iv) $\delta \varphi=0$.

Finally, the class of manifolds with locally conformally parallel vector cross products corresponds to $W_{2}$.

In section 2, we discuss the algebra of the 3 -fold vector cross products $P$, and extend the definition of $P$ so that $P$ operates on $k$-vectors and $k$-forms. Representations of the Lie group Spin (7) and the relevance of the vector cross products into the study of these representations are studied in section 3.

In section 4, we define the space $W$, and the decomposition $W=W_{1} \oplus W_{2}$ is established. In section 5 , we show how each invariant subspace of $W$ corresponds to a subclass of $\mathscr{W}$, and define the 4 classes.

In section 6 , we construct a certain tensor field $v$ which measures the failure of a manifold with vector cross product to be locally conformally related to a manifold with parallel vector cross product. A similar tensor field has been introduced in [17] for almost Hermitian manifolds, and in [9] for Riemannian manifolds with structure group $G_{2}$. Using $y$ we determine which of the 4 classes are preserved under conformal changes of metric. Finally, in section 7, we discuss the strictness of the four inclusion relations between the classes. In fact, we show that three of the four are strict. So for we have been unable to settle the strictness of the inclusion of $\mathscr{T}$ in $\mathfrak{W}_{1}$.

Added in proof. - Recently we have also been able to show the strictness of the inclusion $\mathfrak{J} \subset w_{1}$. The details will appear in a future paper.

I wish to thank Prof. A. Gray and Prof. R. Bryant for several very useful discussions.

## 2. - The algebra of 3 -fold vector cross products on vector spaces.

In this section, we shall study the algebra of 3 -fold vector cross products $P$ and extend the definition of $P$ so that $P$ operates on $k$-vectors.

Definition ([7]). - Let $V$ be a finite dimensional vector space over $\boldsymbol{R}$ with a (positive definite) inner product $\langle$,$\rangle . A 3-fold vector cross product on V$ is a trilinear map $P: V \times V \times V \rightarrow V$ satisfying

$$
\begin{align*}
& \langle P(x, y, z), x\rangle=\langle P(x, y, z), y\rangle=\langle P(x, y, z), z\rangle=0  \tag{2.1}\\
& \|P(x, y, z)\|^{2}=\operatorname{det}\left(\begin{array}{lll}
\|x\|^{2} & \langle x, y\rangle & \langle x, z\rangle \\
\langle y, x\rangle & \|y\|^{2} & \langle y, z\rangle \\
\langle z, x\rangle & \langle z, y\rangle & \|z\|^{2}
\end{array}\right), \tag{2.2}
\end{align*}
$$

for $x, y, z \in V$.
Let $\Lambda^{k}(V)$ denote the $k$-th Grassmann space over $V$ (i.e., the space generated by the skew-symmetric products $\left.v_{1} \wedge \ldots \wedge v_{k}\right)$. It follows from (2.1) that $P(x, y, z)$ is antisymmetric in $x, y, z$. Hence $P$ may be extended to a linear mapping $P: \Lambda^{3}(V) \rightarrow V$. For this reason we shall usually write $P(x \wedge y \wedge z)$ instead of $P(x, y, z)$. Furthermore, the inner product $\langle$,$\rangle can be extended to \Lambda^{k}(V)$ by the formula

$$
\left\langle v_{1} \wedge \ldots \wedge v_{k}, w_{1} \wedge \ldots \wedge w_{k}\right\rangle=\operatorname{det}\left(\left\langle v_{i}, w_{j}\right\rangle\right)
$$

for $v_{1}, \ldots, v_{k}, w_{1}, \ldots, w_{k} \in V$. Then, axiom (2.2) becomes

$$
\begin{equation*}
\|P(x \wedge y \wedge z)\|^{2}=\|x \wedge y \wedge z\|^{2} \tag{2.3}
\end{equation*}
$$

Remark. - (2.3) does not mean that $P$ is an isometry, but only an isometry on decomposable vectors.

Definition. - The fundamental 4 -form $p$ of a 3 -fold vector cross product $P$ is given by

$$
\varphi(x \wedge y \wedge z \wedge w)=\langle P(x \wedge y \wedge z), w\rangle
$$

for $x, y, z, w \in V$. (From (2.1) it follows that $\varphi$ is skew-symmetric.)
Eckmann [7], Whitehead [23], and Brown-Gray [4] have shown that if $V$ has a 3 -fold vector cross product then necessarily $\operatorname{dim} V=4$ or 8 . When $\operatorname{dim} V=4$, the study of $P$ amounts to the study of the volume element of $V$, namely $\varphi$, so we restrict ourselves to the case $\operatorname{dim} V=8$. In this case, it is well known ([4]) that there are two non-isomorphic 3 -fold vector cross products $P_{+}$and $P_{-}$, given ([4], [25]) in terms of the Cayley numbers by

$$
\begin{aligned}
& P_{+}(x \wedge y \wedge z)=-x(\bar{y} z)+\langle x, y\rangle z+\langle y, z\rangle x-\langle x, z\rangle y \\
& P_{-}(x \wedge y \wedge z)=-(x \bar{y}) z+\langle x, y\rangle z+\langle y, z\rangle x-\langle x, z\rangle y
\end{aligned}
$$

for $x, y, z \in V$, and where $x \rightarrow \bar{x}$ is the conjugation in Cay (that is, $\bar{x}=-x+$ $+2\langle x, 1\rangle 1$ ). The reason why there are two distinct 3 -fold vector cross products
is that the Cayley numbers are nonassociative. Furthermore, the automorphism groups of $P_{+}$and $P_{-}$are both isomorphic to $\operatorname{Spin}(7)$. We write $\varphi_{ \pm}$for the fundamental 4 -form of $P_{ \pm}$.

From now on, we shall write $P$ when no distinction between $P_{+}$and $P_{-}$is needed.
First, we shall write some elementary consequences of (2.1)-(2.3).
Lemma 2.1. - We have

$$
\begin{align*}
& \langle P(x \wedge y \wedge z), P(x \wedge y \wedge w)\rangle=\langle x \wedge y \wedge z, x \wedge y \wedge w\rangle  \tag{2.4}\\
& P(x \wedge y \wedge P(x \wedge y \wedge z))=-\|x \wedge y\|^{2} z+\langle x \wedge y, x \wedge z\rangle y+\langle y \wedge x, y \wedge z\rangle x \tag{2.5}
\end{align*}
$$

for $x, y, z, w \in V$.
Furthermore, from (2.5) it follows

$$
\begin{equation*}
P(x \wedge y \wedge P(x \wedge y \wedge P(x \wedge y \wedge z)))=-\|x \wedge y\|^{2} P(x \wedge y \wedge z) \tag{2.6}
\end{equation*}
$$

We now introduce a mapping $p$ that will turn out to be the adjoint of $P$.
Definition. - The linear mapping $p: V \rightarrow \Lambda^{3}(V)$ is given by

$$
p(x)=-\frac{1}{6} \sum_{i, j=0}^{7} e_{i} \wedge e_{j} \wedge P\left(e_{i} \wedge e_{j} \wedge x\right)
$$

for $x \in V$, and where $\left\{e_{0}, \ldots, e_{7}\right\}$ is any orthonormal basis of $V$.
Lemara 2.2. - The mapping $p$ has the following properties
(i) $p$ is the adjoint of $P$; that is for $x \in V, \xi \in \Lambda^{3}(V)$ we have
(ii)

$$
\begin{aligned}
\langle p(x), \xi\rangle & =\langle x, P(\xi)\rangle, \\
P(p(x)) & =7 x
\end{aligned}
$$

for $x \in V$.
Proof. - (i) follows from (2.1), (2.3) and definition of $p$ : From (2.5) we obtain (ii).
Next, we shall define another linear mapping $q$ which will be useful in section 3 .
Definition. - The linear mapping $q: \Lambda^{2}(V) \rightarrow \Lambda^{2}(V)$ is given by

$$
q(x \wedge y)=\frac{1}{2} \sum_{i=0}^{7} e_{i} \wedge P\left(e_{i} \wedge x \wedge y\right)
$$

for $x, y \in V$, and where $\left\{e_{0}, \ldots, e_{7}\right\}$ is any orthonormal basis of $V$.
From (2.5) one has the following

Lemma 2.3. - The mapping q satisfies
(i) $\langle q(x \wedge y), z \wedge w\rangle=\langle P(x \wedge y \wedge z), w\rangle ;$
(ii) $\langle q(x \wedge y), x \wedge y\rangle=0$;
(iii) $\|q(x \wedge y)\|^{2}=3\|x \wedge y\|^{2} ;$
for $x, y, z, w \in V$.
Now, we extend $P, p$ and $q$ to linear maps $P: \Lambda^{k+2}(V) \rightarrow \Lambda^{k}(V), p: \Lambda^{k}(V) \rightarrow$ $\rightarrow \Lambda^{k+2}(V)$ and $q: \Lambda^{k}(V) \rightarrow \Lambda^{k}(V)$.

Definition. - Let $v_{1}, \ldots, v_{k+2} \in V$. Then

$$
\begin{aligned}
& P\left(v_{1} \wedge \ldots \wedge v_{k+2}\right)=\sum_{1 \leqslant i<j<l \leqslant l+2}(-1)^{i+j+1} \boldsymbol{P}\left(v_{i} \wedge v_{j} \wedge v_{l}\right) \wedge v_{1} \wedge \ldots \wedge \hat{v}_{i} \wedge \ldots \wedge \hat{v}_{j} \wedge \ldots \wedge \hat{v}_{l} \wedge \ldots \wedge v_{k+2}, \\
& p\left(v_{1} \wedge \ldots \wedge v_{k}\right)=\sum_{i=1}^{k}(-1)^{i+1} p\left(v_{i}\right) \wedge v_{1} \wedge \ldots \wedge \hat{v}_{i} \wedge \ldots \wedge v_{k}, \\
& q\left(v_{1} \wedge \ldots \wedge v_{k}\right)=\sum_{1 \leqslant i<j \leqslant k}(-1)^{i+j+1} q\left(v_{i} \wedge v_{j}\right) \wedge v_{1} \wedge \ldots \wedge \hat{v}_{i} \wedge \ldots \wedge \hat{v}_{i} \wedge \ldots \wedge v_{k},
\end{aligned}
$$

and $P: \Lambda^{k+2}(V) \rightarrow \Lambda^{k}(V), p: \Lambda^{k}(V) \rightarrow \Lambda^{k+2}(V)$ and $q: \Lambda^{k}(V) \rightarrow \Lambda^{k}(V)$ are their canonical linear extensions.

Note that the sequences

$$
\begin{aligned}
& \Lambda^{7}(V) \underset{v_{5}}{\stackrel{P_{5}}{\rightleftarrows}} \Lambda^{5}(V) \underset{p_{3}}{\stackrel{P_{3}}{\rightleftarrows}} \Lambda^{3}(V) \underset{v_{1}}{\stackrel{P_{1}}{\rightleftarrows}} V \\
& \Lambda^{6}(V) \underset{p_{4}}{\stackrel{P_{4}}{\rightleftarrows}} \Lambda^{4}(V) \underset{p_{2}}{\stackrel{P_{2}}{\rightleftarrows}} \Lambda^{2}(V)
\end{aligned}
$$

are non-exact.
In particular, for $w, x, y, z \in V$ we have

$$
\left.\begin{array}{rl}
p(x \wedge y) & =p(x) \wedge y-p(y) \wedge x \\
p(x \wedge y \wedge z) & =\Im_{x y z} p(x) \wedge y \wedge z \\
P(w \wedge \dot{x} \wedge y \wedge z) & ={\underset{x y z}{ }\{P(w \wedge x \wedge y) \wedge z\}-P(x \wedge y \wedge z) \wedge w}^{q(x \wedge y \wedge z)}
\end{array}\right){\underset{x y z}{S} q(x \wedge y) \wedge z}^{S_{x y}},
$$

where $\mathfrak{S}$ denotes the cyclic sum.
Let $\Lambda(V)=\stackrel{8}{\oplus_{k=0}} A^{k}(V)$, and let $*: A(V) \rightarrow A(V)$ be the Hodge star operator. Then $*\left(\Lambda^{k}(V)\right) \stackrel{k-k}{=} \Lambda^{8-k}(V)$. Next, we determine the form $* \varphi_{ \pm}$. (Here the 4-form * $\varphi_{ \pm}$can be defined by

$$
\left.\left(* \varphi_{ \pm}\right)(x \wedge y \wedge z \wedge w)=\varphi_{ \pm}(*(x \wedge y \wedge z \wedge w))\right)
$$

Lemma 2.4.

$$
\begin{equation*}
* \varphi_{ \pm}= \pm \varphi_{ \pm} \tag{2.7}
\end{equation*}
$$

Proof.- Consider $\left\{1, e_{0}, \ldots, e_{6}\right\}$ an orthonormal basis for $V$ where 1 is the identity in Cay, and such that $e_{i} e_{i+1}=e_{i+3}$ for $i \in Z_{7}$; and let $\left\{\theta_{-1}, \theta_{0}, \ldots, \theta_{6}\right\}$ be the dual basis. Then

$$
\begin{align*}
\varphi_{ \pm} & =\theta_{-1} \wedge\left(\theta_{0} \wedge \theta_{1} \wedge \theta_{3}+\theta_{0} \wedge \theta_{2} \wedge \theta_{6}+\theta_{0} \wedge \theta_{4} \wedge \theta_{5}+\theta_{1} \wedge \theta_{2} \wedge \theta_{4}+\right.  \tag{2.8}\\
& \left.+\theta_{1} \wedge \theta_{5} \wedge \theta_{6}+\theta_{2} \wedge \theta_{3} \wedge \theta_{5}+\theta_{3} \wedge \theta_{4} \wedge \theta_{6}\right) \pm \\
& \pm \theta_{0} \wedge \theta_{1} \wedge \theta_{2} \wedge \theta_{5} \mp \theta_{0} \wedge \theta_{1} \wedge \theta_{4} \wedge \theta_{6} \mp \theta_{0} \wedge \theta_{2} \wedge \theta_{3} \wedge \theta_{4} \pm \\
& \pm \theta_{0} \wedge \theta_{3} \wedge \theta_{5} \wedge \theta_{6} \pm \theta_{1} \wedge \theta_{2} \wedge \theta_{3} \wedge \theta_{6} \mp \theta_{1} \wedge \theta_{3} \wedge \theta_{4} \wedge \theta_{5} \mp \theta_{2} \wedge \theta_{4} \wedge \theta_{5} \wedge \theta_{6} .
\end{align*}
$$

Applying the Hodge star operator to both sides of (2.8), we get (2.7).
Lemma 2.5. - For $P_{ \pm}: \Lambda^{4}(V) \rightarrow \Lambda^{2}(V)$ we have

$$
\begin{equation*}
P_{ \pm *}= \pm P_{ \pm} \tag{2.9}
\end{equation*}
$$

Proof. - This can be checked by choosing an orthonormal basis for $V$ as that in Lemma 2.4, and computing the maps $P_{ \pm^{*}}$ and $P_{ \pm}$.

## 3. - Some representations of $\operatorname{Spin}(7)$.

We shall describe, in this section, some representations of Spin (7) that will be needed in the next section.

A simple method to describe the 8-dimensional representation of Spin (7) is by means of the 3 -fold vector cross products $P$. In fact,

$$
\operatorname{Spin}(7)=\{g \in 0(8) \mid P(g x \wedge g y \wedge g z)=g P(x \wedge y \wedge z) \text { for all } x, y, z \in V\}
$$

and the 21 -dimensional irreducible representation of $\operatorname{Spin}(7)$ is the adjoint representation.

Next, we shall consider, for convenience, the covariant versions of $P, p$ and $q$ which will be denoted by the same letters. Let $V^{*}$ denote the dual space of $V$.

Definition. - The mappings $P: \Lambda^{k}\left(V^{*}\right) \rightarrow \Lambda^{k+2}\left(V^{*}\right), p: \Lambda^{k+2}\left(V^{*}\right) \rightarrow \Lambda^{k}\left(V^{*}\right)$ and $q: \Lambda^{k}\left(V^{*}\right) \rightarrow \Lambda^{k}\left(V^{*}\right)$ are given by $P(\alpha)=\alpha \circ P, p(\beta)=\beta \circ p$ and $q(\alpha)=\alpha \circ q$, for $\alpha \in$ $\in \Lambda^{k}\left(V^{*}\right)$ and $\beta \in \Lambda^{k+2}\left(V^{*}\right)$. (To avoid confusion we shall sometimes write $P_{k}, p_{k}$ and $q_{k}$.)

Thus we have the following non-exact sequences:

$$
\begin{aligned}
& V^{*} \underset{p_{1}}{\stackrel{P_{1}}{\rightleftarrows}} \Lambda^{3}\left(V^{*}\right) \stackrel{P_{3}}{\stackrel{y_{3}}{\leftrightarrows}} \Lambda^{5}\left(V^{*}\right) \stackrel{P_{5}}{\underset{p_{5}}{\leftrightarrows}} \Lambda^{7}\left(V^{*}\right) \\
& \Lambda^{2}\left(V^{*}\right) \stackrel{P_{9}}{\stackrel{p_{3}}{\leftrightarrows}} \Lambda^{4}\left(V^{*}\right) \stackrel{p_{4}}{\underset{p_{4}}{\rightleftarrows}} \Lambda^{6}\left(V^{*}\right)
\end{aligned}
$$

We shall now determine the irreducible components of the inducedrepresentation of Spin (7) on each space $\Lambda^{k}\left(V^{*}\right)$. First, let us note that the representations of $\operatorname{spin}(7)$ on $\Lambda^{k}\left(V^{*}\right)$ and on $\Lambda^{8-k}\left(V^{*}\right)$ are the same because the Hodge star operator $*: \Lambda^{k}\left(V^{*}\right) \rightarrow \Lambda^{8-k}\left(V^{*}\right)$ is an isometry. (We are using on $\Lambda^{k}\left(V^{*}\right)$ the inner product $\langle$,$\rangle given by$

$$
\langle\alpha, \beta\rangle=\sum_{i_{1}, \ldots, i_{k}=0}^{7} \alpha\left(e_{i_{1}} \wedge \ldots \wedge e_{i_{k}}\right) \beta\left(e_{i_{1}} \wedge \ldots \wedge e_{i_{k}}\right)
$$

where $\left\{e_{0}, \ldots, e_{7}\right\}$ is an arbitrary basis of $V$ ). Hence, it suffices to describe the representations of Spin (7) on $V^{*}, \Lambda^{2}\left(V^{*}\right), \Lambda^{3}\left(V^{*}\right)$, and $\Lambda^{4}\left(V^{*}\right)$. The representation of Spin (7) on $V^{*}$ is the irreducible 8-dimensional representation, but the representations of $\operatorname{Spin}(7)$ on $\Lambda^{2}\left(V^{*}\right), \Lambda^{3}\left(V^{*}\right)$ and $\Lambda^{4}\left(V^{*}\right)$ are all reducible. In order to describe the irreducible summands of these representations by means of the vector cross product $P$, we first use Weyl's formula (see for example [21]) to calculate the degrees of the first ten irreducible representations of $\operatorname{Spin}(7)$. It can be verified that these degrees are $1,7,8,21,27,35,42,48,105,112$. Next, we shall define the following spaces

$$
\begin{aligned}
& \Lambda_{1}^{2}\left(V^{*}\right)=\left\{\alpha \in \Lambda^{2}\left(V^{*}\right) \mid q \alpha=0\right\}, \\
& A_{2}^{2}\left(V^{*}\right)=\left\{\alpha \in \Lambda^{2}\left(V^{*}\right) \mid \alpha=q \beta \text { for some } \beta \in \Lambda^{2}\left(V^{*}\right)\right\}, \\
& \Lambda_{1}^{3}\left(V^{*}\right)=\left\{\alpha \in \Lambda^{3}\left(V^{*}\right) \mid p \alpha=0\right\}, \\
& \Lambda_{2}^{3}\left(V^{*}\right)=\left\{\alpha \in \Lambda^{3}\left(V^{*}\right) \mid 7 \alpha=P p \alpha\right\}, \\
& \Lambda_{1+}^{4}\left(V^{*}\right)=\left\{\varphi_{+}\right\}, \\
& \Lambda_{2+}^{4}\left(V^{*}\right)=\left\{\alpha \in \Lambda^{4}\left(V^{*}\right) \mid p_{++}(\alpha)=0, \quad * \alpha=+\alpha \quad\right. \text { and } \\
& \left.\sum_{i, j, k=0}^{7} \alpha\left(e_{i} \wedge e_{j} \wedge e_{k} \wedge P_{+}\left(e_{i} \wedge e_{j} \wedge e_{k}\right)\right)=0\right\}, \\
& \Lambda_{3+}^{4}\left(V^{*}\right)=\left\{\alpha \in \Lambda^{4}\left(V^{*}\right) \mid * \alpha=-\alpha\right\}, \\
& \Lambda_{4+}^{4}\left(V^{*}\right)=\left\{\alpha \in \Lambda^{4}\left(V^{*}\right) \mid \alpha\left(x \wedge y \wedge z \wedge P_{+}(x \wedge y \wedge z)\right)=0 \text { for all } x, y, z \in V\right\}, \\
& \Lambda_{1-}^{4}\left(\nabla^{*}\right)=\left\{\varphi_{-}\right\}, \\
& \Lambda_{2-}^{4}\left(\nabla^{*}\right)=\left\{\alpha \in \Lambda^{4}\left(\nabla^{*}\right) \mid p_{-}(\alpha)=0, \quad * \alpha=-\alpha_{7} \quad\right. \text { and } \\
& \left.\sum_{i, j, k=0}^{7} \alpha\left(e_{i} \wedge e_{j} \wedge e_{k} \wedge P_{-}\left(e_{i} \wedge e_{j} \wedge e_{k}\right)\right)=0\right\}, \\
& \Lambda_{3-}^{4}\left(V^{*}\right)=\left\{\alpha \in \Lambda^{4}\left(V^{*}\right) \mid * \alpha=+\alpha\right\}, \\
& \Lambda_{4-}^{4}\left(V^{*}\right)=\left\{\alpha \in V^{4}\left(V^{*}\right) \mid \alpha\left(x \wedge y \wedge z \wedge P_{-}(x \wedge y \wedge z)\right)=0 \text { for all } x, y, z \in V\right\} .
\end{aligned}
$$

In order to check that Spin (7) acts irreducibly on these spaces it will be necessary to make use of the theory of root systems of semisimple Lie algebras. The Dynkin diagram of the simple Lie algebra $b_{3}$ of Spin (7) is

where $\left\{\alpha_{1}, \alpha_{2}, \alpha_{3}\right\}$ is a system of simple roots, and $\alpha_{1}=\omega_{1}-\omega_{2}, \alpha_{2}=\omega_{2}-\omega_{3}, \alpha_{3}=\omega_{3}$, $\left\langle\omega_{i}, \omega_{j}\right\rangle=\delta_{i j}$. Then

$$
\begin{aligned}
& \frac{\left\langle\alpha_{1}, \alpha_{2}\right\rangle}{\left\|\alpha_{1}\right\|\left\|\alpha_{2}\right\|}=-\frac{1}{2}=\cos \frac{2}{3} \pi \\
& \frac{\left\langle\alpha_{2}, \alpha_{3}\right\rangle}{\left\|\alpha_{2}\right\|\left\|\alpha_{3}\right\|}=-\frac{\sqrt{2}}{2}=\cos \frac{3}{4} \pi
\end{aligned}
$$

and the angle between $\alpha_{1}, \alpha_{3}$ is equal to $\pi / 2$. We shall denote by $\lambda_{i}(i=1,2,3)$ the fundamental dominant weights, and by $\varphi_{\lambda_{i}}(i=1,2,3)$ the corresponding irreducible representations. (In general for an extreme weight $\lambda, \varphi_{\lambda}$ will denote the corresponding irreducible representation.) It can be easily verified that these weights are $\lambda_{1}=\omega_{1}, \lambda_{2}=\omega_{1}+\omega_{2}$ and $\lambda_{3}=\frac{1}{2}\left(\omega_{1}+\omega_{2}+\omega_{3}\right)$. Moreover, $\varphi_{\lambda_{1}}$ has dimension 7. $\varphi_{\lambda_{\mathrm{s}}}$ has dimension 21 ; it is the adjoint representation. $\varphi_{\lambda_{3}}$ has dimension 8; it can be identified with the representation on $V$.

Now, a long but not difficult computation shows that:
i) the weights of (irreducibile) representation $\varphi_{\lambda_{1}}$ are

$$
\pm \lambda_{1}= \pm \omega_{1}, \quad \pm \omega_{2}, \quad \pm \omega_{3}, \quad 0
$$

ii) the weights of $\varphi_{\lambda_{2}}$, i.e. the roots of $b_{3}$, are

$$
\pm \lambda_{2}= \pm\left(\omega_{1}+\omega_{2}\right), \quad \pm\left(\omega_{1}+\omega_{3}\right), \quad \pm\left(\omega_{2}+\omega_{3}\right), \quad \pm \omega_{1}, \quad \pm\left(\omega_{1}-\omega_{3}\right)
$$

$$
\pm \omega_{2}, \quad \pm\left(\omega_{1}-\omega_{2}\right), \quad \pm\left(\omega_{2}-\omega_{3}\right), \quad \pm \omega_{3}, \quad 0(3) ;
$$

iii) the weights of $\varphi_{\lambda_{3}}$ are

$$
\begin{aligned}
& \pm \lambda_{3}= \pm \frac{1}{2}\left(\omega_{1}+\omega_{2}+\omega_{3}\right), \quad \pm \frac{1}{2}\left(\omega_{1}+\omega_{2}-\omega_{3}\right), \quad \pm \frac{1}{2}\left(\omega_{1}-\omega_{2}+\omega_{3}\right) \\
& \pm \frac{1}{2}\left(-\omega_{1}+\omega_{2}+\omega_{3}\right)
\end{aligned}
$$

iv) the weights of the 48 -dimensional irreducible representation $\varphi_{\lambda_{1}+\lambda_{3}}$ are

$$
\begin{array}{lll} 
\pm \frac{1}{2}\left(\omega_{1}+\omega_{2}+\omega_{3}\right)(3), & \pm \frac{1}{2}\left(\omega_{1}+\omega_{2}-\omega_{3}\right)(3), & \pm \frac{1}{2}\left(\omega_{1}-\omega_{2}+\omega_{3}\right)(3), \\
\pm \frac{1}{2}\left(-\omega_{1}+\omega_{2}+\omega_{3}\right)(3), & \pm \frac{1}{2}\left(3 \omega_{1}+\omega_{2}+\omega_{3}\right), & \pm \frac{1}{2}\left(3 \omega_{1}+\omega_{2}-\omega_{3}\right) \\
\pm \frac{1}{2}\left(3 \omega_{1}-\omega_{2}+\omega_{3}\right), & \pm \frac{1}{2}\left(3 \omega_{1}-\omega_{2}-\omega_{3}\right), & \pm \frac{1}{2}\left(\omega_{1}+3 \omega_{2}+\omega_{3}\right),
\end{array}
$$

$$
\begin{array}{lll} 
\pm \frac{1}{2}\left(\omega_{1}+3 \omega_{2}-\omega_{3}\right), & \pm \frac{1}{2}\left(-\omega_{1}+3 \omega_{2}+\omega_{3}\right), & \pm \frac{1}{2}\left(-\omega_{1}+3 \omega_{2}-\omega_{3}\right) ; \\
\pm \frac{1}{2}\left(\omega_{1}+\omega_{2}+3 \omega_{3}\right), & \pm \frac{1}{2}\left(\omega_{1}-\omega_{2}+3 \omega_{3}\right), & \pm \frac{1}{2}\left(-\omega_{1}+\omega_{2}+3 \omega_{3}\right) ; \\
\pm \frac{1}{2}\left(-\omega_{1}-\omega_{2}+3 \omega_{3}\right) ; & &
\end{array}
$$

v) the weights of the 27 -dimensional irreducible representation $\varphi_{2 \lambda_{1}}$ are

$$
\begin{aligned}
& \pm \omega_{1}, \quad \pm \omega_{2}, \quad \pm \omega_{3}, \quad \pm\left(\omega_{1}+\omega_{2}\right), \quad \pm\left(\omega_{1}+\omega_{3}\right), \quad \pm\left(\omega_{2}+\omega_{3}\right) \\
& \pm\left(\omega_{1}-\omega_{2}\right), \quad \pm\left(\omega_{1}-\omega_{3}\right), \quad \pm\left(\omega_{2}-\omega_{3}\right), \quad \pm 2 \omega_{1}, \quad \pm 2 \omega_{2}, \quad \pm 2 \omega_{3}, \\
& 0(3)
\end{aligned}
$$

vi) the weights of the 35 -dimensional irreducible representation $\varphi_{2 \lambda_{3}}$ are

$$
\begin{aligned}
& \pm \omega_{1}(2), \quad \pm \omega_{2}(2), \quad \pm \omega_{3}(2), \quad \pm\left(\omega_{1}+\omega_{2}\right), \quad \pm\left(\omega_{1}+\omega_{3}\right) \\
& \pm\left(\omega_{2}+\omega_{3}\right), \quad \pm\left(\omega_{1}-\omega_{2}\right), \quad \pm\left(\omega_{1}-\omega_{3}\right), \quad \pm\left(\omega_{2}-\omega_{3}\right) \\
& \pm\left(\omega_{1}+\omega_{2}+\omega_{3}\right), \quad \pm\left(\omega_{1}+\omega_{2}-\omega_{3}\right), \quad \pm\left(\omega_{1}-\omega_{2}+\omega_{3}\right) \\
& \pm\left(\omega_{1}-\omega_{2}-\omega_{3}\right), \quad 0(3)
\end{aligned}
$$

We write $\Lambda^{k} \varphi_{\lambda_{3}}$ for the induced reducible representation on the $k$-th Grassmann space $\Lambda^{k}\left(V^{*}\right)$ over $V^{*}$. Then, by computing the weights of $\Lambda^{2} \varphi_{\lambda_{3}}, \Lambda^{3} \varphi_{\lambda_{3}}$ and $\Lambda^{4} \varphi_{\lambda_{3}}$, one follows that

$$
\begin{align*}
\Lambda^{2} \varphi_{\lambda_{3}} & =\varphi_{\lambda_{1}} \oplus \varphi_{\lambda_{2}}  \tag{3.1}\\
\Lambda^{3} \varphi_{\lambda_{3}} & =\varphi_{\lambda_{1}+\lambda_{3}} \oplus \varphi_{\lambda_{3}}  \tag{3.2}\\
\Lambda^{4} \varphi_{\lambda_{3}} & =\varphi_{2 \lambda_{3}} \oplus \varphi_{2 \lambda_{1}} \oplus \varphi_{\lambda_{1}} \oplus \varphi_{0} \tag{3.3}
\end{align*}
$$

where $\varphi_{0}$ is the 1 -dimensional irreducible representation.
Lemma 3.1. - We have

$$
\begin{equation*}
\Lambda^{2}\left(V^{*}\right)=\Lambda_{1}^{2}\left(V^{*}\right) \oplus \Lambda_{2}^{2}\left(V^{*}\right) \tag{3.4}
\end{equation*}
$$

Also Spin (7) acts irreducibly on $\Lambda_{i}^{2}\left(\nabla^{*}\right)$ and

$$
\operatorname{dim} \Lambda_{1}^{2}\left(V^{*}\right)=21, \quad \operatorname{dim} \Lambda_{2}^{2}\left(V^{*}\right)=7
$$

Proof. - Using definition of $q$ it can be verified that (3.4) holds and that the spaces $\Lambda_{i}^{2}\left(V^{*}\right)$ have the stated dimensions. That $\operatorname{Spin}(7)$ acts irreducibly on $\Lambda_{i}^{2}\left(V^{*}\right)$ is immediate from (3.1).

Lemma 3.2. - We have the following orthogonal direct sum

$$
\begin{equation*}
\Lambda^{3}\left(V^{*}\right)=\Lambda_{1}^{3}\left(V^{*}\right) \oplus \Lambda_{2}^{3}\left(V^{*}\right) \tag{3.5}
\end{equation*}
$$

Also Spin (7) acts irreducibly on $\Lambda_{i}^{3}\left(V^{*}\right)$ and

$$
\operatorname{dim} \Lambda_{1}^{3}\left(V^{*}\right)=48, \quad \operatorname{dim} \Lambda_{2}^{3}\left(\nabla^{*}\right)=8
$$

Proof. - From Lemma 2.2 (ii) we obtain

$$
\begin{equation*}
p_{1} \circ P_{1}=7 I_{1} \tag{3.6}
\end{equation*}
$$

where $I_{k}: \Lambda^{k}\left(\boldsymbol{V}^{*}\right) \rightarrow \Lambda^{k}\left(\boldsymbol{V}^{*}\right)$ denotes the identity map. Using (3.6) it is easy to verify that $\frac{1}{7} P_{1} \circ p_{1}$ and $I_{3}-\frac{1}{7} P_{1} \circ p_{1}$ are projections of $\Lambda^{3}\left(V^{*}\right)$ onto $\Lambda_{2}^{3}\left(V^{*}\right)$ and $\Lambda_{1}^{3}\left(V^{*}\right)$, respectively. This proves (3.5).

Again using (3.6), one deduces that $P_{1}: V^{*} \rightarrow \Lambda^{3}\left(V^{*}\right)$ is injective and $p_{1}: \Lambda^{3}\left(V^{*}\right) \rightarrow$ $\rightarrow V^{*}$ is surjective. Furthermore, Image $P_{1}=\Lambda_{2}^{3}\left(V^{*}\right)$. Thus, $\Lambda_{1}^{3}\left(V^{*}\right)$ and $\Lambda_{2}^{3}\left(V^{*}\right)$ have the stated dimensions. These representations of Spin (7) are irreducible by (3.2).

Lemma 3.3. - We have the following orthogonal direct sum

$$
\begin{align*}
& \Lambda^{4}\left(V^{*}\right)=\Lambda_{1+}^{4}\left(V^{*}\right) \oplus \Lambda_{2+}^{4}\left(V^{*}\right) \oplus \Lambda_{3+}^{4}\left(V^{*}\right) \oplus \Lambda_{1+}^{4}\left(V^{*}\right)=  \tag{3.7}\\
&=\Lambda_{1-}^{4}\left(V^{*}\right) \oplus \Lambda_{2-}^{4}\left(V^{*}\right) \oplus \Lambda_{3-}^{4}\left(V^{*}\right) \oplus \Lambda_{4-}^{4}\left(V^{*}\right)
\end{align*}
$$

Also Spin (7) acts irreducibly on each space $\Lambda_{i \pm}^{4}\left(V^{*}\right)$ and

$$
\operatorname{dim} \Lambda_{1 \pm}^{4}\left(V^{*}\right)=1, \quad \operatorname{dim} \Lambda_{2 \pm}^{4}\left(V^{*}\right)=27, \quad \operatorname{dim} \Lambda_{3 \pm}^{4}\left(V^{*}\right)=35, \quad \operatorname{dim} \Lambda_{4 \pm}^{4}\left(V^{*}\right)=7
$$

Proof. - Let $P_{+}$be the 3 -fold vector cross product on $V$. From definition of $P_{+}: \Lambda^{2}\left(V^{*}\right) \rightarrow \Lambda^{4}\left(V^{*}\right)$, it is not difficult to prove that Image $P_{+}=\Lambda_{4+}^{4}\left(V^{*}\right)$, and that $P_{+} \operatorname{maps} \Lambda_{2}^{2}\left(V^{*}\right)$ injectively into $\Lambda_{4+}^{4}\left(V^{*}\right)$. Hence dim $\Lambda_{4+}^{4}\left(V^{*}\right)=7$, and then the subspace $U$ of $\Lambda^{4}(V)$, annihilated by $\Lambda_{4+}^{4}\left(V^{*}\right)$ and generated by the elements of the form $x \wedge y \wedge z \wedge P_{+}(x \wedge y \wedge z), x, y, z \in V$, has $\operatorname{dim} U=63$.

Now, let us consider the mapping $P_{+}: \Lambda^{4}(\nabla) \rightarrow \Lambda^{2}(V)$. Since $\operatorname{dim} U=63$ and $U \subseteq$ kernel $P_{+}$it follows that $U=$ kernel $P_{+}$. Using (2.8) and Lemma 2.5 we obtain $P_{+}\left(\Lambda^{4-}(V)\right)=P_{+}\left(\varphi_{+}^{*}\right)=0$, where $\varphi_{+}^{*}$ is the dual element of the fundamental 4 -form $\varphi_{+}$.

Let $C$ denote the subspace of $\Lambda^{4}(V)$ given by

$$
C=\left\{\xi \in \Lambda^{4}(\nabla) \mid * \xi=+\xi \text { and }\left\langle\xi, \varphi_{+}^{*}\right\rangle=P_{+} \xi=0\right\}
$$

It is easy to verify that kernel $P_{+}=\left\{\varphi_{+}^{*}\right\} \oplus \Lambda^{4-}(V) \oplus C$ and this sum is orthogonal direct.

Considering the dual spaces of $\left\{\varphi_{+}^{*}\right\}, \Lambda^{4-}(V)$ and $O$ (i.e. the spaces $\Lambda_{1+}^{4}\left(V^{*}\right)$, $\Lambda_{3+}^{4}\left(V^{*}\right)$ and $\Lambda_{2+}^{4}\left(\nabla^{*}\right)$, respectively) we get (3.7). Furthermore, all the spaces have the stated dimensions. Using (3.3), it is obvious that Spin (7) acts irreducibly on $\Lambda_{i+}^{4}\left(V^{*}\right)$. Similarly, we obtain the decomposition

$$
\Lambda^{4}\left(V^{*}\right)=\Lambda_{1-}^{4}\left(V^{*}\right) \oplus \Lambda_{2-}^{4}\left(V^{*}\right) \oplus \Lambda_{3-}^{4}\left(V^{*}\right) \oplus \Lambda_{4-}^{4}\left(V^{*}\right)
$$

if $P_{-}$is the vector cross product on $V$.

## 4. - The space of covariant derivatives of the fundamental 4-form.

The covariant derivative $\nabla \varphi$ of the fundamental form $\varphi$ of a 3 -fold vector cross product on a 8 -dimensional manifold is a covariant tensor of degree 5 which has various symmetry properties. In this section, we shall define a finite dimensional vector space $W$ that will consist of those tensors that posses the same symmetries, and study the decomposition of $W$ into irreducible components under the natural representation of Spin (7).

Let us consider the space $\nabla^{*} \otimes \Lambda^{4}\left(V^{*}\right)$, and let $W$ be the subspace of $\nabla^{*} \otimes \Lambda^{4}\left(V^{*}\right)$ defined by

$$
W=\left\{\alpha \in V^{*} \otimes \Lambda^{4}\left(V^{*}\right) \mid \alpha(w, x \wedge y \wedge z \wedge P(x \wedge y \wedge z))=0 \text { for all } w, x, y, z \in V\right\}
$$

Lievima 4.1. $-\operatorname{dim} W=56$.
Proof. - Clearly $W$ is naturally isomorphic to $V^{*} \otimes \Lambda_{4}^{4}\left(V^{*}\right)$. Since $\operatorname{dim} V^{*}=8$ and $\operatorname{dim} \Lambda_{4}^{4}\left(V^{*}\right)=7$ by Lemma 3.3, the result follows.

We note that there is a natural inner product on $W$ given by

$$
\langle\alpha, \beta\rangle=\sum_{h, i, j, k, l=0}^{7} \alpha\left(e_{n}, e_{i} \wedge e_{j} \wedge e_{k} \wedge e_{l}\right) \beta\left(e_{n}, e_{i} \wedge e_{j} \wedge e_{h} \wedge e_{l}\right),
$$

where $\left\{e_{0}, \ldots, e_{7}\right\}$ is an arbitrary orthonormal basis of $V$.
It will also be useful to consider linear maps $L_{3}: W \rightarrow A^{3}\left(V^{*}\right)$, and $L_{1}: W \rightarrow V^{*}$ given by

$$
\begin{aligned}
L_{3}(\alpha)(x \wedge y \wedge z) & =\sum_{i=0}^{7} \alpha\left(e_{i}, e_{i} \wedge x \wedge y \wedge z\right) \\
L_{1}(\alpha)(x) & =\sum_{i, j, k=0}^{7} \alpha\left(P\left(e_{i} \wedge e_{j} \wedge e_{k}\right), e_{i} \wedge e_{j} \wedge e_{k} \wedge x\right)
\end{aligned}
$$

for $x, y, z \in V, \alpha \in W$. First, we shall study the properties of those maps.

Lemira 4.2. - We have

$$
\begin{equation*}
L_{1}(\alpha)(x)=-\sum_{i, j, k=0}^{T} \alpha\left(e_{i}, e_{j} \wedge e_{k} \wedge P\left(e_{i} \wedge e_{j} \wedge \epsilon_{k}\right) \wedge x\right)=6\left(p \circ L_{3}\right)(\alpha)(x), \tag{4.1}
\end{equation*}
$$

for $x \in V, \alpha \in W$.
Proof. - Substituting $P\left(e_{i} \wedge e_{j} \wedge e_{k}\right)$ for $e_{k}$ in the definition of $L_{1}$ and using (2.5), we obtain

$$
\begin{align*}
L_{1}(\alpha)(x) & =\sum_{i, j, k=0}^{7} \alpha\left(P\left(e_{i} \wedge e_{j} \wedge P\left(e_{i} \wedge e_{j} \wedge e_{k}\right)\right), e_{i} \wedge e_{j} \wedge P\left(e_{i} \wedge e_{j} \wedge e_{k}\right) \wedge x\right)=  \tag{4.2}\\
& =\sum_{i, j, k=0}^{7}\left\{\alpha\left(\left(-1+\delta_{i j}^{2}\right) e_{k}, e_{i} \wedge e_{j} \wedge P\left(e_{i} \wedge e_{j} \wedge e_{k}\right) \wedge x\right)+\right. \\
& +\alpha\left(\left(\delta_{j k}-\delta_{i k} \delta_{i j}\right) e_{j}, e_{i} \wedge e_{j} \wedge P\left(e_{i} \wedge e_{j} \wedge e_{k}\right) \wedge x\right)+ \\
& \left.+\alpha\left(\left(\delta_{i k}-\delta_{j k} \delta_{i j}\right) e_{i}, e_{i} \wedge e_{j} \wedge P\left(e_{i} \wedge e_{j} \wedge e_{k}\right) \wedge x\right)\right\}= \\
& =-\sum_{i, j, k=0}^{7} \alpha\left(e_{k}, e_{i} \wedge e_{j} \wedge P\left(e_{i} \wedge e_{j} \wedge e_{k}\right) \wedge x\right)= \\
& =-\sum_{i, j, k=0}^{7} \alpha\left(e_{i}, e_{j} \wedge e_{k} \wedge P\left(e_{i} \wedge e_{j} \wedge e_{k}\right) \wedge x\right)
\end{align*}
$$

On other hand, from definition of $p: V \rightarrow A^{3}(V)$, we see that

$$
\left(p \circ L_{3}\right)(\alpha)(x)=-\frac{1}{6} \sum_{i, j, k=0}^{7} \alpha\left(e_{i}, e_{i} \wedge e_{j} \wedge e_{k} \wedge P\left(e_{j} \wedge e_{k} \wedge x\right)\right)=\frac{1}{6} L_{1}(\alpha)(x)
$$

which proves (4.1).
Lemma 4.3. - Let be $\alpha \in W$, and suppose there is a constant $a$ such that

$$
\begin{align*}
& a(P(x \wedge y \wedge z), x \wedge y \wedge z \wedge w)=  \tag{4.3}\\
& \quad=a\{\alpha(x, P(x \wedge y \wedge z) \wedge y \wedge z \wedge w)
\end{align*} \quad-\alpha(y, P(x \wedge y \wedge z) \wedge x \wedge z \wedge w)+
$$

for all $x, y, z, w \in V$. If $a \neq-\frac{1}{3}$ then $\left(p \circ L_{3}\right)(\alpha)=0$.
Proof. - From Lemma 4.2 and equation (4.3) we obtain

$$
\begin{aligned}
\left(p \circ L_{3}\right)(\alpha)(x) & =\frac{1}{6} L_{1}(\alpha)(x)=\frac{1}{6} \sum_{i, j, k=0}^{7} \alpha\left(P\left(e_{i} \wedge e_{j} \wedge e_{k}\right), e_{i} \wedge e_{j} \wedge e_{k} \wedge x\right)= \\
& =\frac{a}{6} \sum_{i, j, k=0}^{7}\left\{\alpha\left(e_{i}, P\left(e_{i} \wedge e_{j} \wedge e_{k}\right) \wedge e_{j} \wedge e_{k} \wedge x\right)-\alpha\left(e_{j}, P\left(e_{i} \wedge e_{j} \wedge e_{k}\right) \wedge e_{i} \wedge e_{k} \wedge x\right)+\right. \\
& \left.+\alpha\left(e_{k}, P\left(e_{i} \wedge e_{j} \wedge e_{k}\right) \wedge e_{i} \wedge e_{j} \wedge x\right)\right\}=-\frac{\alpha}{2} L_{1}(\alpha)(x)=-3 a\left(p \circ L_{3}\right)(\alpha)(x)
\end{aligned}
$$

hence the lemma follows.

We now define two subspaces $W_{1}$ and $W_{2}$ of $W$ by

$$
\begin{aligned}
& W_{1}=\left\{\alpha \in W \mid L_{1}(\alpha)=0 \text { or } p \circ L_{3}(\alpha)=0\right\} \\
& \begin{aligned}
W_{2}=\left\{\alpha \in W \mid 28 \alpha\left(w, x_{1} \wedge x_{2} \wedge x_{3} \wedge x_{4}\right)\right. & = \\
& =\sum_{i=1}^{4}(-1)^{i+1}\left\{p \circ L_{3}(\alpha)\left(x_{i}\right) \varphi\left(w \wedge x_{1} \wedge \ldots \wedge \hat{x}_{i} \wedge \ldots \wedge x_{4}\right)+\right. \\
& \left.\left.+7<w, x_{i}\right\rangle L_{3}(\alpha)\left(x_{1} \wedge \ldots \wedge \hat{x}_{i} \wedge \ldots \wedge x_{4}\right)\right\}
\end{aligned}
\end{aligned}
$$

The usual representation of $\operatorname{Spin}(7)$ on $V$ induces a representation of Spin (7) on $W$. We shall show that $W_{1}$ and $W_{2}$ are the two irreducible components of this induced representation. First, we need several lemmas.

Lemma 4.4. - $W \cap A^{5}\left(V^{*}\right)=\{0\}$.
Proof. - Let be $\alpha \in W \cap \Lambda^{5}\left(V^{*}\right)$, and $w, x, y, z \in V$. If $z=\lambda P(w \wedge x \wedge y)$, then for any $u \in V$ we have

$$
\alpha(w \wedge x \wedge y \wedge z \wedge u)=\lambda \alpha(u \wedge w \wedge x \wedge y \wedge P(w \wedge x \wedge y))=0
$$

Therefore $w, x, y, z$ and $P(w \wedge x \wedge y)$ may be assumed to be orthogonal, and then $\{w, x, y, z, P(w \wedge x \wedge y), P(w \wedge x \wedge z), P(w \wedge y \wedge z), P(x \wedge y \wedge z)\}$ forms an orthogonal basis for $V$. Thus $\alpha(w \wedge x \wedge y \wedge z \wedge u)=0$ for all $u \in V$. Hence $\alpha=0$.

Lemma 4.5. - Suppose $\alpha \in W$ with $L_{3}(\alpha) \neq 0$ and

$$
\begin{align*}
& \alpha\left(w, x_{1} \wedge x_{2} \wedge x_{3} \wedge x_{4}\right)=\sum_{i=1}^{4}(-1)^{i+1}\left\{a\left(p \circ L_{3}\right)(\alpha)\left(x_{i}\right) \varphi\left(w \wedge x_{1} \wedge \ldots \hat{x}_{i} \wedge \ldots \wedge x_{4}\right)+\right.  \tag{4.4}\\
&\left.+b\left\langle w, x_{i}\right\rangle L_{3}(\alpha)\left(x_{1} \wedge \ldots \wedge \hat{x}_{i} \wedge \ldots \wedge x_{4}\right)\right\}
\end{align*}
$$

for $w, x_{1}, x_{2}, x_{3}, x_{4} \in V$. Then $a=1 / 28, b=1 / 4$ and $P_{p} L_{3}(\alpha)=7 L_{3}(\alpha)$.
Proof. - In (4.4) we consider $x_{1}=e_{i}, x_{2}=e_{j}, x_{3}=e_{k}, x_{4}=P\left(e_{i} \wedge e_{j} \wedge e_{k}\right)$ and take the sum over $i, j, k=0, \ldots, 7$. Then

$$
\begin{equation*}
(168 a-24 b) p L_{3}(\alpha)(w)=0 \tag{5}
\end{equation*}
$$

and thus $7 a=b$.
Applying (4.4) and (4.5), we compute $L_{3}(\alpha)(y \wedge z \wedge u)$ and get

$$
\begin{equation*}
(1-35 a) L_{3}(\alpha)=-a P p L_{3}(\alpha) \tag{4.6}
\end{equation*}
$$

Hence, applying $p$ to both sides of (4.6), we obtain $a=1 / 28$, and then $b=1 / 4$. Finally, substituting the value of $a$ in (4.6) we find $P p L_{3}(\alpha)=7 L_{3}(\alpha)$.

Lemma 4.6.

$$
\begin{align*}
& W_{2} \cap \text { kernel } L_{3}=\{0\}  \tag{4.7}\\
& W_{1} \cap W_{2}=\{0\}  \tag{4.8}\\
& \text { kernel } L_{3}=\{0\} \tag{4.9}
\end{align*}
$$

Proof. - (4.7) is an obvious consequence of the defining condition of the space $W_{2}$. In order to prove (4.8) let $\alpha \in W_{1} \cap W_{2}$; then $L_{1}(\alpha)=0$. Now, by using (4.1), (4.7) and lemma 4.5, we see that $L_{8}(\alpha)=0$. Hence from (4.7) we have $\alpha=0$. On the other hand, it is easy show that

$$
L_{3}\left(W_{1}\right) \subset \Lambda_{1}^{3}\left(V^{*}\right) \quad \text { and } \quad L_{3}\left(W_{2}\right) \subset \Lambda_{2}^{3}\left(V^{*}\right)
$$

Since the spaces $L_{3}\left(W_{1}\right)$ and $L_{3}\left(W_{2}\right)$ both are invariants under the induced representation of Spin (7) on $\Lambda^{3}\left(V^{*}\right)$, it follows, from Lemma 3.2, that

$$
L_{3}\left(W_{1}\right)=\Lambda_{1}^{3}\left(V^{*}\right) \quad \text { and } \quad L_{3}\left(W_{2}\right)=\Lambda_{2}^{3}\left(V^{*}\right)
$$

Hence from (4.7), we get $\operatorname{dim} W_{1} \geqslant 48$ and $\operatorname{dim} W_{2}=8$. Now (4.8) and Lemma 4.1. imply (4.9).

Theoreiv 4.7. - We have $W=W_{1} \oplus W_{2}$. This direct sum is orthogonal, and it is preserved under the induced representation of $\$$ pin (7) on $W$. The induced representation of Spin (7) on $W_{i}$ is irreducible and

$$
\operatorname{dim} W_{1}=48, \quad \operatorname{dim} W_{2}=8
$$

Proof. - In the Lemma 4.6 the dimensions of $W_{i}$ have been calculated, and also it has been proved that $W=W_{1} \oplus W_{2}$, where the sum is direct and orthogonal.

Obviously, the representation of Spin (7) on $W$ is $\varphi_{\lambda_{1}} \oplus \varphi_{\lambda_{3}}$. Since the weights of this representation are
$\pm \frac{1}{2}\left(\omega_{1}+\omega_{2}+\omega_{3}\right)(4), \quad \pm \frac{1}{2}\left(\omega_{1}+\omega_{2}-\omega_{3}\right)\left(4,, \quad \pm \frac{1}{2}\left(\omega_{1}-\omega_{2}+\omega_{3}\right)(4)\right.$,
$\pm \frac{1}{2}\left(-\omega_{1}+\omega_{2}+\omega_{3}\right)(4), \quad \pm \frac{1}{2}\left(3 \omega_{1}+\omega_{2}+\omega_{3}\right), \quad \pm \frac{1}{2}\left(3 \omega_{1}+\omega_{2}-\omega_{3}\right)$,
$\pm \frac{1}{2}\left(3 \omega_{1}-\omega_{2}+\omega_{3}\right), \quad \pm \frac{1}{2}\left(3 \omega_{1}-\omega_{2}-\omega_{3}\right), \quad \pm \frac{1}{2}\left(\omega_{1}+3 \omega_{2}+\omega_{3}\right)$,
$\pm \frac{1}{2}\left(\omega_{1}+3 \omega_{2}-\omega_{3}\right), \quad \pm \frac{1}{2}\left(-\omega_{1}+3 \omega_{2}+\omega_{3}\right), \quad \pm \frac{1}{2}\left(-\omega_{1}+3 \omega_{2}-\omega_{3}\right)$,
$\pm \frac{1}{2}\left(\omega_{1}+\omega_{2}+3 \omega_{3}\right), \quad \pm \frac{1}{2}\left(\omega_{1}-\omega_{2}+3 \omega_{3}\right), \quad \pm \frac{1}{2}\left(-\omega_{1}+\omega_{2}+3 \omega_{3}\right)$,
$\pm \frac{1}{2}\left(-\omega_{1}-\omega_{2}+3 \omega_{3}\right)$,
we have

$$
\begin{equation*}
\varphi_{\lambda_{1}} \otimes \varphi_{\lambda_{3}}=\varphi_{\lambda_{3}} \oplus \varphi_{\lambda_{1}+\lambda_{3}} \tag{4.10}
\end{equation*}
$$

Therefore, $W=W_{1} \oplus W_{2}$ is the decomposition of. $W$ into irreducible components under the natural action of $\operatorname{Spin}(7)$. Moreover, $\varphi_{\lambda_{3}}$ and $\varphi_{\lambda_{1}+\lambda_{3}}$ are the irreducible representations corresponding to $W_{2}$ and $W_{1}$, respectively.

## 5. - The foar classes of 8 -dimensional Riemannian manifolds with a 3 -fold vector cross product.

Using the results obtained in the previous sections, we now establish a classification of 8 -dimensional Riemannian manifolds with a 3 -fold vector cross product.

Let $M$ be a $C^{\infty} 8$-dimensional Riemannian manifold with metric $\langle$,$\rangle . Denote$ by $\mathcal{X}(M)$ the Lie algebra of $C^{\infty}$ vector fields on $M$, and by $\mathcal{F}(M)$ the algebra of $C^{\infty}$ functions on $M$. For each $m \in M$ the tangent space at $m$ will be denoted by $M_{m}$.

Definition. - We say that $(M,\langle\rangle$,$) has a 3$-fold vector cross product $P$ if each tangent space $M_{m}$ has a 3 -fold vector cross product $P_{m}: M_{m} \times M_{m} \times M_{m} \rightarrow M_{m}$, and the mapping $m \rightarrow P_{m}$ is $0^{\infty}$.

It is clear that $P$ gives rise to a tensor field $P: \mathfrak{X}(M) \times \mathfrak{X}(M) \times \mathfrak{X}(M) \rightarrow \mathfrak{X}(M)$ of type $(3,1)$, which satisfies

$$
\begin{align*}
& \langle P(X, Y, Z), X\rangle=\langle P(X, Y, Z), Y\rangle=\langle P(X, Y, Z), Z\rangle=0  \tag{5.1}\\
& \|P(X, X, Z)\|^{2}=\operatorname{det}\left(\begin{array}{lll}
\|X\|^{2} & \langle X, Y\rangle & \langle X, Z\rangle \\
\langle Y, X\rangle & \|Y\|^{2} & \langle Y, Z\rangle \\
\langle Z, X\rangle & \langle Z, Y\rangle & \|Z\|^{2}
\end{array}\right) \tag{5.2}
\end{align*}
$$

for all $X, Y, Z \in \mathfrak{X}(M)$.
Furthermore, the algebraic study carried out in the previous sections can obviously be extended to manifolds. We note that the fundamental 4 -form $\varphi$ becomes a differential 4 -form on $M$.

Let $\nabla$ denote the Riemannian connection of $\langle$,$\rangle . The covariant derivatives$ $\nabla P$ and $\nabla \varphi$ are given by

$$
\begin{align*}
\nabla_{W}(P)(X, Y, Z)=\nabla_{W}(P(X, Y, Z))-P\left(\nabla_{W} X, Y, Z\right)-P(X, & \left.\nabla_{W} Y, Z\right)-  \tag{5.3}\\
& -P\left(X, Y, \nabla_{W} Z\right)
\end{align*}
$$

$$
\begin{align*}
& \nabla_{U}(\varphi)(W, X, Y, Z)=U\{\varphi(W, X, X, Z)\}-\varphi\left(\nabla_{U} W, X, Y, Z\right)-  \tag{5.4}\\
& \quad-\varphi\left(W, \nabla_{U} X, Y, Z\right)-\varphi\left(W, X, \nabla_{U} Y, Z\right)-\varphi\left(W, X, Y, \nabla_{U} Z\right)
\end{align*}
$$

for $U, W, X, Y, Z \in \mathfrak{X}(M)$. From (5.3) and (5.4) one has

$$
\begin{equation*}
\nabla_{U}(\varphi)(W, X, Y, Z)=\left\langle\nabla_{U}(P)(W, X, Y), Z\right\rangle \tag{5.5}
\end{equation*}
$$

and so the study of the covariant derivatives of $P$ is equivalent to that of the covariant derivatives of the fundamental 4 -form $\varphi$.

Lemina 0.1.

$$
\begin{align*}
& \nabla_{U}(\varphi)(W, X, Y . Z)=-\nabla_{U}(\varphi)(X, W, Y, Z)=-\nabla_{0}(\varphi)(W, Y, X, Z)=  \tag{5.6}\\
& =-\nabla_{\nabla}(\varphi)(W, X, Z, Y), \\
& \nabla_{W}(\varphi)(X, I, Z, P(X, Y, Z))=0, \tag{57}
\end{align*}
$$

for all $U, W, X, Y, Z \in \mathscr{X}(M)$.
Proof. - (5.6) is easily checked from (5.4). (5.7) is proved by applying the vector field $W$ to both sides of (5.2) and using (5.3) and (5.5).

We shall henceforth write $\nabla_{W}(P)(X \wedge Y \wedge Z)$ for $\nabla_{W}(P)(X, Y, Z)$, etc.
Now consider the natural 8 -dimensional representation of Spin (7) on each tangent space $M_{m}$, and let $W_{m}$ be the space

$$
W_{m}=\left\{\alpha \in M_{m}^{*} \otimes A^{4}\left(M_{m}^{*}\right) \mid \alpha(w, x \wedge y \wedge z \wedge P(x \wedge y \wedge z))=0 \text { for all } w, x, y, z \in M_{m}\right\}
$$

Then the induced representation of Spin (7) on $W_{m}$ has the two components $W_{m 1}$, $W_{m 2}$ as described in section 4. It is possible to form from these two a total of four invariant subspaces of $W_{m}$ (including $\{0\}$ and $W_{m}$ ).

Definition. - Let $M$ be a 8 -dimensional Riemannian manifold with a 3 -fold vector cross product. For $m \in M$, let $U_{m}$ denote one of the four invariant subspaces of $W_{m}$. Then $\mathfrak{U}$ will denote the class of all 8 -dimensional Riemannian manifolds with a 3-fold vector cross product such that $(\nabla \varphi)_{m} \in U_{m}$ for all $m \in M$.

In order to make this definition meaningful, one must note that for any 8 -dimensional Riemannian manifold $M$ with a 3 -fold vector cross product, $(\nabla \varphi)_{m} \in W_{m}$ for all $m \in M$ by virtue of (5.6) and (5.7).

The class corresponding to $W_{m i}$ will be denoted by $\mathcal{W}_{i}$. $\mathcal{J}$ will also correspond to $\{0\}$ and $W$ to $W_{m}$.

Remark. - There are obvious analogies between some of these classes and the corresponding ones for almost Hermitian manifolds [17], and for the 7 -dimensional Riemannian manifolds with a 2 -fold vector cross product [9]. Nevertheless, Lemma 4.4 implies that if $\nabla_{W}(\varphi)(W \wedge X \wedge Y \wedge Z)=0$ for all $W, X, Y, Z \in \mathfrak{X}(M)$, then $\nabla \varphi=0$. That is, the class $\mathcal{N S}$ of 8 -dimensional Riemannian manifolds with a

3-fold nearly parallel vector cross product, defined by analogy with the nearly Kähler manifolds in [17], is actually the class $\mathcal{T}$. This was proved in [13] by a different method.

Let $d$ and $\delta$ be the exterior differential and the coderivative of the Riemannian manifold $M$. If $\eta$ is a 4 -form on $M$ we have the following explicit formulas for $d \eta$ and $\delta \eta$

$$
\begin{gather*}
d \eta(U \wedge W \wedge X \wedge Y \wedge Z)=\nabla_{U}(\eta)(W \wedge X \wedge Y \wedge Z)-\nabla_{W}(\eta)(U \wedge X \wedge Y \wedge Z)+  \tag{5.8}\\
+\nabla_{\Sigma}(\eta)(U \wedge W \wedge Y \wedge Z)-\nabla_{F}(\eta)(U \wedge W \wedge X \wedge Z)+\nabla_{Z}(\eta)(U \wedge W \wedge X \wedge Y) \\
\delta \eta(X \wedge Y \wedge Z)=-\sum_{i=0}^{7} \nabla_{E_{i}}(\eta)\left(E_{i} \wedge X \wedge Y \wedge Z\right) \tag{5.9}
\end{gather*}
$$

for $U, W, X, Y, Z \in \mathfrak{X}(M)$. Here $\left\{E_{0}, \ldots, E_{7}\right\}$ is an arbitrary local frame filed.
Now, assume that $M$ has a vector cross product $P$ with fundamental 4 -form $\varphi$, then we note that

$$
\begin{gather*}
\delta \varphi=-L_{3}(\nabla \varphi)  \tag{5.10}\\
L_{1}(\nabla \varphi)(X)=\sum_{i, i, k=0}^{7} \nabla_{P\left(E_{i} \wedge E_{j} \wedge E_{k)}\right)}(\varphi)\left(E_{i} \wedge E_{j} \wedge E_{k} \wedge X\right), \tag{5.11}
\end{gather*}
$$

for $X \in \mathfrak{X}(M)$. Using (5.10), (5.11) and Lemma 4.2 it follows that

$$
\begin{equation*}
L_{1}(\nabla \varphi)=-6 p(\delta \varphi) \tag{5.12}
\end{equation*}
$$

Also, we have
Lemma 5.2. $-d \varphi=0$ if and only if $\delta \varphi=0$.
Proof. - We write the 3 -form $\delta \varphi$ in terms of the exterior differential $d$ and of the Hodge star operator *

$$
\begin{equation*}
\delta \varphi=-* d * \varphi \tag{5.13}
\end{equation*}
$$

Then, applying Lemma 2.4 to (5.13), we get the result.
Remark. - Let $\mathcal{A T}$ and $S T$ be the classes of 8 -dimensional Riemannian manifolds with a 3 -fold vector cross product satisfying $d \varphi=0$ and $\delta \varphi=0$, respectively. Then from Lemma 5.2 we have $\mathcal{A T}=\delta \mathcal{S}$. Furthermore, (4.9) and (5.10) imply that if $\delta p=0$, then $\nabla \varphi=0$. Hence we get $\mathfrak{T}=\mathcal{N T}=\mathcal{A T}=\mathcal{S} T$.

Theorem 5.3. - The defining relations for each of the four classes are given in table 1 below

Table 1.

| Class | Defining relations |
| :---: | :---: |
| $\mathfrak{T}=\mathfrak{N} \mathfrak{T}=\mathfrak{A} \mathfrak{T}=\mathfrak{S T}$ | $\begin{gathered} \nabla \varphi=0 \\ \text { (or } d \varphi=0, \text { or } \delta \varphi=0 \text { ) } \end{gathered}$ |
| $w_{1}$ | $L_{1}(\nabla \varphi)=0 \quad($ or $p \delta \varphi=0)$ |
| $w_{2}=\mathfrak{C J}$ | $\begin{aligned} & 28 \nabla_{W}(\varphi)\left(X_{1} \wedge X_{2} \wedge X_{3} \wedge X_{4}\right)= \\ & =-\sum_{i=1}^{4}(-1)^{i+1}\left\{p \delta \varphi\left(X_{i}\right) \varphi\left(W \wedge X_{1} \wedge \ldots \wedge \hat{X}_{i} \wedge \ldots \wedge X_{4}\right)+\right. \\ & \left.\quad+7\langle W, X\rangle \delta \varphi\left(X_{1} \wedge \ldots \wedge \hat{X}_{i} \wedge \ldots \wedge X_{4}\right)\right\} \end{aligned}$ |
| $w=w_{1} \oplus w_{2}$ | No relation |

## 6. - Conformal changes of metric.

In this section, we determine which of the 4 classes are preserved under a conformal change of metric. Let $M$ be a 8 -dimensional Riemannian manifold with metric $\langle$,$\rangle ; and let \langle,\rangle^{0}$ be a metric on $M$ conformally related to $\langle$,$\rangle via$

$$
\begin{equation*}
\langle,\rangle^{0}=e^{2 \sigma}\langle,\rangle, \tag{6.1}
\end{equation*}
$$

where $\sigma \in \mathscr{F}(M)$. It is well known ([11], [12]) that the connections $\nabla^{0}$ of $\left\langle,>^{0}\right.$ and $\nabla$ of $\langle$,$\rangle are related by$

$$
\begin{equation*}
\nabla_{x}^{0} Y=\nabla_{x} Y+(X \sigma) Y+(Y \sigma) X-\langle X, Y\rangle \operatorname{grad} \sigma \tag{6.2}
\end{equation*}
$$

for $X, Y \in \mathfrak{X}(M)$, and where grad $\sigma \in \mathfrak{X}(M)$ is the vector field such that $\langle X, \operatorname{grad} \sigma\rangle=$ $=X \sigma$ for $X \in \mathfrak{X}(M)$.

Suppose that $(M,\langle\rangle$,$) has a 3$-fold vector cross product $P$. Let $P^{0}$ be a 3 -fold vector cross product on $\left(M,\langle,\rangle^{0}\right)$ and $f \in \mathscr{F}(M)$ such that $P^{0}=f P$. Then

$$
\begin{aligned}
&\left\|P^{0}(X \wedge Y \wedge Z)\right\|^{02}=\|X \wedge Y \wedge Z\|^{02}=e^{6 \sigma}\|X \wedge Y \wedge Z\|^{2}=e^{6 \sigma}\|P(X \wedge Y \wedge Z)\|^{2}= \\
&=e^{4 \sigma}\|P(X \wedge Y \wedge Z)\|^{02}
\end{aligned}
$$

for $X, Y, Z \in \mathscr{X}(M)$. Thus we must have $f^{2}=e^{4 \sigma}$. This leads us to the following
Definition. - Let $M$ be a 8 -dimensional Riemannian manifold with metrics $\langle\rangle,,\langle,\rangle^{0}$ conformally related by (6.1). Let $P$ be a 3 -fold vector cross product
on ( $M,\langle$,$\rangle ), then$

$$
\begin{equation*}
P^{0}=e^{2 a} P, \tag{6.3}
\end{equation*}
$$

is a 3 -fold vector cross product on $\left(M,\langle,\rangle^{0}\right)$. In this case we say that $P$ and $P^{0}$ are conformally related.

Let $\varphi, \varphi^{0}$ denote the fundamental 4 -forms corresponding to $P$ and $P^{0}$, and let $p, p^{0}$ be the corresponding adjoints. Also let $\delta, \delta^{0}$ denote the coderivatives of $\langle\rangle,$, $\langle,\rangle^{0}$, respectively

Leinua 6.1. - We have

$$
\begin{align*}
& \varphi^{0}=e^{4 \sigma} \varphi,  \tag{6.4}\\
& p^{0}=e^{-2 \sigma} p, \tag{6.5}
\end{align*}
$$

$$
\begin{equation*}
\left.+\sum_{i=1}^{4}(-1)^{i}\left(\left(X_{i} \sigma\right) \varphi\left(W \wedge X_{1} \wedge \ldots \wedge \hat{X}_{i} \wedge \ldots \wedge X_{4}\right)+\left\langle W, X_{i}\right\rangle P\left(X_{1} \wedge \ldots \wedge \hat{X}_{i} \wedge \ldots \wedge X_{4}\right) \sigma\right)\right\} \tag{6.6}
\end{equation*}
$$

for $W, X_{1}, X_{2}, X_{3}, X_{4} \in \mathfrak{X}(M)$,

$$
\begin{equation*}
\delta^{0} \varphi^{0}(X \wedge Y \wedge Z)=e^{2 \sigma}\{\delta \dot{\varphi}(X \wedge Y \wedge Z)+4 P(X \wedge \Psi \wedge Z) \sigma\} \tag{6.7}
\end{equation*}
$$

for $X, Y, Z \in X(M)$,

$$
\begin{align*}
p^{0} \delta^{0} \varphi^{0} & =p \delta \varphi+28 d \sigma  \tag{6.8}\\
d \varphi^{0} & =e^{4 \sigma}\{4 d \sigma \wedge \varphi+d \varphi\} . \tag{6.9}
\end{align*}
$$

Proof. - Equation (6.4) is an obvious consequence of (6.1) and (6.3). Taking the exterior derivative of (6.4) we get (6.9). Equation (6.5) follows from (6.1), (6.3) and from the fact that if $\left\{E_{0}, \ldots, E_{n}\right\}$ is a frame field on an open subset of $(M,\langle\rangle$,$) ,$ then $\left\{e^{-\sigma} E_{0}, \ldots, e^{-\sigma} E_{7}\right\}$ is a frame field on an open subset of $\left(M,\langle,\rangle^{0}\right)$. (6.6) follows from (5.4), (6.2) and (6.4). From (6.6) and (5.9) we deduce (6.7); and from (6.5), (6.7) and Lemma 2.2 (ii), we obtain (6.8).

Next we shall introduce a tensor field $v$ that will turn out to be a conformal invariant for 3 -fold vector cross products. A similar tensor field has been introduced in [17] for almost Hermitian manifolds, and in [9] for the Riemannian manifolds with structure group $G_{2}$.

Definition. - Let $M$ be a 8 -dimensional Riemannian manifold with metric $\langle$, and vector cross product $P$. Then $v$ is the covariant tensor field of type $(5,0)$
given by

$$
\begin{align*}
& v\left(W, X_{1}, X_{2}, X_{3}, X_{4}\right)=\nabla_{W}(\varphi)\left(X_{1} \wedge X_{2} \wedge X_{3} \wedge X_{4}\right)+  \tag{6.10}\\
&+1 / 28 \sum_{i=1}^{4}(-1)^{i+1}\left\{p \delta \varphi\left(X_{i}\right) \varphi\left(W \wedge X_{1} \wedge \ldots \wedge \hat{X}_{i} \wedge \ldots \wedge X_{4}\right)+\right. \\
&\left.+7\left\langle W, X_{i}\right\rangle \delta \varphi\left(X_{1} \wedge \ldots \wedge \hat{X}_{i} \wedge \ldots \wedge X_{4}\right)\right\}
\end{align*}
$$

for $W, X_{1}, X_{2}, X_{3}, X_{4} \in \mathfrak{X}(M)$.
Lemma 6.2. - Suppose $(P,\langle\rangle$,$) and \left(P^{0},\langle,\rangle^{0}\right)$ are conformally related. Then the corresponding tensor fields $v$ and $\nu^{0}$ satisfy $\nu^{0}=e^{4 \sigma} v$.

Proof. - This follows from Lemma 6.1 and equation (6.10).
Definition. - Let $\mathcal{U}$ be one of the four classes given in table $I$. Then $\mathscr{U}^{0}$ will denote the class of all manifolds locally conformally related to manifolds in $\mathrm{U}^{\mathrm{U}}$. In other words, $\left(M, P^{0},\langle,\rangle^{0}\right) \in \mathcal{U}^{0}$ if and only if for each $m \in M$ there exists an open neighborhood $V$ of $m$ such that $\left(V, P^{0},\langle,\rangle^{0}\right)$ is conformally related to $(V, P,\langle\rangle,) \in \mathcal{U}$.

Theorem 6.3. - For any $\mathcal{U}$ given in table 1 we have $\mathcal{U}^{\circ} \subseteq w_{2} \oplus \mathcal{U}$. Thus $\mathcal{U}^{0}=\mathscr{U}$ if and only if $W_{2} \subseteq \mathcal{U}$. Hence the conformally invariant classes are $\mathcal{W}_{2}$ and $w$.

Proof. - The defining condition for each of the classes mentioned in the statement of the Theorem can be rewritten in terms of $\nu$. From table 1 we have

$$
M \in W_{2} \quad \text { if and only if } \quad v=0
$$

## 7. - Inclusion relations.

In this section, we establish the strictness of some of the inclusions among the four classes.

First we note that the special unitary group $S U(3)=U(3) \cap S l(3, C)$ is a parallelizable 8-dimensional manifold, and hence $S U(3) \in \mathcal{W}$.

It is well known (see, for example, $[19$, p. 515$]$ ) that the Lie algebra $s u(3)$, of $S U(3)$, is a compact real form of simple Lie algebra $s l(3, C)$. Thus ([19, p. 181]) the killing form $B$ of $s u(3)$ is strictly negative definite, being in fact equal to the restriction of Killing form of $s l(3, C)$ to $s u(3) \times s u(3)$. Therefore, ([19, p. 187]), $B(X, Y)=6 T r(X Y)$ for all $X, Y \in s u(3)$. Furthermore, the bilinear symmetric form $-B$ defines a bi-invariant metric on $S U(3)$.

On the other hand, since $s u(3)$ is a 8 -dimensional vector space over $\boldsymbol{R}$ with a (positive definite) inner product, it follows that $s u(3)$ has a Cayley multiplication, and hence the two 3 -fold vector cross products $P_{ \pm}$given as in section 2 . We deter-
mine $P_{ \pm}$identifying $s u(3)$ with the space Cay by means of the orthonormal basis $\left\{1, e_{0}, \ldots, e_{6}\right\}$ of $s u(3)$ given by

$$
\begin{array}{ll}
1=\frac{1}{\sqrt{12}}\left(\begin{array}{ccc}
i & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & -i
\end{array}\right), & e_{0}=\frac{1}{\sqrt{12}}\left(\begin{array}{rrr}
0 & 1 & 0 \\
-1 & 0 & 0 \\
0 & 0 & 0
\end{array}\right) \\
e_{1}=\frac{1}{\sqrt{12}}\left(\begin{array}{ccc}
0 & 0 & 1 \\
0 & 0 & 0 \\
-1 & 0 & 0
\end{array}\right), & e_{2}=\frac{1}{\sqrt{12}}\left(\begin{array}{ccc}
0 & 0 & 0 \\
0 & 0 & 1 \\
0 & -1 & 0
\end{array}\right), \\
e_{3}=\frac{1}{6}\left(\begin{array}{ccc}
i & 0 & 0 \\
0 & -2 i & 0 \\
0 & 0 & i
\end{array}\right), & e_{4}=\frac{1}{\sqrt{12}}\left(\begin{array}{ccc}
0 & i & 0 \\
i & 0 & 0 \\
0 & 0 & 0
\end{array}\right), \\
e_{5}=\frac{1}{\sqrt{12}}\left(\begin{array}{lll}
0 & 0 & i \\
0 & 0 & 0 \\
i & 0 & 0
\end{array}\right), & e_{6}=\frac{1}{\sqrt{12}}\left(\begin{array}{lll}
0 & 0 & 0 \\
0 & 0 & i \\
0 & i & 0
\end{array}\right)
\end{array}
$$

Then, it can be verified that the 8 -dimensional Riemannian manifold $S U(3)$, with the bi-invariant metric defined by $-B$ and the 3 -fold vector cross products $P_{ \pm}$, is not in the class $w_{1}$ nor in the class $W_{2}$. (In fact, the covariant derivative $\nabla \varphi_{ \pm}$ of the fundamental form $\varphi_{ \pm}$does not satisfy the defining relations given in table $I$ for these classes.) Furthermore, $\mathcal{S} U(3) \notin \mathscr{T}$ because $H^{4}(S U(3), \boldsymbol{R})=\{0\}$.

Theorem 7.1. - The following inclusion relations are strict: $\mathfrak{T C} \mathfrak{W _ { 2 } , \mathfrak { w } _ { 1 } \cup \mathfrak { W } _ { 2 } \subset}$ $\subset W_{1} \oplus w_{2}$.

Proof. - Consider $\boldsymbol{R}^{8}$ with the two 3-fold parallel vector cross products, and $S U(3)$ as before. Let $\left(\boldsymbol{R}^{8}\right)^{0}$ denote the manifold $\boldsymbol{R}^{8}$ with a nontrivial change of conformal metric. Then, we have

$$
\begin{aligned}
& \left(\boldsymbol{R}^{8}\right)^{0} \in \mathfrak{w}_{2}-\mathfrak{T} \\
& S U(3) \in w_{1} \oplus w_{2}-w_{1} \cup w_{2}
\end{aligned}
$$

## REFERENCES

[1] D. V. Alekseevskit, Riemannian spaces with unusual holonomy groups, Funkcional Anal. i Priloven, 2 (1968), pp. 1-10. Translated in Functional Anal. Appl.
[2] M. Berger, Sur les groupes d'holonomie homogène des variétés à connexion affine et des variétés riemanniennes, Bull. Soc. Math. France, 83 (1965), pp. 279-330.
[3] E. Bonan, Sur les variétés riemanniennes à groupe d'holonomie $G_{z}$ ou Spin (7), C. R. Acad. Sci. Paris, 262 (1966), pp. 127-129.
[4] R. B. Brown - A. Gray, Vector cross products, Comment. Math. Helv., 42 (1967), pp. 222-236.
[4'] R. Bryant, Metrics with holonomy $G_{2}$ or Spin (7), preprint.
[5] E. Calabi, Construction and properties of some 6-dimensional almost complex manifolds, Trans. Amer. Math. Soc., 87 (1958), pp. 407-438.
[6] S. S. Chern, On a generalization of Kähler geometry, Lefschetz Jubilee Volume, Princeton University Press, (1957), pp. 103-121.
[7] B. Eckmann, Systeme von Richtungsfeldern in Sphären und stetige Lösungen komplexer linearer Gleichungen, Comment. Math. Helv., 15 (1943), pp. 1-26.
[8] B. ECKMANn, Continuous solutions of linear equations-some exceptional dimensions in topology, Batelle Rencontres, (1967), Lectures in Mathematics and Physics W. A. BeNJAMIN, (1968), pp. 516-526.
[9] M. Fernandez - A. Grax, Riemannian manifolds with structure group $G_{2}$, Ann. Mat. Pura Appl., (IV), 32 (1982), pp. 19-45.
[10] S. Goldberg, Curvature and Homology, Acad. Press, 1966.
[11] A. Gray, Minimal varieties and almost Hermitian submanifolds, Michigan Math. J., 12 (1965), pp. 273-279.
[12] A. Gray, Some examples of almost Hermitian manifolds, Ill. J. Math., 10 (1969), pp. 353-366.
[13] A. Gray, Vector cross products on manifolds, Trans. Amer. Math. Soc., 141 (1969), pp. 463-504. Correction, 148 (1970), p. 625.
[14] A. Grax, Weal holonomy groups, Math. Z., 123 (1971), pp. 290-300.
[15] A. Gray, Vector cross products, Rend. Sem. Mat. Univ. Politecn. Torino, 35 (1976-1977), pp. 69-75.
[16] A. Gray - P. Green, Sphere transitive structures and the triality automorphism, Pacific J. Math., 34. (1970), pp. 83-96.
[17] A. Gray - L. Hervella, The sixteen classes of almost Hermitian manifolds and their linear invariants, Ann. Mat. Pura Appl., (IV), 128 (1980), pp. 30-58.
[18] A. Gray, Vector cross products, harmonic maps and the Cauchy Riemann equations, Proc, New Orleans, Lecture Notes Math., Springer-Verlag, 949 (1980), pp. 57-74.
[19] S. Helgason, Differential Geometry, Lie Groups, and Symmetric Spaces, Academic Press, 1978.
[20] P. Libermann, Sur la classification des structures presque hermitiennes, Proceedings of the IV Internat. Coll. on Differential Geometry, Univ. Santiago de Compostela, (1979), pp. 168-191.
[21] H. Samelson, Lie Algebras, Van Nostrand Reinhold Mathematical Studies n. 23, 1969.
[22] J. Simons, On the transitivity of holonomy systems, Ann. of Math., 76 (1967), pp. 213-234.
[23] G. Whitehead, Note on cross-sections in Stiefel manifolds, Comment. Math. Helv., 37 (1962), рp. 239-240.
[24] K. Yano - T. Sumitomo, Differential geometry on hypersurfaces in a Cayley space, Proc. Roy. Soc. Edinburgh Sect. A 66 (1962-64), pp. 216-231 (1965).
[25] P. Zvengrowski, A 3-fold vector product in $\boldsymbol{R}^{8}$, Comment. Math. Helv., 40 (1966), pp. 149-152.


[^0]:    (*) Entrata in Redazione il 19 settembre 1984, Versione riveduta il 2 maggio 1985.
    Indirizzo dell'A.: Universidade de Santiago, Departamento de Geometria e Topologia, Facultade de Matematicas, Santiago de Compostela, Spain.

